

Name:

LOKESH MEHRA

Roll No:
e.g. 170001

220591

Dept.:
e.g. CSE

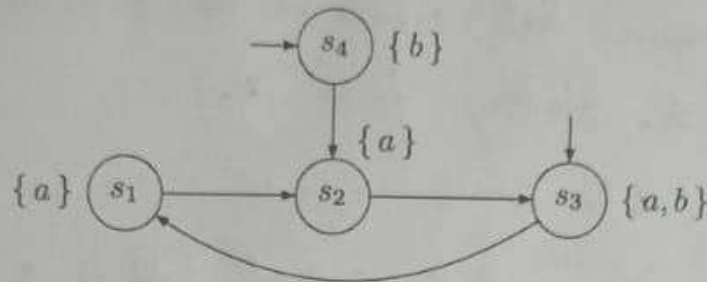
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Indian Institute of Technology Kanpur
CS637 Embedded and Cyber-Physical Systems
Homework Assignment 3
Deadline: November 8, 2024

Total: 40 marks

Problem 1. (10 points)

Consider the following state machine over the set of atomic propositions $\{a, b\}$:



Decide for each of the following LTL specifications whether the model satisfies it. For the positive outcome, provide a proof. For the negative outcome, provide a counterexample trace.

Note that the symbols \bigcirc , \square , \Diamond , and U represent the "next", "always", "eventually", and "until" temporal operators respectively.

- (a) $\bigcirc \bigcirc \bigcirc a$
- (b) $\square b$
- (c) $\square \Diamond a$
- (d) $\square (b U a)$
- (e) $\Diamond (a U b)$

Name:

LOKESH MENKA

Roll No:
e.g. 170001

120591

Dept.:

e.g. CSE

EE

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Deadline: November 8, 2017Ans:a) $\Box \Box \Box a$

This formula requires that a holds in the third state following the current state. Starting from s_1 :

→ The path from s_1 is $s_1 \rightarrow s_2 \rightarrow s_3 \rightarrow s_2$.

→ Following this path, a does indeed hold in s_3 (~~the~~ the third state after the starting state)

Therefore, the model satisfies $\Box \Box \Box a$

b) $\Box b$

The specification requires that b holds in all states in every possible path.

→ In the model, state s_2 does not satisfy b (only a holds in s_2)

→ This means that there is at least one state in the model where b does not hold.

Thus, the model does not satisfy $\Box b$.

→ A counterexample is the path $s_1 \rightarrow s_2$, where b is not true in s_2

c) $\Box \Diamond a$

This formula means that there is some point in the future where a will hold in all subsequent states.

→ However, there is a cycle $s_1 \rightarrow s_2 \rightarrow s_3 \rightarrow s_1$ that does not guarantee a holds always. (For instance, s_3 has both a and b)

→ Thus, the model does not satisfy DDa .

→ A counterexample is the path $s_1 \rightarrow s_2 \rightarrow s_3 \rightarrow s_2$, where b appears periodically.

d) $\Box(b \cup a)$

This specification means that in all paths, b must hold until a eventually holds.

→ In the path $s_4 \rightarrow s_2$, b holds in s_4 , and a holds in s_2 , which satisfies $b \cup a$.

→ In the cycle $s_1 \rightarrow s_2 \rightarrow s_3 \rightarrow s_1$, a is present in each state, which also satisfies $b \cup a$.

Therefore, the model satisfies $\Box(b \cup a)$.

e) $\Diamond(a \cup b)$

This formula specifies that there exists a path where a holds until b eventually holds.

→ In the path $s_1 \rightarrow s_3$, a holds in s_1 , and b holds in s_3 .

→ This satisfies the condition that a holds until b is encountered.

Thus, the model satisfies $\Diamond(a \cup b)$.

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LOKEJH MEHRA

Roll No:
e.g. 170001

220591

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Problem 2. (10 points)

Consider the two state machines in Figure 1 and answer the following questions:

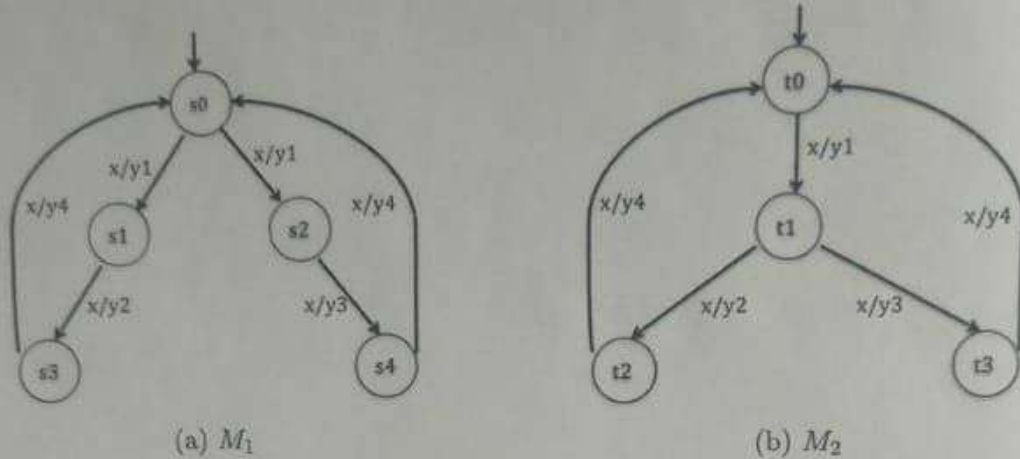


Figure 1

- (a) Does the state machine M_1 simulate the state machine M_2 ? If yes, provide the simulation relation. If no, provide a transition of M_2 that M_1 cannot match.
- (b) Does the state machine M_2 simulate the state machine M_1 ? If yes, provide the simulation relation. If no, provide a transition of M_1 that M_2 cannot match.
- (c) Are the two state machines bisimilar? If yes, provide the bisimulation relation. If no, provide one reason.

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a) To verify if M_1 simulates M_2 , we need to check if there exists a simulation relation $R \subseteq M_1 \times M_2$ such that for every pair of states $(s, t) \in R$, every transition from t in M_2 can be matched by a corresponding transition from s in M_1 .

- From t_0 in M_2 , we have three transitions: $(t_0, x/y_3, t_1)$, $(t_0, x/y_4, t_2)$, and $(t_0, x/y_4, t_3)$.

- From s_0 in M_1 , there are also three transitions: $(s_0, x/y_1, s_1)$, $(s_0, x/y_4, s_3)$ and $(s_0, x/y_4, s_4)$.

By mapping s_1 to t_1 , s_3 to t_2 , and s_4 to t_3 , we can construct a relation $R = \{(s_0, t_0), (s_1, t_1), (s_3, t_2), (s_4, t_3)\}$ such that every transition from a state in M_2 can be matched by a transition from the corresponding state in M_1 .

Therefore, M_1 simulates M_2 .

b) To verify if M_2 simulates M_1 , we again need to check if there exists a simulation relation $R' \subseteq M_2 \times M_1$ such that every transition from a state in M_1 can be matched by a corresponding transition in M_2 .

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Let's examine the states:

- From s_0 in M_1 , there is a transition $(s_0, x/yz, s_3)$
- In M_2 , it does not have a corresponding x/yz transition

Since M_2 cannot match the transition $(s_0, x/yz, s_3)$ from M_1 , there is no simulation relation from M_2 to M_1 . Therefore, M_2 does not simulate M_1 .

© Bisimilarity requires both M_1 simulates M_2 and M_2 simulates M_1 .

As we know from (a & b),

M_1 simulates M_2 but M_2 does not simulate M_1 , ~~hence~~

Since mutual simulation does not hold, M_1 and M_2 are not bisimilar.

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Problem 3. (10 points)

Consider the processes P_1 and P_2 with the shared variables b_1 , b_2 , and x . Variables b_1 and b_2 are Boolean variables, while variable x can take either the value 1 or 2. Initially, each process P_i is in the non-critical section (i.e., P_i is in location *noncrit_i*). The scheduling strategy for giving the processes access to the critical section is realized using x as follows. If both processes want to enter the critical section (i.e., P_i is in location *wait_i*), the value of variable x decides which of the two processes may enter its critical section: if $x = i$, then P_i may enter its critical section *crit_i* (for $i = 1, 2$). On entering location *wait₁*, process P_1 performs $x := 2$, thus giving privilege to process P_2 to enter the critical section. The value of x thus indicates which process has its turn to enter the critical section. Symmetrically, P_2 sets x to 1 when starting to wait. The variables b_i provide information about the current location of P_i . More precisely, b_i is set when P_i starts to wait, and is reset when the process exits the critical section. In pseudocode, P_1 performs as follows (the code for process P_2 is similar):

```

P1  loop forever
      ⋮
      (*noncritical actions*)
      b1 := true; x := 2
      wait until (x = 1 ∨ ¬b2)
      do critical section od
      b1 := false
      ⋮
      (*noncritical actions*)
      end loop

```

- Draw the state machines for P_1 and P_2 .
- Show the state machine that is obtained by asynchronous composition of P_1 and P_2 .
- How many total states are there in the composed state machine? How many of them are reachable?
- Provide an LTL formula that captures the requirement that the process P_1 and P_2 will not enter the critical section simultaneously. Using the composed state machine, determine whether the two systems satisfy the formula (property).

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Ans The pseudocode for P_1 and P_2 indicates that each process has five main states:

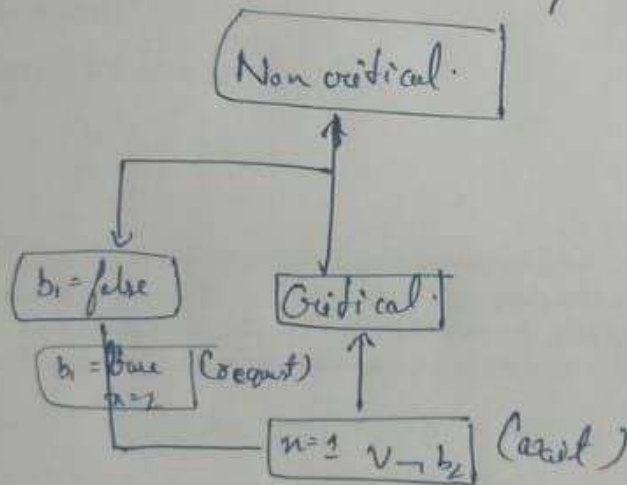
$N \rightarrow$ Noncritical Actions $R \rightarrow$ Request (Setting $b_i := \text{true}$ and $n = i$)

$\omega \rightarrow$ Wait (Waiting for the condition to enter the critical section)

$C \rightarrow$ Critical section (executing critical section code)

$L \rightarrow$ Release (resetting $b_i := \text{false}$ upon exiting the critical section)

The state machines for P_1 and P_2 are as follows.



b) ~~State~~ To compose the state machines asynchronously, we consider the Cartesian product of the states of P_1 and P_2 . Each combined state represents a pair of states, one from P_1 's state machine and one from P_2 's state machine.

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$(N, N), (N, R), (N, W), (N, C), (N, L),$
 $(R, N), (R, R), (R, W), (R, C), (R, L),$
 $(W, N), (W, R), (W, W), (W, C), (W, L),$
 $(C, N), (C, R), (C, W), (C, C), (C, L),$
 $(L, N), (L, R), (L, W), (L, C), (L, L)$

Thus, there are a total of $5 \times 5 = 25$ states.

© Total states in the Composed State machine and Reachability
We need to analyse which state pairs can be reached based on the ~~rules~~ rules set by a, b_1, b_2 . For example:- (C, C) is unreachable because it violates mutual exclusion (both processes cannot be in the critical section at the same time).

- Other unreachable states might include cases where both are waiting indefinitely due to incompatible conditions in a and b_i .

d) To specify that P_1 and P_2 cannot both be in the critical section simultaneously, we use the following Linear Temporal Logic (LTL) formula:

$$\neg \Diamond (C_1 \wedge C_2)$$

where \Diamond denotes P_i in the critical section. - C_2 denotes P_2 in the critical section.

This formula asserts that at no point in time ($\neg \Diamond$, meaning "always") will both P_1 and P_2 be in critical section simultaneously.

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Problem 4. (10 points)

Consider the following program:

```

int count (int a, int b)
{
    int count;
    for (count = 0; count < 2; count++)
    {
        if (a > b)
            b = a + 1;
        else
            b = a - 1;
    }
    return b;
}

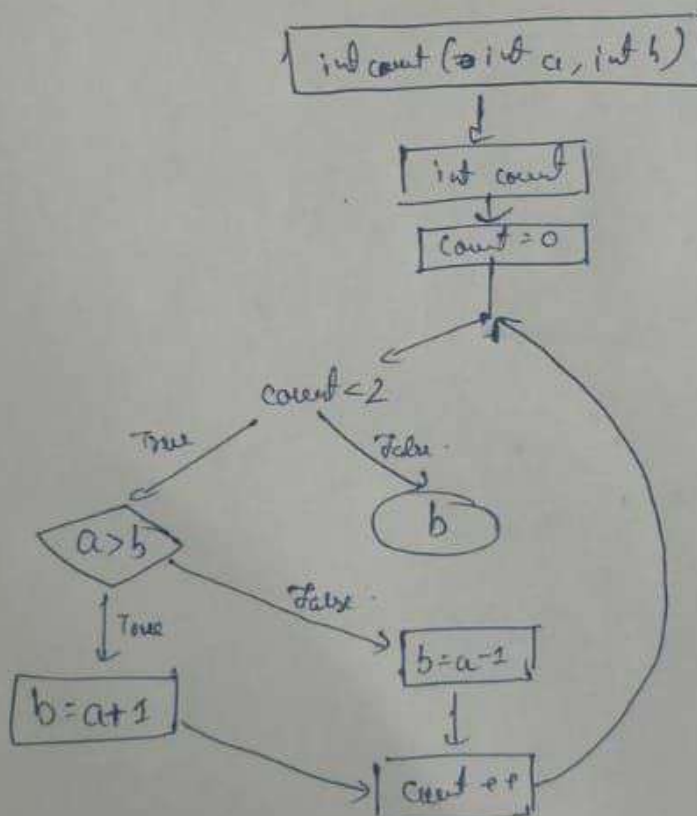
```

- (a) Draw a control flow graph for the program.
 (b) How many paths are there in the program? How many paths are feasible?
 (c) Assume the following:

- An assignment statement (for example, $\text{count} = 0$) requires 2 unit time for execution.
- A statement involving an arithmetic operation followed by an assignment (for example, $\text{count}++$ or $b = a + 1$) requires 6 unit time for execution.
- A comparison statement (for example, $\text{count} < 2$) requires 4 unit time for execution.

Compute a tight bound on the worst-case execution time for the program.

Ans a)



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b) Total no. of paths = 4

i) ~~(a > b)~~ Path 1: $(a > b)$ is true in both iterations.

ii) Path 2: $(a > b)$ is true in the first iteration and false in the second.

iii) Path 3: $(a > b)$ is false in the first iteration and true in the second.

iv) Path 4: $(a > b)$ is false in both iterations.

→ Since b is modified in each iteration, the outcome of $a > b$ can change between iterations.

→ All four paths are feasible depending on the initial values of a and b .

c) Worst Case Execution Time (WCET) Calculations:-

Given Execution times:-

- Initialization

- $\text{count} = 0$; → 2 units

- First Loop condition Check:

- $\text{count} < 2$; → 4 units

- First iteration

- $\text{count}++$; → 6 units

- $a > b$; → 4 units

- $b = a + 1$; → 6 units

- Total for first iteration: $6 + 4 + 6 = 16$ units

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• Second Loop Condition Check:

- $\text{count} < 2$; $\rightarrow 4$ units

• Second Iteration:

- $\text{count}++$; $\rightarrow 6$ units

- $a > b$; $\rightarrow 4$ units

- $b = a \pm 1$; $\rightarrow 6$ units

- Total for second iteration: $6 + 4 + 6 = 16$ units

• Third Loop Condition Check:

- $\text{count} < 2$; $\rightarrow 4$ units (condition fails, loop ends exits)

• Return Statement:

- $\text{return } b$; \rightarrow Execution time negligible or not specified.

Total WCET Calculation:-

Total time = Initialization + First Loop Check + First Iteration

+ Second Loop Check + Second Iteration + Third Loop Check

$$= 2 + 4 + 16 + 4 + 16 + 4$$

$$= 46 \text{ units}$$