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Stochastic Search 随机搜導

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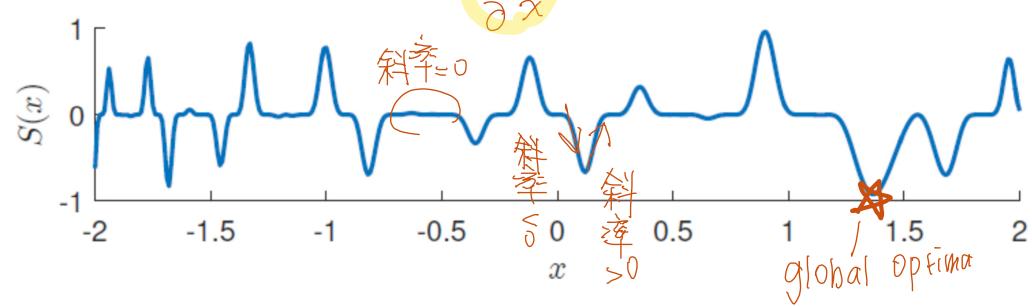
用路机搜寻做强机跳灌,就回找重锋

Difficult Optimization

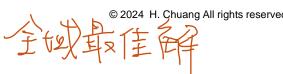


We could easily have multiple local minimums/maximums

$$S(x) = \begin{cases} -e^{-x^2/100} \sin(13x - x^4)^5 \sin(1 - 3x^2)^2, & \text{if } -2 \le x \le 2, \\ \infty, & \text{otherwise.} \end{cases}$$







鲛剑了

Simulated Annealing

S(x) is an arbitrary function to be minimized, x may take values in continuous or discrete set X

Simulated annealing is a Monte Carlo technique for minimization that emulates the physical state of atoms in a metal when the metal is heated up and then slowly cooled down. When the cooling is performed very slowly, the atoms settle down to a minimum-energy state. Denoting the state as x and the energy of a state as S(x), the probability distribution

of the (random) states is described by the Boltzmann pdf

$$f(x) \propto e^{-\frac{S(x)}{kT}}, \quad x \in X,$$
 其引投到最小能量伏態

where k is Boltzmann's constant and T is the temperature.



Simulated Annealing

The idea of simulated annealing is to create a sequence of points $X_1, X_2, ...$ that are approximately distributed according to pdfs $f_{T_1}(x), f_{T_2}(x), ...$, where $T_1, T_2, ...$ is a sequence of "temperatures" that decreases (is "cooled") to 0 — known as the *annealing schedule*. If each X_t were sampled *exactly* from f_{T_t} , then X_t would converge to a global minimum of S(x) as $T_t \to 0$. However, in practice sampling is *approximate* and convergence to a global minimum is not assured. A generic simulated annealing algorithm is as follows.

temperature

Algorithm 3.4.1: Simulated Annealing

```
input: Annealing schedule T_0, T_1, \ldots, function S, initial value x_0. output: Approximations to the global minimizer x^* and minimum value S(x^*).
```

- 1 Set $X_0 \leftarrow x_0$ and $t \leftarrow 1$.
- 2 while not stopping do
- 3 Approximately simulate X_t from $f_{T_t}(x)$.
- 4 $t \leftarrow t + 1$
- 5 return X_t , $S(X_t)$

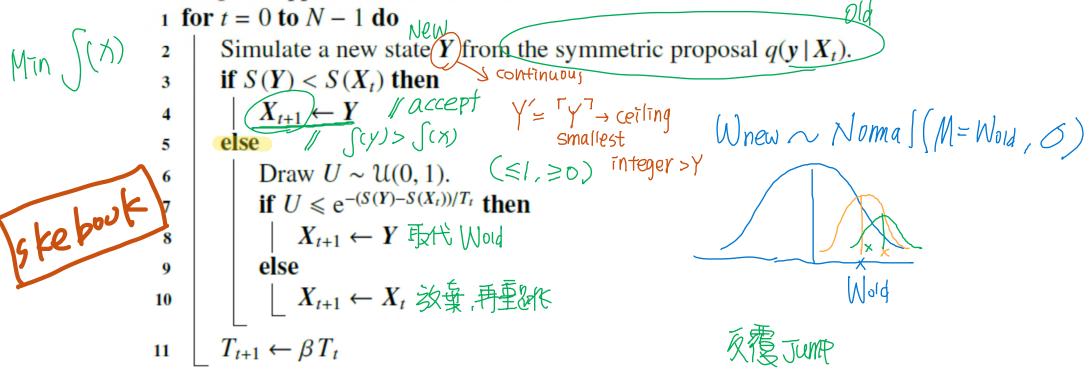


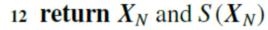
盛散、連続都院式用

Algorithm 3.4.2: Simulated Annealing with a Random Walk Sampler

input: Objective function S, starting state X_0 , initial temperature T_0 , number of iterations N, symmetric proposal density $q(y \mid x)$, constant β .

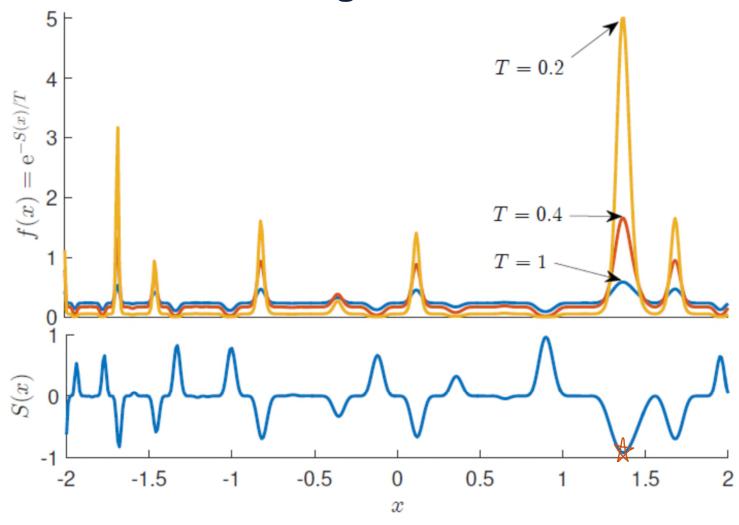
output: Approximate minimizer and minimum value of S.







Simulated Annealing





Multivariable Optimization



Consider the following assets in 2017/11/10 ~2020/11/10 APPLE, FACEBOOK, AMAZON, S&P500, NASDAQ, WWE (?)

Build a portfolio: Six continuous decision variables x in [0, 1] X SI X > 0

Daily return is {price(t)-price(t-1)}/price(t-1) Maximize the **Sharpe ratio**=E[Daily Return]/(Var[Daily Return])^0.5 see https://en.wikipedia.org/wiki/Sharpe_ratio

penalty > 0 Min objective = -1*Sharpe + lambda*(constraint)

How can we accommodate key constraints?

 $((x1+x2+x3+x4+x5+x6)-1)^2 = 2x=1$

 $\int_{-\infty}^{\infty} x_{n}(x_{n}(0), x_{n}(i))^{2}, \text{ for } i=1,2...,6)$ $\int_{-\infty}^{\infty} sum(max(0, -x_{n}(i))^{2}, \text{ for } i=1,2...,6)$ $\int_{-\infty}^{\infty} x_{n}(x_{n}(0), x_{n}(i))^{2}, \text{ for } i=1,2...,6)$

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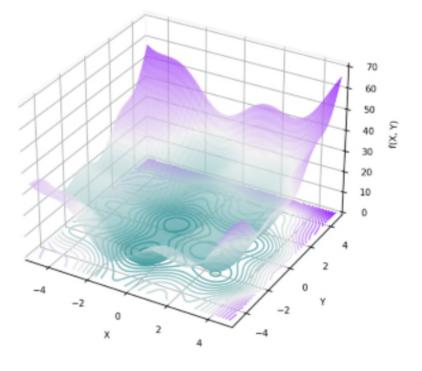


Particle Swarm Optimization, PSO

Inspired by social behavior
 We make decisions by self-experience & group-experience

A group of birds is searching for food, how to move in a valley?





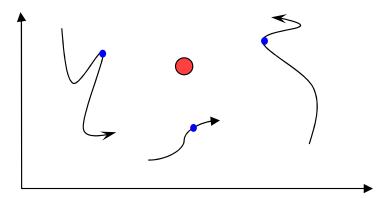
$$f(x,y)=x^2+(y+1)^2-5\cos(3x/2+3/2)$$

$$-3\cos(2y-3/2)$$



Particle Swarm Optimization, PSO

Let's simplify the case into 2 dimensions & only 3 particles



• $X_{n,t}$: travel route of n particles in time period t

$$A_{n,t}$$
 . Traver route of H particles in time period t $P(aaron) = [X_{a,1}, X_{a,2}, X_{a,3}, ..., X_{a,t}], \text{ min at } X_{a,2}$ $f(betty) = [X_{b,1}, X_{b,2}, X_{b,3}, ..., X_{b,t}], \text{ min at } X_{b,3}$ $P(cathy) = [X_{c,1}, X_{c,2}, X_{c,3}, ..., X_{c,t}], \text{ min at } X_{c,t}$

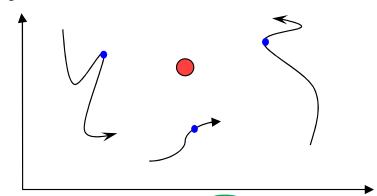
Next position for each particle is calculated by:

$$X_{n,t+1} = X_{n,t} + V_{n,t+1}$$
 / adjustment



Particle Swarm Optimization, PSO

Let's simplify the case into 2 dimensions & only 3 particles



• Now, we have to decide $V_{n,t+1}$ by pbest and gbest

$$V_{n,t+1} = w^*V_{n,t} + c1^*r1(V_{pbest}) + c2^*r2(V_{gbest})$$
 $r1 \& r2 \sim \text{Uniform}(0, 1)$ past self-best group best

Take particle *aaron* for instance

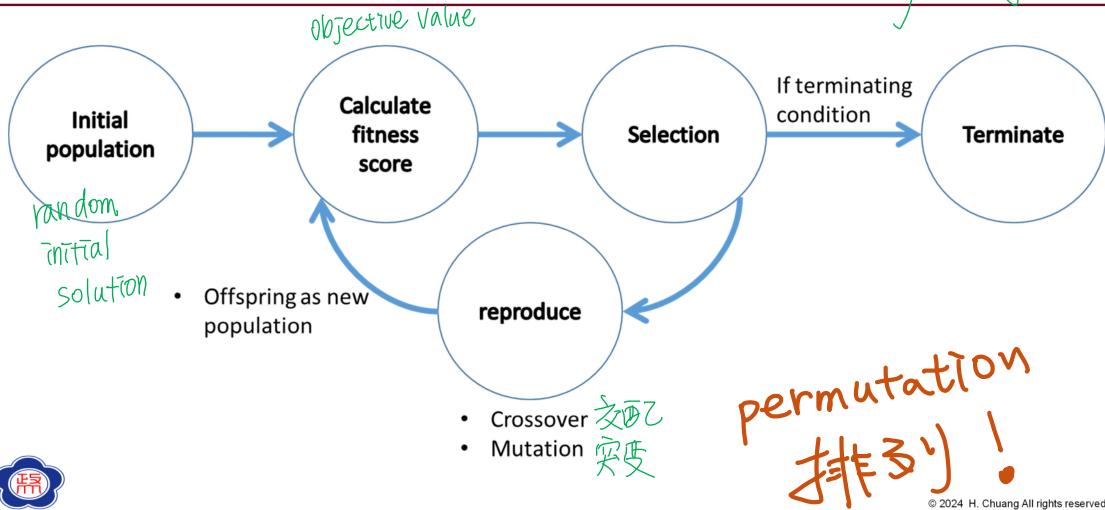
pbest: best self-experience: $X_{a,2}$

gbest: best group-experience: $X_{c,t}$

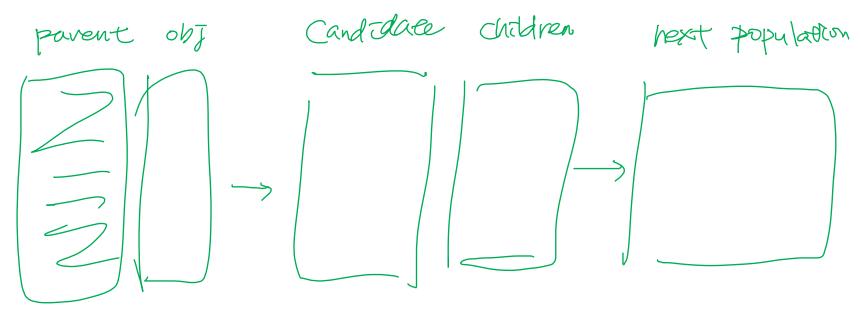




evolutionary Dago



- An extremely popular optimization algorithm
 - 1. Initial population with pop_size
 - 2. Calculate fitness score of population
 - 3. Randomly select pop_size of chromosome with replacement





Selection

Chromosome	Fitness Score	Proportion
A1	10	0.1
A2	20	0.2
А3	30	0.3
A4	40	0.4



Roulette wheel selection





- An extremely popular optimization algorithm
 - 1. Initial population with pop_size
 - 2. Calculate fitness score of population
 - 3. Randomly select pop_size of chromosome with replacement
 - 4. if *rand*₁≤*pcrossover*, make population into pairs and do crossover
 - 5. If rand₂≤pmutation, for each child, do mutate
 - 6. select elitism of highest fitness scores from previous population & randomly select (pop_size elitism) of children as new population

hyper-parameters

pop_size : population size

pcrossover : probability of crossover

pmutation: probability of mutation

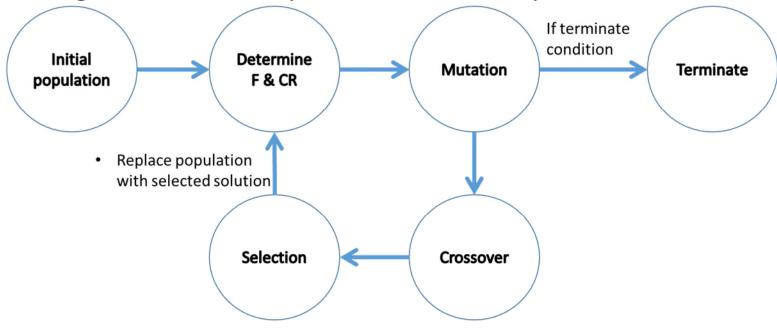
elitism: number of best fitness to survive

maxiter: max iteration



Differential Evolution (DE)

- ullet Choose the parameters $\mathrm{NP} \geq 4$, $\mathrm{CR} \in [0,1]$, and $F \in [0,2]$.
 - NP is the population size, i.e. the number of candidate agents or "parents"; a typical setting is 10n.
 - ullet The parameter $\mathrm{CR} \in [0,1]$ is called the *crossover probability* and the parameter $F \in [0,2]$ is called the *differential weight*. Typical settings are F=0.8 and CR=0.9.
 - Initialize all agents x with random positions in the search-space.





Differential Evolution (DE)

- For each agent x in the population do:
 - Pick three agents a, b, and c from the population at random, they must be distinct from
 each other as well as from agent x. (a is called the "base" vector.)
 - ullet Pick a random index $R \in \{1,\ldots,n\}$ where n is the dimensionality of the problem being optimized.
 - ullet Compute the agent's potentially new position $\mathbf{y} = [y_1, \dots, y_n]$ as follows:
 - ullet For each $i\in\{1,\ldots,n\}$, pick a uniformly distributed random number $r_i\sim U(0,1)$
 - ullet If $r_i < CR$ or i=R then set $y_i=a_i+F imes (b_i-c_i)$ otherwise set $y_i=x_i$. (Index position R is replaced for certain.)
 - If $f(y) \le f(x)$ then replace the agent x in the population with the improved or equal candidate solution y.

