

A new example

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$$A_0 = \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -2 \end{bmatrix} \quad B_0 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & -1 \end{bmatrix}$$

$$C_0 = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 2 \end{bmatrix} \quad (\text{It is controllable and observable})$$

$$G(s) = C_0 (sI - A)^{-1} B_0 = \begin{bmatrix} \frac{2s+3}{(s+1)(s+2)} & -\frac{1}{s+2} \\ \frac{2}{s+2} & -\frac{s}{(s+1)(s+2)} \end{bmatrix}$$

$$\det G(s) = \frac{1}{(s+1)^2(s+2)}$$

$$\text{pole polynomial, } p_G(s) = (s+1)^2(s+2)$$

$$\begin{aligned} \text{pole minimal polynomial, } p'_G(s) &= (s+1)(s+2) \\ &= s^2 + 3s + 2 \equiv s^2 + d_1 s + d_2 \end{aligned}$$

$$\text{Rewrite } G(s) \text{ as } G(s) = \frac{N(s)}{p'_G(s)} \text{ where } N(s) \text{ is a poly. matrix}$$

$$G(s) = \frac{N_1 s + N_2}{s^2 + d_1 s + d_2} ; \quad N_1 = \begin{bmatrix} 2 & -1 \\ 2 & -1 \end{bmatrix}, \quad N_2 = \begin{bmatrix} 3 & -1 \\ 2 & 0 \end{bmatrix}$$

$$d_1 = 3, \quad d_2 = 2$$

The block diagram form is

$$A_1 = \begin{bmatrix} -d_1 I_2 & I_2 \\ -d_2 I_2 & 0 \end{bmatrix} \quad B_1 = \begin{bmatrix} N_1 \\ N_2 \end{bmatrix}$$

$$C_1 = [I_2 \quad 0]$$

(1)

$$\begin{aligned} -\frac{1}{s+2} &= -\frac{s+1}{(s+1)(s+2)} = \frac{-s-1}{(s+1)(s+2)} \\ \frac{2}{s+2} &= \frac{2(s+1)}{(s+1)(s+2)} = \frac{2s+2}{(s+1)(s+2)} \end{aligned}$$



$$G(s) = \frac{N(s)}{P'_G(s)} = \begin{bmatrix} \frac{2s+3}{(s+1)(s+2)} & -\frac{s+1}{(s+1)(s+2)} \\ \frac{2(s+1)}{(s+1)(s+2)} & -\frac{s}{(s+1)(s+2)} \end{bmatrix}$$

Now, construct a MFD.

$$G(s) = \left( P'_G(s) I_2 \right)^{-1} N(s) = \begin{bmatrix} P'_G & 0 \\ 0 & P'_G \end{bmatrix}^{-1} N(s)$$

$$= \begin{bmatrix} \frac{1}{P'_G(s)} & 0 \\ 0 & \frac{1}{P'_G(s)} \end{bmatrix} \begin{bmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{bmatrix} = \begin{bmatrix} \frac{m_{11}}{P'_G} & \frac{m_{12}}{P'_G} \\ \frac{m_{21}}{P'_G} & \frac{m_{22}}{P'_G} \end{bmatrix}$$

ok!

$$D_L = \begin{bmatrix} P'_G & 0 \\ 0 & P'_G \end{bmatrix} \quad N_L = N$$

$$G(s) = D_L(s)^{-1} N_L(s)$$

$$N_L(s) = P'_G(s) G(s)$$

The obtained left MFD of  $G(s)$  is not coprime.

We use the Hermite form to obtain a left coprime MFD.

We use another approach: first build a right MFD, then use the Hermite form construction to get a left-coprime MFD. (2)

Construct a right MFD of  $G(s)$ :

$$G(s) = \frac{N(s)}{P_G'(s)} = \begin{bmatrix} \frac{2s+3}{(s+1)(s+2)} & -\frac{s+1}{(s+1)(s+2)} \\ \frac{2(s+1)}{(s+1)(s+2)} & -\frac{s}{(s+1)(s+2)} \end{bmatrix}$$

$$G(s) = N(s) \left( P_G'(s) I_2 \right)^{-1} = N(s) \begin{bmatrix} P_G' & 0 \\ 0 & P_G' \end{bmatrix}^{-1}$$

$$= \begin{bmatrix} n_{11} & n_{12} \\ n_{21} & n_{22} \end{bmatrix} \begin{bmatrix} \frac{1}{P_G'} & 0 \\ 0 & \frac{1}{P_G'} \end{bmatrix} = \begin{bmatrix} \frac{n_{11}}{P_G'} & \frac{n_{12}}{P_G'} \\ \frac{n_{21}}{P_G'} & \frac{n_{22}}{P_G'} \end{bmatrix}$$

$$G(s) = N_R(s) D_R^{-1}(s)$$

$p \times m \quad p \times m \quad m \times m$

$$N_R(s) = P_G'(s) G(s), \quad D_R(s) = P_G'(s) I_m$$

$$\begin{matrix} m & p \\ p \end{matrix} \begin{bmatrix} U(s) \end{bmatrix} \begin{matrix} m \\ m \end{matrix} \begin{bmatrix} D_R(s) \\ N_R(s) \end{bmatrix} = \begin{matrix} m \\ m \end{matrix} \begin{bmatrix} R(s) \\ 0 \end{bmatrix}$$

$$R(s) = \begin{bmatrix} \bullet & & & \\ & \bullet & & \\ & & \bullet & \\ & & & 0 \end{bmatrix}$$

$$D_L \Rightarrow \begin{bmatrix} -1 & 1 \\ -2 & 2 \end{bmatrix}$$



Recapitulation:

$$G(s) = \begin{bmatrix} \frac{2s+3}{(s+1)(s+2)} & -\frac{1}{s+2} \\ \frac{2}{s+2} & -\frac{s}{(s+1)(s+2)} \end{bmatrix}$$

pole polynomial,  $P_G(s) = (s+1)^2(s+2)$

pole minimal polynomial,  $P'_G(s) = (s+1)(s+2)$

Construct a right MFD of  $G(s)$ :

$$N_R(s) = P'_G(s) G(s) = \begin{bmatrix} 2s+3 & -s-1 \\ 2s+2 & -s \end{bmatrix}$$

$$D_R(s) = P'_G(s) I_m = \begin{bmatrix} (s+1)(s+2) & 0 \\ 0 & (s+1)(s+2) \end{bmatrix}$$

$$G(s) = N_R(s) D_R^{-1}(s)$$

Apply the Hermite form procedure:

$$U(s) \begin{bmatrix} D_R(s) \\ N_R(s) \end{bmatrix} = \begin{bmatrix} R(s) \\ 0 \end{bmatrix} =: H(s) \quad \text{Hermite form} = \begin{bmatrix} 1 & -1 \\ 0 & s+2 \\ 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$U(s) = \begin{bmatrix} U_{11}(s) & U_{12}(s) \\ U_{21}(s) & U_{22}(s) \end{bmatrix} = \left[ \begin{array}{cc|cc} 0 & 0 & 1 & -1 \\ 0 & 0 & -2s-2 & 2s+3 \\ \hline 1 & 0 & s^2+s & -s^2-2s-1 \\ 0 & 1 & 2s^2+4s+2 & -2s^2-5s-3 \end{array} \right]$$

$$G(s) = -U_{22}^{-1}(s) U_{21}(s) = [-U_{22}(s)]^{-1} U_{21}(s)$$

This is a left coprime MFD

$$-U_{22}(s) = \begin{bmatrix} -s^2 - s & s^2 + 2s + 1 \\ -2s^2 - 4s - 2 & 2s^2 + 5s + 3 \end{bmatrix}$$

$$U_{21}(s) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$-U_{22}(s)$  is not row-reduced because the leading row coefficient matrix is singular:

$$\begin{bmatrix} -1 & 1 \\ -2 & 2 \end{bmatrix}.$$

To obtain a row-reduced form of  $-U_{22}(s)$ :

$$\begin{bmatrix} 1 & 0 \\ -2 & 1 \end{bmatrix} \begin{bmatrix} -s^2 - s & s^2 + 2s + 1 \\ -2s^2 - 4s - 2 & 2s^2 + 5s + 3 \end{bmatrix} = \begin{bmatrix} -s^2 - s & s^2 + 2s + 1 \\ -2s - 2 & s + 1 \end{bmatrix}$$

the leading row coefficient matrix is  $\begin{bmatrix} -1 & 1 \\ -2 & 1 \end{bmatrix}$  (not singular)

$$P(s) := \begin{bmatrix} -s^2 - s & s^2 + 2s + 1 \\ -2s - 2 & s + 1 \end{bmatrix}$$

$$Q(s) = \begin{bmatrix} 1 & 0 \\ -2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ -2 & 1 \end{bmatrix}$$

$$G(s) = P^{-1}(s) Q(s) \quad \text{row-reduced left-coprime MFD}$$

$$p \times m \quad p \times p \quad p \times m$$

Observer-form realization from  $P^{-1}(s)Q(s)^*$

(it will be minimal because this MFD is row-reduced and (left-) coprime)

$l_i \triangleq$  degree of the  $i$ -th row of  $P(s)$ ,  $i=1, \dots, p$

$$A_o^\circ = \text{block diag} \left\{ \begin{bmatrix} 0 & 1 & \dots & 1 \\ & \ddots & \ddots & \vdots \\ & & 0 & 1 \\ & & & 0 \end{bmatrix}, l_i \times l_i, i=1, \dots, p \right\}$$

$$C_o^\circ = \text{block diag} \{ [1 \ 0 \ \dots \ 0], 1 \times l_i, i=1, \dots, p \}$$

$$B_o^\circ = I_n, \quad n = \sum_{i=1}^p l_i \quad (= \deg \det P(s))$$

The observer-form realization is

$$A_o = A_o^\circ - P_{ez} P_{hz}^{-1} C_o^\circ, \quad B_o = Q_{ez}$$

$$C_o = P_{hz}^{-1} C_o^\circ$$

Matrices  $P_{hz}$ ,  $P_{ez}$  and  $Q_{ez}$  are determined as follows:

$$P(s) = S(s) P_{hz} + Y(s) P_{ez}$$

$$Q(s) = Y(s) Q_{ez}$$

$$S(s) \triangleq \text{diag} \{ s^{l_i}, i=1, \dots, p \} = \begin{bmatrix} s^{l_1} & & 0 \\ & s^{l_2} & \\ 0 & & \ddots \\ & & & s^{l_p} \end{bmatrix}$$

$$Y(s) \triangleq \text{block diag} \{ [s^{l_i-1} \ \dots \ 1], i=1, \dots, p \} =$$

$$= \begin{bmatrix} s^{l_1-1} & s^{l_1-2} & \dots & 1 & & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & & & & & s^{l_p-1} & s^{l_p-2} & \dots & 1 \end{bmatrix}$$

Observer-form realization from  $\begin{bmatrix} -s^2-3 & s^2+2s+1 \\ -2s-2 & s+1 \end{bmatrix}^{-1} \begin{bmatrix} 1 & 0 \\ -2 & 1 \end{bmatrix}$

$$l_1 = 2, \quad l_2 = 1 \quad (n = l_1 + l_2 = 3)$$

$$A_o^o = \left[ \begin{array}{cc|c} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right], \quad C_o^o = \left[ \begin{array}{ccc|c} 1 & 0 & 0 \\ 0 & 0 & 1 \end{array} \right] \quad B_o^o = I_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$P(s) = \begin{bmatrix} s^2 & 0 \\ 0 & s \end{bmatrix} \underbrace{\begin{bmatrix} -1 & 1 \\ -2 & 1 \end{bmatrix}}_{P_{hr} \triangleq} + \underbrace{\left[ \begin{array}{cc|c} s & 1 & 0 \\ 0 & 0 & 1 \end{array} \right]}_{P_{er} \triangleq} \underbrace{\begin{bmatrix} -1 & 2 \\ 0 & 1 \\ -2 & 1 \end{bmatrix}}_{P_{er} \triangleq}$$

$$Q(s) = \left[ \begin{array}{cc|c} s & 1 & 0 \\ 0 & 0 & 1 \end{array} \right] \underbrace{\begin{bmatrix} 0 & 0 \\ 1 & 0 \\ -2 & 1 \end{bmatrix}}_{Q_{er} \triangleq}$$

$$A_o = A_o^o - P_{er} P_{hr}^{-1} C_o^o = \begin{bmatrix} -3 & 1 & 1 \\ -2 & 0 & 1 \\ 0 & 0 & -1 \end{bmatrix}$$

$$B_o = Q_{er} = \begin{bmatrix} 0 & 0 \\ 1 & 0 \\ -2 & 1 \end{bmatrix}$$

$$C_o = P_{hr}^{-1} C_o^o = \begin{bmatrix} 1 & 0 & -1 \\ 2 & 0 & -1 \end{bmatrix}$$