

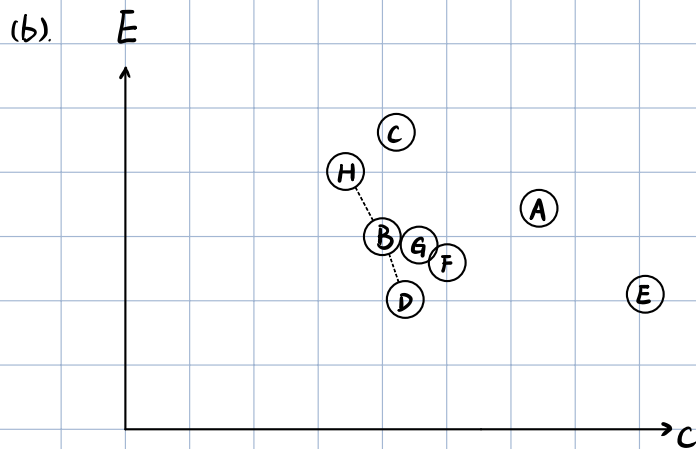
# IL 2212 Homework 2 Weikai Zhou

1. (a)

Candidate Solution	Cost <sub>1</sub>	Cost <sub>2</sub>
A	25.4	21
B	18.5	16.6
C	18.2	21
D	22.3	15.4
E	26	18.2
F	24.8	18.2
G	21.6	17.4
H	24.8	21.8

Therefore, for low power, we should choose C.

For high performance, we should choose D.



Therefore, B, D, H are Pareto Points.

(c) Since  $E \leq 20$ ,  $P \leq 30$ ,  $C \leq 35$ , C, E, H don't satisfy.

For A, it is dominated by B. For F, it is dominated by D.

While for B, D, G, they are not dominated by others.

Therefore, B, D, G are Pareto Points.

2.(a) We can choose a state variable  $\_init = \text{true} \rightarrow \text{false}$ , which is only true in the initial state.

And state variable  $\text{pre}(s)$  for the states of the control FSM.

(b) For  $S_0$ , we have:  $\_init = \text{true}$ ;

$\text{pre}(s) = \text{nil}$ ;

$S_0$ : go to  $S_1$ ;  $--S = \text{false}$ ;  $x = \text{nil}$ ;  $y = \text{nil}$ ;

For  $S_1$ , we have:  $\_init = \text{false}$ ;

$\text{pre}(s) = \text{false}$ ;

$S_1$ : if  $a = \text{true}$ ,  $b = \text{false}$  then

go to  $S_2$ ;  $--S = \text{true}$ ;  $x = \text{false}$ ;  $y = \text{false}$ ;

else if  $a = \text{false}$ ,  $b = \text{true}$  then

go to  $S_1$ ;  $--S = \text{false}$ ;  $x = \text{true}$ ;  $y = \text{false}$ ;

else

go to  $S_1$ ;  $--S = \text{false}$ ;  $x = \text{false}$ ;  $y = \text{false}$ ;

For  $S_2$ , we have:  $\_init = \text{false}$ ;

$\text{pre}(s) = \text{true}$ ;

$S_2$ : if  $a = \text{true}$ ,  $b = \text{false}$  then

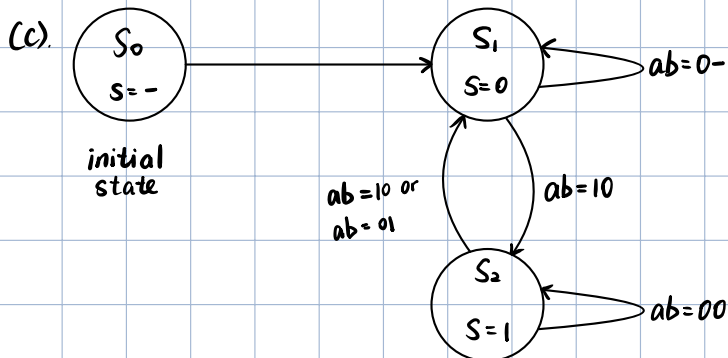
go to  $S_1$ ;  $--S = \text{false}$ ;  $x = \text{true}$ ;  $y = \text{false}$ ;

else if  $a = \text{false}$ ,  $b = \text{true}$  then

go to  $S_1$ ;  $--S = \text{false}$ ;  $x = \text{true}$ ;  $y = \text{true}$ ;

else

go to  $S_2$ ;  $--S = \text{true}$ ;  $x = \text{false}$ ;  $y = \text{false}$ ;



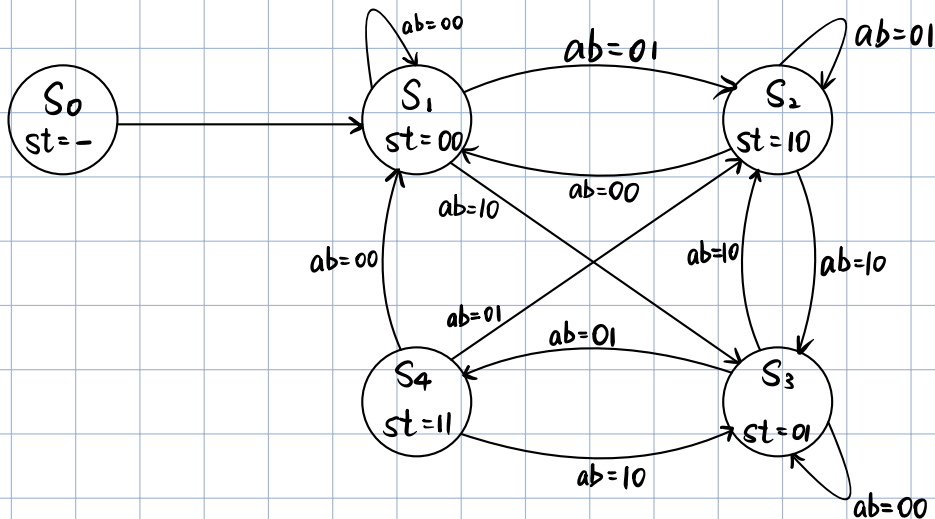
(d) It takes two input  $a, b$  and generates two outputs  $x, y$  based on the internal state  $s$ .

- When  $\text{pre}(s) = \text{false}$ , internal state will not change as long as  $a = \text{false}$ .  $b$  will affect the outputs  $x, y$ . When  $b = \text{true}$ , it will output  $x = \text{true}$ ,  $y = \text{false}$ . When  $b$  is false, it will output  $x = \text{false}$ ,  $y = \text{false}$ .
- When  $\text{pre}(s) = \text{false}$ , internal state will be changed to true when  $a = \text{true}$ .  $b$  can only be false now. Now it outputs  $x = \text{true}$ ,  $y = \text{false}$ .

- When  $\text{pre}(s) = \text{true}$ , the internal state will not change as long as  $a = \text{false}$ ,  $b = \text{false}$ . And it will output  $x = \text{false}$ ,  $y = \text{false}$ .
- When  $\text{pre}(s) = \text{true}$ , the internal state will change when  $(a = \text{true}, b = \text{false})$  or  $(a = \text{false}, b = \text{true})$ . For  $a = \text{true}$ ,  $b = \text{false}$ , it will output  $x = \text{true}$ ,  $y = \text{false}$ . For  $a = \text{false}$ ,  $b = \text{true}$ , it will output  $x = \text{true}$ ,  $y = \text{true}$ .

(e). Please see 'Theoretical 2.c' file

(f).



program\_1 is a mealy FSM while program\_2 is a moore FSM. Mealy machine tends to have less states and both input and state decide the output. For Moore machine, state decides the output, and input decides the state. In fact, a mealy machine can be converted into a moore machine, and vice versa. They are just different representation of logic flow.

3.(a). Please see "sdf.h" file.

(b). Please see "c-bare-metal-skeleton.c" file.

(c). We can arrange different actors on several processors. Eg. AAC on P1 and BD on P2.

We can add "#include <omp.h>" and add "#pragma omp parallel", so that the compiler can do parallel automatically.

The code is like:

```
#pragma omp parallel
```

```
{
```

```
    A;
```

```
    A;
```

```
    B;
```

```
    C;
```

```
    D;
```

```
}
```