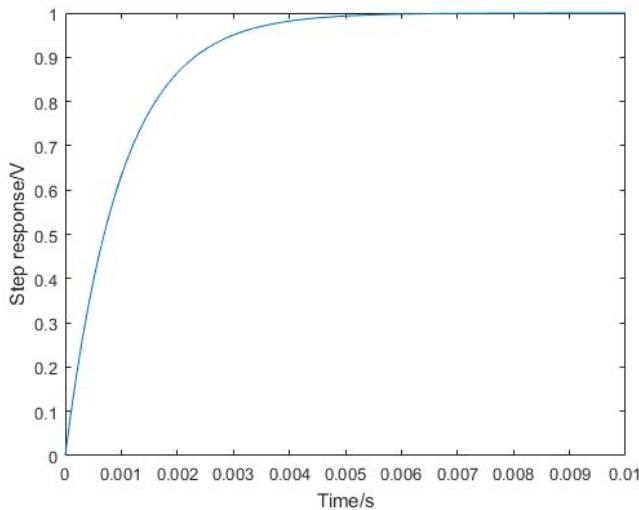


4.1(a). For $t > 0$, $V_{in}(t) = RC \frac{d}{dt} (1 - e^{-\frac{t}{RC}}) + (1 - e^{-\frac{t}{RC}}) = RC \left(\frac{1}{RC} e^{-\frac{t}{RC}} \right) + 1 - e^{-\frac{t}{RC}} = 1$

For $t < 0$, $V_{in}(t) = RC \frac{d}{dt} (0) + 0 = 0$

Therefore, $RC \frac{d}{dt} y_{step}(t) + y_{step}(t) = \begin{cases} 1, & t > 0 \\ 0, & t < 0 \end{cases} = u(t)$

(b). `t=0:0.0001:0.01;`
`y=1-exp(-t./0.001);`
`plot(t,y)`
`xlabel('Time/s')`
`ylabel('Step response/V')`
`axis([0 0.01 0 1])`



4.2 $h(t) = \frac{dy_{step}(t)}{dt} = \frac{1}{RC} e^{-\frac{t}{RC}} \cdot u(t)$

4.3(a). When $V_{in} = u(t)$, we have $V_{out} = (1 - e^{-\frac{t}{RC}}) u(t)$

Therefore, for this problem, we can have

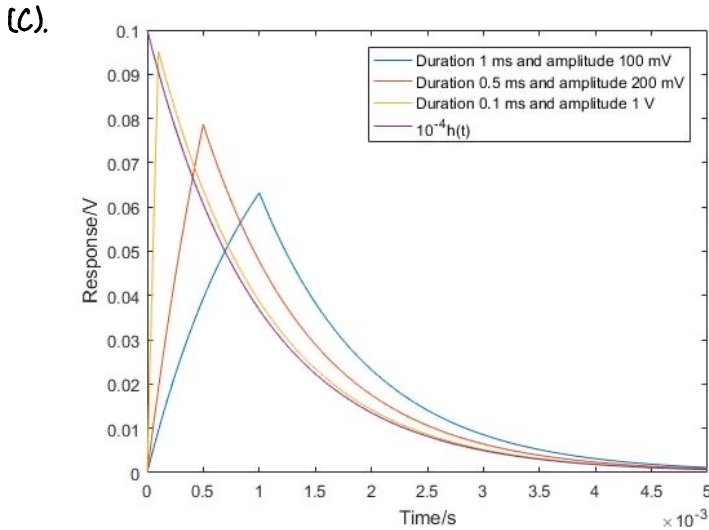
$$V_{out} = \frac{b}{\Delta} (y_{step}(t) - y_{step}(t - \Delta)) = \frac{b}{\Delta} \left((1 - e^{-\frac{t}{RC}}) u(t) - (1 - e^{-\frac{t-\Delta}{RC}}) u(t - \Delta) \right)$$

$$= \begin{cases} 0, & t < 0 \\ \frac{b}{\Delta} (1 - e^{-\frac{t}{RC}}) u(t), & 0 < t < \Delta \\ \frac{b}{\Delta} (e^{-\frac{\Delta-t}{RC}} - e^{-\frac{t}{RC}}), & t > \Delta \end{cases}$$

Optional: $h(t) * V_{in}(t) = \int_{-\infty}^{\infty} h(\tau) V_{in}(t - \tau) d\tau = \frac{b}{RC\Delta} \int_{-\infty}^{\infty} e^{-\frac{t-\tau}{RC}} \cdot u(t - \tau) \cdot \text{rect} \frac{\tau - \frac{\Delta}{2}}{\Delta} d\tau$

$$= \begin{cases} 0, & t < 0 \\ \frac{b}{\Delta} (1 - e^{-\frac{t}{RC}}) u(t), & 0 < t < \Delta \\ \frac{b}{\Delta} (e^{-\frac{\Delta-t}{RC}} - e^{-\frac{t}{RC}}), & t > \Delta \end{cases}$$

$$\begin{aligned}
 \text{(b)} \quad & \lim_{\Delta \rightarrow 0} \frac{1}{\Delta} \left((1 - e^{-\frac{t}{RC}}) u(t) - (1 - e^{-\frac{t-\Delta}{RC}}) u(t-\Delta) \right) \\
 &= \lim_{\Delta \rightarrow 0} \frac{1}{\Delta} \left(1 - e^{-\frac{t}{RC}} - 1 + e^{-\frac{t-\Delta}{RC}} \right) u(t) \\
 &= \lim_{\Delta \rightarrow 0} \frac{1}{\Delta} e^{-\frac{t}{RC}} \left(e^{\frac{\Delta}{RC}} - 1 \right) u(t) \\
 &= e^{-\frac{t}{RC}} u(t) \lim_{\Delta \rightarrow 0} \frac{e^{\frac{\Delta}{RC}} - 1}{\Delta} = e^{-\frac{t}{RC}} u(t) \lim_{\Delta \rightarrow 0} \frac{\frac{1}{RC} e^{\frac{\Delta}{RC}}}{1} = \frac{1}{RC} e^{-\frac{t}{RC}} u(t)
 \end{aligned}$$



4.4 For $u(t) - u(t-0.01)$, we have $V_{out1} = (1 - e^{-1000t}) u(t) - (1 - e^{-1000(t-0.01)}) u(t-0.01)$

For $-2.2(u(t-0.011) - u(t-0.016))$, we have $V_{out2} = -2.2(1 - e^{-1000(t-0.011)}) u(t-0.011) + 2.2(1 - e^{-1000(t-0.016)}) u(t-0.016)$

For $200t(u(t-0.011) - u(t-0.016))$, we first consider $t u(t-t_0)$

$$\begin{aligned}
 t u(t-t_0) * 1000 e^{-1000t} u(t) &= \int_{-\infty}^{\infty} \tau u(\tau-t_0) 1000 e^{-1000(t-\tau)} u(t-\tau) d\tau = u(t-t_0) \int_{t_0}^t \tau 1000 e^{-1000(t-\tau)} d\tau \\
 &= u(t-t_0) \frac{1}{1000} (1000t - 1 - (1000t_0 - 1) e^{1000(t_0-t)})
 \end{aligned}$$

Then, we get $V_{out3} = 200 \left(u(t-0.011) \frac{1}{1000} (1000t - 1 - 10e^{1000(t-0.011)}) - u(t-0.016) \frac{1}{1000} (1000t - 1 - 16e^{1000(t-0.016)}) \right)$

Therefore, $V_{out} = V_{out1} + V_{out2} + V_{out3} = (1 - e^{-1000t}) u(t) - (1 - e^{-1000(t-0.01)}) u(t-0.01) - 2.2(1 - e^{-1000(t-0.011)}) u(t-0.011) + 2.2(1 - e^{-1000(t-0.016)}) u(t-0.016) + \frac{1}{5} (1000t - 1 - 10e^{-1000(t-0.011)}) u(t-0.011) - \frac{1}{5} (1000t - 1 - 16e^{-1000(t-0.016)}) u(t-0.016)$

4.5 $H(j\omega) = \frac{\frac{1}{j\omega C}}{R + \frac{1}{j\omega C}} = \frac{1}{1 + j\omega RC}$

Optional: $\Gamma(j\omega) = \int_{-\infty}^{\infty} \frac{1}{RC} e^{-\frac{t}{RC}} \cdot e^{-j\omega t} dt = \frac{1}{RC(\frac{1}{RC} + j\omega)} = \frac{1}{1 + j\omega RC} = H(j\omega)$

4b $|H(j\omega)| = \left| \frac{1}{1 + j\omega RC} \right|$

f_c	$ H(j2\pi f_c) $	$\angle H(j2\pi f_c)$	T_d
50 Hz	0.9540	-17.4406°	0.9689 ms
200 Hz	0.6227	-51.4881°	0.7151 ms
500 Hz	0.3033	-72.3432°	0.4019 ms
1000 Hz	0.1572	-80.9569°	0.2249 ms
5000 Hz	0.0318	-88.1768°	0.0490 ms