# Example

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The signal  $x(t) = \sum_{n=-\infty}^{\infty} \mathrm{rect}(t-1/2-2n)$  is passed through a filter with frequency response  $H(\omega) = 3 \, \mathrm{rect}(\omega/\pi)$ . Determine the output signal y(t).

(Selected from Midterm Exam 2 of Summer 2014)

### Solution

 $T_0=2$  so  $\omega_0=\pi$ , so the harmonics of x(t) are at multiples of  $\pi$ . All frequency components above  $\pi/2$  are eliminated by this filter, so only the DC component passes through.  $c_0=1/2$ . Thus

$$y(t) = c_0 H(0) = 3/2.$$

 $H(\omega)$  and  $H(j\omega)$  are interchangeable notation

$$H(\omega) = H(j\omega) = \int_{-\infty}^{\infty} h(t)e^{-j\omega t} dt$$

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Consider the following cascade of LTI systems:

$$x(t) 
ightharpoonup h_1(t) 
ightharpoonup h_2(t) 
ightharpoonup y(t),$$

where  $h_1(t) = e^{-t}u(t)$  and  $h_2(t) = e^{-3t}u(t)$ .

- Find the frequency response of the overall system.
- Find the linear constant coefficient differential equation that describes this system.

(Selected from Midterm Exam 2 of Summer 2014)

## Solution

The overall frequency response is

$$H(\omega) = \frac{1}{j\omega + 1} \frac{1}{j\omega + 3}$$

The linear constant coefficient differential equation

$$H(\omega) = \frac{1}{(j\omega+1)(j\omega+3)} = \frac{1}{(j\omega)^2 + 4j\omega + 3}$$

so

$$3y(t) + 4\frac{\mathrm{d}}{\mathrm{d}t}y(t) + \frac{d^2}{dt^2}y(t) = x(t)$$