VE281

Data Structures and Algorithms

Dynamic Programming

Learning Objectives:

- Understand the basic idea of dynamic programming
- Know under what situation dynamic programming could be applied

Outline

- Dynamic Programming
 - Motivation
 - Example: Matrix-Chain Multiplication
 - Summary

Limitation of Divide and Conquer

- Recursively solving subproblems can result in the same computations being repeated when the subproblems **overlap.**
- For example: computing the Fibonacci sequence $f_0 = 0$; $f_1 = 1$; $f_n = f_{n-1} + f_{n-2}, n \ge 2$
- Divide and conquer approach:

```
int fib(int n) {
  if(n <= 1) return n;
  return fib(n-1)+fib(n-2);
}</pre>
```

Fibonacci Sequence

Divide and Conquer Solution

```
int fib(int n) {
    if(n <= 1) return n;</pre>
    return fib(n-1)+fib(n-2);
                                   fib(5)
                   fib(4)
                                                   fib(3)
                           fib(2)
                                                          fib(1)
          fib(3)
                                              fib(2)
                                                   fib(0)
                                         fib(1)
              fib(1)
                               fib(0)
    fib(2)
                       fib(1)
                       Subproblems overlap. A lot of computation
fib(1)
        fib(0)
                      is wasted. Time complexity is \Omega(1.5^n).
```

Fibonacci Sequence

Iterative Solution

• We can also compute the Fibonacci sequence in iterative way:

```
int fib(int n) {
  f[0] = 0; f[1] = 1;
  for(i = 2 to n)
    f[i] = f[i-1]+f[i-2];
  return f[n];
}
```

• Time complexity is $\Theta(n)$.

Dynamic Programming

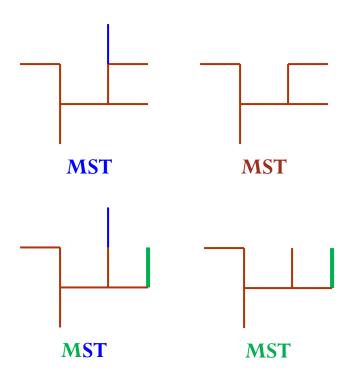
- Used when a problem can be divided into subproblems that overlap.
 - Solve each subproblem once and store the solution in a table.
 - If a subproblem is encountered **again**, simply look up its solution in the table.
 - Reconstruct the solution to the original problem from the solutions to the subproblems.
- The more overlap the better, as this reduces the number of subproblems.
- Dynamic programming can be applied to solve **optimization problem**.

Optimization Problem

- Many problems we encounter are optimization problems:
 - A problem in which some function (called the **objective function**) is to be optimized (usually minimized or maximized) subject to some **constraints**.
- The solutions that satisfy the constraints are called **feasible solutions**.
- The number of feasible solutions is typically very large.
- We obtain the optimal solution by **searching** the feasible solution space.

Optimization Problem

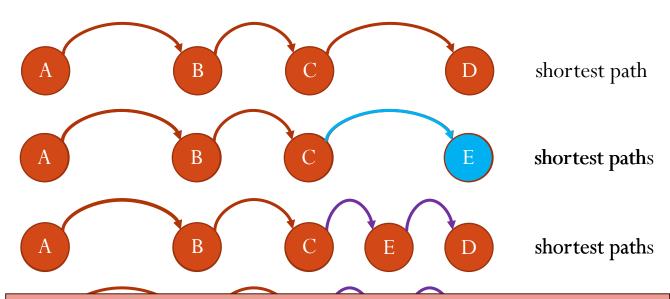
- Minimum spanning tree.
 - Objective function: the sum of all edge weights.
 - Constraints: a subgraph of a MST must also be MSTs.



Optimization Problem

Example

- Shortest path.
 - Objective function: the sum of all edge weights.
 - Constraints: a subgraph of a shortest path must also be shortest paths.



Takeaway: Dynamic Programming is often linked with Induction Book-keep partial results to avoid redundant computation!

Outline

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 - Motivation
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 - Summary

- What is the cost of multiplying two matrices A and B?
 - Suppose A is a $p \times q$ matrix and B is a $q \times r$ matrix.
 - Since the time to compute C = AB is dominated by the number of scalar multiplications, we use the number of scalar multiplications as the complexity measure.
- $\bullet \ C_{ij} = \sum_{k=1}^q A_{ik} B_{kj}.$
 - We need q scalar multiplications to calculate C_{ij} .
 - C is of size $p \times r$.
- The number of scalar multiplications is pqr.

- Now how would you compute the multiplication of three matrices $A \times B \times C$?
 - Suppose A is of size 100×1 , B is of size 1×100 , and C is of size 100×1 .
- If we multiply as $(A \times B) \times C$, the number of scalar multiplications is 20000.
- If we multiply as $A \times (B \times C)$, the number of scalar multiplications is 200.

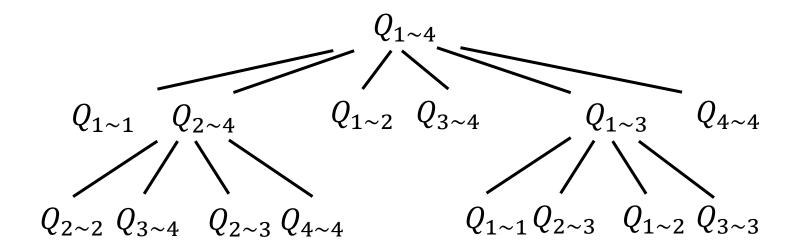
- If we want to multiply a chain of matrices $A_1 \times A_2 \times \cdots \times A_n$, where A_i is of size $p_{i-1} \times p_i$, what is the best order of multiplication to minimize the number of scalar multiplications?
- This is an optimization problem.
- It can be proved that number of different orders on n matrices is $\Omega(4^n/n^{1.5})$.
- Instead of <u>enumerating</u> all of the orders, can we do better to solve the optimization problem?

- For simplicity, define the problem of finding the optimal order to multiply $A_i \times A_{i+1} \times \cdots \times A_j$ as $Q_{i \sim j}$. The minimal number of scalar multiplications is $m_{i \sim i}$.
 - We ultimately want to solve $Q_{1\sim n}$.

- Suppose in the optimal order for $A_i \times \cdots \times A_j$, the <u>last</u> multiplication is $(A_i \times \cdots \times A_k) \times (A_{k+1} \times \cdots \times A_j)$.
- Then the order of computing $A_i \times \cdots \times A_k$ in the **optimal** order of computing $A_i \times \cdots \times A_j$ must be an **optimal** order to compute $A_i \times \cdots \times A_k$.
 - Why?
 - If not, then we copy and paste the better order \rightarrow we have a better order for computing $A_i \times \cdots \times A_i$!
 - Similar conclusion for computing $A_{k+1} \times \cdots \times A_j$.
- If we know k, we can divide the problem $Q_{i\sim j}$ into two smaller instances: $Q_{i\sim k}$ and $Q_{(k+1)\sim j}$.

- Assume we have known the minimum number of scalar multiplications for $Q_{i\sim k}$ and $Q_{(k+1)\sim j}$ as $m_{i\sim k}$ and $m_{(k+1)\sim j}$.
 - Then $m_{i\sim j} = m_{i\sim k} + m_{(k+1)\sim j} + p_{i-1}p_kp_j$.
- However, we don't know k! We need to consider all possible divisions, i.e., all $i \le k \le j-1$.
- Thus, in order to solve $Q_{i\sim j}$, we need to consider all subproblems $Q_{i\sim k}$ and $Q_{(k+1)\sim j}$, for all $i\leq k\leq j-1$.
 - $m_{i\sim j} = \min_{i\leq k\leq j-1} (m_{i\sim k} + m_{(k+1)\sim j} + p_{i-1}p_kp_j)$

• In summary, we can divide the problem into subproblems of the same form.



Many subproblems are overlapped.

- The straightforward recursive algorithm has exponential time complexity.
 - However, it will encounter each subproblem many times in different branches of the tree.
- The total number of different subproblems is not exponential.
 - They are $Q_{i \sim j}$, for $1 \leq i \leq j \leq n$.
 - The total number is n(n+1)/2.
- Instead, we use a **tabular**, **bottom-up** approach.

Bottom-up Approach

• Apply the recursive relation:

$$m_{i\sim j} = \min_{i\leq k\leq j-1}(m_{i\sim k} + m_{(k+1)\sim j} + p_{i-1}p_kp_j)$$

- Initial situation $m_{1\sim 1}=m_{2\sim 2}=\cdots=m_{n\sim n}=0$.
- In the first round, we compute $m_{1\sim 2}$, $m_{2\sim 3}$, ..., $m_{(n-1)\sim n}$.
- In the second round, we compute $m_{1\sim 3}$, $m_{2\sim 4}$, ..., $m_{(n-2)\sim n}$.
- So on and so forth. In the l-th round, we compute $m_{1\sim(l+1)}, m_{2\sim(l+2)}, \ldots, m_{(n-l)\sim n}$.
- Finally, we compute $m_{1 \sim n}$.
- To obtain the multiplication order, we also record the partition k which gives the minimal $m_{i\sim i}$ as $S_{i\sim i}$.

- n = 4, $A_1 \times A_2 \times A_3 \times A_4$.
- $p_0 = 10$, $p_1 = 1$, $p_2 = 10$, $p_3 = 1$, $p_4 = 20$.

	m_{ij}		j		
	melj	1	2	3	4
	1	0			
i	2	_	0		
	3	_	_	0	
	4	_	_		0

	k_{ij}	1	<i>j</i>	3	4
	1	_			
i	2	_	_		
•	3	_	_	_	
	4				_

- $n = 4, A_1 \times A_2 \times A_3 \times A_4$.
- $p_0 = 10$, $p_1 = 1$, $p_2 = 10$, $p_3 = 1$, $p_4 = 20$.

	m_{ij}	1	<i>j</i>	3	1
		1		<u> </u>	
	1	0			
i	2	_	0		
	3	_	_	0	
	4	_	_	_	0

k_{ij}	1	<i>j</i>	3	4
1	_			
2	_	_		
3			_	
4	_	_		_

$$m_{i\sim(i+1)} = m_{i\sim i} + m_{(i+1)\sim(i+1)} + p_{i-1}p_ip_{i+1}$$
$$= p_{i-1}p_ip_{i+1}$$

- $n = 4, A_1 \times A_2 \times A_3 \times A_4$.
- $p_0 = 10$, $p_1 = 1$, $p_2 = 10$, $p_3 = 1$, $p_4 = 20$.

	m_{ij}		j				
	""lj	1	2	3	4		
	1	0	100				
i	2	_	0	10			
	3	_	_	0	200		
	4	_	_	_	0		

k_{ij}	1	<i>j</i>	3	4
1	_	1		
2	_	_	2	
3	_	_	_	3
4	_	_	_	_

$$m_{i\sim(i+1)} = m_{i\sim i} + m_{(i+1)\sim(i+1)} + p_{i-1}p_ip_{i+1}$$
$$= p_{i-1}p_ip_{i+1}$$

- $n = 4, A_1 \times A_2 \times A_3 \times A_4$.
- $p_0 = 10$, $p_1 = 1$, $p_2 = 10$, $p_3 = 1$, $p_4 = 20$.

	m_{ij}	j				
	····lj	1	2	3	4	
	1	0	100			
i	2	_	0	10		
	3	_	_	0	200	
	4	_	_	_	0	

	k_{ij}		j		
	V ij	1	2	3	4
	1	_	1		
•	2	_	_	2	
	3	_	_	_	3
	4	_		_	_

$$m_{i\sim(i+2)} = \min\{m_{i\sim i} + m_{(i+1)\sim(i+2)} + p_{i-1}p_ip_{i+2},$$

$$m_{i\sim(i+1)} + m_{(i+2)\sim(i+2)} + p_{i-1}p_{i+1}p_{i+2}\}$$

- $n = 4, A_1 \times A_2 \times A_3 \times A_4$.
- $p_0 = 10$, $p_1 = 1$, $p_2 = 10$, $p_3 = 1$, $p_4 = 20$.

	m_{ij}	4	j	2	4	
	,	1	2	3	4	
	1	0	100			
i	2	_	0	10		
	3	_	_	0	200	
	4	_	_	_	0	

	k_{ij}	1	<i>j</i>	3	4
	1	_	1		
i	2	_	_	2	
	3	_	_	_	3
	4	_	_	_	_

$$m_{1\sim 3} = \min\{m_{1\sim 1} + m_{2\sim 3} + p_0 p_1 p_3,$$

$$m_{1\sim 2} + m_{3\sim 3} + p_0 p_2 p_3\} = \min\{20, 200\}$$

- $n = 4, A_1 \times A_2 \times A_3 \times A_4$.
- $p_0 = 10$, $p_1 = 1$, $p_2 = 10$, $p_3 = 1$, $p_4 = 20$.

	m_{ij}	j				
	····lj	1	2	3	4	
	1	0	100	20		
i	2	_	0	10		
	3	_	_	0	200	
	4	_	_	_	0	

k_{ij}	1	<i>j</i>	3	4
1	_	1	1	-
2	_	_	2	
3	_	_	_	3
4	_	_	_	_

$$m_{1\sim 3} = \min\{m_{1\sim 1} + m_{2\sim 3} + p_0 p_1 p_3,$$

 $m_{1\sim 2} + m_{3\sim 3} + p_0 p_2 p_3\} = \min\{20, 200\}$

- $n = 4, A_1 \times A_2 \times A_3 \times A_4$.
- $p_0 = 10$, $p_1 = 1$, $p_2 = 10$, $p_3 = 1$, $p_4 = 20$.

	 m_{ij} 1 2 3 4 		j					
		1	2	3	4			
	1	0	100	20				
	10							
	3	_	_	0	200			
	4	_	_	_	0			

	k_{ij}		j				
	reij	1	2	3	4		
	1	_	1	1			
•	2	_	_	2			
	3	_	_	_	3		
	4	_	_	_	_		

$$m_{2\sim 4} = \min\{m_{2\sim 2} + m_{3\sim 4} + p_1 p_2 p_4,$$

$$m_{2\sim 3} + m_{4\sim 4} + p_1 p_3 p_4\} = \min\{400, 30\}$$

- $n = 4, A_1 \times A_2 \times A_3 \times A_4$.
- $p_0 = 10$, $p_1 = 1$, $p_2 = 10$, $p_3 = 1$, $p_4 = 20$.

	m_{ij}	j					k_{ij}	
	• • •	1	2	3	4	_	v)	
	1	0	100	20			1	
i	2	_	0	10	30	i	2	
	3	_	_	0	200		3	
	4	_	_	_	0		4	

k_{ij}		j		
νij	1	2	3	4
1	_	1	1	
2	_	_	2	3
3	_	_	_	3
4	_	_	_	_

$$m_{2\sim 4} = \min\{m_{2\sim 2} + m_{3\sim 4} + p_1 p_2 p_4,$$

$$m_{2\sim 3} + m_{4\sim 4} + p_1 p_3 p_4\} = \min\{400, 30\}$$

- $n = 4, A_1 \times A_2 \times A_3 \times A_4$.
- $p_0 = 10$, $p_1 = 1$, $p_2 = 10$, $p_3 = 1$, $p_4 = 20$.

	m_{ij}	1	<i>j</i>	3	4		k
i	1	0	100	20	'		1
	2	<u> </u>	0	10	30	$_{i}$	2
ı	3	_	_	0	200		3
	4			_	О		4

	k_{ij}		j		
	···ij	1	2	3	4
	1	_	1	1	
i	2	_	_	2	3
	3	_	_	_	3
	4			_	

$$m_{i\sim(i+3)} = \min_{i\leq k\leq i+2} (m_{i\sim k} + m_{(k+1)\sim(i+3)} + p_{i-1}p_k p_{(i+3)})$$

- $n = 4, A_1 \times A_2 \times A_3 \times A_4$.
- $p_0 = 10$, $p_1 = 1$, $p_2 = 10$, $p_3 = 1$, $p_4 = 20$.

	m_{ij}		j		
	····tj	1	2	3	4
	1	0	100	20	
i	2	_	0	10	30
	3	_		0	200
	4	_	_		0

k_{ij}		j		
reij	1	2	3	4
1	_	1	1	
2	_	_	2	3
3	_			3
4	_	_	_	_

$$m_{1\sim 4} = \min_{1\leq k\leq 3} (m_{1\sim k} + m_{(k+1)\sim 4} + p_0 p_k p_4)$$

= \text{min}\{230, 2300, 220}\}

- $n = 4, A_1 \times A_2 \times A_3 \times A_4$.
- $p_0 = 10$, $p_1 = 1$, $p_2 = 10$, $p_3 = 1$, $p_4 = 20$.

	m_{ij}		j			k_{ij}		j		
		1	2	3	4		1	2	3	4
	1	0	100	20 (220	Optimal Value	_	1	1	3
i	2		0	10	30	i^{-2}			2	3
	3		_	0	200	3				3
	4		_	_	0	4	_			_

$$m_{1\sim 4} = \min_{1\leq k\leq 3} (m_{1\sim k} + m_{(k+1)\sim 4} + p_0 p_k p_4)$$

= \min\{230, 2300, 220\}

Constructing an Optimal Order

• We can construct an optimal order based on the records S_{ij} .

```
Print Order(s, i, j) {
  if(i == j) cout << "A;";</pre>
  else {
     cout << "(";
     Print_Order(s, i, s<sub>ij</sub>);
     cout << "*";
     Print_Order(s, s<sub>ij</sub>+1, j);
     cout << ")";
```

• Initial call is Print Order(s, 1, n);

- Construct an optimal order
 - n = 4, $A_1 \times A_2 \times A_3 \times A_4$.
 - $p_0 = 10, p_1 = 1, p_2 = 10, p_3 = 1, p_4 = 20.$

$$k_{14} = 3$$
 $A_1 \times A_2 \times A_3 \times A_4 = (A_1 \times A_2 \times A_3) \times A_4$

$$k_{13} = 1$$
 $A_1 \times A_2 \times A_3 = A_1 \times (A_2 \times A_3)$

$$k_{23} = 2$$
 $A_2 \times A_3 = A_2 \times A_3$

$$A_1 \times A_2 \times A_3 \times A_4 = (A_1 \times (A_2 \times A_3)) \times A_4$$

Time Complexity

- Get the minimum number of scalar multiplications:
 - We need to obtain all m_{ij} and s_{ij} , for $1 \le i \le j \le n$.
 - $O(n^2)$ records
 - Each $m_{i \sim i}$ is the minimum of O(n) terms.
 - Total time complexity is $O(n^3)$.
- Obtain the optimal order:
 - \bullet O(n)

Summary

- Matrix-chain multiplication is an optimization problem.
- The solution is based on **dynamic programming**.
 - The original problem can be divided into same subproblems that **overlap**.
 - Each subproblem is solved once and stored in a table.
 - If a subproblem is encountered again, simply look up its solution in the table.
 - Reconstruct the solution to the original problem from the solutions to the subproblems.

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Dynamic Programming for Optimization

- There are two key ingredients that an optimization problem must have in order for dynamic programming to apply:
 - Optimal substructure;
 - Overlapping subproblems.

Optimal Substructure

- An optimal solution to the problem contains within it optimal solutions to subproblems.
 - In matrix-chain multiplication, the optimal order on calculating $A_i \times \cdots \times A_j$ that splits the product between A_k and A_{k+1} contains within it optimal solutions to the problem of ordering $A_i \times \cdots \times A_k$ and $A_{k+1} \times \cdots \times A_j$.
- You can show optimal substructure property by supposing that each of the subproblem solutions is not optimal and then deriving a contradiction.

Overlapping Subproblems

- A recursive algorithm for the problem solves the same subproblems **over and over**, rather than always generating new subproblems.
 - E.g., subproblems of matrix-chain multiplication overlap.
 - In contrast, a problem for which a divide-and-conquer approach is suitable usually generates **brand-new** problems at each step of the recursion.
- Dynamic-programming algorithms take advantage of overlapping subproblems by
 - solving each subproblem once ...
 - ... and then storing the solution in a table where it can be looked up when needed.

Designing a Dynamic-Programming Algorithm

- 1. Characterize the structure of an optimal solution.
 - Usually, we need to define a general problem.
- 2. Recursively define the value of an optimal solution.
- 3. Compute the value of an optimal solution, typically in a **bottom-up** fashion.
- 4. Construct an optimal solution from computed information.