## **LEC007 Inventory Management II**

#### VG441 SS2021

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# Wagner-Whitin Model

#### INPUT:

- Deterministic demand (non-stationary) over T periods  $(d_1, d_2, d_3, ..., d_{T-1}, d_T)$
- No stockout is allowed
- Lead time L (setting L = 0 WLOG)
- Fixed cost K > 0 per order
- Purchase cost c per unit (setting c = 0 WLOG)
- Inventory hold cost h > 0 per unit per unit of time

#### **OUTPUT:**

The optimal ordering strategy

# Mixed Integer Linear Program (MILP)

 $\forall t = 1, \dots, T$ 

#### **Decision Variables**

```
q_t = the number of units ordered in period
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 $y_t = 1$  if we order in period t, 0 otherwise

 $y_t \in \{0, 1\}$ 

 $x_t =$ the inventory level at the end of period, with  $x_0 \equiv 0$ 

minimize  $\sum_{t=1}^{T} (Ky_t + hx_t)$ subject to  $x_t = x_{t-1} + q_t - d_t \quad \forall t = 1, \dots, T$   $q_t \leq My_t \quad \forall t = 1, \dots, T$   $x_t \geq 0 \quad \forall t = 1, \dots, T$   $q_t \geq 0 \quad \forall t = 1, \dots, T$ 

Inventory-balance constraint

Linking constraint ("a common trick")

## **ZIO Property**

• It is optimal to place orders only in time periods in which the inventory level is zero.

• This suggests that each order is of a size equal to the total demand in an integer number of subsequent periods, i.e., in period t, we either order  $d_t$ ,

or 
$$d_t + d_{t+1}$$
,  
or  $d_t + d_{t+1} + d_{t+2}$ ,  
and so on.

# **Dynamic Programming**

• Define  $\theta_t$  to be the optimal cost in periods [t, T] if we place optimal orders over [t, T].

$$\theta_t = \min_{t < s \leq T+1} \left\{ K + h \sum_{i=t}^{s-1} (i-t) d_i + \theta_s \right\}$$
 Cost of covering demands of periods 
$$t, t+1, \dots, s-1$$

Boundary condition:

$$\theta_{T+1} \equiv 0$$

# **Dynamic Programming**

### Backward induction

$$\theta_t = \min_{t < s \le T+1} \left\{ K + h \sum_{i=t}^{s-1} (i-t)d_i + \theta_s \right\}.$$
 (3.39)

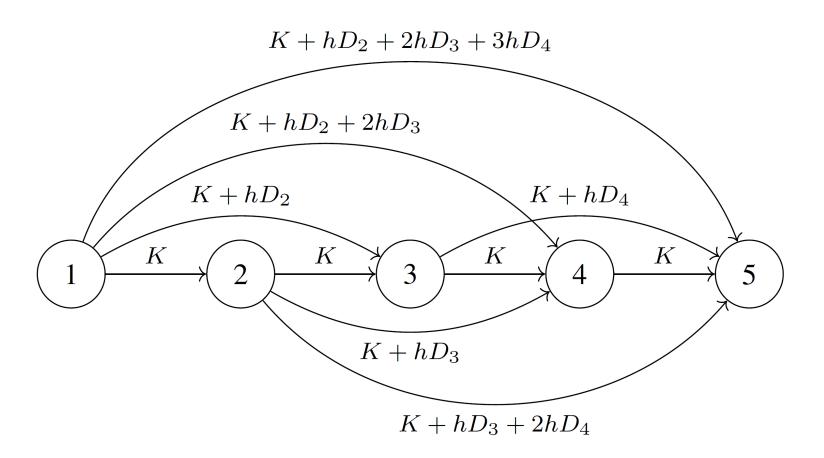
#### **Algorithm 3.1** Wagner–Whitin algorithm

## **Numerical Example**

K = 500, h = 2 per period. The demands are 90, 120, 80, and 70.

$$\begin{aligned} \theta_5 &= 0 \\ \theta_4 &= K + h \left( 0 \cdot d_4 \right) + \theta_5 \\ &= 500 \quad [s(4) = 5] \\ \theta_3 &= \min \left\{ K + h \left( 0 \cdot d_3 \right) + \theta_4, K + h \left( 0 \cdot d_3 + 1 \cdot d_4 \right) + \theta_5 \right\} \\ &= \min \{1000, 640\} \\ &= 640 \quad [s(3) = 5] \\ \theta_2 &= \min \left\{ K + h \left( 0 \cdot d_2 \right) + \theta_3, K + h \left( 0 \cdot d_2 + 1 \cdot d_3 \right) + \theta_4 \right. \\ &\quad K + h \left( 0 \cdot d_2 + 1 \cdot d_3 + 2 \cdot d_4 \right) + \theta_5 \right\} \\ &= \min \{1140, 1160, 940\} \\ &= 940 \quad [s(2) = 5] \\ \theta_1 &= \min \left\{ K + h \left( 0 \cdot d_1 \right) + \theta_2, K + h \left( 0 \cdot d_1 + 1 \cdot d_2 \right) + \theta_3 \right. \\ &\quad K + h \left( 0 \cdot d_1 + 1 \cdot d_2 + 2 \cdot d_3 \right) + \theta_4 \\ &\quad K + h \left( 0 \cdot d_1 + 1 \cdot d_2 + 2 \cdot d_3 + 3 \cdot d_4 \right) + \theta_5 \right\} \\ &= \min \{1440, 1380, 1560, 1480\} \\ &= 1380 \quad [s(1) = 3] \end{aligned}$$

## If you think about this...



**Figure 3.12** Wagner–Whitin network.

## **Shortest Path Problem**

## Input:

- Directed Graph G(V, E) with |V| = n, |E| = m
- Each edge  $e \in E$  has non-negative length  $l_e \ge 0$
- Source vertex s

### Output:

For each  $v \in V$ , compute

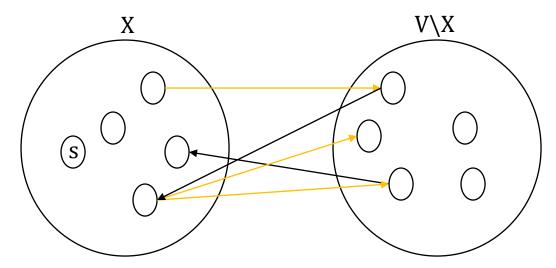
L(v) = length of a shortest s-v path in G

Fastest algorithm is called Dijkstra's Algorithm

Caveat: length/weight/travel time  $l_e \ge 0$ !

# Dijkstra's Algorithm

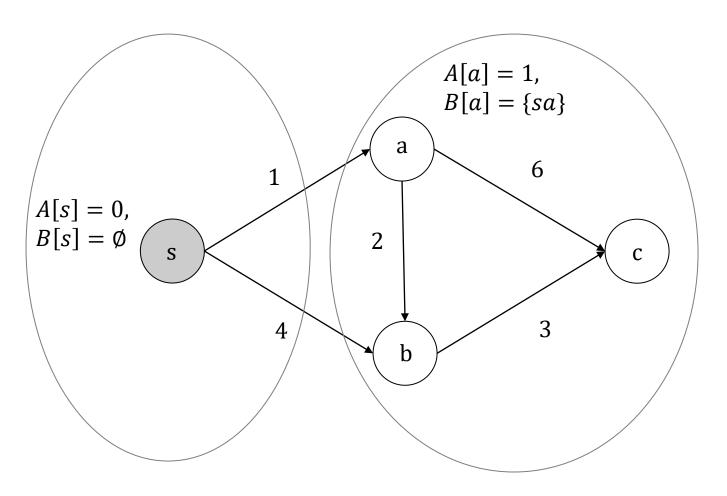
- Initialize  $X = \{s\}, A[s] = 0, B[s] = \emptyset$
- Main loop
  - While  $X \neq V$



- ▶ Of all edges  $(v, w) \in E$  with  $v \in X$  and  $w \notin X$ , pick the one that minimizes  $A[v] + l_{vw}$  (Dijkstra's greedy criterion)
- ► Call the minimizing edge  $(v^*, w^*)$  and add vertex  $w^*$  to X
- ► Set  $A[w^*] = A[v^*] + l_{v^*w^*}$
- $\blacktriangleright \operatorname{Set} B[w^*] = B[v^*] \cup (v^*, w^*)$

## An Example

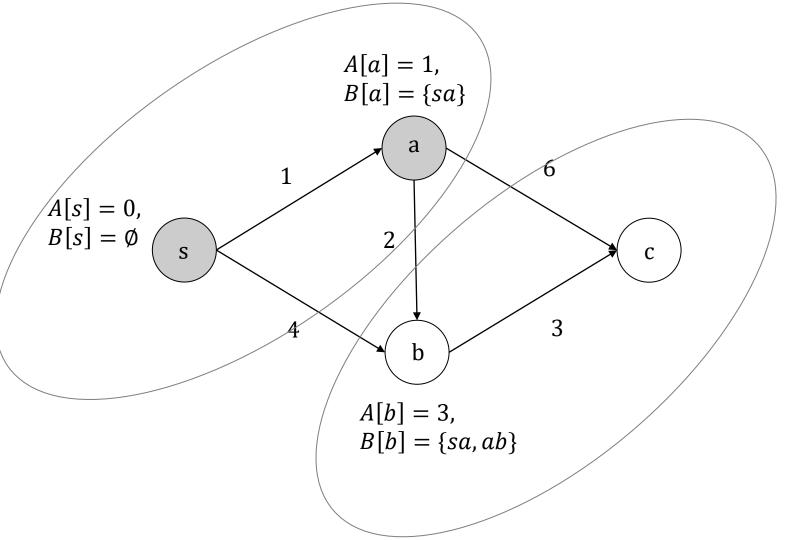
$$A[v] + l_{vw}$$
 (Dijkstra's greedy criterion)  
min  $(A[s] + l_{sa}, A[s] + l_{sb}) = \min(0 + 1, 0 + 4) = 1$ 



## An Example

 $A[v] + l_{vw}$  (Dijkstra's greedy criterion)

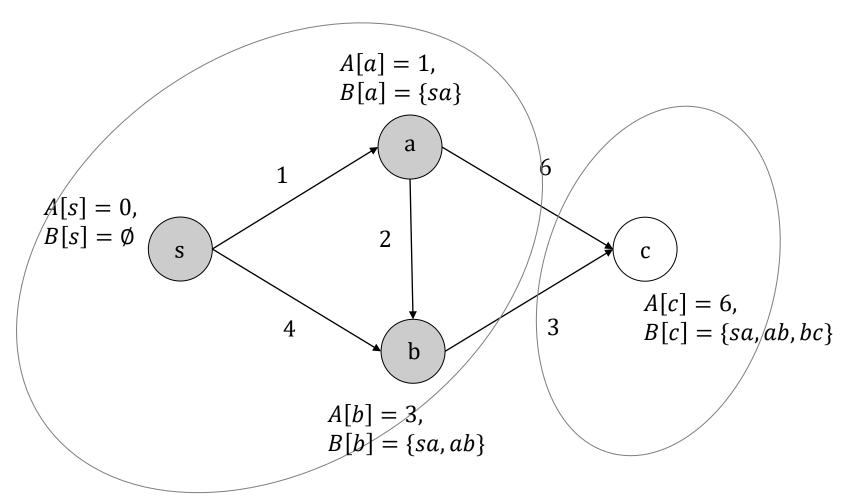
 $\min (A[s] + l_{sb}, A[a] + l_{ab}, A[a] + l_{ac}) = \min (0 + 4, 1 + 2, 1 + 6) = 3$ 



## An Example

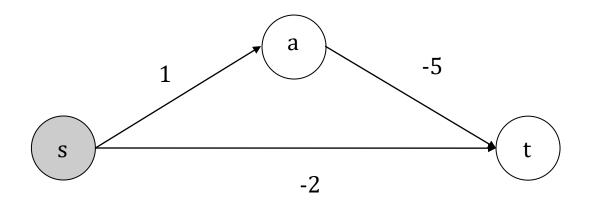
 $A[v] + l_{vw}$  (Dijkstra's greedy criterion)

$$min(A[a] + l_{ac}, A[b] + l_{bc}) = min(1 + 6, 3 + 3) = 6$$



## Non-Example

Dijkstra is incorrect on this G



• Use dynamic programming in this case

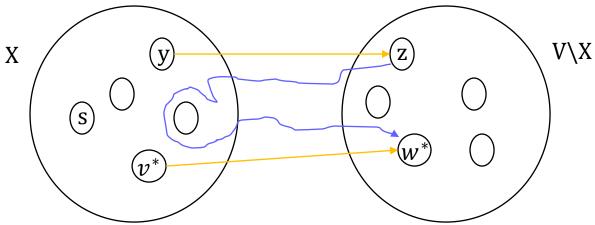
## **Proof of Correctness**

Claim: A[v] = L[v] where A is the output of Dijkstra and L is true shortest distance

Proof: By induction, base case A[s] = L[s] = 0 is true.

Inductive Hypothesis (I.H.): all previous iterations are corrrect, i.e.,

 $\forall v \in X, A[v] = L[v]$  and B[v] gives the shortest path



In the current iteration, Dijkstra have chosen  $v^*w^*$ , we have  $A[w^*] = A[v^*] + l_{v^*w^*}$ Now let P be any  $s \to w^*$  path and it must "cross the frontier"



Length of P  $\geq L(y) + l_{yz} + 0 = A(y) + l_{yz} + 0$ , note that L(y) = A(y) by I.H. Also, by Dijkstra's greedy criterion,

Our length = 
$$A[v^*] + l_{v^*w^*} \le A(y) + l_{yz} \le$$
 Length of P

## General Graph Search

- Let q be an abstract queue object
  - add(node), which adds a node into q
  - popFirst(), which pops the first node from q
- General graph search

While q is not empty:

- $\triangleright v \leftarrow q.popFirst()$
- ▶ For all neighbors u of v such that  $u \notin q$ :
  - add(u)

## General Graph Search

- General graph search
  - While q is not empty:
    - $\triangleright v \leftarrow q.popFirst()$
    - ▶ For all neighbors u of v such that  $u \notin q$ :
      - add(u)
- If q is a standard LIFO stack, then DFS
- If q is a standard FIFO queue, then BFS
- If q is a priority queue, then Dijkstra
- If q is a priority queue with a heuristic, then A\*

# **Priority Queue Implementation**

- $A[s] \leftarrow 0$ , and  $A[v] \leftarrow \infty$  for all  $v \in V \setminus \{s\}$
- q.add(s)
- While q is not empty: Extract min-q
  - $\triangleright v \leftarrow q.popFirst()$
  - ▶ For all neighbors u of v such that  $A[v] + l_{vu} \le A[u]$ 
    - $A[u] \leftarrow A[v] + l_{vu}$
    - q.update(u, A[u])

Decrease-key(q)

Runtime: If using binary minheap,  $O((|E| + |V|)\log |V|)$ If using Fibonacci minheap,  $O(|E| + |V|)\log |V|)$ 

## Summary

- Wagner-Whitin model
- Dynamic Programming
- Shortest Path (Dijkstra's Algorithm)
- Next Up: Stochastic Inventory Model