

vv256: Week 3. Singular Solutions. Linear Spaces. Eigenvalues and Eigenvectors.

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Outline

- 1 Lecture 6: Implicit first-order ODEs. Singular solutions.
 - Implicit first-order ODEs
 - Singular Solutions
- 2 Lecture 7: Linear (vector) spaces and elements of linear algebra.
 - Structure of a linear space.
 - The Wronskian
 - Systems of linear algebraic equations
- 3 Lecture 8: Eigenvalues and Eigenvectors

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be general solutions of (2). **What is the general solution of the equation (1)?**

$$\Phi_1(t, y, C) \cdot \Phi_2(t, y, C) \cdot \dots \cdot \Phi_k(t, y, C) = 0$$

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If a general solution of this equation has the representation $y = \Theta(p, C)$, where Θ is known and C is a constant, then

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Exercise: Find the general solution if $t = \varphi(y')$.

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What happens if $y = \psi(y')$?

Implicit first-order ODEs

What is common in cases 2 and 3?

- In both cases equations are explicit with respect to either t or y , and
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- we differentiate w.r.t. another variable.
- New equations are explicit w.r.t. corresponding derivatives

However, new explicit equations may not have analytical representation of the solution!!!

We are to consider two types of equations for which the approach described above works and explicit equations are solvable.

Lagrange Equation

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$$(\varphi(p) - p)\frac{dt}{dp} + \varphi'(p)t + \psi'(p) = 0.$$

What is the type of this equation? **Linear** \Rightarrow Find its solution $t = \Phi(p, C)$ and obtain the general solution of the Lagrange equation in the form

$$\begin{cases} t = \Phi(p, C) \\ y = \Phi(p, C)\varphi(p) + \psi(p) \end{cases}$$

Attention! The Lagrange equation may also have special solutions of the form $y = \varphi(c)t + \psi(c)$, where c is the root of the equation $\varphi(c) = 0$. We will consider the question of special solutions later.

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Therefore, plugging C instead of y' in Clairaut's equation we immediately obtain the general solution. **How we can get a singular solution from the general one? Differentiate w.r.t C .**

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We have $y' = t$ and $y' = y$. Then $y = \frac{t^2}{2} + C$, $y = Ce^t$ and the general solution is

$$(y - \frac{t^2}{2} - C)(y - Ce^t) = 0.$$

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Case 2 $\Rightarrow y' = p$ and $y = p + p^2 e^p$. Therefore, $dt = \frac{1+(p^2+2p)e^p}{p} dp$ and $t = \ln |p| + (p+1)e^p + C$. The general solution has the form

$$\begin{cases} t = \ln |p| + (p+1)e^p + C \\ y = p + p^2 e^p \end{cases}$$

We need to complement it with the obvious solution $y = 0$.

Exercises

Solve the following ODEs:

$$1. (y')^2 - 2ty' - 8t^2 = 0.$$

$$2. t^2(y')^2 + 3tyy' + 2y^2 = 0.$$

$$3. (y')^3 - y(y')^2 - t^2y' + t^2y = 0.$$

$$4. t = \ln y' + \sin y'.$$

$$5. y = \sin^{-1} y' + \ln(1 + (y')^2).$$

$$6. y = ty' + y' + \sqrt{y'}.$$

$$7. y = y' \ln y'.$$

$$8. y = 3/2ty' + e^{y'}.$$

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- both solutions have the same tangent at the point (t_0, y_0) but
- another non-singular solution is different from the singular one in any arbitrary small neighborhood of the point (t_0, y_0) .

Singular Solutions

Does a singular solution satisfies the equation (3)? Yes. Moreover, if $F(t, y, y')$, $\frac{\partial F}{\partial y}$, $\frac{\partial F}{\partial y'}$ are continuous with respect to all arguments t, y, y' then any singular solution satisfies the equation

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How can we find a singular solutions from (3) and (4)? \Rightarrow Eliminate y' . Elimination gives us an equation

$$\psi_p(t, y) = 0$$

which is called **p -discriminant** of the equation (3), and the integral curve corresponding p -discriminant is called the **p -discriminant integral curve**.

Is a p -discriminant curve unique? Does it define a singular solution? In general, no. \Rightarrow Double-check.

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An **envelope** of the family of parametric curves is a smooth curve Γ that touches one curve of the family at any of its points, and any of its segments is touched by an infinite number of curves from the family.

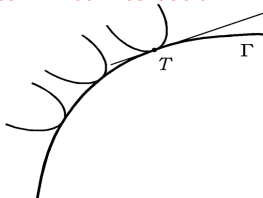
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An envelope is a part of a C -discriminant curve defined a by

$$\begin{cases} \Phi(t, y, C) = 0 \\ \frac{\partial \Phi(t, y, C)}{\partial C} = 0 \end{cases}$$

To make sure that a branch of a C -discriminant curve is an envelope, we check the following conditions.

- there exist bounded partial derivatives
$$\left| \frac{\partial \Phi}{\partial t} \right| \leq M, \left| \frac{\partial \Phi}{\partial y} \right| \leq N, M, N = \text{const},$$
- $\frac{\partial \Phi}{\partial t} \neq 0$, or, $\frac{\partial \Phi}{\partial y} \neq 0$

Are these condition are necessary or sufficient? Sufficient. \Rightarrow if they are not satisfied on a branch of the C -discriminant curve, it can still be an envelope.

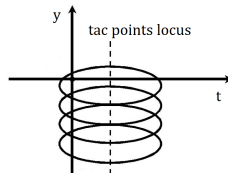
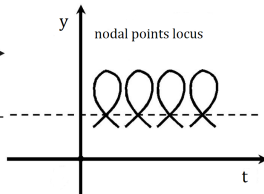
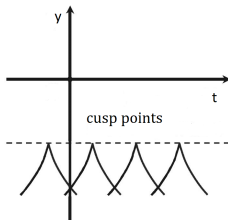
Singular Solutions

The equations of p -discriminant and C -discriminant have a certain structure

$$\psi_p(t, y) = E \cdot C \cdot T^2 = 0,$$

$$\psi_C(t, y) = E \cdot N^2 \cdot C^3 = 0,$$

where $E = 0$ is the equation of the envelope, $C = 0$ is the equation of the cusp locus, $N = 0$ is the equation of nodal locus, $T = 0$ is the equation of the tac locus. Attention! Over all locus points only the envelope is a singular solution.



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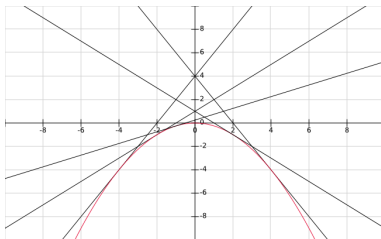
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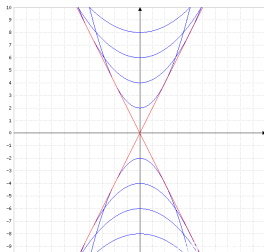
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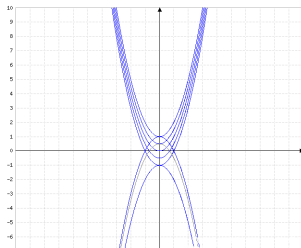
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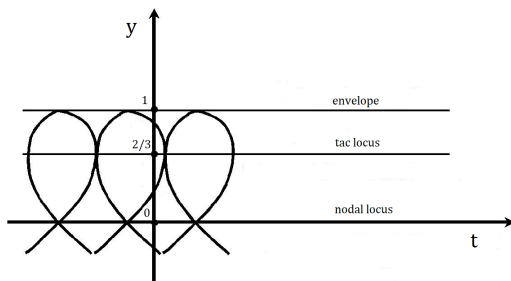
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3. Find the C -discriminant curve $y^2(1 - y) = 0$.



Singular Solutions: Exercises

For the following equations, find singular solutions if they exist.

1. $(1 + (y')^2)y^2 - 4yy' - 4t = 0,$

2. $(y')^2 - 4y = 0,$

3. $(y')^3 - 4tyy' + 8y^2 = 0,$

4. $(y')^2 - y^2 = 0,$

5. $(ty' + y)^2 + 3t^5(ty' - 2y) = 0.$

Use C -discriminant to find singular solutions for the following equations 1. $y = (y')^2 - ty' + t^2/2, y = Ct + C^2 + t^2/2,$

2. $(ty' + y)^2 = y^2y', y(C - t) = C^2,$

3. $y^2(y')^2 + y^2 = 1, (x - C)^2 + y^2 = 1,$

4. $(y')^2 - yy' + e^t = 0, y = Ce^t + 1/C.$

Outline

- 1 Lecture 6: Implicit first-order ODEs. Singular solutions.
 - Implicit first-order ODEs
 - Singular Solutions
- 2 Lecture 7: Linear (vector) spaces and elements of linear algebra.
 - Structure of a linear space.
 - The Wronskian
 - Systems of linear algebraic equations
- 3 Lecture 8: Eigenvalues and Eigenvectors

Definition

Let \mathbb{K} denote a scalar field (either \mathbb{R} or \mathbb{C}).

A set X is called a **linear (or vector) space over the scalar field \mathbb{K}** if there are two binary operations of addition and scalar multiplication defined on X

$$a) \forall x, y \in X \Rightarrow x + y \in X$$

$$b) \forall x \in X, \forall \alpha \in \mathbb{K} \Rightarrow \alpha x \in X$$

satisfying the following properties:

$$1. x + y = y + x \quad \forall x, y \in X \quad \text{commutativity}$$

$$2. x + (y + z) = (x + y) + z \quad \forall x, y, z \in X \quad \text{associativity}$$

$$3. \exists 0 \in X : 0 + x = x + 0 = x \quad \forall x \in X$$

$$4. \forall x \in X \exists (-x) \in X : x + (-x) = 0$$

$$5. 1 \cdot x = x \quad \forall x \in X \quad 6. (\alpha\beta)x = \alpha(\beta x) \quad \forall x \in X \forall \alpha, \beta \in \mathbb{K}$$

$$7. \alpha(x+y) = \alpha x + \alpha y \quad 8. (\alpha+\beta)x = \alpha x + \beta x \quad \forall x, y \in X \forall \alpha, \beta \in \mathbb{K}$$

Examples of Linear Spaces

- \mathbb{R}, \mathbb{C}
- $\mathbb{R}^n = \{x = (x_1, x_2, \dots, x_n) : x_i \in \mathbb{R}, i = 1, \dots, n\}, \mathbb{C}^n$
- $l_\infty = \{x = (x_1, x_2, \dots) : x_i \in \mathbb{K}, i = \overline{1, \infty}, \sup_{i=\overline{1, \infty}} |x_i| < \infty\}$
- $l_1 = \{x = (x_1, x_2, \dots) : x_i \in \mathbb{K}, i = \overline{1, \infty}, \sum_{i=1}^{\infty} |x_i| < \infty\}$
- $l_p = \{x = (x_1, x_2, \dots) : x_i \in \mathbb{K}, i = \overline{1, \infty}, \sum_{i=1}^{\infty} |x_i|^p < \infty\}$
- $C[a, b]$ = the set of all continuous functions defined on $[a, b]$

You need to prove that for any two elements of a set their sum and a scalar product are also elements of the same set and all axioms hold.

Linear Independence

We say that elements x_1, x_2, \dots, x_n of a linear space X over \mathbb{K} are **linearly independent** if the equality

$$\alpha_1 x_1 + \alpha_2 x_2 + \dots + \alpha_n x_n = 0, \quad \alpha_i \in \mathbb{K}, i = \overline{1, n}$$

implies that $\alpha_1 = \alpha_2 = \dots = \alpha_n = 0$. If there is at least one $\alpha_1 \neq 0$ then the elements x_1, x_2, \dots, x_n are called **linearly dependent**.

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For example, consider two system of elements in $C[0, \pi/2]$:

$$x_1(t) = 1, x_2(t) = \sin^2 t, x_3(t) = \cos 2t \text{ and}$$

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Are they linearly dependent or independent? Consider $\alpha_1 x_1(t) + \alpha_2 x_2(t) + \alpha_3 x_3(t) = 0$ for all $t \in [0, \pi/2]$ and determine the values of α_i , $i = 1, 2, 3$ for the each case. What can you say about the elements of the linearly dependent system?

Exercises

Exercise 1: Prove that the system of elements of a linear space is linearly dependent if and only if one of those elements can be expressed as a linear combination of others.

Exercise 2: Prove that following systems are linearly independent

$$1, t, t^2, \dots, t^n;$$

$$e^{at}, te^{at}, t^2e^{at}, \dots, t^ne^{at}, a \neq 0;$$

$$\cos at, \sin at, t \cos at, t \sin at, \dots, t^n \cos at, t^n \sin at, a \neq 0;$$

$$e^{at} \cos bt, e^{at} \sin bt, te^{at} \cos bt, te^{at} \sin bt, \dots,$$

$$t^ne^{at} \cos bt, t^ne^{at} \sin bt, a, b \neq 0.$$

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What is dimension of \mathbb{R} ? $\dim \mathbb{R} = 1$. Why? What about $\dim \mathbb{R}^2, \dim \mathbb{R}^n, \dim C[a, b], \dim l_\infty, \dim l_1, \dim l_p$?

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Proof:

Consider the functions $1, t, t^2, \dots, t^n$ with $n \in \mathbb{N}$ and arbitrary scalars $\alpha_1, \alpha_2, \dots, \alpha_{n+1}$. If $\alpha_1 + \alpha_2 t + \alpha_3 t^2 + \dots + \alpha_{n+1} t^n = 0$ then $\alpha_1 = \alpha_2 = \dots = \alpha_{n+1} = 0 \Rightarrow \{t^i\}$ is a basis but n is arbitrary \Rightarrow infinite dimension.

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- **Inner product spaces:** A linear space with an inner product

$$(\cdot, \cdot) : X \times X \rightarrow \mathbb{C}$$

$$1. (x, x) \geq 0, (x, x) = 0 \text{ iff } x = 0,$$

$$2. (\alpha x + \beta y, z) = \alpha(x, z) + \beta(y, z) \quad 3. (y, x) = \overline{(x, y)}$$

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- What do we need to know to prove that $\|x\| = \sqrt{(x, x)}$ in any inner product space?
- Are metrics, norms and inner products continuous functions?
What is a continuous function?

The Wronskian

The **Wronskian** of n smooth enough functions is defined by

$$W[f_1, f_2, \dots, f_n](t) = \begin{vmatrix} f_1(t) & f_2(t) & \dots & f_n(t) \\ f_1'(t) & f_2'(t) & \dots & f_n'(t) \\ \dots & \dots & \dots & \dots \\ f_1^{(n-1)}(t) & f_2^{(n-1)}(t) & \dots & f_n^{(n-1)}(t) \end{vmatrix}$$

What is a smooth enough function? A continuously differentiable function.

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What happens if $W[f_1, \dots, f_n](t) \neq 0$? Functions are linearly independent!

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The **Wronskian** of n elements $x^1(t), x^2(t), \dots, x^n(t)$ of n components each is

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Systems of Linear Algebraic Equations

Consider a system of n linear algebraic equations in n unknown written in the matrix form

$$Ax = b,$$

where $A = (a_{ij})$ is the $n \times n$ matrix, $x = (x_1, x_2, \dots, x_n)$ is unknown and $b = (b_1, b_2, \dots, b_n)$ is given.

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- if $\det A = 0$, $b \neq 0$ then the system has no solutions but if b satisfies the condition $\sum b_i y_i = 0$ for all $y = (y_1, y_2, \dots, y_n)$ such that $\bar{A}^T y = 0$.

Systems of Linear Algebraic Equations

How can we find a solution? Cramer's rule, Gaussian elimination

Consider the procedures for the sample system

$$\begin{cases} 2x_1 - x_2 + x_3 = -3, \\ x_1 + 2x_2 + 2x_3 = 5, \\ 3x_1 - 2x_2 - x_3 = -8 \end{cases}$$

and apply Cramer's method and Gaussian elimination to solve it.

Outline

- 1 Lecture 6: Implicit first-order ODEs. Singular solutions.
 - Implicit first-order ODEs
 - Singular Solutions
- 2 Lecture 7: Linear (vector) spaces and elements of linear algebra.
 - Structure of a linear space.
 - The Wronskian
 - Systems of linear algebraic equations
- 3 Lecture 8: Eigenvalues and Eigenvectors

Eigenvalues and Eigenvectors

Consider the equation $Ax = y$, where $A = (a_{ij})_{n \times n}$ is a matrix of scalars. Recall that any matrix defines a mapping on finite dimensional linear spaces and vice versa. How can we prove it?

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Definition: The value of λ for which there are nonzero vectors x satisfying the eq. is called the **eigenvalue** of A , and those nonzero vectors x are called the **eigenvectors** of A associated with λ .

How can we find x ? $(A - \lambda I)x = 0 \Rightarrow \det(A - \lambda I) = 0$ for nonzero solutions. This is a polynomial equation of degree n whose n roots are the eigenvalues of A . The roots can be real or complex, single or repeated, or any combination of these cases.

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Thus, $x_1 - x_2 = 0 \Rightarrow$ if $x_1 = a$ then

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The eigenvectors corresponding to $\lambda_1 = 2$ are nonzero solutions of the system $(A - 2I)x = 0$

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Exercise: Compute eigenvalues and corresponding eigenvectors for the following matrices

$$\begin{pmatrix} 2 & -2 & 1 \\ -1 & 3 & -1 \\ 2 & -4 & 3 \end{pmatrix}, \quad \begin{pmatrix} 2 & -1 & 2 \\ -2 & 3 & -4 \\ 1 & -1 & 3 \end{pmatrix}, \quad \begin{pmatrix} 0 & 1 & -2 \\ -1 & 0 & 2 \\ 2 & -2 & 0 \end{pmatrix}$$

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- The eigenvalues of A are the same as the eigenvalues of A^T .
- If λ is an eigenvalue of A with an eigenvector x , then λ^k is an eigenvalue of A^k with a corresponding eigenvector x , $c\lambda$ is an eigenvalue of cA with a corresponding eigenvector x , and $C_m\lambda^m + C_{m-1}\lambda^{m-1} + \dots + C_1\lambda + C_0$ is an eigenvalue of $C_mA^m + C_{m-1}A^{m-1} + \dots + C_1A + C_0I$ with a corresponding eigenvector x . **Prove it.**

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$$\begin{aligned} 0 &= (A - \lambda_1 I)(C_1 x^1 + C_2 x^2) = C_1 (A - \lambda_1 I)x^1 + \\ &+ C_2 (A - \lambda_1 I)x^2 = C_2 (Ax^2 - \lambda_1 x^2) = C_2 (\lambda_2 - \lambda_1)x^2, \end{aligned}$$

and hence, $C_2 = 0$. **Prove that $C_1 = 0$ as well.** $\Rightarrow x^1, x^2$ are linearly independent.

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Therefore, if A and B are similar matrices then they have the same characteristic polynomial, the same eigenvalues, and if x is an eigenvector of B then Tx is the eigenvector of A .

Prove that $A^k = TB^kT^{-1}$, $k = 1, 2, \dots$

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Prove that the eigenvalues of an upper triangular matrix and a lower triangular matrix are the diagonal elements.

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Exercise: Prove that the matrix $A = \begin{pmatrix} 2 & -2 & 1 \\ -1 & 3 & -1 \\ 2 & -4 & 3 \end{pmatrix}$ can be

diagonalized as follows

$$A = \begin{pmatrix} 2 & -1 & 1 \\ 1 & 0 & -1 \\ 0 & 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 6 \end{pmatrix} \begin{pmatrix} 1/5 & 3/5 & 1/5 \\ -2/5 & 4/5 & 3/5 \\ 1/5 & -2/5 & 1/5 \end{pmatrix}$$