# **Review of Probability**

# SciPy.Stats Package

The <u>SciPy.Stats Package (https://docs.scipy.org/doc/scipy/reference/stats.html)</u> contains a large number of probability distributions as well as a growing library of statistical functions.

- · Continuous distributions
- · Multivariate distributions
- Discrete distributions
- · Statistical functions

```
In [ ]: from scipy import stats
  import matplotlib.pyplot as plt
  import numpy as np
  import pandas as pd
  %pylab inline
```

# Some functions to help plotting

```
In [ ]: | def prob(rv, a, b):
            return 1-(rv.cdf(a)+(1-rv.cdf(b)))
        def plotDist(x, func, title, 1, xlabel, ylabel) :
            #plt.figure(fig)
            plt.plot(x, func, 'bo', ms=4, label=1) # plot func for elements of x
            xl = plt.gca().get_xlim()
            plt.hlines(0, x1[0], x1[1], linestyles='--', colors='#999999') #lines on Y-axi
            plt.gca().set xlim(xl)
            plt.vlines(x, 0, func, colors='r', lw=2, alpha=0.5) # lines on X-axis
            plt.legend(loc='best', frameon=False)
            plt.xlabel(xlabel)
            plt.ylabel(ylabel)
            plt.title(title)
            plt.show()
        def plotDist2(x, func, title, 1, xlabel, ylabel) :
            plt.plot(x, func, 'b-', lw=2, alpha=0.6, label=1) # plot func for elements of
            xl = plt.gca().get xlim()
            plt.hlines(0, xl[0], xl[1], linestyles='--', colors='#999999') #lines on Y-axi
            plt.gca().set xlim(xl)
            #plt.vlines(x, 0, func, colors='r', lw=2, alpha=0.5) # lines on X-axis
            plt.legend(loc='best', frameon=False)
            plt.xlabel(xlabel)
            plt.ylabel(ylabel)
            plt.title(title)
        def plotHistDist(func, x, r, title, l, xlabel, ylabel):
            plt.hist(r, normed=True, histtype='stepfilled', alpha=0.2)
            plotDist2(x, func, title, 1, xlabel, ylabel)
```

# **Main Concepts**

# **Experiments and Events**

Experiment is to make observations, events are outcomes

- Simple event is non-decomposed (a sample point)
- Compound event is composed of simple events

# **Probability**

- A Sample Space (or Population) S is the set of all (can be infinitely many) simple events.
- Probability P(A) is a number assigned to event A
  - $0 \le P(A) \le 1$
  - P(S) = 1
  - $P(A_1 \cup A_2) = P(A_1) + P(A_2) P(A_1 \cap A_2)$  for any  $A_1, A_2 \subset S$

# **Example**

A box contains 500 colored balls, among them  $n_1$  in red,  $n_2$  in green,  $n_3$  in white,  $n_4$  in blue and  $n_5$  in black. If a ball is randomly selected from the box, what is the probability that

- a red ball is selected?
- a red or a white ball is selected?
- Neither a black nor a blue ball is selected?

Let A be the event that a red or a black ball is selected and B be the event that a red or a white ball is selected.

• What is  $P(A \cup B)$ , i.e., the probability that A or B occurs?

# **Conditional Probability**

Probability of event A given that event B has occurred is

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

provided P(B) > 0

# **Independent Events**

Two events are independent if

$$P(A|B) = P(A)$$

$$P(B|A) = P(B)$$

$$P(A \cap B) = P(A)P(B)$$

```
In [ ]: print("P(A) = {0:4.3f}, P(B) = {1:4.3f}".format(probA, probB))
    print("P(A|B) = {0:4.3f}".format(probAB / probB))
    print("P(B|A) = {0:4.3f}".format(probAB / probA))
    print("P(A intersect B) = {0:4.3f}".format(probAB))
```

Assume events  $B_1, B_2, \dots, B_k$  partitions S and  $P(B_i) > 0$  for  $1 \le i \le k$ , then

# Law of Total Probability

$$P(A) = \sum_{i=1}^{k} P(A|B_i)P(B_i)$$

# **Bayes Rule**

$$P(B_i|A) = \frac{P(A|B_i)P(B_i)}{\sum_{j=1}^{k} P((A|B_j)P(B_j)}$$

• A simple case

$$P(B|A) = \frac{P(A|B)P(B)}{P((A)}$$

```
In [ ]: probBcA = probAB / probA
probAcB = probAB / probB
print("P(B|A) = {0:4.3f}, P(A|B)P(B)/P(A) = {1:4.3f}".format(probBcA, (probAcB*probB)/probA))
```

#### Random Variable

A random variable is a real valued function on a sample space

- The number of times face "3" is observed when a fair die is tossed 10 times
- The number of auto accidents in the city on any chosen date
- The weight of the next person walks into the store

Each sample point provides a specific value and many sample points may have the same value

EX: Let *Y* be the weight of a person walks into a store.

- Y = 175 is a numeric event that a person walks into the store has a weight of 175 pounds.
- The probability P(Y=175) is the sum of probability of all individuals walk into the store whose weight is 175 pounds

# **Discrete Random Variables and Their Probability Distribution**

A random variable is discrete if it can assume a finite or a countable infinite number of distinct values

- The number of students miss a class
- The number of messages received on your cell phone

A probability distribution of a discrete random variable Y can be defined by

- a formula
- a table
- a graph

that provides P(Y = y) for all y so that

```
• 0 \le P(Y = y) \le 1
• \sum_{y} P(Y = y) = 1
• expected value of Y is \mu = E(Y) = \sum_{y} y P(Y = y)
```

- variance of *Y* is  $\sigma^2 = V(Y) = E((Y E(Y))^2)$
- standard deviation of *Y* is  $\sigma = \sqrt{V(Y)}$

If the distribution is known, we can easily find probability for any set of values of R.V.

```
In [ ]: values = np.array([1, 2, 3, 4, 5])
        probs = pd.Series([0.1, 0.3, 0.15, 0.25, 0.2], index=values)
        eY = (probs*values).sum()
        vY = (((values-eY)**2)*probs).sum()
        print("probabilities =\n", probs,
        print("E(Y) = {:4.2f}".format(eY))
        print("V(Y) = {:4.2f}".format(vY))
        print("sdt(Y) = {:4.2f}".format(vY**0.5))
```

## **Probability Functions of a Random Variable**

• Probability Mass Function (pmf), also Probability Density Function (pdf), is a function that defines

$$Prob(Y = y)$$

• Cumulative Distribution Function (cdf) is a function

$$Prob(Y \leq y)$$

defined over  $(-\infty, \infty)$ 

• Percent Point Function (ppf) is a function

$$y = ppf(q)$$

such that  $q = Prob(Y \le y)$ . So, ppf is an inverse of cdf

### **Example**

A random variable Y may take value from 1, 2, 3, 4, 5

```
In []: values = [1, 2, 3, 4, 5]
    probs = [0.05, 0.2, 0.5, 0.2, 0.05]
    Y = stats.rv_discrete(values=(values, probs))
    print("P(Y<2) = ", (Y.pmf(0)+Y.pmf(1)))
    print("E(Y) = ", Y.mean())
    print("V(Y) = ", Y.var())
    print("std(Y) = ", Y.std())</pre>
```

#### **Binomial Distribution**

- Binomial experiment: Make n observations. Each outcome is success or fail. The probability of observing a success is p.
- Let Y be the total number of success, which can be a value in  $\{0, 1, 2, \dots, n\}$
- A random variable Y has a binomial probability distribution based on n trials with success probability p iff (if and only if) the probability mass function is

$$P(Y = y) = \binom{n}{y} p^{y} (1 - p)^{n - y}$$

where  $y = 1, 2, \dots, n$  and  $0 \le p \le 1$ 

- $\mu = E(Y) = np$
- $\sigma^2 = V(Y) = np(1-p)$

```
In []: # Plot binomial distribution
    n, p = 100, .8
    x = np.arange(0, n)
    rv = stats.binom(n, p)

label = "n={}, p={}".format(n,p) # use distribution parameters to label plot
    # pmf(): probability mass func
    plotDist(x, rv.pmf(x), 'binomial pmf', label, '# of positives', 'probability')
```

#### **Binomial Distribution: An Example**

A lot of 5000 electrical fuse contains 5% defectives. If a sample of five fuses is tested, what is the probability of observing at least one defective?

#### **Solution**

Make n=5 trials. Success means observed a defective. For this large lot, it may be ok to assume p=0.05.

Let Y be number of defectives observed. Y can be assumed to have a binomial distribution with n = 5 and p = 0.05.

The probability of observing at least one defective is P(Y > 0) = 1 - P(Y = 0).

```
In [ ]: # P(Y>0)
    n, p = 5, .05
    Y = stats.binom(n, p)
    print("Binomial distribution with n={} and p={:4.3f}".format(n, p))
    print("P(Y>0)={:4.3f}".format(1-Y.cdf(0)))
```

#### Random numbers generated from a normal distribution

```
In [ ]: # random numbers from a Binomial distribution
n, p = 50, .35
rv = stats.binom(n, p)

r = rv.rvs(size=n) # generate random numbers

x = np.arange(0, n)
label = "n={}, p={}".format(n,p) # use distribution parameters to label plot
plotHistDist(rv.pmf(x), x, r, 'binomial pmf', label, '# of positives', 'probabili
ty')
plt.show()
```

#### **Binomial Distribution: Another Example**

Randomly selected 20 individuals from a large company are polled whether they support a new company policy. If in this sample 6 persons support the policy, what is most likely the proportion of all employees who will support the policy?

#### Solution

Let Y be number of individuals in sample who supports the policy. Y is likely to have a binomial distribution with n=20 and p=?, so

$$P(Y=6) = {20 \choose 6} p^6 (1-p)^{14}$$

To find p that maximize this probability, solve for p from

$$\frac{d}{dp}(\ln(p^6(1-p)^{14})) = \frac{6}{p} - \frac{14}{1-p} = 0$$

So,

$$p = \frac{6}{20} = .3$$

#### **Binomial Test: An Example**

It is known that 30% of all persons afflicted by a certain illness recover. In a new drug test, ten people with the illness were selected at random and received the medication; nine recovered. Is the drug effective?

#### **Solution**

Let Y be number of people among the ten who recovered.

Assume *Y* has binomial distribution with n = 10 and some unknown p = ?

If the drug is useless, the probability of recover will be p=0.3. Under this probability, the average number of recovery, the probability of nine or more recover are as follows.

Since this very unlikely event has been observed, the drug must be effective.

#### **Poisson Distribution**

A random variable Y has a poisson probability distribution iff the pmf is

$$P(Y = y) = \frac{\lambda^y}{y!}e^{-\lambda}$$

where y = 0, 1, 2, ... and  $\lambda > 0$ 

- $\mu = E(Y) = \lambda$  (yes,  $\lambda$  is the mean!)
- $\sigma^2 = V(Y) = \lambda$

Poisson distribution is a binomial distribution when n approaches infinity

$$\lim_{n \to \infty} \binom{n}{y} p^{y} (1 - p)^{n - y} = \frac{\lambda^{y}}{y!} e^{-\lambda}$$

#### **Poisson Distribution: An Example**

A police patrol officer may visit a given location Y = 0, 1, 2, ... times per half-hour and each location is on average visited once per half-hour. Assuming that Y has a Poisson distribution, what is the probability that a location is not visited in a half-hour period and what is the probability that a location is visited once, twice, at least once?

#### **Solution**

Let  $\lambda = 1$ . We need to find probabilities for Y = 0, Y = 1 and Y > 1

# **Zipf Distribution**

```
In []: # plot a zipf distribution
    n, a = 20, 1.15
    rv = stats.zipf(a)
    x = np.arange(0, n)
    label = "a={}".format(a)
    plotDist(x, rv.pmf(x), 'zipf pmf', label, 'value of rv', 'probability')
```

# **Continuous Random Variable and Their Probability Distribution**

For a R.V. Y, distribution is  $F(y) = P(Y \le y)$  for  $-\infty < y < \infty$ 

- $F(-\infty) = 0$
- $F(\infty) = 1$
- If  $y_1 < y_2$ , then  $F(y_1) \le F(y_2)$

*Y* is a continuous random variable if F(y) is continuous for  $-\infty < y < \infty$ 

- $f(y) = P(Y = y) = \frac{dF(y)}{dy}$  is probability density function of Y
- $f(y) \ge 0$  for any value of y
- $P(a \le y \le b) = \int_a^b f(y)dy$  (area under the curve between a and b)
- $\bullet \int_{-\infty}^{\infty} f(y) dy = 1$
- $E(Y) = \int_{-\infty}^{\infty} y f(y) dy$

## Gaussian (a.k.a. Normal) Distribution

A random variable Y has a normal distribution iff for  $\sigma>0$  and  $-\infty<\mu<\infty$ , the density function is

$$f(y) = \mathcal{N}(\mu, \sigma^2) = \frac{1}{\sigma\sqrt{2\pi}} exp(-\frac{(y-\mu)^2}{2\sigma^2}) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(y-\mu)^2}{2\sigma^2}}$$

- $P(a \le y \le b) = \int_a^b \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(y-\mu)^2}{2\sigma^2}} dy$
- $\mu = E(Y)$
- $\sigma^2 = V(Y)$

If Y has a normal distribution with  $\mu$  and  $\sigma^2$ , then

$$Z = \frac{Y - \mu}{\sigma}$$

has a standard normal distribution with  $\mu_Z=0$  and  $\sigma_Z^2=1$ 

```
In []: # Plot a Gausian distribution
    n, mu, sigma = 20, 0, 2.
    rv = stats.norm(mu, sigma)

x = np.arange(mu-0.5*n, mu+0.5*n, 0.01) # range around mu
#for y in x:
    # print("f({0:4.2f})={1:10.8f}\n".format(y, rv.pdf(y)))

label = "loc={}, scale={}".format(mu, sigma)
    plotDist(x, rv.pdf(x), 'normal pdf', label, 'value of rv', 'probability')
```

```
In [ ]: # Normal Distribution
    n, mu, sigma = 20, 0, 2.0
    rv = stats.norm(mu, sigma)
    print("Normal distribution with mu={} and sigma2=()".format(mu, sigma))
    a=rv.ppf(0.05)
    b=rv.ppf(0.95)
    print("P({:4.3f}<=Y<={:4.3f})={:4.3f}".format(a, b, prob(rv, a, b)))
    print("P(-inf<Y<inf)={:4.3f}".format(prob(rv, float('-inf'), float('inf'))))</pre>
```

```
In [ ]: # Random numbers from a Normal distribution
    n, mu, sigma = 20, 0, 2.0
    # Randdom Variable
    rv = stats.norm(mu, sigma)
    # range on X-axis
    x = np.linspace(rv.ppf(0.001), rv.ppf(0.999), 50)
    # a set of random numbers from the distribution
    r = rv.rvs(size=1000)
    # plot histogram of random numbers and overlay the distribution
    label = "loc={}, scale={}".format(mu, sigma)
    plotHistDist(rv.pdf(x), x, r, 'normal pdf', label, 'value of rv', 'probability')
    plt.show()
```

```
In [ ]: # Normal distribution of the Z-score
        n, mu, sigma = 20, 5, 4.0
        rv = stats.norm(mu, sigma)
        r = rv.rvs(size=1000)
        z = stats.zscore(r)
        for i in range(1000):
            print(r[i] , ", ", z[i])
        plt.hist(r, normed=True, histtype='stepfilled', alpha=0.7)
        plt.hist(z, normed=True, histtype='stepfilled', alpha=0.3)
        plt.show()
```

```
Other Distributions
 • Exponential Distribution
 • Student's T-Distribution
 • Chi-Square Distribution
  In [ ]: # Plot an exponential distribution
           loc, scale = 6, 1 # scale will change height and range
           rv = stats.expon(loc, scale)
           x = np.linspace(rv.ppf(0.01),
                           rv.ppf(0.99), 200)
           label = "loc={}, scale={}".format(loc, scale)
           plotDist(x, rv.pdf(x), 'Exponential pdf', label, 'value of rv', 'probability')
  In [ ]: # Plot a Student's t distribution
          df, loc, scale = 4.2, loc, loc
           rv = stats.t(df, loc, scale)
           x = np.linspace(rv.ppf(0.01),
                           rv.ppf(0.99), 200)
           label = "df={} \n loc={}, scale={}".format(df, loc, scale)
           plotDist(x, rv.pdf(x), 'Student\'s t pdf', label, 'value of rv', 'probability')
  In [ ]: # Random numbers from a Student's t distribution
           x = np.linspace(rv.ppf(0.001),
                           rv.ppf(0.999), 200)
           r = rv.rvs(size=1000)
           label = df={}   \log {}  , scale={}".format(df, loc, scale)
           plotHistDist(rv.pdf(x), x, r, 'Student\'s t pdf', label, 'value of rv', 'probabili
           ty')
           plt.show()
  In [ ]: # Plot a chi-square distribution
           df, loc, scale = 10, 3, 10
           rv = stats.chi2(df, loc, scale)
           x = np.linspace(rv.ppf(0.01),
                           rv.ppf(0.99), 200)
           label = df={}  n loc={}, scale={}".format(df, loc, scale)
           plotDist(x, rv.pdf(x), 'Chi-Square pdf', label, 'value of rv', 'probability')
```

# **Bivariate Distribution**

 $Y_1$  and  $Y_2$  are jointly random variables with a joint distribution function

$$F(y_1, y_2) = P(Y_1 \le y_1, Y_2 \le y_2), -\infty < y_1, y_2 < \infty$$

In case of discrete variables

$$F(y_1, y_2) = \sum_{t_1 \le y_1} \sum_{t_2 \le y_2} p(t_1, t_2)$$

where  $p(y_1, y_2) = P(Y_1 = y_1, Y_2 = y_2) \ge 0$  for all  $y_1, y_2$ , are joint probabilities

In case of continuous variables

$$F(y_1, y_2) = \int_{-\infty}^{y_1} \int_{-\infty}^{y_2} f(t_1, t_2) dt_1 dt_2$$

where  $f(y_1, y_2) \ge 0$  for all  $y_1, y_2$ , is the Joint density function

- $F(-\infty, \infty) = 1$
- $F(-\infty, -\infty) = F(-\infty, y_2) = F(y_1, -\infty) = 0$
- $P(a_1 \le Y_1 \le b_1, a_2 \le Y_2 \le b_2) = \sum_{a_1 \le t_1 \le b_1} \sum_{a_2 \le t_2 \le b_2} p(t_1, t_2)$  or
- $P(a_1 \le Y_1 \le b_1, a_2 \le Y_2 \le b_2) = \int_{a_1}^{b_1} \int_{a_2}^{b_2} f(t_1, t_2) dt_1 dt_2$

### **Bivariate Normal Distribution**

The multivariate Normal distribution of an *n*-dimensional vector  $x = (x_1, x_2, \dots, x_n)$  may be written

$$p(x; \mu, \Sigma) = \frac{1}{\sqrt{(2\pi)^n |\Sigma|}} \exp(-\frac{1}{2}(x - \mu)^T \Sigma^{-1}(x - \mu))$$

where  $\mu$  is the n-dimensional mean vector and  $\Sigma$  is the  $n \times n$  covariance matrix.

```
In [ ]: from matplotlib import cm
        from mpl_toolkits.mplot3d import Axes3D
        # Our 2-dimensional distribution will be over variables X and Y
        N = 60
        X = np.linspace(-3, 3, N)
        Y = np.linspace(-3, 4, N)
        X, Y = np.meshgrid(X, Y)
        # Mean vector and covariance matrix
        mu = np.array([0., 1.])
        Sigma = np.array([[1., -0.5], [-0.5, 1.5]])
        # Pack X and Y into a single 3-dimensional array
        pos = np.empty(X.shape + (2,))
        pos[:, :, 0] = X
        pos[:, :, 1] = Y
        def multivariate_gaussian(pos, mu, Sigma):
             """Return the multivariate Gaussian distribution on array pos.
            pos is an array constructed by packing the meshed arrays of variables
            x_1, x_2, x_3, ..., x_k into its _last_ dimension.
            n = mu.shape[0]
            Sigma_det = np.linalg.det(Sigma)
            Sigma inv = np.linalg.inv(Sigma)
            N = np.sqrt((2*np.pi)**n * Sigma det)
            # This einsum call calculates (x-mu)T.Sigma-1.(x-mu) in a vectorized
            # way across all the input variables.
            fac = np.einsum('...k,kl,...l->...', pos-mu, Sigma inv, pos-mu)
            return np.exp(-fac / 2) / N
        # The distribution on the variables X, Y packed into pos.
        Z = multivariate gaussian(pos, mu, Sigma)
        # Create a surface plot and projected filled contour plot under it.
        fig = plt.figure()
        ax = fig.gca(projection='3d')
        ax.plot_surface(X, Y, Z, rstride=3, cstride=3, linewidth=1, antialiased=True,
                        cmap=cm.viridis)
        cset = ax.contourf(X, Y, Z, zdir='z', offset=-0.15, cmap=cm.viridis)
        # Adjust the limits, ticks and view angle
        ax.set zlim(-0.15,0.2)
        ax.set zticks(np.linspace(0,0.2,5))
        ax.view init(27, -21)
        plt.show()
```

## **Marginal and Conditional Probability Distributions**

Let  $Y_1$  and  $Y_2$  be jointly random variables.

· Marginal probability

$$P_1(Y_1 = y_1) = \sum_{y_2} P(Y_1 = y_1, Y_2 = y_2)$$

$$P_2(Y_2 = y_2) = \sum_{y_1} P(Y_1 = y_1, Y_2 = y_2)$$

• Conditional distribution of  $Y_1 \le y_1$  given that  $Y_2 = y_2$ 

$$P(Y_1 \le y_1 | Y_2 = y_2) = \sum_{t_1 \le y_1} \frac{P(Y_1 = t_1, Y_2 = y_2)}{P_2(Y_2 = y_2)}$$

· Marginal density:

$$f_1(y_1) = \int_{-\infty}^{\infty} f(y_1, y_2) dy_2$$

$$f_2(y_2) = \int_{-\infty}^{\infty} f(y_1, y_2) dy_1$$

• Conditional distribution of  $Y_1 \le y_1$  given that  $Y_2 = y_2$ 

$$P(Y_1 \le y_1 | Y_2 = y_2) = \int_{-\infty}^{y_1} \frac{f(t_1, y_2)}{f_2(y_2)} dt_1$$

#### Marginal and Conditional Probability: An Example

From three Republicans, two Democrats, and one independent, a committee of two people is to be randomly selected. Let  $Y_1$  is the number of Republicans and  $Y_2$  be the number of Democrats on the committee. The joint distribution is given in the following table.

- Joint probability distribution:  $P(Y_1=1,Y_2=0)=\frac{3\cdot 1\cdot 1}{15}=0.2$ 
  - there are three ways to get one Republican, one way to get zero Domestic, and one way to get one independent into the committee
- Marginal distribution of  $Y_1: P_1(Y_1 = 0) = 0 + 0.1333 + 0.0666 = 0.2$

Find the conditional probability that one Republican is selected given that one Democrat is already on the committee.

### **Independent Random Variables**

• If  $Y_1$  and  $Y_2$  are discrete random variables with joint probability  $P(Y_1 = y_1, Y_2 = y_2)$ , and marginal probabilities  $P_1(Y_1 = y_1)$  and  $P_2(Y_2 = y_2)$ , then  $Y_1$  and  $Y_2$  are independent iff

$$P(Y_1 = y_1, Y_2 = y_2) = P_1(Y_1 = y_1)P_2(Y_2 = y_2)$$

• If  $Y_1$  and  $Y_2$  are continuous random variables with joint probability density  $f(y_1, y_2)$ , and marginal probability densities  $f_1(y_1)$  and  $f_2(y_2)$ , then  $Y_1$  and  $Y_2$  are independent iff

$$f(y_1, y_2) = f_1(y_1)f_2(y_2)$$

#### **Covariance of Two Random Variables**

- If  $Y_1$  and  $Y_2$  are two random variables with means  $\mu_1$  and  $\mu_2$ , respectively, the covariance of  $Y_1$  and  $Y_2$  is given by  $Cov(Y_1, Y_2) = E((Y_1 \mu_1)(Y_2 \mu_2)) = E(Y_1Y_2) E(Y_1)E(Y_2)$
- In discrete case:

$$E(Y_1Y_2) = \sum_{y_1} \sum_{y_2} y_1 y_2 P(Y_1 = y_1, Y_2 = y_2)$$

and

$$E(Y_1) = \sum_{y_1} y_1 P_1(Y_1 = y_1)$$

In continuous case:

$$E(Y_1Y_2) = \int_{y_1} \int_{y_2} y_1 y_2 f(y_1, y_2) dy_1 dy_2$$

and

$$E(Y_1) = \int_{y_1} y_1 f_1(y_1) dy_1$$

• If  $Y_1$  and  $Y_2$  are independent random variables, then  $Cov(Y_1, Y_2) = 0$ 

```
In [ ]: vals = np.array([1, 2, 3])
    mu_1 = (probs.sum(1) * vals).sum()
    mu_2 = (probs.sum() * vals).sum()
    mu_12 = (probs * np.array([vals, vals*2, vals*3])).sum().sum()
    cov_12 = mu_12 - mu_1*mu_2
    print("cov(Y_1, Y_2) = {0:4.3f}".format(cov_12))
```

# **Conditional Expectations**

If  $Y_1$  and  $Y_2$  are two random variables, the conditional expectation of a function  $g(Y_1)$  given that  $Y_2 = y2$  is

• Discrete case:

$$E(g(Y_1)|Y_2 = y_2) = \sum_{y_1} g(y_1)P(Y_1 = y_1|Y_2 = y_2)$$

• Continuous case:

$$E(g(Y_1)|Y_2 = y_2) = \int_{-\infty}^{\infty} g(y_1)f(y_1|y_2)dy_1$$

```
In [ ]: mu_1_c_Y_2_2=((probs.loc[:, 2]/(probs.loc[:, 2].sum()))*vals).sum()
    print("E(Y_1 | Y_2 = 2) = {0:4.3f}".format(mu_1_c_Y_2_2))
```

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