Review of Probability

CS 3753 Data Science

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Topics

- Events and Probability
- Conditional Probability and Independence
- Beyes Rule
- Discrete Random Variables
- Continuous Random Variables
- Expectation and Variance
- Use SciPy.Stats

SciPy.Stats Package

The <u>SciPy.Stats Package (https://docs.scipy.org/doc/scipy/reference/stats.html)</u> contains a large number of probability distributions as well as a growing library of statistical functions.

- Continuous distributions
- Multivariate distributions
- Discrete distributions
- Statistical functions

```
In [ ]: from scipy import stats
   import matplotlib.pyplot as plt
   import numpy as np
   import pandas as pd
%pylab inline
```

Some Functions to Help Plotting

```
In [ ]: def prob(rv, a, b):
            return 1-(rv.cdf(a)+(1-rv.cdf(b)))
        def plotDist(x, func, title, 1, xlabel, ylabel) :
            #plt.figure(fig)
            plt.plot(x, func, 'bo', ms=4, label=1) # plot func for elements of x
            xl = plt.gca().get_xlim()
            plt.hlines(0, x1[0], x1[1], linestyles='--', colors='#999999') #lines on Y-axi
            plt.gca().set_xlim(xl)
            plt.vlines(x, 0, func, colors='r', lw=2, alpha=0.5) # lines on X-axis
            plt.legend(loc='best', frameon=False)
            plt.xlabel(xlabel)
            plt.ylabel(ylabel)
            plt.title(title)
            plt.show()
        def plotDist2(x, func, title, 1, xlabel, ylabel) :
            plt.plot(x, func, 'b-', lw=2, alpha=0.6, label=1) # plot func for elements of
        X
            xl = plt.gca().get xlim()
            plt.hlines(0, x1[0], x1[1], linestyles='--', colors='#999999') #lines on Y-axi
            plt.gca().set_xlim(xl)
            #plt.vlines(x, 0, func, colors='r', lw=2, alpha=0.5) # lines on X-axis
            plt.legend(loc='best', frameon=False)
            plt.xlabel(xlabel)
            plt.ylabel(ylabel)
            plt.title(title)
        def plotHistDist(func, x, r, title, l, xlabel, ylabel):
            plt.hist(r, normed=True, histtype='stepfilled', alpha=0.2)
            plotDist2(x, func, title, 1, xlabel, ylabel)
```

Experiments and Events

Experiment is to make observations, events are outcomes

- Simple event is non-decomposed (a sample point)
- Compound event is composed of simple events

Probability

- ullet A Sample Space (or Population) S is the set of all (can be infinitely many) simple events.
- Probability P(A) is a number assigned to event A
 - $0 \le P(A) \le 1$
 - P(S) = 1
 - $P(A_1 \cup A_2) = P(A_1) + P(A_2) P(A_1 \cap A_2)$ for any $A_1, A_2 \subset S$

Example

A box contains 500 colored balls, with n_1 in red, n_2 in green, n_3 in white, n_4 in blue and n_5 in black. If a ball is selected randomly from the box, what is the probability that

- a red ball is selected?
- a red or a white ball is selected?
- Neither a black nor a blue ball is selected?

Let A be the event that a red or a black ball is selected and B be the event that a red or a white ball is selected.

• What is $P(A \cup B)$, i.e., the probability that A or B occurs?

Conditional Probability

Probability of event A given that event B has occurred is

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

provided P(B) > 0

Independent Events

Two events are independent if

$$P(A|B) = P(A)$$

$$P(B|A) = P(B)$$

$$P(A \cap B) = P(A)P(B)$$

```
In [ ]: print("P(A) = {0:4.3f}, P(B) = {1:4.3f}".format(probA, probB))
    print("P(A|B) = {0:4.3f}".format(probAB / probB))
    print("P(B|A) = {0:4.3f}".format(probAB / probA))
    print("P(A intersect B) = {0:4.3f}".format(probAB))
```

Assume events B_1, B_2, \dots, B_k partitions S and $P(B_i) > 0$ for $1 \le i \le k$, then

Law of Total Probability

$$P(A) = \sum_{i=1}^{k} P(A|B_i)P(B_i)$$

Bayes Rule

$$P(B_i|A) = \frac{P(A|B_i)P(B_i)}{\sum_{j=1}^{k} P((A|B_j)P(B_j))}$$

• A simple case

$$P(B|A) = \frac{P(A|B)P(B)}{P((A)}$$

Random Variable

A random variable is a real valued function on a sample space

- The number of times face "3" is observed when a fair die is tossed 10 times
- The number of auto accidents in the city on any chosen date
- The weight of the next person walks into the store

Each sample point provides a specific value and many sample points may have the same value

Example: Random Variable

Let *Y* be the weight of a person walks into a store.

- Y = 175 is a numeric event that a person walks into the store has a weight of 175 pounds.
- The probability P(Y = 175) is the sum of probability of all individuals walk into the store whose weight is 175 pounds

Discrete Random Variables and Their Probability Distribution

A random variable is discrete if it can assume a finite or a countable infinite number of distinct values

- The number of students miss a class
- The number of messages received on your cell phone

A probability distribution of a discrete random variable Y can be defined by

- a formula
- a table
- a graph

that provides P(Y = y) for all y so that

```
• 0 \le P(Y=y) \le 1

• \sum_y P(Y=y) = 1

• expected value of Y is \mu = E(Y) = \sum_y y P(Y=y)

• variance of Y is \sigma^2 = V(Y) = E((Y-E(Y))^2)

• standard deviation of Y is \sigma = \sqrt{V(Y)}
```

If the distribution is known, we can easily find probability for any set of values of R.V.

```
In [ ]: values = np.array([1, 2, 3, 4, 5])
    probs = pd.Series([0.1, 0.3, 0.15, 0.25, 0.2], index=values)
    eY = (probs*values).sum()
    vY = (((values-eY)**2)*probs).sum()
    print("probabilities = \n", probs, "\n")
    print("E(Y) = {:4.2f}".format(eY))
    print("V(Y) = {:4.2f}".format(vY))
    print("sdt(Y) = {:4.2f}".format(vY**0.5))
```

Probability Functions of a Random Variable

```
• Probability Mass Function (pmf), also Probability Density Function (pdf), is a function that defines Prob(Y = y)
```

• Cumulative Distribution Function (cdf) is a function

```
Prob(Y \leq y)
```

defined over $(-\infty, \infty)$

• Percent Point Function (ppf) is a function

$$y = ppf(q)$$

such that $q = Prob(Y \le y)$. So, ppf is an inverse of cdf

Example

A random variable Y may take value from 1, 2, 3, 4, 5

```
In []: values = [1, 2, 3, 4, 5]
    probs = [0.05, 0.2, 0.5, 0.2, 0.05]
    Y = stats.rv_discrete(values=(values, probs))
    print("P(Y<2) = ", (Y.pmf(0)+Y.pmf(1)))
    print("E(Y) = ", Y.mean())
    print("V(Y) = ", Y.var())
    print("std(Y) = ", Y.std())</pre>
```

Binomial Distribution

- Binomial experiment: Make *n* observations. Each outcome is success or fail. The probability of observing a success is *p*.
- Let Y be the total number of success, which can be a value in $\{0, 1, 2, \dots, n\}$
- ullet A random variable Y has a binomial probability distribution based on n trials with success probability p iff (if and only if) the probability mass function is

$$P(Y = y) = \binom{n}{y} p^{y} (1 - p)^{n - y}$$

where $y = 1, 2, \dots, n$ and $0 \le p \le 1$

- $\mu = E(Y) = np$
- $\sigma^2 = V(Y) = np(1-p)$

```
In [ ]: # Plot binomial distribution
    n, p = 100, .8
    x = np.arange(0, n)
    rv = stats.binom(n, p)

label = "n={}, p={}".format(n,p) # use distribution parameters to label plot
    # pmf(): probability mass func
    plotDist(x, rv.pmf(x), 'binomial pmf', label, '# of positives', 'probability')
```

Example: Binomial Distribution

A lot of 5000 electrical fuse contains 5% defectives. If a sample of five fuses is tested, what is the probability of observing at least one defective?

Solution

Make n=5 trials. Success means observed a defective. For this large lot, it may be ok to assume p=0.05.

Let Y be number of defectives observed. Y can be assumed to have a binomial distribution with n = 5 and p = 0.05.

The probability of observing at least one defective is P(Y > 0) = 1 - P(Y = 0).

```
In [ ]: # P(Y>0)
    n, p = 5, .05
    Y = stats.binom(n, p)
    print("Binomial distribution with n={} and p={:4.3f}".format(n, p))
    print("P(Y>0)={:4.3f}".format(1-Y.cdf(0)))
```

Random numbers generated from a normal distribution

```
In [ ]: # random numbers from a Binomial distribution
    n, p = 50, .35
    rv = stats.binom(n, p)

r = rv.rvs(size=n) # generate random numbers

x = np.arange(0, n)
    label = "n={}, p={}".format(n,p) # use distribution parameters to label plot
    plotHistDist(rv.pmf(x), x, r, 'binomial pmf', label, '# of positives', 'probabili
    ty')
    plt.show()
```

Example: Binomial Distribution (2)

Randomly selected 20 individuals from a large company are polled whether they support a new company policy. If in this sample 6 persons support the policy, what is most likely the proportion of all employees who will support the policy?

Solution

Let Y be number of individuals in sample who supports the policy. Y is likely to have a binomial distribution with n=20 and p=?, so

$$P(Y=6) = {20 \choose 6} p^6 (1-p)^{14}$$

To find p that maximize this probability, solve for p from

$$\frac{d}{dp}(\ln(p^6(1-p)^{14})) = \frac{6}{p} - \frac{14}{1-p} = 0$$

So,

$$p = \frac{6}{20} = .3$$

Example: Binomial Test

It is known that 30% of all persons afflicted by a certain illness recover. In a new drug test, ten people with the illness were selected at random and received the medication; nine recovered. Is the drug effective?

Solution

Let Y be number of people among the ten who recovered.

Assume *Y* has binomial distribution with n = 10 and some unknown p = ?

If the drug is useless, the probability of recover will be p=0.3. Under this probability, the average number of recovery, the probability of nine or more recover are as follows.

```
In [ ]: n, p = 10, .3
Y = stats.binom(n, p)
# print("Binomial distribution with n={} and p={:4.3f}".format(n, p))
print("E(Y)={:3.2f}".format(Y.mean()))
print("P(Y=9)={:7.6f}".format(Y.pmf(9)))
print("P(Y>=9)={:7.6f}".format(1-Y.cdf(8)))
```

Since this very unlikely event has been observed, the drug must be effective.

Poisson Distribution

A random variable *Y* has a poisson probability distribution iff the pmf is

$$P(Y = y) = \frac{\lambda^y}{y!}e^{-\lambda}$$

where $y = 0, 1, 2, \dots$ and $\lambda > 0$

- $\mu = E(Y) = \lambda$ (yes, λ is the mean!)
- $\sigma^2 = V(Y) = \lambda$

Poisson distribution is a binomial distribution when n approaches infinity

$$\lim_{n \to \infty} \binom{n}{y} p^{y} (1-p)^{n-y} = \frac{\lambda^{y}}{y!} e^{-\lambda}$$

Example: Poisson Distribution

A police patrol officer may visit a given location Y = 0, 1, 2, ... times per half-hour and each location is on average visited once per half-hour. Assuming that Y has a Poisson distribution, what is the probability that a location is not visited in a half-hour period and what is the probability that a location is visited once, twice, at least once?

Solution

Let $\lambda = 1$. We need to find probabilities for Y = 0, Y = 1 and Y > 1

Zipf Distribution

```
In [ ]: # plot a zipf distribution
    n, a = 20, 1.15
    rv = stats.zipf(a)
    x = np.arange(0, n)
    label = "a={}".format(a)
    plotDist(x, rv.pmf(x), 'zipf pmf', label, 'value of rv', 'probability')
```

Continuous Random Variable and Their Probability Distribution

For a R.V. Y, distribution is $F(y) = P(Y \le y)$ for $-\infty < y < \infty$

- $F(-\infty) = 0$
- $F(\infty) = 1$
- If $y_1 < y_2$, then $F(y_1) \le F(y_2)$

Y is a continuous random variable if F(y) is continuous for $-\infty < y < \infty$

- $f(y) = P(Y = y) = \frac{dF(y)}{dy}$ is probability density function of Y
- $f(y) \ge 0$ for any value of y
- $P(a \le y \le b) = \int_a^b f(y)dy$ (area under the curve between a and b)
- $\int_{-\infty}^{\infty} f(y)dy = 1$
- $E(Y) = \int_{-\infty}^{\infty} y f(y) dy$

Gaussian (or Normal) Distribution

A random variable Y has a normal distribution iff for $\sigma > 0$ and $-\infty < \mu < \infty$, the density function is

$$f(y) = \mathcal{N}(\mu, \sigma^2) = \frac{1}{\sigma\sqrt{2\pi}} exp(-\frac{(y-\mu)^2}{2\sigma^2}) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(y-\mu)^2}{2\sigma^2}}$$

- $P(a \le y \le b) = \int_a^b \frac{1}{\sigma \sqrt{2\pi}} e^{-\frac{(y-\mu)^2}{2\sigma^2}} dy$
- $\mu = E(Y)$
- $\sigma^2 = V(Y)$

If Y has a normal distribution with μ and σ^2 , then

$$Z = \frac{Y - \mu}{\sigma}$$

has a standard normal distribution with $\mu_Z=0$ and $\sigma_Z^2=1$

```
In []: # Plot a Gausian distribution
    n, mu, sigma = 20, 0, 2.
    rv = stats.norm(mu, sigma)

x = np.arange(mu-0.5*n, mu+0.5*n, 0.01) # range around mu
#for y in x:
    # print("f({0:4.2f})={1:10.8f}\n".format(y, rv.pdf(y)))

label = "loc={}, scale={}".format(mu, sigma)
    plotDist(x, rv.pdf(x), 'normal pdf', label, 'value of rv', 'probability')
```

```
In [ ]: # Normal Distribution
        n, mu, sigma = 20, 0, 2.0
        rv = stats.norm(mu, sigma)
        print("Normal distribution with mu={} and sigma2=()".format(mu, sigma))
        a=rv.ppf(0.05)
        b=rv.ppf(0.95)
        print("P({:4.3f} \le Y \le {:4.3f}) = {:4.3f}".format(a, b, prob(rv, a, b)))
        print("P(-inf<Y<inf)={:4.3f}".format(prob(rv, float('-inf'), float('inf'))))</pre>
In [ ]: # Random numbers from a Normal distribution
        n, mu, sigma = 20, 0, 2.0
        # Randdom Variable
        rv = stats.norm(mu, sigma)
        # range on X-axis
        x = np.linspace(rv.ppf(0.001), rv.ppf(0.999), 50)
        # a set of random numbers from the distribution
        r = rv.rvs(size=1000)
        # plot histogram of random numbers and overlay the distribution
        label = "loc={}, scale={}".format(mu, sigma)
        \verb|plotHistDist(rv.pdf(x), x, r, 'normal pdf', label, 'value of rv', 'probability')| \\
        plt.show()
In [ ]: # Normal distribution of the Z-score
        n, mu, sigma = 20, 5, 4.0
        rv = stats.norm(mu, sigma)
        r = rv.rvs(size=1000)
        z = stats.zscore(r)
        for i in range(1000):
            print(r[i] , ", ", z[i])
        plt.hist(r, normed=True, histtype='stepfilled', alpha=0.7)
        plt.hist(z, normed=True, histtype='stepfilled', alpha=0.3)
        plt.show()
```

Other Distributions

- Exponential Distribution
- Student's T-Distribution
- Chi-Square Distribution

```
In [ ]: # Random numbers from a Student's t distribution
        x = np.linspace(rv.ppf(0.001),
                         rv.ppf(0.999), 200)
        r = rv.rvs(size=1000)
        label = df={} \in \{n \in {}\}, scale={}".format(df, loc, scale)
        plotHistDist(rv.pdf(x), x, r, 'Student\'s t pdf', label, 'value of rv', 'probabili
        ty')
        plt.show()
```

```
In [ ]: # Plot a chi-square distribution
        df, loc, scale = 10, 3, 10
        rv = stats.chi2(df, loc, scale)
        x = np.linspace(rv.ppf(0.01),
                         rv.ppf(0.99), 200)
        label = df={} \in \{n \in {}\}, scale={}".format(df, loc, scale)
        plotDist(x, rv.pdf(x), 'Chi-Square pdf', label, 'value of rv', 'probability')
```

Bivariate Distribution

 Y_1 and Y_2 are jointly random variables with a joint distribution function

$$F(y_1, y_2) = P(Y_1 \le y_1, Y_2 \le y_2), -\infty < y_1, y_2 < \infty$$

In case of discrete variables

$$F(y_1, y_2) = \sum_{t_1 \le y_1} \sum_{t_2 \le y_2} p(t_1, t_2)$$

where $p(y_1, y_2) = P(Y_1 = y_1, Y_2 = y_2) \ge 0$ for all y_1, y_2 , are joint probabilities

In case of continuous variables

$$F(y_1, y_2) = \int_{-\infty}^{y_1} \int_{-\infty}^{y_2} f(t_1, t_2) dt_1 dt_2$$

where $f(y_1, y_2) \ge 0$ for all y_1, y_2 , is the Joint density function

- $F(-\infty, \infty) = 1$
- $F(-\infty, -\infty) = F(-\infty, y_2) = F(y_1, -\infty) = 0$
- $P(a_1 \le Y_1 \le b_1, a_2 \le Y_2 \le b_2) = \sum_{a_1 \le t_1 \le b_1} \sum_{a_2 \le t_2 \le b_2} p(t_1, t_2)$ or $P(a_1 \le Y_1 \le b_1, a_2 \le Y_2 \le b_2) = \int_{a_1}^{b_1} \int_{a_2}^{b_2} f(t_1, t_2) dt_1 dt_2$

Bivariate Normal Distribution

The multivariate Normal distribution of an *n*-dimensional vector $x = (x_1, x_2, \dots, x_n)$ may be written

$$p(x; \mu, \Sigma) = \frac{1}{\sqrt{(2\pi)^n |\Sigma|}} \exp(-\frac{1}{2}(x - \mu)^T \Sigma^{-1}(x - \mu))$$

where μ is the n-dimensional mean vector and Σ is the $n \times n$ covariance matrix.

```
In [ ]: from matplotlib import cm
        from mpl_toolkits.mplot3d import Axes3D
        # Our 2-dimensional distribution will be over variables X and Y
        N = 60
        X = np.linspace(-3, 3, N)
        Y = np.linspace(-3, 4, N)
        X, Y = np.meshgrid(X, Y)
        # Mean vector and covariance matrix
        mu = np.array([0., 1.])
        Sigma = np.array([[1., -0.5], [-0.5, 1.5]])
        # Pack X and Y into a single 3-dimensional array
        pos = np.empty(X.shape + (2,))
        pos[:, :, 0] = X
        pos[:, :, 1] = Y
        def multivariate_gaussian(pos, mu, Sigma):
             """Return the multivariate Gaussian distribution on array pos.
            pos is an array constructed by packing the meshed arrays of variables
            x_1, x_2, x_3, ..., x_k into its _last_ dimension.
            n = mu.shape[0]
            Sigma_det = np.linalg.det(Sigma)
            Sigma inv = np.linalg.inv(Sigma)
            N = np.sqrt((2*np.pi)**n * Sigma det)
            # This einsum call calculates (x-mu)T.Sigma-1.(x-mu) in a vectorized
            # way across all the input variables.
            fac = np.einsum('...k,kl,...l->...', pos-mu, Sigma inv, pos-mu)
            return np.exp(-fac / 2) / N
        # The distribution on the variables X, Y packed into pos.
        Z = multivariate gaussian(pos, mu, Sigma)
        # Create a surface plot and projected filled contour plot under it.
        fig = plt.figure()
        ax = fig.gca(projection='3d')
        ax.plot_surface(X, Y, Z, rstride=3, cstride=3, linewidth=1, antialiased=True,
                        cmap=cm.viridis)
        cset = ax.contourf(X, Y, Z, zdir='z', offset=-0.15, cmap=cm.viridis)
        # Adjust the limits, ticks and view angle
        ax.set zlim(-0.15,0.2)
        ax.set zticks(np.linspace(0,0.2,5))
        ax.view_init(27, -21)
        plt.show()
```

Marginal and Conditional Probability Distributions

Let Y_1 and Y_2 be jointly random variables.

Marginal probability

$$P_1(Y_1 = y_1) = \sum_{y_2} P(Y_1 = y_1, Y_2 = y_2)$$

$$P_2(Y_2 = y_2) = \sum_{y_1} P(Y_1 = y_1, Y_2 = y_2)$$

• Conditional distribution of $Y_1 \le y_1$ given that $Y_2 = y_2$

$$P(Y_1 \le y_1 | Y_2 = y_2) = \sum_{t_1 \le y_1} \frac{P(Y_1 = t_1, Y_2 = y_2)}{P_2(Y_2 = y_2)}$$

· Marginal density:

$$f_1(y_1) = \int_{-\infty}^{\infty} f(y_1, y_2) dy_2$$

$$f_2(y_2) = \int_{-\infty}^{\infty} f(y_1, y_2) dy_1$$

• Conditional distribution of $Y_1 \le y_1$ given that $Y_2 = y_2$

$$P(Y_1 \le y_1 | Y_2 = y_2) = \int_{-\infty}^{y_1} \frac{f(t_1, y_2)}{f_2(y_2)} dt_1$$

Example: Marginal and Conditional Probability

From three Republicans, two Democrats, and one independent, a committee of two people is to be randomly selected. Let Y_1 is the number of Republicans and Y_2 be the number of Democrats on the committee. The joint distribution is given in the following table.

- Joint probability distribution: $P(Y_1 = 1, Y_2 = 0) = \frac{3 \cdot 1 \cdot 1}{15} = 0.2$
 - there are three ways to get one Republican, one way to get zero Domestic, and one way to get one independent into the committee
- Marginal distribution of Y_1 : $P_1(Y_1 = 0) = 0 + 0.1333 + 0.0666 = 0.2$

Find the conditional probability that one Republican is selected given that one Democrat is already on the committee.

Independent Random Variables

• If Y_1 and Y_2 are discrete random variables with joint probability $P(Y_1 = y_1, Y_2 = y_2)$, and marginal probabilities $P_1(Y_1 = y_1)$ and $P_2(Y_2 = y_2)$, then Y_1 and Y_2 are independent iff

$$P(Y_1 = y_1, Y_2 = y_2) = P_1(Y_1 = y_1)P_2(Y_2 = y_2)$$

• If Y_1 and Y_2 are continuous random variables with joint probability density $f(y_1, y_2)$, and marginal probability densities $f_1(y_1)$ and $f_2(y_2)$, then Y_1 and Y_2 are independent iff

$$f(y_1, y_2) = f_1(y_1)f_2(y_2)$$

Covariance of Two Random Variables

- If Y_1 and Y_2 are two random variables with means μ_1 and μ_2 , respectively, the covariance of Y_1 and Y_2 is given by $Cov(Y_1,Y_2)=E((Y_1-\mu_1)(Y_2-\mu_2))=E(Y_1Y_2)-E(Y_1)E(Y_2)$
- In discrete case:

$$E(Y_1Y_2) = \sum_{y_1} \sum_{y_2} y_1 y_2 P(Y_1 = y_1, Y_2 = y_2)$$

and

$$E(Y_1) = \sum_{y_1} y_1 P_1(Y_1 = y_1)$$

• In continuous case:

$$E(Y_1Y_2) = \int_{y_1} \int_{y_2} y_1 y_2 f(y_1, y_2) dy_1 dy_2$$

and

$$E(Y_1) = \int_{y_1} y_1 f_1(y_1) dy_1$$

• If Y_1 and Y_2 are independent random variables, then $Cov(Y_1, Y_2) = 0$

```
In []: vals = np.array([1, 2, 3])
    mu_1 = (probs.sum(1) * vals).sum()
    mu_2 = (probs.sum() * vals).sum()
    mu_12 = (probs * np.array([vals, vals*2, vals*3])).sum().sum()
    cov_12 = mu_12 - mu_1*mu_2
    print("cov(Y_1, Y_2) = {0:4.3f}".format(cov_12))
```

Conditional Expectations

If Y_1 and Y_2 are two random variables, the conditional expectation of a function $g(Y_1)$ given that $Y_2 = y2$ is

• Discrete case:

$$E(g(Y_1)|Y_2 = y_2) = \sum_{y_1} g(y_1)P(Y_1 = y_1|Y_2 = y_2)$$

· Continuous case:

$$E(g(Y_1)|Y_2 = y_2) = \int_{-\infty}^{\infty} g(y_1)f(y_1|y_2)dy_1$$