

Velocity [mm/s]	Arm ID	PJ 0090 0009 16146 0001			PJ 00090 00009 16145 0001		
	Torque feedback	Deviation [mm]			Deviation [mm]		
		mean	std	max	mean	std	max
30	off	0.12	0.18	2.16	0.13	0.13	1.60
	on	0.10	0.14	1.41	0.12	0.13	1.44
	Amelioration	17%	22%	35%	8%	0%	10%
30*	off	0.39	0.40	2.16	0.32	0.24	1.60
	on	0.32	0.30	1.41	0.33	0.28	1.47
	Amelioration	18%	25%	35%	-3%	-17%	8%
50	off	0.28	0.35	2.05	0.35	0.42	2.87
	on	0.15	0.13	0.82	0.24	0.18	1.13
	Amelioration	46%	63%	60%	31%	57%	61%
50*	off	0.43	0.44	2.05	0.52	0.54	2.87
	on	0.22	0.16	0.81	0.32	0.22	1.13
	Amelioration	49%	64%	60%	38%	59%	61%