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**Ordinary Differential Equations**  
**(Initial Value Problems)**  
**Lab Sheet-1**

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1. The height of the fluid in a tank ( $h(t)$ ) whose outlet flow is dependent on the pressure head (height of fluid) inside the tank and whose inlet flow is a function of time may be modeled via the equation

$$\frac{dh}{dt} = \alpha(t) - \beta\sqrt{h}, \quad h(0) = h_0.$$

Use MATLAB ODE solver function to find the solution  $h(t)$  for  $0 < t < 30$  if the following values for the parameters are given. Input flow:  $\alpha(t) = 10 + 4 \sin(t)$ ,  $\beta = 2$ ,  $h_0 = 1$ .

Also find the approximation solution using

- (a) Forward Euler
  - (b) Backward Euler
  - (c) Modified Euler
  - (d) 2<sup>nd</sup> order Runge-Kutta method
  - (e) 4<sup>th</sup> order Runge-Kutta method
2. Consider the Predator-Prey equation

$$\begin{aligned} u'(t) &= (2 - v(t)) u(t), \\ v'(t) &= (u(t) - 1) v(t) \end{aligned}$$

with the initial conditions  $u(0) = 3, v(0) = 2$ .

- (a) Use MATLAB ODE solver function to solve the problem within  $0 \leq t \leq 10$ , using  $n = 100$  steps.
  - (b) Give two graphs showing the curves  $u(t)$  and  $v(t)$  against  $t$  and a plot of  $u(t)$  against  $v(t)$ .
3. A mass-spring system can be modeled via the following second-order ODE

$$y'' + cy' + \omega^2 y = g(t), \quad y(0) = 1, \quad y'(0) = 0.$$

Find the numerical solution in the time interval  $0 \leq t \leq 10$  for the particular set of conditions  $c = 5$ ,  $\omega = 2$  and  $g(t) = \sin(t)$  using MATLAB.

4. Consider the simple motion of pendulum. Let  $\theta(t)$  be the angle made with the vertical at time  $t$ . Initially  $\theta(0) = \pi/4$  and  $\theta'(0) = 0$ . The subsequent position is described by the differential equation

$$\theta''(t) - \frac{g}{l} \sin(\theta(t)) = 0,$$

where  $g = 9.8m/sec^2$  is the acceleration due to gravity and  $l = 0.5m$  is the length of the pendulum.

- Solve for  $0 \leq t \leq 5$  by taking 40 steps using MATLAB ODE solver function. Plot  $\theta(t)$ . From this computation, what can you conclude about the pendulum's amplitude as time increases.
  - Repeat using 400 steps. What is your estimate of the period of the pendulum's movement.
5. (Vander Pol's equation) The following equation describes the voltage across the triode circuit:

$$\begin{aligned} v''(t) + \epsilon (v(t)^2 - 1) v'(t) + v(t) &= 0, \\ v(2) &= 1, v'(2) = 0. \end{aligned}$$

Take  $\epsilon = 0.897$  and compute the approximate solution at  $t = 10$  using MATLAB ODE solver function. Plot the numerical solution.

6. Consider a nonlinear oscillator with a cubic stiffness term to describe the hardening spring effect observed in many mechanical systems

$$\frac{d^2y}{dt^2} + \epsilon \frac{dy}{dt} + y^3 = \gamma \cos(\omega t).$$

- Set the parameter values to  $\epsilon = 0.15$ ,  $\gamma = 0.3$  and  $\omega = 1$ .
  - Use the initial conditions:  $y(0) = -1$ ,  $y'(0) = 1$ .
  - Use MATLAB ODE solver function to solve on the  $t$  interval  $[0, 100]$ .
  - Plot the solution  $y(t)$ .
7. Consider the Lorenz system of equations

$$\begin{aligned} \frac{dx_1}{dt} &= \sigma(x_2 - x_1), \\ \frac{dx_2}{dt} &= ((1 + r) - x_3) x_1 - x_2, \\ \frac{dx_3}{dt} &= x_1 x_2 - b x_3 \end{aligned}$$

with the initial conditions

$$x_1(0) = -10, \quad x_2(0) = 10, \quad x_3(0) = 25.$$

- Use  $\sigma = 10$ ,  $r = 28$ ,  $b = 8/3$ .
- Use MATLAB ODE solver function to solve on the  $t$  interval  $[0, 50]$ .
- Plot the Lorenz attractor.

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## Formula Sheet

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1.

$$u'(x) \approx \frac{\Delta u(x)}{h} = \frac{u(x+h) - u(x)}{h}, \quad (\text{forward difference formula})$$

$$u'(x) \approx \frac{\nabla u(x)}{h} = \frac{u(x) - u(x-h)}{h}, \quad (\text{backward difference formula})$$

$$u'(x) \approx \frac{\delta u(x)}{2h} = \frac{u(x+h) - u(x-h)}{2h}, \quad (\text{central difference formula})$$

2. Central difference formula:

$$u''(x) = \frac{u(x+h) - 2u(x) + u(x-h)}{h^2} + O(h^2), \quad h > 0.$$

3. Single step methods to solve the initial value problem (IVP):

$$\begin{aligned} \frac{dy}{dx} &= f(x, y(x)), \\ y(x_0) &= y_0. \end{aligned}$$

(a) Forward Euler's method:

$$y_{n+1} = y_n + h f(x_n, y_n), \quad n = 0, 1, 2, \dots$$

(b) Backward Euler's method:

$$y_{n+1} = y_n + h f(x_{n+1}, y_{n+1}), \quad n = 0, 1, 2, \dots$$

(c) Modified Euler's method:

$$y_{n+1} = y_n + \frac{h}{2} [f(x_n, y_n) + f(x_{n+1}, y_{n+1}^*)], \quad n = 0, 1, 2, \dots,$$

$$\text{here } y_{n+1}^* = y_n + h f(x_n, y_n).$$

(d) A second-order Runge-Kutta Method:

$$y_{n+1} = y_n + \frac{h}{2} (k_1 + k_2), \quad n = 0, 1, 2, \dots$$

$$\text{where } k_1 = f(x_n, y_n) \text{ and } k_2 = f(x_n + h, y_n + h k_1).$$

(e) A fourth-order Runge-Kutta method:

$$y_{n+1} = y_n + \frac{h}{6} (k_1 + 2k_2 + 2k_3 + k_4), \quad n = 0, 1, 2, \dots$$

where

$$\begin{aligned} k_1 &= f(x_n, y_n), & k_2 &= f(x_n + \frac{h}{2}, y_n + \frac{k_1}{2}), \\ k_3 &= f(x_n + \frac{h}{2}, y_n + \frac{k_2}{2}), & k_4 &= f(x_n + h, y_n + k_3). \end{aligned}$$

4. Multi step methods to solve the initial value problem (IVP):

$$\begin{aligned} \frac{dy}{dx} &= f(x, y(x)), \\ y(x_0) &= y_0. \end{aligned}$$

(a) Two step Adams-Bashforth method:

$$y_{n+1} = y_n + \frac{h}{2} [3f(x_n, y_n) - f(x_{n-1}, y_{n-1})], \quad n = 1, 2, 3, \dots$$

(b) Four step Adams-Bashforth method:

$$y_{n+1} = y_n + \frac{h}{24} [55f(x_n, y_n) - 59f(x_{n-1}, y_{n-1}) + 37f(x_{n-2}, y_{n-2}) - 9f(x_{n-3}, y_{n-3})],$$

where  $n = 3, 4, 5, \dots$

(c) Three step Adams-Moulton method:

$$y_{n+1} = y_n + \frac{h}{24} [9f(x_{n+1}, y_{n+1}) + 19f(x_n, y_n) - 5f(x_{n-1}, y_{n-1}) + f(x_{n-2}, y_{n-2})],$$

where  $n = 2, 3, 4, \dots$

(d) Adams-Moulton Predictor-Corrector formula:

$$\begin{aligned} y_{n+1}^* &= y_n + \frac{h}{24} [55f(x_n, y_n) - 59f(x_{n-1}, y_{n-1}) + 37f(x_{n-2}, y_{n-2}) - 9f(x_{n-3}, y_{n-3})], \\ y_{n+1} &= y_n + \frac{h}{24} [9f(x_{n+1}, y_{n+1}^*) + 19f(x_n, y_n) - 5f(x_{n-1}, y_{n-1}) + f(x_{n-2}, y_{n-2})]. \end{aligned}$$