

IoT Smart Home Kit for ESP32

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1. Description

As the rapid development of the Internet grows, various intelligent devices are gradually integrated into our daily life. For example, we can use RFID to open the door. In addition, the kitchen is equipped with gas detection alarms and fans. When dangerous gases and large smoke are detected, they can remind people to pay attention to the danger, and the fan will automatically turn on to allow air to flow. When it detects rain, it can automatically collect clothes and close windows. All kinds of electrical equipment can be controlled by mobile phone, control lights, fans, air conditioning and so on.

In this connection, we seek to launch this smart home product with ESP32 control, which has a host of sensors and modules as well as networking function, making the relevant knowledge of the Internet more accessible to you.

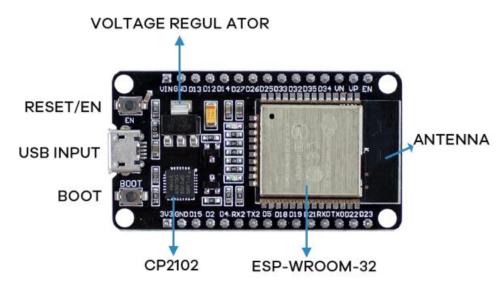
2. Features

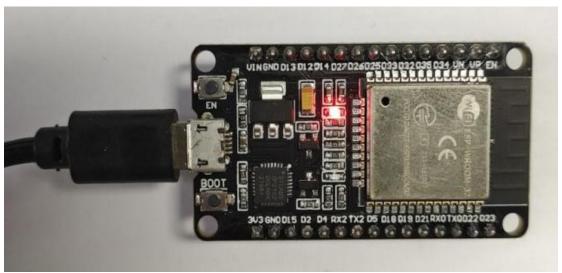
- 1. Elegant appearance
- 2. A host of sensor modules
- 3. Mobile phone APP network control



- 4. Morse password door
- 5. It can automatically close windows
- 6. RFID function
- 7. C language and MicroPython

3. Parameters







4. Projects

Sample code for all projects is in the folder, as shown bel ow:

android APP	2024/4/9 9:06	文件夹
Arduino Tutorials	2024/4/9 9:08	文件夹
Python Tutorials	2024/4/8 18:01	文件夹

Project 1: Control LED

We will first learn how to control LED.



1. Working Principle

LED is also the light-emitting diode, which can be made i nto an electronic module. It will shine if we control pins t o output high level, otherwise it will be off.

2. Parameters

Working voltage	DC 3~5V
Working current	<20mA
Power	0.1W



3. Control Pin

Yellow LED	2
------------	---

Project 1.1 LED Flashing

1. Description

We can make the LED pin output high level and low level to make the LED flash.

2. Test Code

3. Test Result

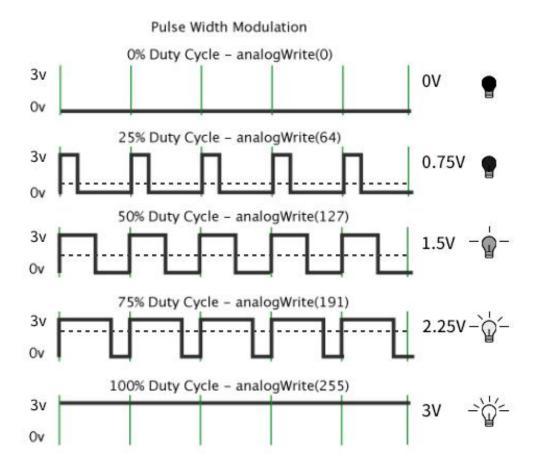
After uploading the code, you can see white and yellow LEDs flashing together.



Project 1.2 Breathing LED

1. Description

A "breathing LED" is a phenomenon where an LED's brightness smoothly changes from dark to bright and back to dark, continuing to do so and giving the illusion of an LED "breathing. However, how to control LED's brightness? It makes sense to take advantage of PWM. Output the number of high level and low level in unit time, the more time the high level occupies, the larger the PWM value, the brighter the LED.





We provide the PWM output library file < analogwrite.h > for ESP32, therefore solely a simple statement analogWrite(); can control the PWM output.

2. Test Code

3. Test Result

The LED gradually gets dimmer then brighter, cyclically, like human breathe.



Project 2: Table Lamp

1. Description

The common table lamp uses LED lights and buttons, which can control the light on and off pressing the button.

2. Button Principle

The button module is a digital sensor, which can only read 0 or 1. When the module is not pressed, it is in a high level state, that is, 1, when pressed, it is a low level 0.



3. Pins of the Button

Button 1	16
Button 2	4

Project 2.1 Read the Button

1. Description

We will work to read the status value of the button and display it on the serial monitor, so as to see it intuitively.

2. Test Code

#define btn1 16
#define btn2 4

void setup() {



```
Serial.begin(9600);
pinMode(btn1, INPUT);
pinMode(btn2, INPUT);
}

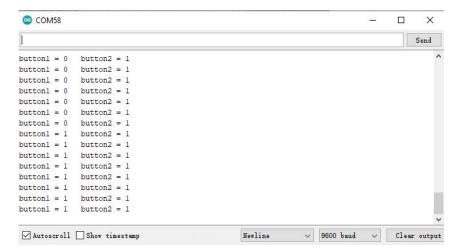
void loop() {
boolean btn1_val = digitalRead(btn1);
boolean btn2_val = digitalRead(btn2);
Serial.print("button1 = ");
Serial.print(btn1_val);
Serial.print(" ");
Serial.print("button2 = ");
Serial.print("button2 = ");
Serial.println(btn2_val);
delay(100);
}
```

Open the serial monitor of the arduino IDE

```
opj2_1_button | Arduino 1.8.3
文件 编辑 项目 工具 帮助
20 11 12
#define btn1 16
#define btn2 4
void setup() {
 Serial.begin(9600);
 pinMode(btn1, INPUT);
 pinMode(btn2, INPUT);
void loop() {
 boolean btn1_val = digitalRead(btn1);
 boolean btn2_val = digitalRead(btn2);
 Serial.print("button1 = ");
 Serial. print (btn1_val);
 Serial.print(" ");
 Serial.print("button2 = ");
 Serial.println(btn2_val);
 delay(100);
```

Press the button again to see the change of the button state value, as shown below:





Project 2.2. Table Lamp

1. Description

For common simple table lamp, click the button it will be opened, click it again, the lamp will be closed.

2. Test Code

Calculate the clicked button times and take the remainder of

2, you can get 0 or 1 two state values.

```
#define btn1 16
#define led_y 2
int btn_count = 0; //Used to count the clicked button times

void setup() {
    Serial.begin(9600);
    pinMode(btn1, INPUT);
    pinMode(led_y, OUTPUT);
}

void loop() {
    boolean btn1_val = digitalRead(btn1);
    if(btn1_val == 0) //If the button is pressed
    {
        delay(10); //Delay 10ms to eliminate button jitter
        if(btn1_val == 0) //Make sure the button is pressed again
```



```
boolean btn_state = 1;
       while(btn_state == 1) //Loop indefinitely until the button is released
         boolean btn_val = digitalRead(btn1);
         if(btn_val == 1) //If the button is released
                               //Automatically increments by 1, account the
            btn_count++;
                                                                                  clicked button
times
            Serial.println(btn_count);
            btn_state = 0; //The button is released and exits the loop
         }
       }
    boolean value = btn_count % 2; //Take the remainder of the value, you will get 0 or 1
    if(value == 1)
       digitalWrite(led_y, HIGH);
    }
    else{
       digitalWrite(led_y, LOW);
```

Open the serial monitor and print out the clicked button times, then click the button once, the LED will be on, click it again, it will be off.





Project 3: PIR Motion Sensor

1. Description

The PIR motion sensor has many application scenarios in daily life, such as automatic induction lamp of stairs, automatic induction faucet of washbasin, etc.

It is also a digital sensor like buttons, which has two state values 0 or 1. And it will be sensed when people are moving.



2. Control Pin

PIR motion sensor	35
-------------------	----



Project 3.1 Read the PIR Motion Sensor

We will print out the value of the PIR motion sensor through the serial monitor.

1. Test Code

```
#define pyroelectric 35

void setup() {
    Serial.begin(9600);
    pinMode(pyroelectric, INPUT);
}

void loop() {
    boolean pyroelectric_val = digitalRead(pyroelectric);
    Serial.print("pyroelectric value = ");
    Serial.println(pyroelectric_val);
    delay(200);
}
```

2. Test Result

When you stand still in front of the sensor, the reading value is 0, move a little, it will change to 1.





Project 3.2 PIR Motion Sensor

If someone moves in front of the sensor, the LED will light up.

1. Test Code

```
#define pyroelectric 35
#define led_y 2 //Define the yellow led pin to 2
void setup() {
    Serial.begin(9600);
    pinMode(pyroelectric, INPUT);
    pinMode(led_y, OUTPUT); //Set pin to output mode
}

void loop() {
    boolean pyroelectric_val = digitalRead(pyroelectric);
    Serial.print("pyroelectric value = ");
    Serial.println(pyroelectric_val);
    delay(200);
    if(pyroelectric_val == 1)
    {
        digitalWrite(led_y, HIGH);
    } else {
        digitalWrite(led_y, LOW);
    }
}
```

2. Test Result

Move your hand in front of the sensor, the LED will turn on.

After 5s of immobility, the LED lights will turn off.



Project 4: Play Music

1. Description

There is a audio power amplifier element in the car expansion board, which is as an external amplification equipment to play music.

In this project, we will work to play a piece of music by using it.

2. Component Knowledge

Passive Buzzer: The audio power amplifier (like the passive buzzer) does not have internal oscillation. When controlling, we need to input square waves of different frequencies to the positive pole of the component and ground the negative pole to control the power amplifier to chime sounds of different frequencies.



3. Control Pin



Project 4.1 Play Happy Birthday

1. Test Code

```
#include <ESP32Tone.h>
#define buzzer pin 32
void setup() {
  pinMode(buzzer pin, OUTPUT);
  birthday();
void loop() {
void birthday()
  tone (buzzer_pin, 294, 250, 0);
                                     //The
                                             four parameters are
                                                                         pin,
frequency, delay and channel
  tone (buzzer_pin, 440, 250, 0);
  tone (buzzer_pin, 392, 250, 0);
  tone (buzzer_pin, 532, 250, 0);
  tone (buzzer_pin, 494, 250, 0);
  tone (buzzer_pin, 392, 250, 0);
  tone (buzzer_pin, 440, 250, 0);
  tone (buzzer_pin, 392, 250, 0);
  tone (buzzer_pin, 587, 250, 0);
  tone (buzzer_pin, 532, 250, 0);
  tone (buzzer pin, 392, 250, 0);
  tone (buzzer pin, 784, 250, 0);
  tone (buzzer_pin, 659, 250, 0);
  tone (buzzer pin, 532, 250, 0);
  tone (buzzer pin, 494, 250, 0);
  tone (buzzer_pin, 440, 250, 0);
  tone (buzzer pin, 698, 250, 0);
```



```
tone (buzzer_pin, 659, 250, 0);
tone (buzzer_pin, 532, 250, 0);
tone (buzzer_pin, 587, 250, 0);
tone (buzzer_pin, 532, 500, 0);
noTone (buzzer_pin, 0); //Close
}
```

The passive buzzer will play happy Birthday.

Project 4.2 Music Box

we will make a music box and switch tunes by pressing b uttons.

1. Test Code

```
#include <ESP32Tone.h>
#include <musicESP32 home.h>
music Music (32);
#define btn1 16
int btn_count = 0; //Used to count the clicked button times
boolean music_flag = 0;
void setup() {
 Serial.begin(9600);
 pinMode(btn1, INPUT);
  pinMode(32, OUTPUT);
//Song List
// Music.tetris();
// Music.birthday();
// Music.Ode_to_Joy();
// Music.christmas();
// Music.super mario();
// Music.star_war_tone();
```



```
void loop() {
  boolean btn1_val = digitalRead(btn1);
  if (btn1_val == 0) //If the button is pressed
  {
    delay(10); //Delay 10ms to eliminate button jitter
    if (btn1 val == 0) //Make sure the button is pressed again
      boolean btn state = 1;
      while (btn state == 1) //Loop indefinitely until the button is
released
       boolean btn_val = digitalRead(btn1);
        if (btn val == 1) //If the button is released
         music_flag = 1;
         btn count++; //Automatically increments by 1 to count the
number of times the button is clicked
         Serial.println(btn_count);
          if(btn count == 4)
           btn_count = 1;
          switch(btn_count)
                                 if(music_flag
                            1:
            case
1) {Music.Ode_to_Joy(); music_flag=0;} break;
                            2:
                                          if (music_flag
1) {Music.christmas(); music_flag=0;} break;
           case 3: if(music_flag == 1) {Music.tetris();music_flag=0;}
break;
         btn_state = 0; //The button is released and exits the loop
```



}

2. Test Result

Click button 1 once, it will play Ode_to_Joy, then click it again, it will play Christmas, after playing, click the button 1 for the third time, it will play a tetris.

Project 5: Automatic Doors and Windows

1. Description

Automatic doors and windows need power device, which will become more automatic with a 180 degree servo and some sensors. Adding a raindrop sensor, you can achieve the effect of closing windows automatically when rainin g. If adding a RFID, we can realize the effect of swiping to open the door and so on.

2. Component Knowledge

Servo: Servo is a position servo driver device consists of a housing, a circuit board, a coreless motor, a gear and a position detector.

Its working principle is that the servo receives the signal sent by MCU or receiver and produces a reference signal with a period of 20ms and width of 1.5ms, then compares the



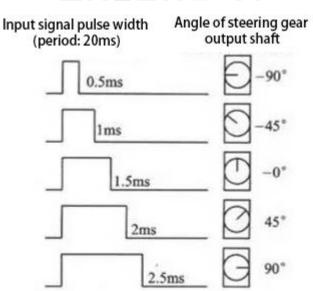
acquired DC bias voltage to the voltage of the potentiometer and obtain the voltage difference output.

The IC on the circuit board judges the direction of rotation, and then drives the coreless motor to start rotation. The power is transmitted to the swing arm through the reduction gear, and the signal is sent back by the position detector to judge whether the positioning has been reached, which is suitable for those control systems that require constant angle change and can be maintained.

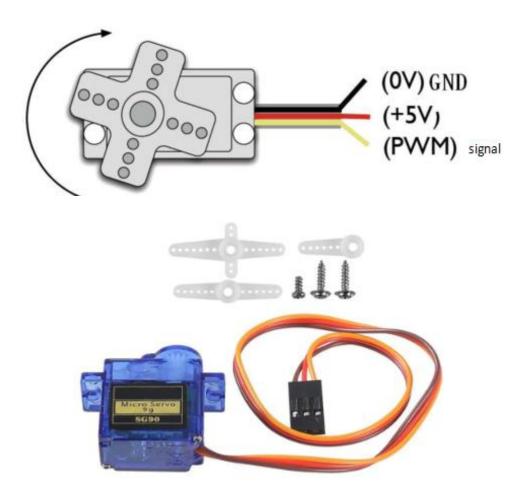
When the motor speed is constant, the potentiometer is driven to rotate through the cascade reduction gear, which leads that the voltage difference is 0, and the motor stops rotating. Generally, the angle range of servo rotation is 0° --180°.

The pulse period of the control servo is 20ms, the pulse width is 0.5ms \sim 2.5ms, and the corresponding position is -90° \sim +90°. Here is an example of a 180° servo:





In general, servo has three lines in brown, red and orange. The brown wire is grounded, the red one is a positive pole line and the orange one is a signal line.





3. Pin

The servo of the window	12
The servo of the door	13

Project 5.1 Control the Door

1. Test Code

```
#include <ESP32 Servo.h>
Servo myservo; // create servo object to control a servo
                   // 16 servo objects can be created on the ESP32
int pos = 0;
               // variable to store the servo position
// Recommended PWM GPIO pins on the ESP32 include 2,4,12-19,21-23,25-27,32-33
int servoPin = 13;
void setup() {
  myservo.attach(servoPin); // attaches the servo on pin 18 to the servo object
}
void loop() {
  for (pos = 0; pos <= 180; pos += 1) { // goes from 0 degrees to 180 degrees
    // in steps of 1 degree
     myservo.write(pos);
                                         // tell servo to go to position in variable 'pos'
    delay(15);
                                           // waits 15ms for the servo to reach the position
  for (pos = 180; pos \geq 0; pos \geq 1) { // goes from 180 degrees to 0 degrees
                                          // tell servo to go to position in variable 'pos'
     myservo.write(pos);
                                           // waits 15ms for the servo to reach the position
     delay(15);
  }
```

2. Test Result

The servo of the door rotates with the door.



Project 5.2 Close the Window

1. Description

We will work to use a servo and a raindrop sensor to make an device closing windows automatically when raining.

2. Component Knowledge

Raindrop Sensor: This is an analog input module, the greater the area covered by water on the detection surface, the greater the value returned (range 0~4096).

3. Test Code

```
#include <ESP32_Servo.h>
Servo myservo;
#define servoPin 12
#define waterPin 34
void setup() {
  Serial.begin(9600);
  pinMode(waterPin, INPUT);
  myservo.attach(servoPin);
  myservo.write(176);
  delay(200);
}
void loop() {
  int water_val = analogRead(waterPin);
  Serial.println(water_val);
  if(water_val > 1500) {
     myservo.write(0);
    delay(200);
  }
  else {
     myservo.write(176);
```



```
delay(200);
}
}
```

At first, the window opens automatically, and when you touch the raindrop sensor with your hand (which has water on the skin), the window will close.

Project 6: Atmosphere Lamp

1. Description

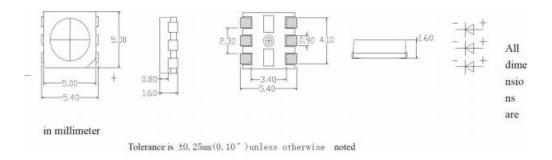
The atmosphere lamp of smart home is a SMD RGB LED. RGB LED belongs to a simple luminous module, which can adjust the color to bring out the lamp effect of different colors. Furthermore, it can be widely used in buildings, b ridges, roads, gardens, courtyards, floors and other fields of decorative lighting and venue layout, Christmas, Hallow een, Valentine's Day, Easter, National Day as well as other festivals during the atmosphere and other scenes.

2. Component Knowledge

SMD RGB LED module is made from a patch of full-color LED. By adjusting the voltage input of R, G, B pins, we can adjust



the strength of the three primary colors (red/blue/green) so to implementation result of full color effect.



Parameter	Symbol	Value	Unit
Forward Current	If	20	mA
Reverse Voltage	Vr	5	v
Operating Temperature	Торг	-25~+85	°C
Storage Temperature	Tstg	-35~+85	°C
Soldering temperature	Tsol	260±5°C (for4sec)	2,
Power Dissipation	Pd	R=40	mW
Pulse Current	I_{FP}	100	mA



3. Pin

R	14
G	27
В	15



Project 6.1 Control RGB

We will control RGB to display various lighting effects.

1. Test Code

Please open the provided test code pj6_1_three_led, as sh own in the image below:

pj1_1_led	2024/4/8 17:39	文件夹
pj1_2_breath_led	2024/4/8 17:39	文件夹
pj2_1_button	2024/4/8 17:39	文件夹
pj2_2_button_led	2024/4/8 17:39	文件夹
pj3_1_pyroelectric	2024/4/8 17:39	文件夹
pj3_2_pyroelectric_led	2024/4/8 17:39	文件夹
pj4_1_buzzer	2024/4/8 17:39	文件夹
pj4_2_music	2024/4/8 17:39	文件夹
pj5_1_servo	2024/4/8 17:39	文件夹
pj5_2_Auto_window	2024/4/8 17:39	文件夹
pj6_1_three_led	2024/4/8 17:39	文件夹

2. Test Result

The atmosphere lamps of the smart home will display a v ariety of colors and light effects.

Project 6.2 Button

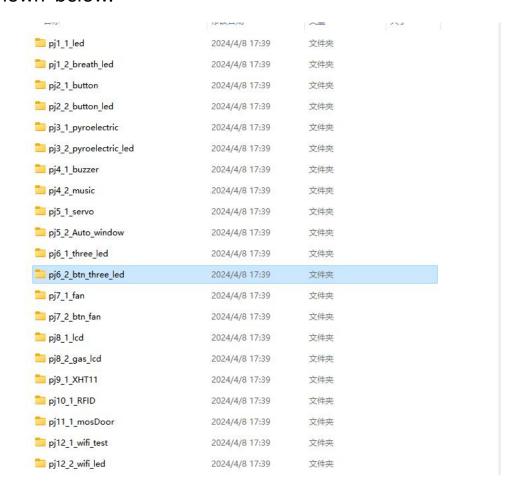
1. Description

There are two buttons to switch the color of the atmosph ere lamp.



2. Test Code

Please open the provided test code pj6_2_btn_three_led, as shown below:



3. Test Result

We can switch the color of the atmosphere lamp by clicking buttons 1 and 2.

Project 7: Fan

1. Description

In this project, we will learn how to make a small fan.



2. Component Knowledge

The small fan uses a 130 DC motor and safe fan blades. You can use PWM output to control the fan speed.



3. Control Method

Two pins are required to control the motor of the fan, one for INA and two for INB. The PWM value range is 0~255. When the PWM output of the two pins is different, the fan can rotate.

INA - INB <= -45	Rotate clockwise
INA - INB >= 45	Rotate anticlockwise
INA == 0, INB == 0	Stop

4. Control Pins

INA	25
INB	33

Project 7.1 Control the Fan

We can control the anticlockwise and clockwise rotation s peed of the fan.



1. Test Code

```
#include <analogWrite.h>
#define fanPinA 25
#define fanPinB 33
void setup() {
  pinMode(fanPinA, OUTPUT);
  pinMode(fanPinB, OUTPUT);
}
void loop() {
  //Fan forward rotation
  digitalWrite(fanPinA, HIGH); //pwm = 255
  digitalWrite(fanPinB, LOW);
  delay(3000);
  digitalWrite(fanPinA, LOW);
  digitalWrite(fanPinB, LOW);
  delay(3000);
  //Fan reversal
  digitalWrite(fanPinA, LOW); //pwm = 0
  digitalWrite(fanPinB, HIGH);
  delay(3000);
  digitalWrite(fanPinA, LOW);
  digitalWrite(fanPinB, LOW);
  delay(3000);
```

2. Test Result

The fan will rotate clockwise and anticlockwise at different speeds.

Project 7.2 Switch On or Off the Fan

One button switches the fan on and the other button con trols the speed of the fan.



1. Test Code

```
#include <analogWrite.h>
#define fanPinA 25
#define fanPinB 33
#define btn1 16
int btn count = 0; //Used to count the clicked button times
#define btn2 4
int btn count2 = 0;
int speed_val = 130; //Define the speed variables
void setup() {
  Serial.begin(9600);
  pinMode(btn1, INPUT);
  pinMode(btn2, INPUT);
  pinMode(fanPinA, OUTPUT);
  pinMode(fanPinB, OUTPUT);
}
void loop() {
  boolean btn1_val = digitalRead(btn1);
  if(btn1_val == 0) //If the button is pressed
     delay(10); //Delay 10ms to eliminate button jitter
     if(btn1_val == 0) //Make sure the button is pressed again
       boolean btn_state = 1;
       while(btn state == 1) //Loop indefinitely until the button is released
         boolean btn_val = digitalRead(btn1);
         if(btn_val == 1) //If the button is released
            btn_count++;
                             //Automatically increments by 1 to count the clicked button times
            Serial.println(btn_count);
            btn_state = 0; //The button is released and exits the loop
         }
       }
     boolean value = btn_count % 2; //Take the remainder of the value, you will get 0 or 1
     while(value == 1)
       //Serial.println("on");
       digitalWrite(fanPinA, LOW); //pwm = 0
       analogWrite(fanPinB, speed_val);
```



```
boolean btn2_val = digitalRead(btn2);
  if(btn2_val == 0)
  {
     delay(10);
     if(btn2_val == 0)
       boolean btn state2 = 1;
       while(btn_state2 == 1)
          boolean btn2_val = digitalRead(btn2);
          if(btn2_val == 1)
            btn_count2++;
            if(btn_count2 > 3)
              btn_count2 = 1;
            switch(btn_count2)
              case 1: speed_val = 130; Serial.println(speed_val);break; //Adjust the speed
              case 2: speed_val = 180; Serial.println(speed_val);break;
              case 3: speed_val = 230; Serial.println(speed_val);break;
            }
            btn_state2 = 0;
         }
       }
    }
  boolean btn1_val = digitalRead(btn1);
  if(btn1_val == 0) //If the button is pressed
     digitalWrite(fanPinA, LOW); //pwm = 0
     analogWrite(fanPinB, 0);
     value = 0; //Exit the loop
  }
}
```

Click button 1, the fan starts to rotate, click button 2, the



speed can be adjusted(there are three different speeds), p ress the button 1 again, the fan stops.

Project 8: LCD1602 Display

1. Description

As we all know, screen is one of the best ways for people to interact with electronic devices.

2. Component Knowledge

1602 is a line that can display 16 characters. There are two lines, which use IIC communication protocol.



3. Control Pins

SDA	21
SCL	22

Project 8.1 Display Characters

1. Test Code

#include <Wire.h>
#include <LiquidCrystal_I2C.h>
LiquidCrystal_I2C mylcd(0x27,16,2);



```
void setup(){
   mylcd.init();
   mylcd.backlight();
}

void loop(){
   mylcd.setCursor(0, 0);
   mylcd.print("hello");
   mylcd.setCursor(0, 1);
   mylcd.print("Lrobruya");
   //mylcd.clear();
}
```

The first line of the LCD1602 shows hello and the second line shows Lrobruya.

Project 8.2 Dangerous Gas Alarm

1. Description

When a gas sensor detects a high concentration of dangerous gas, the buzzer will sound an alarm and the display will show dangerous and the fan will turn on.

2. Component Knowledge

MQ2 Smoke Sensor: It is a gas leak monitoring device for homes and factories, which is suitable for liquefied gas, benzene, alkyl, alcohol, hydrogen as well as smoke detection. Our sensor leads to digital pin D and analog output pin A, which is connected to D as a digital sensor in this



project.



Gas Sensor

39

3. Test Code

```
#include <Wire.h>
#include <LiquidCrystal I2C.h>
LiquidCrystal_I2C mylcd(0x27, 16, 2);
#define fanPinA 25
#define fanPinB 33
#define gasPin 39
#define buzPin 32
boolean i = 1;
boolean j = 1;
void setup() {
  Serial.begin(9600);
  mylcd.init();
  mylcd.backlight();
  pinMode(buzPin, OUTPUT);
  pinMode(gasPin, INPUT);
  mylcd. setCursor(0, 0);
  mylcd.print("safety");
  pinMode(fanPinA, OUTPUT);
  pinMode(fanPinB, OUTPUT);
void loop() {
  boolean gasVal = digitalRead(gasPin); //Reads the value detected by
the gas sensor
  Serial.println(gasVal);
  if(gasVal == 0) //If the hazardous gas is detected, LCD displays
dangerous, the buzzer makes an alarm
```



```
while (i == 1)
    mylcd.clear();
    mylcd.setCursor(0, 0);
    mylcd.print("dangerous");
    digitalWrite(fanPinA, LOW); //pwm = 0
    digitalWrite(fanPinB, HIGH);
    i = 0;
    j = 1;
  digitalWrite(buzPin, HIGH);
  delay(1);
  digitalWrite(buzPin, LOW);
  delay(1);
}
else{
  digitalWrite(buzPin, LOW);
  while (j == 1)
    mylcd.clear();
    mylcd.setCursor(0, 0);
    mylcd.print("safety");
    digitalWrite(fanPinA, LOW);
    digitalWrite(fanPinB, LOW);
    i = 1;
    j = 0;
```

The screen displays "safety" in normal state. However, when the gas sensor detects some dangerous gases, such as carbon



monoxide, at a certain concentration, the buzzer will sound an alarm and the screen displays "dangerous" and the fan will turn on.

Project 9: Temperature and Humidity Sensor

1. Component Knowledge

Its communication mode is serial data and single bus. The temperature measurement range is $-20 \sim +60^{\circ}$ C, accuracy is $\pm 2^{\circ}$ C. However, the humidity range is 5 ~ 95%RH, the accuracy is $\pm 5\%$ RH.



2. Control Pin

Temperature and Humidity Sensor	26
---------------------------------	----

Project 9.1 Temperature and Humidity Tester

```
#include <Wire.h>
#include <LiquidCrystal_I2C.h>
LiquidCrystal_I2C mylcd(0x27,16,2);
#include "xht11.h"
xht11 xht(26);

unsigned char dht[4] = {0, 0, 0, 0};//Only the first 32 bits of data are received, not the parity bits void setup() {
    Serial.begin(9600);//Start the serial port monitor and set baud rate to 9600
```



```
mylcd.init();
  mylcd.backlight();
}
void loop() {
  if (xht.receive(dht)) { //Returns true when checked correctly
    Serial.print("RH:");
    Serial.print(dht[0]); //The integral part of humidity, DHT [1] is the fractional part
    Serial.print("% ");
    Serial.print("Temp:");
    Serial.print(dht[2]); //The integral part of temperature, DHT [3] is the fractional part
    Serial.println("C");
    mylcd.setCursor(0, 0);
    mylcd.print("Hum = ");
    mylcd.print(dht[0]);
    mylcd.print("%");
    mylcd.setCursor(0, 1);
    mylcd.print("Temp=");
    mylcd.print(dht[2]);
    mylcd.print("C");
    //mylcd.clear();
    delay(200);
             //Read error
  } else {
    Serial.println("sensor error");
  delay(1000); //It takes 1000ms to wait for the device to read
                   ****************
```

The LCD1602 displays the temperature (Temp= ** C) and humidity (Hum = ** %). When you breathe into the T/H sensor, you can see that the humidity rises.



Project 10: RFID RC522 Module

1. Component Knowledge

Radio frequency identification, the card reader is composed of a radio frequency module and a high-level magnetic field. The Tag transponder is a sensing device, which doesn't contain a battery. It only contains tiny integrated circuit chips and media for storing data and antennas for receiving and transmitting signals.

To read the data in the tag, first put it into the reading range of the card reader. The reader will generate a magnetic field, which can produce electricity according to Lenz's law, then the RFID tag will supply power, thereby activating the device.



2. Control Pins

RST	17
SDA	5
SCK	18
MISO	19



MOSI 23

Project 10.1 Open the Door

```
#include <Wire.h>
#include <LiquidCrystal I2C.h>
LiquidCrystal I2C mylcd(0x27, 16, 2);
#include <ESP32 Servo.h>
Servo myservo;
#include <Wire.h>
#include <SPI.h>
#include <MFRC522.h>
#define RST_PIN 17 // RST:17
#define SS PIN
                   5
                        // SDA:5
MFRC522 mfrc522(SS PIN, RST PIN);
#define servoPin 13
#define btnPin 16
boolean btnFlag = 0;
void setup() {
  Serial. begin (9600);
                                    // initialize and PC's serial
communication
 mylcd.init();
  mylcd.backlight();
                              // initialize I2C
 Wire. begin();
                              // Initialize SPI bus
 SPI. begin();
  mfrc522.PCD_Init();
                             // Initialize MFRC522 module
  Serial.println("Scan RFID tag to get its UID...");
  myservo. attach(servoPin);
  myservo.write(0);
  pinMode(btnPin, INPUT);
  mylcd. setCursor(0, 0);
```



```
mylcd.print("Card");
void loop() {
    // close door use button
    if(btnFlag == 1)
      boolean btnVal = digitalRead(btnPin);
      if (btnVal == 0) //Swipe the card to open the door and click button
1 to close the door
      {
        Serial.println("close");
        mylcd. setCursor(0, 0);
        mylcd.print("close");
        myservo.write(0);
        btnFlag = 0;
 // select one of door cards. UID and SAK are mfrc522.uid.
 // save UID
  if
                    (mfrc522.PICC IsNewCardPresent()
                                                                      &&
mfrc522.PICC ReadCardSerial()) {
    Serial.print("UID tag:");
    String content = "";
    byte letter;
    for (byte i = 0; i < mfrc522. uid. size; i++) {
       Serial. print (mfrc522. uid. uidByte[i] < 0x10 ? " 0" : " ");
       Serial.print(mfrc522.uid.uidByte[i], HEX);
       content.concat(String(mfrc522.uid.uidByte[i] < 0x10 ? " 0" : "</pre>
"));
       content. concat (String (mfrc522. uid. uidByte[i], HEX));
    Serial.println();
    Serial.print("Message : ");
    content. toUpperCase();
    if (content. substring(1) = "F3 C6 6F 1A") {
```



```
Serial.println("open");
    mylcd.setCursor(0, 0);
    mylcd.print("open");
    myservo.write(180);
    btnFlag = 1;
}
else {
    mylcd.setCursor(0, 0);
    mylcd.print("error");
    btnFlag = 0;
}
```

Close the provided card to the RFID induction area, the door will turn and open, and LCD1602 shows "open". Click button 1 and the door turns and closes. However, when swiping another blue induction block, the LCD1602 shows "error".

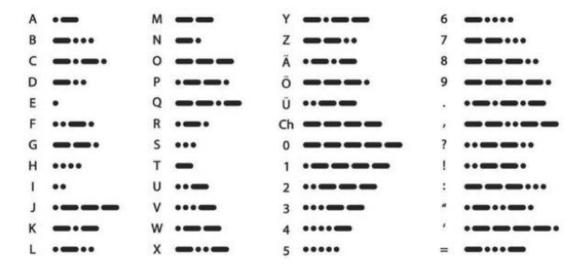
Project 11: Morse Code

Morse code, also known as Morse password, is an on-again, off-again signal code that expresses different letters, numbers, and punctuation marks in different sequences. Now we use it as our password gate.

The Morse code corresponds to the following characters:



Morse Code



Project 11.1 Morse Code Open the Door

1. Description

We use as the correct password. What's more, there is a button library file OneButton, which is very simple to click, double click, long press and other functions. For Morse password, click is ".", long press and release is "-".

```
#include <Wire.h>
#include <LiquidCrystal_I2C.h>
LiquidCrystal_I2C mylcd(0x27,16,2);
#include "OneButton.h"

// Setup a new OneButton on pin 16.
OneButton button1(16, true);

// Setup a new OneButton on pin 4.
OneButton button2(4, true);
#include <ESP32_Servo.h>
Servo myservo;
int servoPin = 13;
String password = "";
String correct_p = "-.-"; //The correct password for the password door
```



```
// setup code here, to run once:
void setup() {
  Serial.begin(115200);
  mylcd.init();
  mylcd.backlight();
  // link the button 1 functions.
  button1.attachClick(click1);
  button1.attachLongPressStop(longPressStop1);
  // link the button 2 functions.
  button2.attachClick(click2);
  button2.attachLongPressStop(longPressStop2);
  myservo.attach(servoPin);
  mylcd.setCursor(0, 0);
  mylcd.print("Enter password");
}
void loop() {
  // keep watching the push buttons:
  button1.tick();
  button2.tick();
  delay(10);
}
// ---- button 1 callback functions
// This function will be called when the button1 was pressed 1 time (and no 2. button press
followed).
void click1() {
  Serial.print(".");
  password = password + '.';
  mylcd.setCursor(0, 1);
  mylcd.print(password);
} // click1
// This function will be called once, when the button1 is released after being pressed for a long
time.
void longPressStop1() {
  Serial.print("-");
  password = password + '-';
  mylcd.setCursor(0, 1);
  mylcd.print(password);
}//longPressStop1
```



```
// ... and the same for button 2:
void click2() {
  Serial.println(password);
  if(password == correct_p)
     myservo.write(180); //Open the door if the password is correct
     mylcd.clear();
     mylcd.setCursor(0, 0);
     mylcd.print("open");
  }
  else
     mylcd.clear();
     mylcd.setCursor(0, 0);
     mylcd.print("error");
     delay(2000);
     mylcd.clear();
     mylcd.setCursor(0, 0);
     mylcd.print("input again");
  password = "";
} // click2
void longPressStop2() {
  //Serial.println("Button 2 longPress stop");
   myservo.write(0); //Close the door
   mylcd.clear();
   mylcd.setCursor(0, 0);
   mylcd.print("close");
}// longPressStop2
```

At first, the LCD1602 displays "Enter password", then click or long press button 1 to tap the password. If we input the correct password "-.-", then click button 2, the door will open, and the LCD1602 will display "open".

If other incorrect passwords are entered, the door will not move, the LCD1602 will display "error" and then "input



again" 2s later. Furthermore, long press button 2 can close the door.

Project 12: WiFi

The easiest way to access the Internet is to use a WiFi to connect. The ESP32 main control board comes with a WiFi module, making our smart home accessible to the Internet easily.



Project 12.1 Smart Home

1. Description

We connect the smart home to a LAN, which is the WiFi in your home or the hot spot of your phone. After the connection is successful, an address will be assigned, which



can be used for communication. We will print the assigned address in the serial monitor.

Suggest using mobile hotspot, command feedback will be faster.

2. Test Code

Note: ssid and password in the code should be filled with your own WiFi name and password.

```
#include <Arduino.h>
#include <WiFi.h>
#include <ESPmDNS.h>
#include <WiFiClient.h>
String item = "0";
const char* ssid = "longvn-US";
const char* password = "11118888";
WiFiServer server (80):
void setup() {
  Serial. begin (115200);
  WiFi. begin (ssid, password);
  while (WiFi.status() != WL_CONNECTED) {
    delay (500);
    Serial. print(".");
  Serial.println("");
  Serial.print("Connected to ");
  Serial.println(ssid);
  Serial.print("IP address: ");
  Serial. println(WiFi. localIP());
  server.begin();
  Serial.println("TCP server started");
  MDNS. addService ("http", "tcp", 80);
```

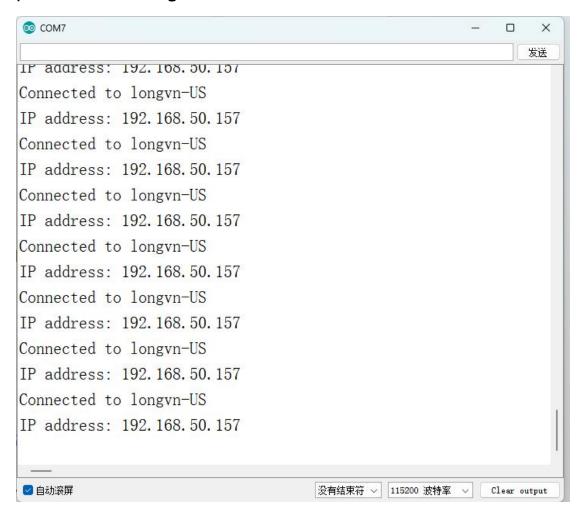


```
void loop() {
  Serial.print("Connected to ");
  Serial. println(ssid);
  Serial.print("IP address: ");
  Serial.println(WiFi.localIP()); //The assigned IP address is printed
on the serial monitor
  delay (200);
  WiFiClient client = server.available();
  if (!client) {
      return;
  while(client.connected() && !client.available()) {
      delay(1);
  String req = client.readStringUntil('\r');
  int addr_start = req.indexOf(' ');
  int addr_end = req.indexOf(' ', addr_start + 1);
  if (addr start == -1 \mid \mid addr end == -1) {
      Serial.print("Invalid request: ");
      Serial. println(req);
      return;
  req = req. substring(addr_start + 1, addr_end);
  item=req;
  Serial.println(item);
  String s;
  if (req = "/") //Browser accesses address can read the information
sent by the client.println(s);
  {
      IPAddress ip = WiFi.localIP();
      String ipStr = String(ip[0]) + '.' + String(ip[1]) + '.' +
String(ip[2]) + '.' + String(ip[3]);
      s = "HTTP/1.1 200 OK\r\nContent-Type: text/html\r\n\r\n<!DOCTYPE
HTML>\r\n<html>Hello from ESP32 at ";
```



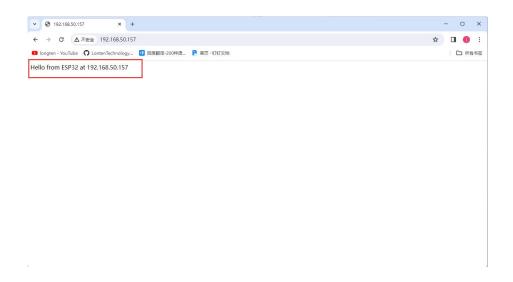
```
s += ipStr;
s += "</html>\r\n\r\n";
Serial.println("Sending 200");
client.println(s); //Send the string S, you can read the information when visiting the address of E smart home using a browser.
// Serial.println(s);
client.stop();
}
```

If the WiFi is connected successfully, the serial monitor will print out the assigned IP address.





Open a browser to access the IP address, then we will read the contents of the string S sent out by the client.printlen(s); in the code.



Project 12.2 Control Smart Home

1. Description

In this project, we will learn how to realize different functions of the smart home through accessing different strings under the address. There is a LCD screen that can print out the IP address, which is much more convenient.

```
#include <WiFi.h>
#include <ESPmDNS.h>
#include <WiFiClient.h>

String item = "0";
const char* ssid = "longvn-US";
const char* password = "11118888";
```



```
WiFiServer server (80);
#include <Wire.h>
#include <LiquidCrystal_I2C.h>
LiquidCrystal_I2C mylcd(0x27, 16, 2);
#include <analogWrite.h>
#define fanPinA 25
#define fanPinB 33
#define led y 2 //Define the yellow led pin to 2
void setup() {
  Serial. begin (115200);
  mylcd.init();
  mylcd.backlight();
  pinMode(led y, OUTPUT);
  pinMode(fanPinA, OUTPUT);
  pinMode(fanPinB, OUTPUT);
  WiFi. begin (ssid, password);
  while (WiFi.status() != WL_CONNECTED) {
    delay (500);
    Serial. print (".");
  Serial.println("");
  Serial.print("Connected to ");
  Serial.println(ssid);
  Serial.print("IP address: ");
  Serial.println(WiFi.localIP());
  server.begin();
  Serial.println("TCP server started");
  MDNS. addService ("http", "tcp", 80);
  mylcd.setCursor(0, 0);
  mylcd.print("ip:");
  mylcd.setCursor(0, 1);
  mylcd.print(WiFi.localIP()); //LCD displays ip adress
```



```
void loop() {
  WiFiClient client = server.available();
  if (!client) {
     return;
  while(client.connected() && !client.available()) {
      delay(1);
  String req = client.readStringUntil('\r');
  int addr start = req.indexOf('');
  int addr end = req.indexOf(' ', addr start + 1);
  if (addr start == -1 \mid \mid addr end == -1) {
      Serial.print("Invalid request: ");
      Serial. println(req);
     return;
 req = req. substring(addr_start + 1, addr_end);
 item=req;
 Serial.println(item);
  String s;
  if (req = "/") //Browser accesses address can read the information
sent by the client.println(s);
  {
      IPAddress ip = WiFi.localIP();
      String ipStr = String(ip[0]) + '.' + String(ip[1]) + '.' +
String(ip[2]) + '.' + String(ip[3]);
      s = "HTTP/1.1 200 OK\r\nContent-Type: text/html\r\n\r\n<!DOCTYPE
HTML>\r\n<html>ESP32 ip:";
      s += ipStr;
      s += "</html>\r\n\r,
      Serial.println("Sending 200");
      client.println(s); //Send the string S, then you can read the
information when visiting the address of E smart home using a browser.
  if (req == "/led/on") //Browser accesses address ip address/led/on
```



```
client.println("turn on the LED");
  digitalWrite(led_y, HIGH);
if(req == "/led/off") //Browser accesses address ip address/led/off
  client.println("turn off the LED");
  digitalWrite(led_y, LOW);
if (req == "/fan/on") //Browser accesses address ip address/fan/on
  client.println("turn on the fan");
  digitalWrite(fanPinA, LOW); //pwm = 0
  analogWrite(fanPinB, 180);
if(req == "/fan/off") //Browser accesses address ip address/fan/off
  client.println("turn off the fan");
  digitalWrite(fanPinA, LOW); //pwm = 0
  analogWrite(fanPinB, 0);
//client.print(s);
client.stop();
```

If the smart home is successfully connected to WiFi, the LCD screen will display the assigned address.





Accessing address must add / led/on when using the browser, such as my address is 192.168.50.157/ led/on. Then the smart home LED lights will be turned on, if accessing 192.168.50.157/ led /off, then the LED lights will be off.



When the browser accesses 192.168.50.157/fan/ on, the fan of the smart home will be turned on and at 192.168.50.157/fan/ off will be turned off.





Project 13: Mobile Phone APP

Download APP

Android APP:

The Android apk installation package is available in our resource pack, as shown below:



Download from Google play:

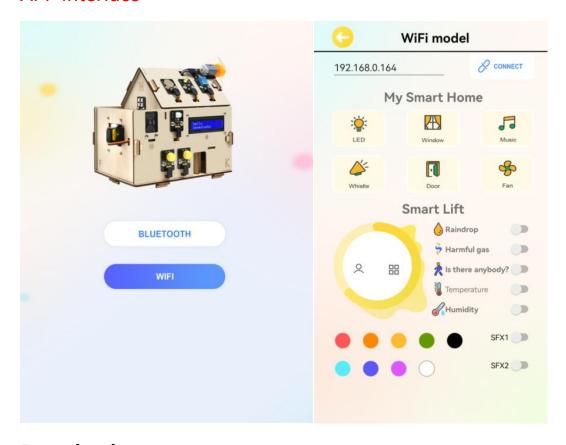
Please search for keyes IoT home on Google play to dow nload it.

Icon:





APP Interface



Download iOS APP

Please search for keyes IoT home on APP Store to download it.

Project 13.1 Test APP

1. Description

We will use APP to control the smart home LED lights and fan switches.



```
#include <WiFi.h>
#include <ESPmDNS.h>
#include <WiFiClient.h>
String item = "0";
const char* ssid = "longvn-US";
const char* password = "11118888";
WiFiServer server (80);
#include <Wire.h>
#include <LiquidCrystal_I2C.h>
LiquidCrystal_I2C mylcd(0x27, 16, 2);
#include <analogWrite.h>
#define fanPinA 25
#define fanPinB 33
#define led_y 2 //Define the yellow led pin to 2
void setup() {
  Serial. begin (115200);
  mylcd.init();
  mylcd.backlight();
  pinMode(led_y, OUTPUT);
  pinMode(fanPinA, OUTPUT);
  pinMode(fanPinB, OUTPUT);
  WiFi. begin (ssid, password);
  while (WiFi.status() != WL CONNECTED) {
    delay (500);
    Serial. print (".");
  Serial. println("");
  Serial.print("Connected to ");
  Serial.println(ssid);
  Serial.print("IP address: ");
  Serial. println(WiFi. localIP());
```



```
server.begin();
  Serial.println("TCP server started");
  MDNS. addService ("http", "tcp", 80);
  mylcd.setCursor(0, 0);
  mylcd.print("ip:");
  mylcd.setCursor(0, 1);
 mylcd.print(WiFi.localIP()); //LCD displays ip adress
void loop() {
  WiFiClient client = server.available();
 if (!client) {
      return;
 while(client.connected() && !client.available()) {
      delay(1);
  String req = client.readStringUntil('\r');
  int addr start = req.indexOf(' ');
  int addr end = req.indexOf(' ', addr start + 1);
  if (addr_start == -1 \mid \mid addr_end == -1) {
      Serial.print("Invalid request: ");
      Serial. println (req);
      return;
 req = req. substring(addr_start + 1, addr_end);
 item=req;
 Serial.println(item);
 String s;
  if (req = "/") //Browser accesses address can read the information
sent by the client.println(s);
  {
      IPAddress ip = WiFi.localIP();
      String ipStr = String(ip[0]) + '.' + String(ip[1]) + '.' +
String(ip[2]) + '.' + String(ip[3]);
      s = "HTTP/1.1 200 OK\r\nContent-Type: text/html\r\n\r\nCOTYPE
```



```
HTML>\r\n<html>ESP32 ip:";
      s += ipStr;
      s += "</html>\r\n";
      Serial.println("Sending 200");
      client.println(s); //Send the string S, then you can read the
information when visiting the address of E smart home using a browser.
  if (req == "/led/on") //Browser accesses address ip address/led/on
    client.println("turn on the LED");
    digitalWrite(led_y, HIGH);
  if (req == "/led/off") //Browser accesses address ip address/led/off
    client.println("turn off the LED");
    digitalWrite(led y, LOW);
  if (req == "/fan/on") //Browser accesses address ip address/fan/on
    client.println("turn on the fan");
    digitalWrite(fanPinA, LOW); //pwm = 0
    analogWrite(fanPinB, 180);
 if (req == "/fan/off") //Browser accesses address ip address/fan/off
    client.println("turn off the fan");
    digitalWrite(fanPinA, LOW); //pwm = 0
    analogWrite(fanPinB, 0);
 //client.print(s);
  client.stop();
```

1. Open the APP and select WIFI





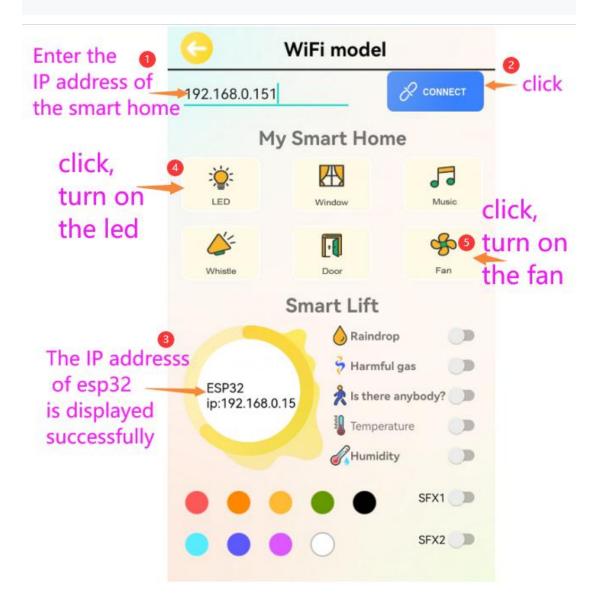
2. APP controls LED and the fan

The mobile phone and the smart home must share the sa me WiFi, or the smart home connects to the hotspot of t he mobile phone.

APP input IP address (LCD1602 displays the assigned IP a ddress), then click connect, the connection is successful if ESP32 IP: 192.168..... is displayed.



Next, you can click the LED, then the smart home LED will be turned on. Click the fan button and the fan will be turned on, as shown below:



Project 13.2 IoT Smart Home

1. Description

The IOT smart home connects to the family WiFi through



WiFi, and the mobile phone used for operation should als o be connected to the same WiFi.

What's more, the smart home also can connect to the hotspot of the mobile phone. If the connection is successful, the LCD1602 will display the IP address. Using the phone APP to input the corresponding IP for communication is enable to realize the APP control of various functions of the smart home.

2. Test Code

Please refer to the sample code, as shown below:



3. Test Result

