map2loop is a map deconstruction library to provide inputs to Loop ([Loop3d.org](https://loop3d.org/)). The development of map2loop is lead by **Mark Jessell** at The University of Western Australia. **Yohan de Rose** at Monash University is now making it better.

What it does:

• Combines information extracted from vector geology maps in various forms to support 3D geological modelling.

Outputs are simple csv files that should be readable by any 3D modelling system (I think), but specific examples are provided for

- https://github.com/Loop3D/LoopStructural LoopStructural,
- https://github.com/cgre-aachen/gempy gempy and
- https://github.com/cgre-aachen/pynoddy noddy.

Loop is led by Laurent Ailleres (Monash University) with a team of Work Package leaders from: * Monash University: Roy Thomson, Lachlan Grose and Robin Armit * University of Western Australia: Mark Jessell, Jeremie Giraud, Mark Lindsay and Guillaume Pirot * Geological Survey of Canada: Boyan Brodaric and Eric de Kemp

- This is very much a proof of concept code that is unlikely to work first time with anything but the example dataset provided, but if you would like to try it with your own data please feel free to contact me at mark.jessell@uwa.edu.au to discuss your plans.
- The fastest install path (thanks to Yohan de Rose) is via docker, go to development version at which provides both map2loop and LoopStructural:

http://github.com/Loop3D/map2loop-2

· otherwise follow these instructions:

https://github.com/Loop3D/map2loop/blob/master/m2I_LS_install.md Install Instructions

• Problems

Any bugs/feature requests/comments please create a new issue: https://github.com/Loop3D/map2loop/issues.

Acknowledgements

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map2loop outputs:

map2loop outputs:

content	filename
Various stratigraphic topology graphs	*/graph/*.gml
Group-level stratigraphic relationships	*/tmp/groups.csv

Formation-level stratigraphic relationships	*/tmp/*_groups.csv
Summary strat relationships	*/tmp/all_sorts.csv or all_sorts_clean.csv
Fault-fault relationship table	*/output/fault-fault-relationships.csv
Fault-fault relationship graph	*/output/fault_network.gml
Fault-unit relationship table	*/output/unit-fault-relationships.csv
Fault-group relationship table	*/output/group-fault-relationships.csv

Digital Terrain Model:

content	filename
dtm in lat long wgs83	*/dtm/dtm.tif
georeferenced dtm	*/dtm/dtm_rp.tif

Geometry:

content	filename
Contact info with z and formation	*/output/contacts4.csv or contacts_clean.csv
Contact info with tangent info	*/tmp/raw_contacts.csv
Fault trace with z	*/output/faults.csv
Basal contacts shapefile	*/tmp/basal_contacts.shp
Clipped geology map shapefile	*/tmp/geol_clip.shp
Clipped fault & fold axial traces shapefile	*/tmp/faults_clip.shp
Pluton contacts with z and formation	*/output/ign_contacts.csv
Local formation thickness estimates	*/output/formation_thicknesses_norm.csv and formation_summary_thickness.csv
Fault dimensions	*/output/fault_dimensions.csv
Fault displacements	*/output/fault_displacement3.csv
Fault strat & thickness-based displacements	*/output/fault_strat_offset3.csv
Near-Fault strat contacts	*/output/fault_tip_contacts*.csv

Orientations:

content	filename
Bed dip dd data with z and formation	*/output/orientations.csv or orientations_clean.csv
Bed dip dd data with calculated polarity	*/output/orientations_polarity.csv
Extra orientations for empty series	*/output/empty_series_orientations.csv
Fault orientation with z	*/output/fault_orientations.csv
Clipped orientations shapefile	*/tmp/structure_clip.shp
Interpolated dip dip direction grid	*/tmp/interpolated_orientations.csv
Interpolated contact vector grid	*/tmp/interpolated_contacts.csv

Combined interpolation grid	*/tmp/interpolated_combined.csv
Pluton contact orientations	*/output /ign_orientations*.csv
Near-Fold Axial Trace strat orientations	*/output/fold_axial_trace_orientations2.csv
Estimated contact orientations	*/output/contact_orientations.csv

loop2model:

content	filename
Gempy	Notebook creates 3D model itself
Basic vtk model thanks to gempy	*/vtk/*.vtp
Geomodeller	m2l.taskfile
LoopStructural	Notebook creates 3D model itself
noddy	Notebook creates 3D model, only of faults itself

Does not deal with sills yet.

Standalone map2model cpp code from Vitaliy provides fault/fault and fault/strat relationships

Installation The best path to isntallation is via a docker. To do this visit the development version at https://github.com/Loop3D/map2loop-2 and follow the instructions.

Requirements rasterio matplotlib networkx numpy pandas geopandas os urllib sys math shapely gempy

Simplified calculation schemes 1) Topology a. Stratigraphic relationships i. Adjacency relationships between neighbouring geological polygons based on formation and group ii. Directed graph based on these relationships and relative age of formations and groups iii. Edges attributed by type of contact (intrusive, stratigraphic, fault)

- b. Fault relationships i. Relative ages of faults longer than a specified length estimated from truncation relationships ii. Directed graph based on these relationships iii. Cyclic relationships removed (A truncates B; B truncates C; C truncates A)
- c. Fault-stratigraphy relationships i. Adjacency matrices of relative ages of faults longer than a specified length and formations and groups based on truncation relationships
- 2) Position Data a. DTM i. DTM downloaded for defined bounding box from SRTM server ii. Re-projected to local EPSG-defined projection system
- b. Basal contacts i. Formation based on stratigraphic relationship (assigned to younger formation) ii. X,Y from contact nodes with optional decimation iii. Z from DTM iv. Nodes that are defined by faults are removed
- c. Igneous contacts i. Formation based on intrusive unit ii. X,Y from contact nodes with optional decimation iii. Z from DTM iv. Nodes that are defined by faults are removed
- d. Faults i. Fault name based on id of fault ii. Optional removal of faults below a certain fault-tip to fault-tip distance iii. X,Y from fault nodes with optional decimation iv. Z from DTM
- e. Fold axial traces i. Fold axial trace name based on id of fold axial trace ii. X,Y from fold axial trace nodes with optional decimation iii. Z from DTM
- f. Local formation thickness i. X,Y from basal contact nodes ii. Z from DTM iii. Thickness from distance from normal to local contact orientation to stratigraphically next upper contact polyline in the taking into account the local orientation of bedding estimated from the interpolation of basal contacts and primary orientation data iv. Normalised formation thickness calculated for each node based on division by median of thicknesses for each formation

- g. Local fault displacement i. X,Y from fault contact nodes ii. Z from DTM iii. Displacement calculated by finding distance between equivalent stratigraphic contacts either side of the fault
 - 3. Gradient data
- a. Primary dip/dip direction i. Orientations of bedding, but filter out dip = 0 ii. X,Y from primary data with optional decimation iii. Add Z from DTM iv. Add geology polygon formation info
 - b. Fault orientations
 - i. Normal to fault tips for azimuth
 - ii. X,Y from midpoint between fault tips
 - iii. Dip as user-defined conceptual constraint
- c. Near-Fold Axial Trace orientations i. X,Y step out normal to fat from local nodes of fold axial trace polyline with optional decimation ii. Add Z from DTM iii. Dip direction from local normal to fat and sign of fold axis iv. Dip arbitrarily set by user
- d. Near-fault orientations i. X,Y step out normal to fault from local nodes of fault polyline with optional decimation ii. Add Z from DTM iii. Dip and dip direction from interpolation of basal contacts and primary orientation data iv. Add geology polygon formation info
 - e. Empty series orientations
- f. Igneous contacts i. X,Y from local nodes of igneous contact polyline with optional decimation ii. Add Z from DTM iii. Dip and polarity arbitrarily defined by user iv. Dip direction from local normal to igneous contact interpolation of basal contacts v. Add geology polygon formation info

Inputs Minimum map2loop inputs:

- 1. EPSG coordinate reference system for input data (metre-based projection like UTM)
- 2. Max/min coordinates of area of interest
- 3. Geology polygons: -a. All polygons are watertight -b. Polygons stop on faults -c. Polygons have as attributes: -i. Object ID -ii. Stratigraphic code -iii. Stratigraphic group -iv. One of more fields that describe if sill, if igneous, if volcanic -v. Min_age field -vi. Max_age field (can be same as Min_age field, and can be simple numerical ordering (bigger number is older))
- 4. Fault/Fold Axial Trace Polylines: -a. Faults terminate on other faults but do not cross -b. Faults/Folds have as attributes: -i. Object ID -ii. Field that determines if polyline is fault or fold axial trace -iii. Field that determine type of fold axial trace e.g. syncline or anticline) -iv. Faults can have dip/dip direction info
- 5. Bedding orientations: -a. Assumes dip/dip direction or dip/strike data -b. Orientations have as attributes: -i. Dip -ii. Dip Direction or strike

Using map2loop with your own or standard datasets

In order to deconstruct a map with map2loop, we need to undertake the following steps:

- 1. Ensure that we have sufficient correctly formatted data, with sufficient information to allow the calculations to work.
- 2. Once we have these data, we then need to define a set of parameters that inform map2loop about this data, and the details of the calculations to undertaken. Use the notebook Utility 1 Config file generator.ipynb to make this slightly less painful.
- 3. Finally, once we have the data and *map2loop* control parameters sorted, we are ready to create a small python script to test the system.

1) Minimum *map2loop* data requirements:

1.1 Vector Geospatial File Data Formats:

'DXF': 'raw', 'CSV': 'raw', 'OpenFileGDB': 'r', 'ESRIJSON': 'r', 'ESRI Shapefile': 'raw', 'GeoJSON': 'rw', 'GeoJSONSeq': 'rw', 'GPKG': 'rw', 'GML': 'raw', 'MapInfo File': 'raw'

r=read, a=append, w=write

- geology polygons with stratigraphic code and rock type info (required)
- fault polylines (required)
- bed dips as points in dip, dip direction (required)
- mineral deposit layer (optional)
- fold axial trace layer (optional)

1.2 Geology Polygons (or Multipolygons):

- no gaps or overlaps between polygons, nodes from neighbouring polygons coincide (we have code to fix errors when the mismatch is smaller than the minimum node spacing).
- Stratigraphic Coherency: Ideally the map should consist of polygons which all have the same stratigraphic heirarchical level, e.g. all formations, all groups, all members etc. This is often not the case, and it makes unravelling the stratigraphy more complex, as the parent and child may appear in the same map, so the age sorting needed to build the model becomes ambiguous. National or state-level stratigraphies, and even stratigraphies described on map sheet legends are by definition simplifications of the the local system extracted by *map2loop*. *map2loop* uses the local stratigraphy first and then uses the regional stratigraphy (if available) as a guide to reduce the uncertainty.
- Attributes with (data type) and {code} (see section 2.2):
 - Fine Scale Stratigraphic coding, e.g. formation name (str) {'c'}
 - Coarser Scale stratigraphic coding, such as its parent, e.g. group (str) {'g'}
 - Alternate Coarser Scale stratigraphic coding, e.g. group (str) {'g2'}
 - Relative or absolute maximum age of Fine Scale Stratigraphic Code (float) {'max'}
 - Relative or absolute minimum age of Fine Scale Stratigraphic Code (float) {'min'}
 - Litho code to help determine if rock is intrusive (str) {'ds'}
 - Litho Code to help determine if this is a sill-like body (str) {'sill'}
 - Unique ID of polygon (str) {'o'}

1.3 Fault Polylines:

- single polyline per fault (no multipolylines)
- nodes on faulted boundaries coincident with geology polygon nodes
- Attributes:
 - Text that identifies polyline as a fault (str) {'fault'}
 - Dip of fault (str or float) {'fdip'}
 - Dip Direction of Fault (str or float) {'fdipdir'}

1.4 Bedding Points:

• single points (no multipoints)

Attributes:

- Dip (float) {'d'}
- Dip Direction or Strike (float) {'dd'}
- Code to show what convention is used: Strike RHR, or DD at the moment (str) {'otype'}
- Code to show what type of foliation: Bedding, S1 etc. (str) {'sf'}
- Code to say this unit is overturned (str) {'bo'}

1.5 Mineral Deposits: (Optional)

• single points (no multipoints)

Attributes:

- Site Code (str) {'msc'}
- Name of deposit (str) {'msn'}
- Type of feature: open pit, occurence, abandoned etc., (str) {'mst'}
- Code to show what main commodity: Fe, Iron, etc. (str) {'mtc'}
- Code to show what main commodity class: Industrial, Metal, etc. (str) {'mcom'}

1.6 Fold Axial Trace Polylines: (Optional)

• single polyline per trace (no multipolylines)

Attributes:

- Text that identifies polyline as a fold axial trace (str) {'feature'}
- Code that defines fold as syncline (str) {'syn'}

2) Defining *map2loop* parameters:

There are four types of parameters we need to define in order to use map2loop:

- a) The paths or URLs that tell *map2loop* where the information layers (GIS files or online sources) are stored. These are passed to the *map2loop* update config() method.
- b) The names of fields and some text flags that tell *map2loop* where specific information can be retrieved from these layers. These are stored in an hison format text file the path of which is passed to the *map2loop* Project() method.
- c) A data output path, bounding box and Coordinate Reference System information to define the extent of the model and where to put it. This is passed to the *map2loop* update_config() method
- d) Parameters that control the specific functioning of *map2loop*: what to calculate, what decimation factors to apply to the augmented data outputs, what resolution interpolations to use etc. These is passed to the map2looop project.run() method.

2.1 paths

These is passed to the map2loop Project() method.

Examples:

Remote WFS layers: See Example 1 Notebook

proj=Project(geology_file = 'http://geo.loop-gis.org/geoserver/loop/wfs?service=WFS&version=1.0.0&request=GetFeature&typeName=loop:geol_500k&bbox={}&srs=EPSG:28350', fault_file='http://etc.',

```
structure_file='http:// etc.',
mindep_file='http:// etc.,
metadata="http://anyurl.org/mydata.hjson',
remote=True)
```

where remote=True signifies that WFS-served data will be accessed.

Standard Australia State Geological Surveys datasets, we have predefined the paths for all data and the following code is sufficient: See Example 2 Notebook

Local GIS layers: see Example 3 notebook

where remote=False signifies that local GIS files will be accessed. Paths can be relative or absolute, or even a URL, however for URLs, the components of the shapefile or TAB file have to be zipped up.

2.2 Layer field codes:

You will need to create or modify an *hjson* format file that provides the names of fields and some text flags that tell *map2loop* where and what specific information can be retrieved from these layers. These are stored in an hjson format text file the path of which is passed to the *map2loop* Project() method. The easiest way to get started is to use a jupyter notebook allows you to reduce errors by providing a primitive GUI for creating an *hjson* config file and associated python script, named: **Utility 1 - Config file generator.ipynb**. Alternatively if you are brave you can edit the values to the right of the colon in each row of an existing *hjson* file. For example to specify that the field in the geospatial layer that contains bedding dip information is called **MYDIP**, replace the appropriate code in the *hjson* file below with:

```
"d":"MYDIP",
```

Some verification is carried out by *map2loop* to ensure the required parameters have been defined. In the following section *field* refers to a field name in a geospatial layer; *text* refers to some text in the contents of a field for a specific geometric object. You shouldn't use the same field for different codes as this may cause problems.

```
{
    # Orientations------
    "d": "DIP", # field that contains dip information
    "dd": "DIP", # field that contains dip direction information
    "sf": "PERTURE", # field that contains information on type of structure
    # text to search for in field defined by sf code to show that this is a bedding measurement
    "bedding": "Bed",
    # flag to determine measurement convention (currently "strike" or "dip direction")

"otype": "dip direction",
    "bo": "TYPE", # field that contains type of foliation
    # text to search for in field defined by bo code to show that this is an overturned bedding measurement
```

```
**Bistatigraphy...

*Bistatigraphy...

*Bistatigraphy...

*Bistatigraphy...

*Bistatigraphy...

*Bistatigraphy...

*Bistatigraphy...

*Bistatigraphy...

*Bistatigraphy...

*C: "UNITAME", # field that contains coarser stratigraphic coding if "g" is blank "g2": "SUBERSUITE", color with a stratigraphic coding if "g" is blank "g2": "SUBERSUITE", color with a stratigraphic coding (not used?)

*Bistatigraphy...

*B
```

2.3 ROI, Projection, output paths

A data output path which points to a new or existing directory (a new directory will be created if needed), bounding box and Coordinate Reference System information to define the extent of the model. This is be passed to the *map2loop* update_config() method

- where bbox coordinates are in CRS defined by proj_crs
- where overwite can be 'overwrite', 'true'

• where quiet controls whether we allow or block print statements and matplotlib figures. Use 'none' to quiet nothing, 'all' to quiet everything, 'no-figures' to disable plots and allow text output. Defaults to 'none'

2.4 Full list of update_config flags:

Project flags:

- out dir Path to write output files to. :type out dir: string
- **overwrite** Allow overwriting the given out_dir if it exists, false, true or in-place, defaults to false :type overwrite: string, optional
- **bbox_3d** 3D bounding box of coordinates and base/top values defining the area, defaults to { "minx": 0, "maxx": 0, "maxx": 0, "base": -10000, "top": 1200, } :type bbox_3d: dict, optional
- dtm_crs Set the projection of the dtm, defaults to {'init': 'EPSG:4326'} :type dtm_crs: dict, optional
- proj_crs Set the projection of the input data, defaults to None :type proj_crs: dict, optional
- **step_out** How far to consider outside the re-projected dtm, defaults to None :type step_out: int, optional
- quiet Allow or block print statements and matplotlib figures, 'None' to quiet nothing, 'all' to quiet everything, 'no-figures' to disable plots and allow text output. Defaults to 'None' :type quiet: string, optional
- clut_path Path to custom map colours file :type clut_path: string, optional
- model_engine Which modelling engine to use and set associated flags for, defaults to loopstructural:type model_engine: string, optional
- run_flags Global dictionary that defines custom params such as decimation and minimum fault length, see Section 2.4 :type run_flags: dict, optional
- **kwargs

2.5 Calculation control parameters

These control the specific functionality of *map2loop*: what to calculate, what decimation factors to apply to the augmented data outputs, what resolution interpolations to use etc. These are passed to the *map2looop* project run() method:

proj.run()

This method performs the data processing steps of the *map2loop* workflow, and can be modified by including the following parameters [defaults](data type):

- aus: Indicates if area is in Australia for using ASUD, the Australian Stratigraphic Units Database to redfine stratigraphic relationships. Should only be True in Australia, and when the finest stratigraphic level is the ASUD standard Formation name. [True] (bool)
- close_dip: Dip to assign to all new fold axial trace orientations. If -999 then the nearest interpolated dip for that supergroup will be used instead. [-999] In degrees (int)
- contact decimate: Save every nth contact data point. 0 means save all data. [5] (int)
- **contact_dip**: Dip to assign to all new basal contact orientations. If -999 then the nearest interpolated dip for that supergroup will be used instead. [-999] In degrees (int)

- contact_orientation_decimate: Save every nth contact orientation point. 0 means save all data. [5] (int)
- **deposits**: Mineral deposit names for focused topology extraction. ["Fe,Cu,Au,NONE"] Topological analysis of faults and strat will only be carried out relative to these deposit type. NONE must always be one of the types (str)
- **dist_buffer**: Buffer for processing basal contacts. Basal contact vertices less than this distance from the fault will be ignored. [10] In metres. (int)
- dtb: Path to depth to basement grid. Geotif of depths in the same projection system as everything else. ["] (str)
- fat_step: How much to step out normal to the fold axial trace. Distance in metres. [750] In metres. (int)
- fault decimate: Save every nth fault data point along fault tace. 0 means save all data. [5] (int)
- fault_dip: default fault dip [90] In degrees (int)
- fold_decimate: Save every nth fold axial trace data point. 0 means save all data. [5] (int)
- interpolation_scheme: What interpolation method to use of scipy_rbf (radial basis) or scipy_idw (inverse distance weighted). ['scipy_rbf'] (str)
- interpolation_spacing: Interpolation grid spacing in meters. Used to interpolation bedding orientations [500] In metres. (int)
- intrusion_mode: 1 to exclude all intrusions from basal contacts, [0] to only exclude sills. [0] (int)
- max_thickness_allowed: when estimating local formation thickness [10000] in metres. (int)
- min_fault_length: Min fault length to be considered. In metres. [5000] In meters. (int)
- misorientation: [30] Maximum misorientation in pole to great circle of bedding between groups to be considered part of same supergroup (int)
- null scheme: How null values present in the depth to basement geotif. ['null'] (str)
- orientation_decimate: Save every nth orientation data point. 0 means save all data. [0] type int
- pluton_dip: default pluton contact dip [45] In degrees (int)
- pluton_form: Possible forms from domes, saucers or pendant. ['domes'] (str)
- thickness_buffer: How far away to look for next highest unit when calculating formation thickness [5000] In metres. (int)
- use_fat: Use fold axial trace info to add near-axis bedding info [True] (bool)
- use_interpolations: Use all interpolated dips for modelling [True] (bool)

2.6 Calculation workflow parameters

- **seismic_section**: Add data from a single seismic section (paths hardwired for the moment) [False] (bool)
- **cover_map**: Add data from a depth to basement grid (paths hardwired for the moment) [False] (bool)
- near fault interpolations: Add stratigraphic info near faults [False] (bool)
- fold_axial_traces: Add dip info either side of fold axial trace to enhance second order folds [False] (bool)
- stereonets: Calculate stereonets to define supergroups [True] (bool)

- formation_thickness: Calculate formation thickness [True] (bool)
- polarity: Calculate bedding polarity (doesn't work!!) [False] (bool)
- strat_offset: Calculate stratigraphic offset across faults [True] (bool)
- contact_dips: Add fixed or interpolated dips to contacts [True] (bool)

Individual workflow parameters can be overwritten AFTER the call to proj.update_config() as follows:

```
proj.workflow['contact_dips'] = False
```

3) Example minimum code:

An example minimum code to run *map2loop* with mostly default settings might look like this (and see the notebook **Example 3 - Local Source Data.ipynb**):

```
from map2loop.project import Project
proj=Project(geology_file="source/geology_polygons.shp",
            fault_file="source/fault_polylines.shp",
            fold_file="source/fold_polylines.shp",
            structure_file="source/bedding_points.shp",
            mindep_file="source/mindep_points.shp",
            metadata="source/meta.hjson"
            dtm_file="./source_data/terr50_gagg_gb_all.tif",
proj.update_config(
                    out_dir='./model-test',
                    bbox_3d={
                         "minx": mbbox.total_bounds[0], #500000,
                         "miny": mbbox.total_bounds[1], #7490000,
                         "maxx": mbbox.total_bounds[2], #545000,
                        "maxy": mbbox.total_bounds[3], #7520000,
                        "base": -4800,
                        "top": 1200,
                        "local': True
                    proj_crs={'init': 'EPSG:28350'}
proj.run()
```