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a convex combination
Convex set: x,y \in C, \theta \in [0,1] \rightarrow \theta x + (1-\theta)y \in C
               It AI, Az... Ai are convex sets. UAi is a convex set
Affline space: S = \{ \pi \mid A \times = b \} is convex polyhedra: \{ \pi \mid A \pi \leq b \}
Convex hull: the smallest convex set containing 5
                conuS = { \( \frac{1}{2} \text{Oixi} : m \in \mathbb{N} \), \( \chi \in \in \mathbb{N} \), \( \chi \in \in \mathbb{N} \)
Attinely independent for xo, x, ... xm. it x, -xo ... xm-xo are linearly independent
Simplex conv \{\pi_0, \pi_1 \dots \pi_n\} = \{0 \circ \chi_0 + 0 | \chi_1 + \dots + 0 m \chi_m\} probability simplex: \Delta_n = \{0 | 0 \geq 0, | ^70 = 1\}
                                                                unit simplex : on' = { 0' | 0'>0, 170' 5 |}
dist(x,c) = inf ||x-z|| theorem: if C nonempty, closed and convex, I unique & dist(x,c) = 1/x- 2/1
                                                          here \hat{\alpha} = P_{c}(\alpha)
projection onto a convex set à : unique
any z in C: <x-2, 2-2> =0 | | Pc(x)-Pc(y) | = | |x-y|
for xoEC : exists a w, sup < w, x> < < w, xo>
boundary of a set C is dc = = \int C
Supporting hyperplane theorem: xoetC, Jw, <w, x> < < w, xo>, bx & C
if C is convex: intC=intc and JC=Jc
Separating hyperplane theorem : Iw: w1x, 5b, w1x, 2b
 if CINC2=$, C=C1-C2 is convex and of € C
Convex tunction: f(0x+ōy) < of(x) + ōf(y) strict convex: < -> <
-f is (strictly) concave
affine function f(x) = wTx+b convex and concave (not strict)
f is convex iff tredomf and any direction d
 extanded-value Extension: f= f(x), xes
                  effective domain don f = domf = S = [x: f(x) < x)}
First-order condition for convexity: 1(y) > f(x) + \forall f(x) \forall (y - x)
                      for univariate convex function: f'is increasing, t'(x) > 0 (semidefinite)
Tt(x) = 0 for a convex function f, x* is a global minimum
                                                                                 for strict condition,
                                                                                 not necessary
 Negative entropy f'(x) = \log x + 1, f'(x) = x^{-1} > 0
Quadratic functions t(x) = x' dx + b7x +c
Least squares loss f(x) = 1/4x - y11,
Log-sum-exp function f(x) = log (\(\tilde{\x}\)exi)
d-sublevel set: Cd = {x ∈ domf: f(x) ≤d} if f is convex. Ca is convex
epigraph: epif=\{(x,y):x\in S,y,f(x)\} and hypograph the opposite
f is convex iff epit is convex
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y = f(x_0) + \nabla f(x_0)'(x - x_0) is a hyperplane of epit
  Jensen's inequality f(\frac{2}{1-1}o_i \times i) \leq \frac{n}{2}o_i f(x_i) e.g. \frac{n}{2} \cdot \frac{1}{n} \cdot x_i \leq \sqrt{\frac{n}{n}} \cdot \frac{n}{2} \cdot x_i^2
   Hölder's inequality: conjugate exponents p and q s.t. p^{-1} + q^{-1} = 1
                                      Minkowski's inequality: 11 x+y 1/p = 11 x 1/p + 1/y 1/p
  Nonnegative combination: t(x) = \( \subseteq \cific(x) \) is whex = fi are convex
Affine composition f(x) = g(Ax+b) is convex \in g is convex e.g. f(x) = \log \left( \sum_{i=1}^{n} e^{mi^{T}x + bi} \right)

Scalar composition f(x) = h(g(x)) from f(x) = h(g(x)) fro
Vector composition xx, y (component wise) h(xx > (5) h(y), h is increasing (decreasing)
Pointwise maximum 1 are convex and f(x) = \max f(x) is convex Hinge function (x)^{+} = \max \{x, 0\}
                                                                                      f(x) = \sup \{f(x) \mid s \mid convex \neq (\lambda) = \sup \{f(x) + \lambda^T g(x)\}
Partial minimization: g(x) convex and $\notin C is convex: \frac{1}{\times} = \inf g(x,y) is convex
Convex optimization min f(x) s.t. cond1, cond2... feasible set X Optimal value f^* = \inf_{x \in X} f(x) can take 1-\infty unbounded low
Optimal point f^* = f(x^*) not always attainable Local optimal: only on ||x-x^*|| \in S

\varepsilon - \sup_{x \in S} f(x) = f(x^*) not always attainable Local optimal: only on ||x-x^*|| \in S

\varepsilon - \sup_{x \in S} f(x) = f(x) = f(x)

the cond of a convex optimization: g(x) \leq g(x) \leq g(x) = g(x)
                        the set of solution X opt is concex
tirst-order optimality condition \nabla f(x^*)^7(x-x^*) > 0
 linear program is: min c/x s.t. Bx sd, Ax=b
                                                                                          A \times = b, \times > 0 (standard)
                                                    Ax = b cinequality)
quadratic program: min \( \frac{1}{2} \times \text{V} \times + C^{\tau} \times \text{st. } \( \text{B} \times \) \( \text{A} \times + \text{D} \)
quadratically constrained quadratic program (QCQP): min =xXTX + cTX s.t. =xTQ;X+ciTx+d; so
                                                                                                                                                                                                                 Ax = b
General unconstrained QP: minf(x) = = xTQx + bTx +C
Geometric program: minf(x) s.t. gi(x) = 1, hj(x) = 1
                                             hj are minomials: f R++ -> R fix) = Y x1, Q1 X2 ... xn Qn
                                      f, gj ave posynomials: If
Decent direction dk: gct) = f(xk+tdk) < f(xk) = g(0)
                                          dk -> g'(0) = dk \ \ \ f(xk) ≤ 0
                                          9'(0) = dk \ \ \ f(xk) < 0 -> dk
Lipschitz continuity · | | f(x) - f(y) | | < L | | x - y | |
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L-smooth: || of(x) - of(y) || E L ||x-y||, Ux.y
           Lmax( v²fix)) ≤L 121 ≤L for all eigenvalues 2 of v²fix)
Quadratic upper bound: f(y) < f(x) + \f(x) (y-x) + \frac{1}{2} ||y-x||^2
Consequence of quaratic upper bound f(x_{k+1}) \le f(x_k) - t(1-\frac{Lt}{2}) || \nabla f(x_k) ||^2 for 0 < t \le \frac{1}{L}:
Convergence analysis f(x_k) - f(x^*) \leq \frac{\|x_0 - x^*\|^2}{2 \operatorname{tk}}
                                                                           f(xk)-f(xk+1) > = 1/7f(xk) //2
Strong convexity: f(x)=f(x)-f(x)-m/1x/12 is convex
                m/2 11 x - y 11 = f(y) - f(x) + of(x) (y-x) = m/2 11 x - y 11
          f(x) - f(x*) = = 1 (10f(x))
          f(xx)-+(x*) = (1-m+)k11x.-x*112
         11 xk-x*112 = (1-mt) K1/x.-x*1/2
Condition number KCD) = Imax(Q) well-conditioned if small ill-condition it large
Exact line search
Backtracking line search
Newton
Stop here. Mid term.
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