

## \* Corrections

A5) Applying Laplace transform to linearised system

$$\textcircled{1} \quad s \bar{Z}_1 = \bar{Z}_2$$

$$\textcircled{2} \quad s \bar{Z}_2 = a_1 \bar{Z}_3 + a_2 \bar{Z}_1 - a_3 \bar{Z}_2$$

$$\textcircled{3} \quad s \bar{Z}_3 = a_4 \bar{V} - a_4 R \bar{Z}_3$$

$$\textcircled{1} \text{ into } \textcircled{2} \quad s(s \bar{Z}_1) = a_1 \bar{Z}_3 + a_2 \bar{Z}_1 - a_3(s \bar{Z}_1)$$

$$s^2 \bar{Z}_1 + s a_3 \bar{Z}_1 - a_2 \bar{Z}_1 = a_1 \bar{Z}_3$$

$$\bar{Z}_3 = \frac{Z_1 (s^2 + a_3 s - a_2)}{a_1} \quad \textcircled{4}$$

$$s \bar{Z}_3 + a_4 R \bar{Z}_3 = a_4 \bar{V}$$

$$\bar{Z}_3 (s + a_4 R) = a_4 \bar{V}$$

Inserting  $\textcircled{4}$

$$\frac{\bar{Z}_1 (s^2 + a_3 s - a_2) (s + a_4 R)}{a_1} = a_4 \bar{V}$$

$$\therefore \frac{\bar{Z}_1}{\bar{V}} = \frac{a_1 a_4}{(s + a_4 R)(s^2 + a_3 s - a_2)} = G_x$$

... decomposed Functions.

$$G_x = \frac{a_1 a_4}{(s + a_4 R)(s^2 + a_3 s - a_2)} = a_1 a_4 \cdot \left( \frac{1}{(s + a_4 R)} \right) \left( \frac{1}{s^2 + a_3 s - a_2} \right)$$

Mapping the Second-order TF component to its co-efficients  
Resolving to general form.

$$\frac{1}{a_2 (s^2 + \frac{a_3}{a_2} s + \frac{1}{a_2})} \quad \frac{1}{a_2 (s^2 + \frac{a_3}{a_2} s + \frac{1}{a_2})}$$

$$\tau^2 = 1$$

$$\tau = 1$$

$$2J\tau = a_3$$

$$2J = a_3$$

$$J = \frac{5b}{7m} \times \frac{1}{2}$$

$$= \frac{5b}{14m}$$

~~Present oscillations providing that~~

The system would present oscillations from an impulse response providing that

$$0 < \frac{5b}{14m} < 1$$