

Contents

Ample Manual	1
Usage	1
Ample-System Format	1
Explicit	2
Functional	2
Prior Modules	3
Module Format	3
Included Modules	4
Table of Options & Default Values	5
Option Descriptions	6

Ample Manual

Usage

`ample` can be called from Matlab using the following command.

```
[a,c] = ample(A,y,priorHandle,<options>);
```

- `y` is the set of observations.
- `A` is the system used to obtain `y` from the unknown signal. This system must be in the **ample-system** format, which will be described below.
- `priorHandle` is a function handle which takes two inputs, the hidden variables $\{R, \Sigma\}$.
- `<options>` is a Matlab-style list of varargin options in the pairs of 'opt_name',opt_value.

The `demos` directory contains a number of useful examples for different signal priors and `ample` option modes. The best place to start is with `demos/ample_gb_demo.m`.

Ample-System Format

In order to find the factorized probabilities, `ample` needs to know the system which generated the observations, `y`. This information is given by the variable `A` in the description in the previous section. `ample` will operate on two different methods of specifying `A`:

Explicit

In this mode, **A** is assumed to be a linear system which is defined by an **MxN** matrix where **y** is of dimensionality **M** and the observed signals are of dimensionality **x**. I.e. a set of observations of a given signal is given by $y = Ax$.

Functional

This is a more general mode for defining the observational model of **A**. Here, both linear and non-linear observations can be constructed. Instead of an explicit matrix defining a linear system, in functional mode, the variable **A** is given as a structure with four fields, each of which is a function handle of a single vector input to produce each of the following four operations...

- **A.forward**: Computes the forward (signal->observation) mapping.
- **A.adjoint**: Computes the adjoint (observation->kernel-space) mapping.
- **A.squared_forward**: The squared operation is particular to the AMP algorithm. For a linear system, the squared forward mapping is equivalent to

$$(A \circ A) x,$$

where \circ is the element-wise, or Hadamard, product.

- **A.squared_adjoint**: The squared adjoint is similar to the above, but for the adjoint operation. For a linear system, this would be equivalent to

$$(A \circ A)^T y.$$

Here is an example of a random linear system using this format.

```
N      = 128;                               % Signal dimensionality
M      = 64;                                 % Number of observations
x      = randn(N,1);                         % Random signal
Phi     = randn(M,N) ./ sqrt(N);             % Random system
PhiT    = Phi';                             % Defining the adjoint
Phi2    = Phi.*Phi;                         % Defining the squared forward
Phi2T   = Phi2';                           % Defining the squared adjoint

A.forward      = @(x_) Phi  *x_;
A.adjoint      = @(y_) PhiT *y_;
A.squared_forward = @(x_) Phi2 *x_;
A.squared_adjoint = @(y_) Phi2T*y_;

y = A.forward(x);
z = A.adjoint(y);
```

Prior Modules

One of the nice aspects of the AMP framework is its applicability to a wide range of possible signal priors. With the right approach, even non-iid (i.e. structured) signal priors can even be used to great effect with AMP. The `ample` package provides this same versatility to the user by modularizing prior-specific calculations. The prior modules follow a standard format.

Module Format

The prior modules must follow the same general format.

```
function [a,c,learned_params] = prior_module(r,s,params)
    % Must return new learned prior parameters if requested
    learn_prior = 0;
    if nargin > 2
        learn_prior = 1;
    end

    % 1. Calculate factorized means of variational distribution, `a`.
    % 2. Calculate factorized means of variational distribution, `c`.
    if learn_prior
        % 3. If new learned parameters are requested, update accordingly
    end
```

Here, the values `r` and `s` are the AMP hidden variables for the means and variances associated with the variational Gaussian. The structure of the `params` variable is entirely up to the module writer, `ample` will support both vector-valued and cell-valued `params`.

Important Note: If `params` is specified as a cell variable, then `params{1}` *must* contain the vector of learned variables !

The module writer must be familiar with the calculation of the means and variances of the variational form of their desired prior distribution,

$$a_i = \langle x_i \rangle = \frac{1}{Z} \int dx \ x \ P_0(x; \theta) \exp \left\{ \frac{(x - R_i)^2}{2\Sigma_i^2} \right\},$$
$$c_i = \langle x_i^2 \rangle - a_i^2 = \frac{1}{Z} \int dx \ x^2 \ P_0(x; \theta) \exp \left\{ \frac{(x - R_i)^2}{2\Sigma_i^2} \right\},$$

where P_0 is the desired prior distribution and θ are the parameters associated with that distribution. This will generally also include the calculation of the

proper partition function. Depending on the prior, this calculation may be extremely non-trivial. If numerical integration is required to solve for these variables, **ample** will still support this, but at the cost computation time.

The determination of the prior parameter update may be equally non-trivial, in general.

Included Modules

For ease of use, some common prior modules are already included in the **ample** package. These serve as good examples for the expected format of the prior modules. **ample** currently provides the following signal priors:

- **Binary**

- `priors/prior_binary.m`
- Signal coefficients are discrete values are in $\{0, 1\}$ and have value 1 with probability ρ .
- `params` format:
 - * `params(1)` – ρ

- **Gauss-Bernoulli**

- `priors/prior_gb.m`
- Signal coefficients are real values given by

$$Prob[x_i = x] \propto (1 - \rho) \delta(x) + \rho \mathcal{N}(\mu, \sigma^2).$$

This distribution has been shown to be very good for modelling “sparse” signals, such as those desired for compressed sensing.

- `params` format:
 - * `params(1)` – μ
 - * `params(2)` – σ^2
 - * `params(3)` – ρ

- **L1-Sparse**

- `priors/prior_l1sparse.m`
- Signal coefficients are assumed to be sparse, or at least compressible. That is, there are assumed to be very few non-zero coefficients. Using the L1-Sparse module isn’t necessarily defining a “prior,” per-se, but it does solve the equivalent LASSO problem when using **ample** for inverse-problems such as compressed sensing,

$$a = \arg \min_x \|x\|_1 \quad \text{s.t.} \quad \|y - Ax\|_2^2 < \epsilon$$

- `params` format:

- * `params(1)` – Minimum coefficient value
- * `params(2)` – Maximum coefficient value
- **Q-ary**
 - `priors/prior_qary.m`
 - Signal coefficients are discrete values in $\{\tau_0, \tau_1, \dots, \tau_{Q-1}\}$ with probabilities defined according to the PMF
$$Prob[x = \tau_q] = \rho_q.$$
 - `params` format:
 - * `params{1}` – PMF vector, $[\rho_0, \rho_1, \dots, \rho_{Q-1}]$
 - * `params{2}` – Alphabet vector, $[\tau_0, \tau_1, \dots, \tau_{Q-1}]$

Table of Options & Default Values

Option Name	Values	Default Value
<code>convergence_tolerance</code>	Positive Small Real	<code>1e-10</code>
<code>convergence_type</code>	<code>{'residual','iteration'}</code>	<code>'iteration'</code>
<code>damp</code>	Real in $[0,1)$	<code>0.0</code>
<code>debug</code>	Boolean	<code>false</code>
<code>delta</code>	Positive Real	<code>1.0</code>
<code>image_mode</code>	Boolean	<code>false</code>
<code>init_a</code>	Vector of reals	<code>zeros(N,1)</code>
<code>init_c</code>	Vector of positive reals	<code>ones(N,1)</code>
<code>learn_delta</code>	Boolean	<code>true</code>
<code>learning_mode</code>	<code>{'track','em'}</code>	<code>'track'</code>
<code>learn_prior_params</code>	Boolean	<code>false</code>
<code>max_em_iterations</code>	Positive Integer	<code>20</code>
<code>max_iterations</code>	Positive Integer	<code>250</code>
<code>mean_approximation</code>	Boolean	<code>false</code>
<code>pause_mode</code>	Boolean	<code>false</code>
<code>prior_damp</code>	Real in $[0,1)$	<code>0.0</code>
<code>prior_params</code>	Function Handle	<i>See 'Prior-Handle Format'</i>
<code>report_history</code>	Boolean	<code>true</code>
<code>true_solution</code>	Vector of Reals	<code>[]</code>

Option Name	Values	Default Value
verbose_mode	{0,1}	1

Option Descriptions

Required

- prior_params:

General

- convergence_tolerance:
- convergence_type:
- max_iterations:
- verbose_mode:
- delta:

Debug

- true_solution:
- debug:
- pause_mode:
- image_mode:
- report_history:

Fine-Tuning

- init_a: Initial value for the factorized means. The dimensionality of init_a should be equal to that of the original signal.
- init_c: Initial value for the factorized variances. The dimensionality of init_c should be equal to that of the original signal.
- damp:
- prior_damp:

Learning Control

- learn_delta:
- learn_prior_params:
- learning_mode:
- max_em_iterations: