



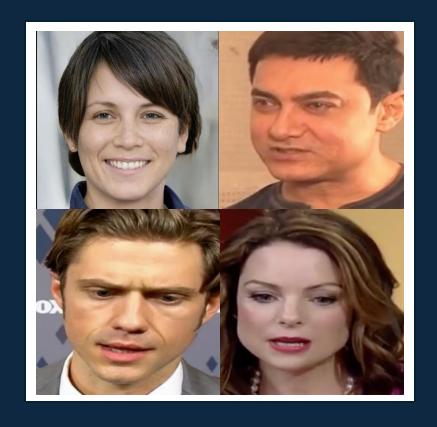
### **DEEP-FAKE DETECTOR**

by GLEM

DATA ANALYTICS AND ARTIFICIAL INTELLIGENCE [EM1405]



#### **ABOUT THE PROJECT**



The aim is to create a model that can tell whether a video is real or generated by Al.

The model is based on a cooperation of CNN and LSTM.



#### **AGENDA**

01. IMAGE CLASSIFICATION

**02. CNN** 

03. VIDEO CLASSIFICATION

04. A DIFFERENT APPROACH: PYTORCH



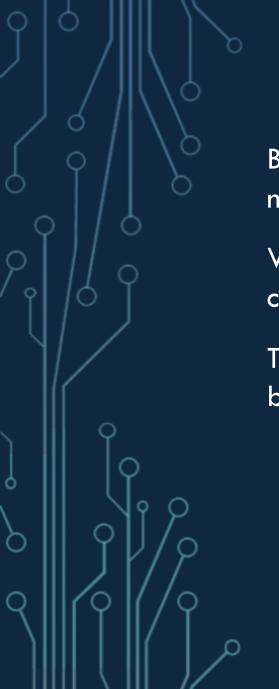
#### 01. IMAGE CLASSIFICATION



The very first dataset is an image one.

The aim is to build a CNN which can classify fake/Al generated images from real ones.

It is divided into three folders, each of them containing 50% of fake and 50% of real images of 256x256 pixels.



#### 01. IMAGE CLASSIFICATION



Before building the models, we first created objects that can be fed to the networks.

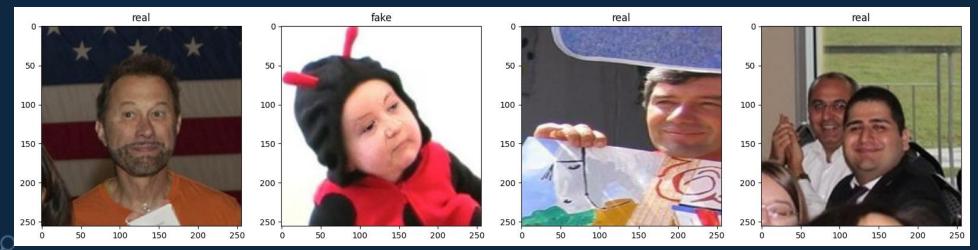
We generated iterators made up of NumPy arrays that store features and corresponding class labels of each image.

These iterators facilitate easier access to the images, allowing batch-by-batch processing.

#### 01. IMAGE CLASSIFICATION











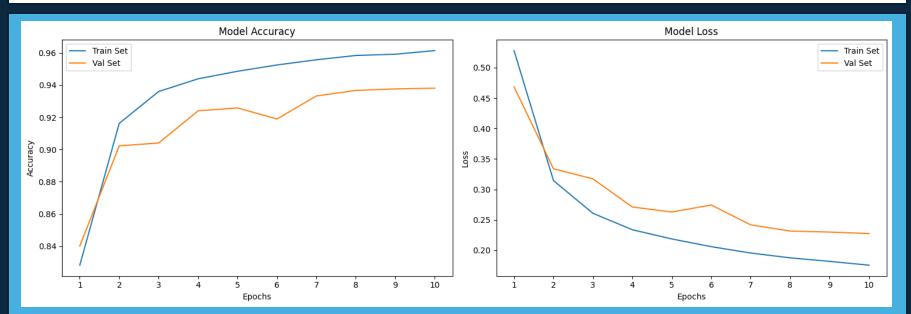
Once retrieved our dataset, we trained the very first CNN.

After some attempts, the accuracy of our model increased to the 96%, which seemed to be the best achievable by it.

On the left, a representation of our network



```
Epoch 1/10
4376/4376
                               354s 77ms/step - accuracy: 0.7584 - loss: 0.6772 - val_accuracy: 0.8197 - val_loss: 0.4993
Epoch 2/10
4376/4376
                               352s 74ms/step - accuracy: 0.9041 - loss: 0.3373 - val_accuracy: 0.8942 - val_loss: 0.3444
Epoch 3/10
                               . 383s 74ms/step – accuracy: 0.9306 – loss: 0.2711 – val_accuracy: 0.9148 – val_loss: 0.2963
4376/4376 -
Epoch 8/10
4376/4376
                               323s 74ms/step - accuracy: 0.9556 - loss: 0.1951 - val accuracy: 0.9322 - val loss: 0.2457
Epoch 9/10
4376/4376 -
                               324s 74ms/step - accuracy: 0.9571 - loss: 0.1897 - val_accuracy: 0.9317 - val_loss: 0.2464
Epoch 10/10
                               401s 78ms/step - accuracy: 0.9590 - loss: 0.1836 - val_accuracy: 0.9319 - val_loss: 0.2447
4376/4376 -
```





**341/341 ----- 4s** 11ms/step - accuracy: 0.9119 - loss: 0.2106

Test Loss: 0.3689965009689331 Test Accuracy: 0.8395231366157532

Even if the accuracy is quite good for a first approach, the loss value up here indicates that misclassification still occurs, as shown by the results on the right.

This also explains the values shown in the classification report and in the confusion matrix.

```
Sample Predictions and True Labels:
True Label: 1, Predicted: [1]
True Label: 1, Predicted: [0]
True Label: 1, Predicted: [0]
True Label: 0, Predicted: [0]
True Label: 1, Predicted: [0]
True Label: 0, Predicted: [1]
True Label: 0, Predicted: [1]
```

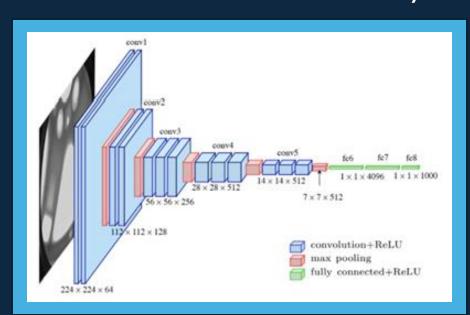
Classification Report:						
pr	ecision	recall	f1-score	support		
0	0.81	0.93	0.87	5492		
1	0.92	0.77	0.84	5413		
accuracy			0.86	10905		
macro avg	0.86	0.85	0.85	10905		
weighted avg	0.86	0.86	0.85	10905		
Confusion Matrix	(:					
[[5132 360]						
[1218 4195]]						





But it was just the beginning of our tries.

As a matter of fact, to see how far we could have gone, we decided to use our dataset to an already made model: InceptionV3.



We obtained a 99% of accuracy but encountered few problems along the way.

Training InceptionV3 is timeconsuming and demands a certain amount of computational power.

For this reason, we used ColabPro which guarantees a more powerful GPU.



Total params: 23,903,010 (91.18 MB)

Trainable params: 23,868,578 (91.05 MB)

Non-trainable params: 34,432 (134.50 KB)

InceptionV3 is a model with 23mln trainable parameters.

We encountered a significant issue: each training epoch, even with the most powerful

GPU available on ColabPro, took around 10 minutes. This resulted in over 1.5 hours for just one training session.

```
4376/4376 701s 142ms/step - accuracy: 0.9436 - loss: 0.1487 - val_accuracy: 0.9607 - val_loss: 0.1020
```

**Test evaluation**: the test accuracy is nearly 10% higher.

```
341/341 43s 79ms/step - accuracy: 0.9046 - loss: 0.4563 Test Loss: 0.4639233350753784 Test Accuracy: 0.9033470749855042
```



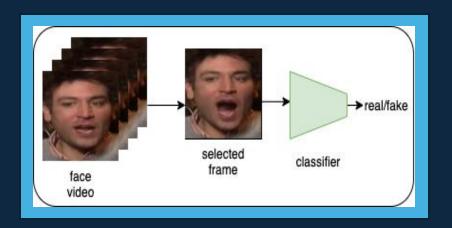


But let's cut to the chase and see which results we can achieve by classifying videos.

The dataset is divided into three folders, each of them containing 50%-50% of real-fake videos of 256x256 pixels.

Powerful machines could have worked with any dimension videos, but ours not!:)

For this reason, we downscaled them to 64x64.





Dimensionality has been a though problem.

Objects storing all the data required for training were too heavy for the RAM to handle.

Data generators extracting data "on-the-fly" is lighter on the RAM, but it's slow during runtime.

To obtain good results in a "small" amount of time, we preprocess data beforehand.

```
:lass VideoDataGenerator(Sequence):
    def __init__(self, data_dir, subset, batch_size=BATCH_SIZE):
        self.data dir = data dir
        self.subset = subset
        self.batch_size = batch_size
        self.classes = ['real', 'fake']
        self.videos = self._get_video_paths()
        self.on_epoch_end()
    def _get_video_paths(self):
        videos = []
        subset_dir = os.path.join(self.data_dir, self.subset)
        for class name in self.classes:
            class dir = os.path.join(subset dir, class name)
            for video_name in os.listdir(class_dir):
                if video name.endswith('.npy'):
                    videos.append((os.path.join(class_dir, video_name), self.classes.index(class_name)))
        return videos
    def len (self):
        return len(self.videos) // self.batch_size
    def __getitem__(self, idx):
        batch videos = self.videos[idx * self.batch size:(idx + 1) * self.batch size]
        batch frames = []
        batch labels = []
        for video_path, label in batch_videos:
            frames = np.load(video_path)
           batch_frames.append(frames)
            batch_labels.append(label)
        return np.array(batch frames), np.array(batch labels)
    def on epoch end(self):
        np.random.shuffle(self.videos)
train generator = VideoDataGenerator(PROCESSED DIR, "Train")
val_generator = VideoDataGenerator(PROCESSED_DIR, "Val")
test_generator = VideoDataGenerator(PROCESSED_DIR, "Test")
```

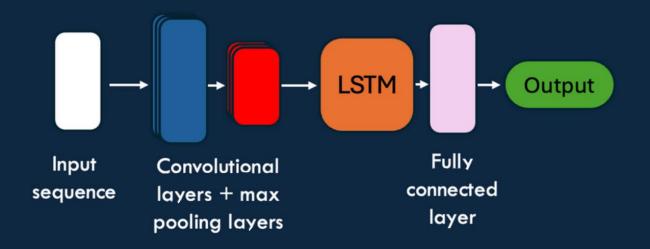




Now that videos are involved, it's time to introduce something new!

First of all, we decided to make our CNN even simpler, getting better results surprisingly!

Once ultimated our CNN, we introduced to it a TimeDistributed layer to feed all the frames from each video, followed by an LSTM approach to extract features from the whole video.

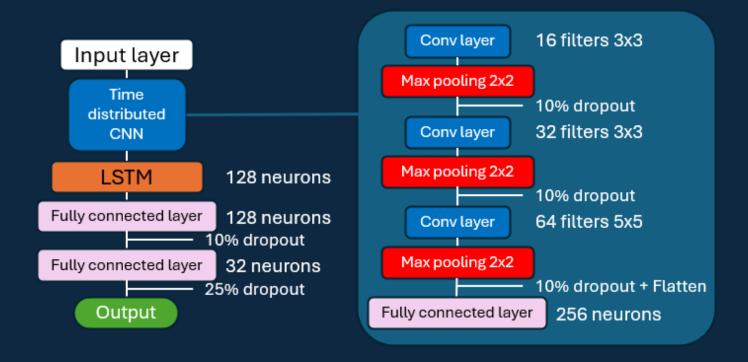






Initially we were led to overfitting due to an overly complex model. But once simplified it, the model performed well.

Here you can see a more detailed representation of the model that led us to the best results.







437/437	- 302s 652ms/step - accuracy: 0.5198 - loss: 0.7172 - val accuracy: 0.6324 - val loss: 0.6407
Epoch 2/40	3023 032113/3 tep - accuracy. 0.3130 - 1033. 0.7172 - Var_accuracy. 0.0324 - Var_1033. 0.0407
437/437	- 178s 405ms/step - accuracy: 0.6967 - loss: 0.5843 - val accuracy: 0.8659 - val loss: 0.3252
Epoch 3/40	1103 403m3/3ccp accuracy. 0.030/ 1033. 0.3043 Var_accuracy. 0.0033 Var_1033. 0.3232
437/437	- 169s 384ms/step - accuracy: 0.8778 - loss: 0.3046 - val accuracy: 0.9278 - val loss: 0.1959
Epoch 4/40	2000 30 mm2, seep deed de j. 010/70 2000 100/20 101_deed de j. 010/270 101_2000 101
•	- 172s 392ms/step - accuracy: 0.9371 - loss: 0.1756 - val accuracy: 0.9425 - val loss: 0.1718
Epoch 5/40	
437/437	- 171s 389ms/step - accuracy: 0.9563 - loss: 0.1280 - val accuracy: 0.9694 - val loss: 0.1038
Epoch 6/40	
437/437	- 170s 387ms/step - accuracy: 0.9658 - loss: 0.0992 - val_accuracy: 0.9748 - val_loss: 0.0816
Epoch 7/40	
437/437	- 168s 382ms/step - accuracy: 0.9751 - loss: 0.0770 - val_accuracy: 0.9765 - val_loss: 0.0884
Epoch 8/40	
437/437	- 1675 378ms/step - accuracy: 0.9817 - loss: 0.0660 - val_accuracy: 0.9802 - val_loss: 0.0706
Epoch 9/40	
437/437	- 170s 387ms/step - accuracy: 0.9814 - loss: 0.0654 - val_accuracy: 0.9755 - val_loss: 0.0910
Epoch 10/40	
437/437	• 174s 396ms/step - accuracy: 0.9847 - loss: 0.0550 - val_accuracy: 0.9688 - val_loss: 0.1074
Epoch 11/40	
	- 166s 376ms/step - accuracy: 0.9879 - loss: 0.0516 - val_accuracy: 0.9758 - val_loss: 0.0852
Epoch 12/40	
437/437	- 166s 378ms/step - accuracy: 0.9877 - loss: 0.0501 - val_accuracy: 0.9745 - val_loss: 0.0978
Epoch 13/40	
437/437	- 165s 375ms/step - accuracy: 0.9862 - loss: 0.0495 - val_accuracy: 0.9842 - val_loss: 0.0597
Epoch 39/40	455- 274- / 0.0074
	- <b>165s</b> 374ms/step - accuracy: 0.9974 - loss: 0.0233 - val_accuracy: 0.9899 - val_loss: 0.0539
Epoch 40/40 437/437	- 165s 376ms/step - accuracy: 0.9967 - loss: 0.0274 - val accuracy: 0.9849 - val loss: 0.0818
437/437	1035 370ms/step - accuracy: 0.9907 - 1055. 0.0274 - Val_accuracy: 0.9849 - Val_1055: 0.0818

Here, some results!

You can see how fast the model reaches the elbow — look at the fall of the loss value!

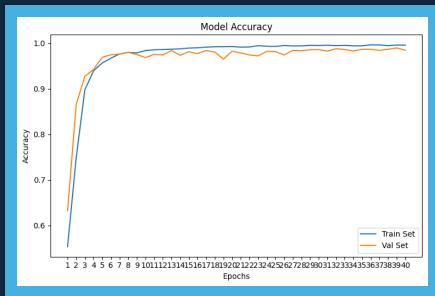
In the last epochs, the accuracy on the training set nearly reaches 100%, with the validation set accuracy showing similarly high values. This indicates a strong model performance.

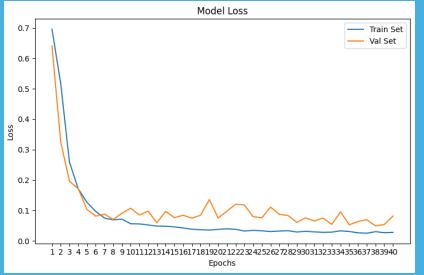
93/93 ----- 17s 186ms/step - accuracy: 0.9892 - loss: 0.0693

Test Loss: 0.08829152584075928
Test Accuracy: 0.9872311949729919

Proof of this, is the test set accuracy!

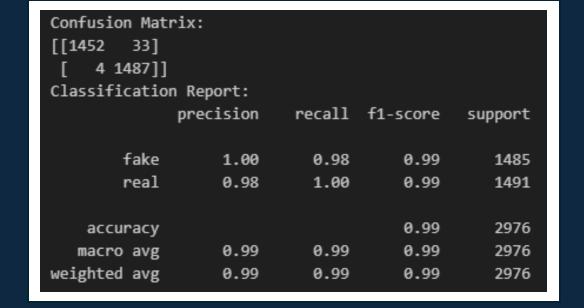






On the left, a representation of what we were saying previously.

Below, the confusion matrix and the summary table provide a more detailed breakdown of the test results.





So far, all our models were built using Tensorflow and Keras.

PyTorch is a different deep learning framework presenting few differences, primarily in its dynamic nature.

On the other hand, we get better results using the more static Tensorflow and Keras.

For the sake of knowledge, we replicated using PyTorch what already done.

Let's have a look!



PyTorch lacks a predefined TimeDistributed class.

The first challenge was to implement it ourselves.

```
# defining the time distributed class
# returns an embedding for each temporal slice of the input

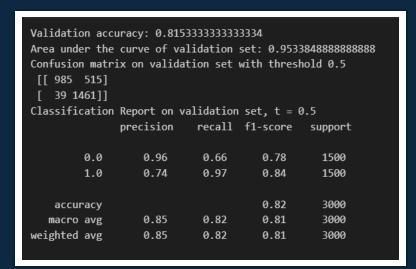
class TimeDistributed(nn.Module):
    This object takes a layer or a sequence of layers and applies it to each individual temporal slice of an input.
    It returns the embedding produced by the given layers for each temporal slice for each data point in the batch
    def __init__(self,layer):
        super(TimeDistributed,self).__init__()
        self.layer = layer

def forward(self, x):
    batch_size, t_slices , *slice_dims = x.shape
        x = x.reshape(batch_size*t_slices, *slice_dims)
        y = self.layer(x)
        output_batches, *embedding_shape = y.shape
        assert output_batches == batch_size * t_slices, f"Wrong Number of batches in the output: the layers inside TimeDistributed should output
        (batch_size * t_slices) batches, but got {output_batches} instead"
        y = y.reshape((batch_size, t_slices, *embedding_shape))
        return y
```

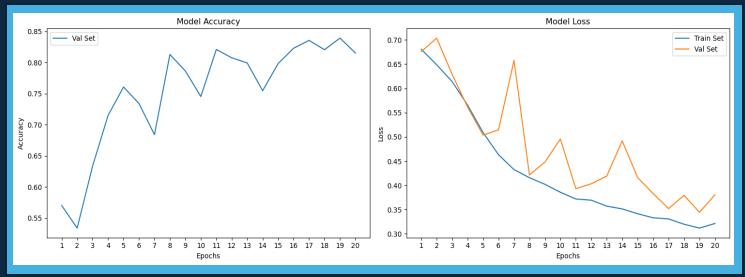
The TimeDistributed layer processes multidimensional temporal data by applying the same network in parallel to each slice of the sequence.

The output are then reshaped to preserve the original temporal data.





Firstly, we trained a CNN on the image dataset, then "froze" it and placed it into a TimeDistributed layer, feeding it into an LSTM similar to our successful TensorFlow model.



The LSTM parameters were trained using the preprocessed videos.



number of parameter: 552865 t\_dist\_cnn.layer.0.weight: torch.float32, params: 432 t\_dist\_cnn.layer.0.bias: torch.float32, params: 16 t\_dist\_cnn.layer.4.weight: torch.float32, params: 4608 t\_dist\_cnn.layer.4.bias: torch.float32, params: 32 t\_dist\_cnn.layer.8.weight: torch.float32, params: 51200 t\_dist\_cnn.layer.8.bias: torch.float32, params: 64 t\_dist\_cnn.layer.13.weight: torch.float32, params: 409600 t\_dist\_cnn.layer.13.bias: torch.float32, params: 256 rnn.weight\_ih\_l0: torch.float32, params: 65536 rnn.weight\_hh\_l0: torch.float32, params: 16384 rnn.bias ih l0: torch.float32, params: 256 rnn.bias\_hh\_l0: torch.float32, params: 256 sequence.0.weight: torch.float32, params: 4096 sequence.0.bias: torch.float32, params: 64 sequence.3.weight: torch.float32, params: 64 sequence.3.bias: torch.float32, params: 1

Though capable of detecting deepfakes, the previous method delivered results clearly inferior to our TensorFlow implementation.

We replicated our first approach: training the CNN and the LSTM together on the vide dataset.

```
Training loop: 438it [02:15, 3.24it/s]

Train Loss: 0.68595 | Progress: [438/438]

Validation Loop: 100%| 94/94 [00:27<00:00, 3.41it/s]

Validation Accuracy 56.30% | Validation Loss 0.683177 | Train Loss 0.68595

Training loop: 438it [00:57, 7.58it/s]

Train Loss: 0.02200 | Progress: [438/438]

Validation Loop: 100%| 94/94 [00:10<00:00, 8.63it/s]

Validation Accuracy 94.93% | Validation Loss 0.139116 | Train Loss 0.02200

Training loop: 438it [00:58, 7.44it/s]

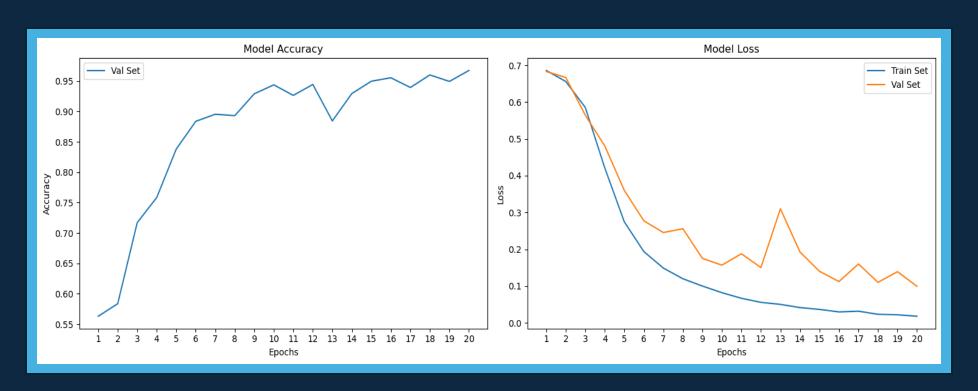
Train Loss: 0.01792 | Progress: [438/438]

Validation Loop: 100%| 94/94 [00:10<00:00, 8.89it/s]

Validation Accuracy 96.73% | Validation Loss 0.099268 | Train Loss 0.01792
```

We noticed a slight drop in accuracy compared to TensorFlow, likely due to differences in optimizer tuning.





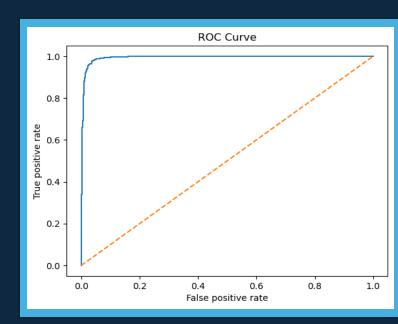
Training the CNN simultaneously with the LSTM yielded better results compared to using a pretrained CNN. However, both approaches are effective at detecting deepfake videos.



This model demonstrates nearly identical performance to the model we developed using TensorFlow.

The high AUC score highlights its strong ability to discriminate between the classes.

Validation accuracy: 0.967333333333334 Area under the curve of validation set: 0.9938391111111111 Confusion matrix on validation set with threshold 0.5 [[1422 78]						
<pre>[ 20 1480]] Classification Report on validation set, t = 0.5</pre>						
0.0 1.0	0.99 0.95	0.95 0.99	0.97 0.97	1500 1500		
accuracy macro avg weighted avg	0.97 0.97	0.97 0.97	0.97 0.97 0.97	3000 3000 3000		







#### THANK YOU FOR YOUR ATTENTION!

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