

hw5

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1 HW5 Least Squares

1.1 Q1. Spline fitting

```
[1]: using CSV;  
data = CSV.read("xy_data.csv");
```

1.1.1 a). Polynomial

$$\underset{a_1, a_2, a_3, a_4}{\text{minimize}} \quad \sum_i (x_i^3 a_1 + x_i^2 a_2 + x_i a_3 + a_4 - y_i)^2 \quad (1)$$

$$\text{subject to:} \quad a_4 = 0 \quad (\text{constraint 1}) \quad (2)$$

$$(3)$$

```
[2]: #using Pkg  
#Pkg.add("Gurobi")
```

```
[3]: #Pkg.build("Gurobi")  
using JuMP, LinearAlgebra, Ipopt;
```

```
[4]: (r,c) = size(data);  
  
highest_order = 3;  
Xc = highest_order + 1;  
X = zeros((r,Xc));  
for i = 1:Xc  
    X[:,Xc-i+1] = data[:,1].^(i-1);  
end  
  
m1 = Model(with_optimizer(Ipopt.Optimizer))  
set_silent(m1);  
a = @variable(m1, [1:Xc]);  
residual1 = @variable(m1, [1:r,1]);  
residual2 = @variable(m1, [1:r,1]);  
@constraint(m1, a[Xc] == 0);
```

```

for i = 1:r
    @constraint(m1, residual1[i] - ((X[i,:]' * a - data[i,2])).^2 == 0);

end

@objective(m1, Min, sum(residual1));
optimize!(m1);

```

```

*****
This program contains Ipopt, a library for large-scale nonlinear optimization.
Ipopt is released as open source code under the Eclipse Public License (EPL).
For more information visit http://projects.coin-or.org/Ipopt
*****

```

This is Ipopt version 3.12.10, running with linear solver mumps.
NOTE: Other linear solvers might be more efficient (see Ipopt documentation).

```

Number of nonzeros in equality constraint Jacobian...:    4176
Number of nonzeros in inequality constraint Jacobian.:      0
Number of nonzeros in Lagrangian Hessian...:    1990

```

```

Total number of variables...:    402
      variables with only lower bounds:    0
      variables with lower and upper bounds:    0
      variables with only upper bounds:    0
Total number of equality constraints...:    200
Total number of inequality constraints...:    0
      inequality constraints with only lower bounds:    0
      inequality constraints with lower and upper bounds:    0
      inequality constraints with only upper bounds:    0

```

iter	objective	inf_pr	inf_du	lg(mu)	d	lg(rg)	alpha_du	alpha_pr	ls
0	0.0000000e+00	1.00e+00	1.72e+00	-1.0	0.00e+00	-	0.00e+00	0.00e+00	0
1	-1.2881730e+02	1.79e+00	2.14e+04	-1.0	1.45e+00	0.0	1.00e+00	1.00e+00f	1
2	-3.9057527e+02	3.01e+01	8.19e+04	-1.0	4.34e+00	-0.5	1.00e+00	1.00e+00f	1
3	-9.3383951e+02	1.56e+01	1.36e+03	-1.0	1.08e+01	-1.0	1.00e+00	1.00e+00f	1
4	-5.1247151e+02	1.15e+01	1.31e+04	-1.0	1.29e+01	-1.4	1.00e+00	1.00e+00h	1
5	-2.8262756e+02	4.15e+00	1.35e+02	-1.0	3.52e+00	-1.9	1.00e+00	1.00e+00h	1
6	-3.4124977e+00	7.81e-02	6.63e+01	-1.0	4.09e+00	-2.4	1.00e+00	1.00e+00h	1
7	1.7728084e+00	6.25e-06	1.86e-01	-1.0	7.82e-02	-2.9	1.00e+00	1.00e+00h	1
8	1.7733305e+00	9.00e-10	9.01e-06	-2.5	2.62e-05	-3.3	1.00e+00	1.00e+00h	1
9	1.7733306e+00	8.64e-14	3.09e-11	-8.6	2.35e-09	-3.8	1.00e+00	1.00e+00h	1

Number of Iterations...: 9

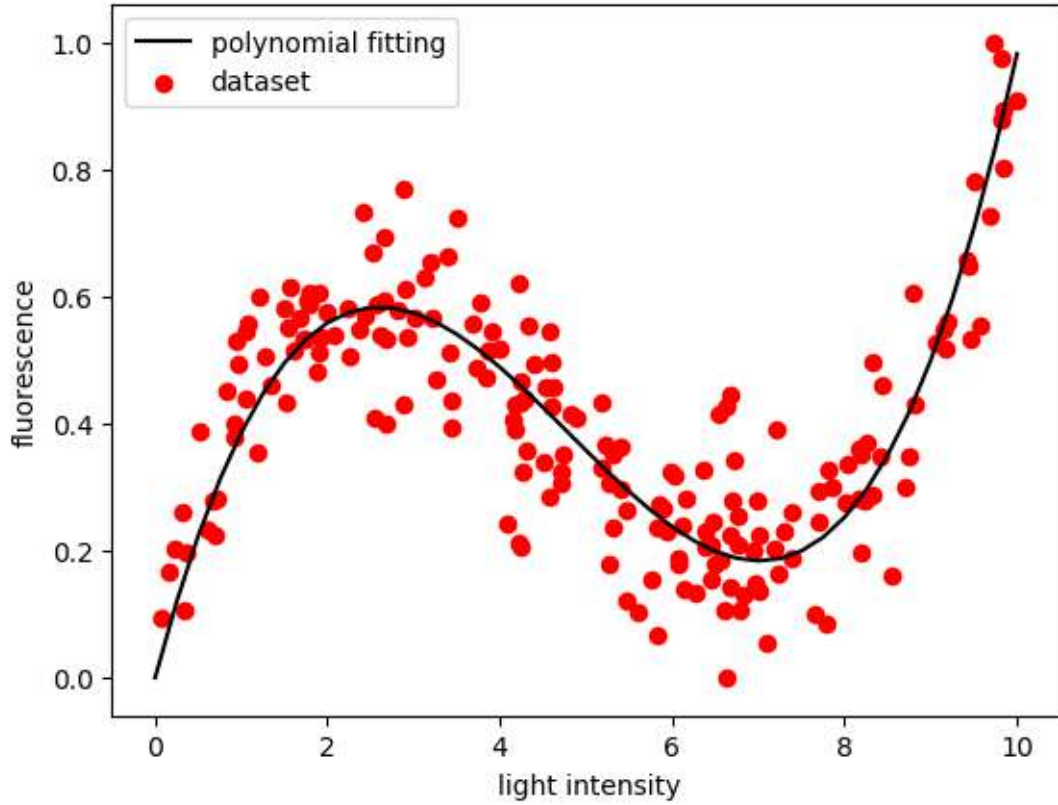
	(scaled)	(unscaled)
Objective....:	1.7733305533111241e+00	1.7733305533111241e+00
Dual infeasibility...:	3.0922819860279560e-11	3.0922819860279560e-11
Constraint violation...:	1.6618650899857812e-14	8.6375351315837179e-14
Complementarity...:	0.0000000000000000e+00	0.0000000000000000e+00
Overall NLP error...:	3.0922819860279560e-11	3.0922819860279560e-11

Number of objective function evaluations	= 10
Number of objective gradient evaluations	= 10
Number of equality constraint evaluations	= 10
Number of inequality constraint evaluations	= 0
Number of equality constraint Jacobian evaluations	= 10
Number of inequality constraint Jacobian evaluations	= 0
Number of Lagrangian Hessian evaluations	= 9
Total CPU secs in IPOPT (w/o function evaluations)	= 1.840
Total CPU secs in NLP function evaluations	= 0.530

EXIT: Optimal Solution Found.

```
[16]: println("The best fitted 'a' values are ->", round.(value.(a), digits = 6));
      ## plot
      using PyPlot;
      Xcoordinate = 0:0.25:10;
      X_plot = zeros(length(Xcoordinate), Xc);
      for i = 1:Xc
          X_plot[:, Xc - i + 1] = Xcoordinate.^(i-1);
      end
      Y_plot = X_plot * value.(a);

      figure();
      plot(Xcoordinate, Y_plot, label = "polynomial fitting", c = "k");
      scatter(data[:, 1], data[:, 2], label = "dataset", c = "r");
      xlabel("light intensity");
      ylabel("fluorescence");
      legend();
```



The best fitted 'a' values are $\rightarrow [0.009324, -0.13453, 0.5111, -0.0]$

1.1.2 b). Spline

$$\underset{p_1, p_2, p_3, q_1, q_2, q_3}{\text{minimize}} \quad \sum_{i=0 \leq x_i < 4} (x_i^2 p_1 + x_i p_2 + p_3 - y_i)^2 + \sum_{i=4 \leq x_i \leq 10} (x_i^2 q_1 + x_i q_2 + q_3 - y_i)^2 \quad (4)$$

$$\text{subject to:} \quad 16p_1 + 4p_2 + p_3 = 16q_1 + 4q_2 + q_3 \quad \begin{matrix} \text{(constraint 1)} \\ (5) \end{matrix}$$

$$\text{subject to:} \quad 8p_1 + p_2 = 8q_1 + q_2 \quad \begin{matrix} \text{(constraint 2)} \\ (6) \end{matrix}$$

$$\text{subject to:} \quad p_3 = 0 \quad \begin{matrix} \text{(constraint 3)} \\ (7) \end{matrix}$$

```
[6]: X_le4 = [];
      Y_le4 = [];
      X_ge4 = [];
      Y_ge4 = [];

      for i = 1:r
```

```

    if data[i,1] <4
        X_le4 = [X_le4; data[i,1]];
        Y_le4 = [Y_le4; data[i,2]];
    else
        X_ge4 = [X_ge4;data[i,1]];
        Y_ge4 = [Y_ge4; data[i,2]];
    end
end

```

```

[7]: K = 3;
X_quad_le4 = zeros((length(X_le4),K));
X_quad_ge4 = zeros((length(X_ge4),K));

for i = 1:K
    X_quad_le4[:,K-i+1] = X_le4.^(i-1);
    X_quad_ge4[:,K-i+1] = X_ge4.^(i-1);
end

```

```

[8]: m1b = Model(with_optimizer(Ipopt.Optimizer));
p = @variable(m1b, [1:K]);
q = @variable(m1b, [1:K]);

@constraint(m1b, 16*p[1] + 4 * p[2] + p[3] == 16*q[1] + 4 * q[2] + q[3]);
@constraint(m1b, 8*p[1] + p[2] == 8 * q[1] + q[2]);
@constraint(m1b, p[3] == 0);

@objective(m1b, Min, sum((X_quad_le4 * p - Y_le4).^2) + sum((X_quad_ge4 * q -
↪Y_ge4).^2));
optimize!(m1b)

```

This is Ipopt version 3.12.10, running with linear solver mumps.

NOTE: Other linear solvers might be more efficient (see Ipopt documentation).

Number of nonzeros in equality constraint Jacobian...	11
Number of nonzeros in inequality constraint Jacobian..	0
Number of nonzeros in Lagrangian Hessian...	12
Total number of variables...	6
variables with only lower bounds:	0
variables with lower and upper bounds:	0
variables with only upper bounds:	0
Total number of equality constraints...	3
Total number of inequality constraints...	0
inequality constraints with only lower bounds:	0
inequality constraints with lower and upper bounds:	0
inequality constraints with only upper bounds:	0

iter	objective	inf_pr	inf_du	lg(mu)	d	lg(rg)	alpha_du	alpha_pr	ls
0	3.9316735e+01	0.00e+00	5.49e+01	-1.0	0.00e+00	-	0.00e+00	0.00e+00	0
1	1.9507600e+00	4.44e-16	1.75e-13	-1.0	2.17e+00	-	1.00e+00	1.00e+00	1

Number of Iterations....: 1

	(scaled)	(unscaled)
Objective....:	4.2324566241679205e-02	1.9507600232172990e+00
Dual infeasibility....:	1.7519319328584970e-13	8.0747402312482086e-12
Constraint violation....:	4.4408920985006262e-16	4.4408920985006262e-16
Complementarity....:	0.0000000000000000e+00	0.0000000000000000e+00
Overall NLP error....:	1.7519319328584970e-13	8.0747402312482086e-12

Number of objective function evaluations	= 2
Number of objective gradient evaluations	= 2
Number of equality constraint evaluations	= 2
Number of inequality constraint evaluations	= 0
Number of equality constraint Jacobian evaluations	= 1
Number of inequality constraint Jacobian evaluations	= 0
Number of Lagrangian Hessian evaluations	= 1
Total CPU secs in IPOPT (w/o function evaluations)	= 0.220
Total CPU secs in NLP function evaluations	= 0.070

EXIT: Optimal Solution Found.

```
[9]: println("The optimal p values are->",round.(value.(p),digits = 6));
println("The optimal q values are->",round.(value.(q),digits = 6));
## plot
using PyPlot;
Xcoordinate = 0:0.25:10;
X_plot = zeros(length(Xcoordinate),K);

piece = 0; ## mark the index where there is a piece wise
for i = 1:(length(Xcoordinate)-1)
    if Xcoordinate[i] < 4 && Xcoordinate[i+1] >= 4
        piece = i;
    end
end

for i = 1:K
    X_plot[:,K - i + 1] = Xcoordinate.^(i-1);
end

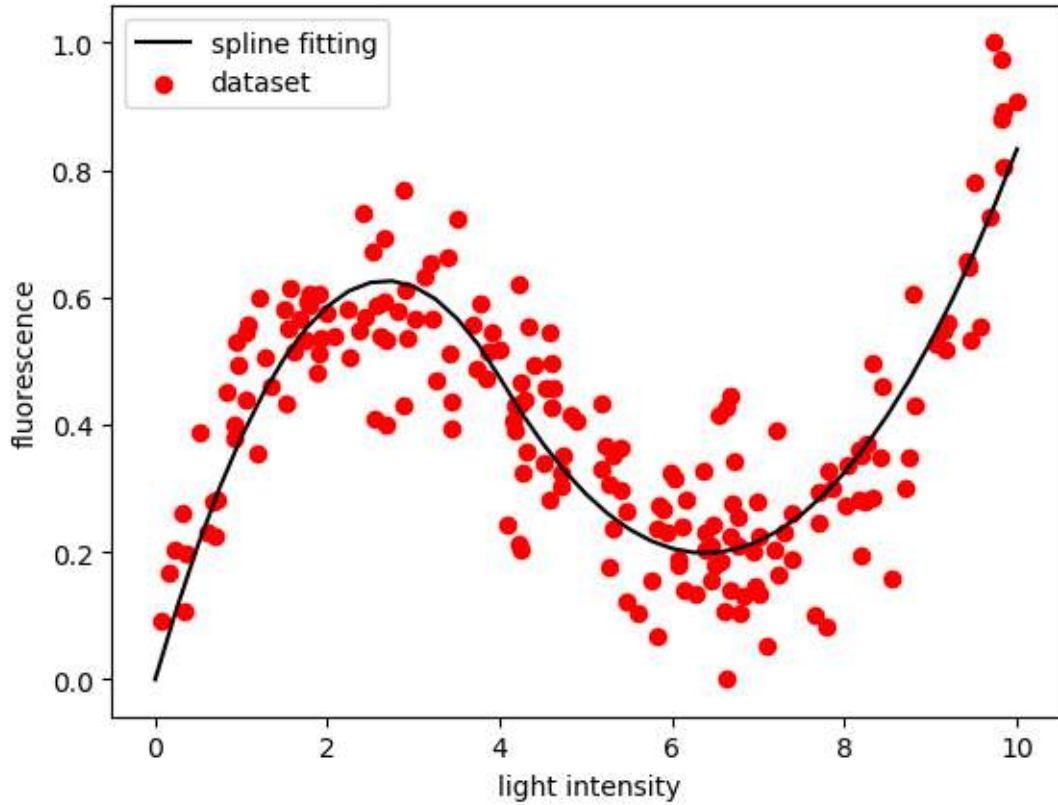
Y_plot = zeros((length(Xcoordinate),1));
Y_plot[1:piece] = X_plot[1:piece,:] * value.(p);
```

```

Y_plot[piece+1:length(Xcoordinate)] = X_plot[piece+1:length(Xcoordinate),:] *
↪value.(q);

figure();
plot(Xcoordinate,Y_plot, label = "spline fitting", c = "k");
scatter(data[:,1], data[:,2], label = "dataset", c = "r");
xlabel("light intensity");
ylabel("fluorescence");
legend();

```



The optimal p values are->[-0.087316, 0.467636, 0.0]

The optimal q values are->[0.048463, -0.618597, 2.172466]

1.2 Q2. Voltage smoothing

$$\underset{V_{smooth}}{\text{minimize}} \quad ||V_{raw} - V_{smooth}||^2 + \lambda R(V_{smooth}) \quad (8)$$

$$(9)$$

The $R()$ is a function calculating the smoothness of a voltage $R(x) = \sum_i^{n-1} (x_{i+1} - x_i)^2$
The λ is the regularization factor.

```
[10]: using CSV
      data2 = CSV.read("voltages.csv");
```

```
[11]: raw_volt = data2[:,1];
```

```
[12]: function smoothness(volt)
      L = length(volt);
      R = 0;
      for i = 1:(L-1)
          R = R + (volt[i+1] - volt[i])^2;
      end
      return R;
end
```

```
[12]: smoothness (generic function with 1 method)
```

```
[13]: using Ipopt, JuMP;
      m2 = Model(with_optimizer(Ipopt.Optimizer));
      set_silent(m2);
      lambda = [10.0^i for i = -1:2];

      opt_volt = zeros((length(raw_volt), length(lambda)));
      new_volt = @variable(m2, [1:length(raw_volt)]);

      for i = 1:length(lambda)
          @objective(m2, Min, sum((new_volt - raw_volt).^2) + lambda[i]*_
      ↪smoothness(new_volt));
          optimize!(m2);
          opt_volt[:,i] = value.(new_volt);
      end
```

This is Ipopt version 3.12.10, running with linear solver mumps.

NOTE: Other linear solvers might be more efficient (see Ipopt documentation).

```
Number of nonzeros in equality constraint Jacobian...:      0
Number of nonzeros in inequality constraint Jacobian.:      0
Number of nonzeros in Lagrangian Hessian...:          397

Total number of variables...:          199
      variables with only lower bounds:          0
      variables with lower and upper bounds:      0
      variables with only upper bounds:          0
Total number of equality constraints...:          0
Total number of inequality constraints...:          0
      inequality constraints with only lower bounds: 0
      inequality constraints with lower and upper bounds: 0
      inequality constraints with only upper bounds: 0
```


iter	objective	inf_pr	inf_du	lg(mu)	d	lg(rg)	alpha_du	alpha_pr	ls
0	3.9000000e+02	0.00e+00	4.00e+00	-1.0	0.00e+00	-	0.00e+00	0.00e+00	0
1	2.7044936e+00	0.00e+00	1.55e-15	-1.0	2.00e+00	-	1.00e+00	1.00e+00f	1

Number of Iterations....: 1

	(scaled)	(unscaled)
Objective....:	2.7044936151370731e+00	2.7044936151370731e+00
Dual infeasibility....:	1.5543122344752192e-15	1.5543122344752192e-15
Constraint violation....:	0.0000000000000000e+00	0.0000000000000000e+00
Complementarity....:	0.0000000000000000e+00	0.0000000000000000e+00
Overall NLP error....:	1.5543122344752192e-15	1.5543122344752192e-15

Number of objective function evaluations	=	2
Number of objective gradient evaluations	=	2
Number of equality constraint evaluations	=	0
Number of inequality constraint evaluations	=	0
Number of equality constraint Jacobian evaluations	=	0
Number of inequality constraint Jacobian evaluations	=	0
Number of Lagrangian Hessian evaluations	=	1
Total CPU secs in IPOPT (w/o function evaluations)	=	0.000
Total CPU secs in NLP function evaluations	=	0.000

EXIT: Optimal Solution Found.

This is Ipopt version 3.12.10, running with linear solver mumps.

NOTE: Other linear solvers might be more efficient (see Ipopt documentation).

Number of nonzeros in equality constraint Jacobian....:	0
Number of nonzeros in inequality constraint Jacobian..:	0
Number of nonzeros in Lagrangian Hessian....:	397

Total number of variables....:	199
variables with only lower bounds:	0
variables with lower and upper bounds:	0
variables with only upper bounds:	0
Total number of equality constraints....:	0
Total number of inequality constraints....:	0
inequality constraints with only lower bounds:	0
inequality constraints with lower and upper bounds:	0
inequality constraints with only upper bounds:	0

iter	objective	inf_pr	inf_du	lg(mu)	d	lg(rg)	alpha_du	alpha_pr	ls
0	3.9000000e+02	0.00e+00	4.00e+00	-1.0	0.00e+00	-	0.00e+00	0.00e+00	0
1	1.4310953e+01	0.00e+00	2.22e-15	-1.0	2.00e+00	-	1.00e+00	1.00e+00f	1

Number of Iterations....: 1

	(scaled)	(unscaled)
Objective....:	1.4310953235786460e+01	1.4310953235786460e+01
Dual infeasibility....:	2.2204460492503131e-15	2.2204460492503131e-15
Constraint violation....:	0.0000000000000000e+00	0.0000000000000000e+00
Complementarity....:	0.0000000000000000e+00	0.0000000000000000e+00
Overall NLP error....:	2.2204460492503131e-15	2.2204460492503131e-15

Number of objective function evaluations	=	2
Number of objective gradient evaluations	=	2
Number of equality constraint evaluations	=	0
Number of inequality constraint evaluations	=	0
Number of equality constraint Jacobian evaluations	=	0
Number of inequality constraint Jacobian evaluations	=	0
Number of Lagrangian Hessian evaluations	=	1
Total CPU secs in IPOPT (w/o function evaluations)	=	0.000
Total CPU secs in NLP function evaluations	=	0.000

EXIT: Optimal Solution Found.

This is Ipopt version 3.12.10, running with linear solver mumps.

NOTE: Other linear solvers might be more efficient (see Ipopt documentation).

Number of nonzeros in equality constraint Jacobian....:	0
Number of nonzeros in inequality constraint Jacobian..:	0
Number of nonzeros in Lagrangian Hessian....:	397

Total number of variables....:	199
variables with only lower bounds:	0
variables with lower and upper bounds:	0
variables with only upper bounds:	0
Total number of equality constraints....:	0
Total number of inequality constraints....:	0
inequality constraints with only lower bounds:	0
inequality constraints with lower and upper bounds:	0
inequality constraints with only upper bounds:	0

iter	objective	inf_pr	inf_du	lg(mu)	d	lg(rg)	alpha_du	alpha_pr	ls
0	3.9000000e+02	0.00e+00	4.00e+00	-1.0	0.00e+00	-	0.00e+00	0.00e+00	0
1	5.0143390e+01	0.00e+00	1.42e-14	-1.0	1.94e+00	-	1.00e+00	1.00e+00	1

Number of Iterations....: 1

	(scaled)	(unscaled)
Objective....:	5.0143389693362174e+01	5.0143389693362174e+01
Dual infeasibility....:	1.4210854715202004e-14	1.4210854715202004e-14
Constraint violation....:	0.0000000000000000e+00	0.0000000000000000e+00
Complementarity....:	0.0000000000000000e+00	0.0000000000000000e+00

Overall NLP error...: 1.4210854715202004e-14 1.4210854715202004e-14

Number of objective function evaluations = 2
 Number of objective gradient evaluations = 2
 Number of equality constraint evaluations = 0
 Number of inequality constraint evaluations = 0
 Number of equality constraint Jacobian evaluations = 0
 Number of inequality constraint Jacobian evaluations = 0
 Number of Lagrangian Hessian evaluations = 1
 Total CPU secs in IPOPT (w/o function evaluations) = 0.000
 Total CPU secs in NLP function evaluations = 0.000

EXIT: Optimal Solution Found.

This is Ipopt version 3.12.10, running with linear solver mumps.

NOTE: Other linear solvers might be more efficient (see Ipopt documentation).

Number of nonzeros in equality constraint Jacobian...: 0
 Number of nonzeros in inequality constraint Jacobian.: 0
 Number of nonzeros in Lagrangian Hessian...: 397

Total number of variables...: 199
 variables with only lower bounds: 0
 variables with lower and upper bounds: 0
 variables with only upper bounds: 0
 Total number of equality constraints...: 0
 Total number of inequality constraints...: 0
 inequality constraints with only lower bounds: 0
 inequality constraints with lower and upper bounds: 0
 inequality constraints with only upper bounds: 0

iter	objective	inf_pr	inf_du	lg(mu)	d	lg(rg)	alpha_du	alpha_pr	ls
0	3.9000000e+02	0.00e+00	4.00e+00	-1.0	0.00e+00	-	0.00e+00	0.00e+00	0
1	1.4085581e+02	0.00e+00	1.14e-13	-1.0	1.39e+00	-	1.00e+00	1.00e+00	1

Number of Iterations...: 1

	(scaled)	(unscaled)
Objective...:	1.4085580642066014e+02	1.4085580642066014e+02
Dual infeasibility...:	1.1368683772161603e-13	1.1368683772161603e-13
Constraint violation...:	0.0000000000000000e+00	0.0000000000000000e+00
Complementarity...:	0.0000000000000000e+00	0.0000000000000000e+00
Overall NLP error...:	1.1368683772161603e-13	1.1368683772161603e-13

Number of objective function evaluations = 2
 Number of objective gradient evaluations = 2
 Number of equality constraint evaluations = 0

```

Number of inequality constraint evaluations      = 0
Number of equality constraint Jacobian evaluations = 0
Number of inequality constraint Jacobian evaluations = 0
Number of Lagrangian Hessian evaluations      = 1
Total CPU secs in IPOPT (w/o function evaluations) = 0.000
Total CPU secs in NLP function evaluations    = 0.000

```

EXIT: Optimal Solution Found.

```

[14]: using PyPlot;
figure();
plot(raw_volt, label = "raw volt", linewidth = 3);
for i = 1:length(lambda)
    #LABEL = ["regularization ="]
    plot(opt_volt[:,i], label = ("regularization = " * string(lambda[i])));
end

legend();
xlabel("time");
ylabel("voltage");

```

