x86 Crash Course

With a focus on Linux and a glance to x86_64

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Introduction

Crash course on Assembly Language

Overview on the common 32-bit Intel Architecture (IA) Overview on Assembly Basic Instructions x86_64

Something more

Program Layout In Memory Functions and Calling Convention objdump – GDB tutorial Conclusion

Instruction Set Architecture (ISA)

Specification of Computer Architecture related to programming. Instructions, registers, memory architecture, interrupt, and etc.

- **x86**, x86_64, IA-32: PCs, Servers, High-Performance, ...
- ► **ARM**: Mobile Devices
- ▶ MIPS: Routers
- PowerPC: Embedded and high-performance processors
- ▶ m68k: Very old
- and more

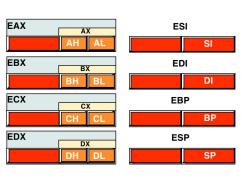
Overview on the common 32-bit Intel Architecture (IA)
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(1) How does the IA-32 look like?

- ► The processor has 32-bits internal registers to manage and execute operations on data
- ► EAX, EBX, ECX, EDX are for general purposes
- ► **EBP** (BP = base pointer) and **ESP** (SP = stack pointer) are the stack bounds
- ► EDI and ESI are extra registers used as source and dest for special instructions (e.g strcpy)
- ► **EIP** (IP = instruction pointer) is the register that contains the address of the next instruction

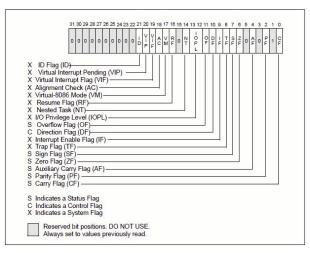


(2) How does Al look like?



- The register naming system is from IA-16 where the registers were called AX, BX, CX, DX.
- the "E" indicates extended (32 bits). Without it, we consider the corresponding 16-bits register
- ► **Memorandum:** although we are in IA-32
 - byte (8 bits)
 - word (2 bytes)
 - dword (double word, 4 bytes)
 - qword (quadruple word, 8 bytes)

(1) What about EFLAGS?



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(2) What about EFLAGS?

- ▶ It's another 32-bits register
- Only 8 bits out of 32 are of interest for us. The others are either for the kernel mode function or are of little interest for programmers
- ► These 8 bits are called flags. We consider them singularly. They are boolean (true/false)
- ► They represent overflow, direction, interrupt disable, sign, zero, auxiliary carry, parity and carry flags
- Since they represent information about the instruction last executed, they change at every execution step. They are VERY important for the control flow of the program



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Assembly

- Low-Level Language
- Directly mapped with binary code
- Custom per Architecture (x86, PowerPC, ARM ...)

Syntax

- ► In the assembly world we can find two main syntaxes: AT&T and Intel
- AT&T syntax is used by all UNIX programs (e.g., gdb by default)
- Intel syntax is used by Microsoft programs (IDApro and others)

(1) Differences in the notation

Consider the following operation:

"move the value 0 to EAX"

► AT&T:

mov \$0x0, %eax

Intel:

mov eax, Oh

- Main differences:
 - ► In AT&T syntax the destination is the second operand, and vice-versa in Intel syntax
 - ► In AT&T syntax registers are denoted with % and immediates (i.e., costants) with \$. In the Intel syntax these tokens are not used

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(2) Differences in pointer de-referencing

► Consider this new operation:

"move the value 0 to the address contained in EBX+4"

► AT&T:

mov
$$$0x0,0x4(\%ebx)$$

► Intel:

- Main differences:
 - Parentheses: round vs. square
 - ▶ Offsets: out and before vs. inside with a '+' sign

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(1) Basic instructions overview

- ▶ Every processor has a large instruction set (see Intel manual¹)
- A subset of the whole instruction set is usually processor dependent
- We will focus on the subset of instructions that is common among the processors
- We will use the Intel syntax as it is the same syntax used in IDApro by default
- Very good reference: http://ref.x86asm.net/geek32.html

(2) Basic Instruction MOV

- MOV <u>destination</u>, <u>source</u> <u>source</u> can be an immediate, a register, a memory location <u>destination</u> can be either a register or a memory location NB: Every combination except memloc to memloc: It is invalid in every instruction!
- Move value from source to destination. There are tons of different versions, depending on the operands size (byte, word, dword), immediate to reg, immediate to memory, etc.
- Examples

| MOV eax, ebx | MOV eax, FFFFFFFh | MOV ax, bx |
|---------------|-----------------------|-------------|
| MOV [eax],ecx | MOV [eax],[ecx] NO!!! | MOV al, FFh |



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(3) Basic Instruction ADD

- ► ADD <u>destination</u>, <u>source</u> <u>source</u> can be an immediate, a register, a memory location <u>destination</u> can be either a register or a memory location NB: The destination has to be at least as large as the source.
- Semantic: destination = destination + source
- Examples

| ADD esp, 44h | ADD eax, ebx | ADD al, dh | |
|--------------|-----------------------|--------------|--|
| ADD edx, cx | ADD [eax],[ecx] NO!!! | ADD [eax],1h | |

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(4) Basic Instruction SUB

- ► SUB <u>destination</u>, <u>source</u> <u>source</u> can be an immediate, a register, a memory location <u>destination</u> can be either a register or a memory location NB: The destination has to be at least as large as the source.
- Semantic: destination = destination source
- Examples

| SUB esp, 33h | SUB eax, ebx | SUB al, dh |
|--------------|-----------------------|--------------|
| SUB edx, cx | SUB [eax],[ecx] NO!!! | SUB [eax],1h |

(5) Basic Instruction MUL

- MUL <u>Operand</u>
 Operand can be an immediate, a register, a memory location
- Multiplies Operand by the value of AL, AX, EAX register, depending on sizeof(Operand)

| sizeof(Operand): | 1 byte | 2 bytes | 4 bytes |
|--------------------------------|--------|---------|---------|
| Other operand | AL | AX | EAX |
| Most sign. part of result in: | AH | DX | EDX |
| Least sign. part of result in: | AL | AX | EAX |

Examples

| sizeof(Operand): | 1 byte | 2 bytes | 4 bytes |
|------------------|---------|-----------|---------------|
| Immediate | MUL 44h | MUL 4455h | MUL 44556677h |
| Register | MUL cl | MUL dx | MUL ebx |

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(6) Basic Instruction DIV

- DIV <u>Operand</u>
 Operand can be an immediate, a register, a memory location
- Divides the value in the dividend register(s) by Operand

| sizeof(Operand): | 1 byte | 2 bytes | 4 bytes |
|------------------|--------|---------|---------|
| Dividend | AX | DX:AX | EDX:EAX |
| Remainder | АН | DX | EDX |
| Quotient | AL | AX | EAX |

Examples

| sizeof(Operand): | 1 byte | 2 bytes | 4 bytes |
|------------------|---------|-----------|---------------|
| Register | DIV bl | DIV bx | DIV ebx |
| Immediate | DIV 66h | DIV 6677h | DIV 66778899h |

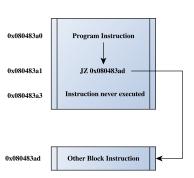
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(7) Control-flow Instruction CMP

- CMP Operand_1, Operand_2
- Operand_1 minus Operand_2 subtraction and sets the flags (ZF,CF,OF, etc.), it doesn't store the result
- Examples

| CMP eax, ebx | CMP eax, 44BBCCDDh | CMP al, dh |
|--------------|--------------------|--------------|
| CMP al, 44h | CMP ax,FFFFh | CMP [eax],4h |

(8) Control-flow Instruction JMP

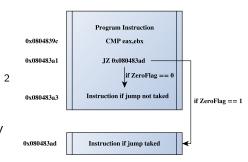


- JMP <u>address</u> or <u>offset</u>
- Called "unconditional jump": sets the EIP to the address. We say that the execution "jumps to address" and it's unconditional because it always happens.
- Using an offset the current EIP is incremented (or decreased) by the constant expressed by the offset resulting in a relative jump.

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(9) Other Control-flow Instructions: JZ, JNZ and so on

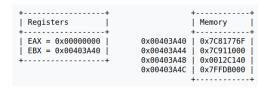
- General: JX address or offset $X \in \{O, NO, S, NS, E, Z, NE...\}$
- These are called "conditional jumps"
- ► The execution will go to **address** if and only if the specific flag of the condition is verified.
- For example: JZ jumps if and only if ZF (zero flag) is 1
- Offset is used for relative position (as in JMP)



(10) Load Effective Address LEA

- LEA <u>destination</u>, <u>source</u> <u>source</u> a memory location <u>destination</u> register
- Like a MOV, but it is storing the pointer not the value
- Example: LEA eax, [ebx+8]

Put [ebx+8] into EAX. **EAX** = 0x00403A48. **N.B.** with MOV eax, [ebx+8] EAX = 0x0012C140



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$\overline{(11)}$ Basic Instruction NOP

- ► NOP
- ► The meaning of NOP is No Operation. Just move to next instruction.
- ► The opcode is pretty famous and is **0x90**
- Really useful in exploitation (we will see).

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(12) Basic Instruction INT

- ► INT VALUE
- ▶ **VALUE** is the software interrupt number to generate (0-255)
- ► Famous values are 21h for call service under Windows and 80 for Linux
- Every OS has its set of interrupt numbers

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$\overline{(13)}$ Syscall/SYSENTER

Nowadays Syscalls are done with specific instructions.

- syscall is used for Linux 64-bit
- ► SYSENTER is used by Microsoft Windows

How much is x86_64 different from x86?

- ► The prefix of the registers is R instead of E so we have (RIP, RAX etc.)
- ► There are 8 new registers (**R8** to **R15**)
- ▶ each of them can be considered at 8, 16, 32, 64 bits (qword) with $X \in \{8..15\}$ we have

| bits | 8 | 16 | 32 | 64 |
|------|-----|-----|-----|----|
| reg | rXb | rXw | rXd | rX |

for better syntax information look at http://www.x86-64.org/documentation/assembly.html

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Binary File Formats

- ▶ PE (Portable Executable): used by Microsoft binary executable.
- ► ELF: common binary format for Unix, Linux, FreeBSD and others
- ▶ In both cases, we are interested in how each executable is mapped into memory, rather than how it is organized on disk.

How an executable is mapped to memory in Linux (ELF)

| Executable | Description |
|--------------|--|
| .bss | This section holds uninitialized data that contributes to the program's memory image. |
| | By definition, the system initializes the data with zeros when the program begins to run. |
| .comment | This section holds version control information. |
| .data/.data1 | These sections hold initialized data that contribute to |
| | the program's memory image |
| .debug | This section holds information symbolic debugging. |
| .text | This section holds the "text," or executable instructions, of a program. |
| .init | This section holds executable instructions that contribute to the process initialization code. |
| | That is, when a program starts to run, the system arranges to execute the code in this |
| | section before calling the main program entry point (called main for C programs). |
| .got | This section holds the global offset table. |

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How an executable is mapped to memory in Windows (PE)

| Executable | Description |
|------------|---|
| .text | Contains the executable code |
| .rdata | Holds read-only data that is globally accessible within |
| | the program |
| .data | Stores global data accessed throughout the program |
| .idata | stores the import function information; |
| .edata | stores the export function information; |
| .pdata | Present only in 64-bit executables and stores |
| | execption-handling information |
| .rsrc | Stores resources needed by the executable |
| .reloc | Contains information for relocation of library files |

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A more realistic view of an elf in memory

Low addresses (0x80000000)

| Shared libraries |
|------------------|
| .text |
| .bss |
| heap (grows ↓) |
| • • • |
| stack (grows ↑) |
| env |
| argc |

High addresses (0xbfffffff)



The stack

- ► Last In First Out (LIFO) data structure: the most recent data placed, or pushed, onto the stack is the first item to be removed, or popped, from it
- A LIFO is ideal for storing transitory data, or data that does not need to be stored for long.
- The stack stores local variables, information related to function calls or used to clean up the stack after a function or procedure returns.
- ► Remember: the stack grows downward the address space, toward lower addresses.

Stack Management Instruction: PUSH

- Pushes a word onto the stack
- Example: PUSH immediate or PUSH register
- Pushes the immediate or register value at the top of the stack and decrements the ESP of sizeof(immediate or register)

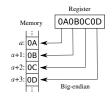
Stack Management Instruction: POP

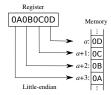
- Pops a word from the stack
- Example: POP destination
- Pops the word off of the top of the stack and moves it at destination, then it increases the ESP of sizeof(data popped).

Endianness

The **endianness** is a convention that specifies in which order the bytes of a data word are lined up sequentially in memory.

Big-endian (left) systems are systems in which the *most significant byte* of the word is stored in the *smallest address* given.



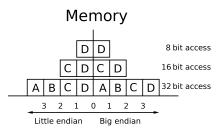


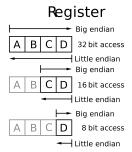
Little-endian (right) systems are those in which the *least significant* byte is stored in the *smallest address*. A-32 is "little endian".

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Endianness cont.

The **endianness** is a convention that specifies in which order the bytes of a data word are lined up sequentially in memory.





Functions

- ► The concept of "function" at the machine level is the same as in high-level programming languages
- ► **Function**: piece of code that receives data from the caller, execute code and returns some value
- ► Calling convention: how parameters are passed and value is retured = which instructions are executed to do this
- There exist several calling conventions, depending on architecture, OS and binary format

CALL and RET Instruction

- ► CALL **func** changes the execution flow to the **func** location. It stores return address of the instruction after the call onto the stack and moves into EIP the address of the first instruction of **func** (PUSH EIP; JMP func;)
- ▶ RET value returns to the previous function (i.e., caller). It restores return address saved by the CALL. (POP EIP;)

Calling Convention

- ► How a function receives parameters and returns the value and how it administers the stack
- There are several calling conventions that dictate where a caller should place any parameters that a function requires
- ► The high-level language, the compiler, the OS, and the target architecture all together "implement" and "agree upon" a certain calling convention.
- Let's look at some examples

The C Calling Convention

- ▶ It's the default calling convention used by most C compilers for the x86 architecture
- When a compiler doesn't use this convention we can force it using the modifier <u>cdecl</u>
- ▶ It specifies that the **caller places** parameters on the stack in the right to left order and that the **caller removes** the parameters from the stack after the called function completes

The C Calling Convention example

```
void demo_cdecl(int a, int b, int c, int z);
//...
demo_cdecl(1, 2, 3, 4); //calling
```

```
; ...
push 4 ; push last parameter value
push 3 ; push third parameter value
push 2 ; ...
push 1
call demo_cdecl ; call the subroutine
```

The Standard Calling Convention

- This is Miscrosoft's calling convention standard
- When a compiler doesn't use this convention we can force it using the modifier <u>stdcall</u>
- The parameters are passed using the stack as in _cdecl, but in _stdcall the called function is responsible for clearing the function parameters from the stack before returning. To do this, the function needs to know the right number of parameter passed. Can be used only with functions having a fixed number of parameters (e.g., no printf).

```
void _stdcall demo_stdcall(int a, int b, int c);
demo_stdcall(1, 2, 3);
```

ret 12; return and clear 12 bytes from the stack

fastcall Convention for x86

- Variation of the standard calling convention
- passes up to 2 parameters via registers (faster than stack).
- ► The Microsoft Visual C/ C++ and GNU GCC/g++ compilers recognize the fastcall modifier in function declaration.
- Example: the 1st and 2nd parameters are passed via ECX and EDX, the remainder parameters pushed on the stack in right to left order. The called function must cleanup the stack when returning.

```
; demo_fastcall(1, 2, 3, 4);
push 4 ; push 4th parameter
push 3 ; push 3rd parameter
mov edx, 2 ; move 2nd parameter in EDX
mov ecx, 1 ; move 1st parameter in ECX
call demo_fastcall
```

A Closer Look at the cdecl Calling Convention

```
void function (int a, int b) {
  int array [5];
}
int main (int argc, char** argv) {
  function(1, 2);
  printf("This is where the ret
      address points");
}
```

Low memory addresses (top of the stack)

```
array[0]
Saved EBP
return address
1
2
```

High memory addresses (bottom of the stack)



Assembler-level View of the Same Example

```
public main
main proc near
push ebp
mov ebp, esp; create stack
and esp.OFFFFFFFOh
sub esp.10h : make room for vars
mov dword ptr[esp+4],2; push 2
mov dwrod ptr[esp],1 ; push 1
call function
mov dword ptr [esp], offset format; "This is..."
call _printf
leave
ret
main endp
public function
function proc near
push ebp
mov ebp.esp : create stack
sub esp,20h; make room for array
leave
retn 8 : remove 2 dwords
function endp
```

Low memory addresses (top of the stack)

```
array[0]
Saved EBP
return address
1
2
```

High memory addresses (bottom of the stack)



Objdump

- man objdump objdump displays information about one or more object files.
- **-x** all-headers
- ▶ -d disassemble
- -M intel intel syntax (default is att)

Our friend gdb

What is GDB?

GDB is GNU Project's Debugger: allows to follow, step by step, at assembler-level granularity, a running program, or what a program was doing right before it crashed.³

³http://www.gnu.org/software/gdb/

Start, break and navigate the execution with gdb

- Suppose you have an executable binary and want run it
 - **gdb** /path/to/executable loads the binary in gdb
- Now you decide to start the program with two parameters
 - run 1 "abc" passes 1 via argv[1] and "abc" as argv[2]
 - run 'printf "AAAAAAAAAAA" (with the back ticks) we're passing the output of the print (very useful when you need to pass non printable characters such as raw bytes)
- Suppose you want to stop the execution at the address of a certain instruction
 - break *0xDEADBEAF places a break point at that address
 - break *main+1 with debugging symbols this can be less painful
 - catch syscall block the execution when a syscall happens



Start, break and navigate the execution with gdb

- Now the execution stops at our break point. Here we can do several things
- Examples:
 - ni allows to procede instruction per instruction
 - next 4 moves 4 lines ahead (if you have the line-numbers information in the binary)
 - si step into function
 - finish run until the end of current function
 - continue runs until the next break point (if any)
- ► To see info about the execution state:
 - ▶ **info registers** to inspect the content of the registers
 - info frame to see the values of the stack frame related to the function where we are in
 - info file print the information about the sections of the binary



Navigate the stack

- Suppose we're stopped somewhere in the code and want to inspect the stack
- Some useful view of the stack is achievable with:
 - x/100wx \$esp prints 100 words of memory from the address found in the ESP to ESP+100 (x = hexadecimal formatting)
 - x/10wo \$ebp-100 prints 10 words of memory from EBP-100 to EBP-100+10 (o = octal formatting)
 - x/s \$eax prints the elements pointed by EAX (s = string formatting)
- ▶ Do you have debug symbols? (i.e., gcc -ggdb)
 - print args prints info about the main parameters
 - **print a** prints the content of variable 'a'
 - print *b prints the value pointed by 'b'



Our friend gdb

► The '~/.gdbinit' file

Gdb is a command line tool and it supports the configuration script as almost all the *nix software.

Some options that you may want to tune are:

- set history save on
 To have the lastest commands always available also when we re-open gdb
- set follow-fork-mode child Allows you, if the process spawns children, to follow them and not only wait their end.
- set disassembly-flavor [intel | att] This option sets in which predefined syntax your disassembled will be showed up. The default one is at&t
- Highly recommended to put this https://github.com/gdbinit/Gdbinit file in ~/.gdbinit

Layout in gdb

- You're not a big fun of the gdb command line?
- Give a simple text-based interface to it
 - layout asm turn the interface to the assembly view always visible during debugging
 - layout src if your binary has the dubugging symbols you will have your c source view visible
 - layout reg add to the interface the register status view. It could be used in combination with one of the view described above
 - **gdb** -tui ./mybin runs gdb directly in this Text User Interface
- ▶ Use CTRL+X A to go back to standard interface.



man strace

In the simplest case **strace** runs the specified command until it exits. It intercepts and records the **system calls** which are called by a process and the signals which are received by a process. The name of each system call, its arguments and its return value are printed on standard error

Itrace

Itrace is a program that simply runs the specified command until it exits. It intercepts and records the **dynamic library calls** which are called by the executed process and the signals which are received by that process. It can also intercept and print the system calls executed by the program.

Bibliography

- The Ida Pro Book 2 Edition
- The Shellcoder Handbook
- Reverse Engineering Code with IDA Pro
- Secrets of Reverse Engineering
- Reverse Engineering for Beginners

End

That's all folks!
Time for (more) questions!