

view_frames Result
Recorded at time: 567.824

wally

odom

base_link

base_footprint

front_bumper_link

imu_link

inertial_link

rear_bumper_link

top_chassis_link

top_plate_link

user_rail_link

velodyne_base_link

front_left_wheel_link

front_right_wheel_link

rear_left_wheel_link

rear_right_wheel_link

top_plate_front_link

top_plate_rear_link

velodyne

Broadcaster: /wally
Average rate: 35.294 Hz
Most recent transform: 567.820 (0.004 sec old)
Buffer length: 2.380 sec

Broadcaster: /ekf_localization
Average rate: 50.000 Hz
Most recent transform: 567.800 (0.024 sec old)
Buffer length: 2.360 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (567.824 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (567.824 sec old)
Buffer length: 0.000 sec

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Average rate: 10000.000 Hz
Most recent transform: 0.000 (567.824 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 50.417 Hz
Most recent transform: 567.824 (0.000 sec old)
Buffer length: 2.400 sec

Broadcaster: /robot_state_publisher
Average rate: 50.417 Hz
Most recent transform: 567.824 (0.000 sec old)
Buffer length: 2.400 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (567.824 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (567.824 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (567.824 sec old)
Buffer length: 0.000 sec