

# Subroutines

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## **Defining a subroutine**

- A subroutine must contain:
  - a label before the first instruction
  - at the end, a branch to the address stored in LR

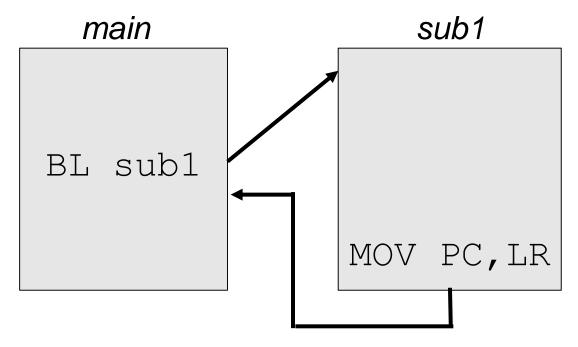
```
MyAdd ADD r0, r0, r1
BX LR
```

 Optionally, the begin and end of a subroutine can be indicated with a couple of directives

```
MyAdd PROC ; or FUNCTION
ADD r0, r0, r1
BX LR
ENDP ; or ENDFUNC
```

#### Call to subroutine

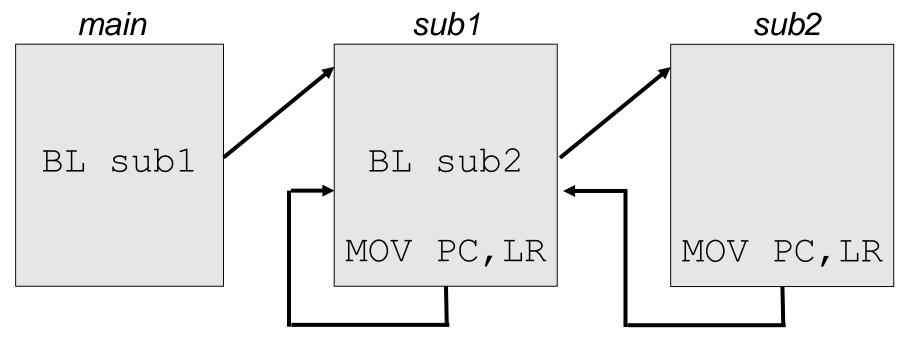
A subroutine is called with BL or BLX.



- BL < label > and BLX < Rn >:
  - write the address of the next instruction to LR
  - write the value of label or Rn to PC

#### **Nested calls to subroutines**

A subroutine can call another subroutine.



- When sub1 calls sub2, LR is overwritten.
- sub1 is not able to return to main.

#### **Nested calls to subroutines**

- Besides changing LR when called, sub2 may also change the value of registers used in sub1.
- Every subroutine should save LR and the other used registers as first instruction:

```
PUSH {regList, LR}
```

 At the end, the subroutine restores PC and the initial value of the used registers:

```
POP {regList, PC}
```

#### Passing parameters and result

- There are three approaches:
  - in registers
  - by reference, i.e., a register with an address in memory
  - on the stack
- Example: a main routine calls a subroutine for computing the absolute difference of two unsigned numbers.

## Passing parameters in registers

```
MOV r0, #0x34
    MOV r1, #0xA3
    BL sub1
    ; r2 contains the result
stop B stop
```

#### Passing parameters in registers

```
PROC
sub1
        PUSH {LR}
        CMP r0, r1
        ITE HS
        SUBHS r2, r0, r1
        SUBLO r2, r1, r0
        POP { PC }
        ENDP
```

#### Passing parameters by reference

```
MOV r0, #0x34
    MOV r1, #0xA3
    LDR r3, =mySpace
    STMIA r3, {r0, r1}
    ; r3 holds address of parameters
    BL sub2
    ;r3 holds address of result
    LDR r2, [r3] ; r2 holds result
stop B stop
```

#### Passing parameters by reference

```
sub2
        PROC
        PUSH {r2, r4, r5, LR}
        LDMIA r3, {r4, r5}
        CMP r4, r5
        TTE HS
        SUBHS r2, r4, r5
        SUBLO r2, r5, r4
        STR r2, [r3]
        POP {r2, r4, r5, PC}
        ENDP
```

#### Passing parameters on the stack

```
MOV r0, #0x34
    MOV r1, #0xA3
  1) PUSH {r0, r1, r2}
    BL sub3
    POP {r0, r1, r2}
    ; r2 contains the result
stop B stop
```

## Passing parameters on the stack

```
sub3
        PROC
     2) PUSH {r6, r4, r5, LR}
        LDR r4, [sp, #16]
        LDR r5, [sp, #20]
        CMP r4, r5
        TTE HS
        SUBHS r6, r4, r5
        SUBLO r6, r5, r4
      3) STR r6, [sp, #24]
      4) POP {r6, r4, r5, PC}
```

#### **Elements in the stack**

	after 1		after 2		after 3 a		fter 4
	r2		r2		r6		r6
	r1		r1		r1		r1
SP	r0		r0		r0	SP	r0
			LR		LR		
			r6		r6		
			r5		r5		
		SP	r4	SP	r4		

# ARM Architecture Procedure Call Standard (AAPCS)

- It regulates the interaction between a calling program and the called subroutine:
  - obligations on the caller: proper program state
  - obligations on the called subroutine: which parts of the program state must be preserved
  - rights of the called subroutine: which parts of the program state can be changed.
- It is part of Application Binary Interface (ABI)

https://developer.arm.com/documentation/ihi0036/latest/

## Registers and AAPCS usage

Register	Synonym	Special	Role in the procedure call standard
r15		PC	The Program Counter
r14		LR	The Link Register
r13		SP	The Stack Pointer
r12		IP	The Intra-Procedure-call scratch register
r11	v8		Variable-register 8
r10	v7		Variable-register 7
r9		v6, SB	Platform register. Meaning defined by platform standard
r8	v5		Variable-register 5
r7	v4		Variable-register 4
r6	v3		Variable-register 3
r5	v2		Variable-register 2
r4	v1		Variable-register 1
r3	a4		Argument / scratch register 4
r2	a3		Argument / scratch register 3
r1	a2		Argument / scratch register 2
r0	a1		Argument / scratch register 1

#### Obligations on the caller

- The first 4 parameters are passed in r0-r3.
- Further parameters are passed in the stack.
- After returning from the called subroutine, parameters must be removed from the stack
  - i.e., the stack pointer must have the same value as before the call.

## Obligations & rights of the called

- The subroutine must preserve the contents of the registers r4-r8, r10, r11 and SP.
- The subroutine can use r0-r3 and r12 as scratch registers.
- The return value is passed in r0-r3:
  - 32-bit sized type -> r0
  - 64-bit sized type -> r0-r1
  - **128-bit sized type ->** r0-r3

## Size of the data types

Type Class	Machine Type	Byte size	Byte alignment	Note	
Integral	Unsigned byte	1	1	Character	
	Signed byte	1	1		
	Unsigned half- word	2	2		
	Signed half- word	2	2		
	Unsigned word	4	4		
	Signed word	4	4		
	Unsigned double-word	8	8		
	Signed double- word	8	8		
Floating Point	Half precision	2	2	See §4.1.1, Half-precision Floating Point.	
	Single precision (IEEE 754)	4	4	The encoding of floating point numbers is described in [ARM ARM] chapter C2, VFP Programmer's Model, §2.1.1 Single-precision format, and §2.1.2 Double-precision format.	
	Double precision (IEEE 754)	8	8		
Containerized	64-bit vector	8	8	ee §4.1.2, Containerized Vectors.	
vector	128-bit vector	16	8	See y4.1.2, Contamenzed vectors.	
Pointer	Data pointer	4	4	Pointer arithmetic should be unsigned.	
	Code pointer	4	4	Bit 0 of a code pointer indicates the target instruction set type (0 ARM, 1 Thumb).	

Table 1, Byte size and byte alignment of fundamental data types