



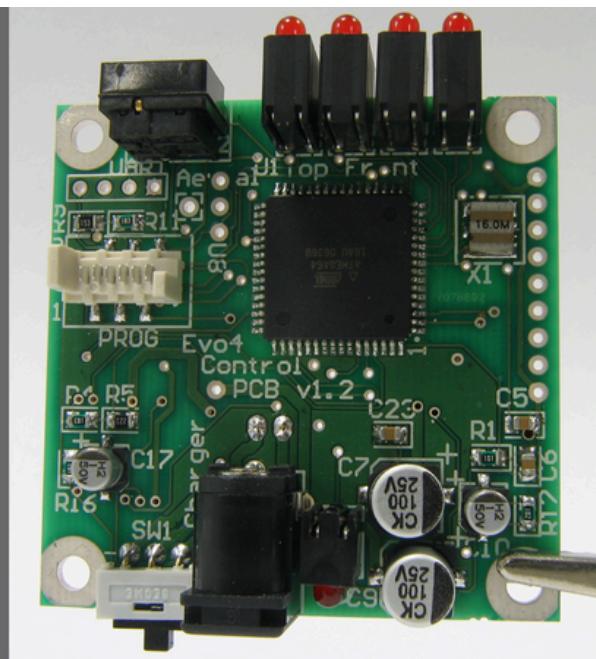
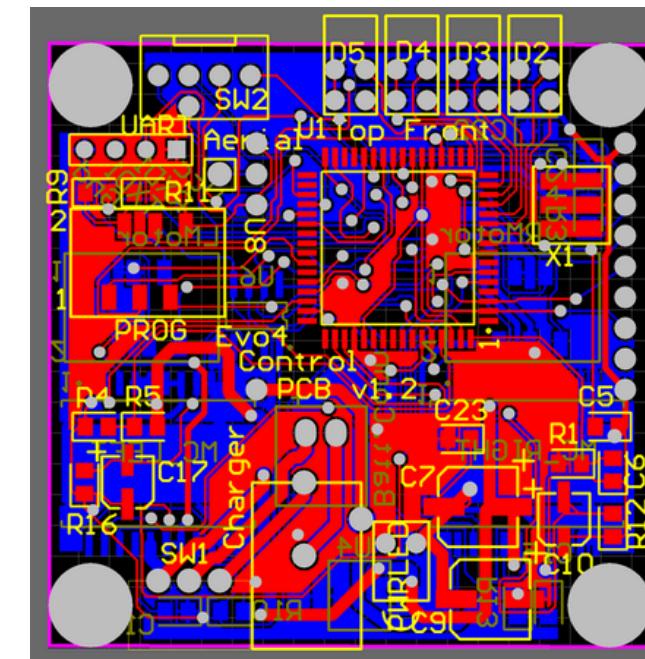
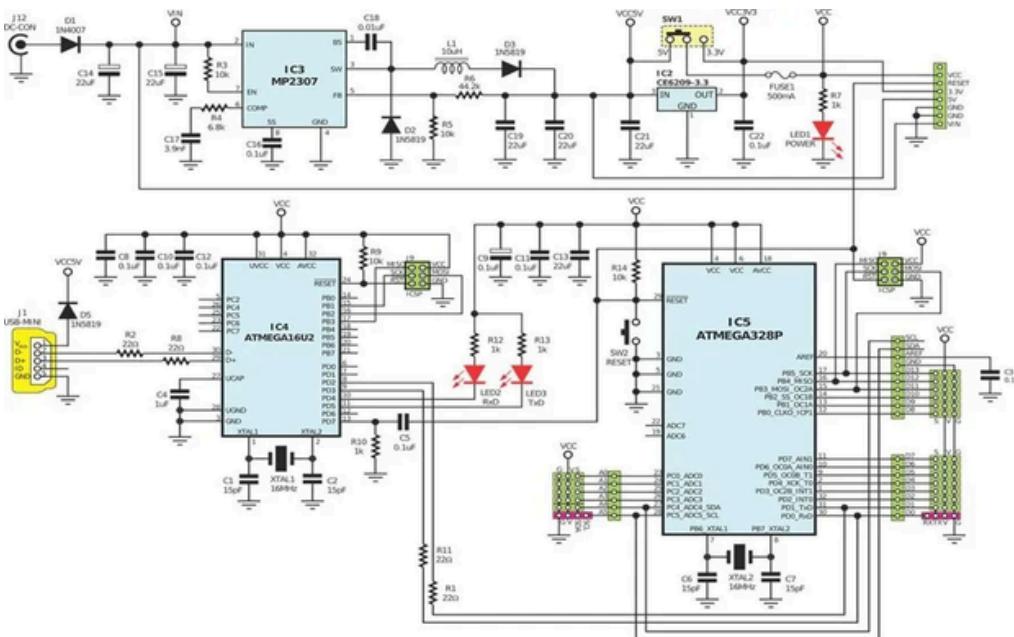
Tonet Lorenzo - Data Science and Artificial Intelligence

PCB - layout optimization

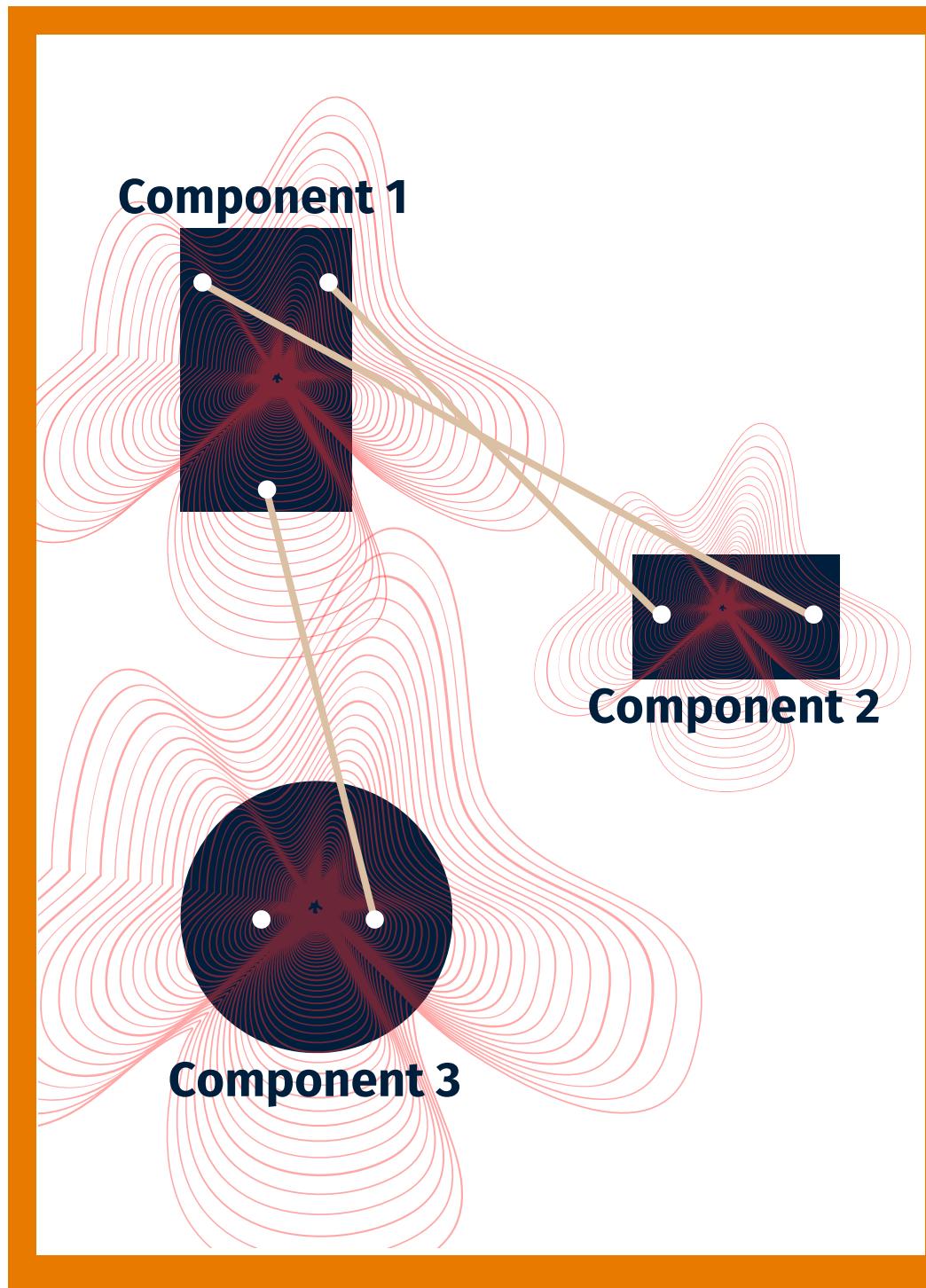
OPTIMIZATION FOR AI - FINAL PROJECT

General problem

PCB layout optimization is the problem of **placing** and **routing** electronic components on a circuit board so as to satisfy electrical, thermal, and manufacturing constraints while minimizing objectives such as signal interference, area, or cost.



Problem definition



The PCB will be composed by a list of **Components** and a list of **links** (pins that need to be connected in the circuit)

Every single component is characterized by:

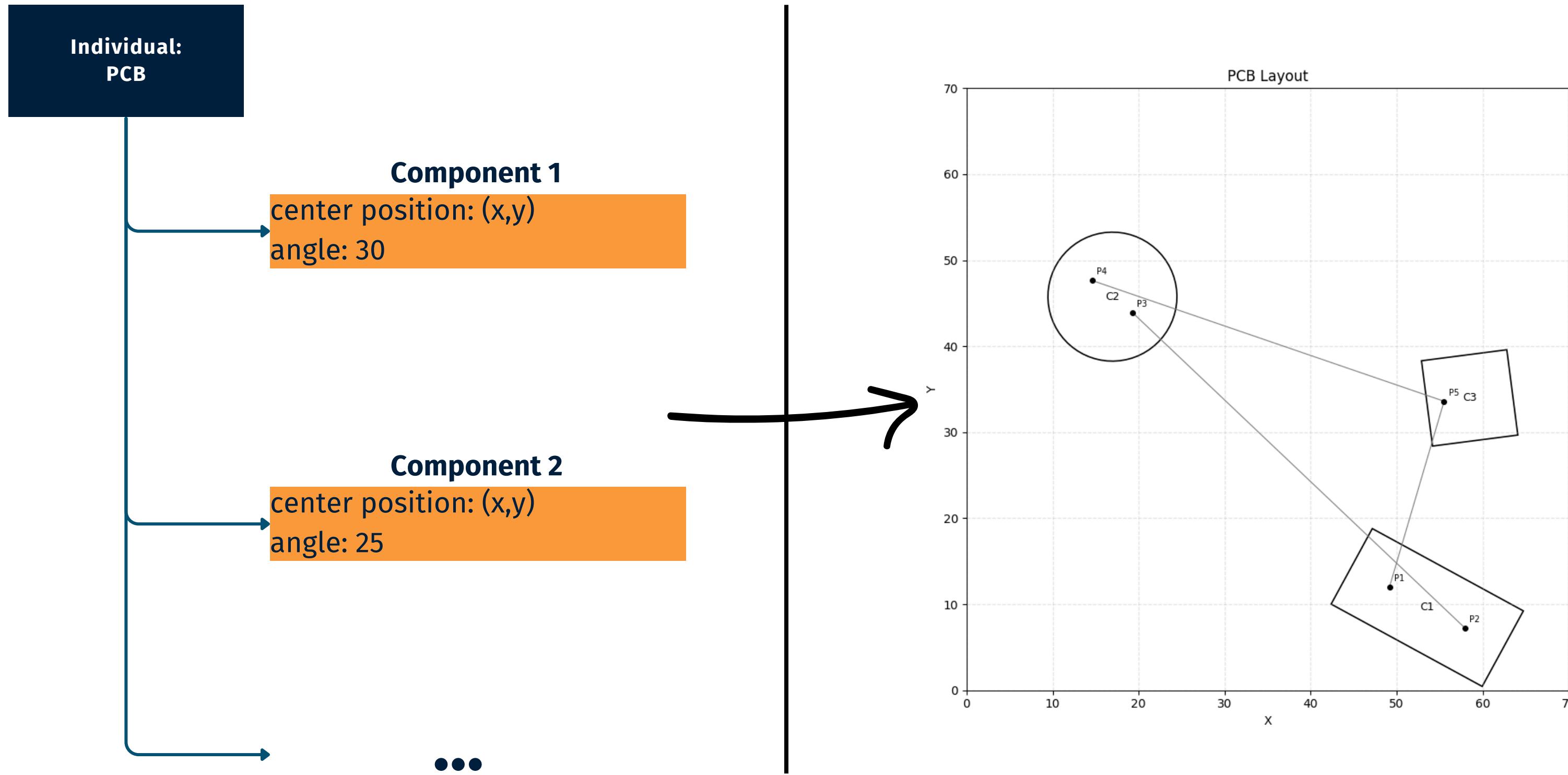
- center position
- rotation angle
- shape (and size)
- set of pins with their relative position
- thermal field

$$f(x) = T_C \times \exp\left(-\frac{d(x, x_c)}{d_L}\right)$$

Annotations for the equation:

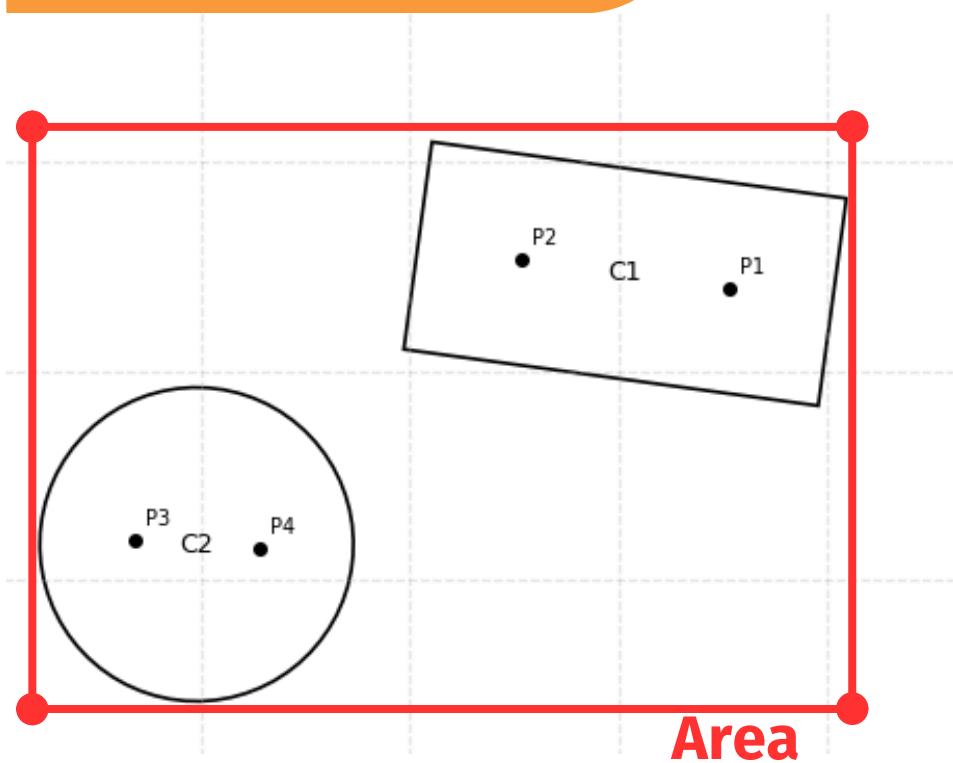
- Distance from the center: Points to the variable $d(x, x_c)$.
- Temperature at the center: Points to the variable T_C .
- Dissipation length: Points to the variable d_L .

Genotype to Phenotype

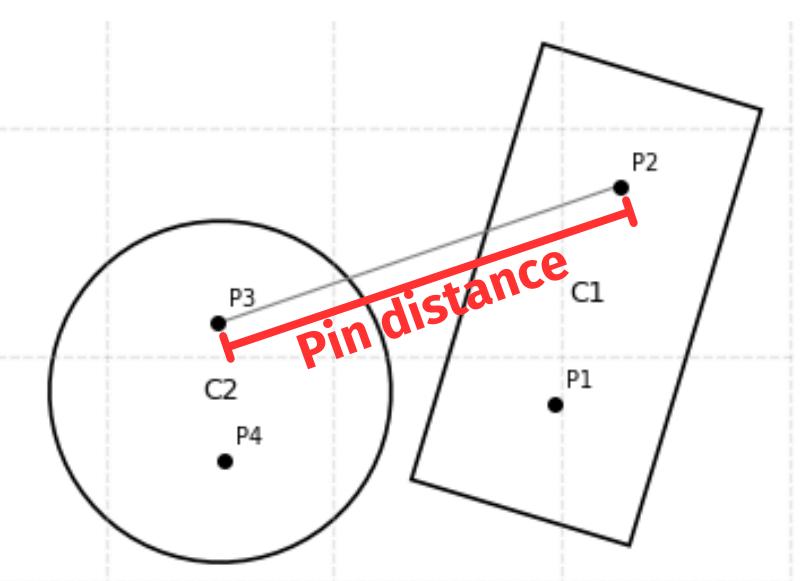


Objective functions

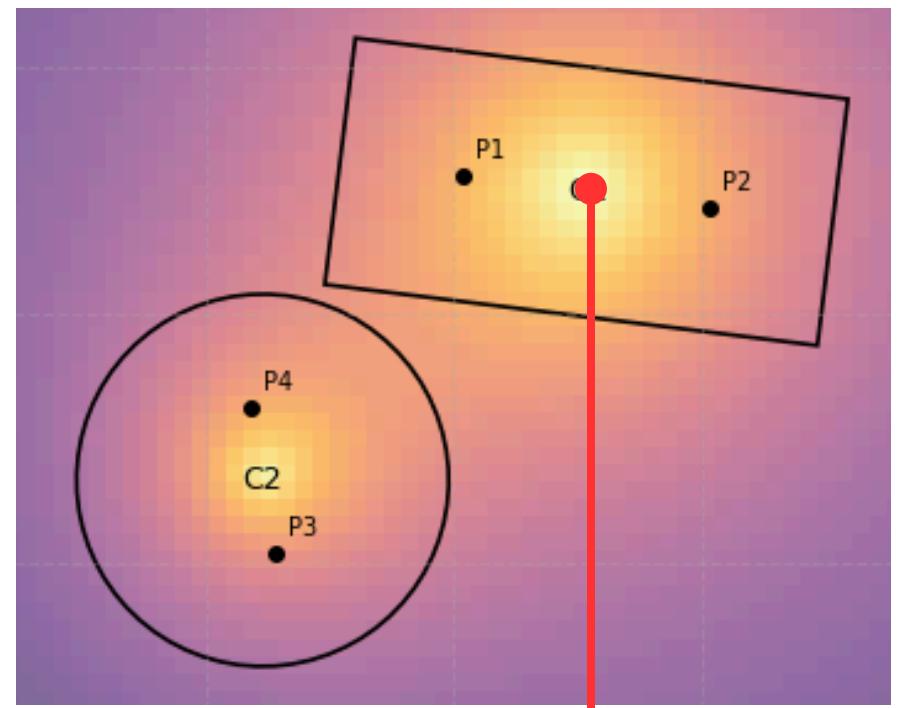
- Occupied Area



- Pin Distance



- Max Temperature



Occupied area and **pin distance** define concordant objectives, since both push the layout toward more compact placements, while maximum temperature acts as a conflicting objective that promotes component spreading.

Maximum
temperature in
the board

Framework: NSGA-II

- Multi-objective optimization through **non-dominated sorting**
- **Elitism**
- Diversity by **Crowding distance**
- **Tournament selection**

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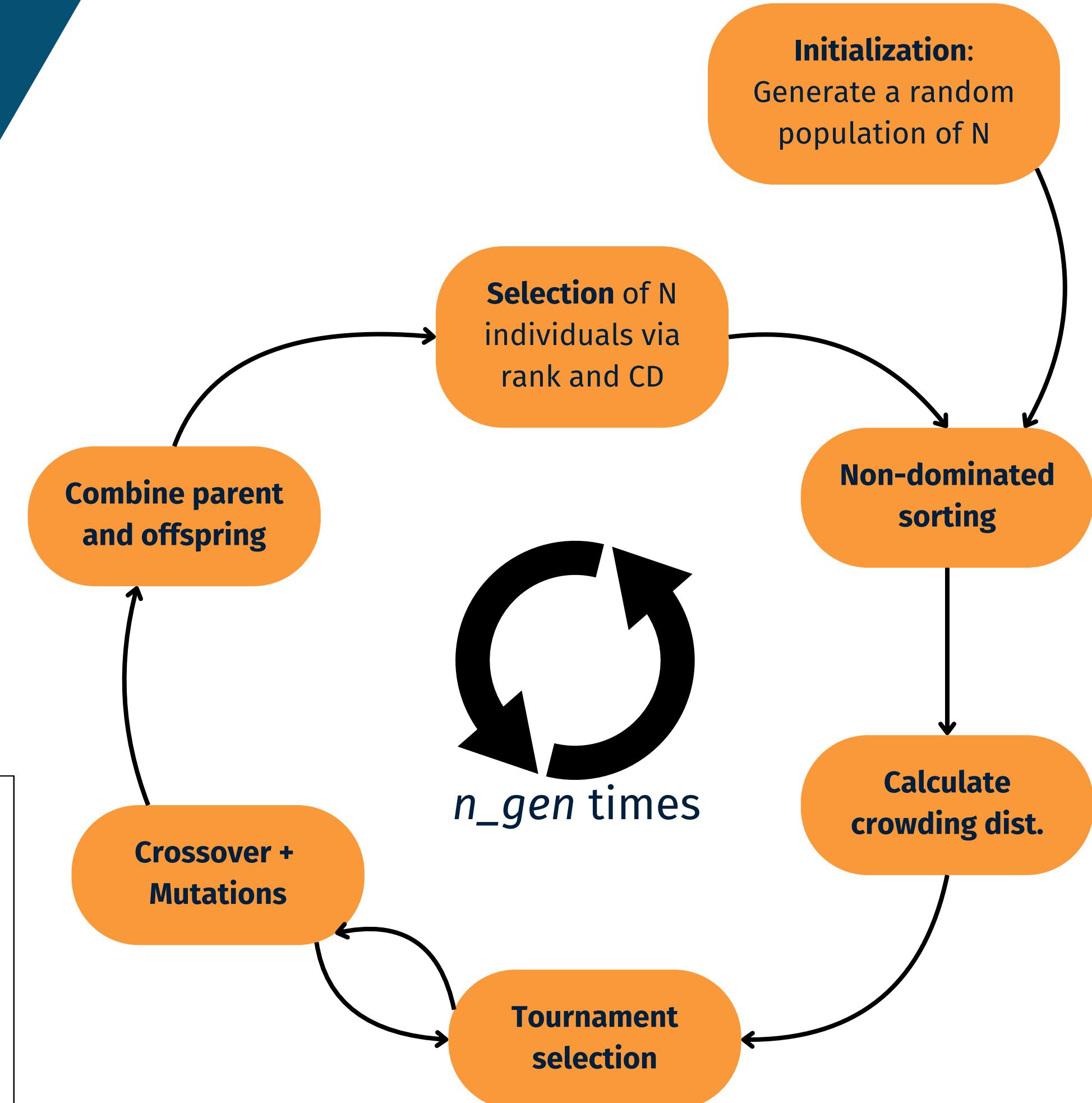
182

**A Fast and Elitist Multiobjective Genetic Algorithm:
NSGA-II**

Kalyanmoy Deb, Associate Member, IEEE, Amrit Pratap, Sameer Agarwal, and T. Meyarivan

Abstract—Multiobjective evolutionary algorithms (EAs) that use nondominated sorting and sharing have been criticized mainly for their: 1) $O(MN^3)$ computational complexity (where M is the number of objectives and N is the population size); 2) nonelitism approach; and 3) the need for specifying a sharing parameter. In this paper, we suggest a nondominated sorting-based multiobjective EA (MOEA), called nondominated

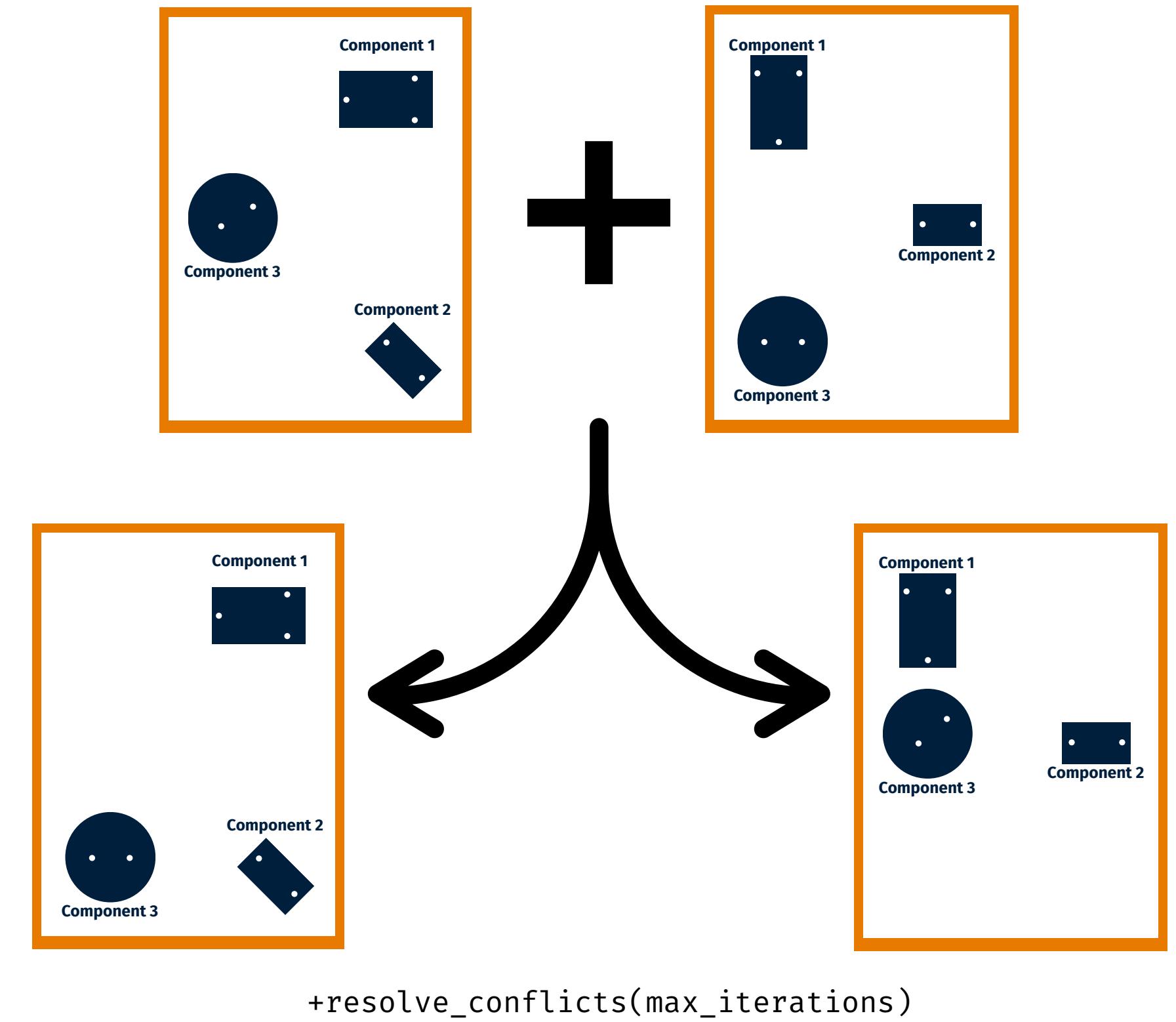
[20], [26]. The primary reason for this is their ability to find multiple Pareto-optimal solutions in one single simulation run. Since evolutionary algorithms (EAs) work with a population of solutions, a simple EA can be extended to maintain a diverse set of solutions. With an emphasis for moving toward the true Pareto-optimal region, an EA can be used to find multiple



Crossover operator

The crossover operation is characterized by 3 operations:

- select n random components from parents
- swap their position and angle
- resolve emerged conflicts

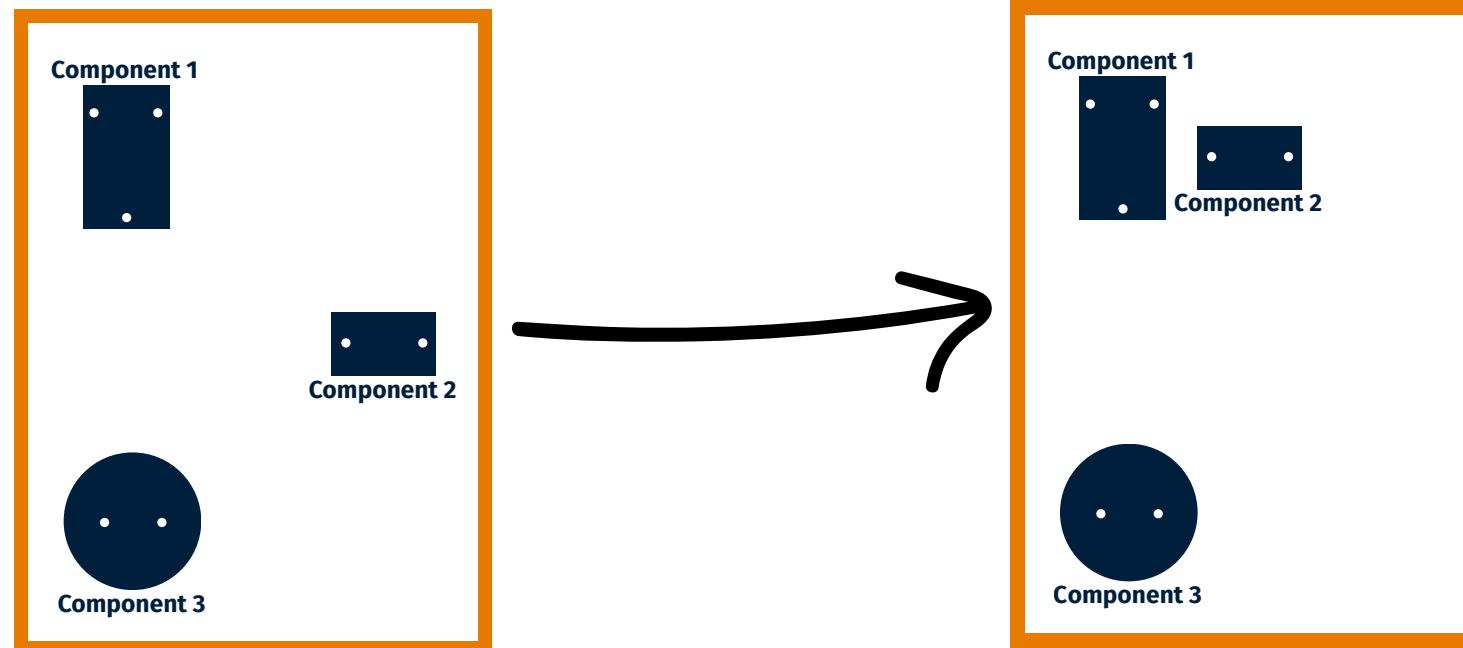


Mutation Operators

Position Mutation

The first mutation operator is characterized by 3 operations:

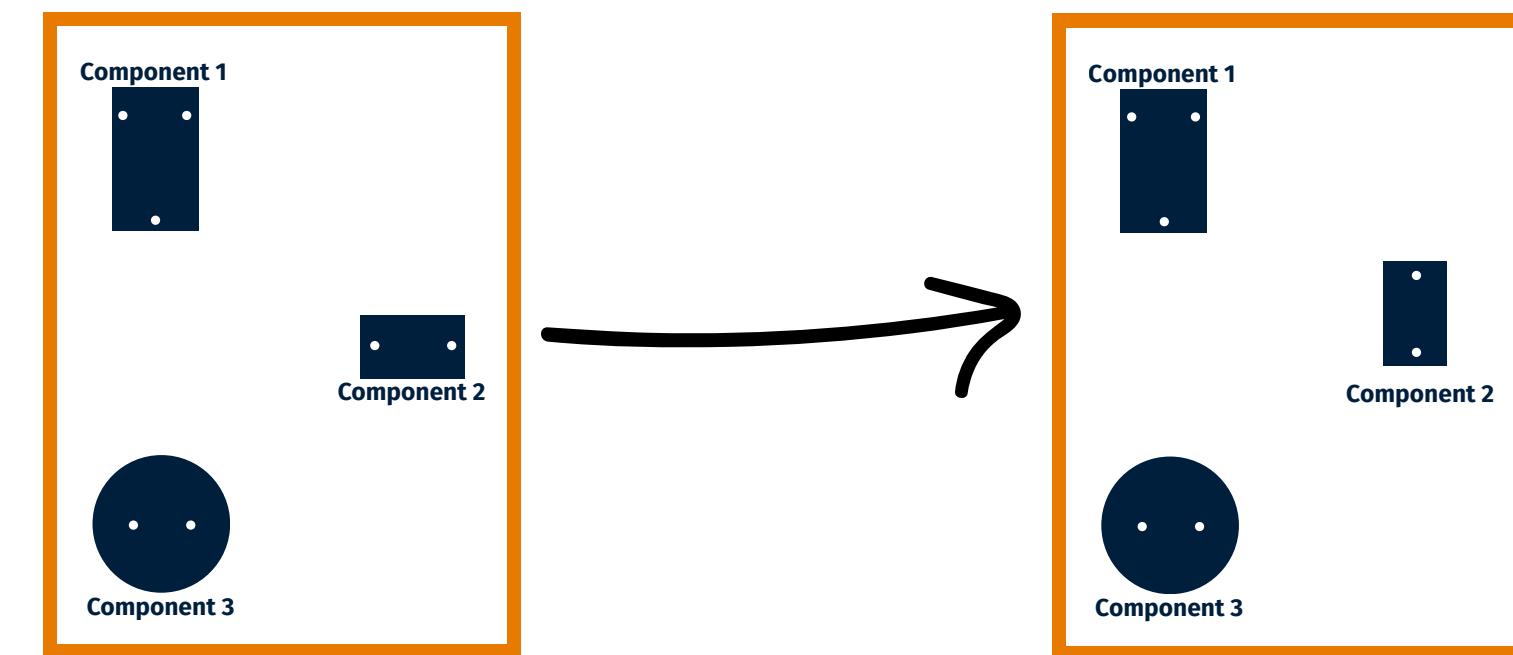
- select a random component
- sample a new random position
- move the component in the new position
- resolve emerged conflicts



Rotation Mutation

The second mutation operator is also characterized by 3 operations:

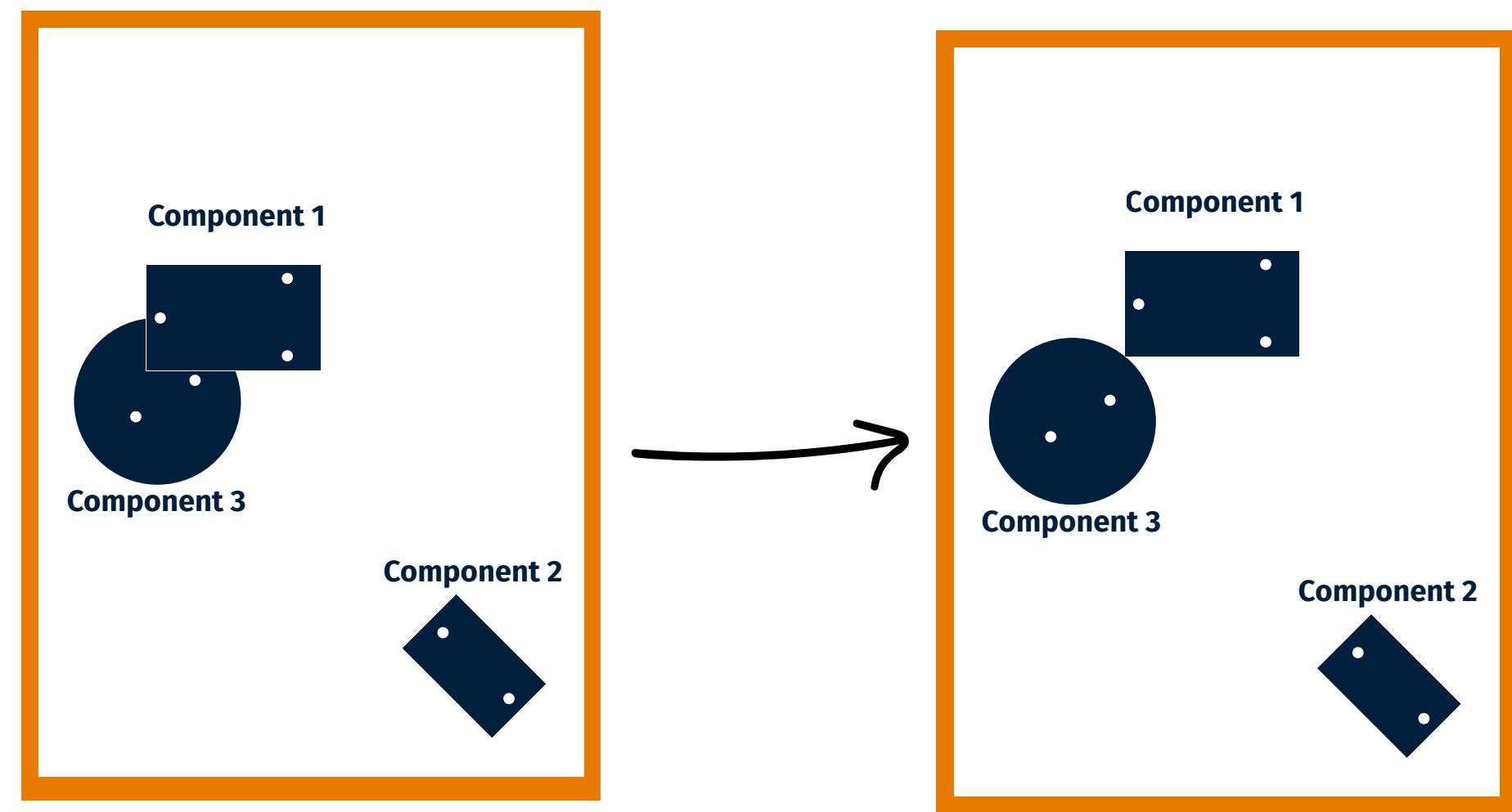
- select a random component
- sample a new angle
- rotate the component
- resolve emerged conflicts



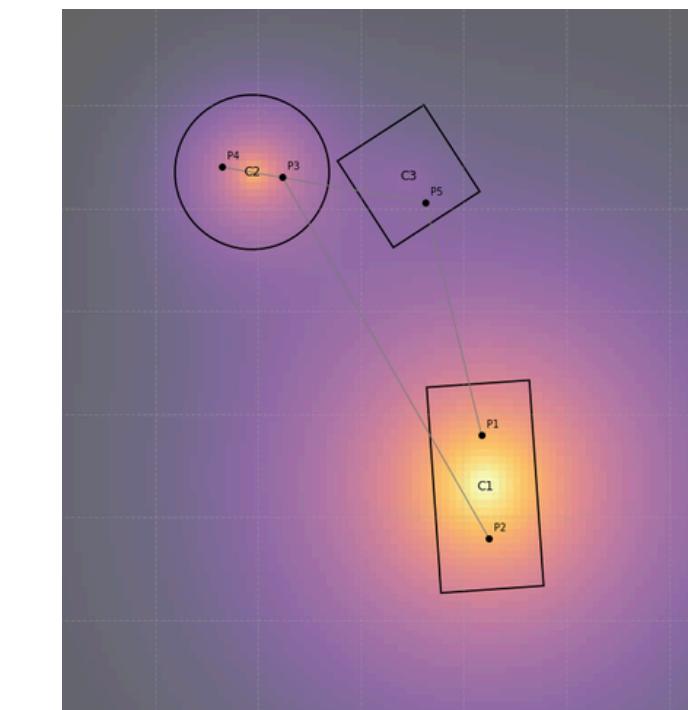
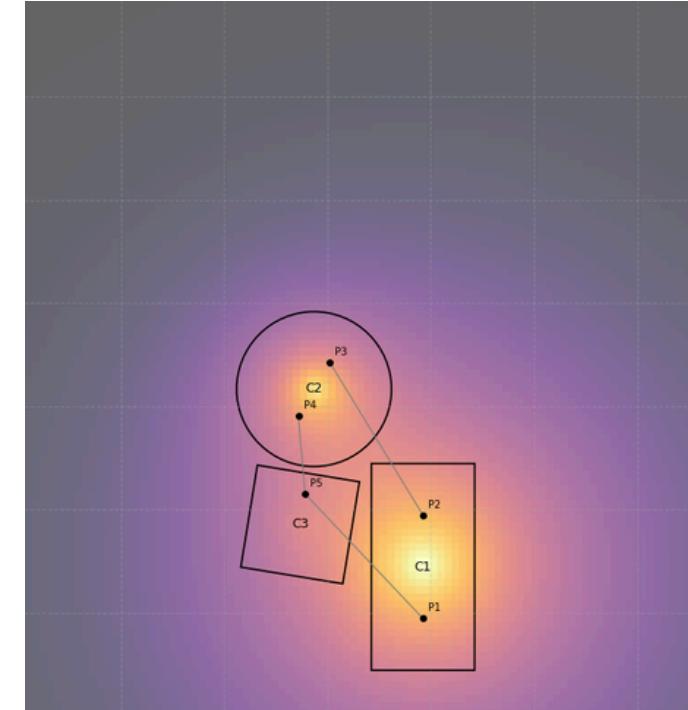
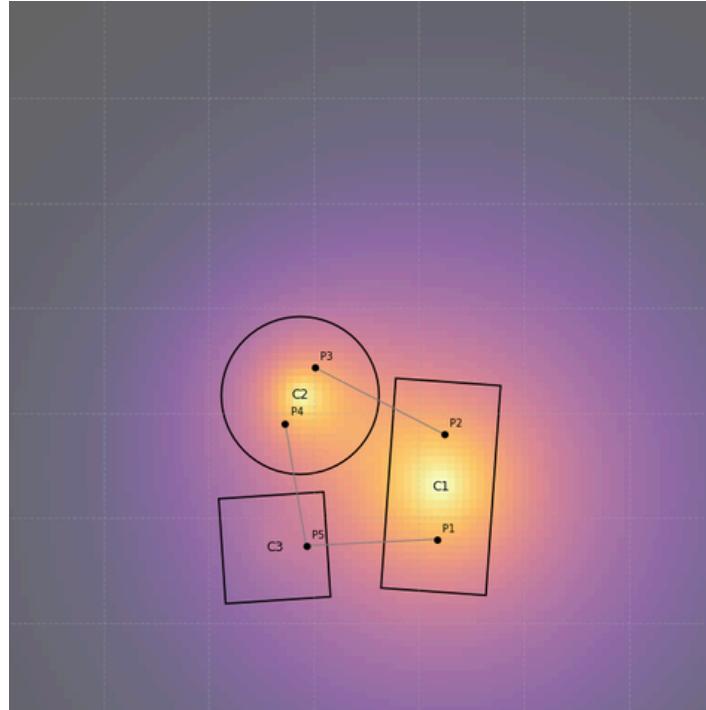
Resolve-conflicts operator

This operator is necessary to **produce valid individuals**. The involved process repeats for a selected number **n** of iterations:

- find all overlaps
- for every overlap:
 - calculate the overlap area
 - $\text{move_distance} = \sqrt{\text{overlap_area}} + 1$
 - move one of the two components in the opposite direction from the other of move_distance
 - (if can't move the component because of boundary conditions, move the other)



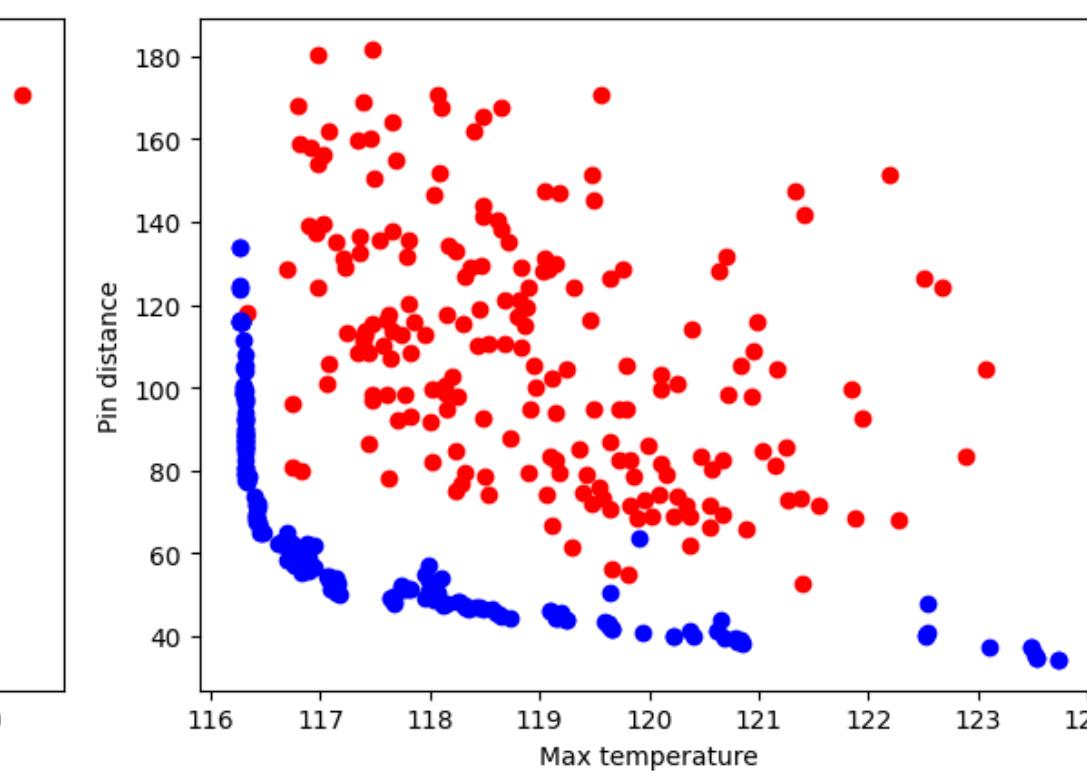
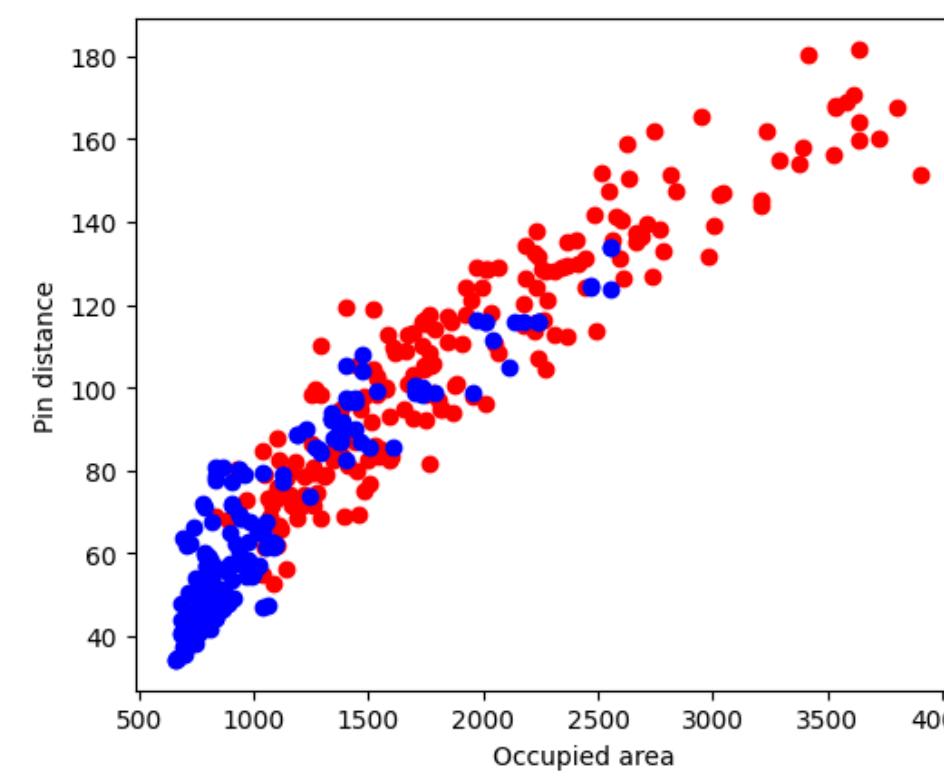
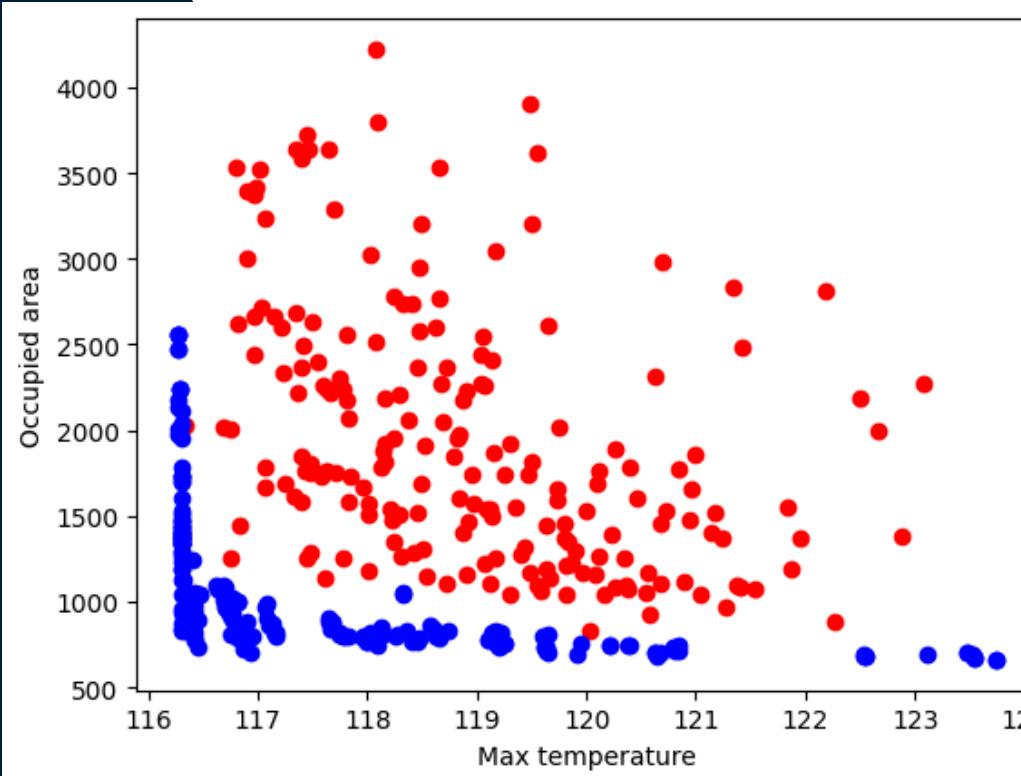
Results



Genetic Algorithm parameters
number_of_generations = 100
population_size = 200

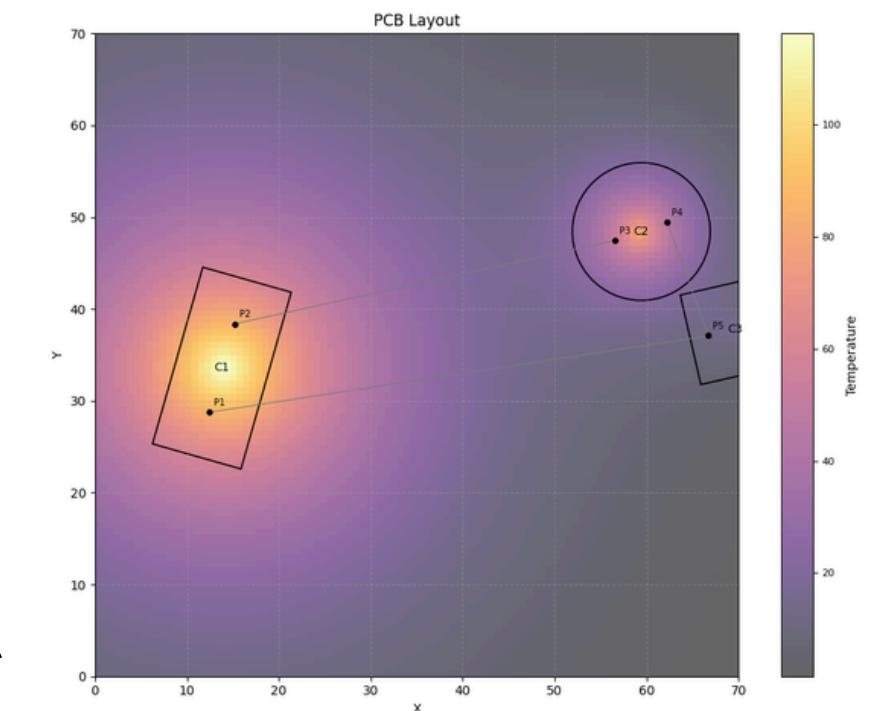
Mutation
rotation_mutation_rate = 0.4
position_mutation_rate = 0.2

Crossover
crossover_rate = 1
components_cross = 1



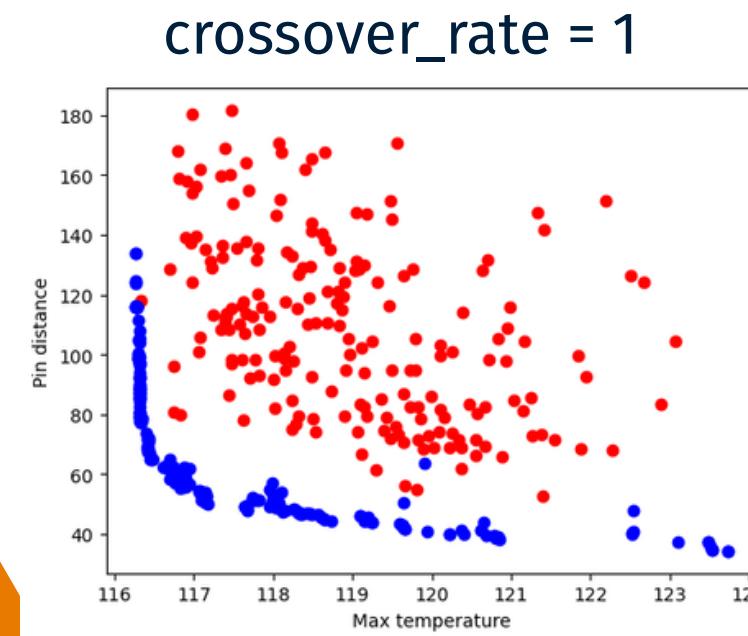
Observations

- By empirical test, it is possible to see how the **crossover helps in maintaining solution diversity**.
- From real-world experience, we know that some solutions on the Pareto front are **impractical, even though they are technically optimal**.
- In real-life problems like this, **objectives can be correlated** between them and share the same type of bounds.

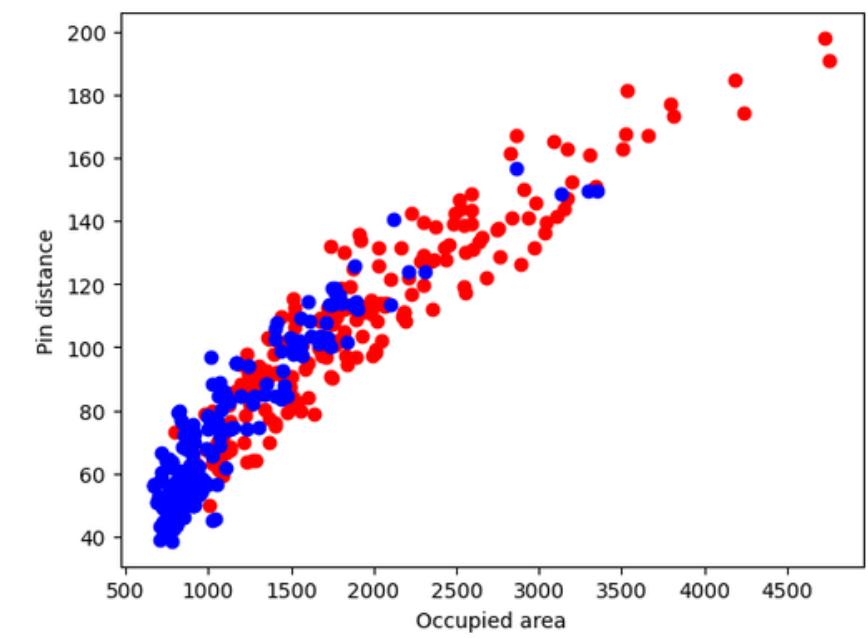
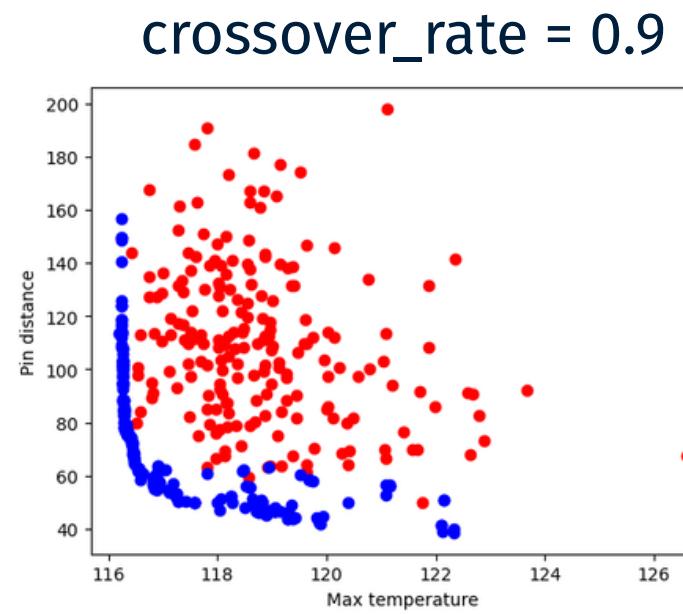


“Good” for temperature but impractical

High correlation between pin distance and occupied area



VS



THE END

Bibliography:

- “A Fast and Elitist Multiobjective Genetic Algorithm: NSGA-II” - Kalyanmoy Deb, Amrit Pratap, Sameer Agarwal, and T. Meyarivan

Implementation:

- https://github.com/LorenzoTonet/PCB_Layout_Optimization/tree/main