

Google Fonts
Google Fonts

opsz 18, wght 650, track -.5

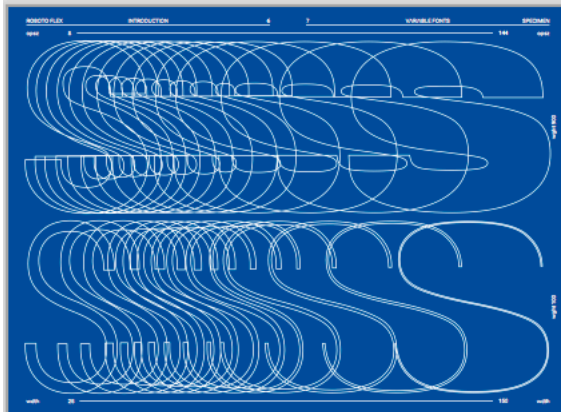
Roboto Flex
Roboto Flex

YTDE YTAS YTUC YTLC YOPQ XOPQ XTRA slnt GRAD width wght opsz

Roboto Flex Specimen Book Review

opsz 18, wght 650, track -.5

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This specimen is published on the release of <i>Moboto Flux</i> , a variable font by Google Fonts with Type Network. Original type design by Christian Robertson, with variable font development by David Marston in Type Network, June 2020.	Introduction	04	Introduction	04	
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[illegible]

I think there is no need to go into parametric space in creative display setting.

ROBOTO FLEX

INTRODUCTION

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VARIABLE DESIGN SPACE

SPECIMEN

VAR

ABLE

DESIGN

SPACE

Roboto Flex designer David Berlow argues the most fundamental quality of type—its optical size—is a function of three attributes: weight, width, and height. Imagine them as a 3D box, but instead of width, length, and height, its dimensions are defined by width, visual weight and height.

These basic attributes—weight, width, and height—are the most

important factors contributing to the color and texture of a page. Which is why optical size is a registered axis: already part of the OpenType specification. (In CSS3.0, axes are denoted by a four-letter code, with optical size being opsz. (Common practice is to put registered axes in lowercase and capitalize others.)

There are five registered axes in OTF: weight, width, optical size, italic, and slant. Of these, Roboto Flex uses four—weight, width, optical size, and slant—plus a fifth that’s a blend of weight and width, called grade (CSS: GRAD). (Grade is also part of Amstelvar. It’s no coincidence Amstelvar and Roboto Flex play well together on the page: these different faces share a common philosophy.)

Sliding along any axis takes you to a different point in this design space—a narrower, taller, or heavier font variation. Because each attribute is a scale, and most axes in Roboto Flex are scaled as thousandths (milles) of an em, its design space contains not a dozen or so instances, but thousands.

Roboto Flex Specimen Book Review

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ROBOTO FLEX

INTRODUCTION

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Rationalizing the Design Space

This is where a key feature of Roboto Flex's approach to variable type comes into play: parametric axes. Axes that work as individuals—but shine as a team.

As you've seen, parametric design treats registered axes as collected sets of other typographic qualities working as a team. For example, a glyph's width is a combination of its stem weight, headline weight, and counter spacing. As you increase a quality like width, you're in effect sliding up the values for these three qualities. This trio of parametric axes are known in CSS as XOPQ, YOPQ, and XTRA.

But parametric design, seeing glyph variations as deltas from the master rather than separately designed glyphs, adds a twist: these axes don't all slide at the same rate. As font size varies—perhaps between an 8pt minima, through the 14pt master, to a 144pt display size—the parametric axes vary in proportion, within a range the designer can modify. The range of an axis doesn't have to use the same minima and maxima as each axis making it up, or even slide in the same direction. Reduce optical size in Roboto Flex, for example, and its component parametric axes—like stem weight and x-height—can rise, to keep characters readable at smaller sizes.

Axes working in concert like this rationalize the design space. Because axes act in proportion to each other, and no iteration of the font looks absurd. It gives the designer extreme control ... without going to extremes.

Like any new technology, parametric typography has a learning curve. But it may not be as steep as

you think. Imagining axes as spatial dimensions is a simple way to start.

An x-y space of two axes is two-dimensional, easy to represent on a page. A box-shaped one including a third axis, z—"into" the page—is only a little harder. This is how to think about variable fonts. Not named glyphs with attributes drawn from a discrete shortlist, but a point in the space defined by their axes.

Of course, beyond three axes, visual representation is impossible. But while it's impossible to draw more than three spatial dimensions, it's perfectly possible to imagine them conceptually. And thinking of the design-variable space conceptually is key to understanding the potential of variable typography.

The design-variable space of Roboto Flex comprises twelve axes, five registered and seven parametric. In the OpenType spec, they're denoted in CSS by four-letter abbreviations. The registered axes are wght (weight), wdth (width), ital (italic), slnt (slant), and opsz (optical size). Roboto Flex doesn't use ital, and it adds one axis that's a blend from wght and wdth, grade, or GRAD. The parametric axes that combine within these registered axes are XOPQ (stem weight), YOPQ (headline weight), XTRA (counter width), YTAB (lowercase ascender height), YTDE (lowercase descender height), YTLC (x-height), and YTUC (uppercase height).

What's more, parametric design is based on techniques and technology familiar to any designer. Glyph masters, font tables, CSS terminology.

Even a single axis—such as weight—defines a design space, albeit of one dimension. But combining axes is how the opportunities of variable typography expand.

Taking it up just one dimension adds great depth and potential to the design space. Imagining weight as the x-axis, adding width as the y creates a space where the designer controls both: grade. A space where glyph width can stay constant while weight increases. Or vice versa.

Of course, an untrammelled design-variable space allows absurd extremes. A set of axes acting alone make for a free-for-all. What if type designers could select factors like weight and width in combination, as blended qualities like grade ... and individually, as the subtle sets of qualities making them up?

Standard font family design space

Variable font design space

ROBOTO FLEX

AXES

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THE 12 AXES

SPECIMEN

Axes

opsz	XTRA
wght	XOPQ
wdth	YOPQ
GRAD	YTLC
slnt	YTUC
	YTAB
	YTDE

USER AXES

PARAMETRIC AXES

I think there is a good reason to show the range of the parametric axes here.

ROBOTO FLEX		AXES	16
<p>Roboto Flex uses a set of 12 axes. So this book is organized the same way. First the five registered axes common to the OpenType Specification and CSS3.0, Then the seven “parametric” axes fundamental to Flex.</p> <p>As you journey through this book, you’ll see how each axis affects a glyph in isolation – but you’ll also see how different axes work as a team, with sensible maxima and minima on one curtailing the risk of absurd extremes on another. It’s an approach to variable typography that keeps all the moving parts connected and in proportion with each other.</p> <p>What this means is there’s an answer to your typographical challenge somewhere in the design space, waiting for you to discover it. Whatever that challenge is. The axes may be constrained. But the choices they enable are limitless.</p>			
<p>opsz blends stem weight, hairline weight, counter width, and x-height as optical size. Its scale is based on familiar point sizes, from 8pt to 144pt, to allow for a huge range of styles.</p>	opsz 8 – 144	BBbb	opsz
<p>The wght registered axis controls overall glyph weight, ranging from 100 to 900 thousandths of an em. It’s the axis instantly familiar to anyone with even a passing interest in type.</p>	wght 100 – 900	BBbb	wght
<p>The wdth axis controls glyph width, within a range that lets the designer tune to fit line measure or type size without allowing absurdly wide characters.</p>	wdth 25 – 151	BBbb	wdth
<p>GRAD is a blended axis: weight and width acting in concert. It allows weight to rise without increasing width—leading to a range of different visual impressions on the page at different sizes.</p>	GRAD -1 – 1	BBbb	GRAD
<p>slnt allows the designer to fine-tune visual verticality. A narrow range of values (scaled in units roughly equivalent to degrees, from -10 to 0) offers a wide range of italic-style type without the</p>	slnt 0 – 10	BBbb	slnt
		THE 12 AXES	
		SPECIMEN	
<p>The XTRA axis controls counter width, enabling precise justification. Its range is .323 to .603 of an em.</p>	XTRA 323 – 603	BBbb	
<p>XOPQ is the axis for stem stroke weight, ranging from 27 to 175 milles of an em.</p>	XOPQ 27 – 175	BBbb	
<p>YOPQ does the same for hairline stroke weight, with a range of 25 to 135. Minima and maxima prevent hairlines from disappearing at 8pt and below.</p>	YOPQ 25 – 135	BBbb	
<p>YTLC covers x-height, and its range is from 416 to 570 milles of an em. It lets the designer increase lowercase height to levels that keep type readable even at tiny sizes.</p>	YTLC 416 – 570	BBbb	XTRA
<p>YTUC deals with the height of uppercase glyphs, with extremes of 528 and 760. Again, visual size of small text is the main benefit.</p>	YTUC 528 – 760	BBbb	XOPQ
<p>The YTAS axis sets the height of lowercase ascenders, from 649 to 854.</p>	YTAS 649 – 854	BBbb	YOPQ
<p>YTDE sets the depth of lowercase descenders below the x-height, with values -305 to -98. Note the scale is negative.</p>	YTDE -305 – -98	PPpp	YTLC
			YTUC
			YTAS
			YTDE

?
Why is this here?

redo
48-49

