

MCD4710

Introduction to algorithms
and programming

Lecture 18

Gaussian Elimination

COMMONWEALTH OF AUSTRALIA

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Overview

- Represent problem as system of **linear equations**
- Represent linear system in **matrix/vector form**
- Apply and implement **backward substitution** to solve upper-triangular systems
- Apply and implement **forward elimination** to transform general system into triangular form

Linear systems of equations

Some Chemistry



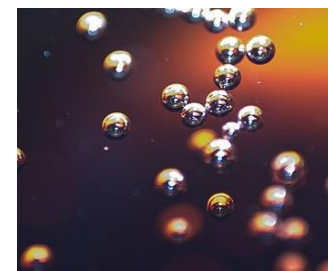
ferric oxide
 Fe_2O_3



carbon
 C



iron
 Fe



carbon dioxide
 CO_2

Some Chemistry



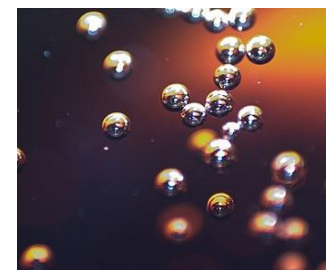
ferric oxide



carbon



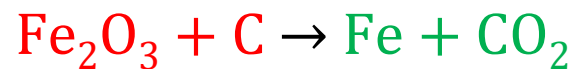
iron



carbon dioxide



Chemical notation



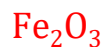
reactants

products

Some Chemistry



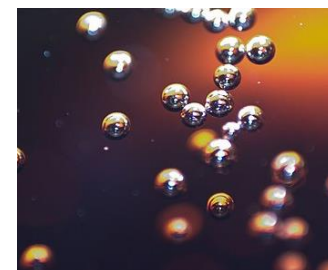
ferric oxide



carbon



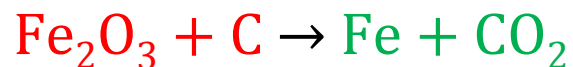
iron



carbon dioxide



Chemical notation



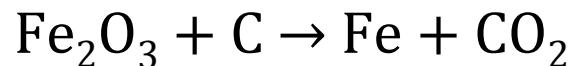
Count atoms

Atom	Reactants	Products
Fe	2	1
O	3	2
C	1	1

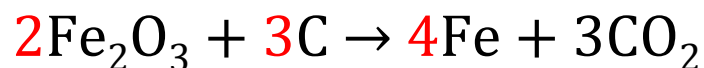
Numbers
don't add
up!

Want to *balance* chemical equation

Unbalanced equation



Balanced equation

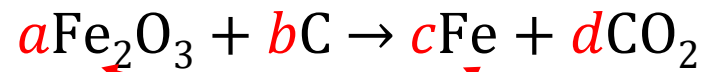


Count atoms

Atom	Reactants	Products
Fe	4	4
O	6	6
C	3	3

Let's balance equation *algorithmically*

General equation



Conditions on solution

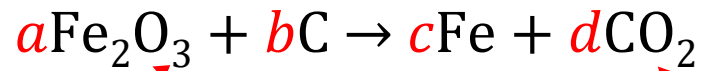
$$2a = c$$

(Fe)



Let's balance equation *algorithmically*

General equation



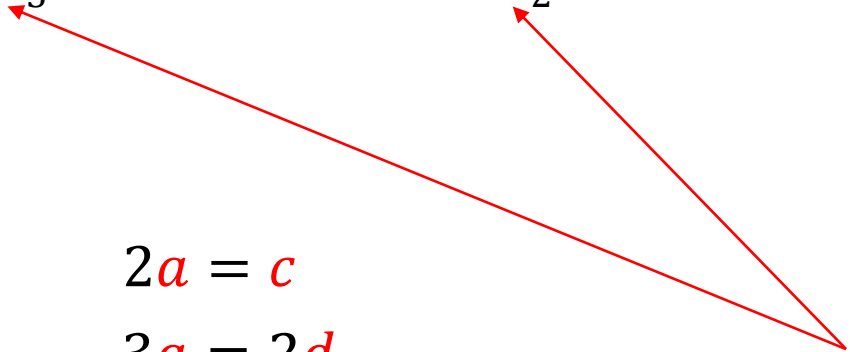
Conditions on solution

$$2a = c$$

$$3a = 2d$$

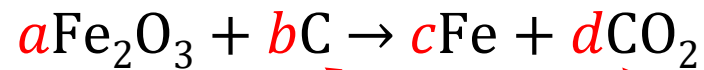
(Fe)

(O)



Let's balance equation *algorithmically*

General equation

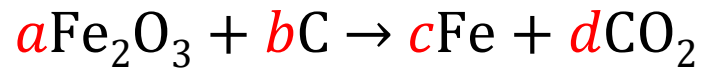


Conditions on solution

$$\begin{aligned} 2a &= c && \text{(Fe)} \\ 3a &= 2d && \text{(O)} \\ b &= d && \text{(C)} \end{aligned}$$


Let's balance equation *algorithmically*

General equation



Conditions on solution

$$2a = c \quad (\text{Fe})$$

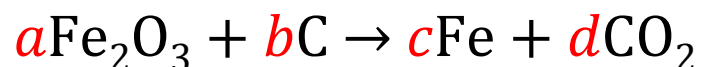
$$3a = 2d \quad (\text{O})$$

$$b = d \quad (\text{C})$$

Does that uniquely **determine** solution?

Let's balance equation *algorithmically*

General equation

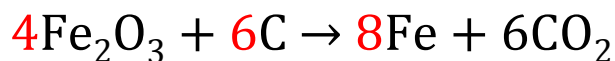


Conditions on solution

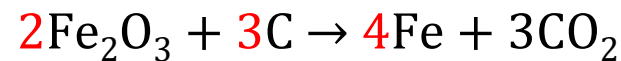
$$2a = c \quad (\text{Fe})$$

$$3a = 2d \quad (\text{O})$$

$$b = d \quad (\text{C})$$



Atom	Reactants	Products
Fe	8	8
O	12	12
C	6	6

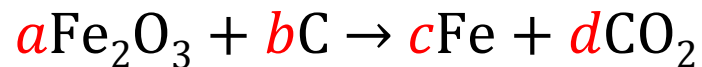


Atom	Reactants	Products
Fe	4	4
O	6	6
C	3	3

← double quantities

Let's balance equation *algorithmically*

General equation



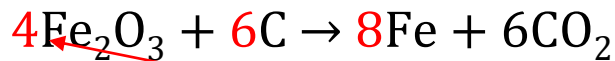
Conditions on solution

$$2a = c \quad (\text{Fe})$$

$$3a = 2d \quad (\text{O})$$

$$b = d \quad (\text{C})$$

$$a = 4$$



Atom	Reactants	Products
Fe	8	8
O	12	12
C	6	6

Fix quantities to
fully determine
solution

Reached a very general problem

Solve Linear Systems

Input: Set of n linear equations in n variables

Output: Assignment of values to variables satisfying all equations

How to **represent** this problem in Python?

Finding systematic representation

Solve Linear Systems

Input: Set of n linear equations in n variables

Output: Assignment of values to variables satisfying all equations

$$\begin{array}{lcl}
 2a = c & & 2a - c = 0 \\
 3a = 2d & \longrightarrow & 3a - 2d = 0 \\
 b = d & & b - d = 0 \\
 a = 4 & & a = 4
 \end{array}
 \longrightarrow
 \begin{array}{l}
 2a + 0b - 1c + 0d = 0 \\
 3a + 0b + 0c - 2d = 0 \\
 0a + 1b + 0c - 1d = 0 \\
 1a + 0b + 0c + 0d = 4
 \end{array}$$

coefficient matrix A \longrightarrow

$$\begin{bmatrix} 2 & 0 & -1 & 0 \\ 3 & 0 & 0 & -2 \\ 0 & 1 & 0 & -1 \\ 1 & 0 & 0 & 0 \end{bmatrix}
 \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix}
 =
 \begin{bmatrix} 0 \\ 0 \\ 0 \\ 4 \end{bmatrix}$$

\longleftarrow right hand side b

\longleftarrow solution vector x

Finding systematic representation

Solve Linear Systems

Input: $n \times n$ -matrix A of coefficients, n -dim vector b

Output: n -dim vector x such that $Ax = b$

Python table

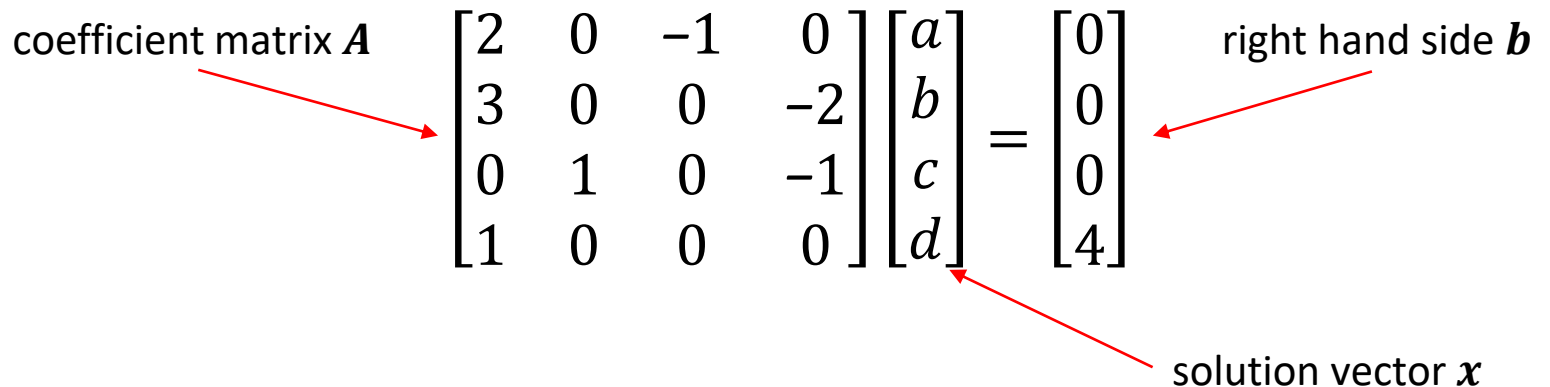
Python list

coefficient matrix A

$$\begin{bmatrix} 2 & 0 & -1 & 0 \\ 3 & 0 & 0 & -2 \\ 0 & 1 & 0 & -1 \\ 1 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 4 \end{bmatrix}$$

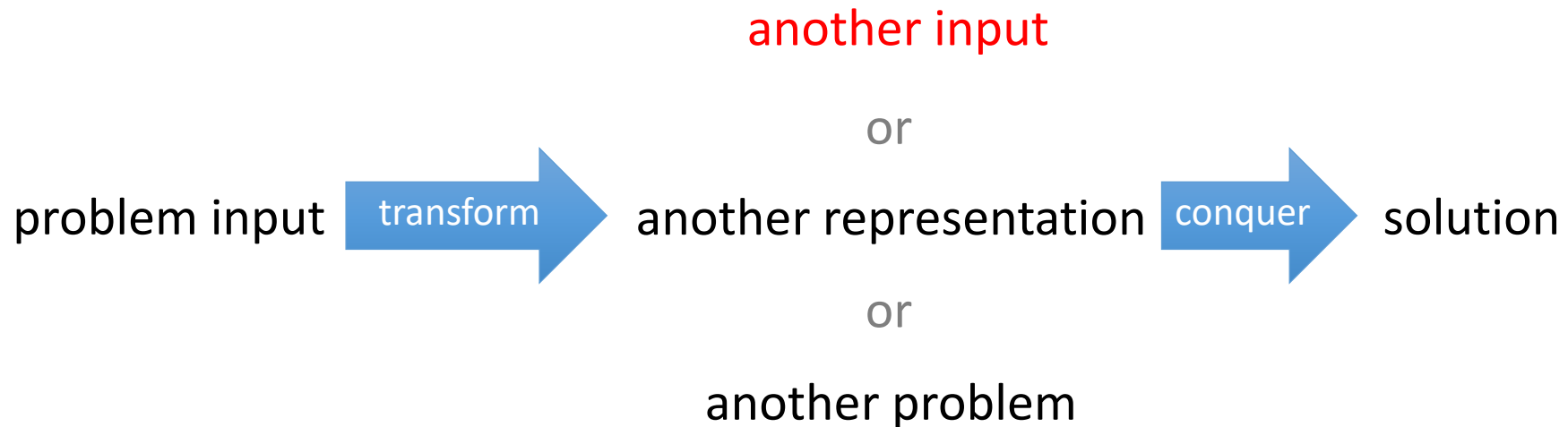
right hand side b

solution vector x



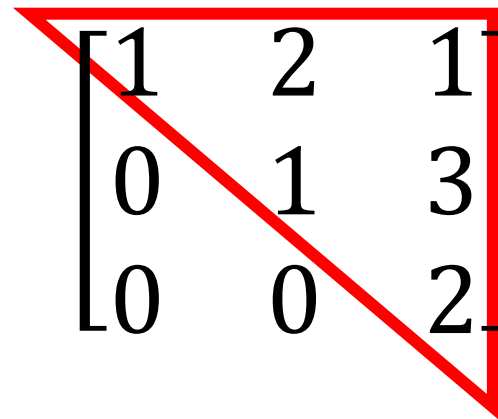
Simple case: triangular system

Overall strategy: Transform and Conquer Paradigm



What are **easy to solve** linear systems?

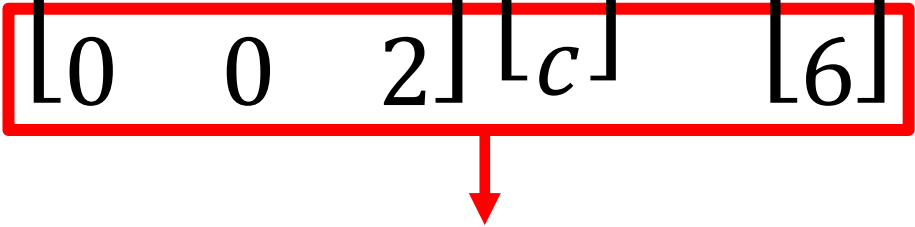
(Upper) triangular systems



$$\begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 3 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 2 \\ 7 \\ 6 \end{bmatrix}$$

called *upper triangular*,
because only coefficients in
main diagonal and above
are non-zero

How can we solve such a system?

Back-substitution algorithm

$$\begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 3 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 2 \\ 7 \\ 6 \end{bmatrix}$$


$$2c = 6$$


$$c = 6/2$$

Back-substitution algorithm

$$\begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 3 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} a \\ b \\ 3 \end{bmatrix} = \begin{bmatrix} 2 \\ 7 \\ 6 \end{bmatrix}$$

$$b + 3c = 7$$

$$b = 7 - 9$$

Back-substitution algorithm

$$\begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 3 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} a \\ -2 \\ 3 \end{bmatrix} = \begin{bmatrix} 2 \\ 7 \\ 6 \end{bmatrix}$$

$$\begin{aligned} a + 2b + c \\ = 2 \end{aligned}$$

$$a = 2 + 4 - 3$$

Back-substitution algorithm

$$\begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 3 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} 3 \\ -2 \\ 3 \end{bmatrix} = \begin{bmatrix} 2 \\ 7 \\ 6 \end{bmatrix}$$

Back-substitution in general

$$\begin{bmatrix} u_{0,0} & u_{0,1} & u_{0,2} & u_{0,3} \\ 0 & u_{1,1} & u_{1,2} & u_{1,3} \\ 0 & 0 & u_{2,2} & u_{2,3} \\ 0 & 0 & 0 & u_{3,3} \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_0 \\ b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

```
def solve_by_back_sub(u,b):  
    n = len(b)  
    x = n*[0]  
    for i in range(n-1, -1, -1):  
        # find value x[i]  
  
    return x
```

Back-substitution algorithm

$$\begin{bmatrix} u_{0,0} & u_{0,1} & u_{0,2} & u_{0,3} \\ 0 & u_{1,1} & u_{1,2} & u_{1,3} \\ 0 & 0 & u_{2,2} & u_{2,3} \\ 0 & 0 & 0 & u_{3,3} \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_0 \\ b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

$u_{i,i}x_i + \underbrace{(u_{i,i+1}x_{i+1} + \dots + u_{i,n-1}x_{n-1})}_s = b_i$

$x_i = (b_i - s)/u_{i,i}$

```
def solve_by_back_sub(u,b):
    n = len(b)
    x = n*[0]
    for i in range(n-1, -1, -1):
        # find value x[i]

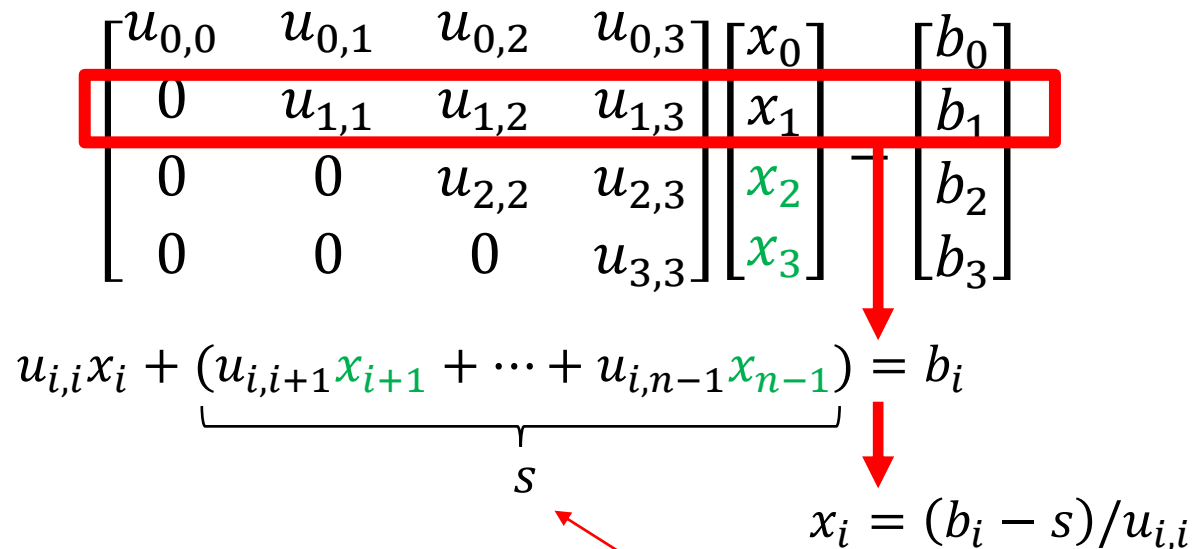
    return x
```

Back-substitution algorithm

$$\begin{bmatrix} u_{0,0} & u_{0,1} & u_{0,2} & u_{0,3} \\ 0 & u_{1,1} & u_{1,2} & u_{1,3} \\ 0 & 0 & u_{2,2} & u_{2,3} \\ 0 & 0 & 0 & u_{3,3} \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_0 \\ b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

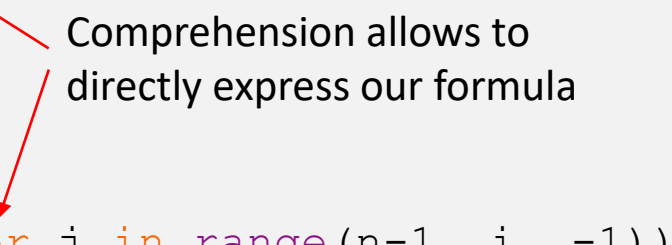
$u_{i,i}x_i + \underbrace{(u_{i,i+1}x_{i+1} + \dots + u_{i,n-1}x_{n-1})}_s = b_i$

$x_i = (b_i - s) / u_{i,i}$



```
def solve_by_back_sub(u, b):
    n = len(b)
    x = n * [0]
    for i in range(n-1, -1, -1):
        s = sum(x[j] * u[i][j] for j in range(n-1, i, -1))
        x[i] = (b[i] - s) / u[i][i]
    return x
```

Comprehension allows to directly express our formula



Back-substitution algorithm

```
def solve_by_back_sub(u,b):
    n = len(b)
    x = n*[0]
    for i in range(n-1, -1, -1):
        s = 0
        for j in range(n-1, i, -1):
            s += u[i][j] * x[j]
        x[i] = (b[i] - s)/u[i][i]
    return x
```

$$u_{i,i}x_i + \underbrace{(u_{i,i+1}x_{i+1} + \cdots + u_{i,n-1}x_{n-1})}_s = b_i$$

for-loop versus
comprehension

```
def solve_by_back_sub(u,b):
    n = len(b)
    x = n*[0]
    for i in range(n-1, -1, -1):
        s = sum(x[j] * u[i][j] for j in range(n-1, i, -1))
        x[i] = (b[i] - s)/u[i][i]
    return x
```

Gaussian Elimination



Carl Friedrich Gauß
1777– 1855

general system

$$\begin{bmatrix} 1 & 2 & 1 \\ -5 & -9 & -2 \\ 2 & 3 & 1 \end{bmatrix}, \begin{bmatrix} 2 \\ -3 \\ 3 \end{bmatrix}$$

transform

forward
elimination

triangular system

$$\begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 3 \\ 0 & 0 & 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 7 \\ 6 \end{bmatrix}$$

conquer

back
substitution

$$\begin{bmatrix} 3 \\ 2 \\ 3 \end{bmatrix}$$

How to *eliminate* coefficients?

$$a + 2b + c = 2$$

$$-5a - 9b - 2c = -3$$



$$-4a - 7b - c = -1$$

Observation:

Given equations **imply** (infinitely) many **other equations**

How to *eliminate* coefficients?

$$\begin{aligned}a + 2b + c &= 2 \\ -5a - 9b - 2c &= -3\end{aligned}$$



$$b - 3c = 7$$

adding 5 times first
equation to second
yields equations where a-
coefficient is *eliminated*

Observation:

Given equations **imply** (infinitely) many **other equations**

How to *eliminate* coefficients?

$$a + 2b + c = 2$$

$$-5a - 9b - 2c = -3$$

$$2a + 3b + c = 3$$

$\Downarrow \quad \Uparrow$

 Simpler system but same solutions

$$a + 2b + c = 2$$

$$b - 3c = 7$$

$$2a + 3b + c = 3$$

Observation:

Given equations **imply** (infinitely) many **other equations**

How to *eliminate* coefficients?

$$\begin{aligned} a + 2b + c &= 2 \\ -5a - 9b - 2c &= -3 \\ 2a + 3b + c &= 3 \end{aligned}$$

↓ ↑

$$\begin{aligned} a + 2b + c &= 2 \\ b - 3c &= 7 \\ 2a + 3b + c &= 3 \end{aligned}$$

$$\begin{bmatrix} 1 & 2 & 1 \\ -5 & -9 & -2 \\ 2 & 3 & 1 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 2 \\ -3 \\ 3 \end{bmatrix}$$

↓ ↑

$$\begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & -3 \\ 2 & 3 & 1 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 2 \\ 7 \\ 3 \end{bmatrix}$$

Observations:

- Solution *invariant* when adding multiple of row to another
- Exploit to get simpler but equivalent system

Iteratively eliminate below diagonal coefficients

simplify column 1

$$\begin{bmatrix} 1 & 2 & 1 \\ -5 & -9 & -2 \\ 2 & 3 & 1 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 2 \\ -3 \\ 3 \end{bmatrix}$$



$$\begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 3 \\ 2 & 3 & 1 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 2 \\ 7 \\ 3 \end{bmatrix}$$



$$\begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 3 \\ 0 & -1 & -1 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 2 \\ 7 \\ -1 \end{bmatrix}$$

simplify column 2

$$\begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 3 \\ 0 & -1 & -1 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 2 \\ 7 \\ -1 \end{bmatrix}$$



$$\begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 3 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 2 \\ 7 \\ 6 \end{bmatrix}$$

General forward elimination

$$\begin{bmatrix} a_{0,0} & a_{0,1} & a_{0,2} & a_{0,3} \\ 0 & a_{1,1} & a_{1,2} & a_{1,3} \\ 0 & a_{2,1} & a_{2,2} & a_{2,3} \\ 0 & a_{3,1} & a_{3,2} & a_{3,3} \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_0 \\ b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

Subtract q times
pivot row j from row i

How to choose q such that $a_{i,j}$ will be eliminated?

```
def triangular(a, b):
    n = len(a)
    for j in range(n):
        for i in range(j + 1, n):
            # eliminate entry a[i][j]

    return a, b
```

General forward elimination

$$\begin{bmatrix} a_{0,0} & a_{0,1} & a_{0,2} & a_{0,3} \\ 0 & a_{1,1} & a_{1,2} & a_{1,3} \\ 0 & a_{2,1} & a_{2,2} & a_{2,3} \\ 0 & a_{3,1} & a_{3,2} & a_{3,3} \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_0 \\ b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

Subtract q times
pivot row j from row i
 $q = a_{i,j}/a_{j,j}$

$$\begin{bmatrix} a_{0,0} & a_{0,1} & a_{0,2} & a_{0,3} \\ 0 & a_{1,1} & a_{1,2} & a_{1,3} \\ 0 & 0 & a_{2,2} - qa_{1,2} & a_{2,3} - qa_{1,3} \\ 0 & a_{3,1} & a_{3,2} & a_{3,3} \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_0 \\ b_1 \\ b_2 - qb_1 \\ b_3 \end{bmatrix}$$

```
def triangular(a, b):
    n = len(a)
    for j in range(n):
        for i in range(j + 1, n):
            # eliminate entry a[i][j]
```

$$a_{i,m} - a_{j,m} \frac{a_{i,j}}{a_{j,j}}$$

$$a_{i,j} - a_{j,j} \frac{a_{i,j}}{a_{j,j}} = 0$$

```
    return a, b
```

General forward elimination

$$\begin{bmatrix} a_{0,0} & a_{0,1} & a_{0,2} & a_{0,3} \\ 0 & a_{1,1} & a_{1,2} & a_{1,3} \\ 0 & a_{2,1} & a_{2,2} & a_{2,3} \\ 0 & a_{3,1} & a_{3,2} & a_{3,3} \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_0 \\ b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

Subtract q times
pivot row j from row i

$$q = a_{i,j}/a_{j,j}$$

$$\begin{bmatrix} a_{0,0} & a_{0,1} & a_{0,2} & a_{0,3} \\ 0 & a_{1,1} & a_{1,2} & a_{1,3} \\ 0 & 0 & a_{2,2} - qa_{1,2} & a_{2,3} - qa_{1,3} \\ 0 & a_{3,1} & a_{3,2} & a_{3,3} \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_0 \\ b_1 \\ b_2 - qb_1 \\ b_3 \end{bmatrix}$$

```
def triangular(a, b):
    n = len(a)
    for j in range(n):
        for i in range(j + 1, n):
            q = a[i][j] / a[j][j]
            # subtract q*a[j] from a[i]
            # subtract q*b[j] from b[j]
    return a, b
```

General forward elimination

$$\begin{bmatrix} a_{0,0} & a_{0,1} & a_{0,2} & a_{0,3} \\ 0 & a_{1,1} & a_{1,2} & a_{1,3} \\ 0 & a_{2,1} & a_{2,2} & a_{2,3} \\ 0 & a_{3,1} & a_{3,2} & a_{3,3} \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_0 \\ b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

Subtract q times
pivot row j from row i

$$q = a_{i,j}/a_{j,j}$$

$$\begin{bmatrix} a_{0,0} & a_{0,1} & a_{0,2} & a_{0,3} \\ 0 & a_{1,1} & a_{1,2} & a_{1,3} \\ 0 & 0 & a_{2,2} - qa_{1,2} & a_{2,3} - qa_{1,3} \\ 0 & a_{3,1} & a_{3,2} & a_{3,3} \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_0 \\ b_1 \\ b_2 - qb_1 \\ b_3 \end{bmatrix}$$

```
def triangular(a, b):
    n = len(a)
    for j in range(n):
        for i in range(j + 1, n):
            q = a[i][j] / a[j][j]
            a[i] = [a[i][m] - q*a[j][m] for m in range(n)]
            b[i] = b[i] - q*b[j]
    return a, b
```

One technical problem remains

$$\begin{bmatrix} 1 & 1 & 0 & 1 \\ -1 & -1 & 1 & 0 \\ 2 & 3 & -1 & 1 \\ -1 & 2 & -2 & 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 1 & -1 & -1 \\ 0 & 3 & -2 & 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ -2 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 0 & 1 \\ 0 & 1 & -1 & -1 \\ 0 & 0 & 1 & 1 \\ 0 & 3 & -2 & 2 \end{bmatrix}, \begin{bmatrix} 1 \\ -2 \\ 1 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 0 & 1 \\ 0 & 1 & -1 & -1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 5 \end{bmatrix}, \begin{bmatrix} 1 \\ -2 \\ 1 \\ 7 \end{bmatrix}$$

```
def triangular(a, b):
    n = len(a)
    for j in range(n):
        for i in range(j + 1, n):
            q = a[i][j] / a[j][j]
            a[i] = [a[i][m] - q*a[j][m] for m in range(n)]
            b[i] = b[i] - q*b[j]
    return a, b
```

Can always flip equations;
their order doesn't matter

Need to find pivot row

$$\begin{bmatrix} 1 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 1 & -1 & -1 \\ 0 & 3 & -2 & 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ -2 \\ 1 \end{bmatrix} \Leftrightarrow \begin{bmatrix} 1 & 1 & 0 & 1 \\ 0 & 1 & -1 & -1 \\ 0 & 0 & 1 & 1 \\ 0 & 3 & -2 & 2 \end{bmatrix}, \begin{bmatrix} 1 \\ -2 \\ 1 \\ 1 \end{bmatrix}$$

```
def triangular(a, b):  
    n = len(a)  
    for j in range(n):  
        # find index k of valid pivot row  
        # swap row j and k of system  
  
        for i in range(j + 1, n):  
            q = a[i][j] / a[j][j]  
            a[i] = [a[i][m] - q*a[j][m] for m in range(n)]  
            b[i] = b[i] - q*b[j]  
    return a, b
```


Need to find pivot row

$$\begin{bmatrix} 1 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 1 & -1 & -1 \\ 0 & 3 & -2 & 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ -2 \\ 1 \end{bmatrix} \Leftrightarrow \begin{bmatrix} 1 & 1 & 0 & 1 \\ 0 & 1 & -1 & -1 \\ 0 & 0 & 1 & 1 \\ 0 & 3 & -2 & 2 \end{bmatrix}, \begin{bmatrix} 1 \\ -2 \\ 1 \\ 1 \end{bmatrix}$$

Assuming a non-zero pivot exists

```
def triangular(a, b):
    n = len(a)
    for j in range(n):
        k = pivot_index(a, j)
        a[j], a[k] = a[k], a[j]
        b[j], b[k] = b[k], b[j]
        for i in range(j + 1, len(a)):
            q = a[i][j] / a[j][j]
            a[i] = [a[i][m] - q*a[j][m] for m in range(n)]
            b[i] = b[i] - q*b[j]
    return a, b
```

```
def pivot_index(a, j):
    max_abs = abs(a[j][j])
    pindex = j
    for i in range(j+1, len(a)):
        if max_abs < abs(a[i][j]):
            pindex = i
    return pindex
```

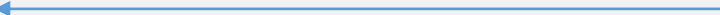

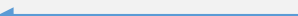
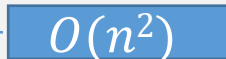
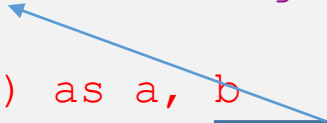
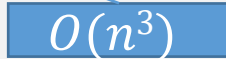
Finishing touches

```
def solve_gauss_elim(a, b):  
    u, c = triangular(a, b)  
    return solve_backsub(u, c)
```

```
def triangular(a, b):  
    u, c = deepcopy(a), deepcopy(b)  ← Operate on copies  
    n = len(u)                        ← to not destroy  
    for j in range(n):                input  
        k = pivot_index(u, j)  
        u[j], u[k] = u[k], u[j]  
        c[j], c[k] = c[k], c[j]  
        for i in range(j + 1, len(a)):  
            q = u[i][j] / u[j][j]  
            u[i] = [u[i][m] - q*u[j][m] for m in range(n)]  
            c[i] = c[i] - q*c[j]  
    return u, c
```

Brief analysis

```
def solve_gauss_elim(a, b):  
    u, c = triangular(a, b)  
    return solve_backsub(u, c)
```

```
def triangular(a, b):  
    u, c = deepcopy(a), deepcopy(b)  
    n = len(u)  
    for j in range(n):    
        k = pivot_index(u, j)  
        u[j], u[k] = u[k], u[j]  
        c[j], c[k] = c[k], c[j]  
        for i in range(j + 1, len(a)):    
            q = u[i][j] / u[j][j]  
            u[i] = [u[i][m] - q*u[j][m] for m in range(n)]  
            c[i] = c[i] - q*c[j]  
               
            #INV: u, c has same solution(s) as a, b  
    return u, c
```

What is the transform step in Gaussian elimination?

- A. Forward elimination
- B. Backward elimination
- C. Forward substitution
- D. Back substitution

1. Visit <https://flux.qa>
2. Log in using your Authcate details (not required if you're already logged in to Monash)
3. Touch the + symbol and enter the code: HHYBXU
4. Answer questions when they pop up.

What is the conquer step in Gaussian elimination?

- A. Forward elimination
- B. Backward elimination
- C. Forward substitution
- D. Back substitution

1. Visit <https://flux.qa>
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4. Answer questions when they pop up.

Summary

- Systems of linear equations can represent real-world problems with linear dependencies between variables
- Triangular systems can be solved by back-substitution
- General systems (with unique solution) can be transformed into triangular form via forward elimination
- Overall cubic $O(n^3)$ complexity

Important further questions

- What if we can't find a pivot index?
- What if we have more unknowns than equations?
- What if we have more equations than unknowns?
- What if there is more than one solution?
- What if there is no solution?

Recommended reading

- Levitin, 6.2, Gaussian Elimination, p. 208
- Gilbert Strang, Textbook: Linear Algebra and its Applications

Coming Up

- Combinatorial Optimisation
- Greedy, Brute-force, and Backtracking