#### PROJECT 2: BINARY SIGNAL RECOVERY

**Abstract.** The scope of the present project is to illustrate how to recover a binary signal from noisy observations using Markov Chain Monte Carlo techniques.

## Binary signal recovery via maximum likelihood estimate

Let  $X \in \mathbb{R}^{m \times d}$  be a random sensing matrix with i.i.d. entries sampled from N(0,1). Let  $\xi \in \mathbb{R}^m$  be a noise vector, independent of X, with i.i.d. entries sampled from N(0,1).

Take  $\Theta = \{0,1\}^d$  (signal space) and let  $\theta \in \Theta$  (signal) be chosen uniformly at random and be independent of the pair  $(X,\xi)$ .

The measurement vector  $y \in \mathbb{R}^m$  is generated as

$$y = X\theta + \xi$$
.

We want to recover the unknown vector  $\theta$  using Markov Chain Monte Carlo techniques, given the observations (X, y). We are interested in the case when d is large. We recover  $\theta$  by finding the maximum likelihood estimate.

In the present setting, the maximum likelihood estimate of  $\theta$  is given by the value  $\hat{\theta} \in \Theta$  that maximizes the likelihood function

$$\mathcal{L}(X, y; \theta) = \frac{\exp\{-\frac{1}{2} \left(y - X\theta\right)^{\mathsf{T}} \left(y - X\theta\right)\}}{(2\pi)^{m/2}},$$

given the observations (X, y). Here the superscript T represents the transpose operation. We can equivalently cast the question in the form of a minimization problem. Indeed, the maximum likelihood estimate of  $\theta$  is given by the value  $\hat{\theta} \in \Theta$  that minimizes the function

$$\mathcal{H}(X, y; \theta) = (y - X\theta)^{\mathsf{T}} (y - X\theta),$$

given the observations (X, y).

## Metropolis-Hastings algorithm

Let  $\beta > 0$  be a fixed real parameter. We construct the Metropolis-Hastings (discrete-time) Markov chain on the state space  $\Theta$ , with stationary distribution

$$\pi_{\beta}(\theta) = \frac{e^{-\beta \mathcal{H}(X,y;\theta)}}{Z_{\beta}}, \quad \text{with} \quad Z_{\beta} = \sum_{\theta \in \Theta} e^{-\beta \mathcal{H}(X,y;\theta)}.$$

Observe that the probability distribution  $\pi_{\beta}$  concentrates on the maximum likelihood estimate as  $\beta \to +\infty$ . Therefore, if we choose  $\beta$  sufficiently large and we run the chain for a large number N of steps, we can take the state visited at time N as the maximum likelihood estimate  $\hat{\theta}$ .

The following algorithm produces the first N steps  $\theta_1, \dots, \theta_N$  of the Metropolis-Hasting chain on  $\Theta$ .

Input: value of the parameter  $\beta$ ; number of steps N;

initial state  $\bar{\theta} \in \Theta$ :

**Output:** trajectory of the Metropolis-Hastings chain starting at  $\bar{\theta}$ ;

## Procedure

Step 1. Set  $\theta_0 = \bar{\theta}$ .

Step 2. For 
$$t = 1, 2, ..., N - 1$$
:

1. pick i uniformly at random in  $\{1, 2, \dots, d\}$ ;

2. let the proposed state be  $\theta^* \in \Theta$ , with entries

$$\theta^*(j) = \begin{cases} \theta_{t-1}(j) & \text{if } j \neq i \\ 1 - \theta_{t-1}(j) & \text{if } j = i \end{cases}$$
  $(j = 1, 2, \dots, d);$ 

3. set

$$\theta_t = \left\{ \begin{array}{ll} \theta^* & \text{ with probability } \min \left\{ 1, \frac{e^{-\beta \mathcal{H}(X,y;\theta^*)}}{e^{-\beta \mathcal{H}(X,y;\theta_{t-1})}} \right\} \\ \\ \theta_{t-1} & \text{ with probability } 1 - \min \left\{ 1, \frac{e^{-\beta \mathcal{H}(X,y;\theta^*)}}{e^{-\beta \mathcal{H}(X,y;\theta_{t-1})}} \right\}. \end{array} \right.$$

# **Project**

By implementing the Metropolis-Hastings algorithm above, we determine an estimate  $\hat{\theta}$  of a signal  $\theta \in \Theta$  for any given realization of (X, y). To check the quality of our estimate, we analyze the mean squared error

$$\mathcal{E} = E\left((\hat{\theta} - \theta)^{\mathsf{T}}(\hat{\theta} - \theta)\right),\,$$

where the expectation is over  $\theta$  and (X, y), for different values of m (number of measurements). Fix d = 10. For every  $1 \le m \le 15$ , compute the mean squared error. Plot  $\mathcal{E}$  as a function of m and comment on the characteristics of your plot. What is the minimum value of  $\frac{m}{d}$  required to reliably recover  $\theta$ ?

Remark. The mean squared error  $\mathcal{E}$  can be estimated by exploiting the law of large numbers. Let M denote the number of independent realizations of  $(\theta, X, y)$ . Moreover, let  $\hat{\theta}^{(j)}$  be the maximum likelihood estimate of the j-th signal  $\theta^{(j)}$ , obtained by the j-th run of the Metropolis-Hastings algorithm, given  $(X^{(j)}, y^{(j)})$ . If M is sufficiently large (use M of order  $10^4$ ), then we have the approximation

$$\mathcal{E} \approx \frac{1}{M} \sum_{j=1}^{M} \left( \hat{\theta}^{(j)} - \theta^{(j)} \right)^{\mathsf{T}} \left( \hat{\theta}^{(j)} - \theta^{(j)} \right).$$

#### References

- Levin D.A. and Peres Y., Markov chains and mixing times, Volume 107, American Mathematical Society, 2017
- [2] Ross S.M., Simulation, Academic Press, 2006