

HW3 Siyong Liu

1

$$\max_i f_i(z) \geq f_k(z) \geq f_k(x) + g^T(z - x) = f(x) + g^T(z - x) \\ g \in \partial f(x)$$

2

$$\partial J(w) = \begin{cases} 0 & 1 - yw^T x < 0 \\ -yx^T & otherwise \end{cases}$$

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$$\begin{aligned} \nabla_w J(w) &= \nabla_w \left(\frac{1}{n} \sum \ell(y_i w^T x_i) + \lambda \|w\|^2 \right) \\ &= \frac{1}{n} \sum \nabla_w \ell(y_i w^T x_i) + 2\lambda w \\ &= \begin{cases} \frac{1}{n} \sum -y_i x_i + 2\lambda w & y_i w^T x_i < 1 \\ \text{undefine} & otherwise \end{cases} \end{aligned}$$

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$$\begin{aligned} w_{t+1} &= w_t - \eta(\lambda w - y_i x) \\ w_{t+1} &= \begin{cases} (1 - \eta_t \lambda) w_t + \eta_t y_i x_i & y_i w^T x_i < 1 \\ (1 - \eta_t \lambda) w_t & otherwise \end{cases} \end{aligned}$$

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```
# 6
def to_sparse(1):
    return Counter(1)
```

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```
# 7
def load_data():
    reviews = load_and_shuffle_data()
    train = reviews[:1500]
    test = reviews[1500:]
    X_train = [x[:-1] for x in train]
    y_train = [x[-1] for x in train]
    X_test = [x[:-1] for x in test]
    y_test = [x[-1] for x in test]
    return X_train, y_train, X_test, y_test

X_train, y_train, X_test, y_test = load_data()
```

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```
# 8
def pegasos1(X, y, lambda_reg=0.25, max_epoch=30):
    epoch = 0
    w = {}
    t = 0
    order_list = range(len(X))
    while epoch < max_epoch:
        random.shuffle()
        for i in order_list:
            t += 1
            eta = 1 / (t * lambda_reg)
            if y[i] * dotProduct(X[i], w) < 1:
                increment(w, - eta * lambda_reg, w)
                increment(w, eta * y[i], X[i])
            else:
                increment(w, - eta * lambda_reg, w)
        epoch += 1
    return w
```

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$$\begin{aligned}s_{t+1}W_{t+1} &= s_t(W_t + \frac{1}{s_{t+1}}\eta_ty_jx_j)(1 - \eta_t\lambda) \\ &= (w_t + \frac{s_t}{s_{t+1}}\eta_ty_jx_j)(1 - \eta_t\lambda) \\ &= (1 - \eta_t\lambda)w_t + \frac{s_t}{s_{t+1}}(1 - \eta_t\lambda)\eta_ty_jx_j \\ &= (1 - \eta_t\lambda)w_t + \eta_ty_jx_j \\ &= w_{t+1}\end{aligned}$$

```
# 9
```

```

def pegasos2(X, y, lambda_reg=0.1, max_epoch=30, tolerance=1e-2,
useConverge=True):
    epoch = 0
    w = {}
    t = 1
    scale = 1
    order_list = range(len(X))
    while epoch < max_epoch:
        epoch += 1
        prev_sum = sum(w[weight]**2 for weight in w)
        for i in order_list:
            t += 1
            eta = 1 / (t * lambda_reg)
            scale = (1 - eta * lambda_reg) * scale
            if y[i] * scale * dotProduct(w, X[i]) < 1:
                increment(w, eta * y[i] / scale, X[i])
        cur_sum = sum(w[weight]**2 for weight in w)
        if useConverge and np.abs(scale**2 * (prev_sum - cur_sum)) < tolerance:
            break
    for k, v in w.items():
        w[k] = v * scale
    return w

```

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```

%%time
w1 = pegasos1(X_train, y_train)
>>>
wall time: 6min 43s

```

```

%%time
w2 = pegasos2(X_train, y_train, useConverge=False)
>>>
wall time: 5.41 s

```

```

print("w1['friends']: ", w1['friends'])
print("w2['friends']: ", w2['friends'])
>>>
w1['friends']: 0.0205333333333333324
w2['friends']: 0.017555165440767868

```

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```

#11 classification error
def classification_error(w, X, y):
    cnt = 0
    for i in range(len(X)):
        if np.sign(dotProduct(X[i],w)) != y[i]:
            cnt += 1
    return cnt/len(X)

w1_err = classification_error(w1, X_test, y_test)
w2_err = classification_error(w2, X_test, y_test)
print('w1_err: ', w1_err)

```

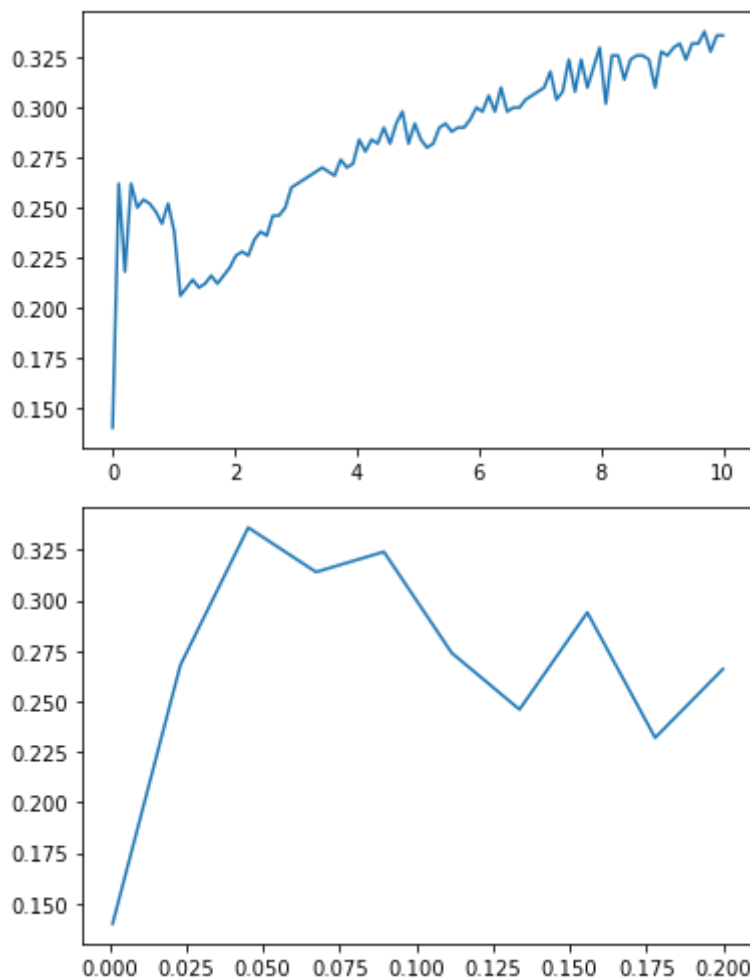
```
print('w2_err: ', w2_err)
>>>
w1_err:  0.246
w2_err:  0.276
```

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```
def test_lambda(lambda_list, X_train, y_train, X_test, y_test):
    err_list = []
    for lambda_reg in lambda_list:
        w = pegasos2(X_train, y_train, lambda_reg)
        err_list.append(classification_error(w, X_test, y_test))
    return err_list
```

```
lambda_list = np.linspace(0.001, 10, 100)
err_list = test_lambda(lambda_list, X_train, y_train, X_test, y_test)
plt.plot(lambda_list, err_list)
```

```
lambda_list = np.linspace(0.001, 0.2, 10)
err_list = test_lambda(lambda_list, X_train, y_train, X_test, y_test)
plt.plot(lambda_list, err_list)
```



best lambda is around [0, 0.025]

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$$\begin{aligned}\partial_w J(w) = 2X^T(Xw - y) + 2\lambda w &= 0 \\ X^T Xw + \lambda Iw &= X^T y \\ (X^T X + \lambda I)w &= X^T y \\ w &= (X^T X + \lambda I)^{-1} X^T y\end{aligned}$$

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$$\begin{aligned}X^T Xw + \lambda Iw &= X^T y \\ \lambda w &= X^T y - X^T Xw \\ w &= \frac{1}{\lambda}(X^T y - X^T Xw) \\ w &= X^T \alpha \\ \alpha &= \frac{1}{\lambda}(y - Xw)\end{aligned}$$

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$$w = X^T \alpha = \sum_{i=1}^m \alpha_i x_i$$

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$$\begin{aligned}\alpha &= \frac{1}{\lambda}(y - Xw) \\ \alpha &= \frac{1}{\lambda}(y - XX^T \alpha) \\ \lambda \alpha &= (y - XX^T \alpha) \\ \lambda \alpha + X^T X \alpha &= y \\ \alpha &= (\lambda I + X^T X)^{-1} y\end{aligned}$$

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$$Xw = XX^T \alpha = X^T X(\lambda I + X^T X)^{-1} y$$

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$$f(x) = x^T w^* = x^T X^T \alpha = k_x^T \alpha$$

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```
def linear_kernel(X1, X2):
    return np.dot(X1, np.transpose(X2))

def RBF_kernel(X1, X2, sigma):
    distance = scipy.spatial.distance.cdist(X1, X2, 'sqeuclidean')
    return np.exp(- 0.5 * distance / pow(sigma, 2))

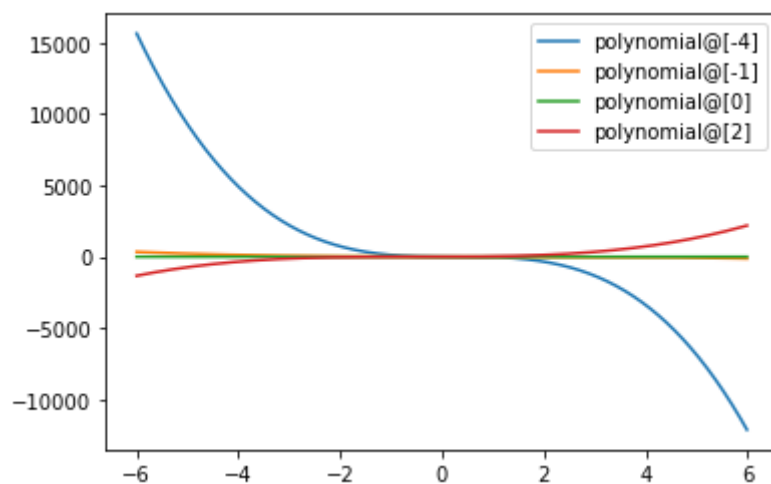
def polynomial_kernel(X1, X2, offset, degree):
    return pow((offset + np.inner(X1, X2)), degree)
```

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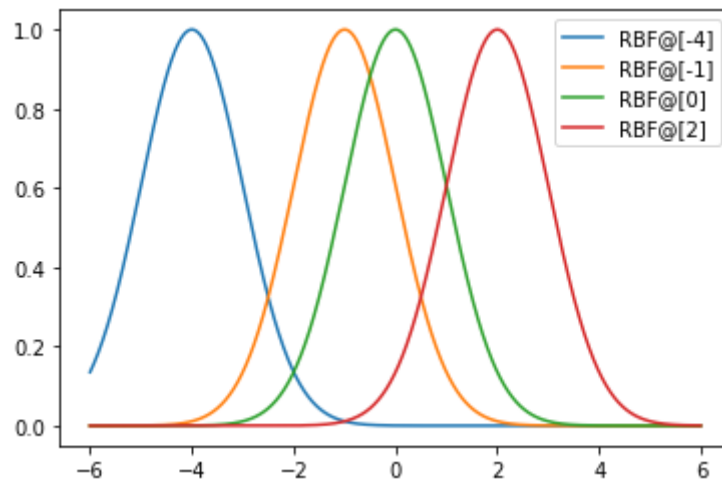
```
array = np.array([[ -4,  -1,  0,  2]]).T
linear_kernel(array, array)
>>>
array([[16,  4,  0, -8],
       [ 4,  1,  0, -2],
       [ 0,  0,  0,  0],
       [-8, -2,  0,  4]])
```

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```
# polynomial
y = polynomial_kernel(prototypes, xpts, 1, 3)
for i in range(len(prototypes)):
    label = "polynomial@" + str(prototypes[i,:])
    plt.plot(xpts, y[i,:], label=label)
plt.legend(loc = 'best')
plt.show()
```



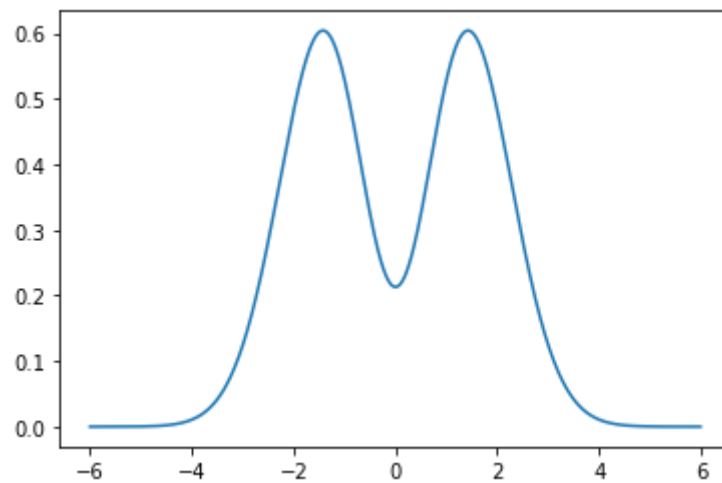
```
y = RBF_kernel(prototypes, xpts, 1)
for i in range(len(prototypes)):
    label = "RBF@" + str(prototypes[i,:])
    plt.plot(xpts, y[i,:], label=label)
plt.legend(loc = 'best')
plt.show()
```



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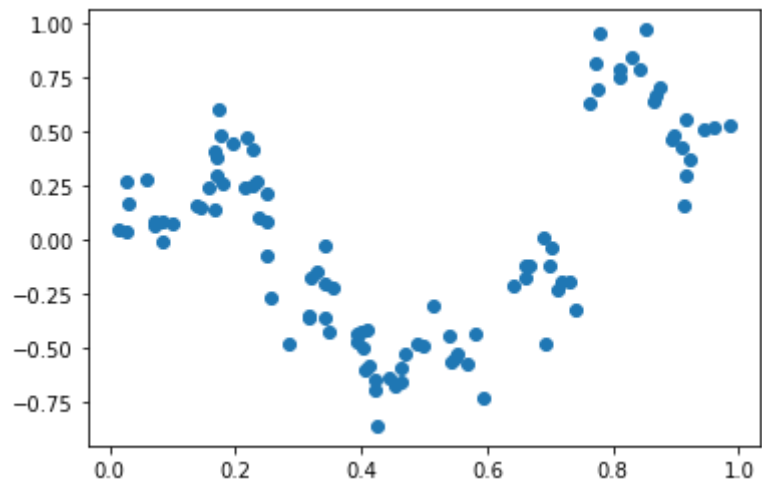
```
def predict(self, x):
    return self.kernel(x, self.training_points) @ self.weights
```

```
rbf_kernel = functools.partial(RBF_kernel, sigma=1)
xpts = np.arange(-6.0, 6, plot_step).reshape(-1,1)
k_machine = Kernel_Machine(rbf_kernel,
    np.array([-1, 0, 1]).reshape(-1, 1),
    np.array([1, -1, 1]).reshape(-1, 1))
plt.plot(xpts, k_machine.predict(xpts))
plt.show()
```



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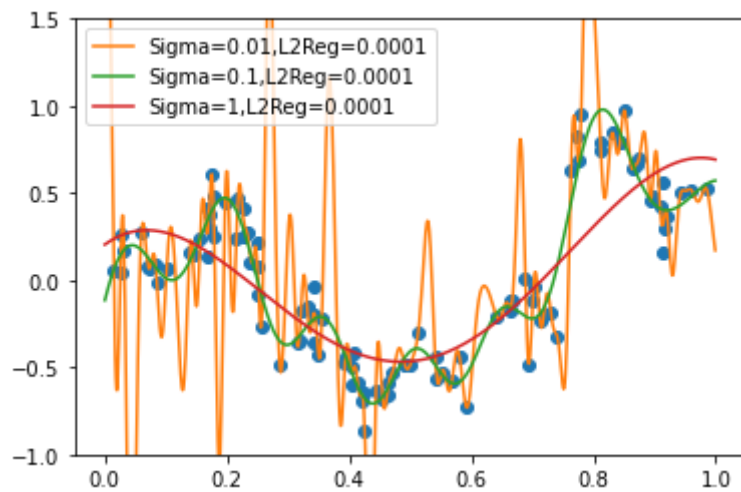
```
plt.scatter(x_train, y_train)
plt.plot()
```



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```
def train_kernel_ridge_regression(X, y, kernel, l2reg):
    alpha = np.linalg.inv(np.identity(X.shape[0])*l2reg + kernel(X, X)) @ y
    return kernel_machine(kernel, X, alpha)
```

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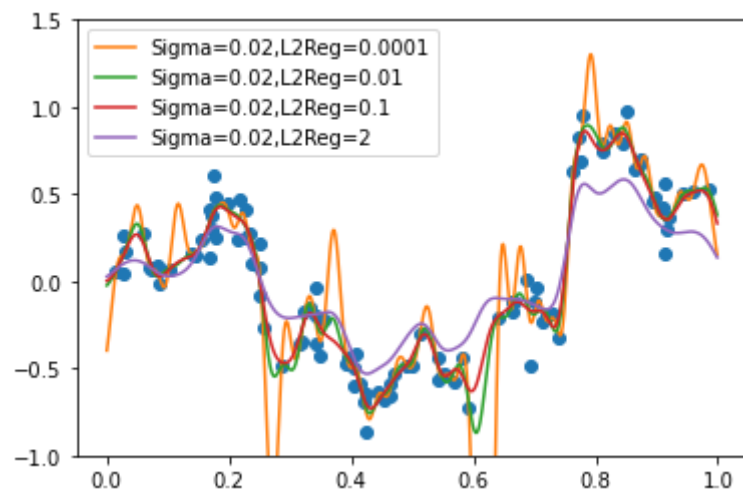


overfit: 0.01

underfit: 1

best: 0.1

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when $\lambda \rightarrow \infty$, model become underfit