1. (2 pts) Bayes vs 1NN classifier. <sup>1</sup> I'd like to collect some Pokemon of which to do battle. Without knowing much, and my primary criteria is to find Pokemon who can throw things to a very far distance. In particular, I will only accept Pokemon who can throw trajectories at least 72 inches (6 ft) distance.

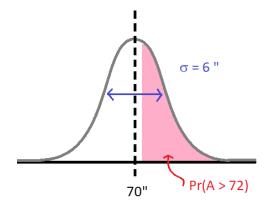
In general, if a Pokemon says he/she can throw x inches, then in truth they are lying, and their true ability follows a Gaussian distribution with mean x and variance  $\sigma^2 = 6^2 = 36$  inches.

For parts (a) and (b), you may use wolframalpha.com to help compute the integral. Report both the symbolic form and the computed number up to 3 significant digits. (We will first try to match your numbers, and if your numbers are incorrect, we will use the symbolic form for partial credit.)

(a) (0.5 pts) Arbok claims that he can throw 70 inches. What is the probability that he fulfills my criteria?

Ans.

Arbok's claim is that he can throw 70 inches, so his throwing ability has a Gaussian distribution with mean 70 and variance 36.

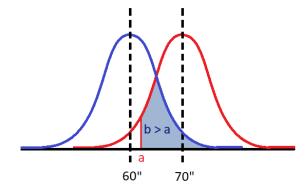


Therefore the probability that he can throw further than 6 ft is

$$\mathbf{Pr}(\text{Arbok throws far enough}) = \int_{72}^{\infty} \frac{1}{\sqrt{2\pi} \cdot 6} \exp\left(-\frac{(x-70)^2}{2 \cdot 6^2}\right) dx \approx 0.369$$

(b) **(0.5 pts)** Bulbasaur claims he can throw 60 inches. What is the probability that he is can actually throw further than Arbok? (Assume their throwing arms are independent.)

**Ans.** Let's denote B the throwing distance of Bulbasaur and A the throwing distance of Arbok. Then we want to measure the area under the pdf for B, starting at some point a, but then sweeping all the possible values of a.



<sup>&</sup>lt;sup>1</sup>All numbers in this problem are made up.

That is,

$$\mathbf{Pr}(B > A) = \int_{-\infty}^{\infty} \mathbf{Pr}(B > A|A = a)\mathbf{Pr}(A = a)da$$

$$= \int_{-\infty}^{\infty} \left(\int_{b=a}^{\infty} f_B(b)db\right) f_A(a)da$$

$$= \int_{-\infty}^{\infty} \left(\int_{b=a}^{\infty} \frac{1}{\sqrt{2\pi} \cdot 6} \exp\left(-\frac{(b-60)^2}{2 \cdot 6^2}\right) db\right) \frac{1}{\sqrt{2\pi} \cdot 6} \exp\left(-\frac{(a-70)^2}{2 \cdot 6^2}\right) da$$

$$\approx 0.110$$

- (c) Charmander is the next Pokemon who crosses my path, and he claims to throw exactly 72 inches. Consider the following reward function: If I accept him, and Charmander does fulfill this criteria, then he wins tons of battles and I get +10 reward. If he in fact is not fulfilling my critiera, I waste my resources, he loses battles, and I end up with a deadbeat Pokemon, translating to a −1 reward. If I reject Charmander and in fact was able to throw far enough, then someone else will scoop him up and destroy my other Pokemon, giving me a −25 reward. But if I reject Charmander and he was in fact unable, there is 0 reward. Think of loss as negative reward.
  - i. (0.4 pts) What is the Bayes risk of accepting vs rejecting?

    Ans. Since Charmander reported exactly 72 inches and the pdf is symmetric, then there is a 50% chance that his true throwing distance is more than 72", and 50% chance that it is less.

    So, if I accept, then

Risk = 
$$-10 \cdot \mathbf{Pr}(C > 72) + 1 \cdot \mathbf{Pr}(C < 72) = -10 \cdot 0.5 + 1 \cdot 0.5 = -4.5$$
.

If I reject, then

Risk = 
$$25 \cdot \mathbf{Pr}(C > 72) + 0 \cdot \mathbf{Pr}(C < 72) = 25 \cdot 0.5 + 1 \cdot 0 = 12.5$$
.

- ii. (0.1 pts) What does the Bayes classifier tell me to do?

  Ans. Since the risk of rejecting (12.5) is clearly greater than the risk of accepting (-4.5), according to the Bayes classifier (which selects the option of less risk) I should take the "risk" and accept!
- (d) **(0.5 pts)** Diglett, Eevee, and Flareon are former Pokemons of mine, who have all lied about their abilities. Diglett wrote he throws 85 inches but actually he can only throw 60 inches. Eevee wrote she throws 72 inches and in fact she throws closer to 70 inches. Flareon wrote 90 inches and it's not a bad estimate; he throws 89 inches. Think of these three Pokefriends as my training dataset.

Gardevoir suddenly appears and walks across my keyboard. I ask him "How far can you throw your projectiles?" and he sniffs, and says "82 inches, easily." Does a 1-nearest neighbor regressor predict that Gardevoir fulfills my critiria? Explain your answer.

**Ans.** Gardevoir reports 82 inches, and the closest sample in my dataset is Diglett, who wrote 85 inches. But I know that Diglett's true distance is actually 60 inches, so a 1-NN regressor would in fact say that Gardevoir's true throwing distance is 60 inches.

2. (3 pts) Decision theory. I run a factory that makes widgets and gadgets. Despite best efforts, manufacturing defects can always occur. I would like to inspect each of these items individually, but the cost of inspection is pretty high, so I cannot inspect each individual widget and gadget.

The widgets and gadgets are printed on disks. A disk has a 10% chance of being warped. There are two printing presses, a blue one and a red one. The table below gives the possibility that, given a disk of a particular state printed by a particular press, a widget or gadget printed on that disk is warped.

disk \ press	red	blue
warped	30%	85%
normal	5%	0 %

(To interpret the table, the probability that a gadget is defective if it were on a disk that is not warped, and printed by a red press, is 5%.)

- (a) First, we consider only the loss of quality in a product. That is, if we ship a widget or gadget is defective, we incur a loss of +1. Otherwise, we incur no losses.
  - i. (0.5 pts) Without inspecting anything (that is, we ship out everything we make), what is the Bayes risk of using a red press, over a single disk? a blue press? Which machine would I use to minimize the Bayes' risk?

**Ans.** We write D if a widget or gadget is defective and ND if not defective. We write W if a disk is warped and NW if not warped.

In this case, I just assume that nothing is defective.

Bayes' risk = 
$$\mathbb{E}_{\text{truth}}[\text{loss}(\text{guess} = ND, \text{truth})] = \text{Pr}(D)\text{loss}(D) + \text{Pr}(ND)\text{loss}(ND)$$

For the red press, the probability of an item being defective is

$$\mathbf{Pr}(D|\text{red}) = \mathbf{Pr}(D, \text{disk} = W|\text{red})\mathbf{Pr}(\text{disk} = W|\text{red}) + \mathbf{Pr}(D, \text{disk} = NW|\text{red})\mathbf{Pr}(\text{disk} = NW|\text{red})$$

$$= 0.3 \cdot 0.1 + 0.05 \cdot 0.9 = 0.075$$

For the blue press, the probability of an item being defective is

$$\mathbf{Pr}(D|\text{blue}) = \mathbf{Pr}(D, \text{disk} = W|\text{red})\mathbf{Pr}(\text{disk} = W|\text{blue}) + \mathbf{Pr}(D, \text{disk} = NW|\text{blue})\mathbf{Pr}(\text{disk} = NW|\text{blue})$$
  
=  $0.85 \cdot 0.1 + 0.0 \cdot 0.9 = 0.085$ .

Therefore, since loss(D) = 1 and loss(ND) = 0, the Bayes risk is

Bayes' risk, red machine = 0.075, Bayes' risk, blue machine = 0.085.

For the lowest Bayes' risk, I would use the red machine.

ii. (0.2 pts) Without inspecting anything, what is the Minimax risk of using a red press? a blue press? Ans. The question here is based more on logic. Recall that

$$\label{eq:minimax} \text{minimax risk} = \max_{\text{truth}}[\mathbf{loss}(\text{guess} = ND, \text{truth})].$$

Since, as calculated above, the probability that a widget or gadget is defective given red or blue machine is greater than 0, then our minimax risk is 1 in both cases.

iii. (0.2 pts) Suppose I invest the effort into inspecting disks, and remove all warped disks. What is the Bayes risk, per disk, of using a red press? a blue press?

**Ans.** Now, for the red press, the probability of an item being defective is simply

$$Pr(D|red, disk = NW) = 5\%$$

and for the blue press,

$$\mathbf{Pr}(D|\text{blue}, \text{disk} = NW) = 0\%.$$

Then the Bayes risk is simply this quantity:

Bayes' risk, red machine = 
$$0.05$$
, Bayes' risk, blue machine =  $0.0$ .

iv. (0.1 pts) After removing all warped disks, what is the minimax risk of using a red press? a blue press? Ans. Since the chance of a defection with the red press is still nonzero, then the minimax loss is 1. For the blue press, since the chance of defection is 0 once all warped disks are removed, the minimax loss is 0.

(b) Widgets are primarily used in online advertising. If they are defective, they will end up sending an ad that is undesirable. However, if they are removed, then no ad is sent out. Therefore, the revenue gained from a widget is estimated at

$$\text{revenue per widget} = \begin{cases} \$1 & \text{if widget is sold and is not defective} \\ -\$1 & \text{if widget is sold and is defective} \\ 0 & \text{if the widget is not sold.} \end{cases}$$

There is no cost to rejecting a disk, but the cost of inspection is \$1 per percent of disks inspected, per widget. (So, if I inspect every disk, I pay \$100 per widget. If I inspect only 10% of disks, I pay \$10 per widget.) Every widget that is not on a disk that was found to be warped is sold.

i. (0.5 pts) Compute the Bayes reward (e.g. the expected profit per day) as a function of  $x = \mathbf{Pr}$  (inspection) for widgets, when using the blue press. Compute the same for the red press. (Remember that we are computing the cost *per widget*.)

**Ans.** Since the reward of being right is \$1 and of being wrong is -\$1, then, with S as the event that the chip was sold and W the event that the disk was warped,,

$$\mathbb{E}_{\text{defection}}[\text{profit}] = \underbrace{\mathbf{Pr}(ND,S) - \mathbf{Pr}(D,S)}_{\text{profit from sales}} - \underbrace{100x}_{\text{inspection cost}}.$$

More concretely, taking I as disk was inspected and NI as not inspected, and given that being warped or inspected are independent events,

$$\begin{aligned} \mathbf{Pr}(D,S) &= \underbrace{\mathbf{Pr}(D,S|I,W)}_{=0} \mathbf{Pr}(I,W) + \underbrace{\mathbf{Pr}(D,S|NI,W)}_{=\mathbf{Pr}(D|W)} \mathbf{Pr}(NI,W) \\ &+ \underbrace{\mathbf{Pr}(D,S|I,NW)}_{=\mathbf{Pr}(D|NW)} \mathbf{Pr}(I,NW) + \underbrace{\mathbf{Pr}(D,S|NI,NW)}_{=\mathbf{Pr}(D|NW)} \mathbf{Pr}(NI,NW) \\ &= \mathbf{Pr}(D|W) \mathbf{Pr}(NI) \mathbf{Pr}(W) + \mathbf{Pr}(D|NW) \underbrace{\left(\mathbf{Pr}(I) + \mathbf{Pr}(NI)\right)}_{=1} \mathbf{Pr}(NW) \\ &= \begin{cases} 85\% \cdot (1-x) \cdot 10\% & \text{if press is blue} \\ 30\% \cdot (1-x) \cdot 10\% + 5\% \cdot 90\% & \text{if press is red} \end{cases} \\ &= \begin{cases} 8.5\% - 8.5\% \cdot x & \text{if press is blue} \\ 7.5\% - 3\% \cdot x & \text{if press is red} \end{cases} \end{aligned}$$

Along the same lines,

$$\begin{array}{lll} \mathbf{Pr}(ND,S) & = & \underbrace{\mathbf{Pr}(ND,S|I,W)}_{=0} \mathbf{Pr}(I,W) + \underbrace{\mathbf{Pr}(ND,S|NI,W)}_{=\mathbf{Pr}(ND|W)} \mathbf{Pr}(NI,W) \\ & + \underbrace{\mathbf{Pr}(ND,S|I,NW)}_{=\mathbf{Pr}(ND|NW)} \mathbf{Pr}(I,NW) + \underbrace{\mathbf{Pr}(ND,S|NI,NW)}_{=\mathbf{Pr}(ND|NW)} \mathbf{Pr}(NI,NW) \\ & = & \mathbf{Pr}(ND|W) \mathbf{Pr}(NI) \mathbf{Pr}(W) + \mathbf{Pr}(ND|NW) \underbrace{\left(\mathbf{Pr}(I) + \mathbf{Pr}(NI)\right)}_{=1} \mathbf{Pr}(NW) \\ & = & \begin{cases} 15\% \cdot (1-x) \cdot 10\% + 90\% & \text{if press is blue} \\ 70\% \cdot (1-x) \cdot 10\% + 95\% \cdot 90\% & \text{if press is red} \end{cases} \\ & = & \begin{cases} 91.5\% - 1.5\%x & \text{if press is blue} \\ 92.5\% - 7\%x & \text{if press is red} \end{cases} \end{array}$$

The Bayes reward is therefore

$$\mathbb{E}_{\text{defection}}[\text{profit}] = -100x + \mathbf{Pr}(ND, S) - \mathbf{Pr}(D, S)$$

$$= \begin{cases} -99.96x + 0.83 & \text{if blue} \\ -100.04x + 0.85 & \text{if red} \end{cases}$$

$$= \begin{cases} 0.83 - 99.83x & \text{if blue} \\ 0.85 - 99.04x & \text{if red}. \end{cases}$$

ii. (0.5 pts) If you were a consultant for my factory, how much inspection would you recommend? Would you recommend using one press over the other for widgets?

**Ans.** From a purely profit point of view, I make the most money if I don't inspect anything at all. Even if I do inspect, I can't inspect more than around 8% of disks before, on average, I start losing money. The same logic applies to both machines.

(c) Gadgets are primarily used in medical care. If they are defective, someone will die. However, if they are removed, then someone waits a day longer to get a much-needed test. While we can never assign monetary value to a human life, in terms of insurance costs experts have estimated the following value:

revenue per gadget = 
$$\begin{cases} \$500 & \text{if gadget is sold and is not defective} \\ -\$10,000 & \text{if gadget is sold and is defective} \\ \$0 & \text{if the gadget is not sold.} \end{cases}$$

Again, there is no cost to rejecting a disk, and again, the cost of inspection is \$1 per percent of disks inspected, per gadget. Every gadget that is not on a disk that was found to be warped is sold.

i. (0.5 pts) Compute the Bayes reward (e.g. the expected profit per day) as a function of  $x = \mathbf{Pr}(\text{inspection})$  for gadgets, when using the blue press. Compute the same for the red press.

**Ans.** With the new reward construct, and reusing calculations from the previous part for  $\mathbf{Pr}(D, S)$ , the Bayes reward is

$$\mathbb{E}_{\text{defective}}[\text{profit}] = 500 \cdot \mathbf{Pr}(ND, S) - 10,000\mathbf{Pr}(D, S) - 100x$$

$$= \begin{cases} 442.5x - 392.5 & \text{if blue} \\ 165x - 287.5 & \text{if red} \end{cases}$$

ii. (0.5 pts) If you were a consultant for my factory, how much inspection would you recommend? Would you recommend using one press over the other for gadgets?

**Ans.** In fact, I stand to get the most profit if I inspect all of the disks, with a clear preference toward using exclusively the blue machine.

- 3. (3 pts) K-nearest neighbors classification. We will now try to use the KNN classifier to classify MNIST digits.
  - Open hw2\_minst\_release.ipynb. Load the necessary packages and the data, and take a look at how the data is formatted and structured. I have done all the "data cleaning" needed for this assignment (which is very minimal for this exercise). I have also included a function get\_small\_dataset which will return a subset of the training data (60000 samples!) so that we can reasonably train some things on even the worst laptops.
  - (1.0 pt) Distance function. The first step in establishing a KNN classifier is deciding what is going to be your metric for "distance", and writing a function that, given the training data Xtrain and query point zquery, can as efficiently as possible return a vector of distances between zquery and all of the datapoints in Xtrain.

There are many ways to do this, some faster than others. In general, if your implementation involves a for loop, you may be in for a lot of waiting and some very warm laptops. One implementation that avoids for loops is to really try to use the optimized numerical linear algebra functions of the numpy library as much as possible, e.g. using functions like np.dot, np.sum, etc.

The distance function we will use is the 2 norm squared. It may help to see this metric expanded, e.g.

$$d(x_i, z) = ||x_i - z||_2^2 = x_i^T x_i - 2x_i^T z + z^T z.$$

One "optimized" approach is to compute each term separately, using optimized numpy functions. (Although the code is not set up this way, you could even further optimize things by computing the terms involving only the training data ahead of time.)

In your writeup, print what you see when you run the box, e.g. the print outputs of

```
print(get_dist(Xtrain,Xtrain[0,:])[0])
print(get_dist(Xtrain,Xtest[0,:])[10])
print(get_dist(Xtrain,Xtest[10,:])[50])
```

**Ans.** 0.0, 6069462.0, 5661744.0

• (1 pts) Prediction. Implement a K-nearest-neighbor classification predictor, which takes a test data point, finds the closest point (in terms of Euclidean distance) in the train data set, and returns the KNN prediction. Use a majority vote scheme to decide which label to return; use whatever scheme you wish to break ties.

Hint: take a look at scipy.stats.mode()

In your writeup, print the output for K = 3 and m = 100, e.g. the output for the lines

```
print(ytest_pred[:20])
print(ytest[:20])
```

## Ans.

```
prediction line: [7 2 1 0 4 1 4 4 6 9 0 0 9 0 1 9 7 7 3 4] truth line: [7 2 1 0 4 1 4 9 5 9 0 6 9 0 1 5 9 7 3 4]
```

• Evaluate based on classification accuracy. Now write a function that returns the classification accuracy given a list of true labels (ytrue) and predicted labels (ypred).

In your writeup, print classification accuracy of the test set.

Ans. 0.6476

• (1 pts) Hyperparameter tuning. I have included in the next box an experiment in which your KNN predictor is tested for a training dataset with 100, 1000, and 2500 data samples. In each case, the code will run your predictor and return three numbers: m, the prediction accuracy, and the prediction runtime. Run this box and return the classification accuracy and runtimes for m = 100, 1000, 2500 and K = 1, 3, 5.

m	K	accuracy	runtime (sec)
100	1		
100	3		
100	5		
1000	1		
1000	3		
1000	5		
2500	1		
2500	3		
2500	5		

Ans. Here are the numbers on my (pretty crappy) laptop. Obviously the runtime answers will vary on different laptops, but the accuracy numbers should be exact.

m	K	accuracy	runtime (sec)
100	1	0.6794	2.61
100	3	0.6476	2.59
100	5	0.6232	2.58
1000	1	0.8690	42.18
1000	3	0.8622	49.17
1000	5	0.8582	48.27
2500	1	0.9136	121.42
2500	3	0.9146	121.49
2500	5	0.9101	120.88

Comment a bit on the performance of the model for these different hyperparameter choices. In particular:

- Is it feasible to run this model for the full m=60000 training dataset in runtime? Is it advisable? **Ans.** On my laptop, the scaling is just terrible. I can't get anywhere near training the entire dataset with m=60000 samples. Even if I were running this on a large-ish server, it may not be advisable to be using such a large training set at runtime, where we need performance to be pretty fast.
- How does the accuracy depend on K for different values of m?
  Ans. Interestingly, we seem to see a drop in performance as K increases. For low values of m, this is somewhat reasonable, since there are very few examples of each digit, so it is maybe more likely that a wrong digit is a nearest neighbor. For larger values of m, at least this degradation seems smaller, and it wouldn't be surprising if the performance started to increase with K for very large values of m. In general, 2-norm-squared distance is not a great metric for image distances; MNIST is one of the few tasks where it's known to provide reasonable resutls at all.

## 4. (2 pts) Naive Bayes and Alice in Wonderland.

**Ans.** See also accompanying notebook for more details.

- Open the python notebook hw2\_alice\_naivebayes\_release.ipynb . After running the first couple boxes, you should have loaded the entire text of "Alice in Wonderland" by Lewis Caroll, as an ordered list of words. Our task today will be to do word prediction based on this corpus. Throughout this exercise, this corpus will serve as both our training and testing data.
- Tokenize While the exact word means a lot to us, for a (primitive) computer, a word is just some object; in particular, we represent each unique word as a unique number. This is the word's token. Run the 3rd block to tokenize the data, and understand what it is doing.
- (a) **(0.5 pt) Bigram classifier**. We predict the next word using only the previous word. Here, we should think of features x as the previous word, and label y as the next word. Therefore, a fully populated table of  $\mathbf{Pr}(x|y)$  should have  $V \times V$  entries, where V is the size of the vocabulary.

Populate the next box with the calculation for the posterior  $\mathbf{Pr}(x|y)$  and the prior  $\mathbf{Pr}(y)$  based on the statistics of the corpus. Do not worry about normalization, e.g. the likelihood function can return the first term of

$$\mathbf{Pr}(x|y)\mathbf{Pr}(y) \propto \mathbf{Pr}(y|x).$$

Now construct a Bayes classifier using only this feature. **Report the classification accuracy** over the entire corpus of this classifier.

**Ans.** 22.4%

(b) **(0.5 pt)** Well, that was pretty terrible. Let's try and incorporate not just the past word, but the past 2 words. Fill in the posterior for  $\mathbf{Pr}(x|y)$  where now x is the 2nd previous word. Now construct a Naive Bayes classifier that uses both the past and past 2nd word as features. **Report the classification accuracy** over the entire corpus of this classifier. (Note that this is not a 3-gram classifier, which would be the not-Naive-Bayes version of what we are doing here.)

**Ans.** 36.1%

• (0.25 pt) Text generation Using the likelihoods computed from the bigram classifier, and starting with a seed word "alice", generate the next 25 words by always picking the most likely next word.

**Ans.** The answer here should not vary, and should be

alice and the queen and

• (0.25 pt)Text generation Do the same thing with the 2-past-words Naive Bayes likelihood, starting with the seed phrase "alice was".

**Ans.** The answer here also should not vary, and should be

alice was the little of the queen and the

• (0.5 pt, 0.25 per generation) In both of those cases, you should have found that the generator was terrible, and gets stuck in a loop through a very short and uninteresting phrase. We could try to spice things up a little, however. In your generation script, instead of returning the next word with highest likelihood, sample the next word according to the likelihood weights. (hint: check out random.choices()) Are either of these good generators, in your view?

**Ans.** Answers should vary here, but for me: past word:

alice it said the mouse the mock turtle to the queen had a little alice was the poor alice as the gryphon the hatter the other

 $\operatorname{past} 2 \operatorname{words}$ : alice was the white and that the gryphon and the other and i to be a very little of it was the little the mock turtle in

To me, this is a better generator than the previous one, but it's still not that great. For better generators, we need much better capturing of sentence structure. Using past words alone, this may be possible for very large n, but that may come at an unwanted memory cost.