$x_{list.append(x)}$ v_list.append(v) t_list.append(t) plt.plot(t_list, x_list, color='r') plt.xlabel("Time") plt.ylabel("Position") plt.rcParams["figure.figsize"] = (20, 10) plt.title("Solution of Quartic Oscillator") Text(0.5, 1.0, 'Solution of Quartic Oscillator') Solution of Quartic Oscillator 1.0 0.5 Time In [4]: plt.plot(x_list, v_list, color='r') plt.xlabel("Time") plt.ylabel("Position") plt.rcParams["figure.figsize"] = (20, 10) plt.title("Phase Space Diagram of Quartic Oscillator") Text(0.5, 1.0, 'Phase Space Diagram of Quartic Oscillator') Phase Space Diagram of Quartic Oscillator 2.0 1.5 1.0 0.5 0.0 -0.5 -1.0 -1.5 -2.0 -1.0 0.0 0.5 1.0 Phase Space Diagram of Quartic Oscilltor for Different Values of Coupling Constants: Let's plot the phase space diagrams for different values of α . In [5]: def f(a, t, x, v): return -w0**2*x - a* x**2 - b* x**3 w0 = 1b = 3ti = 0 x0 = 1v0 = 0tf = 30n = 1000 h = (tf - ti) / nt = ti x = x0v = v0 $x_list = [x0]$ $v_list = [v0]$ t_list = [ti] for a in range(0,6): t = ti x = x0V = V0 $x_list = [x0]$ $v_list = [v0]$ t_list = [ti] for i in range(n): #print(a, t, x, v) k1 = vj1 = f(a,t,x,v)k2 = v + (h*j1)/2.0j2 = f(a, t+ h/2.0, x+ (k1*h)/2.0, v + (j1*h)/2.0)k3 = v + (h*j2)/2.0j3 = f(a, t+ h/2.0, x+ (k2*h)/2.0, v + (j2*h)/2.0)k4 = v + (h*j3)j4 = f(a, t+ h, x+ (k3*h), v + (j3*h))x = x + h*(k1 + 2.0* k2 + 2.0* k3 + k4)/6.0v = v + h*(j1 + 2.0* j2 + 2.0* j3 + j4)/6.0t = t+h $x_{list.append(x)}$ v_list.append(v) t_list.append(t) plt.plot(x_list, v_list, label = a) plt.legend() plt.rcParams["figure.figsize"] = (20, 10) plt.title("Phase Space Diagram of Quartic Oscillator at Different Values of Coupling Constant (a)") plt.xlabel("Position") plt.ylabel("Velocity") Phase Space Diagram of Quartic Oscillator at Different Values of Coupling Constant (a) 2 -2 -2.0 -1.5 -1.0 Position Now, Let's plot for different values of β . In [6]: **def** f(b, t, x, v): return -w0**2*x - a* x**2 - b* x**3 w0 = 1a = 2 ti = 0 x0 = 1v0 = 0 tf = 30n = 1000 h = (tf - ti) / nt = ti x = x0v = v0 $x_list = [x0]$ $v_list = [v0]$ t_list = [ti] for b in range(1,7): t = ti x = x0v = v0 $x_list = [x0]$ $v_list = [v0]$ $t_list = [ti]$ for i in range(n): #print(b, t, x, v) k1 = vj1 = f(b,t,x,v)k2 = v + (h*j1)/2.0j2 = f(b, t+ h/2.0, x+ (k1*h)/2.0, v + (j1*h)/2.0)k3 = v + (h*j2)/2.0j3 = f(b, t+ h/2.0, x+ (k2*h)/2.0, v + (j2*h)/2.0)k4 = v + (h*j3)j4 = f(b, t+ h, x+ (k3*h), v + (j3*h))x = x + h*(k1 + 2.0* k2 + 2.0* k3 + k4)/6.0v = v + h*(j1 + 2.0* j2 + 2.0* j3 + j4)/6.0t = t+h $x_{list.append(x)}$ v_list.append(v) t_list.append(t) plt.plot(x_list, v_list, label = b) plt.legend() plt.rcParams["figure.figsize"] = (20, 10) plt.title("Phase Space Diagram of Quartic Oscillator at Different Values of Coupling Constant (b)") plt.xlabel("Position") plt.ylabel("Velocity") Phase Space Diagram of Quartic Oscillator at Different Values of Coupling Constant (b) -2.0 -1.5 -1.0 0.0 0.5 1.0 From the above plots it is clear that the anhormocity is increasing with increase in coupling constant α and β . In the 1st case, when we increased the α , the curves appear to be shifted towards left and in the 2nd case, when we increased the β , the curves appear to be shifted towards right.

Quartic Oscillator:

import matplotlib.pyplot as plt

import seaborn as sns
import math as mth

def f(t, x, v):

h = (tf - ti) / n

for i in range(n):
 print(t,x,v)

j1 = f(t,x,v)

k2 = v + (h*j1)/2.0

k3 = v + (h*j2)/2.0

k4 = v + (h*j3)

t = t+h

j2 = f(t+ h/2.0, x+ (k1*h)/2.0, v + (j1*h)/2.0)

j3 = f(t+ h/2.0, x+ (k2*h)/2.0, v + (j2*h)/2.0)

 $x = x + h^*(k1 + 2.0^* k2 + 2.0^* k3 + k4)/6.0$ $v = v + h^*(j1 + 2.0^* j2 + 2.0^* j3 + j4)/6.0$

j4 = f(t+ h, x+ (k3*h), v + (j3*h))

k1 = v

x_list = [x0]
v_list = [v0]
t_list = [ti]

sns.set_style('darkgrid')

Program:

w0 = 1 a = 2 b = 3 ti = 0 x0 = 1 v0 = 0 tf = 30 n = 1000

t = ti x = x0 v = v0

In [1]:

So, the equation of motion becomes $\ddot{x} = -\omega_0^2 x - lpha x^2 - eta x^3$

return -w0**2*x - a* x**2 - b* x**3

A quartic oscillator is an anharmonic oscillator, where the potential is $V=rac{1}{2}\omega_0^2x^2+rac{1}{3}\alpha x^3+rac{1}{4}\beta x^4$

Now, let's write a program to solve the above differential equation by using RK-4 method.