## Coupled Oscillator Without Walls

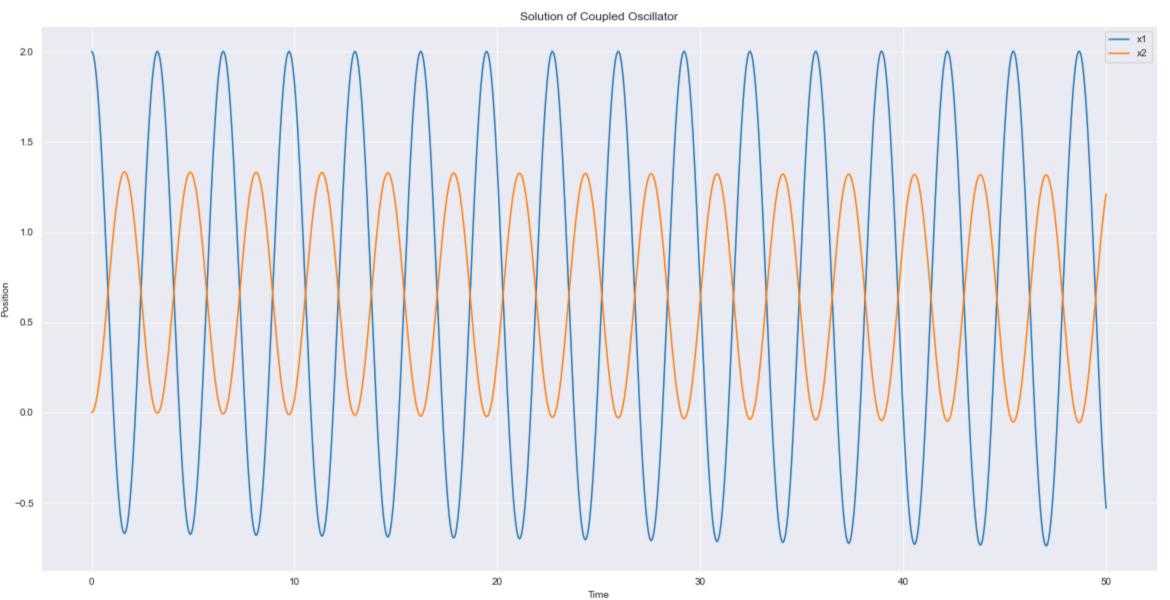
The coupled differential equations we need to solve are:  $m\ddot{x_1} + K(x_1 - x_2) = 0$  and  $m\ddot{x_2} - K(x_1 - x_2) = 0$ .

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import matplotlib.pyplot as plt
         import seaborn as sns
         import math as mth
         import numpy as np
         sns.set_style('darkgrid')
In [5]:
         def f1(t, x1, x2, v1):
             return -(k/m1)*(x1-x2)
         def f2(t,x1,x2,v2):
             return (k/m2)*(x1-x2)
         # take inputs
         k = float(input("Input the value of spring constant:"))
         x10 = float(input("Enter the intial displacement of m1 :"))
         x20 = float(input("Enter the intial displacement of m2 :"))
         m1 = float(input("Enter the mass of m1 :"))
         m2 = float(input("Enter the mass of m2 :"))
         # intial conditions
         v10 = 0 # intial velocities
         v20 = 0
         ti = 0 # time interval
         n = 3000
         h = (tf - ti) / n
         t = ti
         x1 = x10
         x2 = x20
         v1 = v10
         v2 = v20
         x1_list = [x10]
         v1_list = [v10]
         x2_list = [x20]
         v2_list = [v20]
         t_list = [ti]
         for i in range(n):
             #print(t, x1, v1, x2, v2)
             k1x1 = v1
             j1x1 = f1(t, x1, x2, v1)
             k1x2 = v2
             j1x2 = f2(t,x1,x2,v2)
             k2x1 = v1 + (h*j1x1)/2.0
             j2x1 = f1(t+ h/2.0, x1+ (k1x1*h)/2.0, x2+ (k1x2*h)/2.0, v1 + (j1x1*h)/2.0)
             k2x2 = v2 + (h*j1x2)/2.0
             j2x2 = f2(t+ h/2.0, x1+ (k1x1*h)/2.0, x2+ (k1x2*h)/2.0, v2 + (j1x2*h)/2.0)
             k3x1 = v1 + (h*j2x1)/2.0
             j3x1 = f1(t+ h/2.0, x1+ (k2x1*h)/2.0, x2+ (k2x2*h)/2.0, v1 + (j2x1*h)/2.0)
             k3x2 = v2 + (h*j2x2)/2.0
             j3x2 = f2(t+ h/2.0, x1+ (k2x1*h)/2.0, x2+ (k2x2*h)/2.0, v2 + (j2x2*h)/2.0)
             k4x1 = v1 + (h*j3x1)
             j4x1 = f1(t+h, x1+(k3x1*h), x2+(k3x2*h)/2.0, v1+(j3x1*h))
             k4x2 = v2 + (h*j3x2)
             j4x2 = f2(t+ h, x1+ (k3x1*h), x2+ (k3x2*h), v2 + (j3x2*h))
             x1 = x1 + h*(k1x1 + 2.0* k2x1 + 2.0* k3x1 + k4x1)/6.0
             v1 = v1 + h*(j1x1 + 2.0* j2x1 + 2.0* j3x1 + j4x1)/6.0
             x2 = x2 + h*(k1x2 + 2.0* k2x2 + 2.0* k3x2 + k4x2)/6.0
             v2 = v2 + h*(j1x2 + 2.0* j2x2 + 2.0* j3x2 + j4x2)/6.0
             t = t+h
             x1_list.append(x1)
             v1_list.append(v1)
             x2_{list.append(x2)}
             v2_list.append(v2)
             t_list.append(t)
        Input the value of spring constant:10
```

Input the value of spring constant:10
Enter the intial displacement of m1 :2
Enter the intial displacement of m2 :0
Enter the mass of m1 :4
Enter the mass of m2 :8

In [6]:
 plt.plot(t\_list, x1\_list, label = "x1")
 plt.plot(t\_list, x2\_list, label = "x2")
 plt.legend()
 plt.rcParams["figure.figsize"] = (20, 10)
 plt.title("Solution of Coupled Oscillator")
 plt.xlabel("Time")
 plt.ylabel("Position")

Out[6]: Text(0, 0.5, 'Position')



```
In [7]:
    plt.plot(x1_list, v1_list, label = "x1")
    plt.plot(x2_list, v2_list, label = "x2")
    plt.legend()
    plt.rcParams["figure.figsize"] = (20, 10)
    plt.title("phase space of Coupled Oscillator")
    plt.xlabel("position")
    plt.ylabel("velocity")
```

Out[7]: Text(0, 0.5, 'velocity')

