

Lösningarna skall presenteras på ett sådant sätt att räkningar och resonemang blir lätta att följa. Alla svar skall motiveras. Avsluta varje lösning med ett tydligt angivet svar.

- 1 Visa att $z = i/2$ är en rot till $p(z) = 1 + 4z + 4z^2 + 16z^3$, och faktorisera sedan $p(z)$ i linjära faktorer. (5p)

- 2 Låt $T : \mathbb{R}^3 \rightarrow \mathbb{R}^4$ vara den linjära transformationen $T(\mathbf{x}) = A\mathbf{x}$ där

$$A = \begin{bmatrix} -2 & 1 & -3 \\ 4 & 2 & -2 \\ 2 & 2 & -3 \\ 2 & 0 & 1 \end{bmatrix}, \text{ och } \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \in \mathbb{R}^3.$$

- a. Bestäm en bas för värderummet till T . (3p)
b. Avgör om $(4, 4, 5, -1)$ tillhör värderummet till T . (2p)
- 3 Underrummet V till \mathbb{R}^3 som ges av $V = \{(x, y, z) \in \mathbb{R}^3 : 4x - 2y + z = 0\}$ har basen $B = \{(1, 4, 4), (-1, 2, 8)\}$.
a. Bestäm koordinatvektorn för $\mathbf{u} = (1, -1, -6)$ i basen B . (3p)
b. Visa att B bildar en bas till V . (3p)
- 4 Bestäm en matris P som diagonaliserar matrisen A och ange matrisen D som uppfyller $A = PDP^{-1}$, då (5p)

$$A = \begin{bmatrix} 1 & 0 \\ 9 & 4 \end{bmatrix}.$$

- 5 För vilka värden på $a \in \mathbb{R}$ blir $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ linjärt oberoende då $\mathbf{v}_1 = (1, 2, a, 1)$, $\mathbf{v}_2 = (-1, 1, 0, 1)$, och $\mathbf{v}_3 = (1, a, 1, 1)$. (4p)

All solutions should be presented so that calculations and arguments are easy to follow. All answers should be motivated. Each solution should end with a clearly stated answer.

- 1** Show that $z = i/2$ is a root to $p(z) = 1 + 4z + 4z^2 + 16z^3$, and then factor $p(z)$ into linear factors. (5p)

- 2** Let $T : \mathbb{R}^3 \rightarrow \mathbb{R}^4$ be the linear transformation $T(\mathbf{x}) = A\mathbf{x}$ where

$$A = \begin{bmatrix} -2 & 1 & -3 \\ 4 & 2 & -2 \\ 2 & 2 & -3 \\ 2 & 0 & 1 \end{bmatrix}, \text{ and } \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \in \mathbb{R}^3.$$

- a.** Find a basis for the range of T . (3p)
b. Determine if $(4, 4, 5, -1)$ is in the range of T . (2p)
- 3** The subspace V of \mathbb{R}^3 given by $V = \{(x, y, z) \in \mathbb{R}^3 : 4x - 2y + z = 0\}$ has $B = \{(1, 4, 4), (-1, 2, 8)\}$ as basis.
a. Find the coordinate vector of $\mathbf{u} = (1, -1, -6)$ relative to B . (3p)
b. Show that B is a basis for V . (3p)
- 4** Find a matrix P that diagonalize the matrix A and state the matrix D that satisfies $A = PDP^{-1}$, where (5p)

$$A = \begin{bmatrix} 1 & 0 \\ 9 & 4 \end{bmatrix}.$$

- 5** For what values of $a \in \mathbb{R}$ is $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ linearly independent when $\mathbf{v}_1 = (1, 2, a, 1)$, $\mathbf{v}_2 = (-1, 1, 0, 1)$, and $\mathbf{v}_3 = (1, a, 1, 1)$. (4p)

MAA150 Vektoralgebra, HT2016

Assessment criteria for TEN2 2017-01-12

General assessment criteria

All solutions should be presented so that calculations and arguments are easy to follow. All answers should be motivated. Each solution should end with a clearly stated answer.

Points may be deducted for erroneous mathematical statements, calculations, or failure to use proper mathematical notation.

Assessment problems

1. [5 points]
Showing that $i/2$ is a root (1p), finding the root $-i/2$ with motivation (1p), concluding that $z^2 + 1/4$ is a factor (1p), finding the remaining root with long division and correct answer (2p)
2. [5 points]
 - a. Correct method; e.g. relevant row-operations (2p), finding a basis (1p)
 - b. A condition for the vector being in the range of T (1p), checking the condition (1p)
3. [6 points]
 - a. Equation for the coordinates (1p), finding the coordinates (1p), correct coordinate vector (1p)
 - b. Conditions for B being a basis with motivation (1p), checking the conditions (2p)
4. [5 points]
Correct eigenvalues (1p), method of finding the eigenvectors (2p), giving the correct matrices P and D (2p)
5. [4 points]
Condition for linear independence (1p), solving the relevant equation (2p), finding values of a with motivation (1p)

① $z_0 = i/2$, $p(z) = 1 + 4z + 4z^2 + 16z^3$

$$p(i/2) = 1 + 4 \cdot \left(\frac{i}{2}\right) + 4 \cdot \left(\frac{i}{2}\right)^2 + 16 \cdot \left(\frac{i}{2}\right)^3 = 1 + 2i - 2 - 2i = 0 \quad (1p)$$

Since $p(z)$ is a real polynomial $\bar{z}_0 = \overline{\frac{i}{2}} = -\frac{i}{2}$ is also a root. Then both $(1p)$

$(z - \frac{i}{2})$ and $(z + \frac{i}{2})$ are factors in $p(z)$ and therefore also

$$(z - \frac{i}{2}) \cdot (z + \frac{i}{2}) = z^2 + \frac{1}{4} \quad (1p)$$

We use long division to find the remaining linear factor. (In total 3 roots since $\deg(P) = 3$.)

$$\begin{array}{r} 16z + 4 \\ \hline 16z^3 + 4z^2 + 4z + 1 \quad \boxed{z^2 + \frac{1}{4}} \\ - (16z^3 + 4z) \\ \hline 4z^2 + 1 \\ - (4z^2 + 1) \\ \hline 0 \end{array}$$

So $p(z) = (z^2 + \frac{1}{4}) \cdot (16z + 4)$

Answer: $p(z) = (z + \frac{i}{2}) \cdot (z - \frac{i}{2}) \cdot (16z + 4)$ (2p)

Check: $(z^2 + \frac{1}{4}) \cdot (16z + 4) = 16z^3 + 4z^2 + 4z + 1 = p(z)$ ok!

$$\textcircled{2} \text{ a) } \begin{bmatrix} -2 & 1 & -3 \\ 4 & 2 & -2 \\ 2 & 2 & -3 \\ 2 & 0 & 1 \end{bmatrix} \begin{matrix} \textcircled{2} \textcircled{1} \\ \leftarrow \\ \leftarrow \\ \leftarrow \end{matrix} \sim \begin{bmatrix} -2 & 1 & -3 \\ 0 & 4 & -8 \\ 0 & 3 & -6 \\ 0 & 1 & -2 \end{bmatrix} \begin{matrix} \times -\frac{1}{2} \\ \times \frac{1}{4} \\ \times \frac{1}{3} \end{matrix} \sim \begin{bmatrix} 1 & -\frac{1}{2} & \frac{3}{2} \\ 0 & 1 & -2 \\ 0 & 1 & -2 \\ 0 & 1 & -2 \end{bmatrix} \begin{matrix} \\ \textcircled{1} \\ \leftarrow \\ \leftarrow \end{matrix}$$

$$\sim \begin{bmatrix} \textcircled{1} & -\frac{1}{2} & \frac{3}{2} \\ 0 & \textcircled{1} & -2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

↑ ↑ leading ones

(2p)

Therefore $B = \{(-2, 4, 2, 2), (1, 2, 2, 0)\}$ is a basis for the range of T .

(1p)

b) $\vec{v} = (4, 4, 5, -1)$ is in the range of T iff \vec{v} is a linear combination of $(-2, 4, 2, 2)$ and $(1, 2, 2, 0)$, i.e. there exist constants k_1 and k_2 such that

$$(1p) \quad k_1 \begin{bmatrix} -2 \\ 4 \\ 2 \\ 2 \end{bmatrix} + k_2 \begin{bmatrix} 1 \\ 2 \\ 2 \\ 0 \end{bmatrix} = \begin{bmatrix} 4 \\ 4 \\ 5 \\ -1 \end{bmatrix} \quad \text{Solving this gives}$$

$$\left[\begin{array}{cc|c} -2 & 1 & 4 \\ 4 & 2 & 4 \\ 2 & 2 & 5 \\ 2 & 0 & -1 \end{array} \right] \begin{matrix} \textcircled{2} \textcircled{1} \\ \leftarrow \\ \leftarrow \\ \leftarrow \end{matrix} \sim \left[\begin{array}{cc|c} -2 & 1 & 4 \\ 0 & 4 & 12 \\ 0 & 3 & 9 \\ 0 & 1 & 3 \end{array} \right] \sim \left[\begin{array}{cc|c} -2 & 1 & 4 \\ 0 & 1 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right] (1p)$$

which has a solution.

Answer a) $B = \{(-2, 4, 2, 2), (1, 2, 2, 0)\}$ is a basis for V .
b) $(4, 4, 5, -1)$ is in the range of T .

$$(3) B = \{\bar{v}_1, \bar{v}_2\} = \{(1, 4, 4), (-1, 2, 8)\}, \quad \bar{u} = (1, -1, -6)$$

$$V = \{(x, y, z) : 4x - 2y + z = 0\}$$

$$a) (\bar{u})_B = (k_1, k_2) \Leftrightarrow \bar{u} = k_1 \cdot \bar{v}_1 + k_2 \cdot \bar{v}_2 \quad (1p)$$

$$\left[\begin{array}{cc|c} 1 & -1 & 1 \\ 4 & 2 & -1 \\ 4 & 8 & -6 \end{array} \right] \xrightarrow{\substack{-4 \\ -4}} \sim \left[\begin{array}{cc|c} 1 & -1 & 1 \\ 0 & 6 & -5 \\ 0 & 12 & -10 \end{array} \right] \xrightarrow{-2} \sim \left[\begin{array}{cc|c} 1 & -1 & 1 \\ 0 & 6 & -5 \\ 0 & 0 & 0 \end{array} \right] \times \frac{1}{6} \sim$$

$$\sim \left[\begin{array}{cc|c} 1 & -1 & 1 \\ 0 & 1 & -5/6 \\ 0 & 0 & 0 \end{array} \right] \xrightarrow{+1} \sim \left[\begin{array}{cc|c} 1 & 0 & 1/6 \\ 0 & 1 & -5/6 \\ 0 & 0 & 0 \end{array} \right] \Rightarrow \begin{cases} k_1 = 1/6 \\ k_2 = -5/6 \end{cases} \quad (1p)$$

$$\text{Answer: } (\bar{u})_B = (1/6, -5/6)_B \quad (1p)$$

b) V is a plane in \mathbb{R}^3 so $\dim(V) = 2$. Therefore it is enough to show that (i) $B \subset V$ and (ii) B is linearly independent. (1p)

$$(i) \quad \bar{v}_1 \in V: 4 \cdot 1 - 2 \cdot 4 + 4 = 0 \text{ ok!} \quad \text{so } B \subset V \quad (1p)$$

$$\bar{v}_2 \in V: 4 \cdot (-1) - 2 \cdot 2 + 8 = 0 \text{ ok!}$$

$$(ii) \quad B \text{ is linearly independent iff } \begin{bmatrix} 1 & -1 \\ 4 & 2 \\ 4 & 8 \end{bmatrix} \text{ has rank 2.}$$

$$\begin{bmatrix} 1 & -1 \\ 4 & 2 \\ 4 & 8 \end{bmatrix} \text{ (as above)} \sim \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \text{ so it has rank 2.} \quad (1p)$$

Therefore by (i) and (ii) and Thm 4.5.4, B is a basis for V .

④ $A = \begin{bmatrix} 1 & 0 \\ 9 & 4 \end{bmatrix}$. To diagonalize A we need to find eigenvalues and eigenvectors.

$$(CE) \det(A - \lambda I) = \begin{vmatrix} 1-\lambda & 0 \\ 9 & 4-\lambda \end{vmatrix} = (1-\lambda) \cdot (4-\lambda) = 0$$

$$\Leftrightarrow \lambda = 1 \text{ or } \lambda = 4. \quad (1.p)$$

Eigenvectors: $(A - \lambda I)\bar{v} = \bar{0}$, where $\bar{v} = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$

$$\boxed{\lambda=1} \quad \left[\begin{array}{cc|c} 0 & 0 & 0 \\ 9 & 3 & 0 \end{array} \right] \sim \left[\begin{array}{cc|c} 3 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

\uparrow free; set $\bar{v}_2 = 3t$

$$\Rightarrow v_1 = -t, \text{ i.e. } \bar{v} = \begin{bmatrix} -t \\ 3t \end{bmatrix} = t \cdot \begin{bmatrix} -1 \\ 3 \end{bmatrix}$$

so $\begin{bmatrix} -1 \\ 3 \end{bmatrix}$ is an eigenvector for $\lambda=1$.

$$\boxed{\lambda=4} \quad \left[\begin{array}{cc|c} -3 & 0 & 0 \\ 9 & 0 & 0 \end{array} \right] \sim \left[\begin{array}{cc|c} 1 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

\uparrow free; $v_2 = t \Rightarrow v_1 = 0$

Then $\bar{v} = \begin{bmatrix} 0 \\ t \end{bmatrix} = t \cdot \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ so $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$ is an eigenvector for $\lambda=4$. Then

$$P = \begin{bmatrix} -1 & 0 \\ 3 & 1 \end{bmatrix} \text{ and } D = \begin{bmatrix} 1 & 0 \\ 0 & 4 \end{bmatrix} \quad (2.p)$$

Check: $A \cdot P = P \cdot D$?

$$A \cdot P = \begin{bmatrix} 1 & 0 \\ 9 & 4 \end{bmatrix} \cdot \begin{bmatrix} -1 & 0 \\ 3 & 1 \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 3 & 4 \end{bmatrix}, \quad P \cdot D = \begin{bmatrix} -1 & 0 \\ 3 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 \\ 0 & 4 \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 3 & 4 \end{bmatrix} \text{ ok!}$$

5) $\vec{v}_1 = (1, 2, a, 1), \vec{v}_2 = (-1, 1, 0, 1), \vec{v}_3 = (1, a, 1, 1)$

$\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ is linearly independent iff $k_1\vec{v}_1 + k_2\vec{v}_2 + k_3\vec{v}_3 = \vec{0}$ (*) only has the trivial solution $k_1 = k_2 = k_3 = 0$. (1p)

$$\left[\begin{array}{ccc|c} 1 & -1 & 1 & 0 \\ 2 & -1 & a & 0 \\ a & 0 & 1 & 0 \\ 1 & 1 & 1 & 0 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & -1 & 1 & 0 \\ 0 & 3 & a-2 & 0 \\ 0 & a & 1-a & 0 \\ 0 & 2 & 0 & 0 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 0 & 1 & 0 \\ 0 & 0 & a-2 & 0 \\ 0 & 0 & 1-a & 0 \\ 0 & 2 & 0 & 0 \end{array} \right] \sim$$

$$\sim \left[\begin{array}{ccc|c} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & a-2 & 0 \\ 0 & 0 & a-1 & 0 \end{array} \right] \Rightarrow \begin{cases} k_1 + k_3 = 0 \\ k_2 = 0 \\ (a-2)k_3 = 0 \\ (a-1)k_3 = 0 \end{cases} (*) (2p)$$

Regardless of value of $a \in \mathbb{R}$, (*) implies that $k_3 = 0 \Rightarrow k_1 = k_2 = 0$ so $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ is linearly independent for all $a \in \mathbb{R}$. (1p)