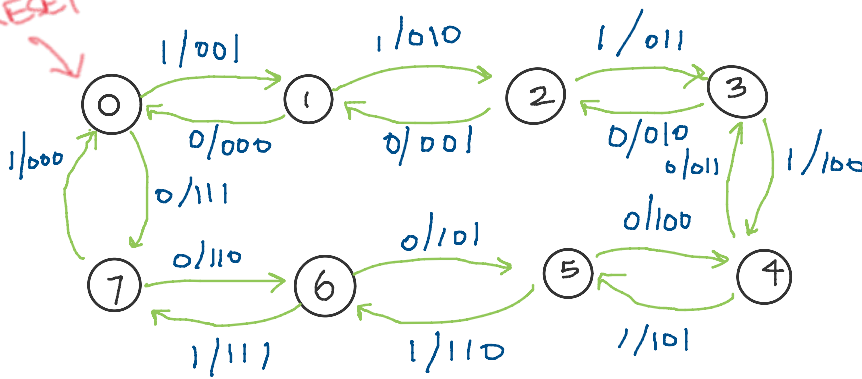


Lab 6: Q2

21 March 2021 07:31

RESET



$$M = \{I, O, S, S_0, \delta, \lambda\}$$

Input (u) := $\{0, 1\}$

States (S) := 3-bit strings

Output (O) := 3-bit strings

$\delta := (\delta_2, \delta_1, \delta_0)$

$\lambda := (\lambda_2, \lambda_1, \lambda_0)$

We are maintaining FSM
s.t. state we are currently in
is the output.

$$\therefore \delta_2 = \lambda_2 ; \quad \delta_1 = \lambda_1 ; \quad \delta_0 = \lambda_0 ;$$

$$S_0 = \{000\}$$

KMAPS:-

$$\delta_2(s_2, s_1, s_0, u) := \overline{s_2} \overline{s_1} \overline{s_0} \overline{u} + \overline{s_2} s_1 s_0 u + s_2 s_1 \overline{s_0} + s_2 \overline{s_1} u + \overline{s_2} s_1 s_0 + s_2 s_0 \overline{u}$$

$\begin{smallmatrix} s_2 s_1 \\ s_0 u \end{smallmatrix}$	00	01	11	10
00	1	0	1	0
01	0	0	1	1
11	0	1	0	1
10	0	0	1	1

$$\delta_1(s_2, s_1, s_0, u) := \overline{s_1} \overline{s_0} \overline{u} + s_1 \overline{s_0} u + \overline{s_1} s_0 u + s_1 s_0 \overline{u}$$

$\begin{smallmatrix} s_2 s_1 \\ s_0 u \end{smallmatrix}$	00	01	11	10
00	1	0	0	1
01	0	1	1	0
11	1	0	0	1
10	0	1	1	0

$$\delta_0(s_a, s_1, s_0, u) := \overline{s_0}$$

$\begin{smallmatrix} s_2 s_1 \\ s_0 u \end{smallmatrix}$	00	01	11	10
00	1	1	1	1
01	1	1	1	1
11	0	0	0	0
10	0	0	0	0

State change / Output

