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The Aluffi algebra of the Jacobian of points in projective space: Torsion-freeness



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ABSTRACT

The algebra in the title has been introduced by P. Aluffi. Let $J\subset I$ be ideals in the commutative ring R. The (embedded) Aluffi algebra of I on R/J is an intermediate graded algebra between the symmetric algebra and Rees Algebra of the ideal I/J over R/J. A pair of ideals has been dubbed an Aluffi torsion-free pair if the surjective map of the Aluffi algebra of I/J onto the Rees algebra of I/J is injective. In this paper we focus on the situation where J is the ideal of points in general linear position in projective space and I is its Jacobian ideal. \bigcirc 2016 Elsevier Inc. All rights reserved.

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1. Introduction

In [1] Aluffi introduced a graded algebra for the purpose of defining a characteristic cycle of a hypersurface in parallel to the well-known conormal cycle in intersection theory. Inspired by this construction, in [7] the first author and then in [8] the first two authors have explored its algebraic side, naming it the Aluffi algebra of a pair of ideals $J \subset I$ (or of I on R/J). A little later, the torsion-freeness problem stated in [8] was considered by the first and the third authors in [9] for a special class of ideals. However, by and large, this question is widely open.

By definition, the (embedded) Aluffi algebra is

$$\mathcal{A}_{R/J}(I/J) := \mathcal{S}_{R/J}(I/J) \otimes_{\mathcal{S}_R(I)} \mathcal{R}_R(I) \simeq \bigoplus_{t \geq 0} I^t/JI^{t-1},$$

where $S_B(\mathfrak{a})$ and $\mathcal{R}_B(\mathfrak{a})$ denote respectively the symmetric and the Rees algebra of an ideal \mathfrak{a} in a ring B. Clearly, there are natural surjections $S_{R/J}(I/J) \twoheadrightarrow \mathcal{A}_{R/J}(I/J) \twoheadrightarrow \mathcal{R}_{R/J}(I/J)$. The kernel of the rightmost surjection, called the *module of Valabrega-Valla* has appeared before in a different context (see [13], also [14, 5.1]):

$$\mathcal{W}_{J\subset I} = \bigoplus_{t>2} \frac{J\cap I^t}{JI^{t-1}}.$$
 (1)

As it turns out, provided I has a regular element module J, the Valabrega–Valla module is the torsion of the Aluffi algebra [8, Proposition 2.5] and, consequently, the Rees algebra of I/J is the Aluffi algebra modulo its torsion. We say that the pair of ideals $J \subset I$ is (Aluffi) torsion-free if $\mathcal{W}_{J\subset I} = \{0\}$. Dealing directly with the Valabrega–Valla module makes the structure of the Aluffi algebra itself slightly invisible. On the bright side, the results get simplified since for an ideal I of quadrics as considered in this paper the heavy work is transferred to the nature of the Jacobian ideal of I. Besides, the existence of non-trivial torsion is often delivered at the level of degree 2 of $\mathcal{W}_{J\subset I}$.

In this work we focus on the case where $J \subset R = k[x_0, \ldots, x_n]$ denotes the ideal of a set of points in projective space $\mathbb{P}^n = \mathbb{P}^n_k$ over an algebraically closed field k, and I denotes the Jacobian ideal of J, i.e., $I = (J, I_n(\Theta))$ where $I_n(\Theta)$ is the ideal of n-minors of the Jacobian matrix Θ of a minimal set of homogeneous generators of J. We will restrict ourselves to the case where the number of points does not exceed 2n, in which case the ideal is generated by forms of degree ≤ 2 [4, Theorem 1.4], consequently Θ has linear entries. In addition, the standing assumption will be that the points are in general linear position.

Now, quite generally, suppose that J is an ideal generated by 2-forms in the standard graded polynomial ring $R = k[x_0, \ldots, x_n]$. In this situation, the Jacobian matrix Θ has linear entries throughout. If $\operatorname{ht}(J) \geq 2$ then, as a particular case of [8, Example 2.19] (see also [9, Proposition 1.5]), knowing that the ideal $I_r(\Theta)$ is the rth power of the irrelevant maximal ideal of R implies that the pair $J \subset (J, I_r(\Theta))$ is Aluffi torsion-free.

The overall tactics we employ follow this path. However, there are some cases where $I_r(\Theta)$ is smaller. These exceptions require a special treatment since the pair $J \subset I$ may still be torsion-free. The finer analysis crosses recent examples of Gorenstein ideals and in one case the underlying geometry has a classical flavor interwoven with additional results from commutative algebra.

The basic preliminary statement of the paper is Theorem 2.3, while the main results concerning the central matter are Proposition 4.1, Proposition 4.5 and Theorem 4.4.

2. Ideal of points generated by quadrics

Let $R = k[\mathbf{X}] = k[x_0, \dots, x_n]$ denote a standard graded polynomial ring over a field k, let $J \subset R$ be a homogeneous ideal and let $I \subset R$ stand for the Jacobian ideal of J, by which we always mean the ideal $(J, I_r(\Theta))$ where $r = \operatorname{ht}(J)$ and $I_r(\Theta)$ stands for the critical ideal of J, i.e., the ideal generated by the r-minors of the Jacobian matrix Θ of a set of generators of J. (It is well-known that the ideal $(J, I_r(\Theta))/J \subset R/J$ does not depend on the choice of generators of J.)

We will henceforth focus on the case of an ideal of points in projective space generated by 2-forms. Let $\Gamma = \{p_1, \ldots, p_s\}$ be a set of distinct points of $\mathbb{P}^n = \mathbb{P}^n_k$, where k is an algebraically closed field and $n \geq 2$. The defining ideal of Γ is the ideal $J = \bigcap_{i=1}^s I(p_i)$ where $I(p_i)$ is the prime ideal of p_i – since we are assuming that k is algebraically closed then $I(p_i)$ is generated by n linear forms. Note that R/J is a reduced ring of dimension one, hence is a Cohen–Macaulay ring. We say that the points in Γ are in general linear position if either $s \leq n$ and the points span a \mathbb{P}^{s-1} , or else $s \geq n+1$, in which case no subset of n+1 points of Γ is contained in a hyperplane of \mathbb{P}^n . We will often use the following facts without further ado: (1) the Aluffi torsion-freeness is invariant under a projective change of coordinates; given two sets each consisting of the same number $s \leq n+2$ of points in general linear position, then there is a projective change of coordinates carrying one onto the other.

2.1. Results for arbitrary n

The following preliminary result will allow us to focus on the case where the number s of points is at least n + 2.

Proposition 2.1. Let $J \subset R$ denote the ideal of $1 \le s \le n+1$ points in general linear position in \mathbb{P}^n . The pair $J \subset I = (J, I_n(\Theta))$ is torsion-free if and only if $s \ne 2$.

Proof. The case s=1 is trivially torsion-free. For s=2, by a projective change of coordinates, the ideal J will be $J=(x_0x_1,x_2,x_3,\ldots,x_n)$ with Jacobian ideal $I=(J,I_n(\Theta))=(x_0,\ldots,x_n)$. Then, for example, $x_0x_1\in J\cap I^2\setminus JI$.

Let $3 \le s \le n$. By a projective change of coordinates, we may assume that the points are the coordinate points $[0:\cdots:0:1:0:\cdots:0]$, where 1 is in the *i*th position

for $i=0,\ldots,s-1$. The defining ideal J of these points is generated by square-free monomials of degree 2 and n-s+1 variables as follows

$$J = (x_i x_j : 0 \le i < j \le s - 1, x_s, \dots, x_n).$$

The Jacobian matrix Θ of J is of the form

$$\Theta = \begin{bmatrix} \frac{\Theta' & 0 & \cdots & 0}{0 & 1 & \cdots & 0} \\ \vdots & & & & \\ 0 & 0 & \cdots & 1 \end{bmatrix},$$

where Θ' is the Jacobian matrix of the defining ideal of s coordinate points in \mathbb{P}^{s-1} . Then, $I_n(\Theta) = I_{s-1}(\Theta') = (x_0, \dots, x_{s-1})^{s-1}$. The Jacobian ideal I is

$$(J, I_n(\Theta)) = (J, (x_0, \dots, x_{s-1})^{s-1}) = (J, x_0^{s-1}, \dots, x_{s-1}^{s-1}).$$

Set $\Delta = (x_0^{s-1}, \dots, x_{s-1}^{s-1}).$

CLAIM: $J \cap \Delta^t \subseteq JI^{t-1}$.

The proof uses the algorithmic procedure for intersection of monomial ideals. Namely, setting $J_1 = (x_s, \ldots, x_n)$ and $J_2 = (x_i x_j : 0 \le i < j \le s - 1)$, one has

$$J \cap \Delta^t = J_1 \cap \Delta^t + J_2 \cap \Delta^t$$
 , $J_1 \cap \Delta^t = J_1 \Delta^t \subset J \Delta^{t-1}$

and

$$J_2 \cap \Delta^t = J_2 \cap \left(x_0^{t(s-1)}, \dots, x_{s-1}^{t(s-1)} \right) + J_2 \cap \left(x_0^{\alpha_0(s-1)} \cdots x_{s-1}^{\alpha_{s-1}(s-1)} \mid \sum_{i=0}^{s-1} \alpha_i = t \right)$$

$$= \sum_{k=0}^{s-1} J_2 \cap \left(x_k^{t(s-1)} \right) + \left(x_0^{\alpha_0(s-1)} \cdots x_{s-1}^{\alpha_{s-1}(s-1)} \mid \sum_{i=0}^{s-1} \alpha_i = t \right).$$

For the first summand it obtains

$$(x_i x_j) \cap (x_k^{t(s-1)}) = \begin{cases} x_k^{t(s-1)} x_j = (x_k x_j) x_k^{t(s-1)-1} & \text{if } i = k \\ x_i x_k^{t(s-1)} = (x_i x_k) x_k^{t(s-1)-1} & \text{if } j = k \\ (x_i x_j) x_k^{t(s-1)} & \text{if } k \neq i, j, \end{cases}$$

hence $\sum_{k=0}^{s-1} J_2 \cap (x_k^{t(s-1)}) \in JI^{t-1}$. Since $s \geq 3$, the second summand belongs to JI^{t-1} and the claim is proved.

Assume next that s = n + 1. By a projective change of coordinates, we may assume that the given points are the coordinate points in \mathbb{P}^n . The defining ideal is generated by

all degree 2 square-free monomials $x_i x_j$, $0 \le i < j \le n$. Since this ideal is the edge ideal of a complete graph, the assertion follows as in [9, Example 3.4(i)]. \square

In the above proposition, if the assumption that the points are in general linear position is omitted, the assertion may fail, as shown in the following example.

Example 2.2. The points $(0,1,0), (0,0,1), (0,1,1) \in \mathbb{P}^2$ lie on the straight line $\{x_0=0\}$ and the ideal of these points is $J=(x_0,x_1x_2(x_1-x_2))$. A calculation with [2] shows that $J \cap I^2 \not\subset JI$ – e.g., $x_1x_2^3(x_1-x_2) \in J \cap I^2 \setminus JI$.

2.2. Explicit generators

As remarked earlier, when $3 \le s \le 2n$ points are in general linear position in \mathbb{P}^n then the corresponding ideal of points J is generated by quadrics. We wish to give further precision to this fact. The following result might exist in some form in the previous literature, but we could not find a definite reference.

Theorem 2.3. Let Γ be a set of $n+2 \leq s \leq 2n$ points in general linear position in \mathbb{P}^n . Let t be an integer running in the interval [2n-s+1,n-1]. Then the corresponding ideal J of points is minimally generated by the quadrics of the form

$$g_{ij} = x_i x_j + \sum_{t=2n-s+1}^{n-1} \alpha_{ij}^{(t)} x_t x_n, \quad (i,j) \in \Lambda,$$

where

$$\Lambda := \{(i,j) \in \{0,\ldots,n\} \times \{0,\ldots,n\} \,|\, (i,j) \neq (t,n) \,\forall t\},\,$$

and $\alpha_{ij}^{(t)} \in k$ are uniquely determined by the coordinates of the points in Γ . In particular, the minimal number of generators $\mu(J)$ of J is $|\Lambda| = \binom{n+1}{2} - (s - (n+2)) = \binom{n+2}{2} - s$, hence lies in the interval $\binom{n}{2} + 1 \le \mu(J) \le \binom{n+1}{2} + 1$.

Proof. Since the points in Γ are in general linear position, we may assume that n+1 of them are the coordinate points and an (n+2)nd point is $[1:1:\ldots:1]$. For the remaining points, write $[a_{h,0}:a_{h,1}:\ldots:a_{h,n-1}:1]$ for $n+3\leq h\leq s$. Consider the system of equations in the unknowns $\alpha_{ij}^{(t)}\in k\ (0\leq i< j\leq n)$:

$$\begin{cases}
1 + \sum_{t=2n-s+1}^{n-1} \alpha_{ij}^{(t)} = 0 \\
a_{h,i} a_{h,j} + \sum_{t=2n-s+1}^{n-1} \alpha_{ij}^{(t)} a_{h,t} = 0, & (n+3 \le h \le s).
\end{cases}$$
(2)

To find $\alpha_{ij}^{(t)}$ it is enough to solve the following matrix equations

$$\begin{bmatrix} 1 & 1 & \cdots & 1 \\ a_{n+3,t} & a_{n+3,t+1} & \cdots & a_{n+3,n-1} \\ \vdots & \vdots & \cdots & \vdots \\ a_{s,t} & a_{s,t+1} & \cdots & a_{s,n-1} \end{bmatrix} \begin{bmatrix} \alpha_{ij}^{(t)} \\ \alpha_{ij}^{(t+1)} \\ \vdots \\ \alpha_{ij}^{(n-1)} \end{bmatrix} = \begin{bmatrix} -1 \\ -a_{n+3,i}a_{n+3,j} \\ \vdots \\ -a_{s,i}a_{s,j} \end{bmatrix}.$$
(3)

Now, since the points are in general linear position, any (n+1)-minor of the following matrix is nonzero.

$$M = \begin{bmatrix} 1 & 0 & \cdots & 0 & 0 & 1 & a_{n+3,0} & \cdots & a_{s,0} \\ 0 & 1 & \cdots & 0 & 0 & 1 & a_{n+3,1} & \cdots & a_{s,1} \\ \vdots & & \ddots & & \vdots & \vdots & & & \vdots \\ 0 & 0 & \cdots & 1 & 0 & 1 & a_{n+3,n-1} & \cdots & a_{s,n-1} \\ 0 & 0 & \cdots & 0 & 1 & 1 & 1 & \cdots & 1 \end{bmatrix}.$$

Then the minor

$$\begin{bmatrix} 1 & 0 & \cdots & 0 & 0 & 0 & \cdots & 0 & 0 \\ 0 & 1 & \cdots & 0 & 0 & 0 & \cdots & 0 & 0 \\ \vdots & & \ddots & \vdots & & \vdots & & \vdots & \vdots & \vdots \\ 0 & 0 & \cdots & 1 & 0 & 0 & \cdots & 0 & 0 \\ 0 & 0 & \cdots & 0 & 0 & 0 & \cdots & 0 & 1 \\ a_{n+3,0} & a_{n+3,1} & \cdots & a_{n+3,t-1} & a_{n+3,t} & a_{n+3,t+1} & \cdots & a_{n+3,n-1} & 1 \\ \vdots & & & \vdots & \vdots & \vdots & \cdots & & \vdots \\ a_{s,0} & a_{s,1} & \cdots & a_{s,t-1} & a_{s,t} & a_{s,t+1} & \cdots & a_{s,n-1} & 1 \end{bmatrix}$$

is nonzero, which implies that the determinant of the first matrix in (3) does not vanish. Therefore, the system (3) has unique solution. Furthermore, by Cramer's rule, $\alpha_{in}^{(t)} \neq 0$ for $0 \le i \le 2n - s$ and $2n - s + 1 \le t \le n - 1$.

Consider the ideal $J' \subset R$ generated by the quadrics g_{ij} as in the statement, where the coefficients $\alpha_{ij}^{(t)} \in k \ (0 \leq i < j \leq n)$ are the uniquely determined solutions of (2). Clearly, the generators of J' vanish on Γ and J is a radical ideal. Therefore, $J' \subseteq J$. We show that J and J' have the same Hilbert function, hence must be equal. Now, one knows by [3] that the ideal J of a set of points in general linear position in \mathbb{P}^n has maximal Hilbert function, that is

$$\dim_k(R/J)_t = s, \quad t > 0.$$

As for J', we claim that its Gröbner basis with respect to the deg-revlex term ordering with $x_0 > x_1 > \ldots > x_n$ is the set

$$G \cup \{x_l^2 x_n + \sum_{t=2n-s+1, t \neq l}^{n-1} \beta_l^{(t)} x_t x_n^2, \ 2n-s+1 \le l \le n-1\},$$
 (4)

where G is the above generating set of J' and each indexed $\beta_l^{(t)}$ is a certain polynomial expression of the α 's. For this, we consider the S-pairs of elements in this set. First, we look at the S-polynomial of g_{0l} and g_{0n} for $2n - s + 1 \le l \le n - 1$ is

$$x_{l} \sum_{t=2n-s+1}^{n-1} \alpha_{0n}^{(t)} x_{t} x_{n} - x_{n} \sum_{t=2n-s+1}^{n-1} \alpha_{0n}^{(t)} x_{t} x_{n}$$

which upon division by the generators of J' is reducible to $f_l = x_l^2 x_n + \sum_{t=2n-s+1, t\neq l}^{n-1} \beta_l^{(t)} x_t x_n^2$, where $\beta_l^{(t)}$ is a certain polynomial like expression in the α 's. Since the initial monomial of each of the f_l 's is not divisible by the initial term of any generator of J' we add these polynomials to the generating set of J'.

Now consider the S-pairs $\{g_{ij}, g_{kl}\}$ of the remaining generators of J', where either $i \neq 0$ or $j \neq n$. The initial monomial of any g_{ij} in the generating set of J' is x_ix_j . Clearly, we may assume that $\{i, j\} \cap \{k, l\} \neq \emptyset$, as otherwise x_ix_j and x_kx_l are relatively prime. Say, i = k and j < l. In this case, the S-polynomial of g_{ij} and g_{kl} is $x_j (\sum_{t=2n-s+1}^{n-1} \alpha_{ij}^{(t)} x_t x_n) - x_l (\sum_{t=2n-s+1}^{n-1} \alpha_{kl}^{(t)} x_t x_n)$. The monomial $x_j x_t x_n$ is divisible by initial term of g_{jt} or f_j and the monomial $x_l x_t x_n$ is divisible by initial term of g_{lt} or f_l . Thus, the remainder of this polynomial upon division by the augmented generating set of J' is zero.

The argument for the cases where i = l, j = k or j = l is entirely similar. As for a pair $\{g_{ij}, f_l\}$, if $j \neq n$ then their initial terms are relatively prime, hence assume j = n. In this case the S-polynomial is

$$x_l^2 \sum_{t=2n-s+1}^{n-1} \alpha_{ij}^{(t)} x_t x_n - x_i \sum_{t=2n-s+1}^{n-1} \beta_l^{(t)} x_t x_n^2.$$

Each term of this polynomial is divisible by the initial term of g_{in} or of f_l . The S-polynomial of a pair $\{f_l, f_{l'}\}$ similarly reduces to zero.

Thus, the following set is a minimal generating set for the initial ideal of J':

$$\{x_i x_j, x_t^2 x_n, 0 \le i < j \le n, (i, j) \ne (t, n), 2n - s + 1 \le t \le n - 1\}.$$

Therefore for any r > 0,

$$\dim_k(R/J')_r = \#\{x_i^r, \ 0 \le i \le n, \ x_t x_n^{r-1}, 2n - s + 1 \le t \le n - 1\} = s,$$

as stated. In particular, $\mu(J) = \dim_k(J_2) = \dim_k(R/J_2) = \binom{n+2}{2} - s$ is the minimal number of generators of J. \square

3. Points in \mathbb{P}^2

3.1. Exceptions

We now consider the case n=2. For $s\leq 3$, the question is taken care by Proposition 2.1.

The case of s=n+2=4 is surprisingly more involved and it turns out that the pair is not Aluffi torsion-free. As will be seen later n=2 is the only dimension for which n+2 points in general linear position are such that the Aluffi algebra of the pair $J \subset I$ is not torsion-free.

We can assume that the four points in general linear position in the projective plane are the coordinate points (1:0:0), (0:1:0), (0:0:1) and the additional point (1:1:1). By Theorem 2.3, the defining ideal is J=(xz-yz,xy-yz), while the Jacobian matrix of these 2-forms is:

$$\Theta = \begin{pmatrix} z & -z & x - y \\ y & x - z & -y \end{pmatrix}$$

Therefore, $I:=(J,I_2(\Theta))=(xy-xz,xz-yz,xz+yz-z^2,-xy+y^2-yz,-x^2+xy+xz)$. A computation with [2] gives that $J\cap I^2$ is minimally generated by 11 quartics, while JI is obviously generated by at most 10 quartics. Therefore, the pair $J\subset I$ is not torsion-free.

Strikingly enough, this example has a curious algebraic-geometric background.

In one end, the underlying algebra will tell us that the ideal I belongs to the class of ideals of k[x, y, z] of finite colength minimally generated by 5 quadrics which happen to be syzygetic in the sense of [11, Section 2]. By [6], these ideals are Gorenstein.

Let φ denote the 5×5 skew-symmetric matrix whose Pfaffians are the generators of I. Pick a new set of indeterminates $\mathbf{T} = \{T_1, T_2, T_3, T_4, T_5\}$ (think of them as the homogeneous coordinates of \mathbb{P}^4) and consider the entries of the matrix product $\mathbf{T} \cdot \varphi$. Next take the Jacobian matrix ψ of these bihomogeneous polynomials of bidegree (1,1) with respect to x, y, z – the so-called Jacobian dual matrix of φ [12]. Note that this a 5×3 matrix whose entries are linear forms in $k[\mathbf{T}]$.

By a known argument as in [5], one can show that the maximal minors of ψ are polynomial relations of the 5 original quadrics. Therefore, since dim k[I] = 3 the codimension of the ideal $I_3(\psi)$ is at most 2. It can further be shown that $I_3(\psi)$ is a prime ideal of codimension 2.

But a lot more is true:

Proposition 3.1. With the above notation we have:

$$\mathcal{R}_R(I) \simeq R[\mathbf{T}]/(I_1(\mathbf{T}.\varphi), I_3(\psi)).$$

Thus, I is an ideal of fiber type. Moreover, $\mathcal{R}_R(I)$ has depth 1 – the lowest possible.

Proof. Since $I_1(\mathbf{T} \cdot \varphi)$ defines the symmetric algebra of I and as a consequence of the above discussion, the ideal $(I_1(\mathbf{T} \cdot \varphi), I_3(\psi)) \subset R[\mathbf{T}]$ is contained in a presentation ideal of $\mathcal{R}_R(I)$ on $R[\mathbf{T}]$ and, moreover, $I_3(\psi)$ is the homogenous defining ideal of k[I]. We must show that the whole ideal $(I_1(\mathbf{T} \cdot \varphi), I_3(\psi))$ is a prime ideal of codimension 4.

In the other end, consider the rational map $\mathbb{P}^2 \dashrightarrow \mathbb{P}^4$ defined by generators of I which is birational onto its image. By [10, Theorem 2.4] one has $\operatorname{rank}(\psi) \equiv 2 \pmod{I_3(\psi)}$ and moreover, the coordinates of any nonzero homogeneous syzygy of ψ modulo $I_3(\psi)$ defines the inverse rational map. In particular, these forms are algebraically independent over k. Actually, they will generate an ideal of linear forms modulo $I_3(\psi)$. From this and from [10, Proposition 2.1] now follows that $(I_1(\mathbf{T} \cdot \varphi), I_3(\psi))$ is a presentation ideal of $\mathcal{R}_R(I)$ on $R[\mathbf{T}]$. For the proof that $\mathcal{R}_R(I)$ has depth 1 see [6, Theorem 2.1 (ii)]. \square

It is possible to write down the presentation ideal of the Aluffi algebra as well, based on the presentation ideal in the above proposition. Although hardly useful at this point, we can moreover compute the torsion of the Aluffi algebra, the latter being generated by two forms in degree 2.

To understand the underlying geometric content, consider the rational map \mathcal{F} : $\mathbb{P}^2 \dashrightarrow \mathbb{P}^4$ defined by five sufficiently general quadrics $\mathbf{q} = \{q_1, q_2, q_3, q_4, q_5\} \subset R$. It is classically known that the image of this map is a surface obtained as a general projection of the 2-Veronese embedding of \mathbb{P}^2 in \mathbb{P}^5 . Therefore, the integral closure of the homogeneous coordinate ring of the image (i.e., the k-subalgebra $k[\mathbf{q}] \subset R$ up to an obvious degree normalization) is the Veronese algebra $R^{(2)}$. Write $P \subset k[\mathbf{T}]$ for the homogeneous defining ideal of the image of \mathcal{F} . By geometric considerations, one knows that the homogeneous defining ideal of this smooth surface is generated by 7 cubic forms. To subsume the geometry under the algebra, one checks that the ideal generated by 5 sufficiently general quadrics is syzygetic. Perhaps remarkable is that then the cubic forms can be taken to be the minimal generators of the ideal of maximal minors of the well-structured 5×3 matrix described above.

3.2. When is the critical locus a power?

Quite generally, suppose that $J \subset R$ is an ideal generated by 2-forms. In this situation, the Jacobian matrix Θ has linear entries throughout. If $\operatorname{ht}(J) \geq 2$ then, as a particular case of [8, Example 2.19] (see [9, Proposition 1.5]), knowing that $I_r(\Theta)$ is the rth power of the irrelevant maximal ideal of R, implies that the pair $J \subset (J, I_r(\Theta))$ is Aluffi torsion-free. It seemed reasonable to conjecture in [9] that it is always the case that $I_r(\Theta)$ is \mathfrak{m} -primary if and only if it coincides with the rth power of $\mathfrak{m} = (x_0, \ldots, x_n)$ [9, Conjecture 2.6]. Unfortunately, this conjecture is not true in all its generality as shown in the following example.

Example 3.2. Consider the 6 points in \mathbb{P}^3_k , which are written as columns of the following matrix:

$$\begin{pmatrix}
1 & 0 & 0 & 0 & 1 & -1 \\
0 & 1 & 0 & 0 & 1 & 2 \\
0 & 0 & 1 & 0 & 1 & 3 \\
0 & 0 & 0 & 1 & 1 & 1
\end{pmatrix}$$

They are in general linear position since all the 4-minors are nonzero. By Theorem 2.3, one has

$$J = (x_0x_1 - 5x_1x_3 + 4x_2x_3, x_0x_2 - 6x_1x_3 + 5x_2x_3, x_0x_3 - 4x_1x_3 + 3x_2x_3, x_1x_2 - 4x_1x_3 + 3x_2x_3).$$

A computation with [2] yields

- $I = (J, x_1x_3^2, x_2x_3^2, x_0^3, x_1^3, x_2^3, x_3^3)$
- m³ ⊂ I
- $\mu(I_3(\Theta)) = 16$ (hence $\mathfrak{m}^3 \neq I_3(\Theta)$)

Still, since $\mathfrak{m}^3 \subset I$ and the inclusion $I_3(\Theta) \subset \mathfrak{m}^3$ always holds, then $I = (J, \mathfrak{m}^3)$ hence, the pair $J \subset I$ is torsion-free by [8, Example 2.19].

Remark 3.3. It may be contended that the above example, although in general linear position, is not "general enough". However, a computation with random coordinates for the points yields the same result, so the failure is due to the nature of the given data, no matter what sort of stronger general position notion is assumed.

Examining closely the data of the above example, the following might be a more realistic question.

Question 3.4. Let J be generated in degree 2 and assume that $r := \operatorname{ht}(J) > 2$. If $I_r(\Theta)$ is \mathfrak{m} -primary and $I := (J, I_r(\Theta))$ contains at least the pure powers x_0^r, \ldots, x_n^r , does then $\mathfrak{m}^r \subset I$ (and hence, $I = (J, \mathfrak{m}^r)$)?

4. Points in \mathbb{P}^n

4.1. Points in \mathbb{P}^n $(n \geq 3)$

In this part we assume that $n \geq 3$. Recall the negative sort of result in Example 3.2 for s = n + 3, where it has been seen that the critical ideal $I_n(\Theta)$ is not always a power of the irrelevant $R_+ = \mathfrak{m}$ even though the pair $J \subset (J, I_n(\Theta))$ is torsion-free. Clearly, the inclusion $I_n(\Theta) \subset \mathfrak{m}^n$ always holds as they are both generated in degree n

Yet, for s = n + 2 one has:

Proposition 4.1. Let Γ be a set of n+2 distinct points in general linear position in \mathbb{P}^n with $n \geq 3$. Let $J \subset R = k[x_0, \ldots, x_n]$ be the corresponding ideal of points. Then $I_n(\Theta) = \mathfrak{m}^n$; in particular the pair $J \subset (J, I_n(\Theta))$ is torsion-free.

Proof. By Theorem 2.3, up to a projective change of coordinates J is generated by the following quadrics

$$\{x_i x_j - x_{n-1} x_n, \ 0 \le i < j \le n, \ (i,j) \ne (n-1,n)\}.$$
 (5)

Then J is the "canonical" submaximal ideal of quadrics of the square-free Veronese Cohen–Macaulay ideal $K = (x_i x_j, 0 \le i < j \le n)$ (edge ideal of the complete (n+1)-graph). The transposed Jacobian matrix $\Theta(K)^t$ of K is the well-known Koszul matrix of K "without signs", hence its ideal of u-minors is \mathfrak{m}^u for every $u \le n$.

After applying to $\Theta(K)^t$ elementary column operations consisting of subtracting the last column from the remaining columns, one easily sees that

$$\Theta(K)^{t} = \begin{bmatrix} \Theta(J)^{t} & 0 \\ 0 & \vdots \\ 0 & x_{n} \\ x_{n-1} \end{bmatrix}.$$

A straightforward calculation now gives the equality $I_n(\Theta(J))^t = I_n(\Theta(K))^t = \mathfrak{m}^n$. \square

Remark 4.2. (1) An alternative inductive argument would depend on writing

$$\Theta(J)^t = \begin{bmatrix} x_1 & x_2 & \cdots & x_n & 0 & \cdots & 0 \\ & & & & & & & \\ & & * & & & \Theta' & \end{bmatrix},$$

where Θ' is the transposed Jacobian matrix of the ideal of suitable n+1 points in general linear position in \mathbb{P}_k^{n-1} viewed in coordinate x_1, \ldots, x_n . But the procedure would work as far down as from n=4 to n=3. In dimension 3 a direct argument would be required, since the statement of the Proposition is false for n=2.

(2) The ideal J is Gorenstein, pretty much as in the full Veronese case, corresponding to the situation of finite colength [6]. It would be interesting to study this class of 1-dimensional Gorenstein ideals.

We introduce a notion weaker than general linear position:

Definition 4.3. Let Γ denote a set of $s \geq n+2$ distinct points in \mathbb{P}^n . We say that Γ is in hyperplane linear position if it admits s-1 points spanning a hyperplane $H \subset \mathbb{P}^n$ and in general linear position as points of the $\mathbb{P}^{n-1} \simeq H$, while the remaining point of Γ lies outside H.

Theorem 4.4. Let Γ be a set of n+2 distinct points in hyperplane linear position in \mathbb{P}^n , where $n \geq 2$. Let $J \subset R = k[x_0, \dots, x_n]$ denote the corresponding ideal of points. Then the pair $J \subset (J, I_n(\Theta))$ is torsion-free.

Proof. By a projective change of coordinates one may assume that $H: \{x_n = 0\}$. Further, by identifying H with \mathbb{P}^{n-1} , we may assume that the n+1 points lying on H are the coordinate points of $H = \mathbb{P}^{n-1}$ and the "diagonal unit" point, stacking 0 as the nth coordinate of each of these points as point of \mathbb{P}^n . In addition, concatenating the matrix of the coordinates of these n+1 points with the vector of coordinates of the remaining point and then applying elementary column operations, we may assume that the last point is $(0:0:\cdots:0:1)$. This gives the matrix of points coordinates

$$\begin{pmatrix} 1 & 0 & \cdots & 0 & 1 & 0 \\ 0 & 1 & \cdots & 0 & 1 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots & \vdots \\ 0 & 0 & \cdots & 1 & 1 & 0 \\ \hline 0 & 0 & \cdots & 0 & 0 & 1 \end{pmatrix}.$$

The surprise in this weaker setup is that, even for n=2 the pair $J\subset I$ is torsion-free. Indeed, an immediate calculation gives

$$J = (x_1, x_2) \cap (x_0, x_2) \cap (x_0 - x_1, x_2) \cap (x_0, x_1) = (x_0 x_2, x_1 x_2, x_0 x_1 (x_0 - x_1)).$$

(Note the exceptional behavior: there is a minimal generator of degree 3.)

Another direct calculation yields $I=(x_0^3,x_0^2x_1,x_0x_1^2,x_1^3,x_0x_2,x_1x_2,x_2^2)$. Now, a computation with [2] yields that the relation type of I/J on R/J is 2 (note that this result is a bit elusive, as a set of minimal generators of I contains one of J, yet the ideal of R generated by the complementary subset of minimal generators of I has relation type 3). Then, by [8, Corollary 2.17] it suffices to check that $J \cap I^2 \subset JI$. An additional elementary computation with [2] yields this inclusion.

Now suppose that $n \geq 3$. In this case we show that $I_n(\Theta(J)) = \mathfrak{m}^n$ by a similar argument as in the proof of the preceding proposition. For that, we need to know a set of minimal generators of J.

CLAIM:
$$J = (x_i x_i - x_{n-2} x_{n-1}, x_i x_n, 0 \le i < j \le n-1).$$

(Note that we cannot use Theorem 2.3 automatically since Γ is not in general linear position, hence one needs a different approach.)

From the shape of the coordinates of the points, J surely contains the ideal J' generated by these 2-forms. In order to show that J = J' we prove that the respective Hilbert functions coincide (a debate one could avoid by providing a direct proof that J' is a saturated ideal of multiplicity (degree) n + 2).

Write $\Gamma = \Gamma_1 \cup \Gamma_2$ where Γ_1 is the set of n+1 points spanning H and Γ_2 is the set consisting of the unique point not on H. Since Γ_1 is in general linear position as points up to change of coordinates in \mathbb{P}^{n-1} , then Theorem 2.3 is applicable, hence as in (5) its ideal of points is

$$J_{\Gamma_1} = (x_i x_j - x_{n-2} x_{n-1}, x_n, \ 0 \le i < j \le n-1).$$

Clearly, $J_{\Gamma_2}=(x_0,x_1,\ldots,x_{n-1}).$ Since $J=J_{\Gamma_1}\cap J_{\Gamma_2},$ one has a short exact sequence

$$0 \longrightarrow R/J \longrightarrow R/J_{\Gamma_1} \oplus R/J_{\Gamma_2} \longrightarrow R/(J_{\Gamma_1}, J_{\Gamma_2}) \longrightarrow 0.$$

Direct inspection gives

$$R/(J_{\Gamma_1}, J_{\Gamma_2}) \simeq k$$
, $R/J_{\Gamma_1} \simeq k[x_0, \dots, x_{n-1}]/(x_i x_j - x_{n-2} x_{n-1})$, $R/J_{\Gamma_2} \simeq k[x_n]$.

By the additive property of Hilbert function, we derive the Hilbert function of R/J:

$$\mathrm{Hilb}_{R/J}(0) = 1$$
, $\mathrm{Hilb}_{R/J}(1) = n + 1$, $\mathrm{Hilb}_{R/J}(t) = n + 2$, $t \ge 2$.

For the Hilbert function of R/J', we compute a Gröbner basis of J' in the lex order with $x_0 > x_1 > \cdots > x_n$. By a similar argument as in proof on the Theorem 2.3, we can show that a Gröbner basis is

$$\{x_ix_j - x_{n-2}x_{n-1}, x_ix_n, \ x_{n-2}^2x_{n-1} - x_{n-2}x_{n-1}^2, \quad 0 \le i < j \le n-1\}.$$

The initial ideal of J' is generated by $\{x_ix_j, x_{n-2}^2x_n, 0 \leq i < j \leq n, i \neq n-2 \}$. The rest is as in the end of the proof of Theorem 2.3, thus showing that J = J', as claimed.

We now argue that the pair $J \subset I$ is Aluffi torsion-free by showing that $I_n(\Theta(J)) = \mathfrak{m}^n$, in pretty much the same way as was argued in the proof of Proposition 4.1. Namely, we consider the squarefree Veronese "hull" of J:

$$K = (x_i x_j, \ 0 \le i < j \le n) = (x_i x_j, \ 0 \le i < j \le n - 1; x_0 x_n, \dots, x_{n-1} x_n),$$

from which the above set of generators of J is obtained by some obvious elementary transformations of the generators of K.

Accordingly, up to the same elementary operations applied to the corresponding columns of $\Theta(K)^t$, we get

$$\Theta(K)^{t} = \begin{bmatrix} & 0 & 0 \\ 0 & \vdots & \vdots \\ \Theta(J)^{t} & 0 & \vdots \\ x_{n-2} & x_{n-1} & 0 \end{bmatrix}.$$

A straightforward calculation now gives the equality $I_n(\Theta(J))^t = I_n(\Theta(K))^t = \mathfrak{m}^n$, where as before the last equality comes from the structure of $\Theta(K)^t$ as Koszul matrix without signs. \square

4.2. Points in \mathbb{P}^n $(n \geq 4)$

Proposition 4.5. Let Γ be a set of n+3 distinct points in general linear position in \mathbb{P}^n_k with $n \geq 4$. Let $J \subset R = k[x_0, \dots, x_n]$ be the defining ideal of Γ and let $I = (J, I_n(\Theta))$ stand for the Jacobian ideal of J. Then the pair $J \subset I$ is Aluffi torsion-free.

Proof. Since Γ is in general linear position, we may assume that n+1 of them are the coordinate points and an (n+2)nd point is $[1:1:\ldots:1]$. Let $[a_0:\ldots:a_{n-1}:1]$ denote the (n+3)rd point. Note that the general linear position property of points implies that $a_{n-2} \neq a_{n-1}$.

By Theorem 2.3, the defining ideal of these points is

$$J = (x_i x_j + \alpha_{ij}^{(n-2)} x_{n-2} x_n - \alpha_{ij}^{(n-1)} x_{n-1} x_n ,$$

$$0 \le i < j \le n, \ (i,j) \ne (n-2,n), (n-1,n))$$

where $\alpha_{ij}^{(n-2)} = \frac{a_{n-1} - a_i a_j}{a_{n-2} - a_{n-1}}, \ \alpha_{ij}^{(n-1)} = \frac{a_i a_j - a_{n-2}}{a_{n-2} - a_{n-1}}.$

The transposed Jacobian matrix of J has the form

$$\Theta = \begin{bmatrix} x_1 & x_2 & \cdots & x_n & 0 & \cdots & 0 \\ & & & & & & \Theta' & \end{bmatrix},$$

where Θ' is the transposed Jacobian matrix of the defining ideal of n+2 points in general linear position in \mathbb{P}^{n-1} with coordinate x_1, \ldots, x_n . Then the result follows by induction on n, except when n=4 and s=4+3=7 as in this case Θ' is the Jacobian matrix of n+2=6 points in \mathbb{P}^{n-1} , when the minors of Θ' do not generate the entire power of \mathfrak{m} . Thus, in this case one needs a direct argument, as follows.

According to Theorem 2.3, a generating set of J consists of the following polynomials:

$$x_0x_1 + \alpha_{01}^{(2)}x_2x_4 + \alpha_{01}^{(3)}x_3x_4 \quad , \quad x_1x_2 + \alpha_{12}^{(2)}x_2x_4 + \alpha_{12}^{(3)}x_3x_4$$

$$x_0x_2 + \alpha_{02}^{(2)}x_2x_4 + \alpha_{02}^{(3)}x_3x_4 \quad , \quad x_1x_3 + \alpha_{13}^{(2)}x_2x_4 + \alpha_{13}^{(3)}x_3x_4$$

$$x_0x_3 + \alpha_{03}^{(2)}x_2x_4 + \alpha_{03}^{(3)}x_3x_4 \quad , \quad x_1x_4 + \alpha_{14}^{(2)}x_2x_4 + \alpha_{14}^{(3)}x_3x_4$$

$$x_0x_4 + \alpha_{04}^{(2)}x_2x_4 + \alpha_{04}^{(3)}x_3x_4 \quad , \quad x_2x_3 + \alpha_{23}^{(2)}x_2x_4 + \alpha_{23}^{(3)}x_3x_4.$$

The Jacobian matrix of J therefore has the form:

$$\Theta = \begin{bmatrix} x_1 & x_0 & \alpha_{01}^{(2)}x_4 & \alpha_{01}^{(3)}x_4 & \alpha_{01}^{(2)}x_2 + \alpha_{01}^{(3)}x_3 \\ x_2 & 0 & x_0 + \alpha_{02}^{(2)}x_4 & \alpha_{02}^{(3)}x_4 & \alpha_{02}^{(2)}x_2 + \alpha_{02}^{(3)}x_3 \\ x_3 & 0 & \alpha_{03}^{(2)}x_4 & x_0 + \alpha_{03}^{(3)}x_4 & \alpha_{03}^{(2)}x_2 + \alpha_{03}^{(3)}x_3 \\ x_4 & 0 & \alpha_{04}^{(2)}x_4 & \alpha_{03}^{(3)}x_4 & x_0 + \alpha_{04}^{(2)}x_2 + \alpha_{04}^{(3)}x_3 \\ \hline 0 & x_2 & x_1 + \alpha_{12}^{(2)}x_4 & \alpha_{12}^{(3)}x_4 & \alpha_{12}^{(2)}x_2 + \alpha_{12}^{(3)}x_3 \\ 0 & x_3 & \alpha_{13}^{(2)}x_4 & x_1 + \alpha_{13}^{(3)}x_4 & \alpha_{13}^{(2)}x_2 + \alpha_{13}^{(3)}x_3 \\ 0 & x_4 & \alpha_{14}^{(2)}x_4 & \alpha_{14}^{(3)}x_4 & x_1 + \alpha_{14}^{(2)}x_2 + \alpha_{13}^{(3)}x_3 \\ 0 & 0 & x_3 + \alpha_{23}^{(2)}x_4 & x_2 + \alpha_{23}^{(3)}x_4 & \alpha_{23}^{(2)}x_2 + \alpha_{23}^{(3)}x_3 \end{bmatrix},$$

where the lower right block is the Jacobian matrix of six points in general linear position in \mathbb{P}^3 with coordinates x_1, x_2, x_3, x_4 . By Example 3.2, $(x_1, x_2, x_3, x_4)^3 \subseteq (J_{x_0}, I_3(\Theta_{x_0}))$. Then, $(x_1, x_2, x_3, x_4)^4 \subseteq (J, I_4(\Theta))$. By changing the roles of x_0 and x_1 , we get $(x_0, x_2, x_3, x_4)^3 \subseteq (J_{x_1}, I_3(\Theta_{x_1}))$ and $(x_0, x_2, x_3, x_4)^4 \subseteq (J, I_4(\Theta))$, where J_{x_i} and Θ_{x_i} for i = 0, 1, denote the ideal and its Jacobian matrix of six points in coordinates x_1, x_2, x_3, x_4 and x_0, x_2, x_3, x_4 , respectively. By inspection one can see that $x_0^3 x_1, x_0^2 x_1^2, x_0 x_1^3 \in (J, I_4(\Theta))$. Therefore, $(x_0, x_1, x_2, x_3, x_4)^4 \subseteq (J, I_4(\Theta))$, thus yielding $I = (J, I_4(\Theta)) = (J, \mathfrak{m}^4)$ and hence, $J \subseteq I$ is Aluffi torsion-free. \square

We close with the following conjecture and example.

Conjecture 4.6. Let Γ be a set of s=2n distinct points in general position in \mathbb{P}^n with $n \geq 4$. Let $J \subset R = k[x_0, \ldots, x_n]$ be the defining ideal of Γ and let $I = (J, I_n(\Theta))$ stand for the Jacobian ideal of J. Then $I_n(\Theta) = \mathfrak{m}^n$. In particular, the pair $J \subset I$ is Aluffi torsion-free.

Note that by Example 3.2 the above conjecture is not valid for the case n=3. As a consequence of this conjecture, using a similar argument as the induction step in the proof of the Proposition 4.5, one can deduce the Aluffi torsion freeness of $n+4 \le s \le 2n$ points in general linear position in \mathbb{P}^n .

Example 4.7. Consider the 8 points in \mathbb{P}^4 which are written as columns of the following matrix:

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 1 & 1/2 & 1/2 \\ 0 & 1 & 0 & 0 & 0 & 1 & 1 & 4 \\ 0 & 0 & 1 & 0 & 0 & 1 & -2 & -3 \\ 0 & 0 & 0 & 1 & 0 & 1 & 3 & 2 \\ 0 & 0 & 0 & 0 & 1 & 1 & -1/2 & -1 \end{pmatrix}.$$

All 5-minors of this matrix are non-zero thus these points are in general linear position. By Theorem 2.3 the ideal J is generated by the following polynomials:

$$x_0 x_1 - \frac{4}{5} x_2 x_4 - \frac{1}{5} x_3 x_4 \quad , \quad x_1 x_2 - \frac{9}{4} x_1 x_4 + \frac{11}{10} x_2 x_4 + \frac{3}{20} x_3 x_4$$

$$x_0 x_2 - \frac{1}{8} x_1 x_4 - \frac{3}{20} x_2 x_4 - \frac{29}{40} x_3 x_4 \quad , \quad x_1 x_3 + \frac{1}{4} x_1 x_4 - \frac{19}{10} x_2 x_4 + \frac{13}{20} x_3 x_4$$

$$x_0 x_3 - \frac{3}{4} x_1 x_4 - \frac{9}{10} x_2 x_4 + \frac{13}{20} x_3 x_4 \quad , \quad x_2 x_3 + \frac{5}{4} x_1 x_4 + \frac{13}{10} x_2 x_4 - \frac{71}{20} x_3 x_4$$

$$x_0 x_4 - \frac{1}{4} x_1 x_4 - \frac{2}{5} x_2 x_4 - \frac{7}{20} x_3 x_4 .$$

A computation with Macaulay [2] shows that $I_4(\Theta) = (x_0, x_1, x_2.x_3, x_4)^4$, where Θ is the Jacobian matrix of J.

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