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List decoding algorithm based on voting in Gröbner bases for general one-point AG codes ☆

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ABSTRACT

We generalize the unique decoding algorithm for one-point AG codes over the Miura–Kamiya C_{ab} curves proposed by Lee et al. (2012) to general one-point AG codes, without any assumption. We also extend their unique decoding algorithm to list decoding, modify it so that it can be used with the Feng–Rao improved code construction, prove equality between its error correcting capability and half the minimum distance lower bound by Andersen and Geil (2008) that has not been done in the original proposal except for one-point Hermitian codes, remove the unnecessary computational steps so that it can run faster, and analyze its computational complexity in terms of multiplications and divisions in the finite field. As a unique decoding algorithm, the proposed one is empirically and theoretically as fast as the BMS algorithm for one-point Hermitian codes. As a list decoding algorithm, extensive experiments suggest that it can be much faster for many moderate size/usual inputs than the algorithm by Beelen and Brander (2010). It should be noted that as a list decoding algorithm the proposed method seems to have exponential worst-case computational complexity while the previous proposals (Beelen and Brander, 2010; Guruswami and Sudan, 1999) have polynomial ones, and that the proposed method is expected to be slower than the previous proposals for very large/special inputs.

☆ The proposed algorithm in this paper was published without any proof of its correctness in Proc. 2012 IEEE International Symposium on Information Theory, Cambridge, MA, USA, July 2012, pp. 86–90 (Geil et al., 2012).

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1. Introduction

We consider the list decoding of one-point algebraic geometry (AG) codes. Guruswami and Sudan (1999) proposed the well-known list decoding algorithm for one-point AG codes, which consists of the interpolation step and the factorization step. The interpolation step has large computational complexity and many researchers have proposed faster interpolation steps, see Beelen and Brander (2010, Fig. 1).

By modifying the unique decoding algorithm (Lee et al., 2012) for primal one-point AG codes, we propose another list decoding algorithm based on voting in Gröbner bases whose error correcting capability is higher than Guruswami and Sudan (1999) and whose computational complexity is empirically smaller than Beelen and Brander (2010), Guruswami and Sudan (1999) in many cases that are examined and reported in our computational experiments. It should be noted that as a list decoding algorithm the proposed method seems to have exponential worst-case computational complexity while the previous proposals (Beelen and Brander, 2010; Guruswami and Sudan, 1999) have polynomial ones, and that the proposed method is expected to be slower than the previous proposals for very large/special inputs. A decoding algorithm for primal one-point AG codes was proposed in Matsumoto and Miura (2000c), which was a straightforward adaptation of the original Feng–Rao majority voting for the dual AG codes (Feng and Rao, 1993) to the primal ones. The Feng–Rao majority voting in Matsumoto and Miura (2000c) for one-point primal codes was generalized to multi-point primal codes in Beelen and Høholdt (2008, Section 2.5). The one-point primal codes can also be decoded as multi-point dual codes with majority voting (Beelen, 2007; Duursma et al., 2011; Duursma and Park, 2010), whose faster version was proposed in Sakata and Fujisawa (2011) for the multi-point Hermitian codes. Lee et al. (2012) proposed another unique decoding (not list decoding) algorithm for primal codes based on the majority voting inside Gröbner bases. The module used by them (Lee et al., 2012) is a curve theoretic generalization of one used for Reed–Solomon codes in Ali and Kuijper (2011) that is a special case of the module used in Lee and O'Sullivan (2008). An interesting feature in Lee et al. (2012) is that it did not use differentials and residues on curves for its majority voting, while they were used in Beelen and Høholdt (2008), Matsumoto and Miura (2000c). The above studies (Beelen and Høholdt, 2008; Lee et al., 2012; Matsumoto and Miura, 2000c) dealt with the primal codes. We recently proved in Geil et al. (2013) that the error-correcting capabilities of Lee et al. (2012), Matsumoto and Miura (2000c) are the same. The earlier papers (Duursma, 1994; Pellikaan, 1993) suggest that central observations in Andersen and Geil (2008), Geil et al. (2013), Matsumoto and Miura (2000c) were known to the Dutch group, which is actually the case (Duursma, 2012). Chen (1999), Elbrønd Jensen et al. (1999) and Bras-Amorós and O'Sullivan (2006) studied the error-correcting capability of the Feng–Rao (Feng and Rao, 1993) or the BMS algorithm (Sakata et al., 1995a, 1995b) with majority voting beyond half the designed distance that are applicable to the dual one-point codes.

There was room for improvements in the original result (Lee et al., 2012), namely, (a) they have not clarified the relation between its error-correcting capability and existing minimum distance lower bounds except for the one-point Hermitian codes, (b) they have not analyzed the computational complexity, (c) they assumed that the maximum pole order used for code construction is less than the code length, and (d) they have not shown how to use the method with the Feng–Rao improved code construction (Feng and Rao, 1995). We shall (1) prove that the error-correcting capability of the original proposal is always equal to half of the bound in Andersen and Geil (2008) for the minimum distance of one-point primal codes (Proposition 7), (2) generalize their algorithm to work with any one-point AG codes, (3) modify their algorithm to a list decoding algorithm, (4) remove the assumptions (c) and (d) above, (5) remove unnecessary computational steps from the original proposal, (6) analyze the computational complexity in terms of the number of multiplications and divisions in the finite field. We remark that a generalization of Lee et al. (2012) to arbitrary primal AG code is also reported in Lee et al. (2014) using a similar idea in this paper reported earlier as a conference paper (Geil et al., 2012).

The proposed algorithm is implemented on the Singular computer algebra system (Decker et al., 2011), and we verified that the proposed algorithm can correct more errors than Beelen and Brander

(2010), Guruswami and Sudan (1999) with manageable computational complexity in many cases that are examined and reported in our computational experiments.

This paper is organized as follows: Section 2 introduces notations and relevant facts. Section 3 improves Lee et al. (2012) in various ways, and the differences to the original (Lee et al., 2012) are summarized in Section 3.8. Section 4 shows that the proposed modification to Lee et al. (2012) works as claimed. Section 5 compares its computational complexity with the conventional methods. Section 6 concludes the paper. Part of this paper was presented at 2012 IEEE International Symposium on Information Theory, Cambridge, MA, USA, July 2012 (Geil et al., 2012).

2. Notation, preliminaries and the statement of problem

Our study heavily relies on the standard form of algebraic curves introduced independently by Geil and Pellikaan (2002) and Miura (1998), which is an enhancement of earlier results (Miura, 1993; Saints and Heegard, 1995). Let $F/\mathbf{F}_q$ be an algebraic function field of one variable over a finite field $\mathbf{F}_q$ with q elements. Let g be the genus of F. Fix $n+1$ distinct places $Q, P_1, \ldots, P_n$ of degree one in F and a nonnegative integer u. We consider the following one-point algebraic geometry (AG) code

$$C_u = \{\mathrm{ev}(f) \mid f \in \mathcal{L}(uQ)\} \tag{1}$$

where $\mathrm{ev}(f) = (f(P_1), \ldots, f(P_n))$.

The problem considered in this paper is as follows: We use a linear code C_u (or its improved version C_Γ defined in Eq. (4)). A codeword in C_u (or C_Γ) is transmitted, and the receiver receives $\vec{r} \in \mathbf{F}_q^n$. A list-decoding algorithm with a decoding radius τ finds all the codewords in C_u (or C_Γ) whose Hamming distances from $\vec{r}$ are within τ. Our aim is to propose another list-decoding algorithm based on Gröbner bases and demonstrate its computational complexity in a wide range of examples.

Suppose that the Weierstrass semigroup $H(Q)$ at Q is generated by $a_1, \ldots, a_t$, and choose t elements $x_1, \ldots, x_t$ in F whose pole divisors are $(x_i)_\infty = a_i Q$ for $i = 1, \ldots, t$. We do *not* assume that a_1 is the smallest among $a_1, \ldots, a_t$. Without loss of generality we may assume the availability of such $x_1, \ldots, x_t$, because otherwise we cannot find a basis of C_u for every u. Then we have that $\mathcal{L}(\infty Q) = \cup_{i=1}^{\infty} \mathcal{L}(iQ)$ is equal to $\mathbf{F}_q[x_1, \ldots, x_t]$ (Saints and Heegard, 1995). We express $\mathcal{L}(\infty Q)$ as a residue class ring $\mathbf{F}_q[X_1, \ldots, X_t]/I$ of the polynomial ring $\mathbf{F}_q[X_1, \ldots, X_t]$, where $X_1, \ldots, X_t$ are transcendental over $\mathbf{F}_q$, and I is the kernel of the canonical homomorphism sending X_i to x_i. Geil and Pellikaan (2002), Miura (1998) identified the following convenient representation of $\mathcal{L}(\infty Q)$ by using Gröbner basis theory (Buchberger, 1965) (see, for example, a textbook by Adams and Loustaunau, 1994). The following review is borrowed from Matsumoto and Miura (2000b). Hereafter, we assume that the reader is familiar with the Gröbner basis theory in Adams and Loustaunau (1994).

Let $\mathbf{N}_0$ be the set of nonnegative integers. For $(m_1, \ldots, m_t), (n_1, \ldots, n_t) \in \mathbf{N}_0^t$, we define the weighted reverse lexicographic monomial order $\succ$ such that $(m_1, \ldots, m_t) \succ (n_1, \ldots, n_t)$ if $a_1 m_1 + \cdots + a_t m_t > a_1 n_1 + \cdots + a_t n_t$, or $a_1 m_1 + \cdots + a_t m_t = a_1 n_1 + \cdots + a_t n_t$, and $m_1 = n_1$, $m_2 = n_2$, $\ldots$, $m_{i-1} = n_{i-1}$, $m_i < n_i$, for some $1 \le i \le t$. Note that a Gröbner basis of I with respect to $\succ$ can be computed by Saints and Heegard (1995, Theorem 15), Schicho (1998), Tang (1998, Theorem 4.1) or Vasconcelos (1998, Proposition 2.17), starting from any affine defining equations of $F/\mathbf{F}_q$.

Example 1. The Klein quartic over $\mathbf{F}_8$ is given by the equation

$$u^3 v + v^3 + u = 0.$$

There exists a unique $\mathbf{F}_8$-rational place Q, namely $(0:1:0)$, that is a unique pole of v. The numbers 3, 5 and 7 is the minimal generating set of the Weierstrass semigroup at Q. Define three functions $x_1 = v$, $x_2 = uv$, $x_3 = u^2 v$. We have $(x_1)_\infty = 3Q$, $(x_2)_\infty = 5Q$, $(x_3)_\infty = 7Q$ as shown in Høholdt and Pellikaan (1995, Example 3.7). By Tang (1998, Theorem 4.1) we can see that the standard form of the Klein quartic is given by

$$X_2^2 + X_3 X_1, X_3 X_2 + X_1^4 + X_2, X_3^2 + X_2 X_1^3 + X_3,$$

which is the reduced Gröbner basis with respect to the monomial order $\succ$. We can see that $a_1 = 3$, $a_2 = 5$, and $a_3 = 7$.

Example 2. Consider the function field $\mathbf{F}_9(u_1, v_2, v_3)$ with relations

$$v_2^3 + v_2 = u_1^4, \quad v_3^3 + v_3 = (v_2/u_1)^4. \tag{2}$$

This is the third function field in the asymptotically good tower introduced by Garcia and Stichtenoth (1995). Substituting v_2 with u_1u_2 and v_3 with u_2u_3 in Eq. (2) we have affine defining equations

$$u_1^2u_2^3 + u_2 - u_1^3 = 0, \quad u_2^2u_3^3 + u_3 - u_2^3 = 0$$

in $\mathbf{F}_9(u_1, u_2, u_3) = \mathbf{F}_9(u_1, v_2, v_3)$. The minimal generating set of the Weierstrass semigroup $H(Q)$ at Q is 9, 12, 22, 28, 32 and 35 (Voss and Høholdt, 1997, Example 4.11). It has genus 22 and 77 $\mathbf{F}_9$-rational points different from Q (Garcia and Stichtenoth, 1995).

Define six functions $x_1 = u_1$, $x_2 = u_1u_2$, $x_3 = u_1^2u_2u_3$, $x_4 = u_1^3u_2^2u_3^2$, $x_5 = ((u_1u_2)^2 + 1)u_2u_3$ and $x_6 = ((u_1u_2)^2 + 1)u_2^2u_3^2$. We have $(x_1)_\infty = 9Q$, $(x_2)_\infty = 12Q$, $(x_3)_\infty = 22Q$, $(x_4)_\infty = 35Q$, $(x_5)_\infty = 28Q$ and $(x_6)_\infty = 32Q$ (Umehara and Uyematsu, 1998). From this information and Tang (1998, Theorem 4.1) we can compute the 15 polynomials in the reduced Gröbner basis of the ideal $I \subset \mathbf{F}_9[X_1, \ldots, X_6]$ defining $\mathcal{L}(\infty Q)$ as $\{X_2^3 - X_1^4 + X_2, X_5X_2 - X_3X_1^2, X_6X_2 - X_4X_1, X_3^2 - X_4X_1, X_3X_2^2 - X_5X_1^2 + X_3, X_5X_3 - X_6X_1^2, X_6X_3 - X_1^6 + X_5X_1^2 + X_2X_1^2, X_5^2 - X_4X_2X_1 - X_6, X_4X_3 - X_2X_1^5 + X_3X_1^3 + X_2^2X_1, X_4X_2^2 - X_6X_1^3 + X_4, X_6X_5 - X_2^2X_1^4 + X_3X_2X_1^2 + X_5, X_5X_4 - X_1^7 + X_5X_1^3 + X_2X_1^3, X_6^2 - X_5X_1^4 + X_4X_2X_1 + X_3X_1^2 + X_6, X_6X_4 - X_3X_1^5 + X_6X_1^3 + X_3X_2X_1, X_4^2 - X_3X_2X_1^4 + X_4X_1^3 + X_5X_1^2 - X_3\}$. Note that polynomials in the above Gröbner basis are in the ascending order with respect to the monomial order $\prec$ while terms in each polynomial are in the descending order with respect to $\prec$.

For $i = 0, \ldots, a_1 - 1$, we define $b_i = \min\{m \in H(Q) \mid m \equiv i \pmod{a_1}\}$, and L_i to be the minimum element $(m_1, \ldots, m_t) \in \mathbf{N}_0^t$ with respect to $\prec$ such that $a_1m_1 + \cdots + a_tm_t = b_i$. Note that b_i's are the well-known Apéry set (Rosales and García-Sánchez, 2009, Lemmas 2.4 and 2.6) of the numerical semigroup $H(Q)$. Then we have $\ell_1 = 0$ if we write L_i as $(\ell_1, \ldots, \ell_t)$. For each $L_i = (0, \ell_{i2}, \ldots, \ell_{it})$, define $y_i = x_2^{\ell_{i2}} \cdots x_t^{\ell_{it}} \in \mathcal{L}(\infty Q)$.

The footprint of I, denoted by $\Delta(I)$, is $\{(m_1, \ldots, m_t) \in \mathbf{N}_0^t \mid X_1^{m_1} \cdots X_t^{m_t}$ is not the leading monomial of any nonzero polynomial in I with respect to $\prec\}$, and define $\Omega_0 = \{x_1^{m_1} \cdots x_t^{m_t} \mid (m_1, \ldots, m_t) \in \Delta(I)\}$. Then Ω_0 is a basis of $\mathcal{L}(\infty Q)$ as an $\mathbf{F}_q$-linear space (Adams and Loustaunau, 1994), two distinct elements in Ω_0 have different pole orders at Q, and

$$\begin{aligned}\Omega_0 &= \{x_1^m x_2^{\ell_2} \cdots, x_t^{\ell_t} \mid m \in \mathbf{N}_0, (0, \ell_2, \ldots, \ell_t) \in \{L_0, \ldots, L_{a_1-1}\}\} \\ &= \{x_1^m y_i \mid m \in \mathbf{N}_0, i = 0, \ldots, a_1 - 1\}. \end{aligned} \tag{3}$$

Equation (3) shows that $\mathcal{L}(\infty Q)$ is a free $\mathbf{F}_q[x_1]$-module with a basis $\{y_0, \ldots, y_{a_1-1}\}$. Note that the above structured shape of Ω_0 reflects the well-known property of every weighted reverse lexicographic monomial order, see the paragraph preceding to Eisenbud (1995, Proposition 15.12).

Remark 3. For a description of the proposed algorithm, only a_1, $b_1, \ldots, b_{a_1-1}$, $y_1, \ldots, y_{a_1-1}$ are absolutely necessary, and we can remove φ_s, $x_2, \ldots, x_t$, $a_2, \ldots, a_t$, $X_1, \ldots, X_t$, $Y_1, \ldots, Y_t$ from our presentation.

However, we retain those notations for the following two reasons: Firstly, because s will be used as the iteration variable and our proposed algorithm will focus on the monomial in Ω_0 whose pole order at Q is s, the notation φ_s clarifies the relation between s and the monomial in Ω_0 focused in the s-th iteration.

Secondly, the proposed algorithm needs to find the normal form of a function in $\mathcal{L}(\infty Q)$ that is an $\mathbf{F}_q$-linear combination of monomials in Ω_0. Functions in $\mathcal{L}(\infty Q)$ are represented by multivariate polynomials over $\mathbf{F}_q$. The specific definition of $X_1, \ldots, X_t$ and the specific choice of the monomial order in $\mathbf{F}_q[X_1, \ldots, X_t]$ enable us to compute the normal form just by the standard Gröbner basis division, and make implementation of our proposal easier in practice. Thirdly, $Y_1, \ldots, Y_t$ will be used to explain how we count the computational cost. They are necessary to allow readers to reproduce our experimental results presented later in this paper.

Example 4. For the curve in Example 1, we have $y_0 = 1$, $y_1 = x_3$, $y_2 = x_2$.

Let v_Q be the unique valuation in F associated with the place Q. The semigroup $H(Q)$ is equal to $\{ia_1 - v_Q(y_j) \mid 0 \le i, 0 \le j < a_1\}$ (Rosales and García-Sánchez, 2009, Lemma 2.6). By Matsumoto and Miura (2000b, Proposition 3.18), for each nongap $s \in H(Q)$ there is a unique monomial $x_1^i y_j \in \Omega_0$ with $0 \le j < a_1$ such that $-v_Q(x_1^i y_j) = s$, and let us denote this monomial by φ_s. Let $\Gamma \subset H(Q)$, and we may consider the one-point codes

$$C_\Gamma = \langle \{\mathrm{ev}(\varphi_s) \mid s \in \Gamma\} \rangle, \tag{4}$$

where $\langle \cdot \rangle$ denotes the $\mathbf{F}_q$-linear space spanned by $\cdot$. Since considering linearly dependent rows in a generator matrix has no merit, we assume

$$\Gamma \subseteq \widehat{H}(Q), \tag{5}$$

where $\widehat{H}(Q) = \{u \in H(Q) \mid C_u \neq C_{u-1}\}$. One motivation for considering these codes is that it was shown in Andersen and Geil (2008) how to increase the dimension of the one-point codes without decreasing the lower bound d_{AG} for the minimum distance. The bound $d_{\mathrm{AG}}(C_\Gamma)$ is defined for C_Γ as follows (Andersen and Geil, 2008): For $s \in \Gamma$, let

$$\lambda(s) = \sharp\{j \in H(Q) \mid j + s \in \widehat{H}(Q)\}. \tag{6}$$

Then $d_{\mathrm{AG}}(C_\Gamma) = \min\{\lambda(s) \mid s \in \Gamma\}$. It is proved in Geil et al. (2011) that d_{AG} gives the same estimate for the minimum distance as the Feng–Rao bound (Feng and Rao, 1993) for one-point dual AG codes when both d_{AG} and the Feng–Rao bound can be applied, that is, when the dual of a one-point code is isometric to a one-point code. Furthermore, it is also proved in Geil et al. (2011) that $d_{\mathrm{AG}}(C_\Gamma)$ can be obtained from the bounds in Beelen (2007), Duursma et al. (2011), Duursma and Park (2010), hence d_{AG} can be understood as a particular case of these bounds (Beelen, 2007; Duursma et al., 2011; Duursma and Park, 2010).

3. Procedure of new list decoding based on voting in Gröbner bases

3.1. Overall structure

Suppose that we have a received word $\vec{r} \in \mathbf{F}_q^n$. We shall modify the unique decoding algorithm proposed by Lee et al. (2012) so that we can find all the codewords in C_Γ in Eq. (4) within the Hamming distance τ from $\vec{r}$. τ is a parameter independent of $\vec{r}$, and τ is chosen before reception of $\vec{r}$. The overall structure of the modified algorithm is as follows:

(1) Precomputation before getting a received word $\vec{r}$,
(2) Initialization after getting a received word $\vec{r}$,
(3) Termination criteria of the iteration, and
(4) Main part of the iteration.

Steps 2 and 4 are based on Lee et al. (2012). Steps 1 and 3 are not given in Lee et al. (2012). Each step is described in the following subsections in Section 3. We shall analyze time complexity except the precomputation part of the algorithm.

3.2. Modified definitions for the proposed modification

We retain notations from Section 2. In this subsection, we modify notations and definitions in Lee et al. (2012) to describe the proposed modification to their algorithm. We also introduce several new notations. Define a set $\Omega_1 = \{x_1^i y_j z^k \mid 0 \le i,\ 0 \le j < a_1,\ k = 0, 1\}$. Our Ω_1 is Ω in Lee et al. (2012). Recall also that $\Omega_0 = \{\varphi_s \mid s \in H(Q)\}$.

Since the $\mathbf{F}_q[x_1]$-module $\mathcal{L}(\infty Q)z \oplus \mathcal{L}(\infty Q)$ has a free basis $\{y_j z, y_j \mid 0 \le j < a_1\}$, we can regard Ω_1 as the set of monomials in the Gröbner basis theory for modules. We introduce a monomial order on Ω_1 as follows. For given two monomials $x_1^{i_1} y_j z^{i_{t+1}}$ and $x_1^{i'_1} y_{j'} z^{i'_{t+1}}$, first rewrite y_j and $y_{j'}$ by

$x_2, \ldots, x_t$ defined in Section 2 and get $x_1^{i_1} y_j z^{i_{t+1}} = x_1^{i_1} x_2^{i_2} \cdots x_t^{i_t} z^{i_{t+1}}$ and $x_1^{i'_1} y_{j'} z^{i'_{t+1}} = x_1^{i'_1} x_2^{i'_2} \cdots x_t^{i'_t} z^{i'_{t+1}}$. For a nongap $s \in H(Q)$, we define the monomial order $x_1^{i_1} x_2^{i_2} \cdots x_t^{i_t} z^{i_{t+1}} <_s x_1^{i'_1} x_2^{i'_2} \cdots x_t^{i'_t} z^{i'_{t+1}}$ parametrized by s if $i_{t+1}s - v_Q(x_1^{i_1} x_2^{i_2} \cdots x_t^{i_t}) < i'_{t+1}s - v_Q(x_1^{i'_1} x_2^{i'_2} \cdots x_t^{i'_t})$ or $i_{t+1}s - v_Q(x_1^{i_1} x_2^{i_2} \cdots x_t^{i_t}) = i'_{t+1}s - v_Q(x_1^{i'_1} x_2^{i'_2} \cdots x_t^{i'_t})$ and $i_1 = i'_1, i_2 = i'_2, \ldots, i_{\ell-1} = i'_{\ell-1}$ and $i_\ell > i'_\ell$ for some $1 \le \ell \le t+1$. Observe that the restriction of $<_s$ to Ω_0 is equal to $\prec$ defined in Section 2. In what follows, every Gröbner basis, leading term, and leading coefficient is obtained by considering the Gröbner basis theory for modules, not for ideals.

For $f \in \mathcal{L}(\infty Q)z \oplus \mathcal{L}(\infty Q)$, $\gamma(f)$ denotes the number of nonzero terms in f when f is expressed as an $\mathbf{F}_q$-linear combination of monomials in Ω_1. $\gamma_{\neq 1}(f)$ denotes the number of nonzero terms whose coefficients are not $1 \in \mathbf{F}_q$.

For the code C_Γ in Eq. (4), define the divisor $D = P_1 + \cdots + P_n$. Define $\mathcal{L}(-G + \infty Q) = \bigcup_{i=1}^{\infty} \mathcal{L}(-G + iQ)$ for a positive divisor G of $F/\mathbf{F}_q$. Then $\mathcal{L}(-D + \infty Q)$ is an ideal of $\mathcal{L}(\infty Q)$ (Matsumoto and Miura, 2000a). Let η_i be any element in $\mathcal{L}(-D + \infty Q)$ such that $\mathrm{LM}(\eta_i) = x_1^j y_i$ with j being the minimal given i. Then by Lee et al. (2012, Proposition 1), $\{\eta_0, \ldots, \eta_{a_1-1}\}$ is a Gröbner basis for $\mathcal{L}(-D + \infty Q)$ with respect to $<_s$ as an $\mathbf{F}_q[x_1]$-module. For a nonnegative integer s, define $\Gamma^{(\le s)} = \{s' \in \Gamma \mid s' \le s\}$, $\Gamma^{(>s)} = \{s' \in \Gamma \mid s' > s\}$, and $\mathrm{prec}(s) = \max\{s' \in H(Q) \mid s' < s\}$. We define $\mathrm{prec}(0) = -1$.

3.3. Precomputation before getting a received word

Before getting $\vec{r}$, we need to compute the Pellikaan–Miura standard form of the algebraic curve, $y_0(=1), y_1, \ldots, y_{a_1-1}$, and φ_s for $s \in H(Q)$ as defined in Section 2. Also compute $\eta_0, \ldots, \eta_{a_1-1}$, which can be done by Matsumoto and Miura (2000a).

For each (i, j), express $y_i y_j$ as an $\mathbf{F}_q$-linear combination of monomials in Ω_0. Such expressions will be used for computing products and quotients in $\mathcal{L}(\infty Q)$ as explained in Section 3.4.1. From the above data, we can easily know $\mathrm{LC}(y_i y_j)$, which will be used in Eqs. (14) and (22).

Find elements $\varphi_s \in \Omega_0$ with $s \in \widehat{H}(Q)$. There are n such elements, which we denote by $\psi_1, \ldots \psi_n$ such that $-v_Q(\psi_i) < -v_Q(\psi_{i+1})$. Compute the $n \times n$ matrix

$$M = \begin{pmatrix} \psi_1(P_1) & \cdots & \psi_1(P_n) \\ \vdots & \vdots & \vdots \\ \psi_n(P_1) & \cdots & \psi_n(P_n) \end{pmatrix}^{-1}. \tag{7}$$

3.4. Multiplication and division in an affine coordinate ring

In both of the original unique decoding algorithm (Lee et al., 2012) and our modified version, we need to quickly compute the product gh of two elements g, h in the affine coordinate ring $\mathcal{L}(\infty Q)$. In our modified version, we also need to compute the quotient g/h depending on the choice of iteration termination criterion described in Section 3.6. Since the authors could not find quick computational procedures for those tasks in $\mathcal{L}(\infty Q)$, we shall present such ones here.

3.4.1. Multiplication in an affine coordinate ring

The normal form of g, for $g \in \mathcal{L}(\infty Q)$, is the expression of g written as an $\mathbf{F}_q$-linear combination of monomials $\varphi_s \in \Omega_0$. g, h are assumed to be in the normal form. We propose the following procedure to compute the normal form of gh. Let the normal form of $y_i y_j$ be

$$\sum_{k=0}^{a_1-1} y_k f_{i,j,k}(x_1).$$

with $f_{i,j,k}(x_1) \in \mathbf{F}_q[x_1]$, which is computed in Section 3.3.

We denote by $X_1, Y_1, \ldots, Y_{a_1-1}$ algebraically independent variables over $\mathbf{F}_q$.

(1) Assume that g and h are in their normal forms. Change y_i to Y_i and x_1 to X_1 in g, h for $i = 1, \ldots, a_1 - 1$. Recall that $y_0 = 1$. Denote the results by G, H.
(2) Compute GH. This step needs

$$\gamma(g) \times \gamma(h) \tag{8}$$

multiplications in $\mathbf{F}_q$.
(3) Let $GH = \sum_{0 \le i,j < a_1} Y_i Y_j F_{G,H,i,j}(X_1)$. Then we have

$$gh = \sum_{0 \le i,j < a_1} F_{G,H,i,j}(x_1) \sum_{k=0}^{a_1-1} y_k f_{i,j,k}(x_1). \tag{9}$$

Computation of $F_{G,H,i,j}(X_1) \sum_{k=0}^{a_1-1} y_k f_{i,j,k}(x_1)$ needs at most $\gamma_{\neq 1}(\sum_{k=0}^{a_1-1} y_k f_{i,j,k}(x_1)) \gamma(F_{G,H,i,j}(x_1))$ multiplications in $\mathbf{F}_q$. Therefore, the total number of multiplications in $\mathbf{F}_q$ in this step is at most

$$\sum_{0 \le i,j < a_1} \gamma(F_{G,H,i,j}(x_1)) \gamma_{\neq 1}(\sum_{k=0}^{a_1-1} y_k f_{i,j,k}(x_1)). \tag{10}$$

Therefore, the total number of multiplications in $\mathbf{F}_q$ is at most

$$\gamma(g) \times \gamma(h) + \sum_{0 \le i,j < a_1} \gamma(F_{G,H,i,j}(x_1)) \gamma_{\neq 1}(\sum_{k=0}^{a_1-1} y_k f_{i,j,k}(x_1)). \tag{11}$$

Define Eq. (11) as multi(g, h).

We emphasize that when the characteristic of $\mathbf{F}_q$ is 2 and all the coefficients of defining equations belong to $\mathbf{F}_2$, which is almost always the case for those cases of interest for applications in coding theory, then $\gamma_{\neq 1}(\sum_{k=0}^{a_1-1} y_k f_{i,j,k}(x_1))$ in Eq. (11) is zero. This means that $\mathcal{L}(\infty Q)$ has little additional overhead over $\mathbf{F}_q[X]$ for computing products of their elements in terms of the number of $\mathbf{F}_q$-multiplications and divisions.

Remark 5. Define (i, j) to be equivalent to (i', j') if $y_i y_j = y_{i'} y_{j'} \in \mathcal{L}(\infty Q)$. Denote by $[i, j]$ the equivalence class represented by (i, j). For $(i, j), (i', j') \in [i, j]$ we have $f_{i,j,k}(x_1) = f_{i',j',k}(x_1)$, which is denoted by $f_{[i,j],k}(x_1)$. The right hand side of Eq. (9) can be written as

$$\sum_{[i,j]} \left(\sum_{(i',j') \in [i,j]} F_{G,H,i',j'}(x_1) \right) \sum_{k=0}^{a_1-1} y_k f_{[i,j],k}(x_1). \tag{12}$$

By using Eq. (12) instead of Eq. (9), we have another upper bound on the number of multiplications as

$$\gamma(g) \times \gamma(h) + \sum_{[i,j]} \gamma \left(\sum_{(i',j') \in [i,j]} F_{G,H,i',j'}(x_1) \right) \gamma_{\neq 1}(\sum_{k=0}^{a_1-1} y_k f_{[i,j],k}(x_1)). \tag{13}$$

Since

$$\gamma \left(\sum_{(i',j') \in [i,j]} F_{G,H,i',j'}(x_1) \right) \le \sum_{(i',j') \in [i,j]} \gamma(F_{G,H,i',j'}(x_1)),$$

we have Eq. (13) $\le$ Eq. (11). However, Eq. (13) is almost always the same as Eq. (11) over the curve in Example 2, and Eq. (13) will not be used in our computer experiments in Section 5.

3.4.2. Computation of the quotient

Assume $h \neq 0$. The following procedure computes the quotient $g/h \in \mathcal{L}(\infty Q)$ or declares that g does not belong to the principal ideal of $\mathcal{L}(\infty Q)$ generated by h.

(1) Initialize $\sigma = 0$. Also initialize $\zeta = 0$.
(2) Check if $-v_Q(g) \in -v_Q(h) + H(Q)$. If not, declare that g does not belong to the principal ideal of $\mathcal{L}(\infty Q)$ generated by h, and finish the procedure.
(3) Let $\varphi_s \in \Omega_0$ such that $-v_Q(g) = -v_Q(\varphi_s h)$. Observe that $\mathrm{LC}(\varphi_s \mathrm{LM}(h)) = \mathrm{LC}(y_{s \bmod a_1} y_{-v_Q(h) \bmod a_1})$ and that $\mathrm{LC}(y_{s \bmod a_1} y_{-v_Q(h) \bmod a_1})$ is precomputed as in Section 3.3. Let
$$\mathbf{F}_q \ni t = \mathrm{LC}(g)/(\mathrm{LC}(h) \times \underbrace{\mathrm{LC}(\varphi_s \mathrm{LM}(h))}_{\text{Precomputed in Section 3.3}}). \tag{14}$$
Computation of $t\varphi_s$ needs one multiplication and one division in $\mathbf{F}_q$. Observe that $-v_Q(g - t\varphi_s h) < -v_Q(g)$.
(4) Compute the normal form of $t\varphi_s h$, which requires at most $\mathrm{multi}(t\varphi_s, h)$ multiplications in $\mathbf{F}_q$. Increment ζ by $2 + \mathrm{multi}(t\varphi_s, h)$.
(5) Update $\sigma \leftarrow \sigma + t\varphi_s$ and $g \leftarrow g - t\varphi_s h$. If the updated g is zero, then output the updated σ as the quotient and finish the procedure. Otherwise go to Step 2. This step has no multiplication nor division.

Define $\mathrm{quot}(g, h)$ as ζ after finishing the above procedure. $\mathrm{quot}(g, h)$ is an upper bound on the number of multiplications and divisions in $\mathbf{F}_q$ in the above procedure. The program variable ζ is just to define $\mathrm{quot}(g, h)$, and the decoding algorithm does not need to update ζ. Observe also that the above procedure is a straightforward generalization of the standard long division of two univariate polynomials (McKeague, 2012).

3.5. Initialization after getting a received word $\vec{r}$

Let $(i_1, \ldots, i_n)^T = M\vec{r}$, where M is defined in Eq. (7). Define $h_{\vec{r}} = \sum_{j=1}^{n} i_j \psi_j$. Then we have $\mathrm{ev}(h_{\vec{r}}) = \vec{r}$. The computation of $h_{\vec{r}}$ from $\vec{r}$ needs at most n^2 multiplications in $\mathbf{F}_q$.

Let $N = -v_Q(h_{\vec{r}})$. For $i = 0, \ldots, a_1 - 1$, compute $g_i^{(N)} = \eta_i \in \mathcal{L}(\infty Q)$ and $f_i^{(N)} = y_i(z - h_{\vec{r}}) \in \mathcal{L}(\infty Q)z \oplus \mathcal{L}(\infty Q)$. The computation of $f_i^{(N)}$ needs at most $\mathrm{multi}(y_i, h_{\vec{r}})$ multiplications in $\mathbf{F}_q$. Therefore, the total number of multiplications in the initialization is at most
$$n^2 + \sum_{i=0}^{a_1 - 1} \mathrm{multi}(y_i, h_{\vec{r}}). \tag{15}$$

Let $s = N$ and execute the following steps.

3.6. Three termination criteria of the iteration

After finishing the initialization step in Section 3.5, we iteratively compute $f_i^{(s)}$ and $g_i^{(s)}$ with $N \geq s \in H(Q) \cup \{-1\}$ and w_s with $N \geq s \in H(Q)$ from larger s to smaller s. The single iteration consists of two parts: The first part is to check if an iteration termination criterion is satisfied. The second part is computation of $f_i^{(s)}$ and $g_i^{(s)}$ for $N \geq s \in H(Q) \cup \{-1\}$. We describe the first part in Section 3.6.

Let $f_{\min} = \alpha_0 + z\alpha_1$ having the smallest $-v_Q(\alpha_1)$ among $f_0^{(s)}, \ldots, f_{a_1-1}^{(s)}$. In the following subsections, we shall propose three different procedures to judge whether or not iterations in the proposed algorithm can be terminated. In an actual implementation of the proposed algorithm, one criterion is chosen and the chosen one is consistently used throughout the iterations. The first one and the second one are different generalizations of Ali and Kuijper (2011, Theorem 12) from the case $g = 0$ to $g > 0$. Ali and Kuijper (2011, Theorem 12) proved that if the number δ of errors satisfies $2\delta < d_{\mathrm{RS}}(C_s)$,

where $d_{\mathrm{RS}}(C_s)$ is the minimum distance $n-s$ of the $[n, s+1]$ Reed–Solomon code C_s, then the transmitted information word is obtained by Ali–Kuijper's algorithm as $-\alpha_0/\alpha_1$. To one-point primal AG codes, $d_{\mathrm{RS}}(C_s)$ can be generalized as either $d_{\mathrm{AG}}(C_s)$ or $n-s-g$. The former generalization $d_{\mathrm{AG}}(C_s)$ corresponds to the first criterion in Section 3.6.1 and the latter $n-s-g$ corresponds to the second one in Section 3.6.2.

The third one is almost the same as the original procedure in Lee et al. (2012). The first one was proposed in Geil et al. (2012) while the second and the third ones are new in this paper. We shall compare the three criteria in Section 5.2. Throughout this paper, $\mathrm{wt}(\vec{x})$ denotes the Hamming weight of a vector $\vec{x} \in \mathbf{F}_q^n$.

The proposed decoding algorithm can perform both unique decoding and list decoding depending on whether or not $d_{\mathrm{AG}}(C_{\Gamma^{(\leq s)}}) > 2\tau$. To provide a unified presentation of both variants of our proposal, we will include the condition $d_{\mathrm{AG}}(C_{\Gamma^{(\leq s)}}) > 2\tau$ in the following. Observe that the condition $d_{\mathrm{AG}}(C_{\Gamma^{(\leq s)}}) > 2\tau$ can be checked when one implements our proposal by an electronic circuit or a computer software, before executing the proposed algorithm.

3.6.1. First criterion for judging termination

If

- $s \in \Gamma$,
- $d_{\mathrm{AG}}(C_{\Gamma^{(\leq s)}}) > 2\tau$, and
- $-v_Q(\alpha_1) \leq \tau + g$

then do the following:

(1) Compute $\alpha_0/\alpha_1 \in F$. This needs at most

$$\mathrm{quot}(\alpha_0, \alpha_1) \tag{16}$$

multiplications and divisions in $\mathbf{F}_q$.

(2) If $\alpha_0/\alpha_1 \in \mathcal{L}(\infty Q)$ and α_0/α_1 can be written as a linear combination of monomials in $\{\varphi_{s'} \in s' \in \Gamma^{(\leq s)}\}$, then do the following:
   (a) If $d_{\mathrm{AG}}(C_\Gamma) > 2\tau$ or $-v_Q(\alpha_1) \leq \tau$ then include the coefficients of $-\alpha_0/\alpha_1 + \sum_{s' \in \Gamma^{(>s)}} w_{s'}\varphi_{s'}$ into the list of transmitted information vectors, and avoid proceeding with the rest of the decoding procedure. When $\Gamma^{(>s)} = \emptyset$, the summation over $\Gamma^{(>s)}$ is regarded as zero.
   (b) Otherwise compute $\mathrm{ev}(-\alpha_0/\alpha_1 + \sum_{s' \in \Gamma^{(>s)}} w_{s'}\varphi_{s'})$. This needs at most

$$n\gamma\left(-\alpha_0/\alpha_1 + \sum_{s' \in \Gamma^{(>s)}} w_{s'}\varphi_{s'}\right) \tag{17}$$

   multiplications and divisions in $\mathbf{F}_q$.
   (c) If

$$\mathrm{wt}\left(\mathrm{ev}(-\alpha_0/\alpha_1 + \sum_{s' \in \Gamma^{(>s)}} w_{s'}\varphi_{s'}) - \vec{r}\right) \leq \tau,$$

   then include the coefficients of $-\alpha_0/\alpha_1 + \sum_{s' \in \Gamma^{(>s)}} w_{s'}\varphi_{s'}$ into the list of transmitted information vectors, and avoid proceeding with s. Otherwise, continue the iterations unless $s < n-g-2\tau$.

3.6.2. Second criterion for judging termination

If $s = \max\{s' \in \Gamma \mid s' < n-2\tau-g\}$, then do the following:

(1) If $-v_Q(\alpha_1) > \tau + g$ then stop proceeding with iteration.
(2) Otherwise compute $\alpha_0/\alpha_1 \in F$. This needs at most

$$\mathrm{quot}(\alpha_0, \alpha_1) \tag{18}$$

multiplications and divisions in $\mathbf{F}_q$.

(3) If $2\tau < d_{\mathrm{AG}}(C_\Gamma)$, $\alpha_0/\alpha_1 \in \mathcal{L}(\infty Q)$, and α_0/α_1 can be written as a linear combination of monomials in $\{\varphi_{s'} \in s' \in \Gamma^{(\leq s)}\}$ then declare the coefficients of $-\alpha_0/\alpha_1 + \sum_{s' \in \Gamma^{(>s)}} w_{s'}\varphi_{s'}$ as the only transmitted information and finish. When $\Gamma^{(>s)} = \emptyset$, the summation over $\Gamma^{(>s)}$ is regarded as zero. Otherwise declare "decoding failure" and finish.
(4) If $2\tau \geq d_{\mathrm{AG}}(C_\Gamma)$, $\alpha_0/\alpha_1 \in \mathcal{L}(\infty Q)$ and α_0/α_1 can be written as a linear combination of monomials in $\{\varphi_{s'} \in s' \in \Gamma^{(\leq s)}\}$, then do the following:
   (a) If $-v_Q(\alpha_1) \leq \tau$ then include the coefficients of $-\alpha_0/\alpha_1 + \sum_{s' \in \Gamma^{(>s)}} w_{s'}\varphi_{s'}$ into the list of transmitted information vectors, and avoid proceeding with s.
   (b) Otherwise compute $\mathrm{ev}(-\alpha_0/\alpha_1 + \sum_{s' \in \Gamma^{(>s)}} w_{s'}\varphi_{s'})$. This needs at most

$$n\gamma(-\alpha_0/\alpha_1 + \sum_{s' \in \Gamma^{(>s)}} w_{s'}\varphi_{s'}) \tag{19}$$

   multiplications and divisions in $\mathbf{F}_q$.
   (c) If

$$\mathrm{wt}\left(\mathrm{ev}(-\alpha_0/\alpha_1 + \sum_{s' \in \Gamma^{(>s)}} w_{s'}\varphi_{s'}) - \vec{r}\right) \leq \tau,$$

   then include the coefficients of $-\alpha_0/\alpha_1 + \sum_{s' \in \Gamma^{(>s)}} w_{s'}\varphi_{s'}$ into the list of transmitted information vectors.
(5) Finish the iteration no matter what happened in the above steps.

3.6.3. Third criterion for judging termination

The third criterion terminates the algorithm when it finds $f_i^{(s)}$ at $s = -1$ for $i = 0, \ldots, a_1 - 1$ in the main iteration presented in Section 3.7. If $2\tau < d_{\mathrm{AG}}(C_\Gamma)$ then declare the vector $(w_s : s \in \Gamma)$ as the only transmitted information and finish.

If $2\tau \geq d_{\mathrm{AG}}(C_\Gamma)$ then do the following:

(1) If $\alpha_0 = 0$ and $-v_Q(\alpha_1) \leq \tau$ then include the vector $(w_s : s \in \Gamma)$ into the list of transmitted information vectors. Finish the iteration.
(2) If $-v_Q(\alpha_1) > \tau + g$ then finish the iteration.
(3) Otherwise compute $\mathrm{ev}(\sum_{s \in \Gamma} w_s\varphi_s)$. This needs at most

$$n\gamma(\sum_{s \in \Gamma} w_s\varphi_s) \tag{20}$$

   multiplications and divisions in $\mathbf{F}_q$.
(4) If

$$\mathrm{wt}\left(\mathrm{ev}(\sum_{s \in \Gamma} w_s\varphi_s) - \vec{r}\right) \leq \tau,$$

   then include the vector $(w_s : s \in \Gamma)$ into the list of transmitted information vectors. Finish the iteration.

3.7. Iteration of pairing, voting, and rebasing

The iteration of the original algorithm (Lee et al., 2012) consists of three steps, called pairing, voting, and rebasing. We will make a small change to the original. Our modified version is described below.

3.7.1. Pairing

Let

$$g_i^{(s)} = \sum_{0 \leq j < a_1} c_{i,j} y_j z + \sum_{0 \leq j < a_1} d_{i,j} y_j, \text{ with } c_{i,j}, d_{i,j} \in \mathbf{F}_q[x_1],$$

$$f_i^{(s)} = \sum_{0 \le j < a_1} a_{i,j} y_j z + \sum_{0 \le j < a_1} b_{i,j} y_j, \text{ with } a_{i,j}, b_{i,j} \in \mathbf{F}_q[x_1],$$

and let $\nu_i^{(s)} = \mathrm{LC}(d_{i,i})$. We assume that $\mathrm{LT}(f_i^{(s)}) = a_{i,i} y_i z$ and $\mathrm{LT}(g_i^{(s)}) = d_{i,i} y_i$. For $0 \le i < a_1$, as in Lee et al. (2012) there are unique integers $0 \le i' < a_1$ and k_i satisfying

$$-\nu_Q(a_{i,i} y_i) + s = a_1 k_i - \nu_Q(y_{i'}).$$

Note that by the definition above

$$i' = i + s \bmod a_1, \tag{21}$$

and the integer $-\nu_Q(a_{i,i} y_i) + s$ is a nongap if and only if $k_i \ge 0$. Now let $c_i = \deg_{x_1}(d_{i',i'}) - k_i$. Note that the map $i \mapsto i'$ is a permutation of $\{0, 1, \ldots, a-1\}$ and that the integer c_i is defined such that $a_1 c_i = -\nu_Q(d_{i',i'} y_{i'}) + \nu_Q(a_{i,i} y_i) - s$.

3.7.2. Voting

For each $i \in \{0, \ldots a_1 - 1\}$, we set

$$\mu_i = \mathrm{LC}(a_{i,i} y_i \varphi_s), \ w_{s,i} = -\frac{b_{i,i'}[x_1^{k_i}]}{\mu_i}, \ \bar{c}_i = \max\{c_i, 0\}, \tag{22}$$

where $b_{i,i'}[x_1^{k_i}]$ denotes the coefficient of $x_1^{k_i}$ of the univariate polynomial $b_{i,i'} \in \mathbf{F}_q[x_1]$. We remark that the leading coefficient μ_i must be considered after expressing $a_{i,i} y_i \varphi_s$ by monomials in Ω_0.

Observe that $\mathrm{LC}(y_i \varphi_s) = \mathrm{LC}(y_i y_{s \bmod a_1})$ and that $\mathrm{LC}(y_i y_{s \bmod a_1})$ is already precomputed as in Section 3.3. By using that precomputed table, computation of μ_i needs one multiplication. The total number of multiplications and divisions in Eq. (22) is

$$2a_1 \tag{23}$$

excluding negation from the number of multiplication.

Let

$$\nu(s) = \frac{1}{a_1} \sum_{0 \le i < a_1} \max\{-\nu_Q(\eta_{i'}) + \nu_Q(y_i) - s, 0\}. \tag{24}$$

We consider two different candidates depending on whether $s \in \Gamma$ or not:

- If $s \in H(Q) \setminus \Gamma$, set
$$w = 0. \tag{25}$$
- If $s \in \Gamma$, let w be one of the element(s) in $\mathbf{F}_q$ with
$$\sum_{w = w_{s,i}} \bar{c}_i \ge \sum_{w \ne w_{s,i}} \bar{c}_i - 2\tau + \nu(s). \tag{26}$$

Let $w_s = w$. If several w's satisfy the condition above, repeat the rest of the algorithm for each of them.

3.7.3. Rebasing

In all of the following cases, we need to compute the normal form of the product $w\varphi_s \times \sum_{j=0}^{a_1-1} a_{i,j} y_j$, and the product $w\varphi_s \times \sum_{j=0}^{a_1-1} c_{i,j} y_j$. For each i, the number of multiplications is

$$\le \mathrm{multi}(w\varphi_s, \sum_{j=0}^{a_1-1} a_{i,j} y_j) + \mathrm{multi}(w\varphi_s, \sum_{j=0}^{a_1-1} c_{i,j} y_j), \tag{27}$$

where $\mathrm{multi}(\cdot, \cdot)$ is defined in Section 3.4.1.

- If $w_{s,i} = w$, then let

$$g_{i'}^{(\mathrm{prec}(s))} = g_{i'}^{(s)}(z + w\varphi_s),$$
$$f_i^{(\mathrm{prec}(s))} = f_i^{(s)}(z + w\varphi_s)$$

  where the parentheses denote substitution of the variable z and let $\nu_{i'}^{(\mathrm{prec}(s))} = \nu_{i'}^{(s)}$. The number of multiplications in this case is bounded by Eq. (27).
- If $w_{s,i} \neq w$ and $c_i > 0$, then let

$$g_{i'}^{(\mathrm{prec}(s))} = f_i^{(s)}(z + w\varphi_s),$$
$$f_i^{(\mathrm{prec}(s))} = x_1^{c_i} f_i^{(s)}(z + w\varphi_s) - \frac{\mu_i(w - w_{s,i})}{\nu_{i'}^{(s)}} g_{i'}^{(s)}(z + w\varphi_s)$$

  and let $\nu_{i'}^{(\mathrm{prec}(s))} = \mu_i(w - w_{s,i})$.
  Computation of $\frac{\mu_i(w-w_{s,i})}{\nu_{i'}^{(s)}}$ needs one multiplication and one division. The product of $\frac{\mu_i(w-w_{s,i})}{\nu_{i'}^{(s)}}$ and $g_{i'}^{(s)}(z + w\varphi_s)$ needs $\gamma(g_{i'}^{(s)}(z + w\varphi_s))$ multiplications, where γ is defined in Section 3.4.1. Thus, the number of multiplications and divisions is

$$\leq 2 + \gamma(g_{i'}^{(s)}(z + w\varphi_s)) + \text{Eq. (27)}. \tag{28}$$

- If $w_{s,i} \neq w$ and $c_i \leq 0$, then let

$$g_{i'}^{(\mathrm{prec}(s))} = g_{i'}^{(s)}(z + w\varphi_s),$$
$$f_i^{(\mathrm{prec}(s))} = f_i^{(s)}(z + w\varphi_s) - \frac{\mu_i(w - w_{s,i})}{\nu_{i'}^{(s)}} x_1^{-c_i} g_{i'}^{(s)}(z + w\varphi_s)$$

  and let $\nu_{i'}^{(\mathrm{prec}(s))} = \nu_{i'}^{(s)}$.
  Computation of $\frac{\mu_i(w-w_{s,i})}{\nu_{i'}^{(s)}}$ needs one multiplication and one division. The product of $\frac{\mu_i(w-w_{s,i})}{\nu_{i'}^{(s)}}$ and $g_{i'}^{(s)}(z + w\varphi_s)$ needs $\gamma(g_{i'}^{(s)}(z + w\varphi_s))$ multiplications, where γ is defined in Section 3.4.1. Thus, the number of multiplications and divisions is $\leq$ Eq. (28).

After computing $f_i^{(\mathrm{prec}(s))}$ and $g_i^{(\mathrm{prec}(s))}$ as above, update the program variable s to $\mathrm{prec}(s)$ and return to the beginning of Section 3.6, that is, return to the step of the chosen termination criterion.

3.8. Difference to the original method

In this subsection, we review advantages of our modified algorithm over the original (Lee et al., 2012).

- Our version can handle any one-point primal AG codes, while the original can handle codes only coming from the C_{ab} curves (Miura, 1993). This generalization is enabled only by replacing y^j in Lee et al. (2012) by y_j defined in Section 2.
- Our version can find all the codewords within Hamming distance τ from the received word $\vec{r}$, while the original is a unique decoding algorithm.
- Our version does not compute $f_i^{(s)}$, $g_i^{(s)}$ for a Weierstrass gap $s \notin H(Q)$, while the original computes them for $N \geq s \notin H(Q)$.
- The original algorithm assumed $u < n$, where u is as defined in Eq. (1). This assumption is replaced by another less restrictive assumption (5) in our version.
- Our version supports the Feng–Rao improved code construction (Feng and Rao, 1995), while the original does not. This extension is made possible by the change at Eq. (25).

- The first and the second termination criteria come from Ali and Kuijper (2011, Theorem 12) and do not exist in the original (Lee et al., 2012).
- The third termination criterion is essentially the same as the original (Lee et al., 2012), but examination of the Hamming distance between the decoded codeword and $\vec{r}$ is added when $2\tau \geq d_{\mathrm{AG}}(C_\Gamma)$.
- The original (Lee et al., 2012) is suitable for parallel implementation on electric circuit similar to the Kötter architecture (Kötter, 1998). Our modified version retains this advantage.

3.9. Small example of algorithm execution

We show a short example execution of the proposed list decoding. Consider the well-known Hermitian function field $\mathbf{F}_4(u, v)/\mathbf{F}_4$ with the relation $v^2 + v - u^3 = 0$, which implies $a_1 = 2$. We choose the common pole of u and v as Q, and $P_1 = (0, 0)$, $P_2 = (0, 1)$, $P_3 = (1, \beta)$, $P_4 = (1, \beta^2)$, $P_5 = (\beta, \beta)$, $P_6 = (\beta, \beta^2)$, $P_7 = (\beta^2, \beta)$, $P_8 = (\beta^2, \beta^2)$, where β is a primitive element in $\mathbf{F}_4$. Then we have $\widehat{H}(Q) = \{0, 2, 3, 4, 5, 6, 7, 9\}$. The above choice gives $\eta_0 = u^4 + u$ and $\eta_1 = u^4 v + uv$.

We use C_u with $u = 4$ for decoding. Then $\Gamma = \{0, 2, 3, 4\}$ and $d_{\mathrm{AG}}(C_\Gamma) = 4$. We shall try to correct $\tau = 2$ errors. Suppose that $\vec{0}$ was transmitted and $\vec{r} = (0, 0, 1, 1, 0, 0, 0, 0)$ was received. This received word $\vec{r}$ has four codewords within Hamming distance 2, and all of them are found by the proposed decoding algorithm. We shall show how one of the four codeword is found.

According to Section 3.5, we have $h_{\vec{r}} = u^3 + u^2 + u$, which implies $N = -v_Q(h_{\vec{r}}) = 6$. We start the iteration from $s = 6 (= N)$, and again according to Section 3.5 we have

$$
\begin{aligned}
f_0^{(6)} &= z + u^3 + u^2 + u, \\
f_1^{(6)} &= vz + u^3 v + u^2 v + uv, \\
g_0^{(6)} &= u^4 + u, \\
g_1^{(6)} &= u^4 v + uv.
\end{aligned}
$$

At the iteration for $s = 6$ none of the termination criteria is satisfied. Since $6 \notin \Gamma$, we do not need voting and set $w_6 = 0$, and we compute new polynomials as

$$
\begin{aligned}
f_0^{(5)} &= uz + u^3 + u^2 + u, \\
f_1^{(5)} &= uvz + u^3 v + u^2 v + uv, \\
g_0^{(5)} &= z + u^3 + u^2 + u, \\
g_1^{(5)} &= vz + u^3 v + u^2 v + uv.
\end{aligned}
$$

At the iteration for $s = 5$ none of the termination criteria is satisfied. Since $5 \notin \Gamma$, we do not need voting and set $w_5 = 0$, and we compute new polynomials as

$$
\begin{aligned}
f_0^{(4)} &= f_0^{(5)}, \\
f_1^{(4)} &= f_1^{(5)}, \\
g_0^{(4)} &= g_0^{(5)}, \\
g_1^{(4)} &= g_1^{(5)}.
\end{aligned}
$$

At the iteration for $s = 4$ none of the termination criteria is satisfied. We need voting at $s = 4$, and all the candidates 0, 1, β, β^2 in $\mathbf{F}_4$ get zero vote. Therefore, the execution of the proposed algorithm splits to four branches at $s = 4$. Firstly we consider the choice $w_4 = 1$, which will result in an incorrect decoding.

The choice $w_4 = 1$ gives

$$f_0^{(3)} = uz + u^2 + u,$$
$$f_1^{(3)} = uvz + u^2v + uv,$$
$$g_0^{(3)} = z + u^3 + u,$$
$$g_1^{(3)} = vz + u^3v + uv.$$

At the iteration for $s = 3$ only the first termination criterion is satisfied. We have $\alpha_0 = u^2 + u$ and $\alpha_1 = u$, and the decoded codeword by the first criterion is $(1, 1, 1, 1, 0, 0, 0, 0)$ which is at the Hamming distance 2 from $\vec{r}$ but not equal to the transmitted codeword.

The second or the third termination criterion is not satisfied. In the voting for $s = 3$, $w_3 = 0$ is chosen with two votes while other candidates get zero vote. The choice $w_3 = 0$ gives

$$f_0^{(2)} = f_0^{(3)},$$
$$f_1^{(2)} = f_1^{(3)},$$
$$g_0^{(2)} = g_0^{(3)},$$
$$g_1^{(2)} = g_1^{(3)}.$$

At the iteration for $s = 2$ the second termination criterion is satisfied. The computation process and the decoded codeword by the second criterion at $s = 2$ are the same as those by first criterion at $s = 3$.

In the voting for $s = 2$, $w_2 = 0$ is chosen with two votes while other candidates get zero vote. The choice $w_2 = 0$ gives

$$f_0^{(1)} = f_0^{(2)},$$
$$f_1^{(1)} = f_1^{(2)},$$
$$g_0^{(1)} = g_0^{(2)},$$
$$g_1^{(1)} = g_1^{(2)}.$$

In the voting for $s = 1$, $w_1 = 1$ is chosen with two votes while other candidates get zero vote. The choice $w_1 = 0$ gives

$$f_0^{(0)} = uz + u,$$
$$f_1^{(0)} = uvz + uv,$$
$$g_0^{(0)} = z + u^3,$$
$$g_1^{(0)} = vz + u^3v.$$

In the voting for $s = 0$, $w_0 = 1$ is chosen with four votes while other candidates get zero vote. The choice $w_0 = 1$ gives

$$f_0^{(-1)} = uz,$$
$$f_1^{(-1)} = uvz,$$
$$g_0^{(-1)} = z + u^3 + 1,$$
$$g_1^{(-1)} = vz + u^3v + v.$$

At $s = -1$, we find $\alpha_0 = 0$, $\alpha_1 = u$ and $2 = -v_Q(\alpha_1) \leq \tau = 2$. Thus the algorithm outputs $(w_s)_{s\in\Gamma}$ as decoded information by the third termination criterion. The decoded codeword is again

$(1, 1, 1, 1, 0, 0, 0, 0)$. The three termination criterion give the same decoded codeword, but their numbers of iterations are different.

Recall that all of candidates $w_4 = 0,\ 1,\ \beta,\ \beta^2$ are chosen by voting at $s = 4$ because all the candidates have the same number of votes. Only $w_4 = 0$ gives the correct codeword, while $w_4 = \beta$ and $w_4 = \beta^2$ give two other different incorrect codewords whose Hamming distances are both 2 from $\vec{r}$. In this example, multiple candidates are chosen only at $s = 4$.

4. Theoretical analysis of the proposed modification

In this section we prove that our modified algorithm can find all the codewords within Hamming distance τ from the received word $\vec{r}$. We also give upper bounds on the number of iterations in Section 4.6.

4.1. Supporting lemmas

In Section 4.1 we shall introduce several lemmas necessary in Sections 4.2–4.5. Recall that the execution of our modified algorithm can branch when there are multiple candidates satisfying the condition (26). For a fixed sequence of determined w_s, define $\vec{r}^{(N)} = \vec{r}$ and recursively define $\vec{r}^{(\mathrm{prec}(s))} = \vec{r}^{(s)} - \mathrm{ev}(w_s\varphi_s)$. By definition $\vec{r}^{(-1)} = \vec{r} - \mathrm{ev}(\sum_{s\in\Gamma} w_s\varphi_s)$.

The following lemma explains why the authors include "Gröbner bases" in the paper title. The module $I_{\vec{r}^{(N)}}$ was used in Beelen and Brander (2010), Fujisawa et al. (2006), Lax (2012), Lee and O'Sullivan (2009), Matsumoto et al. (2013), Sakata (2001, 2003) but the use of $I_{\vec{r}^{(s)}}$ with $s < N$ was new in Lee et al. (2012).

Lemma 6. *Fix $s \in H(Q) \cup \{-1\}$. Let $\vec{r}^{(s)}$ correspond to w_s ($s \in \Gamma$) chosen by the decoding algorithm. Define the $\mathbf{F}_q[x_1]$-submodule $I_{\vec{r}^{(s)}}$ of $\mathcal{L}(\infty Q)z \oplus \mathcal{L}(\infty Q)$ by*

$$I_{\vec{r}^{(s)}} = \{\alpha_0 + \alpha_1 z \mid \alpha_0, \alpha_1 \in \mathcal{L}(\infty Q),\ v_{P_i}(\alpha_0 + r_i^{(s)}\alpha_1) \geq 1,\ 1 \leq i \leq n\}, \tag{29}$$

where $\vec{r}^{(s)} = (r_1^{(s)}, \ldots, r_n^{(s)})$. Then $\{f_i^{(s)}, g_i^{(s)} \mid i = 0, \ldots, a_1 - 1\}$ is a Gröbner basis of $I_{\vec{r}^{(s)}}$ with respect to $<_s$ as an $\mathbf{F}_q[x_1]$-module.

Proof. This lemma is a generalization of Lee et al. (2012, Proposition 11). We can prove this lemma in exactly the same way as the proof of Lee et al. (2012, Proposition 11) with replacing y^j in Lee et al. (2012) with y_j and $s - 1$ in Lee et al. (2012) by $\mathrm{prec}(s)$. □

The following proposition shows that the original decoding algorithm in Lee et al. (2012) can correct errors up to half the bound $d_{\mathrm{AG}}(C_\Gamma)$, which was not claimed in Lee et al. (2012).

Proposition 7. *Fix $s \in \Gamma$. Let $\lambda(s)$ as defined in Eq. (6) and $\nu(s)$ as defined in Eq. (24). Then $\nu(s) = \lambda(s)$.*

Proof. Let $T_i = \{j \in H(Q) \mid j \equiv i \pmod{a_1},\ j + s \in \widehat{H}(Q)\}$, then we have $\lambda(s) = \sharp T_0 + \cdots + \sharp T_{a_1-1}$. Moreover, observe that

$$H(Q) \setminus \widehat{H}(Q) = \{-v_Q(\eta_i x_1^k) \mid i = 0, \ldots, a_1 - 1, k = 0, 1, \ldots\}.$$

Therefore, for $s \in \Gamma$ we have

$$\begin{aligned}
T_i &= \{j \in H(Q) \mid j \equiv i \pmod{a_1},\ j + s \in \widehat{H}(Q)\} \\
&= \{j \in H(Q) \mid j \equiv i \pmod{a_1},\ j + s \notin H(Q) \setminus \widehat{H}(Q)\} \\
&= \{j \in H(Q) \mid j \equiv i \pmod{a_1},\ j + s \notin \{-v_Q(\eta_{i'} x_1^k) \mid k \geq 0\}\} \\
&= \{-v_Q(y_i x_1^m) \mid s - v_Q(y_i x_1^m) \notin \{-v_Q(\eta_{i'} x_1^k) \mid k \geq 0\}\},
\end{aligned}$$

where the third equality holds by Eq. (21). By the equalities above, we see

$$\sharp T_i = \max\left\{0, \frac{-v_Q(\eta_{i'}) + v_Q(y_i) - s}{-v_Q(x_1)}\right\},$$

which proves the equality $\nu(s) = \lambda(s)$. □

Lee et al. (2012) showed that their original decoding algorithm can correct up to $\lfloor (d_{\mathrm{LBAO}}(C_u) - 1)/2 \rfloor$ errors, where $d_{\mathrm{LBAO}}(C_u) = \min\{\nu(s) \mid s \in H(Q),\ s \le u\}$. Proposition 7 implies that $d_{\mathrm{LBAO}}(C_u)$ is equivalent to $d_{\mathrm{AG}}(C_u)$ for every one-point primal code C_u, and therefore Andersen and Geil (2008, Theorem 8) implies Lee et al. (2012, Proposition 12). In another recent paper (Geil et al., 2013) we proved that d_{AG} and d_{LBAO} are equal to the Feng–Rao bound as defined in Beelen and Høholdt (2008), Matsumoto and Miura (2000c) for C_u.

4.2. Lower bound for the number of votes

In Section 4.2 we discuss the number of votes (26) which a candidate $w_{s,i}$ receives. Since we study list decoding, we cannot assume the original transmitted codeword nor the error vector as in Lee et al. (2012). Nevertheless, the original theorems in Lee et al. (2012) allow natural generalizations to the list decoding context.

Lemma 8. *Fix $s \in \Gamma$. For $s' \in \Gamma^{(>s)}$, fix a sequence of $w_{s'}$ chosen by the decoding algorithm, and define $\vec{r}^{(s)}$ corresponding to the chosen sequence of $w_{s'}$. Fix $\omega_s \in \mathbf{F}_q$. Let $\vec{e} = (e_1, \dots, e_n)^T$ be a nonzero vector with the minimum Hamming weight in the coset $\vec{r}^{(s)} - \mathrm{ev}(\omega_s \varphi_s) + C_{s-1}$, where C_{s-1} is as defined in Eq. (1). Define*

$$\begin{aligned} J_{\vec{e}} &= \bigcap_{e_i \neq 0} \mathcal{L}(-P_i + \infty Q) \\ &= \mathcal{L}\left(\infty Q - \sum_{e_i \neq 0} P_i\right) \text{ (by Matsumoto and Miura, 2000a).} \end{aligned}$$

Let $\{\epsilon_0, \dots, \epsilon_{a_1 - 1}\}$ be a Gröbner basis for $J_{\vec{e}}$ as an $\mathbf{F}_q[x_1]$-module with respect to $<_s$ (for any integer s), such that $\mathrm{LM}(\epsilon_j) = x_1^{k_j} y_j$.

Under the above notations, we have

$$\begin{aligned} -v_Q(\epsilon_i) + v_Q(a_{i,i} y_i) &\ge a_1 \bar{c}_i, \\ \min\{-v_Q(\epsilon_i) + s, -v_Q(\eta_{i'})\} &\ge -v_Q(d_{i',i'} y_{i'}), \end{aligned}$$

for i with $w_{s,i} \neq \omega_s$, and

$$\min\{-v_Q(\epsilon_i) + s, -v_Q(\eta_{i'})\} \ge -v_Q(d_{i',i'} y_{i'}) - a_1 \bar{c}_i,$$

for i with $w_{s,i} = \omega_s$.

Proof. The proof is the same as those of Lee et al. (2012, Propositions 7 and 8), with replacing y^j in Lee et al. (2012) by y_j, $\delta(\cdot)$ in Lee et al. (2012) by $-v_Q(\cdot)$. □

The following lemma is a modification to Lee et al. (2012, Proposition 9) for the list decoding.

Lemma 9. *We retain notations from Lemma 8. We have*

$$\begin{aligned} a_1 \sum_{w_{s,i} = \omega_s} \bar{c}_i &\ge a_1 \sum_{w_{s,i} \neq \omega_s} \bar{c}_i - 2a_1 \mathrm{wt}(\vec{e}) \\ &+ \sum_{0 \le i < a_1} \max\{-v_Q(\eta_{i'}) + v_Q(y_i) - s, -v_Q(\epsilon_i) + v_Q(y_i)\}. \end{aligned}$$

Proof. Lemma 8 implies

$$\begin{aligned}\sum_{w_{s,i}=\omega_s} a_1\bar{c}_i &\geq \sum_{w_{s,i}=\omega_s} -v_Q(d_{i',i'}y_{i'}) - \min\{-v_Q(\epsilon_i)+s, -v_Q(\eta_{i'})\}\\ &\geq \sum_{0\leq i<a_1} -v_Q(d_{i',i'}y_{i'}) - \min\{-v_Q(\epsilon_i)+s, -v_Q(\eta_{i'})\}\end{aligned}$$

and

$$\begin{aligned}\sum_{w_{s,i}\neq\omega_s} a_1\bar{c}_i &\leq \sum_{w_{s,i}\neq\omega_s} -v_Q(\epsilon_i) + v_Q(a_{i,i}y_i)\\ &\leq \sum_{0\leq i<a_1} -v_Q(\epsilon_i) + v_Q(a_{i,i}y_i).\end{aligned}$$

Now we have a chain of inequalities

$$\begin{aligned}&\sum_{w_{s,i}=\omega_s} a_1\bar{c}_i - \sum_{w_{s,i}\neq\omega_s} a_1\bar{c}_i\\ &\geq \sum_{0\leq i<a_1} -v_Q(d_{i',i'}y_{i'}) - \min\{-v_Q(\epsilon_i)+s, -v_Q(\eta_{i'})\}\\ &\quad - \sum_{0\leq i<a_1} -v_Q(\epsilon_i) + v_Q(a_{i,i}y_i)\\ &= \sum_{0\leq i<a_1} -v_Q(d_{i',i'}y_{i'}) - v_Q(a_{i,i}y_i)\\ &\quad - \min\{-v_Q(\epsilon_i)+s, -v_Q(\eta_{i'})\} + v_Q(\epsilon_i)\\ &= \sum_{0\leq i<a_1} -v_Q(\eta_{i'}) - v_Q(y_i)\\ &\quad + \max\{+v_Q(\epsilon_i)-s, +v_Q(\eta_{i'})\} + v_Q(\epsilon_i)\\ &= \sum_{0\leq i<a_1} \max\{-v_Q(\eta_{i'})+v_Q(y_i)-s, -v_Q(\epsilon_i)+v_Q(y_i)\}\\ &\quad - \sum_{0\leq i<a_1} 2(-v_Q(\epsilon_i)+v_Q(y_i)) \qquad (30)\end{aligned}$$

where at Eq. (30) we used the equality

$$\begin{aligned}&\sum_{0\leq i<a_1} -v_Q(d_{i',i'}y_{i'}) + \sum_{0\leq i<a_1} -v_Q(a_{i,i}y_i)\\ &= \sum_{0\leq i<a_1} -v_Q(d_{i,i}y_i) + \sum_{0\leq i<a_1} -v_Q(a_{i,i}y_i)\\ &= \sum_{0\leq i<a_1} (-v_Q(d_{i,i}) - v_Q(a_{i,i})) + \sum_{0\leq i<a_1} -2v_Q(y_i)\\ &= a_1 n + \sum_{0\leq i<a_1} -2v_Q(y_i)\\ &= \sum_{0\leq i<a_1} (-v_Q(\eta_i)+v_Q(y_i)) + \sum_{0\leq i<a_1} -2v_Q(y_i)\\ &= \sum_{0\leq i<a_1} -v_Q(\eta_{i'}) + \sum_{0\leq i<a_1} -v_Q(y_i)\end{aligned}$$

shown in Lee et al. (2012, Lemma 2 and Eq. (1)). Finally note that

$$\begin{aligned}&\sum_{0\le i<a_1} 2(-v_Q(\epsilon_i)+v_Q(y_i))\\ &=\sum_{0\le i<a_1} 2a_1\deg_{x_1}(\epsilon_i)=2a_1\mathrm{wt}(\vec{e})\end{aligned}$$

by Lee et al. (2012, Eq. (3)). □

The following lemma is a modification of Lee et al. (2012, Proposition 10) for list decoding, and provides a lower bound for the number of votes (26) received by any candidate $\omega_s \in \mathbf{F}_q$, as indicated in the section title.

Proposition 10. *We retain notations from Lemma 8. Let $\nu(s)$ be as defined in Eq. (24). We have*

$$\sum_{w_{s,i}=\omega_s} \bar{c}_i \ge \sum_{w_{s,i}\ne\omega_s} \bar{c}_i - 2\mathrm{wt}(\vec{e}) + \nu(s).$$

Proof. We have

$$\begin{aligned}&\sum_{0\le i<a_1} \max\{-v_Q(\eta_{i'})+v_Q(y_i)-s, -v_Q(\epsilon_i)+v_Q(y_i)\}\\ &\ge \sum_{0\le i<a_1} \max\{-v_Q(\eta_{i'})+v_Q(y_i)-s, 0\}\end{aligned}$$

as $-v_Q(\epsilon_i)+v_Q(y_i)\ge 0$ for $0\le i<a_1$. □

4.3. Correctness of the modified list decoding algorithm with the third iteration termination criterion

In this subsection and the following sections, we shall prove that the proposed list decoding algorithm will find all the codewords within the Hamming distance τ from the received word $\vec{r}$. Since the third iteration termination criterion is the easiest to analyze, we start with the third one.

Fix a sequence w_s for $s\in\Gamma$. If $\mathrm{wt}(\vec{r}-\mathrm{ev}(\sum_{s\in\Gamma} w_s\varphi_s))\le\tau$ then the sequence w_s is found by the algorithm because of Proposition 10. When $2\tau < d_{\mathrm{AG}}(C_\Gamma)$, by Proposition 7 the decoding is not list decoding, and the algorithm just declares the sequence w_s as the transmitted information.

On the other hand, if $2\tau \ge d_{\mathrm{AG}}(C_\Gamma)$, then the found sequence could correspond to a codeword more distant than Hamming distance τ, and the algorithm examines the Hamming distance between the found codeword and the received word $\vec{r}$.

Since computing $\mathrm{ev}(f)$ for $f\in\mathcal{L}(\infty Q)$ needs many multiplications in $\mathbf{F}_q$, the algorithm checks some sufficient conditions to decide the Hamming distance between the found codeword and the received word $\vec{r}$. Let $\vec{r}^{(-1)}=(r_1^{(-1)},\dots,r_n^{(-1)})$. When $\alpha_0=0$ in Section 3.6.3, by Lemma 6, we have

$$\begin{aligned}\mathrm{wt}(\vec{r}-\mathrm{ev}(\sum_{s\in\Gamma} w_s\varphi_s)) &= \mathrm{wt}(\vec{r}^{(-1)})\\ &\le \sum_{r_i^{(-1)}\ne 0} v_{P_i}(\alpha_1)\\ &\le -v_Q(\alpha_1),\end{aligned}$$

because of Eq. (29) and $\alpha_0=0$ implies that $v_{P_i}(\alpha_1)\ge 1$ for $r_i^{(-1)}\ne 0$. By the above equation, $-v_Q(\alpha_1)\le\tau$ implies that the found codeword is within Hamming distance τ from $\vec{r}$. This explains why the algorithm can avoid computation of the evaluation map ev in Step 1 in Section 3.6.3.

In order to explain Step 2 in Section 3.6.3, we shall show that the condition of Step 2 in Section 3.6.3 implies that $\mathrm{wt}(\vec{r} - \mathrm{ev}(\sum_{s\in\Gamma} w_s\varphi_s)) > \tau$. Suppose that $\mathrm{wt}(\vec{r} - \mathrm{ev}(\sum_{s\in\Gamma} w_s\varphi_s)) \le \tau$. Then there exists $\beta_1 \in \mathcal{L}(\infty Q)$ such that $v_{P_i}(\beta) \ge 1$ for $r_i^{(-1)} \ne 0$, $-v_Q(\beta) \le \tau + g$, and $\beta_1 z \in I_{\vec{r}^{(-1)}}$. Because the leading term of $\beta_1 z$ must be divisible by $\mathrm{LT}(f_i^{(-1)})$ for some i by the property of Gröbner bases, we must have $-v_Q(\alpha_1) \le -v_Q(\beta_1)$. This explains why the algorithm can avoid computation of the evaluation map ev in Step 2 in Section 3.6.3.

Otherwise, the algorithm computes the Hamming distance between the found codeword and $\vec{r}$ in Steps 3 and 4 in Section 3.6.3.

4.4. Correctness of the modified list decoding algorithm with the second iteration termination criterion

We shall explain why the second criterion in Section 3.6.2 correctly finds the required codewords. For explanation, we present slightly rephrased version of facts in Beelen and Høholdt (2008).

Lemma 11. *(See Beelen and Høholdt, 2008, Lemma 2.3.) Let $\beta_1 z + \beta_0 \in I_{\vec{r}^{(s)}}$ with $\mathrm{LT}(\beta_1 z + \beta_0) = \mathrm{LT}(\beta_1 z)$ with respect to $<_s$ and $-v_Q(\beta_1) < n - \tau - s$. If there exists $f \in \mathcal{L}(sQ)$ such that $\mathrm{wt}(\mathrm{ev}(f) - \vec{r}^{(s)}) \le \tau$, then we have $f = -\beta_0/\beta_1$.*

Proof. Observe that $\mathrm{LT}(\beta_1 z + \beta_0) = \mathrm{LT}(\beta_1 z)$ implies that $-v_Q(\beta_0) \le -v_Q(\beta_1) + s < n - \tau$. The claim of Lemma 11 is equivalent to Beelen and Høholdt (2008, Lemma 2.3) with $A = (n - \tau - 1)Q$ and $G = sQ$. Note that the assumption $\deg A > (n + \deg G)/2 + g - 1$ was not used in Beelen and Høholdt (2008, Lemma 2.3) but only in Beelen and Høholdt (2008, Lemma 2.4). □

Note that the following proposition was essentially proved in Beelen and Høholdt (2008, Proposition 2.10), Justesen and Høholdt (2004, Section 14.2), and Shokrollahi and Wasserman (1999, Theorem 2.1) with $b = 1$.

Proposition 12. *Let α_0 and α_1 be as in Section 3.6.2. If $s < n - g - 2\tau$ and there exists $f \in \mathcal{L}(sQ)$ such that $\mathrm{wt}(\mathrm{ev}(f) - \vec{r}^{(s)}) \le \tau$, then we have $f = -\alpha_0/\alpha_1$.*

Proof. Let $g \in \mathcal{L}(\infty Q)$ such that $g(P_i) = 0$ if $f(P_i) \ne r_i^{(s)}$, and assume that g has the minimum pole order at Q among such elements in $\mathcal{L}(\infty Q)$. Then $-v_Q(g) \le \tau + g$. One has that $gz - fg \in I_{\vec{r}^{(s)}}$ and $\mathrm{LT}(gz - fg) = \mathrm{LT}(gz)$ with respect to $<_s$. By the property of Gröbner bases, $\mathrm{LT}(gz)$ is divisible by $\mathrm{LT}(f_i^{(s)})$ for some i, which implies $-v_Q(\alpha_1) \le -v_Q(g) \le \tau + g$. By Lemma 11 we have $f = -\alpha_0/\alpha_1$. □

We explain how the procedure in Section 3.6.2 works as desired. When the condition in Step 1 in Section 3.6.2 is true, then there cannot be a codeword within Hamming distance τ from $\vec{r}^{(s)}$ by the same reason as in Section 4.3. So the algorithm stops processing with $\vec{r}^{(s)}$.

When $2\tau < d_{\mathrm{AG}}(C_\Gamma)$, then the algorithm declares $-\alpha_0/\alpha_1 + \sum_{s'\in\Gamma^{(>s)}} w_{s'}\varphi_{s'}$ as the unique codeword.

When $2\tau \ge d_{\mathrm{AG}}(C_\Gamma)$, then the algorithm examines the found codeword close enough to $\vec{r}$ in Steps 4a and 4b in Section 3.6.2. When $-v_Q(\alpha_1) \le \tau$ we can avoid computation of the evaluation map ev by the same reason as in Section 4.3, which is checked at Step 4a. Otherwise we compute the codeword vector at Step 4b and examine its Hamming distance to $\vec{r}^{(s)}$.

By Proposition 12, the codeword must be found at $s = \max\{s' \in \Gamma \mid s' < n - 2\tau + g\}$. Therefore, we do not execute the iteration at $s < \max\{s' \in \Gamma \mid s' < n - 2\tau + g\}$.

4.5. Correctness of the modified list decoding algorithm with the first iteration termination criterion

We shall explain why the first criterion in Section 3.6.1 correctly finds the required codewords. The idea behind the first criterion is that there cannot be another codeword within Hamming distance τ

from $\vec{r}^{(s)}$ when the algorithm already found one. So the algorithm can stop iteration with smaller s once a codeword is found as $\mathrm{ev}(-\alpha_0/\alpha_1 + \sum_{s' \in \Gamma^{(>s)}} w_{s'} \varphi_{s'})$.

The algorithm does not examine conditions when $-v_Q(\alpha_1) > \tau + g$ by the same reason as in Sections 4.3 and 4.4. When $2\tau < d_{\mathrm{AG}}(C_\Gamma)$, then the algorithm declares $-\alpha_0/\alpha_1 + \sum_{s' \in \Gamma^{(>s)}} w_{s'} \varphi_{s'}$ as the unique codeword.

When $2\tau \geq d_{\mathrm{AG}}(C_\Gamma)$, then the algorithm examines the found codeword close enough to $\vec{r}$ in Steps 2a–2c in Section 3.6.1. When $-v_Q(\alpha_1) \leq \tau$ we can avoid computation of the evaluation map ev by the same reason as in Section 4.3, which is checked at Step 2a.

By Proposition 12, the codeword must be found at some $s \geq \max\{s' \in \Gamma \mid s' < n - 2\tau + g\}$. Therefore, we do not execute the iteration at $s < \max\{s' \in \Gamma \mid s' < n - 2\tau + g\}$.

4.6. Upper bound on the number of iterations and the worst case complexity

Observe that for $s > \max \Gamma$ we set always w_s to 0. For each $s \in \Gamma$ satisfying $\nu(s) \leq 2\tau$, the number of accepted candidates satisfying Eq. (26) can be at most q. On the other hand, for s with $\nu(s) > 2\tau$, the number of candidates is either zero or one, because at most one $w \in \mathbf{F}_q$ can satisfy Eq. (26). Therefore, we have upper bounds for the number of iterations, counting executions of Rebasing in Section 3.7.3, as

$$\begin{aligned} &\sharp\{s \in H(Q) \mid \max \Gamma \leq s < N\} + \exp_q(\sharp\{s \in \Gamma \mid \nu(s) \leq 2\tau\}) \\ &\quad \times \sharp\{s \in H(Q) \cup \{-1\} \mid s < \max \Gamma\} \end{aligned} \tag{31}$$

for the third criterion for judging termination, where $\exp_q(x) = q^x$, and

$$\begin{aligned} &\sharp\{s \in H(Q) \mid \max \Gamma \leq s < N)\} + \exp_q(\sharp\{s \in \Gamma \mid \nu(s) \leq 2\tau\}) \\ &\quad \times \sharp\{s \in H(Q) \mid \max\{s' \in \Gamma \mid s' < n - 2\tau - g\} \leq s < \max \Gamma\} \end{aligned} \tag{32}$$

for the first and the second criteria for judging termination. We will use $\max \widehat{H}(Q)$ in place of N in Eqs. (31) and (32) for computation in Tables 1–4, because N depends on $\vec{r}$ and $N \leq \max \widehat{H}(Q)$.

The proposed algorithm processes $2a_1$ polynomials (elements in $\mathcal{L}(\infty Q)$) in each iteration and each polynomial has $O(n)$ terms. For a precise closed-form evaluation of Eqs. (31) and (32), we need a closed-form upper bound of $\sharp\{s \in \Gamma \mid \nu(s) \leq 2\tau\}$ in terms of τ, but the authors could not find such one. Clearly n is an upper bound on $\sharp\{s \in \Gamma \mid \nu(s) \leq 2\tau\}$, and the number of iterations is $O(\exp_q(n))$. Therefore the worst-case complexity is $O(a_1 n \exp_q(n))$. Nonetheless, we will see that the actual computational cost can be lower than the existing list decoding algorithms in some cases in Section 5. We remark that when $\tau < d_{\mathrm{AG}}(C_\Gamma)$ the number of iterations is $\leq n$ and the worst case complexity is $O(a_1 n^2)$ because the number of chosen candidate is at most one by voting at each iteration, and that the complexity $O(a_1 n^2)$ is the same as the BMS algorithm (Sakata et al., 1995a, 1995b).

Observe that the list decoding can be implemented as $\exp_q(\sharp\{s \in \Gamma \mid \nu(s) \leq 2\tau\})$ parallel execution of the unique decoding. Therefore, when one can afford $\exp_q(\sharp\{s \in \Gamma \mid \nu(s) \leq 2\tau\})$ parallel implementation, which increases the circuit size, the decoding time of list decoding is the same as that of the unique decoding.

5. Comparison to conventional methods

5.1. Simulation condition and results

We have provided an upper bound on the number of multiplications and divisions at each step of the proposed algorithm. We simulated 1000 transmissions of codewords with the one-point primal codes on Klein quartic over $\mathbf{F}_8$ with $n = 23$ by using Examples 1 and 4, the one-point Hermitian codes over $\mathbf{F}_{16}$ with $n = 64$, and the one-point primal codes on the curve in Example 2 over $\mathbf{F}_9$ with $n = 77$.

The program is implemented on the Singular computer algebra system (Decker et al., 2011). The program used for this simulation is available from http://arxiv.org/src/1203.6127v5/anc.

Table 1
Decoding results of codes on the Klein quartic ($\mathbf{F}_q = \mathbf{F}_8$, $g = 3$ and $n = 23$).

$\sharp\Gamma$	$d_{\mathrm{AG}}(C_\Gamma)$	# Errors $= \tau$	Termination criterion in Sec. 3.6	# Iterations			# Multiplications & divisions in $\mathbf{F}_q$		# Codewords found	
				Eqs. (31), (32)	Avg.	Max.	Avg.	Max.	Avg.	Max.
18	4	1	1st	11	8.00	8	1170.09	1254	1.00	1
			2nd	11	11.00	11	844.98	879		
			3rd	26	26.00	26	976.32	1018		
		2	1st	328	196.63	260	26,203.96	77,209	1.34	3
			2nd	328	200.64	269	8,349.67	15,457		
			3rd	1160	219.07	313	7,813.76	10,083		
		3	1st	28,680	11,996.34	13,353	1,626,658.69	2,490,386	19.75	28
			2nd	28,680	12,055.56	13,419	608,535.03	711,315		
			3rd	73,736	12,436.00	13,853	580,504.03	642,419		
11	10	4	1st	17	14.64	15	1,324.76	1484	1.00	1
			2nd	17	16.64	17	1,161.52	1293		
			3rd	26	25.64	26	1,329.07	1468		
		5	1st	47	35.20	44	3,673.78	5549	1.00	1
			2nd	47	38.20	47	2,915.04	3622		
			3rd	103	45.41	72	3,072.08	3769		
		6	1st	3087	1,507.95	1692	164,274.07	188,797	1.11	3
			2nd	3087	1,511.28	1695	113,592.10	130,810		
			3rd	5647	1,535.23	1725	113,472.30	130,697		

Table 2
Decoding results of the one-point Hermitian codes ($\mathbf{F}_q = \mathbf{F}_{16}$, $g = 6$, $n = 64$ and $\sharp\Gamma = 55$). The meanings of N and R in the third column is explained in Section 5.1.

$\sharp\Gamma$	$d_{\mathrm{AG}}(C_\Gamma)$	# Errors $= \tau$	Termination criterion in Sec. 3.6	# Iterations			# Multiplications & divisions in $\mathbf{F}_q$		# Codewords found	
				Eqs. (31), (32)	Avg.	Max.	Avg.	Max.	Avg.	Max.
55	6	2R	1st	22	16.38	17	9,049.77	9495	1.00	1
			2nd	22	21.79	22	5,483.91	5614		
			3rd	70	69.79	70	6,331.16	6530		
		2N	1st	22	16.22	17	9,005.92	9477	1.00	1
			2nd	22	21.22	22	5,414.32	5607		
			3rd	70	69.22	70	6,291.44	6527		
		3R	1st	2829	796.17	1139	289,992.45	2,154,489	1.00	2
			2nd	2829	800.66	1143	116,784.32	164,299		
			3rd	14,605	846.78	1191	117,848.30	130,366		
		3N	1st	2829	750.73	817	334,588.68	360,413	2.28	5
			2nd	2829	761.79	825	120,575.80	131,791		
			3rd	14,605	872.97	917	119,940.46	134,297		
		4R	1st	851,981	21,376.57	33,187	8,012,813.23	14,988,534	1.48	4
			2nd	851,981	21,384.19	33,198	2,431,318.50	3,763,057		
			3rd	3,735,565	21,458.60	33,327	2,432,782.60	3,761,206		
		4N	1st	851,981	21,744.53	32,943	10,952,709.73	16,938,498	4.29	5
			2nd	851,981	21,769.88	32,962	2,457,072.25	3,801,066		
			3rd	3,735,565	21,985.53	33,174	2,439,145.90	3,805,702		

In the execution, we counted the number of iterations (executions of Rebasing in Section 3.7.3), the sum of upper bounds on the number of multiplications and divisions given in Eqs. (15), (16), (17), (18), (19), (20), (23), (27) and (28), and the number of codewords found. Note also that Eq. (11) instead of Eq. (13) is used.

The parameter τ is set to the same as the number of generated errors in each simulation condition. N or R in the number of errors in Tables 2 and 3 indicates that the error vector is generated

Table 3
Decoding results of the one-point Hermitian codes ($\mathbf{F}_q = \mathbf{F}_{16}$, $g = 6$, $n = 64$ and $\sharp\Gamma = 39$). The meanings of N and R in the third column is explained in Section 5.1.

$\sharp\Gamma$	$d_{\mathrm{AG}}(C_\Gamma)$	# Errors $= \tau$	Termination criterion in Sec. 3.6	# Iterations			# Multiplications & divisions in $\mathbf{F}_q$		# Codewords found	
				Eqs. (31), (32)	Avg.	Max.	Avg.	Max.	Avg.	Max.
39	20	9R	1st	36	30.77	31	10,726.51	11,175	1.00	1
			2nd	36	35.77	36	8,851.66	9249		
			3rd	70	69.77	70	10,781.91	11,504		
		9N	1st	36	30.73	32	9,747.36	12,008	1.00	1
			2nd	36	35.73	36	7,807.55	8378		
			3rd	70	69.73	70	9,607.34	10,645		
		10R	1st	143	74.99	93	37,643.43	47,179	1.00	1
			2nd	143	80.99	99	22,792.85	25,972		
			3rd	655	112.99	131	25,023.33	28,398		
		10N	1st	143	77.64	126	46,759.83	177,947	2.00	2
			2nd	143	89.61	138	23,971.51	43,332		
			3rd	655	153.73	244	28,063.19	36,453		
		11R	1st	36,895	12,112.08	12,859	7,480,228.09	7,911,646	1.00	1
			2nd	36,895	12,118.08	12,865	3,186,977.77	3,352,388		
			3rd	159,775	12,148.10	12,895	3,189,262.07	3,354,588		
		11N	1st	36,895	10,417.34	12,285	6,123,703.49	7,582,687	2.01	6
			2nd	36,895	10,429.34	12,297	2,638,130.92	3,226,308		
			3rd	159,775	10,491.11	12,357	2,641,014.19	3,230,078		

Table 4
Decoding results of codes on the curve in Example 2 ($\mathbf{F}_q = \mathbf{F}_9$, $g = 22$ and $n = 77$). We note that Eq. (31) give the same value for $\tau = 10$ and $\tau = 11$.

$\sharp\Gamma$	$d_{\mathrm{AG}}(C_\Gamma)$	# Errors $= \tau$	Termination criterion in Sec. 3.6	# Iterations			# Multiplications & divisions in $\mathbf{F}_q$		# Codewords found	
				Eqs. (31), (32)	Avg.	Max.	Avg.	Max.	Avg.	Max.
58	6	2	1st	60	38.85	42	39,473.98	62,479	1.00	1
			2nd	60	59.30	60	12,255.73	13,348		
			3rd	89	88.30	89	13,710.71	14,886		
		3	1st	2862	62.50	120	36,350.41	72,463	1.00	1
			2nd	2862	79.62	134	21,754.75	30,030		
			3rd	5049	106.62	161	23,556.44	31,555		
52	10	4	1st	64	46.94	51	37,228.61	78,090	1.00	1
			2nd	64	63.25	64	15,212.23	16,708		
			3rd	89	88.25	89	17,082.34	18,879		
		5	1st	196,866	48.96	163	24,776.23	88,893	1.00	1
			2nd	196,866	66.17	178	20,660.52	69,176		
			3rd	347,769	89.17	201	22,591.78	71,264		
37	20	9	1st	73	57.28	60	24,998.86	48,611	1.00	1
			2nd	73	72.34	73	23,168.98	24,784		
			3rd	89	88.34	89	25,655.70	27,675		
		10	1st	1915	58.67	61	25,492.43	43,294	1.00	1
			2nd	1915	74.39	75	27,355.54	29,452		
			3rd	3049	88.39	89	29,678.00	31,836		
		11	1st	2077	225.59	253	167,152.76	191,250	1.00	1
			2nd	2077	242.36	268	124,664.66	139,519		
			3rd	3049	254.36	280	126,693.96	141,989		

toward another codeword nearest from the transmitted codeword or completely randomly, respectively. The distribution of codewords is uniform on C_Γ. That of error vectors is uniform on the vectors of Hamming weight τ.

In the code construction, we always try to use the Feng–Rao improved construction. Specifically, for a given designed distance δ, we choose $\Gamma = \{s \in \widehat{H}(Q) \mid \lambda(s) = \nu(s) \geq \delta\}$, and construct C_Γ of Eq. (4). In the following, the designed distance is denoted by $d_{\mathrm{AG}}(C_\Gamma)$. It can be seen from Tables 1–4 and the following subsections that the computational complexity of the proposed algorithm tends to explode when the number of errors exceeds the error-correcting capability of the Guruswami–Sudan algorithm (Guruswami and Sudan, 1999).

5.2. Comparison among the three proposed termination criteria

In Section 3.6 we proposed three criteria for terminating iteration of the proposed algorithm. From Tables 1–4, one can see the following. The first criterion has the smallest number of iterations, and the second is the second smallest. On the other hand, the first criterion has the largest number of multiplications and divisions. The second and the third have the similar numbers. Only the first criterion was proposed in Geil et al. (2012) and we see that the new criteria are better than the old one.

The reason is as follows: The computation of quotient α_0/α_1 at Step 1 in Section 3.6.1 is costlier than updating $f_i^{(s)}$ and $g_i^{(s)}$ in Section 3.7.3 and the first criterion computes α_0/α_1 many times, which cancels the effect of decrease in the number of iterations. On the other hand, the second criterion computes α_0/α_1 only once, so it has the smaller number of multiplications and divisions than the first.

The second criterion is faster when $2\tau < d_{\mathrm{AG}}(C_\Gamma)$, while the third tends to be faster when $2\tau \geq d_{\mathrm{AG}}(C_\Gamma)$. In addition to this, the ratio of the number of iterations in the second criterion to that of the third is smaller with $2\tau < d_{\mathrm{AG}}(C_\Gamma)$ than with $2\tau \geq d_{\mathrm{AG}}(C_\Gamma)$. We speculate the reason behind them as follows: When $2\tau \geq d_{\mathrm{AG}}(C_\Gamma)$ and a wrong candidate is chosen at Eq. (26), after several iterations of Sections 3.6 and 3.7, we often observe in our simulation that no candidate satisfies Eq. (26) and the iteration stops automatically. Under such situation, the second criterion does not help much to decrease the number of iterations nor the computational complexity when a wrong candidate is chosen at Eq. (26), and there are many occasions at which a wrong candidate is chosen at Eq. (26) when $2\tau \geq d_{\mathrm{AG}}(C_\Gamma)$. On the other hand, when $2\tau < d_{\mathrm{AG}}(C_\Gamma)$, the second criterion helps to determine the transmitted information earlier than the third.

5.3. Tightness of upper bounds (31) and (32)

In Table 4, we observe that the upper bounds (31) and (32) are much larger than the actual number of iterations for $\tau = 5$. The disappearance of candidates satisfying Eq. (26) in the last paragraph may also explain the reason behind the large differences for $\tau = 5$.

On the other hand, we observe that the upper bound (32) is quite tight for $\tau = 5$ in Table 1 and $\tau = 10$ N in Table 3. This suggests that improvement of Eq. (32) may need some additional assumption.

5.4. Klein quartic, $(d_{\mathrm{AG}}(C_\Gamma), \tau) = (4, 1)$ or $(10, 4)$

We can use Beelen (2007), Beelen and Høholdt (2008), Duursma et al. (2011), Duursma and Park (2010), Matsumoto and Miura (2000c) to decode this set of parameters. It is essentially the forward elimination in the Gaussian elimination, and it takes roughly $n^3/3$ multiplications. In this case $n^3/3 = 4055$. The proposed algorithm has lower complexity than Beelen (2007), Beelen and Høholdt (2008), Duursma et al. (2011), Duursma and Park (2010), Matsumoto and Miura (2000c).

5.5. Klein quartic, $(d_{\mathrm{AG}}(C_\Gamma), \tau) = (4, 2)$ or $(4, 3)$

The code is C_u with $u = 20$, $\dim C_u = 18$. There is no previously known algorithm that can handle this case.

5.6. Klein quartic, $(d_{\mathrm{AG}}(C_\Gamma), \tau) = (10, 5)$

The code is C_u with $u = 13$, $\dim C_u = 11$. According to Beelen and Brander (2010, Fig. 1), we can use the original Guruswami–Sudan (Guruswami and Sudan, 1999) but it seems that its faster variants cannot be used. We need multiplicity 7 to correct 5 errors. We have to solve a system of $23(7+1)7/2 = 644$ linear equations. It takes $644^3/3 = 89{,}029{,}994$ multiplications in $\mathbf{F}_8$. The proposed algorithm is much faster.

5.7. Klein quartic, $(d_{\mathrm{AG}}(C_\Gamma), \tau) = (10, 6)$

The code is C_u with $u = 13$, $\dim C_u = 11$. There is no previously known algorithm that can handle this case.

5.8. Hermitian, $(d_{\mathrm{AG}}(C_\Gamma), \tau) = (6, 2)$ *or* $(20, 9)$

We can use the BMS algorithm (Sakata et al., 1995a, 1995b) for this case. The complexity of Sakata et al. (1995a, 1995b) is estimated as $O(a_1 n^2)$ and $a_1 n^2 = 24{,}576$. The complexity of the proposed algorithm seems comparable to Sakata et al. (1995a, 1995b). However, we are not sure which one is faster.

5.9. Hermitian, $(d_{\mathrm{AG}}(C_\Gamma), \tau) = (6, 3)$ *or* $(6, 4)$

The code becomes the Feng–Rao improved code with designed distance 6. Its dimension is 55. In order to have the same dimension by C_u we have to set $u = 60$, whose AG bound (Andersen and Geil, 2008) is 4 and the Guruswami–Sudan can correct up to 2 errors. The proposed algorithm finds all codewords in the improved code with 3 and 4 errors.

5.10. Hermitian, $(d_{\mathrm{AG}}(C_\Gamma), \tau) = (20, 10)$

The code is C_u with $u = 44$. The required multiplicity is 11, and the required designed list size is 14. The fastest algorithm for the interpolation step seems Beelen and Brander (2010). Beelen and Brander (2010, Example 4) estimates the complexity of their algorithm as $O(\lambda^5 n^2 (\log \lambda n)^2 \log(\log \lambda n))$, where λ is the designed list size. Ignoring the log factor and assuming the scaling factor one in the big-O notation, the number of multiplications and divisions is $\lambda^5 n^2 = 2{,}202{,}927{,}104$. The proposed algorithm needs much fewer number of multiplications and divisions in $\mathbf{F}_{16}$.

5.11. Hermitian, $(d_{\mathrm{AG}}(C_\Gamma), \tau) = (20, 11)$

The Guruswami–Sudan algorithm (Guruswami and Sudan, 1999) can correct up to 10 errors and there seems no previously known algorithm that can handle this case.

5.12. Garcia–Stichtenoth (Example 2), $(d_{\mathrm{AG}}(C_\Gamma), \tau) = (6, 2)$, $(10, 4)$, *or* $(20, 9)$

We can use Beelen (2007), Beelen and Høholdt (2008), Duursma et al. (2011), Duursma and Park (2010), Matsumoto and Miura (2000c) to decode this set of parameters. It is essentially the forward elimination in the Gaussian elimination, and it takes roughly $n^3/3$ multiplications. In this case $n^3/3 = 152{,}177$. The proposed algorithm has the lower complexity than Beelen (2007), Beelen and Høholdt (2008), Duursma et al. (2011), Duursma and Park (2010), Matsumoto and Miura (2000c).

5.13. Garcia–Stichtenoth (Example 2), $(d_{\mathrm{AG}}(C_\Gamma), \tau) = (6, 3)$

This is a Feng–Rao improved code with dimension 58. In order to realize a code with the same dimension, we have to set $u = 79$ in C_u. The Guruswami–Sudan algorithm (Guruswami and Sudan, 1999) can correct no error in this set of parameters. There seems no previously known algorithm that can handle this case.

5.14. Garcia–Stichtenoth (Example 2), $(d_{\mathrm{AG}}(C_\Gamma), \tau) = (10, 5)$

This is a Feng–Rao improved code with dimension 52. In order to realize a code with the same dimension, we have to set $u = 73$ in C_u. The Guruswami–Sudan algorithm (Guruswami and Sudan, 1999) can correct 2 errors in this set of parameters. There seems no previously known algorithm that can handle this case.

5.15. Garcia–Stichtenoth (Example 2), $(d_{\mathrm{AG}}(C_\Gamma), \tau) = (20, 10)$

This is an ordinary one-point AG code C_u with $u = 58$ and dimension 37. The Guruswami–Sudan algorithm (Guruswami and Sudan, 1999) can correct 10 errors with the multiplicity 154 and the designed list size 178. We have to solve a system of $77 \times (154+1)154/2 = 918{,}995$ linear equations. It takes $918{,}995^3/3 = 258{,}712{,}963{,}551{,}308{,}291$ multiplications in $\mathbf{F}_9$. The proposed algorithm is much faster.

5.16. Garcia–Stichtenoth (Example 2), $(d_{\mathrm{AG}}(C_\Gamma), \tau) = (20, 11)$

The Guruswami–Sudan algorithm (Guruswami and Sudan, 1999) can correct up to 10 errors and there seems no previously known algorithm that can handle this case.

6. Conclusion

In this paper, we modified the unique decoding algorithm for plane AG codes in Lee et al. (2012) so that it can support one-point AG codes on *any* curve, and so that it can do the list decoding. The error correction capability of the original (Lee et al., 2012) and our modified algorithms are also expressed in terms of the minimum distance lower bound in Andersen and Geil (2008).

We also proposed procedures to compute products and quotients in coordinate ring of affine algebraic curves, and by using those procedures we demonstrated that the modified decoding algorithm can be executed quickly. Specifically, its computational complexity is theoretically the same as the BMS algorithm (Sakata, 1995a, 1995b) for one-point Hermitian codes. It is also much faster than the standard list decoding algorithms (Beelen and Brander, 2010; Guruswami and Sudan, 1999) for many cases that are examined and reported in our computational experiments in which examined error-correcting codes have medium sizes. It should be noted that as a list decoding algorithm the proposed method seems to have exponential worst-case computational complexity while the previous proposals (Beelen and Brander, 2010; Guruswami and Sudan, 1999) have polynomial ones, and that the proposed method is expected to be slower than the previous proposal for very large/special inputs.

The original decoding algorithm (Lee et al., 2012) allows parallel implementation on circuits like the Kötter architecture (Kötter, 1998). Our modified algorithm retains this advantage. Moreover, if one can afford large circuit size, the proposed list decoding algorithm can be executed as quickly as the unique decoding algorithm by parallel implementation on a circuit.

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