

3.

```
20 //start building index of the contents of book
21 clock_t startTime = clock();
22 //read word to temp
23 while (inFile >> temp)
24 {
25     if (temp != "-----")
26     {
27         //all transform to lowercase
28         transform(temp.begin(), temp.end(), temp.begin(), ::tolower);
29         //add to IndexMap
30         bookContent.add(temp, bookPage, wordNum);
31         wordNum++;
32     }
33     else
34     {
35         //advance page number; reset wordNum to 1
36         bookPage++;
37         wordNum = 1;
38     }
39 }
40 clock_t endTime = clock();
41 double seconds = static_cast<double>(endTime - startTime) / CLOCKS_PER_SEC;
42 cout << "The time (1 trial) for this function is: " << seconds << " seconds." << endl << endl;
43 cout << "Number of keys stored in the index (distinct words): " << bookContent.numKeys() << "." << endl << endl;
44 IndexRecord fathers = bookContent.get("fathers");
45 cout << fathers << endl << endl;
```

*Code for building the index using Hash Table*

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**BigO Analysis (in general cases):**

- total words in external text file:  $m = 186,000$  (given)
- number of distinct words in index:  $n = 11,325$  (from program)

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**BigO Analysis (build the index through Hash Table)**

Line 23 :  $O(m)$ ; read through all the words in the external text file

Line 30 (add()) : average  $O(1)$ ; derived below;

Rest of the Line :  $O(1)$

**Overall BigO** :  $O(m)$

**Time required (1 trial)** : 0.188s

**3a. BigO Analysis (build the index through Self-balancing BST)**

**BigO for insert for BST** :  $O(\log n)$

This BST will only insert distinct records;  $n$  refers to the number of distinct records as stated above.

**Overall BigO (BST ver.)** :  $O(m * \log(n))$

**Time required:** :  $186000 * \log(11325) * 0.188 / 186000$   
= 0.762s

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### 3b. BigO Analysis (build the index vector)

BigO for insert for vector/array :  $O(n)$

Vector approach follows similar idea, it will first search the entire vector ( $O(n)$  through linear search). If it is not found, it will insert at the back of the vector ( $O(1)$ ).

Overall BigO (vector ver.) :  $O(m * n)$ ; //m total words \* n searches

Time required: :  $186000 * 11325 * 0.188 / 186000$   
= 2129s

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```
107 //Add indicated location to the map.
108 // If the key does not exist in the map, add an IndexRecord for it
109 // If the key does exist, add a Location to its IndexRecord
110 void IndexMap::add(const std::string& key, int pageNumber, int wordNumber)
111 {
112     if (key == EMPTY_CELL || key == PREVIOUS_USED_CELL)
113         throw invalid_argument("Invalid key");
114
115     int bucketNumber = getLocationFor(key);
116
117     if (contains(key))
118         buckets[bucketNumber].addLocation(IndexLocation(pageNumber, wordNumber));
119     else
120     {
121         if (keyCount > MAX_LOAD * numBuckets)
122             grow();
123
124         while (buckets[bucketNumber].word != EMPTY_CELL && buckets[bucketNumber].word != PREVIOUS_USED_CELL)
125         {
126             if (bucketNumber == numBuckets - 1)
127                 bucketNumber = 0;
128             else
129                 bucketNumber++;
130         }
131         buckets[bucketNumber].word = key;
132         buckets[bucketNumber].addLocation(IndexLocation(pageNumber, wordNumber));
133         keyCount++;
134     }
135 }
```

*Code for add()*

BigO for add()

Line 112-113 :  $O(1)$

Line 115 (getLocationFor()) :  $O(1)$

Line 117 (contains()) : avg  $O(1)$

it follows the BigO of random access from vector. However once collision occurs, it will move further steps to check if the cell is valid (maximum steps is around tableCapacity \* 0.7; as it will grow once the keySize reaches the threshold)

Line 118 (addLocation()) :  $O(1)$

Line 122 (grow()) :  $O(numBuckets * total\ number\ of\ records\ in\ locations)$

for this hash map, **grow()** will scan through the entire `buckets[numBuckets]`, once the cell contains valid data, it will copy the data (words in string and locations in array).

Other Line :  $O(1)$

**Overall BigO for add()** : avg  $O(1)$

Although BigO of `grow()` is more significant than the other functions, `grow()` will only be implemented in specific situation. When we are considering the average BigO for `add()`, most of the time it will cost  $O(1)$  only. Therefore, `add()` should cost in average  $O(1)$ .

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```
31 //hash function to return the position of the bucket
32 unsigned int IndexMap::getLocationFor(const std::string& key) const
33 {
34     std::hash<string> hasher;
35     unsigned int hashValue = static_cast<unsigned int>(hasher(key));
36
37     //return that mapped onto table
38     return hashValue % numBuckets;
39 }
```

*Code for getLocationFor(); BigO:  $O(1)$*

```
84 //Returns true if indicated key is in the map
85 bool IndexMap::contains(const std::string& key) const
86 {
87     if(key == EMPTY_CELL || key == PREVIOUS_USED_CELL)
88         throw invalid_argument("Invalid key");
89
90     int bucketNumber = getLocationFor(key);
91
92     while(buckets[bucketNumber].word != EMPTY_CELL && buckets[bucketNumber].word != PREVIOUS_USED_CELL)
93     {
94         if(buckets[bucketNumber].word == key)
95             return true;
96         else
97         {
98             if(bucketNumber == numBuckets - 1)
99                 bucketNumber = 0;
100             else
101                 bucketNumber++;
102         }
103     }
104     return false;
105 }
```

*Code for contains(); BigO: avg  $O(1)$*

```
63 void IndexRecord::addLocation(const IndexLocation& loc)
64 {
65     locations.push_back(loc);
66 }
```

*Code for addLocation(); BigO:  $O(1)$*

```
12 //handle resizing the hash table into a new array with twice as many buckets
13 void IndexMap::grow()
14 {
15     IndexRecord* oldPtr = buckets;
16     int oldNumBuckets = numBuckets;
17     numBuckets = 2 * numBuckets;
18     buckets = new IndexRecord[numBuckets];
19     keyCount = 0;
20     for (int i = 0; i < oldNumBuckets; i++)
21     {
22         if(oldPtr[i].word != EMPTY_CELL && oldPtr[i].word != PREVIOUS_USED_CELL)
23         {
24             for(int j = 0; j < oldPtr[i].locations.size(); j++)
25                 add(oldPtr[i].word, oldPtr[i].locations[j].pageNum, oldPtr[i].locations[j].wordNum);
26         }
27     }
28     delete [] oldPtr;
29 }
```

*Code for grow(); BigO:  $O(\text{numBuckets} * \text{total number of records in locations})$*