MoteC Product Specification				
<b>Document Number</b>	PSAU0009	-		
Title	MoTeC M800 Set 1 Data P	rotocol		
Revision Date	Prepared By	Approved By		
04/7/01	Andrew Naumann	Andrew Dennison		
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## Introduction

This document describes the data protocol implemented in the MoTeC M800 ECU as Telemetry data set 1. This protocol is used between MoTeC products and may change between versions to encompass increased functionality. Changes are typically limited to adding more channels to the end of the data set, however this is not guaranteed.

A separate data set, that is common for all MoTeC ECU, is recommended for 3<sup>rd</sup> party systems that wish to support all MoTeC ECU's with a common data set.

## **Protocol Description**

Byte	Name	Scaling
0:1	RPM	1RPM
2:3	Throttle Position	0.1%
4:5	Manifold Pressure	0.1kPa
6:7	Air Temperature	0.1C
8:9	Engine Temperature	0.1C
10:11	Lambda 1	0.001La
12:13	Lambda 2	0.001La
14:15	Exhaust Manifold Pressure	0.1kPa
16:17	Mass Air Flow	0.1*
18:19	Fuel Temperature	0.1C
20:21	Fuel Pressure	0.1kPa
22:23	Oil Temperature	0.1C
24:25	Oil Pressure	0.1kPa
26:27	Gear Voltage	0.01V
28:29	Knock Voltage	0.01V
30:31	Gear Shift Force	0.1kg
32:33	Exhaust Temperature 1	1C
34:35	Exhaust Temperature 2	1C
36:37	User Channel 1	0.1*
38:39	User Channel 2	0.1*
40:41	User Channel 3	0.1*
42:43	User Channel 4	0.1*
44:45	Battery Voltage	0.01V
46:47	ECU Temperature	0.1C
48:49	Digital Input 1 Speed	0.1km/h
50:51	Digital Input 2 Speed	0.1km/h
52:53	Digital Input 3 Speed	0.1km/h
54:55	Digital Input 4 Speed	0.1km/h
56:57	Drive Speed	0.1km/h
58:59	Ground Speed	0.1km/h
60:61	Slip	0.1km/h
62:63	Aim Slip	0.1km/h
64:65	Launch RPM	1RPM
66:67	Lambda 1 short term trim	0.1%
68:69	Lambda 2 short term trim	0.1%
70:71	Lambda 1 long term trim	0.1%

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PSAU000		1	Pa
72:73	Lambda 2 long term trim	0.1%	
74:75	Aim Lambda 1	0.001La	
76:77	Aim Lambda 2	0.001La	
78:79	Fuel Cut Level	*100/255 = 0.1%	
80:81	Ignition Cut Level	*100/255 = 0.1%	
82:83	Ignition Advance	0.1dBTDC	
84:85	Load Point	0.1	
86:87	Efficiency Point	0.1	
88:89	Fuel Used	0.01L*	
90	Auxiliary O/P 1 Duty Cycle	1%	
91	Auxiliary O/P 2 Duty Cycle	1%	
92	Auxiliary O/P 3 Duty Cycle	1%	
93	Auxiliary O/P 4 Duty Cycle	1%	
94	Auxiliary O/P 5 Duty Cycle	1%	
95	Auxiliary O/P 6 Duty Cycle	1%	
96	Auxiliary O/P 7 Duty Cycle	1%	
97	Auxiliary O/P 8 Duty Cycle	1%	
98:99	Fuel Actual Pulse Width	0.5 μs	
100:101	Fuel Effective Pulse Width	0.5 μs	
100:101	Fuel Injector Duty Cycle	0.1%	
102:103	Gear	/10 = gear	
104:103	Sync Position	0.1%	
108:107	Fuel Comp 1	0.1%	
110:111	Fuel Comp 2	0.1%	
	<u> </u>		1
112	Diagnostic Error Group 1	TP_ERR	1
		MAP_ERR AT ERR	2 4
		ET ERR	8
		LA1 ERR	16
		LAI_ERR	32
		EMAP_ERR	64
		MAF ERR	128
113	Diagnostic Error Group 2	BARO ERR	1
113	Diagnostic Effor Group 2	FT ERR	2
		FP ERR	4
		OT ERR	8
		OP ERR	16
		LAT G ERR	32
		LONG_G_ERR	64
		SLIP V ERR	128
114	Diagnostic Error Group 3	GEAR V ERR	1
** '	Singhood Ditor Group 5	KNOCK ERR	2
		EGT1 ERR	4
		EGT2 ERR	8
		USER1 ERR	16
		USER2 ERR	32
		USER3 ERR	64
		USER4 ERR	128
115	Diagnostic Error Group 4	BATV ERR	1
		ECUT ERR	2
		VERT G ERR	4
		GEAR FORCE ERR	8
		DBW CONT	16
		DBW ERR	32
		DBW_AIM	64
		DBW_FB	128
116	Diagnostic Error Group 5	-	
117	Diagnostic Error Group 6	LOW BAT ERR	1
	_ ^	OVER BOOST ERR	2
		NO SŸNC ERR	4
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PSAU0	009		Pa
		SYNC_ERR	8
		NO REF ERR	16
		REF ERR	32
		RPM OVER ERR	64
		F MAX DTY ERR	128
118	Diagnostic Error Group 7	MEM ERR	1
110	Diagnostic Life Group /	DELTA BAT	2
		LA1_HEATER_ERR	4
		LA2_HEATER_ERR	8
		LA1_OT	16
		LA2_OT	32
		LA1_SENS_ERR	64
		LA2_SENS_ERR	128
119	Diagnostic Error Group 8	-	
120	Diagnostic Error Group 9	RESET TESTMOD	1
		RESET SYS	2
		RESET_NOXTAL	4
		LESET_NOMINE	8
		RESET HALTMON	16
		RESET_HALTMON	
		-	32
		-	64
		RESET_EXT	128
121	Diagnostic Error Group 10	INJ1_ERR	1
		INJ2_ERR	2
		INJ3_ERR	4
		INJ4 ERR	8
		INJ5 ERR	16
		INJ6 <sup>-</sup> ERR	32
		INJ7 ERR	64
		INJ8 ERR	128
122	Diagnostic Error Group 11	INJ1 SHORT	1
122	Diagnostic Effor Group 11	INJ2 SHORT	$\begin{vmatrix} 1 \\ 2 \end{vmatrix}$
		_	4
		INJ3_SHORT	
		INJ4_SHORT	8
		INJ5_SHORT	16
		INJ6_SHORT	32
		INJ7_SHORT	64
		INJ8_SHORT	128
123	Diagnostic Error Group 12	INJ1_OPEN	1
		INJ2_OPEN	2
		INJ3 OPEN	4
		INJ4 OPEN	8
		INJ5 <sup>OPEN</sup>	16
		INJ6 OPEN	32
		INJ7 OPEN	64
		INJ8 OPEN	128
124	Diagnostic Error Group 13	INJ1 PEAK	1
124	Diagnostic Effor Group 13		1
		INJ2_PEAK	2
		INJ3_PEAK	4
		INJ4_PEAK	8
		INJ5_PEAK	16
		INJ6_PEAK	32
		INJ7_PEAK	64
		INJ8_PEAK	128
125	Diagnostic Error Group 14	SYNC LOW	1
	5 <sub>F</sub> 1.	SYNC RNT	2
		SYNC TRIG	4
		_	8
		SYNC_ARM	1
		REF_LOW	16
		REF_RNT	32
		REF_TRIG	64

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I SACOO.		REF ARM	128
126	Diagnostic Error Group 15	-	
127	Diagnostic Error Group 16	-	
128	Diagnostic Error Group 17	-	
129	Diagnostic Error Group 18	-	
130	Diagnostic Error Group 19	-	
131	Status Flags Group 1	RPM Limit Exceeded	1
131	Status Flago Group 1	Launch Control	2
		Gear Change Ign Cut	4
		REF/SYNC Synched	8
		Closed Loop La 1	16
		Closed Loop La 2	32
		Lambda 1 Cold	64
		Lambda 2 Cold	128
132	Status Flags Group 2	Overrun Boost	1
		Alternator Off	2
		Overrun Fuel Cut	4
		_	8
		=	16
		-	32
		=	64
		-	128
133	Status Flags Group 3	Digital Input 1	1
		Digital Input 2	2
		Digital Input 3	4
		Digital Input 4	8
		-	16
		Nitrous	32
		Air Con Request	64
		Dual RPM Limit	128
134	Status Flags Group 4	Traction Ctrl Disable	1
		Clutch	2
		Logging Enable	4
		Beacon Mark	8
		Overrun Boost Enable	16
		Gear Chg Cut Request	32
		Ignition Switch	64
		Brake	128
135	Status Flags Group 5	-	
		- C D	2
		Spray Bar	4
		-	8
		Tolomoter, Control	16 32
		Telemetry Control Power Steer OvLd	64
		Ground Speed Limit	128
126	Status Flags Group 6	Orouna Speca Lillin	120
136	Status Flags Group 6 Status Flags Group 7	Digital Input 5	1
13/	Status Mags Group /	Digital Input 6	$\begin{bmatrix} 1 \\ 2 \end{bmatrix}$
		Digital Input 7	4
		Digital Input 8	8
		Digital Input 9	16
		Digital Input 10	32
		- 2151mi iiiput 10	64
		_	128
138	Status Flags Group 8	-	
139	Number of Data Bytes	139	I.
140	Marker Byte 1	FC	
141	Marker Byte 2	FB	
141	Marker Byte 3	FA	
142	CHKSUM	1 1	
143	CHROUM		

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## NOTE:

- 1. CHKSUM is the sum of all bytes of the structure up to and including marker byte 3
- 2. All units specified assume the ECU is calibrated in the recommended default units (metric). Changes to the ECU units will be reflected in the values transmitted
- 3. For channels marked '\*' there are no default units the units are dependent on ECU configuration
- 4. All channel values are signed quantities
- 5. For compatibility with later versions, do not assume the number of data bytes is a constant