

Developing Heuristic Algorithms for Graph Optimization Problems using Tree Decompositions

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Overview

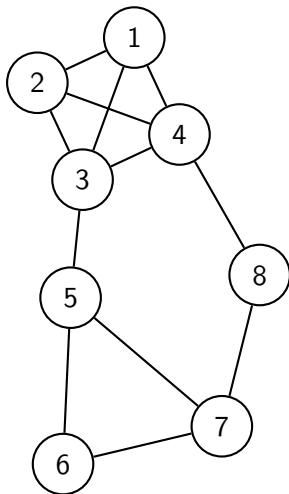
- ① Introduction
- ② Maximum Happy Vertices
- ③ A Heuristic Algorithm using Nice Tree Decompositions
- ④ Future Work

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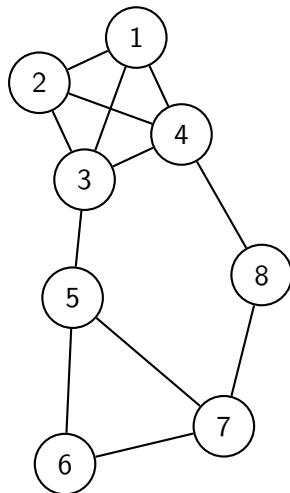
Graph

- A graph $G = (V, E)$
- vertices $V(G)$: 1, 2, 3, ...
 - edges $E(G)$: $\{1, 2\}$, $\{3, 5\}$, $\{7, 8\}$,
...



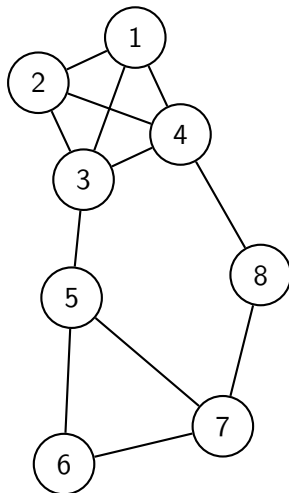
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 - $\deg(3) = 4$, $\deg(8) = 2$
- ▶ For all $v \in V(G)$, $N(v)$ is the set of vertices u such that $uv \in E(G)$
 - $N(3) = \{1, 2, 4, 5\}$, $N(8) = \{4, 7\}$



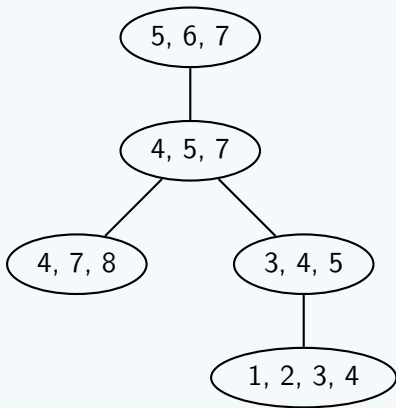
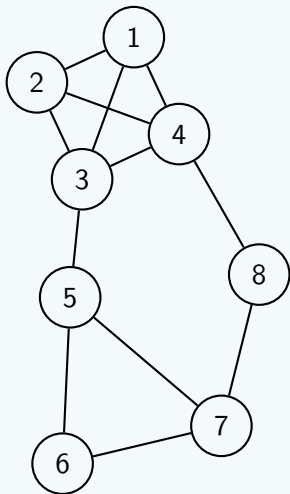
Tree Decomposition

Definition (Tree decomposition Cygan et al. 2015)

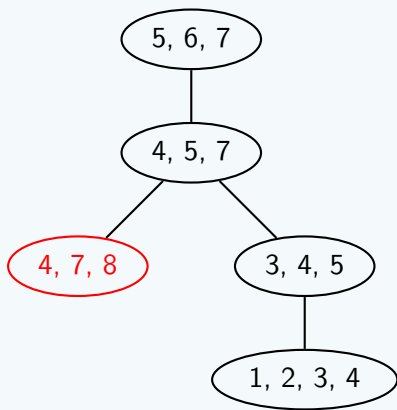
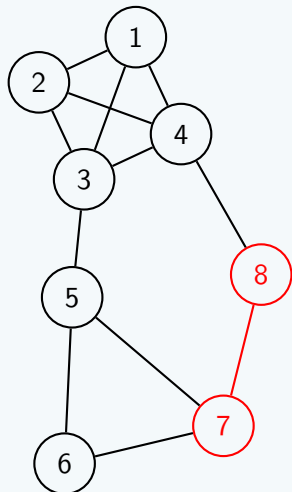
A *tree decomposition* of graph G is a pair $\mathcal{T} = (T, \{X_t\}_{t \in V(T)})$ where T is a tree whose every node t is assigned a vertex subset $X_t \subseteq V(G)$, called a *bag*, such that the following three conditions hold:

- 1 $\bigcup_{t \in V(T)} X_t = V(G)$: every vertex $v \in V(G)$ is contained in some bag X_t for $t \in V(T)$.
- 2 For every $\{u, v\} \in E(G)$, there exists a node t of $V(T)$ such that bag X_t contains both u and v .
- 3 For every $v \in V(G)$, the set $T_v = \{t \in V(T) : v \in X_t\}$ induces a connected subtree of T .

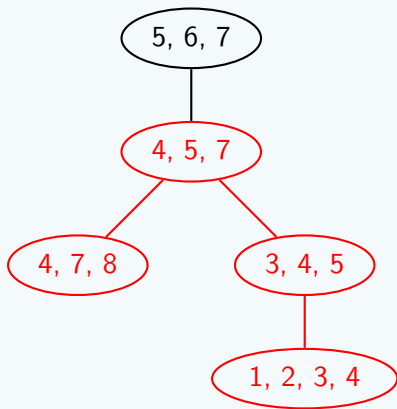
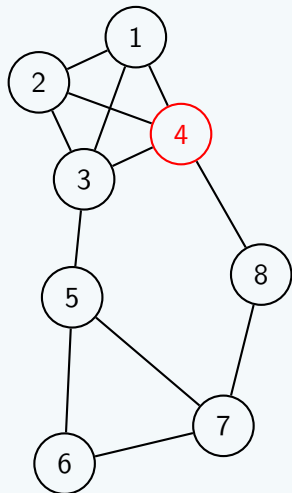
Example (Property 1: $\bigcup_{t \in V(T)} X_t = V(G)$): every vertex $v \in V(G)$ is contained in some bag X_t for $t \in V(T)$)



Example (Property 2: For every $\{u, v\} \in E(G)$, there exists a node t of $V(T)$ such that bag X_t contains both u and v)



Example (Property 3: For every $v \in V(G)$, the set $T_v = \{t \in V(T) : v \in X_t\}$ induces a connected subtree of T)



Treewidth

Definition (Width of a tree decomposition)

The *width of a tree decomposition* $\mathcal{T} = (T, \{X_t\}_{t \in V(T)})$ equals $\max_{t \in V(T)} |X_t| - 1$.

Definition (Treewidth of a graph)

The *treewidth* of a graph G – denoted by $t = tw(G)$ – is the minimum possible width of a tree decomposition of G .

The Treewidth Problem

Theorem (Arnborg, Corneil, and Proskurowski 1987)

Given a graph G and integer t , deciding if G has a treewidth of at most t is \mathcal{NP} -complete.

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 - Exponential time exact algorithms
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 - Heuristics with local search
 - See [Bodlaender 2005](#) for an extensive overview

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 - See [Bodlaender 2005](#) for an extensive overview
- ▶ PACE 2017: [Dell et al. 2018](#)
 - Construct an algorithm to compute tree decompositions
 - See for example [Tamaki 2019](#); [Strasser 2017](#); [Bannach and Berndt 2019](#)

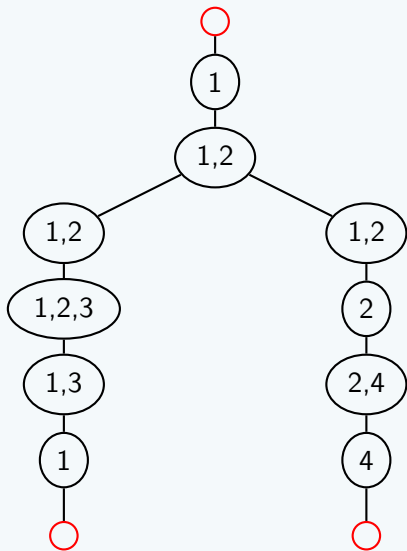
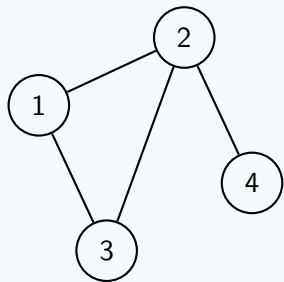
Nice Tree Decomposition

Definition (Nice Tree Decomposition)

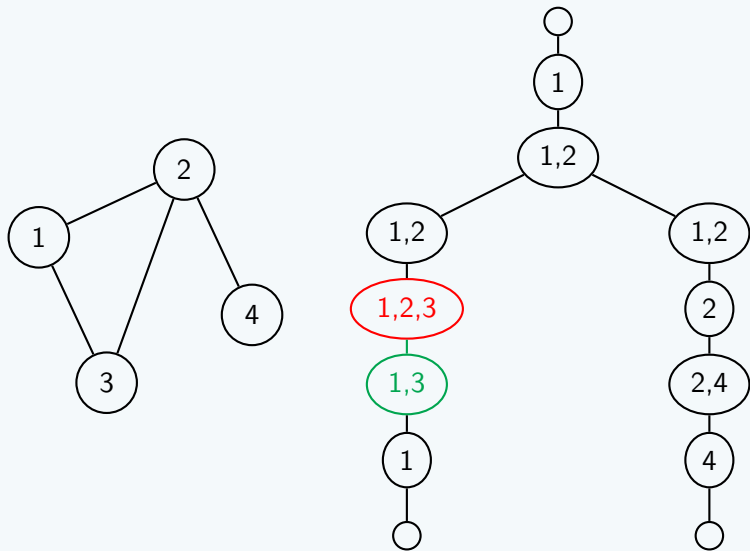
A rooted tree decomposition $\mathcal{T} = (T, \{X_t\}_{t \in V(T)})$ of graph G is *nice* if the following conditions hold:

- ▶ $X_r = \emptyset$ and $X_l = \emptyset$ for every leaf l of $V(T)$.
- ▶ Every non-leaf node of T is one of the following types:
 - 1 Introduce node: a node t with exactly 1 child t' such that $X_t = X_{t'} \cup \{v\}$ for some vertex $v \notin X_{t'}$.
 - 2 Forget node: a node t with exactly 1 child t' such that $X_t = X_{t'} \setminus \{v\}$ for some vertex $v \in X_{t'}$.
 - 3 Join node: a node t with exactly two children t_1, t_2 such that $X_t = X_{t_1} = X_{t_2}$.

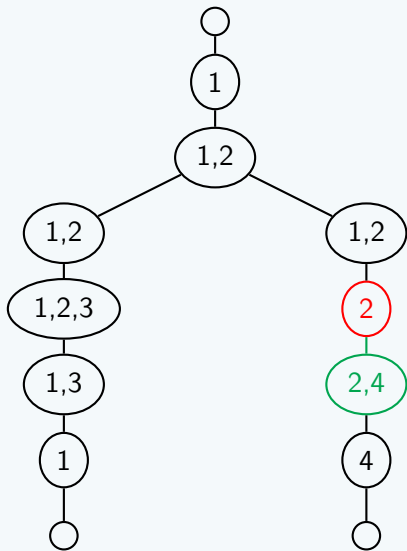
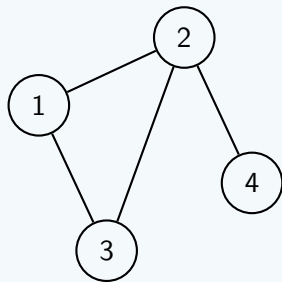
Example (Root and leaves)



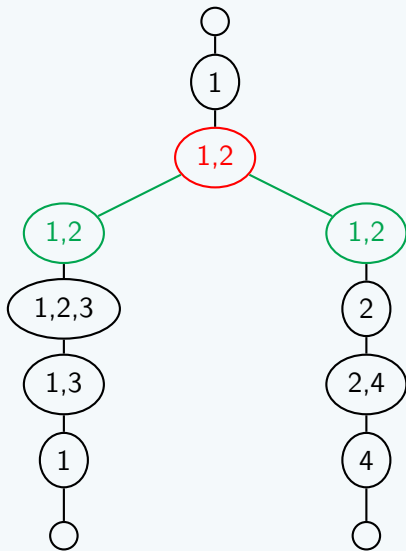
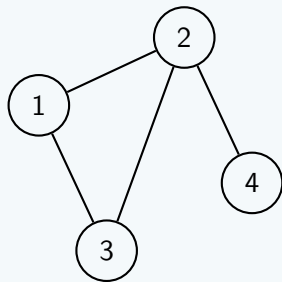
Example (Introduce node)



Example (Forget node)



Example (Join node)



Dynamic Programming using Nice Tree Decompositions

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 Goal of my thesis

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- ① Introduction
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Maximum Happy Vertices Problem (Zhang and Li 2015)

Definition (Happy and Unhappy Vertices)

Given a graph G and a colouring $c : V(G) \rightarrow \{1 \dots k\}$. A vertex $v \in V(G)$ is said to be *happy* if and only if $c(v) = c(v')$ for all vertices $v' \in N(v)$, otherwise vertex v is said to be *unhappy*.

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Definition (Maximum Happy Vertices Problem – MHV)

Given a graph G and a partial colouring $c : V(G) \rightarrow \{1 \dots k\}$. Extend the partial colouring c to a full colouring c' such that the number of happy vertices is maximized.

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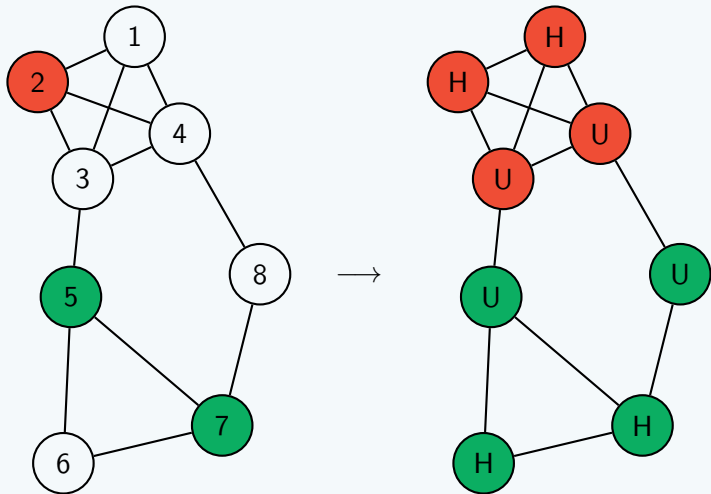
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Definition (k -MHV)

An instance of the MHV problem, in which the number of colours k is a constant.

Example



Applications of Maximum Happy Vertices

- 1 Modeling social networks: *homophily*
 - People tend to be similar to their friends
 - Elements in a small community share remarkable common features
 - The feature values are represented by a colour
 - See [Easley, Kleinberg, et al. 2010](#); [Li and Peng 2011](#); [Li and Peng 2012](#) for more information

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- 2 Clustering
 - The vertices represent data points
 - The edges represent strong connections between the data points
 - The colours represent the different clusters

Complexity of the Maximum Happy Vertices Problem

Theorem (Zhang and Li 2015)

The k -MHV problem is \mathcal{NP} -complete for every constant $k \geq 3$.

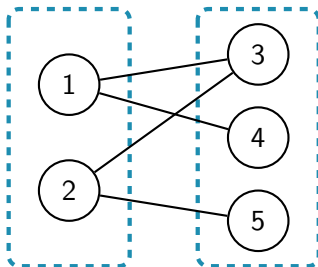
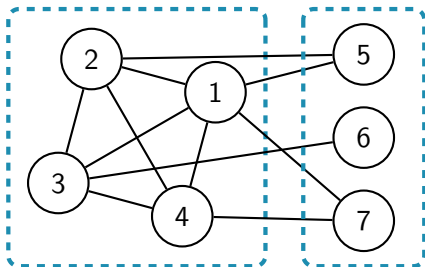
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Theorem (Agrawal 2017)

The MHV problem when parametrized by the number of happy vertices is $\mathcal{W}[1]$ -hard.

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Heuristic Approach

- ▶ What causes the exponential term in the running time?

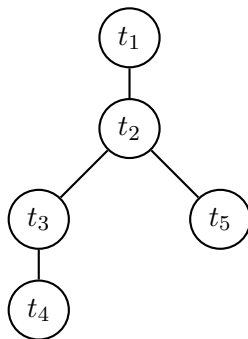
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- ▶ Compute a fixed number of colour functions at each node
- ▶ Colour functions at node t contain information about $X_{t'}$ for all descendants t' of t
 - Descendants of t_3 : $\{t_4\}$
 - Descendants of t_2 : $\{t_3, t_4, t_5\}$



Leaf Nodes

- ▶ Leaf nodes have empty bags
 - ➡ Pass initial colour function to parent



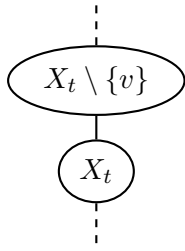
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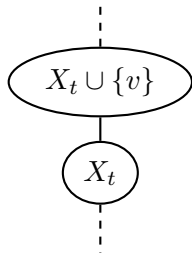
Forget Nodes

- ▶ Vertex v is 'forgotten' from the tree decomposition
- ▶ Sub tree contains the same vertices
 - ➡ Pass colour functions of child to parent



Introduce Nodes

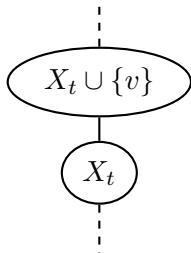
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Two approaches:

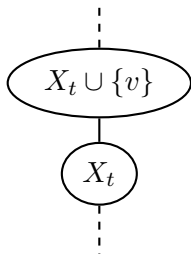


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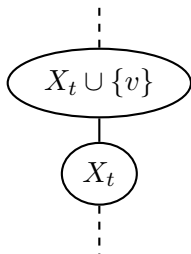


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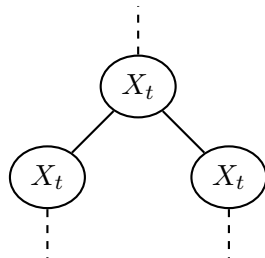
Two approaches:

- 1 For each colour function of child, give v the colour that results in the most happy vertices
- 2 For each colour function of child, give v all the possible colours and select the best colour functions



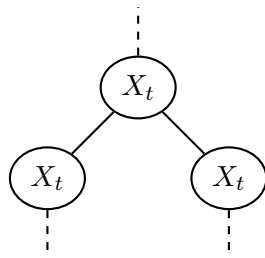
Join Nodes

- ▶ The left and right children pass different colour functions to the join node
- ▶ Merge all colour functions c_l of the left child with all colour functions c_r of the right child
- ▶ Iterate over all vertices $v \in X_t$ and assign it a colour



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Order to iterate over the vertices in X_t ?

- 1 Static: random, greatest degree first, smallest degree first
- 2 Dynamic: vertex connected to most/fewest already coloured vertices, vertex with fewest differently coloured neighbours

Evaluation method

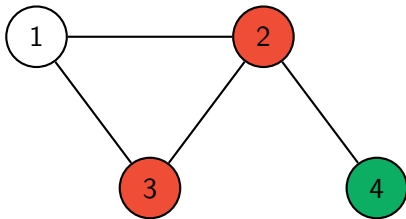
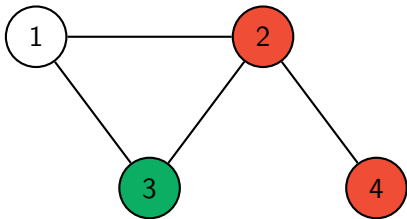
How to decide what the best colour function is?

- 1 Count the number of happy vertices

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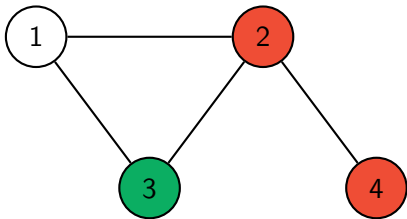
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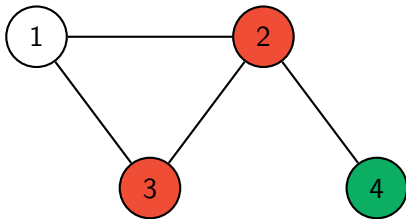
Evaluation method

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vertex 4 is happy, but the other vertices can never be happy

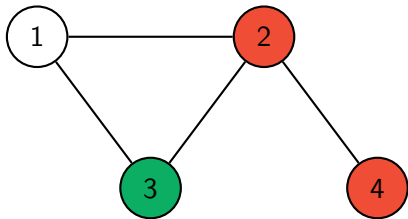


No vertex is happy, but both vertex 1 and 3 are happy if vertex 1 is coloured red

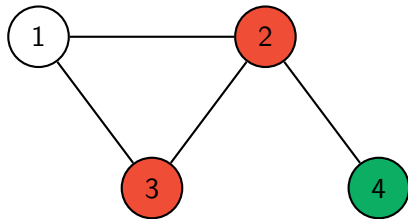
Evaluation method

How to decide what the best colour function is?

- 1 Count the number of happy vertices
- 2 Count the number of happy and potentially happy vertices



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Future Work

Algorithm improvement:

- ▶ Implement more techniques to handle the different types of nodes
- ▶ Apply kernelization on the input graph [H. Gao and W. Gao 2018](#)

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Experimental analysis:


- ▶ Compare algorithm performance against other, existing heuristic algorithms
- ▶ Compare the influence on both solution quality and running time for different tree decompositions
- ▶ Compare the retrieved colouring functions of the heuristic approach and exact algorithm at each node t of the tree decomposition
- ▶ Apply *framework* on other problems

Thank you for your attention!






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