Using SimGrid 101 Getting Started to Use SimGrid

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About this Presentation

Goals and Contents

- ► Installing the framework
- Writing your first MSG simulator (in C, Java or lua)
- Trace replay execution mode
- ▶ Other practical considerations

The SimGrid 101 serie

- ▶ This is part of a serie of presentations introducing various aspects of SimGrid
- ▶ SimGrid 101. Introduction to the SimGrid Scientific Project
- ► SimGrid User 101. Practical introduction to SimGrid and MSG
- ► SimGrid User::Platform 101. Defining platforms and experiments in SimGrid
- ► SimGrid User::SimDag 101. Practical introduction to the use of SimDag
- ► SimGrid User::Visualization 101. Visualization of SimGrid simulation results
- ► SimGrid User::SMPI 101. Simulation MPI applications in practice
- ► SimGrid User::Model-checking 101. Formal Verification of SimGrid programs
- ► SimGrid Internal::Models. The Platform Models underlying SimGrid
- SimGrid Internal::Kernel. Under the Hood of SimGrid
- ▶ Get them from http://simgrid.gforge.inria.fr/documentation.html

Outline

 Installing SimGrid Stable release Unstable Version The Bindings

 Your First SimGrid Program User Interface(s) Master/Workers Trace Replay

 Further topics Configuring your simulators Surviving in C Bindings Performance

Conclusion

Installing a stable version (most advised for users)

On Debian, Ubuntu and similar

- sudo apt-get install simgrid
- ▶ Manual download: http://packages.debian.org/simgrid

On Windows

- ▶ Get the installer: http://simgrid.gforge.inria.fr/download.php
- Execute it and follow the instructions

For Java (regardless of your OS)

- ► Get the binary jarfile: http://simgrid.gforge.inria.fr/download.php
- Add it to your classpath. That's it: C library included for your convenience

From the sources

- 1. Get the archive: http://simgrid.gforge.inria.fr/download.php
- 2. Open, config and build: tar xfz simgrid-*.tar.gz; cmake .; make

Details: http://simgrid.gforge.inria.fr/simgrid/latest/doc/install.html

Installing an unstable version (developers only!)

So you want to keep on the bleeding edge, hu?

Unstable is not for anyone

- Only use it if you want to improve SimGrid
- ▶ Stable releases are frequent enough to use SimGrid
- ▶ Hint: it's called *unstable*. It may harm your kittens even if we do our best

Actually installing unstable

- ▶ git clone git://scm.gforge.inria.fr/simgrid/simgrid.git
- Configure and build source as usual

Additional Build Dependencies

▶ If you change the XML parsers, you need both flexml and flex

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The Bindings

So you don't want to code in C, hu?

Some people don't like coding in C

- C is the modern assembly language: potentially fast but tedious
- ▶ Using C is not enough for maximal performance: you need to really master it

Bindings available

- ▶ Java bindings: Rock stable, very efficient, used by many people
- Lua bindings; Should work, but no community of users (yet)
- Ruby bindings: Used to work but not anymore (dropped)
- Patches to add news bindings are welcome (but uneasy: threading mess)

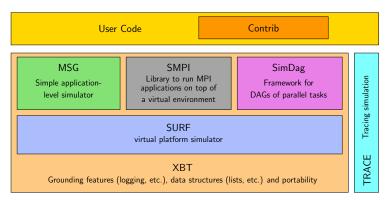
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Outline

- Installing SimGrid
- Your First SimGrid Program User Interface(s) Master/Workers Trace Replay
- Further topics
- Conclusion

Introduction Installing

SimGrid Overview



SimGrid user APIs

- ▶ If your application is a DAG of (parallel) tasks ~ use SimDag
- ► To study an existing MPI code ~> use SMPI
- In any other cases → use MSG (easily study concurrent processes and prototype distributed applications)

The MSG User Interface

Main MSG abstractions

- ▶ Agent: some code, some private data, running on a given host
- ▶ Task: amount of work to do and of data to exchange
- ▶ Host: location on which agents execute
- Mailbox: Rendez-vous points between agents (think of MPI tags)
 - You send stuff to a mailbox; you receive stuff from a mailbox
 - Establish rendez-vous regardless of network location
 - ▶ Mailboxes identified as *strings* ~ host:port, yellow pages or whatever

More information

- examples/msg in archive; Reference doc: doc/group_MSG_API.html
- ▶ Interface extended, never modified since 2002 (if using MSG_USE_DEPRECATED)

Executive Summary (detailed below)

1. Write the Code of your Agents

```
int master(int argc, char **argv) {
for (i = 0: i < number of tasks: i++) {
t=MSG_task_create(name, comp_size, comm_size, data);
 sprintf(mailbox, "worker-%d", i % workers_count);
MSG task send(t. mailbox):}
```

```
int worker(int ,char**){
sprintf(my_mailbox, "worker-%d", my_id);
while(1) {
 MSG_task_receive(&task, my_mailbox);
 MSG task execute(task):
 MSG_task_destroy(task);}
```

2. Describe your Experiment

```
XML Platform File
<?xml version='1.0'?>
<!DOCTYPE platform SYSTEM
"http://simgrid.gforge.inria.fr/simgrid.dtd">
<platform version="3">
<AS id="blah" routing="Full">
  <host id="host1" power="1E8"/>
  <host id="host2" power="1E8"/>
  link id="link1" bandwidth="1E6"
                   latency="1E-2" />
  <route src="host1" dst="host2">
    <link ctn id="link1"/>
  </route>
</AS>
</platform>
```

XML Deployment File

```
<?xml version='1.0'?>
<!DOCTYPE platform SYSTEM
"http://simgrid.gforge.inria.fr/simgrid.dtd">
<platform version="3">
<!-- The master process -->
cprocess host="host1" function="master">
 <argument value="10"/><!--arqv[1]:#tasks-->
 <argument value="1"/><!--argv[2]:#workers-->
</process>
<!-- The workers -->
cprocess host="host2" function="worker">
  <argument value="0"/></process>
</platform>
```

3. Write a main gluing things together, link and run

Master/Workers: Describing the Agents (1/2)

The master has a large number of tasks to dispatch to its workers for execution

```
#include <msg/msg.h> /* mandatory cruft */
XBT_LOG_NEW_DEFAULT_CATEGORY(tuto, "all the info and debug messages of this tutorial");
int master(int argc, char *argv[]) {
 int number_of_tasks = atoi(argv[1]);
                                            double task_comp_size = atof(argv[2]);
 double task comm size = atof(argv[3]):
                                            int workers count = atoi(argv[4]):
 char mailbox[80];
                                            char buff[64];
 int i:
                                            msg_task_t task;
 /* Dispatching (dumb round-robin algorithm) */
 for (i = 0: i < number of tasks: i++) {
   sprintf(buff, "Task %d", i):
  task = MSG_task_create(buff, task_comp_size, task_comm_size, NULL);
   sprintf(mailbox, "worker-%d", i % workers_count);
   XBT_INFO("Sending \"%s\" to mailbox \"%s\"", task->name, mailbox);
   MSG_task_send(task, mailbox);
 /* Send finalization message to workers */
 XBT_INFO("All tasks dispatched. Let's stop workers");
for (i = 0; i < workers_count; i++) {
   sprintf(mailbox, "worker-%ld", i % workers_count);
  MSG task send(MSG task create("finalize", 0, 0, 0), mailbox):
}
XBT_INFO("Goodbye now!"); return 0;
```

Master/Workers: Describing the Agents (2/2)

```
int worker(int argc, char *argv[]) {
 msg_task_t task;
                                  int errcode:
  int id = atoi(argv[1]):
  char mailbox[80];
  sprintf(mailbox, "worker-%d", id);
  while(1) {
   errcode = MSG_task_receive(&task, mailbox);
   xbt assert(errcode == MSG OK, "MSG task get failed"):
   if (!strcmp(MSG_task_get_name(task), "finalize")) {
     MSG_task_destroy(task);
     break;
    }
   XBT_INFO("Processing '%s'", MSG_task_get_name(task));
   MSG_task_execute(task);
   XBT_INFO("'%s' done", MSG task get name(task)):
   MSG_task_destroy(task);
  }
  XBT_INFO("I'm done. See you!");
 return 0:
```

Master/Workers: gluing things together

```
int main(int argc, char *argv[]) {
 MSG_init(&argc,argv);
  /* Declare all existing agent, binding their name to their function */
  MSG_function_register("master", &master);
  MSG_function_register("worker", &worker);
  /* Load a platform instance */
  MSG_create_environment("my_platform.xml"); // we could take the names of XML files as argv
  /* Load a deployment file */
  MSG_launch_application("my_deployment.xml");
  /* Launch the simulation (until its end) */
 MSG_main();
 XBT_INFO("Simulation took %g seconds", MSG_get_clock());
```

Compiling and Executing the result

```
$ gcc *.c -lsimgrid -o my_simulator
$ ./mv_simulator
[verbose output removed]
```

Master/Workers: deployment file

Specifying which agent must be run on which host, and with which arguments

```
XML deployment file
<?xml version="1.0"?>
<!DOCTYPE platform SYSTEM "http://simgrid.gforge.inria.fr/simgrid.dtd">
<platform version="3">
 <!-- The master process (with some arguments) -->
 cprocess host="host1" function="master">
    <argument value="6"/> <!-- Number of tasks -->
    <argument value="50000000"/> <!-- Computation size of tasks -->
    <argument value="1000000"/> <!-- Communication size of tasks -->
    <argument value="3"/> <!-- Number of workers -->
 </process>
 <!-- The worker process (argument: mailbox number to use) -->
 cprocess host="host2" function="worker"><argument value="2"/></process>
</platform>
```

Thanks to mailboxes, the master doesn't have to know where the workers are (nor the contrary)

Master/Worker in Java (1/2)

```
import org.simgrid.msg.*;
public class BasicTask extends org.simgrid.msg.Task {
   public BasicTask(String name, double computeDuration, double messageSize) {
       super(name, computeDuration, messageSize);
public class FinalizeTask extends org.simgrid.msg.Task {
   public FinalizeTask() {
     super("finalize".0.0):
public class Worker extends org.simgrid.msg.Process {
   public Worker (Host host, String name, String[]args) { // Mandatory: this constructor is
     super(host,name,args);
                                                                        used internally
   }
   public void main(String[] args) throws TransferFailureException, HostFailureException,
                                           TimeoutException, TaskCancelledException {
     String id = args[0];
     while (true) {
         Task t = Task.receive("worker-" + id):
         if (t instanceof FinalizeTask)
            break:
         BasicTask task = (BasicTask)t;
         Msg.info("Processing '" + task.getName() + "'");
         task.execute():
         Msg.info("'" + task.getName() + "' done ");
     Msg.info("Received Finalize. I'm done. See you!");
```

Master/Workers in Java (2/2)

```
import org.simgrid.msg.*;
public class Master extends org.simgrid.msg.Process {
   public Master(Host host, String name, String[]args) { // mandatory constructor
     super(host,name,args);
  public void main(String[] args) throws MsgException {
     int numberOfTasks = Integer.valueOf(args[0]).intValue();
     double taskComputeSize = Double.valueOf(args[1]).doubleValue():
     double taskCommunicateSize = Double.valueOf(args[2]).doubleValue();
     int workerCount = Integer.valueOf(args[3]).intValue();
     Msg.info("Got "+ workerCount + " workers and " + numberOfTasks + " tasks.");
     for (int i = 0; i < numberOfTasks; i++) {
        BasicTask task = new BasicTask("Task " + i .taskComputeSize.taskCommunicateSize):
        task.send("worker-" + (i % workerCount));
        Msg.info("Send completed for the task " + task.getName() +
                  " on the mailbox 'worker-" + (i % workerCount) + "'");
     Msg.info("Goodbye now!");
```

The rest of the story

- ▶ No need to write the glue (thanks to Java introspection)
- Same XML files (in deployment, capitalization and package name matters)

Master/Workers in Lua (1/2)

```
function Master(...)
  local nb_task, comp_size, comm_size, slave_count = unpack(arg)
  -- Dispatch the tasks
 for i = 1, nb_task do
   local tk = simgrid.task.new("Task " .. i, comp_size, comm_size)
   local alias = "worker " .. (i % worker_count)
   simgrid.info("Sending '" .. tk:get name() .."' to '" .. alias .."'")
   tk:send(alias)
   simgrid.info("Done sending '".. tk:get_name() .."' to '" .. alias .."'")
  end
  -- Sending finalize message to others
  for i = 0, worker_count - 1 do
   local alias = "worker " .. i:
   simgrid.info("Sending finalize to " .. alias)
   local finalize = simgrid.task.new("finalize", comp size, comm size)
   finalize:send(alias)
  end
end
```

Master/workers in Lua (2/2)

```
The worker
function Worker(...)
 local my_mailbox="worker " .. arg[1]
  while true do
   local tk = simgrid.task.recv(my_mailbox)
   if (tk:get_name() == "finalize") then
     simgrid.info("Got finalize message")
     break
    end
   tk:execute()
  end
  simgrid.info("Worker '" ..my_mailbox.."': I'm done. See you!")
end
Setting up your experiment
require "simgrid"
simgrid.platform("my_platform.xml")
simgrid.application("my_deployment.xml")
simgrid.run()
simgrid.info("Simulation's over. See you.")
```

Master/Workers in Ruby (1/2)

(beware, Ruby bindings "not in very good shape" currently)

```
require 'simgrid'
include MSG
The master
class Master < MSG::Process
  def main(args)
    numberOfTask = Integer(args[0])
     taskComputeSize = Float(args[1])
    taskCommunicationSize = Float(args[2])
    workerCount = Integer(args[3])
    for i in 0..numberOfTask-1
        task = Task.new("Task_"+ i.to_s, taskComputeSize , taskCommunicationSize);
        mailbox = "worker " + (i%workerCount).to_s
        MSG::info("Master Sending "+ task.name + " to " + mailbox)
        task.send(mailbox)
        MSG::info("Master Done Sending " + task.name + " to " + mailbox)
     end
    for i in 0..workerCount-1
        mailbox = "worker " + i.to_s
        finalize task = Task.new("finalize".0.0)
        finalize_task.send(mailbox)
     end
  end
end
```

Master/Workers in Ruby (2/2)

```
The worker
class Worker < MSG::Process
 def main(args)
   mailbox = "worker " + args[0]
   while true
      task = Task.receive(mailbox)
       if (task.name == "finalize")
          break
       end
       task.execute
       MSG::debug("Worker '" + mailbox + "' done executing task "+ task.name + ".")
    end
   MSG::info("I'm done, see you")
  end
end
```

```
Setting up your experiment
MSG.createEnvironment("platform.xml")
MSG.deployApplication("deploy.xml")
MSG, run
puts "Simulation time : " + MSG.getClock .to_s
MSG.exit
```

Trace Replay: Separate your applicative workload

▶ If your application is event-oriented (as a P2P DHT or a scheduling heuristic), you need to get the applicative workload from somewhere

```
C code
```

```
static void action_blah(xbt_dynar_t parameters) { ... }
static void action_blih(xbt_dynar_t parameters) { ... }
int main(int argc, char *argv[]) {
   MSG_init(&argc, argv);
   MSG_create_environment(argv[1]);
   MSG_launch_application(argv[2]);
   /* No need to register functions as usual: actions started anyway */
   xbt_replay_action_register("blah", blah);
   xbt_replay_action_register("blih", blih);
   MSG_action_trace_run(argv[3]); // The trace file to run
}
```

Deployment

```
<?xml version='1.0'?>
<!DOCTYPE platform SYSTEM "http://simgrid.gforge.inria.fr/simgrid.dt
<platform version="3">
  cprocess host="host1" function="toto"/>
  cprocess host="host2" function="tutu"/>
</platform>
```

Trace file

tutu blah toto 1e10 tutu blih 12 toto blih 12

Alternatives for DAG-formated workload: DAX or dot files (see SimDag 101)

Trace Replay (2/2)

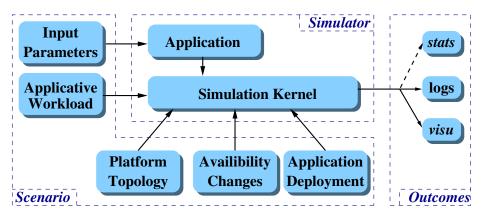
Separating the trace of each process

- ▶ Because it's sometimes more convenient (for MPI, you'd have to merge them)
- Simply pass NULL to MSG_action_trace_run()
- ▶ Pass the trace file to use as argument to each process in deployment

Action Semantic

- ▶ This mecanism is completely agnostic: attach the meaning you want to events
- ▶ In examples/actions/action.c, we have pre-written event functions for:
 - ▶ Basics: send, recv, sleep, compute
 - ► MPI-specific: isend, irecv, wait, barrier, reduce, bcast, allReduce

SimGrid is not a Simulator



That's a Generic Simulation Framework

Configuring your simulators

Every simulator using SimGrid accepts a set of options

- -help: get some help
- -help-models: long help on models
- -log: configure the verbosity
- -cfg: change some settings

Note: SMPI-specific settings, are only visible in SMPI simulators

The log argument

- It's similar to Log4J, but in C
- ▶ You can increase the amount of output for some specific parts of SimGrid
- ► Example: See everything by using -log=root.thres:debug
- ► List of all existing channels: doc/html/group_XBT_log_cats.html

XBT from 10.000 feets

C is a basic language: we reinvented the wheel for you

```
Logging support: Log4C
XBT_LOG_NEW_DEFAULT_CATEGORY(test,
    "mv own little channel"):
XBT_LOG_NEW_SUBCATEGORY(details, test,
    "Another channel"):
INFO("Value: %d", variable);
CDEBUG(details. "blah %d %f %d", x.v.z):
```

```
Exception support ___
xbt_ex_t e;
TRY {
  block
} CATCH(e) {
  block /* DO NOT RETURN FROM THERE */
}
```

Debugging your code

- ► Ctrl-C once: see processes' status
- Press it twice (in 5s): kill simulator

```
xbt_backtrace_display_current() ____
Backtrace (displayed in thread 0x90961c0):
---> In master() at masterslave_mailbox.c:35
---> In ?? ([0x4a69ba5])
```

Advanced data structures

- Hash tables (Perl's ones)
- Dynamic arrays, FIFOs; Graphs

String functions

- bprintf: malloc()ing sprintf
- trim, split, subst, diff
- string buffers

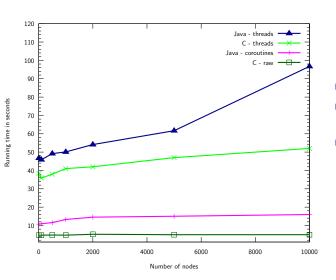
Threading support

- Portable wrappers (Lin, Win, Mac, Sim)
- Synchro (mutex, conds, semaphores)

Other

- Mallocators
- Configuration support
- Unit testing (check src/testall)
- Integration tests (tesh: testing shell)

Bindings Performance



- ► C: breath taking
- Java: not too bad (JVM patch \sim good)
- Others: a bit behind

(version 3.7.1)

More information on using SimGrid

Read more

- ► Tutorials (http://simgrid.gforge.inria.fr/101)
 - ► SimGrid 101. Introduction to the SimGrid Scientific Project
 - SimGrid User 101. Practical introduction to SimGrid and MSG
 - ► SimGrid User::Platform 101. Defining platforms and experiments in SimGrid
 - ► SimGrid User::SimDag 101. Practical introduction to the use of SimDag
 - ▶ SimGrid User: Visualization 101 Visualization of SimGrid simulation results
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 - SimGrid User::Model-checking 101. Formal Verification of SimGrid programs
 - ► SimGrid Internal::Models. The Platform Models underlying SimGrid
 - SimGrid Internal::Kernel, Under the Hood of SimGrid
- Examples for almost all features included in archives
- ► The documentation itself should be ok now [SimGrid v3.9 and higher]

Get in touch

- ▶ Mailing list: mailto:simgrid-user@lists.gforge.inria.fr
- ► IRC: #simgrid on irc.debian.org
- ► Ask your questions on Stack Overflow, and participate to the community
- Report bugs: https://gforge.inria.fr/tracker/?atid=165&group_id=12

Please RTFM because we WTFM

- ▶ The documentation used to be even worse
- Our classical answers to users shouting "Write The Fine Manual" were:

User manuals are for wimps

- ▶ Real Men read some slides 'cause they are more concise
- ▶ They read the examples, pick one modify it to fit their needs
- ▶ They may read 2 or 5% of the reference guide to check the syntax
- ▶ In doubt, they just check the source code

lusers don't read the manual either

- Proof: that's why the RTFM expression were coined out
- Instead, they always ask same questions to lists, and get pointed to the FAQ

But things improved; We still try to help Real Men working the way they like :-)