```
library IEEE;
     use IEEE.std logic 1164.all;
 3
     use IEEE.numeric std.all;
 5
     entity adderTB is
 6
     end entity;
 7
8
     architecture behavior of adderTB is
9
       constant TIME DELAY : time := 20 ns;
10
       constant NUM VALS : integer := 6;
11
12
13
       type A array is array(0 to (NUM VALS - 1)) of std logic vector(15 downto 0);
       type B array is array(0 to (NUM VALS - 1)) of std logic vector(15 downto 0);
14
       type C array is array(0 to (NUM VALS - 1)) of std logic vector(15 downto 0);
15
16
       type mode array is array(0 to (NUM VALS - 1)) of std logic vector(2 downto 0);
       type Zero_array is array(0 to (NUM_VALS - 1)) of std logic;
17
18
       type OE array is array(0 to (NUM VALS - 1)) of std logic;
19
       type Cout array is array(0 to (NUM VALS - 1)) of std logic;
20
21
       -- Expected input and output data.
22
       -- You need to correct and add more values here based on your design
23
       -- TODO: test the following cases (make 10 test cases total):
24
       -- Full Zeros
25
       -- a negative and a positive
26
       -- a negative and a negative
27
       -- a positive and negative that sums to zero
28
       -- overflows in the negative and positive direvtion
29
30
       -- a positive and a positive
31
32
       constant A vals : A array := (B"0000 0000 0000 0000",
                                      B"1000 1000 0000 0000",
33
                                      B"1111 0000 0000 0000",
34
35
                                      B"1111 1111 1111 1111",
                                      B"1000 0000 0000 0000",
36
37
                                      B"0000 0000 0000 1000");
38
39
40
41
       constant B vals : B array := (B"0000 0000 0000 0000",
42
                                      B"0000 0001 0001 0000",
                                      B"1000 0101 0000 0000",
43
                                      B"0000 0000 0000 0001",
44
                                      B"1000 0000 0000 0001",
45
46
                                      B"0000 0000 0000 0010");
47
48
49
50
       constant mode_vals : mode array := (B"000",
51
                                            B"000",
                                            B"000",
52
53
                                            B"000",
54
                                            B"000",
55
                                            B"000");
56
57
       constant Zero vals : Zero array := ('1','0','0', '1', '0', '0');
58
59
       constant OE vals : OE array := ('1','1','1','1', '1', '1');
60
       constant Cout vals : Cout array := ('0','0','0', '0', '1', '0');
61
62
63
       constant C vals : C array := (B"0000 0000 0000 0000",
64
                                      B"1000 1001 0001 0000",
65
                                      B"1111 0101 0000 0000",
                                      B"0000 0000 0000 0000",
66
                                      B"0000 0000 0000 0001",
67
                                      B"0000 0000 0000 1010");
68
69
```

```
70
 71
        signal A sig : std logic vector(15 downto 0);
        signal B sig : std logic vector(15 downto 0);
 72
        signal C sig : std logic vector(15 downto 0);
 73
 74
        signal mode_sig : std_logic_vector(2 downto 0);
 75
        signal Zero_sig : std_logic;
 76
        signal OE sig : std logic;
 77
        signal Cout sig : std logic;
 78
 79
      begin
 80
 81
        DUT : entity work.ALU (behavioral)
 82
          port map(A => A sig,
                   B => B sig,
 83
                    C \Rightarrow C sig,
 84
 85
                   Mode => mode sig,
                    Zero => Zero_sig,
 86
                    OE => OE_sig,
 87
 88
                    Cout => Cout sig);
 89
 90
        stimulus : process
 91
        begin
 92
          for i in 0 to (NUM VALS - 1) loop
 93
            A sig <= A vals(i);
 94
            B sig <= B vals(i);
 95
            --C_sig <= C_vals(i);
 96
            mode sig <= mode vals(i);</pre>
 97
            OE sig <= OE vals(i);
 98
            wait for TIME DELAY;
 99
          end loop;
100
          wait;
101
        end process stimulus;
102
103
        monitor : process
104
          variable i : integer := 0;
105
        begin
          wait for TIME DELAY/4;
106
107
          while (i < NUM VALS) loop</pre>
108
            assert C_sig = C_vals(i)
109
              report "C value is incorrect."
110
              severity error;
111
112
            assert Zero sig = Zero vals(i)
113
              report "Zero value is incorrect."
114
              severity error;
115
116
            wait for TIME DELAY/2;
117
118
            assert Cout sig = Cout vals(i)
119
              report "Cout value is incorrect."
              severity error;
120
121
122
            i := i + 1;
123
            wait for TIME DELAY/2;
124
          end loop;
125
          wait;
126
        end process monitor;
127
128
      end behavior;
129
```