

```

1  library IEEE;
2  use IEEE.std_logic_1164.all;
3  use IEEE.numeric_std.all;
4
5  entity oeTB is
6  end entity;
7
8  architecture behavior of oeTB is
9      constant TIME_DELAY : time := 20 ns;
10     constant NUM_VALS : integer := 2;
11
12
13     type A_array is array(0 to (NUM_VALS - 1)) of std_logic_vector(15 downto 0);
14     type B_array is array(0 to (NUM_VALS - 1)) of std_logic_vector(15 downto 0);
15     type C_array is array(0 to (NUM_VALS - 1)) of std_logic_vector(15 downto 0);
16     type mode_array is array(0 to (NUM_VALS - 1)) of std_logic_vector(2 downto 0);
17     type Zero_array is array(0 to (NUM_VALS - 1)) of std_logic;
18     type OE_array is array(0 to (NUM_VALS - 1)) of std_logic;
19     type Cout_array is array(0 to (NUM_VALS - 1)) of std_logic;
20
21     -- positive and negative
22     -- negative and positive
23     -- two full zeros
24     -- one that results in a zero
25     -- result is odd
26
27     constant A_vals : A_array := (B"0000_0000_0000_0000",
28                                   B"1111_1111_1111_1111");
29
30
31     constant B_vals : B_array := (B"0000_0000_0000_0001",
32                                   B"0000_0000_0000_1000");
33
34
35
36     constant mode_vals : mode_array := (B"000",
37                                          B"000");
38
39     constant Zero_vals : Zero_array := ('0','0');
40
41     constant OE_vals : OE_array := ('1','0');
42
43     constant Cout_vals : Cout_array := ('0','0');
44
45     constant C_vals : C_array := (B"0000_0000_0000_0001",
46                                   "ZZZZZZZZZZZZZZZZZZ");
47
48
49
50     signal A_sig : std_logic_vector(15 downto 0);
51     signal B_sig : std_logic_vector(15 downto 0);
52     signal C_sig : std_logic_vector(15 downto 0);
53     signal mode_sig : std_logic_vector(2 downto 0);
54     signal Zero_sig : std_logic;
55     signal OE_sig : std_logic;
56     signal Cout_sig : std_logic;
57
58 begin
59
60     DUT : entity work.ALU(behavioral)
61         port map(A => A_sig,
62                 B => B_sig,
63                 C => C_sig,
64                 Mode => mode_sig,
65                 Zero => Zero_sig,
66                 OE => OE_sig,
67                 Cout => Cout_sig);
68
69     stimulus : process

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```

70  begin
71      for i in 0 to (NUM_VALS - 1) loop
72          A_sig <= A_vals(i);
73          B_sig <= B_vals(i);
74          --C_sig <= C_vals(i);
75          mode_sig <= mode_vals(i);
76          OE_sig <= OE_vals(i);
77          wait for TIME_DELAY;
78      end loop;
79
80      -- C_sig <= B"0000_0000_0000_0000";
81      -- wait for TIME_DELAY;
82      -- A_sig <= A_vals(0);
83      -- B_sig <= B_vals(0);
84      -- mode_sig <= mode_vals(0);
85      -- OE_sig <= '1';
86      wait;
87  end process stimulus;
88
89  monitor : process
90      variable i : integer := 0;
91  begin
92      wait for TIME_DELAY/4;
93      while (i < NUM_VALS) loop
94          assert C_sig = C_vals(i)
95              report "C value is incorrect."
96              severity error;
97
98          assert Zero_sig = Zero_vals(i)
99              report "Zero value is incorrect."
100             severity error;
101
102          wait for TIME_DELAY/2;
103
104          assert Cout_sig = Cout_vals(i)
105              report "Cout value is incorrect."
106              severity error;
107
108          i := i + 1;
109          wait for TIME_DELAY/2;
110      end loop;
111
112      -- assert C_sig = B"0000_0000_0000_0000";
113      -- report "Cout value is incorrect."
114      -- severity error;
115      -- wait for TIME_DELAY/2;
116
117      -- assert C_sig = C_vals(0);
118      -- report "Cout Value is incorrect."
119      -- severity error;
120
121      wait;
122  end process monitor;
123
124  end behavior;
125

```