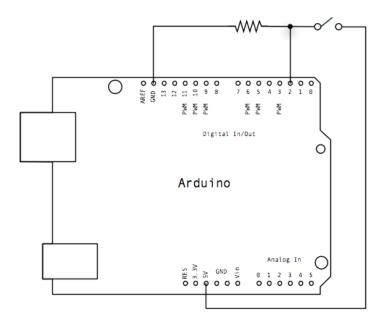
Trigger Switch

1. Basic Button



const int buttonPin = 2; void setup() { Serial.begin(9600); pinMode(buttonPin, INPUT); } void loop() { int buttonState = digitalRead(buttonPin); Serial.println(buttonState); }

2. Get button state

TriggerSwitch

```
const int buttonPin = 2;
bool pressing = false;
void setup() {
Serial.begin(9600);
pinMode(buttonPin, INPUT);
}
void loop() {
  int buttonState = digitalRead(buttonPin);
  if(pressing == false){
    if(buttonState == 1){
      pressing = true;
      Serial.println("Press");
    }
  }else{
    if(buttonState == 0){
      pressing = false;
      Serial.println("Release");
    }
 }
}
```

Fix error from button by add shot delay

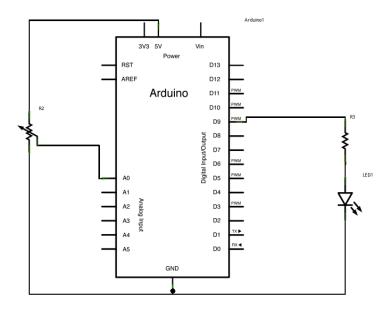
```
void loop() {
  int buttonState = digitalRead(buttonPin);
  if(pressing == false){
    if(buttonState == 1){
      pressing = true;
      Serial.println("Press");
      delay(100);
    }
  }else{
    if(buttonState == 0){
      pressing = false;
      Serial.println("Release");
      delay(100);
    }
  }
}
```

3. Add LED State

```
bool ledState = false;
void loop() {
  int buttonState = digitalRead(buttonPin);
  if(pressing == false){
    if(buttonState == 1){
      pressing = true;
      Serial.println("Press");
      ledState = !ledState;
      delay(100);
    }
  }else{
    if(buttonState == 0){
      pressing = false;
      Serial.println("Release");
      delay(100);
    }
  }
  digitalWrite(ledPin, ledState);
}
```

Down light

Arduino has an analogRead range from 0 to 1023, and an analogWrite range only from 0 to 255



1. analogWrite

```
const int analogOutPin = 9;

void setup() {
   Serial.begin(9600);
   pinMode(analogOutPin, OUTPUT);
}
```

```
void loop() {{
    analogWrite(analogOutPin, 0);
    delay(1000);
    analogWrite(analogOutPin, 85);
    delay(1000);
    analogWrite(analogOutPin, 85);
    delay(1000);
    analogWrite(analogOutPin, 170);
    delay(1000);
    analogWrite(analogOutPin, 255);
    delay(1000);
}
```

2. analogRead

```
const int analogOutPin = 9;
const int analogInput = A0;
int sensorValue = 0;

void setup() {
    Serial.begin(9600);
    pinMode(analogOutPin, OUTPUT);
    pinMode(analogInput, INPUT);
}

void loop() {
    sensorValue = analogRead(analogInput);
    Serial.println(sensorValue);
}
```

3. Mapping value

```
int mapValue = 0;
int myMap(int sensor, int sMin, int sMax, int outMin, int outMax)
  int valuse = 0;
  double deltaIn = sMax - sMin;
  double deltaOut = outMax - outMin;
  double k = deltaOut/deltaIn;
  valuse = (k * sensor) + outMin;
  return valuse;
}
 void loop() {
   sensorValue = analogRead(analogInput);
   mapValue = myMap(sensorValue, 0, 1023, 0, 255);
   Serial.println(mapValue);
 }
```

4. Combine code

```
void loop() {
  sensorValue = analogRead(analogInput);

mapValue = myMap(sensorValue, 0, 1023, 0, 255);
  analogWrite(analogOutPin, mapValue);
  Serial.println(mapValue);
}
```