

# eCMD Perl Module Version Development Reference Manual

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# Chapter 1

## eCMD Perl Module Version Development Main Page

### 1.1 eCMD Perl API

In addition to a C/C++ API, eCMD provides a Perl API. To do this, Perl's DynaLoader module handles the loading of a special eCMD shared object and the Perl XS interface handles the function calls between eCMD C code and Perl.

The API interface is implemented as a "ecmdClientPerlapi" object. The ecmdClientPerlapi class has methods to initialize eCMD, make standard function calls.

### 1.2 Related Information

NOTE : Some of this documentation may look like C/C++ files/headers but that is a side effect of the tool we are using to generate the PerlAPI and documentation. Treat as Perl functions and especially look at any usage information associated with each function description

- **ecmdClientPerlapi.H**(p. 124)
- **ecmdDataBuffer**(p. 24)
- **ecmdStructs.H**(p. 213)
- **ecmdUtils.H**(p. 225)
- **ecmdSharedUtils.H**(p. 208)

#### 1.2.1 Api Extensions

CIP (Cronus/IP) Extension

- **cipClientPerlapi.H**(p. 99)

CMD (Command Line) Extension

- **cmdClientPerlapi.H**(p. 111)

GIP (GFW IP Series) Extension

- **gipClientPerlapi.H**(p. 229)

CRO (Cronus) Extension

- **croClientPerlapi.H**(p. 113)

Z Series Extension

- **zseClientPerlapi.H**(p. 236)

## 1.3 Perl Version

eCMD Scripts need Perl version 5.8.1 which is installed as part of the CTE package on all supported sites. All scripts using the perl module should start with the following:

In an IP Series LAB environment

TBD ...

In a CTE only environment

```
#!/bin/ksh
#! -*- perl -*-
```

```
eval `
if [ "X$CTEPATH" = "X" ]; then echo "CTEPATH env var is not set."; exit 1; fi
export CTEPERLBIN=$CTEPATH/tools/perl/5.8.1/bin/perl;
export CTEPERLPATH=$CTEPATH/tools/perl/5.8.1;
export CTEPERLLIB=$CTEPERLPATH/lib/5.8.1:$CTEPATH/tools/ecmd/$ECMD_RELEASE/perlapi/'uname'/:$CTEPERLLIB;
```

```
exec $CTEPERLBIN -x -S $0 ${1+"$@"}
,
if 0;
```

```
use strict;
use ecmd;
```

```
# Initialize the Plugin - has to be first thing done
# Here we pass in that we know this script supports eCMD Releases 1.x if we know we support more we could pass
if (ecmdLoadDll("", "ver1")) { die "Fatal errors initializing DLL"; }
```

## 1.4 Using eCMD Perl Extensions

If you need functionality from an eCMD Extension that provides the Perl Api, it is initialized like below. This is a 'cip' extension example but all extensions work the same way just replace the prefix with the extension of choice.

```
# Initialize the Plugin - has to be first thing done
if (ecmdLoadDll("", "ver1")) { die "Fatal errors initializing DLL"; }

# Now initialize the extension as well - notice I use the $cp variable that points to my extension
if (cipInitExtension("ver1")) { die "Fatal errors initializing CIP Extension"; }
```

## 1.5 Data Passing

### 1.5.1 ecmdDataBuffer's

Data is passed between the client Perl script and the eCMD shared object in the form of the same **ecmdDataBuffer**(p.24) that is part of the C-API. The function set is the identical. For additional documentation on the **ecmdDataBuffer**(p.24) see the C/C++ Api Documentation.

Here is an example usage of the **ecmdDataBuffer**(p.24):

```
# Create a pointer to an DataBuffer class
my $data = new ecmd::ecmdDataBuffer();

# Set the size of my buffer
$data->$setBitLength(32);

# Set the first word of data in this class
$data->$setWord(0,0xFEEDBEEF);

# Read data from the chip
my $rc = 0;
$rc = getRing($target, "idreg", $data);

# What is in the first word
printf("Data : %.08X",$data->$getWord(0));

#Change the value
$data->$setWord(0,0xAAAA5555);
printf("Data : %.08X",$data->$getWord(0));

# Write my new value to the chip
$rc = putRing($target, "idreg", $data);
```

**WARNING:** The '=' operator DOES NOT work between ecmdDataBuffer's or any other structure like you would expect it to in C. See 'Perl API Usage' below

### 1.5.2 uint64\_t (64 bit data)

Perl doesn't support 64 bit variables, so all 64 bit data is converted to a string.

```
my $addr = "0012a33e884bb338";
putMemProc($target, $addr, $data);
```

## 1.6 Chip/Object targeting

Perl functions use the same `ecmdChipTarget`(p.20) structure as the C-API.

```
my $target = new ecmd::ecmdChipTarget();
$target->${chipType} = "pu";
$target->${cage} = 0;
$target->${node} = 0;
$target->${slot} = 0;
$target->${pos} = 1;
$target->${core} = 0;

$src = putRing($target, "idreg", $data);
```

**WARNING:** The '=' operator DOES NOT work between `ecmdChipTarget`'s or any other structure like you would expect it to in C. See 'Perl API Usage' below

## 1.7 Using Lists

Some eCMD functions return data to Perl in the form of a list of elements. This is the same way this data is handled on the C-API.

Functions available on a Perl list :

<code>\$list-&gt;size()</code>	Returns the number of entries in the list
<code>\$list-&gt;empty()</code>	Returns True/False as to whether the list is empty
<code>\$list-&gt;clear()</code>	Empty the list
<code>\$list-&gt;push_back(\$entry)</code>	Push a new entry onto the back of the list
<code>\$list-&gt;push_front(\$entry)</code>	Push a new entry onto the front of the list
<code>\$entry = \$list-&gt;pop_back()</code>	Pop an entry from the back of the list and return
<code>\$entry = \$list-&gt;pop_front()</code>	Pop an entry from the front of the list and return
<code>\$list-&gt;begin()</code>	Returns an iterator that points to the beginning of list
<code>\$list-&gt;end()</code>	Returns an iterator that points to end of list

Iterators are pointers to a position in the list, they can be used to walk a list and view all elements.

Functions available on a Perl list iterator :



<code>\$entry = \$listIter-&gt;getValue()</code>	Return the entry that this iterator points to
<code>\$listIter-&gt;setValue(\$entry)</code>	Overwrite the value at this position with the new entry
<code>\$listIter++</code>	Increment the iterator to next entry
<code>\$listIter--</code>	Decrement the iterator to previous entry
<code>\$listIter == \$listIter2</code>	Check if two iterators point to the same entry
<code>\$listIter != \$listIter2</code>	Check if two iterators point to different entries
<code>\$listIter-&gt;setIter(\$list-&gt;begin())</code>	Set the iterator pointer to an position in the list
<code>\$listIter2-&gt;setIter(\$listIter-&gt;getIter())</code>	Retrieve the iterator pointer to assign to another iterator

Loading data into a list :

```
my $isteps = new ecmd::listString();
$isteps->$push_back("proc_cfaminit");
$isteps->$push_back("proc_runiap");
$isteps->$push_back("asic_cfaminit");
iStepsByNameMultiple($isteps);
```

Displaying data on a list :

```
my $istepIter = new ecmd::listStringIterator();
while ($istepIter != $isteps->$end()) {
    printf(" name: %s", $istepIter->$getValue());
    $istepIter++;
}
```

## 1.8 Using Vectors

Some eCMD functions return data to Perl in the form of a vector(array) of elements. This is the same way this data is handled on the C-API.

Functions available on a Perl vector :

<code>\$vector-&gt;size()</code>	Returns the number of entries in the vector
<code>\$vector-&gt;empty()</code>	Returns True/False as to wether the vector is empty
<code>\$vector-&gt;clear()</code>	Empty the vector
<code>\$vector-&gt;push_back(\$entry)</code>	Push a new entry onto the back of the vector
<code>\$entry = \$vector-&gt;pop_back()</code>	Pop an entry from the back of the vector and return
<code>\$entry = \$vector-&gt;get(\$index)</code>	Retrieve entry at specified index
<code>\$vector-&gt;set(\$index, \$entry)</code>	Overwrite entry at specified index
<code>\$vector-&gt;begin()</code>	Returns an iterator that points to the beginning of vector
<code>\$vector-&gt;end()</code>	Returns an iterator that points to end of vector

Iterators are pointers to a position in the vector, they can be used to walk a vector and view all elements.

Functions available on a Perl vector iterator :

<code>\$entry = \$vectorIter-&gt;getValue()</code>	Return the entry that this iterator points to
<code>\$vectorIter-&gt;setValue(\$entry)</code>	Overwrite the value at this position with the new entry
<code>\$vectorIter++</code>	Increment the iterator to next entry
<code>\$vectorIter--</code>	Decrement the iterator to previous entry
<code>\$vectorIter == \$vectorIter2</code>	Check if two iterators point to the same entry
<code>\$vectorIter != \$vectorIter2</code>	Check if two iterators point to different entries

Usage of a vector is identical to a list like above.

## 1.9 Perl API Usage

The following should be observed when using the Perl API.

1. The **ecmdLoadDll()**(p.137) function should ALWAYS be the first function called.
2. The **ecmdUnloadDll()**(p.138) function should be called just before script exit
3. Perl should be picked up as shown in the example below to grab the eCMD supported version

### 1.9.1 The '=' operator

**WARNING:** Because of the behavior of Perl the following statements results in two variables pointing to the same data:

```
my $data1 = new ecmd::ecmdDataBuffer();
$data1.setBitLength(32);
$data1.setWord(0,0xFEEDBEEF);

# Use the = operator
my $data2 = $data1;

printf("Data 1 : %.08X", $data1.getWord(0));      # This will echo 'Data 1 : FEEDBEEF'
printf("Data 2 : %.08X", $data2.getWord(0));      # This will echo 'Data 2 : FEEDBEEF'

# Now just set Data 2
$data2.setWord(0,0xAAAA5555);

printf("Data 1 : %.08X", $data1.getWord(0));      # This will echo 'Data 1 : AAAA5555'
printf("Data 2 : %.08X", $data2.getWord(0));      # This will echo 'Data 2 : AAAA5555'
```

NOTE : Since both \$data1 and \$data2 point to the same memory space when one is modified they are both modified. This behavior is the same for the **ecmdDataBuffer**(p.24) and all eCMD structures found in **ecmdStructs.H**(p.213)

## 1.10 Example Perl Script

Please see the eCMD web page under 'Use eCMD' for an example Perl script at : <http://rhea.rchland.ibm.com/eCMD/>

## Chapter 2

# eCMD Perl Module Version Development Hierarchical Index

### 2.1 eCMD Perl Module Version Development Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

ecmdArrayData . . . . .	13
ecmdArrayEntry . . . . .	15
ecmdCageData . . . . .	16
ecmdChipData . . . . .	17
ecmdChipTarget . . . . .	20
ecmdCoreData . . . . .	23
ecmdDataBuffer . . . . .	24
ecmdOptimizableDataBuffer . . . . .	84
ecmdDataBufferImplementationHelper . . . . .	68
ecmdDllInfo . . . . .	69
ecmdIndexEntry . . . . .	71
ecmdIndexVectorEntry . . . . .	72
ecmdLatchData . . . . .	73
ecmdLatchEntry . . . . .	75
ecmdLooperData . . . . .	77
ecmdMemoryEntry . . . . .	80
ecmdNameEntry . . . . .	81
ecmdNameVectorEntry . . . . .	82
ecmdNodeData . . . . .	83
ecmdProcRegisterInfo . . . . .	85
ecmdQueryData . . . . .	86
ecmdRingData . . . . .	87
ecmdScomData . . . . .	89
ecmdSimModelInfo . . . . .	90
ecmdSlotData . . . . .	91
ecmdSpyData . . . . .	92
ecmdSpyGroupData . . . . .	94
ecmdThreadData . . . . .	95
ecmdTraceArrayData . . . . .	96



## Chapter 3

# eCMD Perl Module Version Development Class Index

### 3.1 eCMD Perl Module Version Development Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

<b>ecmdArrayData</b> (Used for the ecmdQueryArray function to return array info ) . . . .	13
<b>ecmdArrayEntry</b> (Used by the getArrayMultiple function to pass data ) . . . . .	15
<b>ecmdCageData</b> (Used for the ecmdQueryConfig function to return cage data ) . . . .	16
<b>ecmdChipData</b> (Used for the ecmdQueryConfig function to return chip data ) . . . .	17
<b>ecmdChipTarget</b> (Structure used to designate which cec object/chip you would like the function to operate on ) . . . . .	20
<b>ecmdCoreData</b> (Used for the ecmdQueryConfig function to return core data ) . . . .	23
<b>ecmdDataBuffer</b> (Provides a means to handle data from the eCMD C API ) . . . . .	24
<b>ecmdDataBufferImplementationHelper</b> (This is used to help low-level implemen- tation of the <b>ecmdDataBuffer</b> (p.24), this CAN NOT be used by any eCMD client or data corruption will occur ) . . . . .	68
<b>ecmdDllInfo</b> (This is used by ecmdQueryDllInfo to return info to the client about what Dll instance they are actually running with ) . . . . .	69
<b>ecmdIndexEntry</b> (Used by get/put Gpr/Fpr Multiple function to pass data ) . . . . .	71
<b>ecmdIndexVectorEntry</b> (Used by ??? function to pass data ) . . . . .	72
<b>ecmdLatchData</b> (Used for the ecmdQueryLatch function to return latch info ) . . . .	73
<b>ecmdLatchEntry</b> (Used by getlatch function to return data ) . . . . .	75
<b>ecmdLooperData</b> (Used internally by ecmdConfigLooper to store looping state infor- mation ) . . . . .	77
<b>ecmdMemoryEntry</b> (Used by ecmdReadDcard ) . . . . .	80
<b>ecmdNameEntry</b> (Used by get/putSprMultiple function to pass data ) . . . . .	81
<b>ecmdNameVectorEntry</b> (Used by getTraceArrayMultiple function to pass data ) . .	82
<b>ecmdNodeData</b> (Used for the ecmdQueryConfig function to return node data ) . . . .	83
<b>ecmdOptimizableDataBuffer</b> . . . . .	84
<b>ecmdProcRegisterInfo</b> (Used by ecmdQueryProcRegisterInfo function to return data about a Architected register ) . . . . .	85
<b>ecmdQueryData</b> (Used by the ecmdQueryConfig function to return data ) . . . . .	86
<b>ecmdRingData</b> (Used for the ecmdQueryRing function to return ring info ) . . . . .	87
<b>ecmdScomData</b> (Used for the ecmdQueryScom function to return scom info ) . . . . .	89
<b>ecmdSimModelInfo</b> (Used by simGetModelInfo ) . . . . .	90
<b>ecmdSlotData</b> (Used for the ecmdQueryConfig function to return slot data ) . . . . .	91

<b>ecmdSpyData</b> (Used for the ecmdQuerySpy function to return spy info ) . . . . .	92
<b>ecmdSpyGroupData</b> (Used by get/puts Spy function to create the return data from a group ) . . . . .	94
<b>ecmdThreadData</b> (Used for the ecmdQueryConfig function to return thread data ) .	95
<b>ecmdTraceArrayData</b> (Used for the ecmdQueryTraceArray function to return trace array info ) . . . . .	96

## Chapter 4

# eCMD Perl Module Version Development File Index

### 4.1 eCMD Perl Module Version Development File List

Here is a list of all files with brief descriptions:

<b>cipClientPerlapi.H</b> (Cronus & IP eCMD Perlapi Extension ) . . . . .	99
<b>cmdClientPerlapi.H</b> (Command Line eCMD Perlapi Extension ) . . . . .	111
<b>croClientPerlapi.H</b> (Cronus eCMD Perlapi Extension ) . . . . .	113
<b>ecmdClientPerlapi.H</b> (ECMD Perl API Usage : ) . . . . .	124
<b>ecmdDataBuffer.H</b> (Provides a means to handle data from the eCMD C API ) . . . .	202
<b>ecmdSharedUtils.H</b> (Useful functions for use throughout the ecmd C API and Plugin )	208
<b>ecmdStructs.H</b> (All the Structures required for the eCMD Capi ) . . . . .	213
<b>ecmdUtils.H</b> (Useful functions for use throughout the ecmd C API ) . . . . .	225
<b>gipClientPerlapi.H</b> (IP eCMD Perlapi Extension ) . . . . .	229
<b>zseClientPerlapi.H</b> (Z Series Perlapi Extension ) . . . . .	236





## Chapter 5

# eCMD Perl Module Version Development Class Documentation

### 5.1 ecmdArrayData Struct Reference

Used for the ecmdQueryArray function to return array info.

```
#include <ecmdStructs.H>
```

#### Public Attributes

- **std::string arrayName**  
*(Detail: Low) Names used to reference this array*
- **int readAddressLength**  
*(Detail: Low) Bit length of read address*
- **int writeAddressLength**  
*(Detail: Low) Bit length of write address*
- **int length**  
*(Detail: Low) Length of array (number of entries)*
- **int width**  
*(Detail: Low) Bit width of array entry*
- **bool isCoreRelated**  
*(Detail: Low) This array is related to the core level of a chip*
- **std::string clockDomain**  
*(Detail: High) Clock domain this array belongs to*
- **ecmdClockState\_t clockState**  
*(Detail: High) Required clock state to access this array*

### 5.1.1 Detailed Description

Used for the `ecmdQueryArray` function to return array info.

### 5.1.2 Member Data Documentation

#### 5.1.2.1 `std::string ecmdArrayData::arrayName`

(Detail: Low) Names used to reference this array

#### 5.1.2.2 `int ecmdArrayData::readAddressLength`

(Detail: Low) Bit length of read address

#### 5.1.2.3 `int ecmdArrayData::writeAddressLength`

(Detail: Low) Bit length of write address

#### 5.1.2.4 `int ecmdArrayData::length`

(Detail: Low) Length of array (number of entries)

#### 5.1.2.5 `int ecmdArrayData::width`

(Detail: Low) Bit width of array entry

#### 5.1.2.6 `bool ecmdArrayData::isCoreRelated`

(Detail: Low) This array is related to the core level of a chip

#### 5.1.2.7 `std::string ecmdArrayData::clockDomain`

(Detail: High) Clock domain this array belongs to

#### 5.1.2.8 `ecmdClockState_t ecmdArrayData::clockState`

(Detail: High) Required clock state to access this array

The documentation for this struct was generated from the following file:

- `ecmdStructs.H`

## 5.2 ecmdArrayEntry Struct Reference

Used by the `getArrayMultiple` function to pass data.

```
#include <ecmdStructs.H>
```

### Public Attributes

- **ecmdDataBuffer address**  
*Array address/element to access.*
- **ecmdDataBuffer buffer**  
*Array data from address.*
- **uint32\_t rc**  
*Error code in retrieving this entry.*

### 5.2.1 Detailed Description

Used by the `getArrayMultiple` function to pass data.

### 5.2.2 Member Data Documentation

#### 5.2.2.1 ecmdDataBuffer ecmdArrayEntry::address

Array address/element to access.

#### 5.2.2.2 ecmdDataBuffer ecmdArrayEntry::buffer

Array data from address.

#### 5.2.2.3 uint32\_t ecmdArrayEntry::rc

Error code in retrieving this entry.

The documentation for this struct was generated from the following file:

- **ecmdStructs.H**

## 5.3 ecmdCageData Struct Reference

Used for the ecmdQueryConfig function to return cage data.

`#include <ecmdStructs.H>`

### Public Attributes

- **uint32\_t cageId**  
*(Detail: Low) Cage number of this entry*
- **uint32\_t unitId**  
*(Detail: High) Unit Id of this entry*
- **std::list< ecmdNodeData > nodeData**  
*(Detail: Low) List of all nodes requested in this cage - in numerical order by nodeId*

### 5.3.1 Detailed Description

Used for the ecmdQueryConfig function to return cage data.

Operators Supported : <

### 5.3.2 Member Data Documentation

#### 5.3.2.1 uint32\_t ecmdCageData::cageId

(Detail: Low) Cage number of this entry

#### 5.3.2.2 uint32\_t ecmdCageData::unitId

(Detail: High) Unit Id of this entry

#### 5.3.2.3 std::list<ecmdNodeData> ecmdCageData::nodeData

(Detail: Low) List of all nodes requested in this cage - in numerical order by nodeId

The documentation for this struct was generated from the following file:

- **ecmdStructs.H**

## 5.4 ecmdChipData Struct Reference

Used for the ecmdQueryConfig function to return chip data.

```
#include <ecmdStructs.H>
```

### Public Attributes

- **std::string chipType**  
(Detail: Low) Full name of chip , ie. p6, enterprise, corona
- **std::string chipShortType**  
(Detail: Low) Short name of chip, ie. p6, ent, cor (should be 3chars or less)
- **std::string chipCommonType**  
(Detail: Low) common name of chip, ie. pu, iohub, l3cache
- **uint32\_t pos**  
(Detail: Low) Position of this entry
- **uint32\_t unitId**  
(Detail: High) Unit Id of this entry
- **uint8\_t numProcCores**  
(Detail: Low) Number of cores this entry supports - only valid for Processor compute cores
- **uint32\_t chipEc**  
(Detail: High) EC level of this chip, (ec read from 'jtag' chip id or CFAM id)
- **uint32\_t simModelEc**  
(Detail: High) Model EC level of this chip
- **ecmdChipInterfaceType\_t interfaceType**  
(Detail: High) Interface Macro used by the chip
- **uint32\_t chipFlags**  
(Detail: High) Various additional info about the chip - bitmask of defines
- **std::list< ecmdCoreData > coreData**  
(Detail: Low) List of all cores requested in this chip - only valid for Processor compute cores - in numerical order by coreId

### 5.4.1 Detailed Description

Used for the ecmdQueryConfig function to return chip data.

Operators Supported : <

## 5.4.2 Member Data Documentation

### 5.4.2.1 `std::string ecmdChipData::chipType`

(Detail: Low) Full name of chip , ie. p6, enterprise, corona

### 5.4.2.2 `std::string ecmdChipData::chipShortType`

(Detail: Low) Short name of chip, ie. p6, ent, cor (should be 3chars or less)

### 5.4.2.3 `std::string ecmdChipData::chipCommonType`

(Detail: Low) common name of chip, ie. pu, iohub, l3cache

### 5.4.2.4 `uint32_t ecmdChipData::pos`

(Detail: Low) Position of this entry

### 5.4.2.5 `uint32_t ecmdChipData::unitId`

(Detail: High) Unit Id of this entry

### 5.4.2.6 `uint8_t ecmdChipData::numProcCores`

(Detail: Low) Number of cores this entry supports - only valid for Processor compute cores

### 5.4.2.7 `uint32_t ecmdChipData::chipEc`

(Detail: High) EC level of this chip, (ec read from 'jtag' chip id or CFAM id)

### 5.4.2.8 `uint32_t ecmdChipData::simModelEc`

(Detail: High) Model EC level of this chip

### 5.4.2.9 `ecmdChipInterfaceType_t ecmdChipData::interfaceType`

(Detail: High) Interface Macro used by the chip

### 5.4.2.10 `uint32_t ecmdChipData::chipFlags`

(Detail: High) Various additional info about the chip - bitmask of defines

### 5.4.2.11 `std::list<ecmdCoreData> ecmdChipData::coreData`

(Detail: Low) List of all cores requested in this chip - only valid for Processor compute cores - in numerical order by coreId

The documentation for this struct was generated from the following file:

- `ecmdStructs.H`

## 5.5 ecmdChipTarget Struct Reference

Structure used to designate which cec object/chip you would like the function to operate on.

```
#include <ecmdStructs.H>
```

### Public Attributes

- **uint32\_t cage**  
*cage that contains node with chip*
- **uint32\_t node**  
*node that contains chip*
- **uint32\_t slot**  
*Card Slot/Fru to target.*
- **std::string chipType**  
*name of chip to access , either actual or common name*
- **uint32\_t pos**  
*position of chip within node*
- **uint8\_t core**  
*which core on chip to access, if chip is multi-core*
- **uint8\_t thread**  
*which thread on chip to access, if chip is multi-threaded*
- **uint32\_t unitId**  
*This is an optional field if unitid's are used to specify the target, the above info still needs to be filled in.*
- **ecmdChipTargetState\_t cageState**  
*cage field state*
- **ecmdChipTargetState\_t nodeState**  
*node field state*
- **ecmdChipTargetState\_t slotState**  
*slot field state*
- **ecmdChipTargetState\_t chipTypeState**  
*chipType field state*
- **ecmdChipTargetState\_t posState**  
*pos field state*
- **ecmdChipTargetState\_t coreState**  
*core field state*



- **ecmdChipTargetState\_\_t threadState**

*thread field state*

- **ecmdChipTargetState\_\_t unitIdState**

*unitId field state*

### 5.5.1 Detailed Description

Structure used to designate which cec object/chip you would like the function to operate on.

- The state bits are used by D/A functions to tell the calling function what level of granularity the function operates on Ex. putmem/getmem display memory through the processor, they are only dependent on cage/node/pos because they do not use the cores to perform their function However put/getspr display architected registers from the processor, they will signify that cage/node/pos/core and depending on the particular spr referenced threads may be valid
- The state bits are used slightly differently for the queryFunctions they are used there to signify what data coming in is valid to refine a query

### 5.5.2 Member Data Documentation

#### 5.5.2.1 uint32\_\_t ecmdChipTarget::cage

cage that contains node with chip

#### 5.5.2.2 uint32\_\_t ecmdChipTarget::node

node that contains chip

#### 5.5.2.3 uint32\_\_t ecmdChipTarget::slot

Card Slot/Fru to target.

#### 5.5.2.4 std::string ecmdChipTarget::chipType

name of chip to access , either actual or common name

#### 5.5.2.5 uint32\_\_t ecmdChipTarget::pos

position of chip within node

#### 5.5.2.6 uint8\_\_t ecmdChipTarget::core

which core on chip to access, if chip is multi-core

**5.5.2.7    uint8\_t ecmdChipTarget::thread**

which thread on chip to access, if chip is multi-threaded

**5.5.2.8    uint32\_t ecmdChipTarget::unitId**

This is an optional field if unitid's are used to specify the target, the above info still needs to be filled in.

**5.5.2.9    ecmdChipTargetState\_t ecmdChipTarget::cageState**

cage field state

**5.5.2.10   ecmdChipTargetState\_t ecmdChipTarget::nodeState**

node field state

**5.5.2.11   ecmdChipTargetState\_t ecmdChipTarget::slotState**

slot field state

**5.5.2.12   ecmdChipTargetState\_t ecmdChipTarget::chipTypeState**

chipType field state

**5.5.2.13   ecmdChipTargetState\_t ecmdChipTarget::posState**

pos field state

**5.5.2.14   ecmdChipTargetState\_t ecmdChipTarget::coreState**

core field state

**5.5.2.15   ecmdChipTargetState\_t ecmdChipTarget::threadState**

thread field state

**5.5.2.16   ecmdChipTargetState\_t ecmdChipTarget::unitIdState**

unitId field state

The documentation for this struct was generated from the following file:

- **ecmdStructs.H**

## 5.6 ecmdCoreData Struct Reference

Used for the ecmdQueryConfig function to return core data.

```
#include <ecmdStructs.H>
```

### Public Attributes

- **uint8\_t coreId**  
*(Detail: Low) core number of this entry*
- **uint8\_t numProcThreads**  
*(Detail: Low) Number of threads per core this entry supports - only valid for Processors*
- **uint32\_t unitId**  
*(Detail: High) Unit Id of this entry*
- **std::list< ecmdThreadData > threadData**  
*(Detail: Low) List of all threads available for this chip - only valid for Processor compute cores - in numerical order*

### 5.6.1 Detailed Description

Used for the ecmdQueryConfig function to return core data.

Operators Supported : <

### 5.6.2 Member Data Documentation

#### 5.6.2.1 uint8\_t ecmdCoreData::coreId

(Detail: Low) core number of this entry

#### 5.6.2.2 uint8\_t ecmdCoreData::numProcThreads

(Detail: Low) Number of threads per core this entry supports - only valid for Processors

#### 5.6.2.3 uint32\_t ecmdCoreData::unitId

(Detail: High) Unit Id of this entry

#### 5.6.2.4 std::list<ecmdThreadData> ecmdCoreData::threadData

(Detail: Low) List of all threads available for this chip - only valid for Processor compute cores - in numerical order

The documentation for this struct was generated from the following file:

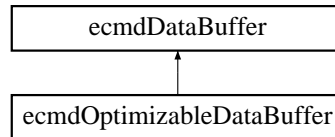
- **ecmdStructs.H**

## 5.7 ecmdDataBuffer Class Reference

Provides a means to handle data from the eCMD C API.

```
#include <ecmdDataBuffer.H>
```

Inheritance diagram for ecmdDataBuffer::



### Public Member Functions

#### ecmdDataBuffer Constructors

- **ecmdDataBuffer** ()  
*Default Constructor.*
- **ecmdDataBuffer** (uint32\_t i\_numBits)  
*Constructor.*
- **ecmdDataBuffer** (const **ecmdDataBuffer** &other)  
*Copy Constructor.*
- virtual **~ecmdDataBuffer** ()  
*Default Destructor.*

#### Buffer Size Functions

- uint32\_t **clear** ()  
*Called by the destructor, available to user to reset buffer to default constructor state.*
- uint32\_t **getWordLength** () const  
*Return the length of the buffer in words.*
- uint32\_t **getByteLength** () const  
*Return the length of the buffer in bytes.*
- uint32\_t **getBitLength** () const  
*Return the length of the buffer in bits.*
- uint32\_t **getCapacity** () const  
*Return the actual capacity of the internal buffer in words.*
- uint32\_t **setWordLength** (uint32\_t i\_newNumWords)  
*Reinitialize the Buffer to specified length.*
- uint32\_t **setByteLength** (uint32\_t i\_newNumBytes)  
*Reinitialize the Buffer to specified length.*

- `uint32_t setBitLength (uint32_t i_newNumBits)`  
*Reinitialize the Buffer to specified length.*
- `uint32_t setCapacity (uint32_t i_newNumWords)`  
*Reinitialize the internal buffer to specified length.*
- `uint32_t shrinkBitLength (uint32_t i_newNumBits)`  
*Shrink buffer size to a new bit size.*
- `uint32_t growBitLength (uint32_t i_newNumBits)`  
*Expand buffer size to a new bit size maintaining current data.*
- `virtual bool isBufferOptimizable (void)`  
*Returns value of iv\_BufferOptimizable.*

### Bit/Word Manipulation Functions

- `uint32_t setBit (uint32_t i_bit)`  
*Turn on a bit in buffer.*
- `uint32_t setBit (uint32_t i_bit, uint32_t i_len)`  
*Turn on a bit in buffer.*
- `uint32_t writeBit (uint32_t i_bit, uint32_t i_value)`  
*Write a bit to specified value in buffer.*
- `uint32_t setWord (uint32_t i_wordoffset, uint32_t i_value)`  
*Set a word of data in buffer.*
- `uint32_t getWord (uint32_t i_wordoffset) const`  
*Fetch a word from ecmdDataBuffer.*
- `uint32_t setByte (uint32_t i_byteoffset, uint8_t i_value)`  
*Set a byte of data in buffer.*
- `uint8_t getByte (uint32_t i_byteoffset) const`  
*Fetch a byte from ecmdDataBuffer.*
- `uint32_t setHalfWord (uint32_t i_halfwordoffset, uint16_t i_value)`  
*Set a halfword of data in buffer.*
- `uint16_t getHalfWord (uint32_t i_halfwordoffset) const`  
*Fetch a halfword from ecmdDataBuffer.*
- `uint32_t setDoubleWord (uint32_t i_doublewordoffset, uint64_t i_value)`  
*Set a doubleword of data in buffer.*
- `uint64_t getDoubleWord (uint32_t i_doublewordoffset) const`  
*Fetch a doubleword from ecmdDataBuffer.*
- `uint32_t clearBit (uint32_t i_bit)`  
*Clear a bit in buffer.*
- `uint32_t clearBit (uint32_t i_bit, uint32_t i_len)`

*Clear multiple bits in buffer.*

- `uint32_t flipBit (uint32_t i_bit)`  
*Invert bit.*
- `uint32_t flipBit (uint32_t i_bit, uint32_t i_len)`  
*Invert multiple bits.*
- `bool isBitSet (uint32_t i_bit) const`  
*Test if bit is set.*
- `bool isBitSet (uint32_t i_bit, uint32_t i_len) const`  
*Test if multiple bits are set.*
- `bool isBitClear (uint32_t i_bit) const`  
*Test if bit is clear.*
- `bool isBitClear (uint32_t i_bit, uint32_t i_len) const`  
*Test if multiple bits are clear.*
- `uint32_t getNumBitsSet (uint32_t i_bit, uint32_t i_len) const`  
*Count number of bits set in a range.*

### Buffer Manipulation Functions

- `uint32_t shiftRight (uint32_t i_shiftnum)`  
*Shift data to right.*
- `uint32_t shiftLeft (uint32_t i_shiftnum)`  
*Shift data to left.*
- `uint32_t shiftRightAndResize (uint32_t i_shiftnum)`  
*Shift data to right - resizing buffer.*
- `uint32_t shiftLeftAndResize (uint32_t i_shiftnum)`  
*Shift data to left - resizing buffer.*
- `uint32_t rotateRight (uint32_t i_rotatenum)`  
*Rotate data to right.*
- `uint32_t rotateLeft (uint32_t i_rotatenum)`  
*Rotate data to left.*
- `uint32_t flushTo0 ()`  
*Clear entire buffer to 0's.*
- `uint32_t flushTo1 ()`  
*Set entire buffer to 1's.*
- `uint32_t invert ()`  
*Invert entire buffer.*
- `uint32_t reverse ()`  
*Bit reverse entire buffer.*

- `uint32_t applyInversionMask (const uint32_t *i_invMask, uint32_t i_invByteLen)`  
*Apply an inversion mask to data inside buffer.*
- `uint32_t applyInversionMask (const ecmdDataBuffer &i_invMaskBuffer, uint32_t i_invByteLen)`  
*Apply an inversion mask to data inside buffer Just a wrapper that takes in a ecmdDataBuffer and calls uint32\_t applyInversionMask.*
- `uint32_t insert (const ecmdDataBuffer &i_bufferIn, uint32_t i_targetStart, uint32_t i_len, uint32_t i_sourceStart=0)`  
*Copy part of another DataBuffer into this one.*
- `uint32_t insert (const uint32_t *i_datain, uint32_t i_targetStart, uint32_t i_len, uint32_t i_sourceStart=0)`  
*Copy part of a uint32\_t array into this DataBuffer.*
- `uint32_t insert (uint32_t i_datain, uint32_t i_targetStart, uint32_t i_len, uint32_t i_sourceStart=0)`  
*Copy part of a uint32\_t into the DataBuffer.*
- `uint32_t insertFromRight (const uint32_t *i_datain, uint32_t i_start, uint32_t i_len)`  
*Copy a right aligned (decimal) uint32\_t array into this DataBuffer.*
- `uint32_t insertFromRight (uint32_t i_datain, uint32_t i_start, uint32_t i_len)`  
*Copy a right aligned (decimal) uint32\_t into the DataBuffer.*
- `uint32_t extract (ecmdDataBuffer &o_bufferOut, uint32_t i_start, uint32_t i_len) const`  
*Copy data from this DataBuffer into another.*
- `uint32_t extract (uint32_t *o_data, uint32_t i_start, uint32_t i_len) const`  
*Copy data from this DataBuffer into another.*
- `uint32_t extractPreserve (ecmdDataBuffer &o_bufferOut, uint32_t i_start, uint32_t i_len, uint32_t i_targetStart=0) const`  
*Copy data from this buffer into another at a given offset, preserving the size and other data in the output buffer.*
- `uint32_t extractPreserve (uint32_t *o_data, uint32_t i_start, uint32_t i_len, uint32_t i_targetStart=0) const`  
*Copy data from this DataBuffer into a generic output buffer at a given offset.*
- `uint32_t extractToRight (ecmdDataBuffer &o_bufferOut, uint32_t i_start, uint32_t i_len) const`  
*Copy data from this DataBuffer into another DataBuffer and right justify.*
- `uint32_t extractToRight (uint32_t *o_data, uint32_t i_start, uint32_t i_len) const`  
*Copy data from this DataBuffer into a uint32\_t buffer.*
- `uint32_t concat (const ecmdDataBuffer &i_buf0, const ecmdDataBuffer &i_buf1)`  
*Concatenate 2 DataBuffers into in this one.*

- `uint32_t concat` (const `ecmdDataBuffer` &i\_buf0, const `ecmdDataBuffer` &i\_buf1, const `ecmdDataBuffer` &i\_buf2)  
*Concatenate 3 DataBuffers into in this one.*
- `uint32_t setOr` (const `ecmdDataBuffer` &i\_bufferIn, uint32\_t i\_startbit, uint32\_t i\_len)  
*OR data into DataBuffer.*
- `uint32_t setOr` (const uint32\_t \*i\_datain, uint32\_t i\_startbit, uint32\_t i\_len)  
*OR data into DataBuffer.*
- `uint32_t setOr` (uint32\_t i\_datain, uint32\_t i\_startbit, uint32\_t i\_len)  
*OR data into DataBuffer.*
- `uint32_t merge` (const `ecmdDataBuffer` &i\_bufferIn)  
*OR data into DataBuffer.*
- `uint32_t setXor` (const `ecmdDataBuffer` &i\_bufferIn, uint32\_t i\_startbit, uint32\_t i\_len)  
*XOR data into DataBuffer.*
- `uint32_t setXor` (const uint32\_t \*i\_datain, uint32\_t i\_startbit, uint32\_t i\_len)  
*XOR data into DataBuffer.*
- `uint32_t setXor` (uint32\_t i\_datain, uint32\_t i\_startbit, uint32\_t i\_len)  
*XOR data into DataBuffer.*
- `uint32_t setAnd` (const `ecmdDataBuffer` &i\_bufferIn, uint32\_t i\_startbit, uint32\_t i\_len)  
*AND data into DataBuffer.*
- `uint32_t setAnd` (const uint32\_t \*i\_datain, uint32\_t i\_startbit, uint32\_t i\_len)  
*AND data into DataBuffer.*
- `uint32_t setAnd` (uint32\_t i\_datain, uint32\_t i\_startbit, uint32\_t i\_len)  
*AND data into DataBuffer.*
- `uint32_t copy` (`ecmdDataBuffer` &o\_copyBuffer) const  
*Copy entire contents of this ecmdDataBuffer into o\_copyBuffer.*
- `uint32_t memCopyIn` (const uint32\_t \*i\_buf, uint32\_t i\_bytes)  
*Copy buffer into this ecmdDataBuffer.*
- `uint32_t memCopyOut` (uint32\_t \*o\_buf, uint32\_t i\_bytes) const  
*Copy DataBuffer into supplied uint32\_t buffer.*
- `uint32_t flatten` (uint8\_t \*o\_data, uint32\_t i\_len) const  
*Flatten all the object data into a uint8\_t buffer.*
- `uint32_t unflatten` (const uint8\_t \*i\_data, uint32\_t i\_len)  
*Unflatten object data from a uint8\_t buffer into this DataBuffer.*
- `uint32_t flattenSize` (void) const  
*Return number of bytes needed for a buffer to flatten the object.*



### Parity Functions

- `uint32_t oddParity (uint32_t i_start, uint32_t i_stop) const`  
*Generate odd parity over a range of bits.*
- `uint32_t evenParity (uint32_t i_start, uint32_t i_stop) const`  
*Generate even parity over a range of bits.*
- `uint32_t oddParity (uint32_t i_start, uint32_t i_stop, uint32_t i_insertpos)`  
*Generate odd parity over a range of bits and insert into DataBuffer.*
- `uint32_t evenParity (uint32_t i_start, uint32_t i_stop, uint32_t i_insertpos)`  
*Generate even parity over a range of bits and insert into DataBuffer.*

### Buffer Character Conversion Functions

- `std::string genHexLeftStr (uint32_t i_start, uint32_t i_bitlen) const`  
*Return Data as a hex left aligned char string.*
- `std::string genHexRightStr (uint32_t i_start, uint32_t i_bitlen) const`  
*Return Data as a hex right aligned char string.*
- `std::string genBinStr (uint32_t i_start, uint32_t i_bitlen) const`  
*Return Data as a binary char string.*
- `std::string genAsciiStr (uint32_t i_start, uint32_t i_bitlen) const`  
*Return Data as an ASCII char string. If it's out of range, a . is printed.*
- `std::string genHexLeftStr () const`  
*Return entire buffer as a hex left aligned char string.*
- `std::string genHexRightStr () const`  
*Return entire buffer as a hex right aligned char string.*
- `std::string genBinStr () const`  
*Return entire buffer as a binary char string.*
- `std::string genAsciiStr () const`  
*Return Data as an ASCII char string. If it's out of range, a . is printed.*
- `std::string genXstateStr (uint32_t i_start, uint32_t i_bitlen) const`  
*Retrieve a section of the Xstate Data.*
- `std::string genXstateStr () const`  
*Retrieve entire Xstate Data buffer.*

### String to Data conversion functions

- `uint32_t insertFromHexLeft (const char *i_hexChars, uint32_t i_start=0, uint32_t i_length=0)`  
*Convert data from a hex left-aligned string and insert it into this data buffer.*

- **uint32\_t insertFromHexLeftAndResize** (const char \*i\_hexChars, uint32\_t i\_start=0, uint32\_t i\_length=0)  
*Convert data from a hex left-aligned string and insert it into this data buffer - and set's buffer length to size of data.*
- **uint32\_t insertFromHexRight** (const char \*i\_hexChars, uint32\_t i\_start=0, uint32\_t i\_expectedLength=0)  
*Convert data from a hex right-aligned string and insert it into this data buffer.*
- **uint32\_t insertFromHexRightAndResize** (const char \*i\_hexChars, uint32\_t i\_start=0, uint32\_t i\_expectedLength=0)  
*Convert data from a hex right-aligned string and insert it into this data buffer - and set's buffer length to size of data.*
- **uint32\_t insertFromBin** (const char \*i\_binChars, uint32\_t i\_start=0)  
*Convert data from a binary string and insert it into this data buffer.*
- **uint32\_t insertFromBinAndResize** (const char \*i\_binChars, uint32\_t i\_start=0)  
*Convert data from a binary string and insert it into this data buffer - and set's buffer length to size of data.*

### Simulation Buffer Functions

- **uint32\_t enableXstateBuffer** ()  
*Initializes the X-state buffer, from then on all changes are reflected in Xstate.*
- **uint32\_t disableXstateBuffer** ()  
*Removes the X-state buffer, from then on no changes are made to Xstate.*
- **bool isXstateEnabled** () const  
*Query to find out if this buffer has X-states enabled.*
- **uint32\_t flushToX** (char i\_value)  
*Load entire buffer with an X-state value.*
- **bool hasXstate** () const  
*Check Entire buffer for any X-state values.*
- **bool hasXstate** (uint32\_t i\_start, uint32\_t i\_length) const  
*Check section of buffer for any X-state values.*
- **char getXstate** (uint32\_t i\_bit) const  
*Retrieve an Xstate value from the buffer.*
- **uint32\_t setXstate** (uint32\_t i\_bit, char i\_value)  
*Set an Xstate value in the buffer.*
- **uint32\_t setXstate** (uint32\_t i\_bit, char i\_value, uint32\_t i\_length)  
*Set an Xstate value in the buffer.*
- **uint32\_t setXstate** (uint32\_t i\_bitoffset, const char \*i\_datastr)  
*Set a range of Xstate values in buffer.*
- **uint32\_t memCopyInXstate** (const char \*i\_buf, uint32\_t i\_bytes)

*Copy buffer into the Xstate data of this ecmdDataBuffer.*

- `uint32_t memCopyOutXstate (char *o_buf, uint32_t i_bytes) const`  
*Copy DataBuffer into supplied char buffer from Xstate data.*

## Misc Functions

- `uint32_t writeFile (const char *i_filename, ecmdFormatType_t i_format, const char *i_facName=NULL)`  
*Write buffer out into a file in the format specified.*
- `uint32_t writeFileMultiple (const char *i_filename, ecmdFormatType_t i_format, ecmdWriteMode_t i_mode, uint32_t &o_dataNumber, const char *i_property=NULL)`  
*Writes/Appends buffer out into a file in the format specified.*
- `uint32_t writeFileStream (std::ostream &o_filestream)`  
*Write buffer out into the stream in ECMD\_SAVE\_FORMAT\_BINARY\_DATA format.*
- `uint32_t readFile (const char *i_filename, ecmdFormatType_t i_format, std::string *o_property=NULL)`  
*Read data from the file into the buffer.*
- `uint32_t readFileMultiple (const char *i_filename, ecmdFormatType_t i_format, uint32_t i_dataNumber=0, std::string *o_property=NULL)`  
*Read data from the file into the buffer.*
- `uint32_t queryNumOfBuffers (const char *i_filename, ecmdFormatType_t i_format, uint32_t &o_num)`  
*Get the number of databuffers stored in the file created by writeFile/writeFileMultiple.*
- `uint32_t readFileStream (std::istream &i_filestream, uint32_t i_bitlength)`  
*Read data from the stream (in ECMD\_SAVE\_FORMAT\_BINARY\_DATA format) into the buffer.*
- `uint32_t shareBuffer (ecmdDataBuffer *i_sharingBuffer)`  
*This function will take the passed in buffer, delete any current data it holds, and point its data var to that which is owned by the one being called with. It will not have iv\_UserOwned flag set, so it should not delete the buffer it points to, nor resize it, but it can alter the data. The use of this function is for caching data for reads.*
- `void queryErrorState (uint32_t &o_errorState)`  
*This function returns the stored error state that could have been caused by any number of previous operations on the buffer.*

## Operator overloads

- `int operator== (const ecmdDataBuffer &other) const`  
*Overload the == operator.*
- `int operator!= (const ecmdDataBuffer &other) const`  
*Overload the != operator.*

- **ecmdDataBuffer operator &** (const **ecmdDataBuffer** &other) const  
*Overload the & operator.*
- **ecmdDataBuffer operator|** (const **ecmdDataBuffer** &other) const  
*Overload the | operator.*

## Protected Member Functions

- **uint32\_t fillDataStr** (char fillChar)

## Protected Attributes

- **uint32\_t iv\_Capacity**  
*Actual buffer capacity - always  $\geq$  iv\_NumWords.*
- **uint32\_t iv\_NumWords**  
*Specified buffer size rounded to next word.*
- **uint32\_t iv\_NumBits**  
*Specified buffer size in bits.*
- **uint32\_t \* iv\_Data**  
*Pointer to buffer inside iv\_RealData.*
- **uint32\_t \* iv\_RealData**  
*Real buffer - with header and tail.*
- **bool iv\_UserOwned**  
*Whether or not this buffer owns the data.*
- **bool iv\_BufferOptimizable**  
*Whether or not this is an optimizable buffer.*
- **char \* iv\_DataStr**
- **bool iv\_XstateEnabled**

## Friends

- **class ecmdDataBufferImplementationHelper**

### 5.7.1 Detailed Description

Provides a means to handle data from the eCMD C API.

## 5.7.2 Constructor & Destructor Documentation

### 5.7.2.1 ecmdDataBuffer::ecmdDataBuffer ()

Default Constructor.

**Postcondition:**

buffer is not allocated, can be allocated later with setWordLength, setCapacity or setBitLength

### 5.7.2.2 ecmdDataBuffer::ecmdDataBuffer (uint32\_t *i\_numBits*)

Constructor.

**Parameters:**

*i\_numBits* Size of data in bits to initialize

**Postcondition:**

ecmdDataBuffer is initialized and zero'd out

### 5.7.2.3 ecmdDataBuffer::ecmdDataBuffer (const ecmdDataBuffer & *other*)

Copy Constructor.

**Parameters:**

*other* Buffer to copy

### 5.7.2.4 virtual ecmdDataBuffer::~~ecmdDataBuffer () [virtual]

Default Destructor.

## 5.7.3 Member Function Documentation

### 5.7.3.1 uint32\_t ecmdDataBuffer::clear ()

Called by the destructor, available to user to reset buffer to default constructor state.

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

*ECMD\_DBUF\_NOT\_OWNER* when called on buffer not owned

*nonzero* on failure

**Postcondition:**

Memory deallocated and size set to 0

**5.7.3.2    uint32\_t ecmdDataBuffer::getWordLength () const**

Return the length of the buffer in words.

**Return values:**

*Buffer* length in words rounded up

**5.7.3.3    uint32\_t ecmdDataBuffer::getByteLength () const**

Return the length of the buffer in bytes.

**Return values:**

*Buffer* length in bytes rounded up

**5.7.3.4    uint32\_t ecmdDataBuffer::getBitLength () const**

Return the length of the buffer in bits.

**Return values:**

*Buffer* length in bits

**5.7.3.5    uint32\_t ecmdDataBuffer::getCapacity () const**

Return the actual capacity of the internal buffer in words.

**Return values:**

*Actual* capacity in words of internal buffer

**5.7.3.6    uint32\_t ecmdDataBuffer::setWordLength (uint32\_t i\_newNumWords)**

Reinitialize the Buffer to specified length.

**Parameters:**

*i\_newNumWords* Length of new buffer in words

**Postcondition:**

Buffer is reinitialized and zero'd out

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

*ECMD\_DBUF\_INIT\_FAIL* failure occurred setting new length

*ECMD\_DBUF\_NOT\_OWNER* when called on buffer not owned

NOTE : Capacity will be adjusted to fit new size if neccesary CAUTION : All data stored in buffer will be lost

**5.7.3.7 uint32\_t ecmdDataBuffer::setByteLength (uint32\_t i\_newNumBytes)**

Reinitialize the Buffer to specified length.

**Parameters:**

*i\_newNumBytes* Length of new buffer in bytes

**Postcondition:**

Buffer is reinitialized and zero'd out

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

*ECMD\_DBUF\_INIT\_FAIL* failure occurred setting new length

*ECMD\_DBUF\_NOT\_OWNER* when called on buffer not owned

NOTE : Capacity will be adjusted to fit new size if necessary CAUTION : All data stored in buffer will be lost

**5.7.3.8 uint32\_t ecmdDataBuffer::setBitLength (uint32\_t i\_newNumBits)**

Reinitialize the Buffer to specified length.

**Parameters:**

*i\_newNumBits* Length of new buffer in bits

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

*ECMD\_DBUF\_INIT\_FAIL* failure occurred setting new length

*ECMD\_DBUF\_NOT\_OWNER* when called on buffer not owned

**Postcondition:**

Buffer is reinitialized and zero'd out

NOTE : Capacity will be adjusted to fit new size if necessary CAUTION : All data stored in buffer will be lost

**5.7.3.9 uint32\_t ecmdDataBuffer::setCapacity (uint32\_t i\_newNumWords)**

Reinitialize the internal buffer to specified length.

**Parameters:**

*i\_newNumWords* length of internal data buffer in words

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

*ECMD\_DBUF\_INIT\_FAIL* failure occurred setting new length

*ECMD\_DBUF\_NOT\_OWNER* when called on buffer not owned

**Postcondition:**

Internal buffer is reinitialized and zero'd out. Requests to decrease the capacity are ignored

CAUTION : All data stored in buffer will be lost

**5.7.3.10** `uint32_t ecmdDataBuffer::shrinkBitLength (uint32_t i_newNumBits)`

Shrink buffer size to a new bit size.

**Parameters:**

*i\_newNumBits* New bit length for buffer (must be <= current buffer length)

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

**Postcondition:**

Internal buffer size is reset but data inside new size is not lost

**5.7.3.11** `uint32_t ecmdDataBuffer::growBitLength (uint32_t i_newNumBits)`

Expand buffer size to a new bit size maintaining current data.

**Parameters:**

*i\_newNumBits* New bit length for buffer

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

**Postcondition:**

Internal buffer size is reset but data inside is not lost

NOTE : Capacity will be adjusted to fit new size if neccesary

**5.7.3.12** `virtual bool ecmdDataBuffer::isBufferOptimizable (void) [inline, virtual]`

Returns value of iv\_BufferOptimizable.

**5.7.3.13** `uint32_t ecmdDataBuffer::setBit (uint32_t i_bit)`

Turn on a bit in buffer.

**Parameters:**

*i\_bit* Bit in buffer to turn on

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

*ECMD\_DBUF\_BUFFER\_OVERFLOW* *i\_bit* is not contained in the size of this buffer



**5.7.3.14** `uint32_t ecmdDataBuffer::setBit (uint32_t i_bit, uint32_t i_len)`

Turn on a bit in buffer.

**Parameters:**

*i\_bit* start bit in buffer to turn on

*i\_len* Number of consecutive bits from start bit to turn on

**Return values:**

***ECMD\_DBUF\_SUCCESS*** on success

***ECMD\_DBUF\_BUFFER\_OVERFLOW*** *i\_bit* is not contained in the size of this buffer

**5.7.3.15** `uint32_t ecmdDataBuffer::writeBit (uint32_t i_bit, uint32_t i_value)`

Write a bit to specified value in buffer.

**Parameters:**

*i\_bit* Bit in buffer to turn on

*i\_value* Value to write

**Return values:**

***ECMD\_DBUF\_SUCCESS*** on success

***ECMD\_DBUF\_BUFFER\_OVERFLOW*** *i\_bit* is not contained in the size of this buffer

**5.7.3.16** `uint32_t ecmdDataBuffer::setWord (uint32_t i_wordoffset, uint32_t i_value)`

Set a word of data in buffer.

**Parameters:**

*i\_wordoffset* Offset of word to set

*i\_value* 32 bits of data to put into word

**Return values:**

***ECMD\_DBUF\_SUCCESS*** on success

***ECMD\_DBUF\_BUFFER\_OVERFLOW*** *i\_wordoffset* is not contained in the size of this buffer

**5.7.3.17** `uint32_t ecmdDataBuffer::getWord (uint32_t i_wordoffset) const`

Fetch a word from ecmdDataBuffer.

**Parameters:**

*i\_wordoffset* Offset of word to fetch

**Return values:**

*Value* of word requested

**5.7.3.18** `uint32_t ecmdDataBuffer::setByte (uint32_t i_byteoffset, uint8_t i_value)`

Set a byte of data in buffer.

**Parameters:**

*i\_byteoffset* Offset of byte to set  
*i\_value* 8 bits of data to put into byte

**Return values:**

***ECMD\_DBUF\_SUCCESS*** on success  
***ECMD\_DBUF\_BUFFER\_OVERFLOW*** *i\_byteoffset* is not contained in the size of this buffer

**5.7.3.19** `uint8_t ecmdDataBuffer::getBytes (uint32_t i_byteoffset) const`

Fetch a byte from ecmdDataBuffer.

**Parameters:**

*i\_byteoffset* Offset of byte to fetch

**Return values:**

*Value* of byte requested

NOTE : If offset > buffer length retval = 0 and error printed

**5.7.3.20** `uint32_t ecmdDataBuffer::setHalfWord (uint32_t i_halfwordoffset, uint16_t i_value)`

Set a halfword of data in buffer.

**Parameters:**

*i\_halfwordoffset* Offset of halfword to set  
*i\_value* 16 bits of data to put into halfword

**Return values:**

***ECMD\_DBUF\_SUCCESS*** on success  
***ECMD\_DBUF\_BUFFER\_OVERFLOW*** *i\_halfwordoffset* is not contained in the size of this buffer

**5.7.3.21** `uint16_t ecmdDataBuffer::getHalfWord (uint32_t i_halfwordoffset) const`

Fetch a halfword from ecmdDataBuffer.

**Parameters:**

*i\_halfwordoffset* Offset of halfword to fetch

**Return values:**

*Value* of halfword requested

### 5.7.3.22 uint32\_t ecmdDataBuffer::setDoubleWord (uint32\_t i\_doublewordoffset, uint64\_t i\_value)

Set a doubleword of data in buffer.

#### Parameters:

*i\_doublewordoffset* Offset of doubleword to set  
*i\_value* 64 bits of data to put into doubleword

#### Return values:

**ECMD\_DBUF\_SUCCESS** on success  
**ECMD\_DBUF\_BUFFER\_OVERFLOW** *i\_doublewordoffset* is not contained in the size of this buffer

### 5.7.3.23 uint64\_t ecmdDataBuffer::getDoubleWord (uint32\_t i\_doublewordoffset) const

Fetch a doubleword from ecmdDataBuffer.

#### Parameters:

*i\_doublewordoffset* Offset of doubleword to fetch

#### Return values:

*Value* of doubleword requested

### 5.7.3.24 uint32\_t ecmdDataBuffer::clearBit (uint32\_t i\_bit)

Clear a bit in buffer.

#### Parameters:

*i\_bit* Bit in buffer to turn off

#### Return values:

**ECMD\_DBUF\_SUCCESS** on success  
**ECMD\_DBUF\_BUFFER\_OVERFLOW** *i\_bit* is not contained in the size of this buffer

### 5.7.3.25 uint32\_t ecmdDataBuffer::clearBit (uint32\_t i\_bit, uint32\_t i\_len)

Clear multiple bits in buffer.

#### Parameters:

*i\_bit* Start bit in buffer to turn off  
*i\_len* Number of consecutive bits from start bit to off

#### Return values:

**ECMD\_DBUF\_SUCCESS** on success  
**ECMD\_DBUF\_BUFFER\_OVERFLOW** *i\_bit* is not contained in the size of this buffer

**5.7.3.26** `uint32_t ecmdDataBuffer::flipBit (uint32_t i_bit)`

Invert bit.

**Parameters:**

*i\_bit* Bit in buffer to invert

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

*ECMD\_DBUF\_BUFFER\_OVERFLOW* *i\_bit* is not contained in the size of this buffer

**5.7.3.27** `uint32_t ecmdDataBuffer::flipBit (uint32_t i_bit, uint32_t i_len)`

Invert multiple bits.

**Parameters:**

*i\_bit* Start bit in buffer to invert

*i\_len* Number of consecutive bits to invert

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

*ECMD\_DBUF\_BUFFER\_OVERFLOW* *i\_bit* is not contained in the size of this buffer

**5.7.3.28** `bool ecmdDataBuffer::isBitSet (uint32_t i_bit) const`

Test if bit is set.

**Parameters:**

*i\_bit* Bit to test

**Return values:**

*true* if bit is set - false if bit is clear

**5.7.3.29** `bool ecmdDataBuffer::isBitSet (uint32_t i_bit, uint32_t i_len) const`

Test if multiple bits are set.

**Parameters:**

*i\_bit* Start bit to test

*i\_len* Number of consecutive bits to test

**Return values:**

*true* if all bits in range are set - false if any bit is clear

**5.7.3.30 bool ecmdDataBuffer::isBitClear (uint32\_t *i\_bit*) const**

Test if bit is clear.

**Parameters:**

*i\_bit* Bit to test

**Return values:**

*true* if bit is clear - false if bit is set

**5.7.3.31 bool ecmdDataBuffer::isBitClear (uint32\_t *i\_bit*, uint32\_t *i\_len*) const**

Test if multiple bits are clear.

**Parameters:**

*i\_bit* Start bit to test

*i\_len* Number of consecutive bits to test

**Return values:**

*true* if all bits in range are clear - false if any bit is set

**5.7.3.32 uint32\_t ecmdDataBuffer::getNumBitsSet (uint32\_t *i\_bit*, uint32\_t *i\_len*) const**

Count number of bits set in a range.

**Parameters:**

*i\_bit* Start bit to test

*i\_len* Number of consecutive bits to test

**Return values:**

*Number* of bits set in range

**5.7.3.33 uint32\_t ecmdDataBuffer::shiftRight (uint32\_t *i\_shiftnum*)**

Shift data to right.

**Parameters:**

*i\_shiftnum* Number of bits to shift

**Postcondition:**

Bits in buffer are shifted to right by specified number of bits - data is shifted off the end  
Buffer size is unchanged

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

**5.7.3.34** `uint32_t ecmdDataBuffer::shiftLeft (uint32_t i_shiftnum)`

Shift data to left.

**Parameters:**

*i\_shiftnum* Number of bits to shift

**Postcondition:**

Bits in buffer are shifted to left by specified number of bits - data is shifted off the beginning  
Buffer size is unchanged

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

**5.7.3.35** `uint32_t ecmdDataBuffer::shiftRightAndResize (uint32_t i_shiftnum)`

Shift data to right - resizing buffer.

**Parameters:**

*i\_shiftnum* Number of bits to shift

**Postcondition:**

Bits in buffer are shifted to right by specified number of bits  
Buffer size is resized to accomodate shift

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

*ECMD\_DBUF\_NOT\_OWNER* when called on buffer not owned

**5.7.3.36** `uint32_t ecmdDataBuffer::shiftLeftAndResize (uint32_t i_shiftnum)`

Shift data to left - resizing buffer.

**Parameters:**

*i\_shiftnum* Number of bits to shift

**Postcondition:**

Bits in buffer are shifted to left by specified number of bits - data is shifted off the beginning  
Buffer size is resized to accomodate shift

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

*ECMD\_DBUF\_NOT\_OWNER* when called on buffer not owned

**5.7.3.37** uint32\_t ecmdDataBuffer::rotateRight (uint32\_t i\_rotatenum)

Rotate data to right.

**Parameters:**

*i\_rotatenum* Number of bits to rotate

**Postcondition:**

Bits in buffer are rotated to the right by specified number of bits - data is rotated to the beginning

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

**5.7.3.38** uint32\_t ecmdDataBuffer::rotateLeft (uint32\_t i\_rotatenum)

Rotate data to left.

**Parameters:**

*i\_rotatenum* Number of bits to rotate

**Postcondition:**

Bits in buffer are rotated to the left by specified number of bits - data is rotated to the end

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

**5.7.3.39** uint32\_t ecmdDataBuffer::flushTo0 ()

Clear entire buffer to 0's.

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

**5.7.3.40** uint32\_t ecmdDataBuffer::flushTo1 ()

Set entire buffer to 1's.

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

**5.7.3.41** uint32\_t ecmdDataBuffer::invert ()

Invert entire buffer.

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

**5.7.3.42** `uint32_t ecmdDataBuffer::reverse ()`

Bit reverse entire buffer.

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

**5.7.3.43** `uint32_t ecmdDataBuffer::applyInversionMask (const uint32_t *  
i_invMask, uint32_t i_invByteLen)`

Apply an inversion mask to data inside buffer.

**Parameters:**

*i\_invMask* Buffer that stores inversion mask

*i\_invByteLen* Buffer length provided in bytes

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

**5.7.3.44** `uint32_t ecmdDataBuffer::applyInversionMask (const ecmdDataBuffer &  
i_invMaskBuffer, uint32_t i_invByteLen)`

Apply an inversion mask to data inside buffer Just a wrapper that takes in a ecmdDataBuffer and calls uint32\_t applyInversionMask.

**Parameters:**

*i\_invMaskBuffer* Buffer that stores inversion mask

*i\_invByteLen* Buffer length provided in bytes

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

**5.7.3.45** `uint32_t ecmdDataBuffer::insert (const ecmdDataBuffer & i_bufferIn,  
uint32_t i_targetStart, uint32_t i_len, uint32_t i_sourceStart = 0)`

Copy part of another DataBuffer into this one.

**Parameters:**

*i\_bufferIn* DataBuffer to copy data from - data is taken left aligned

*i\_targetStart* Start bit to insert to

*i\_len* Length of bits to insert

*i\_sourceStart* Start bit in i\_bufferIn - default value is zero

**Precondition:**

DataBuffer must be pre-allocated

**Postcondition:**

Data is copied from i\_bufferIn to this DataBuffer in specified location



**Return values:***ECMD\_DBUF\_SUCCESS* on success*ECMD\_DBUF\_BUFFER\_OVERFLOW* operation requested out of range

**5.7.3.46** `uint32_t ecmdDataBuffer::insert (const uint32_t * i_datain, uint32_t i_targetStart, uint32_t i_len, uint32_t i_sourceStart = 0)`

Copy part of a uint32\_t array into this DataBuffer.

**Parameters:***i\_datain* uint32\_t array to copy into this DataBuffer - data is taken left aligned*i\_targetStart* Start bit to insert into*i\_len* Length of bits to insert*i\_sourceStart* Start bit in *i\_datain* - default value is zero**Precondition:**

DataBuffer must be pre-allocated

**Postcondition:**Data is copied from *i\_datain* to this DataBuffer in specified location**Return values:***ECMD\_DBUF\_SUCCESS* on success*ECMD\_DBUF\_BUFFER\_OVERFLOW* operation requested out of range

**5.7.3.47** `uint32_t ecmdDataBuffer::insert (uint32_t i_datain, uint32_t i_targetStart, uint32_t i_len, uint32_t i_sourceStart = 0)`

Copy part of a uint32\_t into the DataBuffer.

**Parameters:***i\_datain* uint32\_t value to copy into DataBuffer - data is taken left aligned*i\_targetStart* Start bit to insert into*i\_len* Length of bits to insert (must be <= 32)*i\_sourceStart* Start bit in *i\_datain* - default value is zero**Precondition:**

DataBuffer must be pre-allocated

**Postcondition:**Data is copied from *bufferIn* to this DataBuffer in specified location**Return values:***ECMD\_DBUF\_SUCCESS* on success*ECMD\_DBUF\_BUFFER\_OVERFLOW* operation requested out of range

**5.7.3.48** `uint32_t ecmdDataBuffer::insertFromRight (const uint32_t * i_datain,  
uint32_t i_start, uint32_t i_len)`

Copy a right aligned (decimal) uint32\_t array into this DataBuffer.

**Parameters:**

*i\_datain* uint32\_t array to copy into this DataBuffer - data is taken right aligned

*i\_start* Start bit to insert into

*i\_len* Length of bits to insert

**Precondition:**

DataBuffer must be pre-allocated

**Postcondition:**

Data is copied from datain into this DataBuffer at specified location

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

*ECMD\_DBUF\_BUFFER\_OVERFLOW* operation requested out of range

NOTE : Data is assumed to be aligned on the word boundary of i\_len

**5.7.3.49** `uint32_t ecmdDataBuffer::insertFromRight (uint32_t i_datain, uint32_t  
i_start, uint32_t i_len)`

Copy a right aligned (decimal) uint32\_t into the DataBuffer.

**Parameters:**

*i\_datain* uint32\_t value to copy into DataBuffer - data is taken right aligned

*i\_start* Start bit to insert into

*i\_len* Length of bits to insert (must be <= 32)

**Precondition:**

DataBuffer must be pre-allocated

**Postcondition:**

Data is copied from datain into this DataBuffer at specified location

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

*ECMD\_DBUF\_BUFFER\_OVERFLOW* operation requested out of range

**5.7.3.50** `uint32_t ecmdDataBuffer::extract (ecmdDataBuffer & o_bufferOut,  
uint32_t i_start, uint32_t i_len) const`

Copy data from this DataBuffer into another.

**Parameters:**

*o\_bufferOut* DataBuffer to copy into - data is placed left aligned

*i\_start* Start bit of data in this DataBuffer to copy

*i\_len* Length of consecutive bits to copy

**Postcondition:**

Data is copied from specified location in this DataBuffer to bufferOut

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

*ECMD\_DBUF\_BUFFER\_OVERFLOW* operation requested out of range

NOTE : The o\_bufferOut buffer is resized to the extract length and any data in the buffer is lost

**5.7.3.51** `uint32_t ecmdDataBuffer::extract (uint32_t * o_data, uint32_t i_start, uint32_t i_len) const`

Copy data from this DataBuffer into another.

**Parameters:**

*o\_data* uint32\_t buffer to copy into - data is placed left aligned - must be pre-allocated

*i\_start* Start bit of data in DataBuffer to copy

*i\_len* Length of consecutive bits to copy

**Postcondition:**

Data is copied from specified location in this DataBuffer to o\_data

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

*ECMD\_DBUF\_BUFFER\_OVERFLOW* operation requested out of range

**5.7.3.52** `uint32_t ecmdDataBuffer::extractPreserve (ecmdDataBuffer & o_bufferOut, uint32_t i_start, uint32_t i_len, uint32_t i_targetStart = 0) const`

Copy data from this buffer into another at a given offset, preserving the size and other data in the output buffer.

**Parameters:**

*o\_bufferOut* Target data buffer where data is copied into

*i\_start* Start bit in this DataBuffer to begin copy

*i\_len* Length of consecutive bits to copy

*i\_targetStart* Start bit in output buffer where data is copied defaults to zero

**Postcondition:**

Data is copied from offset in this buffer to offset in out buffer

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

*EMCD\_DBUF\_BUFFER\_OVERFLOW* data requested is out of range in one of the 2 buffers

**5.7.3.53** `uint32_t ecmdDataBuffer::extractPreserve (uint32_t * o_data, uint32_t i_start, uint32_t i_len, uint32_t i_targetStart = 0) const`

Copy data from this DataBuffer into a generic output buffer at a given offset.

**Parameters:**

- o\_data* Array of data to write into, must be pre-allocated
- i\_start* Start bit in this DataBuffer to begin the copy
- i\_len* Length of consecutive bits to copy
- i\_targetStart* Starting bit in output data to place extracted data, defaults to zero

**Postcondition:**

Data is copied from offset in this DataBuffer to offset in output buffer

**Return values:**

- ECMD\_DBUF\_SUCCESS* on success
- ECMD\_DBUF\_INIT\_FAIL* unable to allocate databuffer
- ECMD\_DBUF\_BUFFER\_OVERFLOW* request is out of range for this DataBuffer, output buffer is NOT checked for overflow

**5.7.3.54** `uint32_t ecmdDataBuffer::extractToRight (ecmdDataBuffer & o_bufferOut, uint32_t i_start, uint32_t i_len) const`

Copy data from this DataBuffer into another DataBuffer and right justify.

**Parameters:**

- o\_bufferOut* DataBuffer to copy into - data is placed right aligned
- i\_start* Start bit of data in DataBuffer to copy
- i\_len* Length of consecutive bits to copy

**Postcondition:**

Data is copied from specified location in this DataBuffer to o\_bufferOut, right aligned. Data is only right aligned if i\_len < 32

**Return values:**

- ECMD\_DBUF\_SUCCESS* on success
- ECMD\_DBUF\_BUFFER\_OVERFLOW* operation requested out of range

**5.7.3.55** `uint32_t ecmdDataBuffer::extractToRight (uint32_t * o_data, uint32_t i_start, uint32_t i_len) const`

Copy data from this DataBuffer into a uint32\_t buffer.

**Parameters:**

- o\_data* uint32\_t buffer to copy into - data is placed right aligned - must be pre-allocated
- i\_start* Start bit of data in DataBuffer to copy
- i\_len* Length of consecutive bits to copy

**Postcondition:**

Data is copied from specified location in this DataBuffer to o\_data, right aligned. Data is only right aligned if i\_len < 32

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

*ECMD\_DBUF\_BUFFER\_OVERFLOW* operation requested out of range

### 5.7.3.56 uint32\_t ecmdDataBuffer::concat (const ecmdDataBuffer & i\_buf0, const ecmdDataBuffer & i\_buf1)

Concatenate 2 DataBuffers into in this one.

**Parameters:**

*i\_buf0* First DataBuffer to concatenate; copied to beginning of this buffer

*i\_buf1* Second DataBuffer to concatenate; copied to this buffer after the first buffer

**Postcondition:**

Space is allocated, and data from the 2 DataBuffers is concatenated and copied to this buffer

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

*ECMD\_DBUF\_BUFFER\_OVERFLOW* operation requested out of range

### 5.7.3.57 uint32\_t ecmdDataBuffer::concat (const ecmdDataBuffer & i\_buf0, const ecmdDataBuffer & i\_buf1, const ecmdDataBuffer & i\_buf2)

Concatenate 3 DataBuffers into in this one.

**Parameters:**

*i\_buf0* First DataBuffer to concatenate; copied to beginning of this buffer

*i\_buf1* Second DataBuffer to concatenate; copied to this buffer after the first buffer

*i\_buf2* Third DataBuffer to concatenate; copied to this buffer after the second buffer

**Postcondition:**

Space is allocated, and data from the 3 DataBuffers is concatenated and copied to this buffer

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

*ECMD\_DBUF\_BUFFER\_OVERFLOW* operation requested out of range

### 5.7.3.58 uint32\_t ecmdDataBuffer::setOr (const ecmdDataBuffer & i\_bufferIn, uint32\_t i\_startbit, uint32\_t i\_len)

OR data into DataBuffer.

**Parameters:**

*i\_bufferIn* DataBuffer to OR data from - data is taken left aligned

*i\_startbit* Start bit to OR to

*i\_len* Length of bits to OR

**Postcondition:**

Data is ORed from i\_bufferIn to this DataBuffer in specified location

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

*ECMD\_DBUF\_BUFFER\_OVERFLOW* operation requested out of range

**5.7.3.59** `uint32_t ecmdDataBuffer::setOr (const uint32_t * i_datain, uint32_t i_startbit, uint32_t i_len)`

OR data into DataBuffer.

**Parameters:**

*i\_datain* uint32\_t buffer to OR data from - data is taken left aligned

*i\_startbit* Start bit to OR to

*i\_len* Length of bits to OR

**Postcondition:**

Data is ORed from datain to this DataBuffer in specified location

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

*ECMD\_DBUF\_BUFFER\_OVERFLOW* operation requested out of range

**5.7.3.60** `uint32_t ecmdDataBuffer::setOr (uint32_t i_datain, uint32_t i_startbit, uint32_t i_len)`

OR data into DataBuffer.

**Parameters:**

*i\_datain* uint32\_t to OR data from - data is taken left aligned

*i\_startbit* Start bit to OR to

*i\_len* Length of bits to OR (must be <= 32)

**Postcondition:**

Data is ORed from datain to this DataBuffer in specified location

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

*ECMD\_DBUF\_BUFFER\_OVERFLOW* operation requested out of range

**5.7.3.61** `uint32_t ecmdDataBuffer::merge (const ecmdDataBuffer & i_bufferIn)`

OR data into DataBuffer.

**Parameters:**

*i\_bufferIn* DataBuffer to OR data from - data is taken left aligned

**Postcondition:**

Entire data is ORed from bufferIn to this DataBuffer

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

*ECMD\_DBUF\_BUFFER\_OVERFLOW* operation requested out of range

**5.7.3.62** `uint32_t ecmdDataBuffer::setXor (const ecmdDataBuffer & i_bufferIn, uint32_t i_startbit, uint32_t i_len)`

XOR data into DataBuffer.

**Parameters:**

*i\_bufferIn* DataBuffer to XOR data from - data is taken left aligned

*i\_startbit* Start bit to XOR to

*i\_len* Length of bits to XOR

**Postcondition:**

Data is XORed from i\_bufferIn to this DataBuffer in specified location

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

*ECMD\_DBUF\_BUFFER\_OVERFLOW* operation requested out of range

**5.7.3.63** `uint32_t ecmdDataBuffer::setXor (const uint32_t * i_datain, uint32_t i_startbit, uint32_t i_len)`

XOR data into DataBuffer.

**Parameters:**

*i\_datain* uint32\_t buffer to XOR data from - data is taken left aligned

*i\_startbit* Start bit to XOR to

*i\_len* Length of bits to XOR

**Postcondition:**

Data is XORed from datain to this DataBuffer in specified location

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

*ECMD\_DBUF\_BUFFER\_OVERFLOW* operation requested out of range

**5.7.3.64** `uint32_t ecmdDataBuffer::setXor (uint32_t i_datain, uint32_t i_startbit, uint32_t i_len)`

XOR data into DataBuffer.

**Parameters:**

*i\_datain* uint32\_t to XOR data from - data is taken left aligned  
*i\_startbit* Start bit to XOR to  
*i\_len* Length of bits to XOR (must be <= 32)

**Postcondition:**

Data is XORED from datain to this DataBuffer in specified location

**Return values:**

***ECMD\_DBUF\_SUCCESS*** on success  
***ECMD\_DBUF\_BUFFER\_OVERFLOW*** operation requested out of range

**5.7.3.65** `uint32_t ecmdDataBuffer::setAnd (const ecmdDataBuffer & i_bufferIn, uint32_t i_startbit, uint32_t i_len)`

AND data into DataBuffer.

**Parameters:**

*i\_bufferIn* Bitvector to AND data from - data is taken left aligned  
*i\_startbit* Start bit to AND to  
*i\_len* Length of bits to AND

**Postcondition:**

Data is ANDed from bufferIn to this DataBuffer in specified location

**Return values:**

***ECMD\_DBUF\_SUCCESS*** on success  
***ECMD\_DBUF\_BUFFER\_OVERFLOW*** operation requested out of range

**5.7.3.66** `uint32_t ecmdDataBuffer::setAnd (const uint32_t * i_datain, uint32_t i_startbit, uint32_t i_len)`

AND data into DataBuffer.

**Parameters:**

*i\_datain* uint32\_t buffer to AND data from - data is taken left aligned  
*i\_startbit* Start bit to AND to  
*i\_len* Length of bits to AND

**Postcondition:**

Data is ANDed from datain to this DataBuffer in specified location

**Return values:**

***ECMD\_DBUF\_SUCCESS*** on success  
***ECMD\_DBUF\_BUFFER\_OVERFLOW*** operation requested out of range



### 5.7.3.67 uint32\_t ecmdDataBuffer::setAnd (uint32\_t *i\_datain*, uint32\_t *i\_startbit*, uint32\_t *i\_len*)

AND data into DataBuffer.

**Parameters:**

*i\_datain* uint32\_t to AND data from - data is taken left aligned  
*i\_startbit* Start bit to AND to  
*i\_len* Length of bits to AND (must be <= 32)

**Postcondition:**

Data is ANDed from datain to this DataBuffer in specified location

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success  
*ECMD\_DBUF\_BUFFER\_OVERFLOW* operation requested out of range

### 5.7.3.68 uint32\_t ecmdDataBuffer::copy (ecmdDataBuffer & *o\_copyBuffer*) const

Copy entire contents of this ecmdDataBuffer into o\_copyBuffer.

**Parameters:**

*o\_copyBuffer* DataBuffer to copy data into

**Postcondition:**

copyBuffer is allocated, is an exact duplicate of this DataBuffer

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

### 5.7.3.69 uint32\_t ecmdDataBuffer::memCopyIn (const uint32\_t \* *i\_buf*, uint32\_t *i\_bytes*)

Copy buffer into this ecmdDataBuffer.

**Parameters:**

*i\_buf* Buffer to copy from  
*i\_bytes* Byte length to copy

**Precondition:**

DataBuffer must be pre-allocated

**Postcondition:**

Xstate and Raw buffer are set to value in i\_buf for smaller of i\_bytes or buffer capacity

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success  
*ECMD\_DBUF\_BUFFER\_OVERFLOW* operation requested out of range

**5.7.3.70** `uint32_t ecmdDataBuffer::memCopyOut (uint32_t * o_buf, uint32_t i_bytes) const`

Copy DataBuffer into supplied uint32\_t buffer.

**Parameters:**

*o\_buf* Buffer to copy into - must be pre-allocated

*i\_bytes* Byte length to copy

**Postcondition:**

*o\_buf* has contents of databuffer for smaller of *i\_bytes* or buffer capacity

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

*ECMD\_DBUF\_BUFFER\_OVERFLOW* operation requested out of range

**5.7.3.71** `uint32_t ecmdDataBuffer::flatten (uint8_t * o_data, uint32_t i_len) const`

Flatten all the object data into a uint8\_t buffer.

**Parameters:**

*o\_data* Byte buffer to write the flattened data to - should

*i\_len* Number of bytes in the *o\_data* buffer

**Postcondition:**

*o\_data* buffer has a flattened version of the DataBuffer - must be pre-allocated Data format (all in network byte order): First Word: *iv\_Capacity\*32* (in bits) Second Word: *iv\_NumBits* Remaining Words: Buffer data

**5.7.3.72** `uint32_t ecmdDataBuffer::unflatten (const uint8_t * i_data, uint32_t i_len)`

Unflatten object data from a uint8\_t buffer into this DataBuffer.

**Parameters:**

*i\_data* Byte buffer to read the flattened data from

*i\_len* Number of bytes in the *i\_data* buffer

**Postcondition:**

This DataBuffer is allocated and initialized with the unflattened version of *i\_data* Data format (all in network byte order): First Word: *iv\_Capacity\*32* (in bits) Second Word: *iv\_NumBits* Remaining Words: Buffer data

**5.7.3.73** `uint32_t ecmdDataBuffer::flattenSize (void) const`

Return number of bytes needed for a buffer to flatten the object.

**Return values:**

*Number* of bytes needed

**5.7.3.74** `uint32_t ecmdDataBuffer::oddParity (uint32_t i_start, uint32_t i_stop) const`

Generate odd parity over a range of bits.

**Parameters:**

*i\_start* Start bit of range

*i\_stop* Stop bit of range

**Return values:**

0 or 1 depending on parity of range

**5.7.3.75** `uint32_t ecmdDataBuffer::evenParity (uint32_t i_start, uint32_t i_stop) const`

Generate even parity over a range of bits.

**Parameters:**

*i\_start* Start bit of range

*i\_stop* Stop bit of range

**Return values:**

0 or 1 depending on parity of range

**5.7.3.76** `uint32_t ecmdDataBuffer::oddParity (uint32_t i_start, uint32_t i_stop, uint32_t i_insertpos)`

Generate odd parity over a range of bits and insert into DataBuffer.

**Parameters:**

*i\_start* Start bit of range

*i\_stop* Stop bit of range

*i\_insertpos* Bit position to insert parity

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

*ECMD\_DBUF\_BUFFER\_OVERFLOW* operation requested out of range

**5.7.3.77** `uint32_t ecmdDataBuffer::evenParity (uint32_t i_start, uint32_t i_stop, uint32_t i_insertpos)`

Generate even parity over a range of bits and insert into DataBuffer.

**Parameters:**

*i\_start* Start bit of range

*i\_stop* Stop bit of range

*i\_insertpos* Bit position to insert parity

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

*ECMD\_DBUF\_BUFFER\_OVERFLOW* operation requested out of range

**5.7.3.78** `std::string ecmdDataBuffer::genHexLeftStr (uint32_t i_start, uint32_t i_bitlen) const`

Return Data as a hex left aligned char string.

**Parameters:**

*i\_start* Start bit of data to convert

*i\_bitlen* Number of consecutive bits to convert

**Return values:**

*String* containing requested data

**5.7.3.79** `std::string ecmdDataBuffer::genHexRightStr (uint32_t i_start, uint32_t i_bitlen) const`

Return Data as a hex right aligned char string.

**Parameters:**

*i\_start* Start bit of data to convert

*i\_bitlen* Number of consecutive bits to convert

**Return values:**

*String* containing requested data

**5.7.3.80** `std::string ecmdDataBuffer::genBinStr (uint32_t i_start, uint32_t i_bitlen) const`

Return Data as a binary char string.

**Parameters:**

*i\_start* Start bit of data to convert

*i\_bitlen* Number of consecutive bits to convert

**Return values:**

*String* containing requested data

**5.7.3.81** `std::string ecmdDataBuffer::genAsciiStr (uint32_t i_start, uint32_t i_bitlen) const`

Return Data as an ASCII char string. If it's out of range, a . is printed.

**Parameters:**

*i\_start* Start bit of data to convert

*i\_bitlen* Number of consecutive bits to convert

**Return values:**

*String* containing requested data

**5.7.3.82** `std::string ecmdDataBuffer::genHexLeftStr () const`

Return entire buffer as a hex left aligned char string.

**Return values:**

*String* containing requested data

**5.7.3.83** `std::string ecmdDataBuffer::genHexRightStr () const`

Return entire buffer as a hex right aligned char string.

**Return values:**

*String* containing requested data

**5.7.3.84** `std::string ecmdDataBuffer::genBinStr () const`

Return entire buffer as a binary char string.

**Return values:**

*String* containing requested data

**5.7.3.85** `std::string ecmdDataBuffer::genAsciiStr () const`

Return Data as an ASCII char string. If it's out of range, a . is printed.

**Return values:**

*String* containing requested data

**5.7.3.86** `std::string ecmdDataBuffer::genXstateStr (uint32_t i_start, uint32_t i_bitlen) const`

Retrieve a section of the Xstate Data.

**Parameters:**

*i\_start* Start bit of data to retrieve

*i\_bitlen* Number of consecutive bits to retrieve

**Return values:**

*String* containing requested data

### 5.7.3.87 `std::string ecmdDataBuffer::genXstateStr () const`

Retrieve entire Xstate Data buffer.

**Return values:**

*String* containing requested data

### 5.7.3.88 `uint32_t ecmdDataBuffer::insertFromHexLeft (const char * i_hexChars, uint32_t i_start = 0, uint32_t i_length = 0)`

Convert data from a hex left-aligned string and insert it into this data buffer.

**Parameters:**

*i\_hexChars* Hex Left-aligned string of data to insert

*i\_start* Starting position in data buffer to insert to, 0 by default

*i\_length* Length of data to insert, defaults to length of *i\_hexChars*, zeroes are padded or data dropped from right if necessary

**Return values:**

*ECMD\_DBUF\_INVALID\_DATA\_FORMAT* if non-hex chars detected in *i\_hexChars*

*ECMD\_SUCCESS* on success

*non-zero* on failure

### 5.7.3.89 `uint32_t ecmdDataBuffer::insertFromHexLeftAndResize (const char * i_hexChars, uint32_t i_start = 0, uint32_t i_length = 0)`

Convert data from a hex left-aligned string and insert it into this data buffer - and set's buffer length to size of data.

**Parameters:**

*i\_hexChars* Hex Left-aligned string of data to insert

*i\_start* Starting position in data buffer to insert to, 0 by default

*i\_length* Length of data to insert, defaults to length of *i\_hexChars*, zeroes are padded or data dropped from right if necessary

**Return values:**

*ECMD\_DBUF\_INVALID\_DATA\_FORMAT* if non-hex chars detected in *i\_hexChars*

*ECMD\_SUCCESS* on success

*non-zero* on failure

**5.7.3.90** `uint32_t ecmdDataBuffer::insertFromHexRight (const char * i_hexChars,  
uint32_t i_start = 0, uint32_t i_expectedLength = 0)`

Convert data from a hex right-aligned string and insert it into this data buffer.

**Parameters:**

- i\_hexChars* Hex Right-aligned string of data to insert
- i\_expectedLength* The expected length of the string data, zeros are padded or data dropped from the left if necessary
- i\_start* Starting position in data buffer to insert to, 0 by default

**Return values:**

- ECMD\_DBUF\_INVALID\_DATA\_FORMAT*** if non-hex chars detected in *i\_hexChars*
- ECMD\_SUCCESS*** on success
- non-zero*** on failure

**5.7.3.91** `uint32_t ecmdDataBuffer::insertFromHexRightAndResize (const char *  
i_hexChars, uint32_t i_start = 0, uint32_t i_expectedLength = 0)`

Convert data from a hex right-aligned string and insert it into this data buffer - and set's buffer length to size of data.

**Parameters:**

- i\_hexChars* Hex Right-aligned string of data to insert
- i\_expectedLength* The expected length of the string data, zeros are padded or data dropped from the left if necessary
- i\_start* Starting position in data buffer to insert to, 0 by default

**Return values:**

- ECMD\_DBUF\_INVALID\_DATA\_FORMAT*** if non-hex chars detected in *i\_hexChars*
- ECMD\_SUCCESS*** on success
- non-zero*** on failure

**5.7.3.92** `uint32_t ecmdDataBuffer::insertFromBin (const char * i_binChars,  
uint32_t i_start = 0)`

Convert data from a binary string and insert it into this data buffer.

**Return values:**

- 0** on success- **non-zero** on failure

**Parameters:**

- i\_binChars* String of 0's and 1's to insert
- i\_start* Starting position in data buffer to insert to, 0 by default

**Return values:**

*ECMD\_DBUF\_INVALID\_DATA\_FORMAT* if non-binary chars detected in *i\_binChars*  
*ECMD\_SUCCESS* on success  
*non-zero* on failure

### 5.7.3.93 `uint32_t ecmdDataBuffer::insertFromBinAndResize (const char * i_binChars, uint32_t i_start = 0)`

Convert data from a binary string and insert it into this data buffer - and set's buffer length to size of data.

**Return values:**

0 on success- non-zero on failure

**Parameters:**

*i\_binChars* String of 0's and 1's to insert  
*i\_start* Starting position in data buffer to insert to, 0 by default

**Return values:**

*ECMD\_DBUF\_INVALID\_DATA\_FORMAT* if non-binary chars detected in *i\_binChars*  
*ECMD\_SUCCESS* on success  
*non-zero* on failure

### 5.7.3.94 `uint32_t ecmdDataBuffer::enableXstateBuffer ()`

Initializes the X-state buffer, from then on all changes are reflected in Xstate.

**Postcondition:**

Xstate buffer is created and initialized to value of current raw buffer

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success  
*ECMD\_DBUF\_INIT\_FAIL* failure occurred allocating X-state array  
*ECMD\_DBUF\_NOT\_OWNER* when called on buffer not owned

### 5.7.3.95 `uint32_t ecmdDataBuffer::disableXstateBuffer ()`

Removes the X-state buffer, from then on no changes are made to Xstate.

**Postcondition:**

Xstate buffer is deallocated

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success  
*ECMD\_DBUF\_NOT\_OWNER* when called on buffer not owned



**5.7.3.96 bool ecmdDataBuffer::isXstateEnabled () const**

Query to find out if this buffer has X-states enabled.

**Return values:**

*true* if the Xstate buffer is active

*false* if the Xstate buffer is not active

**5.7.3.97 uint32\_t ecmdDataBuffer::flushToX (char i\_value)**

Load entire buffer with an X-state value.

**Parameters:**

*i\_value* Value to load into buffer

**Return values:**

*ECMD\_DBUF\_SUCCESS* on success

**5.7.3.98 bool ecmdDataBuffer::hasXstate () const**

Check Entire buffer for any X-state values.

**Return values:**

*true* if xstate found false if none

**5.7.3.99 bool ecmdDataBuffer::hasXstate (uint32\_t i\_start, uint32\_t i\_length)  
const**

Check section of buffer for any X-state values.

**Parameters:**

*i\_start* Start bit to test

*i\_length* Number of consecutive bits to test

**Return values:**

*true* if xstate found false if none

**5.7.3.100 char ecmdDataBuffer::getXstate (uint32\_t i\_bit) const**

Retrieve an Xstate value from the buffer.

**Parameters:**

*i\_bit* Bit to retrieve

NOTE - To retrieve multiple bits use genXstateStr

### 5.7.3.101 `uint32_t ecmdDataBuffer::setXstate (uint32_t i_bit, char i_value)`

Set an Xstate value in the buffer.

#### Parameters:

*i\_bit* Bit to set  
*i\_value* Xstate value to set

#### Return values:

*ECMD\_DBUF\_SUCCESS* on success  
*ECMD\_DBUF\_BUFFER\_OVERFLOW* operation requested out of range

### 5.7.3.102 `uint32_t ecmdDataBuffer::setXstate (uint32_t i_bit, char i_value, uint32_t i_length)`

Set an Xstate value in the buffer.

#### Parameters:

*i\_bit* Bit to set  
*i\_value* Xstate value to set  
*i\_length* Number of consecutive bits to set to i\_value

#### Return values:

*ECMD\_DBUF\_SUCCESS* on success  
*ECMD\_DBUF\_BUFFER\_OVERFLOW* operation requested out of range

### 5.7.3.103 `uint32_t ecmdDataBuffer::setXstate (uint32_t i_bitoffset, const char * i_datastr)`

Set a range of Xstate values in buffer.

#### Parameters:

*i\_bitoffset* bit in buffer to start inserting  
*i\_datastr* Character value to set bit - can be "0XX0", "1", "X"

#### Return values:

*ECMD\_DBUF\_SUCCESS* on success  
*ECMD\_DBUF\_BUFFER\_OVERFLOW* operation requested out of range

### 5.7.3.104 `uint32_t ecmdDataBuffer::memCopyInXstate (const char * i_buf, uint32_t i_bytes)`

Copy buffer into the Xstate data of this ecmdDataBuffer.

#### Parameters:

*i\_buf* Buffer to copy from

*i\_bytes* Byte length to copy (char length)

**Postcondition:**

Xstate and Raw buffer are set to value in *i\_buf* for smaller of *i\_bytes* or buffer capacity

**Return values:**

***ECMD\_DBUF\_SUCCESS*** on success

***ECMD\_DBUF\_BUFFER\_OVERFLOW*** operation requested out of range

**5.7.3.105** `uint32_t ecmdDataBuffer::memCopyOutXstate (char * o_buf, uint32_t i_bytes) const`

Copy DataBuffer into supplied char buffer from Xstate data.

**Parameters:**

*o\_buf* Buffer to copy into - must be pre-allocated

*i\_bytes* Byte length to copy (char length)

**Postcondition:**

*o\_buf* has contents of databuffer for smaller of *i\_bytes* or buffer capacity

**Return values:**

***ECMD\_DBUF\_SUCCESS*** on success

***ECMD\_DBUF\_BUFFER\_OVERFLOW*** operation requested out of range

**5.7.3.106** `uint32_t ecmdDataBuffer::writeFile (const char * i_filename,  
ecmdFormatType_t i_format, const char * i_facName = NULL)`

Write buffer out into a file in the format specified.

**Parameters:**

*i\_filename* file to write to

*i\_format* format to write in

*i\_property* name(len <= 200 chars) associated with the databuffer(e.g. ringname/spynome)-default is NULL

**Return values:**

***ECMD\_DBUF\_SUCCESS*** on success

***ECMD\_DBUF\_FOPEN\_FAIL*** Unable to open the file for write

***ECMD\_DBUF\_XSTATE\_ERROR*** If Xstate values are detected on non-Xstate format request

**5.7.3.107** `uint32_t ecmdDataBuffer::writeFileMultiple (const char * i_filename,  
ecmdFormatType_t i_format, ecmdWriteMode_t i_mode, uint32_t &  
o_dataNumber, const char * i_property = NULL)`

Writes/Appends buffer out into a file in the format specified.

**Parameters:**

*i\_filename* file to write to  
*i\_format* format to write in  
*i\_mode* mode to open the file in  
*o\_dataNumber* the sequence number for this data, used by readFileMultiple to pick the right databuffer  
*i\_property* name(len <= 200 chars) associated with the databuffer(e.g. ringname/spynome)-default is NULL

**Return values:**

**ECMD\_DBUF\_SUCCESS** on success  
**ECMD\_DBUF\_FOPEN\_FAIL** Unable to open the file for write  
**ECMD\_DBUF\_XSTATE\_ERROR** If Xstate values are detected on non-Xstate format request **ECMD\_SAVE\_FORMAT\_BINARY\_DATA** not accepted when *ecmdWriteMode\_t* is **ECMD\_APPEND\_MODE**

**5.7.3.108** `uint32_t ecmdDataBuffer::writeFileStream (std::ostream &  
o_filestream)`

Write buffer out into the stream in **ECMD\_SAVE\_FORMAT\_BINARY\_DATA** format.

**Parameters:**

*o\_filestream* output stream to write to

**Return values:**

**ECMD\_DBUF\_SUCCESS** on success  
*non-zero* on failure

**5.7.3.109** `uint32_t ecmdDataBuffer::readFile (const char * i_filename,  
ecmdFormatType_t i_format, std::string * o_property = NULL)`

Read data from the file into the buffer.

**Parameters:**

*i\_filename* to read from  
*i\_format* data format to expect in the file  
*o\_property* string associated with the databuffer read from the file(if present)

**Return values:**

**ECMD\_DBUF\_SUCCESS** on success  
**ECMD\_DBUF\_FILE\_FORMAT\_MISMATCH** specified format not found in the file  
**ECMD\_DBUF\_FOPEN\_FAIL** Unable to open the file for read  
**ECMD\_DBUF\_XSTATE\_ERROR** If XState format is requested when XState is not defined for the configuration

**5.7.3.110** `uint32_t ecmdDataBuffer::readFileMultiple (const char * i_filename,  
ecmdFormatType_t i_format, uint32_t i_dataNumber = 0, std::string  
* o_property = NULL)`

Read data from the file into the buffer.

**Parameters:**

*i\_filename* to read from  
*i\_format* data format to expect in the file  
*i\_dataNumber* data requested in case of multiple databuffers  
*o\_property* string associated with the databuffer read from the file(if present)

**Return values:**

**ECMD\_DBUF\_SUCCESS** on success  
**ECMD\_DBUF\_FILE\_FORMAT\_MISMATCH** specified format not found in the file  
**ECMD\_DBUF\_FOPEN\_FAIL** Unable to open the file for read  
**ECMD\_DBUF\_XSTATE\_ERROR** If XState format is requested when XState is not defined for the configuration  
**ECMD\_DBUF\_DATANUMBER\_NOT\_FOUND** If requested *i\_dataNumber* is not available in file ECMD\_SAVE\_FORMAT\_BINARY\_DATA not accepted when *i\_dataNumber* != 0

**5.7.3.111** `uint32_t ecmdDataBuffer::queryNumOfBuffers (const char * i_filename,  
ecmdFormatType_t i_format, uint32_t & o_num)`

Get the number of databuffers stored in the file created by writeFile/writeFileMultiple.

**Parameters:**

*i\_filename* to read from  
*i\_format* data format to expect in the file  
*o\_num* number of data buffers stored in the file

**Return values:**

**ECMD\_DBUF\_SUCCESS** on success  
**ECMD\_DBUF\_FILE\_FORMAT\_MISMATCH** specified format not found in the file  
**ECMD\_DBUF\_FOPEN\_FAIL** Unable to open the file for read

**5.7.3.112** `uint32_t ecmdDataBuffer::readFileStream (std::istream & i_filestream,  
uint32_t i_bitlength)`

Read data from the stream (in ECMD\_SAVE\_FORMAT\_BINARY\_DATA format) into the buffer.

**Parameters:**

*i\_filestream* input stream to read from  
*i\_bitlength* used to est. the number of bytes to read from the stream

**Return values:**

**ECMD\_DBUF\_SUCCESS** on success  
**non-zero** on failure

### 5.7.3.113 `uint32_t ecmdDataBuffer::shareBuffer (ecmdDataBuffer * i_sharingBuffer)`

This function will take the passed in buffer, delete any current data it holds, and point its data var to that which is owned by the one being called with. It will not have iv\_UserOwned flag set, so it should not delete the buffer it points to, nor resize it, but it can alter the data. The use of this function is for caching data for reads.

#### Parameters:

*i\_sharingBuffer* input buffer

#### Return values:

*ECMD\_DBUF\_SUCCESS* on success

### 5.7.3.114 `void ecmdDataBuffer::queryErrorState (uint32_t & o_errorState)`

This function returns the stored error state that could have been caused by any number of previous operations on the buffer.

#### Parameters:

*o\_errorState* Stored Error state

### 5.7.3.115 `int ecmdDataBuffer::operator== (const ecmdDataBuffer & other) const`

Overload the == operator.

### 5.7.3.116 `int ecmdDataBuffer::operator!= (const ecmdDataBuffer & other) const`

Overload the != operator.

### 5.7.3.117 `ecmdDataBuffer ecmdDataBuffer::operator & (const ecmdDataBuffer & other) const`

Overload the & operator.

### 5.7.3.118 `ecmdDataBuffer ecmdDataBuffer::operator| (const ecmdDataBuffer & other) const`

Overload the | operator.

**5.7.3.119** `uint32_t ecmdDataBuffer::fillDataStr (char fillChar)` [protected]

## 5.7.4 Friends And Related Function Documentation

**5.7.4.1** `friend class ecmdDataBufferImplementationHelper` [friend]

## 5.7.5 Member Data Documentation

**5.7.5.1** `uint32_t ecmdDataBuffer::iv_Capacity` [protected]

Actual buffer capacity - always  $\geq$  `iv_NumWords`.

**5.7.5.2** `uint32_t ecmdDataBuffer::iv_NumWords` [protected]

Specified buffer size rounded to next word.

**5.7.5.3** `uint32_t ecmdDataBuffer::iv_NumBits` [protected]

Specified buffer size in bits.

**5.7.5.4** `uint32_t* ecmdDataBuffer::iv_Data` [protected]

Pointer to buffer inside `iv_RealData`.

**5.7.5.5** `uint32_t* ecmdDataBuffer::iv_RealData` [protected]

Real buffer - with header and tail.

**5.7.5.6** `bool ecmdDataBuffer::iv_UserOwned` [protected]

Whether or not this buffer owns the data.

**5.7.5.7** `bool ecmdDataBuffer::iv_BufferOptimizable` [protected]

Whether or not this is an optimizable buffer.

**5.7.5.8** `char* ecmdDataBuffer::iv_DataStr` [protected]

**5.7.5.9** `bool ecmdDataBuffer::iv_XstateEnabled` [protected]

The documentation for this class was generated from the following file:

- `ecmdDataBuffer.H`

## 5.8 ecmdDataBufferImplementationHelper Class Reference

This is used to help low-level implementation of the **ecmdDataBuffer**(p. 24), this CAN NOT be used by any eCMD client or data corruption will occur.

```
#include <ecmdDataBuffer.H>
```

### Static Public Member Functions

- **uint32\_t \* getDataPtr** (void \**i\_buffer*)
- **void applyRawBufferToXstate** (void \**i\_buffer*)

#### 5.8.1 Detailed Description

This is used to help low-level implementation of the **ecmdDataBuffer**(p. 24), this CAN NOT be used by any eCMD client or data corruption will occur.

#### 5.8.2 Member Function Documentation

**5.8.2.1**    **uint32\_t\* ecmdDataBufferImplementationHelper::getDataPtr** (void \**i\_buffer*)    [static]

**5.8.2.2**    **void ecmdDataBufferImplementationHelper::applyRawBufferToXstate**  
              (void \* *i\_buffer*)    [static]

The documentation for this class was generated from the following file:

- **ecmdDataBuffer.H**



## 5.9 ecmdDllInfo Struct Reference

This is used by `ecmdQueryDllInfo` to return info to the client about what Dll instance they are actually running with.

```
#include <ecmdStructs.H>
```

### Public Attributes

- **ecmdDllType\_t dllType**  
*Dll instance type running.*
- **ecmdDllProduct\_t dllProduct**  
*Dll product supported.*
- **std::string dllProductType**  
*Dll product type currently configured.*
- **ecmdDllEnv\_t dllEnv**  
*Dll environment (Simulation vs Hardware).*
- **std::string dllBuildDate**  
*Date the Dll was built.*
- **std::string dllCapiVersion**  
*should be set to ECMD\_CAPI\_VERSION*
- **std::string dllBuildInfo**  
*Any additional info the Dll/Plugin would like to pass.*

### 5.9.1 Detailed Description

This is used by `ecmdQueryDllInfo` to return info to the client about what Dll instance they are actually running with.

### 5.9.2 Member Data Documentation

#### 5.9.2.1 **ecmdDllType\_t ecmdDllInfo::dllType**

Dll instance type running.

#### 5.9.2.2 **ecmdDllProduct\_t ecmdDllInfo::dllProduct**

Dll product supported.

#### 5.9.2.3 **std::string ecmdDllInfo::dllProductType**

Dll product type currently configured.

**5.9.2.4 ecmdDllEnv\_t ecmdDllInfo::dllEnv**

Dll environment (Simulation vs Hardware).

**5.9.2.5 std::string ecmdDllInfo::dllBuildDate**

Date the Dll was built.

**5.9.2.6 std::string ecmdDllInfo::dllCapiVersion**

should be set to ECMD\_CAPI\_VERSION

**5.9.2.7 std::string ecmdDllInfo::dllBuildInfo**

Any additional info the Dll/Plugin would like to pass.

The documentation for this struct was generated from the following file:

- **ecmdStructs.H**

## 5.10 ecmdIndexEntry Struct Reference

Used by get/put Gpr/Fpr Multiple function to pass data.

```
#include <ecmdStructs.H>
```

### Public Attributes

- **int index**  
*Index of entry.*
- **ecmdDataBuffer buffer**  
*Data to/from entry.*
- **uint32\_t rc**  
*Error code in retrieving this entry.*

#### 5.10.1 Detailed Description

Used by get/put Gpr/Fpr Multiple function to pass data.

#### 5.10.2 Member Data Documentation

##### 5.10.2.1 int ecmdIndexEntry::index

Index of entry.

##### 5.10.2.2 ecmdDataBuffer ecmdIndexEntry::buffer

Data to/from entry.

##### 5.10.2.3 uint32\_t ecmdIndexEntry::rc

Error code in retrieving this entry.

The documentation for this struct was generated from the following file:

- **ecmdStructs.H**

## 5.11 ecmdIndexVectorEntry Struct Reference

Used by `????` function to pass data.

```
#include <ecmdStructs.H>
```

### Public Attributes

- **int index**  
*Index of entry.*
- **std::vector< ecmdDataBuffer > buffer**  
*Vector of data to/from entry.*
- **uint32\_t rc**  
*Error code in retrieving this entry.*

### 5.11.1 Detailed Description

Used by `????` function to pass data.

### 5.11.2 Member Data Documentation

#### 5.11.2.1 int ecmdIndexVectorEntry::index

Index of entry.

#### 5.11.2.2 std::vector<ecmdDataBuffer> ecmdIndexVectorEntry::buffer

Vector of data to/from entry.

#### 5.11.2.3 uint32\_t ecmdIndexVectorEntry::rc

Error code in retrieving this entry.

The documentation for this struct was generated from the following file:

- **ecmdStructs.H**

## 5.12 ecmdLatchData Struct Reference

Used for the ecmdQueryLatch function to return latch info.

```
#include <ecmdStructs.H>
```

### Public Attributes

- **std::string latchName**  
*(Detail: Low) Latch Name*
- **std::string ringName**  
*(Detail: Low) Ring that this latch belongs to*
- **int bitLength**  
*(Detail: Low) length of latch, sum of all the parts*
- **bool isCoreRelated**  
*(Detail: Low) This latch is related to the core level of a chip*
- **std::string clockDomain**  
*(Detail: High) Clock domain this latch belongs to*
- **ecmdClockState\_t clockState**  
*(Detail: High) Required clock state to access this latch*

### 5.12.1 Detailed Description

Used for the ecmdQueryLatch function to return latch info.

### 5.12.2 Member Data Documentation

#### 5.12.2.1 std::string ecmdLatchData::latchName

(Detail: Low) Latch Name

#### 5.12.2.2 std::string ecmdLatchData::ringName

(Detail: Low) Ring that this latch belongs to

#### 5.12.2.3 int ecmdLatchData::bitLength

(Detail: Low) length of latch, sum of all the parts

#### 5.12.2.4 bool ecmdLatchData::isCoreRelated

(Detail: Low) This latch is related to the core level of a chip

**5.12.2.5 std::string ecmdLatchData::clockDomain**

(Detail: High) Clock domain this latch belongs to

**5.12.2.6 ecmdClockState\_t ecmdLatchData::clockState**

(Detail: High) Required clock state to access this latch

The documentation for this struct was generated from the following file:

- **ecmdStructs.H**

## 5.13 ecmdLatchEntry Struct Reference

Used by getlatch function to return data.

```
#include <ecmdStructs.H>
```

### Public Attributes

- **std::string latchName**  
*Latch name of entry.*
- **std::string ringName**  
*Ring that latch came from.*
- **ecmdDataBuffer buffer**  
*Latch data.*
- **int latchStartBit**  
*Start bit of data inside latch.*
- **int latchEndBit**  
*End bit of data inside latch.*
- **uint32\_t rc**  
*Error code in retrieving this entry.*

### 5.13.1 Detailed Description

Used by getlatch function to return data.

### 5.13.2 Member Data Documentation

#### 5.13.2.1 std::string ecmdLatchEntry::latchName

Latch name of entry.

#### 5.13.2.2 std::string ecmdLatchEntry::ringName

Ring that latch came from.

#### 5.13.2.3 ecmdDataBuffer ecmdLatchEntry::buffer

Latch data.

#### 5.13.2.4 int ecmdLatchEntry::latchStartBit

Start bit of data inside latch.

**5.13.2.5 int ecmdLatchEntry::latchEndBit**

End bit of data inside latch.

**5.13.2.6 uint32\_t ecmdLatchEntry::rc**

Error code in retrieving this entry.

The documentation for this struct was generated from the following file:

- **ecmdStructs.H**



## 5.14 ecmdLooperData Struct Reference

Used internally by ecmdConfigLooper to store looping state information.

```
#include <ecmdUtils.H>
```

### Public Attributes

- **bool ecmdLooperInitFlag**  
*Is fresh ?*
- **bool ecmdUseUnitid**  
*This looper is looping on unitid targets not config data.*
- **ecmdConfigLoopMode\_t ecmdLoopMode**  
*Is this a variable depth or static loop?*
- **ecmdQueryData ecmdSystemConfigData**  
*Config data queried from the system.*
- **std::list< ecmdCageData >::iterator ecmdCurCage**  
*Pointer to current Cage.*
- **std::list< ecmdNodeData >::iterator ecmdCurNode**  
*Pointer to current Node.*
- **std::list< ecmdSlotData >::iterator ecmdCurSlot**  
*Pointer to current Slot.*
- **std::list< ecmdChipData >::iterator ecmdCurChip**  
*Pointer to current Chip.*
- **std::list< ecmdCoreData >::iterator ecmdCurCore**  
*Pointer to current Core.*
- **std::list< ecmdThreadData >::iterator ecmdCurThread**  
*Pointer to current Thread.*
- **ecmdChipTarget prevTarget**  
*Pointer to previous target.*
- **std::list< ecmdChipTarget > unitIdTargets**  
*List of targets if looping on a unitid.*
- **std::list< ecmdChipTarget >::iterator curUnitIdTarget**  
*Pointer to current unitid target.*

### 5.14.1 Detailed Description

Used internally by ecmdConfigLooper to store looping state information.

## 5.14.2 Member Data Documentation

### 5.14.2.1 `bool ecmdLooperData::ecmdLooperInitFlag`

Is fresh ?

### 5.14.2.2 `bool ecmdLooperData::ecmdUseUnitid`

This looper is looping on unitid targets not config data.

### 5.14.2.3 `ecmdConfigLoopMode_t ecmdLooperData::ecmdLoopMode`

Is this a variable depth or static loop?

### 5.14.2.4 `ecmdQueryData ecmdLooperData::ecmdSystemConfigData`

Config data queried from the system.

### 5.14.2.5 `std::list<ecmdCageData>::iterator ecmdLooperData::ecmdCurCage`

Pointer to current Cage.

### 5.14.2.6 `std::list<ecmdNodeData>::iterator ecmdLooperData::ecmdCurNode`

Pointer to current Node.

### 5.14.2.7 `std::list<ecmdSlotData>::iterator ecmdLooperData::ecmdCurSlot`

Pointer to current Slot.

### 5.14.2.8 `std::list<ecmdChipData>::iterator ecmdLooperData::ecmdCurChip`

Pointer to current Chip.

### 5.14.2.9 `std::list<ecmdCoreData>::iterator ecmdLooperData::ecmdCurCore`

Pointer to current Core.

### 5.14.2.10 `std::list<ecmdThreadData>::iterator ecmdLooperData::ecmdCurThread`

Pointer to current Thread.

### 5.14.2.11 `ecmdChipTarget ecmdLooperData::prevTarget`

Pointer to previous target.

**5.14.2.12** `std::list<ecmdChipTarget> ecmdLooperData::unitIdTargets`

List of targets if looping on a unitid.

**5.14.2.13** `std::list<ecmdChipTarget>::iterator ecmdLooperData::curUnitIdTarget`

Pointer to current unitid target.

The documentation for this struct was generated from the following file:

- `ecmdUtils.H`

## 5.15 ecmdMemoryEntry Struct Reference

Used by ecmdReadDcard.

```
#include <ecmdStructs.H>
```

### Public Attributes

- `uint64_t` `address`
- `ecmdDataBuffer` `data`
- `ecmdDataBuffer` `tags`

#### 5.15.1 Detailed Description

Used by ecmdReadDcard.

#### 5.15.2 Member Data Documentation

**5.15.2.1** `uint64_t` `ecmdMemoryEntry::address`

**5.15.2.2** `ecmdDataBuffer` `ecmdMemoryEntry::data`

**5.15.2.3** `ecmdDataBuffer` `ecmdMemoryEntry::tags`

The documentation for this struct was generated from the following file:

- `ecmdStructs.H`

## 5.16 ecmdNameEntry Struct Reference

Used by get/putSprMultiple function to pass data.

```
#include <ecmdStructs.H>
```

### Public Attributes

- **std::string name**  
*Name of entry.*
- **ecmdDataBuffer buffer**  
*Data to/from entry.*
- **uint32\_t rc**  
*Error code in retrieving this entry.*

### 5.16.1 Detailed Description

Used by get/putSprMultiple function to pass data.

### 5.16.2 Member Data Documentation

#### 5.16.2.1 std::string ecmdNameEntry::name

Name of entry.

#### 5.16.2.2 ecmdDataBuffer ecmdNameEntry::buffer

Data to/from entry.

#### 5.16.2.3 uint32\_t ecmdNameEntry::rc

Error code in retrieving this entry.

The documentation for this struct was generated from the following file:

- **ecmdStructs.H**

## 5.17 ecmdNameVectorEntry Struct Reference

Used by getTraceArrayMultiple function to pass data.

```
#include <ecmdStructs.H>
```

### Public Attributes

- `std::string name`  
*Name of entry.*
- `std::vector< ecmdDataBuffer > buffer`  
*Vector of data to/from entry.*
- `uint32_t rc`  
*Error code in retrieving this entry.*

### 5.17.1 Detailed Description

Used by getTraceArrayMultiple function to pass data.

### 5.17.2 Member Data Documentation

#### 5.17.2.1 `std::string ecmdNameVectorEntry::name`

Name of entry.

#### 5.17.2.2 `std::vector<ecmdDataBuffer> ecmdNameVectorEntry::buffer`

Vector of data to/from entry.

#### 5.17.2.3 `uint32_t ecmdNameVectorEntry::rc`

Error code in retrieving this entry.

The documentation for this struct was generated from the following file:

- `ecmdStructs.H`

## 5.18 ecmdNodeData Struct Reference

Used for the ecmdQueryConfig function to return node data.

```
#include <ecmdStructs.H>
```

### Public Attributes

- **uint32\_t nodeId**  
*(Detail: Low) Node number of this entry*
- **uint32\_t unitId**  
*(Detail: High) Unit Id of this entry*
- **std::list< ecmdSlotData > slotData**  
*(Detail: Low) List of all slots requested in this node - in numerical order by slotId*

### 5.18.1 Detailed Description

Used for the ecmdQueryConfig function to return node data.

Operators Supported : <

### 5.18.2 Member Data Documentation

#### 5.18.2.1 uint32\_t ecmdNodeData::nodeId

(Detail: Low) Node number of this entry

#### 5.18.2.2 uint32\_t ecmdNodeData::unitId

(Detail: High) Unit Id of this entry

#### 5.18.2.3 std::list<ecmdSlotData> ecmdNodeData::slotData

(Detail: Low) List of all slots requested in this node - in numerical order by slotId

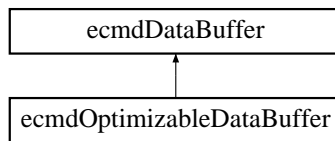
The documentation for this struct was generated from the following file:

- **ecmdStructs.H**

## 5.19 ecmdOptimizableDataBuffer Class Reference

```
#include <ecmdDataBuffer.H>
```

Inheritance diagram for ecmdOptimizableDataBuffer::



### Public Member Functions

- **ecmdOptimizableDataBuffer ()**  
*Default constructor for ecmdOptimizableDataBuffer class.*
- **ecmdOptimizableDataBuffer (uint32\_t numBits)**  
*Constructor with bit length specified.*
- **~ecmdOptimizableDataBuffer ()**  
*Destructor for ecmdOptimizableDataBuffer class.*

### 5.19.1 Constructor & Destructor Documentation

#### 5.19.1.1 ecmdOptimizableDataBuffer::ecmdOptimizableDataBuffer ()

Default constructor for ecmdOptimizableDataBuffer class.

#### 5.19.1.2 ecmdOptimizableDataBuffer::ecmdOptimizableDataBuffer (uint32\_t *numBits*)

Constructor with bit length specified.

#### 5.19.1.3 ecmdOptimizableDataBuffer::~~ecmdOptimizableDataBuffer () [inline]

Destructor for ecmdOptimizableDataBuffer class.

The documentation for this class was generated from the following file:

- **ecmdDataBuffer.H**



## 5.20 ecmdProcRegisterInfo Struct Reference

Used by ecmdQueryProcRegisterInfo function to return data about a Architected register.

```
#include <ecmdStructs.H>
```

### Public Attributes

- **int bitLength**  
*Bit length of each entry.*
- **int totalEntries**  
*Total number of entries available.*
- **bool threadReplicated**  
*Register is replicated for each thread.*

### 5.20.1 Detailed Description

Used by ecmdQueryProcRegisterInfo function to return data about a Architected register.

### 5.20.2 Member Data Documentation

#### 5.20.2.1 int ecmdProcRegisterInfo::bitLength

Bit length of each entry.

#### 5.20.2.2 int ecmdProcRegisterInfo::totalEntries

Total number of entries available.

#### 5.20.2.3 bool ecmdProcRegisterInfo::threadReplicated

Register is replicated for each thread.

The documentation for this struct was generated from the following file:

- **ecmdStructs.H**

## 5.21 ecmdQueryData Struct Reference

Used by the ecmdQueryConfig function to return data.

```
#include <ecmdStructs.H>
```

### Public Attributes

- **ecmdQueryDetail\_t detailLevel**  
*(Detail: Low) This is set to the detail level of the data contained within*
- **std::list< ecmdCageData > cageData**  
*(Detail: Low) List of all cages in the system - in numerical order by cageId*

### 5.21.1 Detailed Description

Used by the ecmdQueryConfig function to return data.

### 5.21.2 Member Data Documentation

#### 5.21.2.1 ecmdQueryDetail\_t ecmdQueryData::detailLevel

(Detail: Low) This is set to the detail level of the data contained within

#### 5.21.2.2 std::list<ecmdCageData> ecmdQueryData::cageData

(Detail: Low) List of all cages in the system - in numerical order by cageId

The documentation for this struct was generated from the following file:

- **ecmdStructs.H**

## 5.22 ecmdRingData Struct Reference

Used for the ecmdQueryRing function to return ring info.

```
#include <ecmdStructs.H>
```

### Public Attributes

- **std::list< std::string > ringNames**  
*(Detail: Low) Names used to reference this ring*
- **uint32\_t address**  
*(Detail: Low) Address modifier*
- **int bitLength**  
*(Detail: Low) length of ring*
- **bool hasInversionMask**  
*(Detail: High) Ring has an inversion mask applied before scanning*
- **bool supportsBroadsideLoad**  
*(Detail: High) This ring supports broadside load in simulation*
- **bool isCheckable**  
*(Detail: High) This ring can be run through the check\_rings command*
- **bool isCoreRelated**  
*(Detail: Low) This ring is related to the core level of a chip*
- **std::string clockDomain**  
*(Detail: High) Clock domain this ring belongs to*
- **ecmdClockState\_t clockState**  
*(Detail: High) Required clock state to access this ring*

### 5.22.1 Detailed Description

Used for the ecmdQueryRing function to return ring info.

### 5.22.2 Member Data Documentation

#### 5.22.2.1 std::list<std::string> ecmdRingData::ringNames

(Detail: Low) Names used to reference this ring

#### 5.22.2.2 uint32\_t ecmdRingData::address

(Detail: Low) Address modifier

**5.22.2.3 int ecmdRingData::bitLength**

(Detail: Low) length of ring

**5.22.2.4 bool ecmdRingData::hasInversionMask**

(Detail: High) Ring has an inversion mask applied before scanning

**5.22.2.5 bool ecmdRingData::supportsBroadsideLoad**

(Detail: High) This ring supports broadside load in simulation

**5.22.2.6 bool ecmdRingData::isCheckable**

(Detail: High) This ring can be run through the check\_rings command

**5.22.2.7 bool ecmdRingData::isCoreRelated**

(Detail: Low) This ring is related to the core level of a chip

**5.22.2.8 std::string ecmdRingData::clockDomain**

(Detail: High) Clock domain this ring belongs to

**5.22.2.9 ecmdClockState\_t ecmdRingData::clockState**

(Detail: High) Required clock state to access this ring

The documentation for this struct was generated from the following file:

- **ecmdStructs.H**

## 5.23 ecmdScomData Struct Reference

Used for the ecmdQueryScom function to return scom info.

```
#include <ecmdStructs.H>
```

### Public Attributes

- **uint32\_t address**  
*(Detail: Low) Scom Address*
- **bool isCoreRelated**  
*(Detail: Low) This scom is related to the core level of a chip*
- **std::string clockDomain**  
*(Detail: High) Clock domain this scom belongs to*
- **ecmdClockState\_t clockState**  
*(Detail: High) Required clock state to access this scom*

### 5.23.1 Detailed Description

Used for the ecmdQueryScom function to return scom info.

### 5.23.2 Member Data Documentation

#### 5.23.2.1 uint32\_t ecmdScomData::address

(Detail: Low) Scom Address

#### 5.23.2.2 bool ecmdScomData::isCoreRelated

(Detail: Low) This scom is related to the core level of a chip

#### 5.23.2.3 std::string ecmdScomData::clockDomain

(Detail: High) Clock domain this scom belongs to

#### 5.23.2.4 ecmdClockState\_t ecmdScomData::clockState

(Detail: High) Required clock state to access this scom

The documentation for this struct was generated from the following file:

- **ecmdStructs.H**

## 5.24 ecmdSimModelInfo Struct Reference

Used by `simGetModelInfo`.

```
#include <ecmdStructs.H>
```

### Public Attributes

- char **modelname** [255]
- char **modeldate** [255]
- char **modeltime** [255]
- char **multivalue**  
*!=0 multivalue, ==0 2-state*

### 5.24.1 Detailed Description

Used by `simGetModelInfo`.

### 5.24.2 Member Data Documentation

**5.24.2.1** char `ecmdSimModelInfo::modelname`[255]

**5.24.2.2** char `ecmdSimModelInfo::modeldate`[255]

**5.24.2.3** char `ecmdSimModelInfo::modeltime`[255]

**5.24.2.4** char `ecmdSimModelInfo::multivalue`

*!=0 multivalue, ==0 2-state*

The documentation for this struct was generated from the following file:

- **ecmdStructs.H**

## 5.25 ecmdSlotData Struct Reference

Used for the ecmdQueryConfig function to return slot data.

```
#include <ecmdStructs.H>
```

### Public Attributes

- **uint32\_t slotId**  
*(Detail: Low) Slot number of this entry*
- **uint32\_t unitId**  
*(Detail: High) Unit Id of this entry*
- **std::list< ecmdChipData > chipData**  
*(Detail: Low) List of all chips requested in this slot - in order by chipType and pos*

### 5.25.1 Detailed Description

Used for the ecmdQueryConfig function to return slot data.

Operators Supported : <

### 5.25.2 Member Data Documentation

#### 5.25.2.1 uint32\_t ecmdSlotData::slotId

(Detail: Low) Slot number of this entry

#### 5.25.2.2 uint32\_t ecmdSlotData::unitId

(Detail: High) Unit Id of this entry

#### 5.25.2.3 std::list<ecmdChipData> ecmdSlotData::chipData

(Detail: Low) List of all chips requested in this slot - in order by chipType and pos

The documentation for this struct was generated from the following file:

- **ecmdStructs.H**

## 5.26 ecmdSpyData Struct Reference

Used for the ecmdQuerySpy function to return spy info.

```
#include <ecmdStructs.H>
```

### Public Attributes

- **std::string spyName**  
*Names used to reference this spy.*
- **int bitLength**  
*length of spy*
- **ecmdSpyType\_t spyType**  
*Type of spy.*
- **bool isEccChecked**  
*This spy affects some ECC groupings.*
- **bool isEnumerated**  
*This spy has enumerated values.*
- **bool isCoreRelated**  
*This spy is related to the core level of a chip.*
- **std::string clockDomain**  
*Clock domain this spy belongs to.*
- **ecmdClockState\_t clockState**  
*Required clock state to access this spy.*
- **std::list< std::string > enums**  
*Possible enum values for Spy - I/P Can only provide this on a client, not on the FSP.*
- **std::list< std::string > epCheckers**  
*Possible epChecker names affected by this Spy.*

### 5.26.1 Detailed Description

Used for the ecmdQuerySpy function to return spy info.

### 5.26.2 Member Data Documentation

#### 5.26.2.1 std::string ecmdSpyData::spyName

Names used to reference this spy.



**5.26.2.2 int ecmdSpyData::bitLength**

length of spy

**5.26.2.3 ecmdSpyType\_t ecmdSpyData::spyType**

Type of spy.

**5.26.2.4 bool ecmdSpyData::isEccChecked**

This spy affects some ECC groupings.

**5.26.2.5 bool ecmdSpyData::isEnumerated**

This spy has enumerated values.

**5.26.2.6 bool ecmdSpyData::isCoreRelated**

This spy is related to the core level of a chip.

**5.26.2.7 std::string ecmdSpyData::clockDomain**

Clock domain this spy belongs to.

**5.26.2.8 ecmdClockState\_t ecmdSpyData::clockState**

Required clock state to access this spy.

**5.26.2.9 std::list<std::string> ecmdSpyData::enums**

Possible enum values for Spy - I/P Can only provide this on a client, not on the FSP.

**5.26.2.10 std::list<std::string> ecmdSpyData::epCheckers**

Possible epChecker names affected by this Spy.

The documentation for this struct was generated from the following file:

- **ecmdStructs.H**

## 5.27 ecmdSpyGroupData Struct Reference

Used by get/putspy function to create the return data from a group.

```
#include <ecmdStructs.H>
```

### Public Attributes

- **ecmdDataBuffer extractBuffer**  
*The data read from the ring buffer.*
- **ecmdDataBuffer deadbitsMask**  
*A mask of the bits that were deadbits in that buffer.*

### 5.27.1 Detailed Description

Used by get/putspy function to create the return data from a group.

### 5.27.2 Member Data Documentation

#### 5.27.2.1 ecmdDataBuffer ecmdSpyGroupData::extractBuffer

The data read from the ring buffer.

#### 5.27.2.2 ecmdDataBuffer ecmdSpyGroupData::deadbitsMask

A mask of the bits that were deadbits in that buffer.

The documentation for this struct was generated from the following file:

- **ecmdStructs.H**

## 5.28 ecmdThreadData Struct Reference

Used for the ecmdQueryConfig function to return thread data.

```
#include <ecmdStructs.H>
```

### Public Attributes

- **uint8\_t threadId**  
*(Detail: Low) Thread number of this entry*
- **uint32\_t unitId**  
*(Detail: High) Unit Id of this entry*

### 5.28.1 Detailed Description

Used for the ecmdQueryConfig function to return thread data.

Operators Supported : <

### 5.28.2 Member Data Documentation

#### 5.28.2.1 uint8\_t ecmdThreadData::threadId

(Detail: Low) Thread number of this entry

#### 5.28.2.2 uint32\_t ecmdThreadData::unitId

(Detail: High) Unit Id of this entry

The documentation for this struct was generated from the following file:

- **ecmdStructs.H**

## 5.29 ecmdTraceArrayData Struct Reference

Used for the ecmdQueryTraceArray function to return trace array info.

```
#include <ecmdStructs.H>
```

### Public Attributes

- **std::string traceArrayName**  
*(Detail: Low) Name of Trace array*
- **int length**  
*(Detail: Low) Length of trace array (number of entries)*
- **int width**  
*(Detail: Low) Bit width of trace array entry*
- **bool isCoreRelated**  
*(Detail: Low) This tracearray is related to the core level of a chip*
- **std::string clockDomain**  
*(Detail: High) Clock domain this array belongs to*
- **ecmdClockState\_t clockState**  
*(Detail: High) Required clock state to access this array*

### 5.29.1 Detailed Description

Used for the ecmdQueryTraceArray function to return trace array info.

### 5.29.2 Member Data Documentation

#### 5.29.2.1 std::string ecmdTraceArrayData::traceArrayName

(Detail: Low) Name of Trace array

#### 5.29.2.2 int ecmdTraceArrayData::length

(Detail: Low) Length of trace array (number of entries)

#### 5.29.2.3 int ecmdTraceArrayData::width

(Detail: Low) Bit width of trace array entry

#### 5.29.2.4 bool ecmdTraceArrayData::isCoreRelated

(Detail: Low) This tracearray is related to the core level of a chip

**5.29.2.5 std::string ecmdTraceArrayData::clockDomain**

(Detail: High) Clock domain this array belongs to

**5.29.2.6 ecmdClockState\_t ecmdTraceArrayData::clockState**

(Detail: High) Required clock state to access this array

The documentation for this struct was generated from the following file:

- **ecmdStructs.H**



## Chapter 6

# eCMD Perl Module Version Development File Documentation

### 6.1 cipClientPerlapi.H File Reference

Cronus & IP eCMD Perlapi Extension.

```
#include <ecmdReturnCodes.H>
#include <ecmdStructs.H>
#include <ecmdDataBuffer.H>
#include <cipStructs.H>
```

#### Load/Unload Functions

- **int cipInitExtension** (const char \*i\_clientVersion)  
*Initialize eCMD CIP Extension DLL.*

#### Processor Functions

- **uint32\_t cipStartInstructions** (ecmdChipTarget &i\_target)  
*Start Instructions.*
- **uint32\_t cipStartAllInstructions** ()  
*Start Instructions on all configured processors.*
- **uint32\_t cipStartInstructionsSreset** (ecmdChipTarget &i\_target)  
*Start Instructions using an S-Reset.*
- **uint32\_t cipStartAllInstructionsSreset** ()  
*Start Instructions on all configured processors using an S-Reset.*
- **uint32\_t cipStopInstructions** (ecmdChipTarget &i\_target)  
*Stop Instructions.*

- **uint32\_t cipStopAllInstructions ()**  
*Stop All Instructions.*
- **uint32\_t cipStepInstructions (ecmdChipTarget &i\_target, uint32\_t i\_steps)**  
*Step Instructions.*
- **uint32\_t cipSetBreakpoint (ecmdChipTarget &i\_target, uint64\_t i\_address, ecmdBreakpointType\_t &i\_type)**  
*Set a hardware breakpoint in Processor using a real address.*
- **uint32\_t cipClearBreakpoint (ecmdChipTarget &i\_target, uint64\_t i\_address, ecmdBreakpointType\_t &i\_type)**  
*Clear a hardware breakpoint from Processor using a real address.*
- **uint32\_t cipGetVr (ecmdChipTarget &i\_target, uint32\_t i\_vrNum, ecmdDataBuffer &o\_data)**  
*Reads the selected Processor Architected VMX Register (VR) into the data buffer.*
- **uint32\_t cipGetVrMultiple (ecmdChipTarget &i\_target, std::list< ecmdIndexEntry > &i\_entries)**  
*Reads the selected Processor Architected VMX Register (VR) into the data buffers.*
- **uint32\_t cipPutVr (ecmdChipTarget &i\_target, uint32\_t i\_vrNum, ecmdDataBuffer &i\_data)**  
*Writes the data buffer into the selected Processor Architected VMX Register (VR).*
- **uint32\_t cipPutVrMultiple (ecmdChipTarget &i\_target, std::list< ecmdIndexEntry > &i\_entries)**  
*Writes the data buffer into the selected Processor Architected VMX Register (VR).*

## Memory Functions

- **uint32\_t cipGetMemProc (ecmdChipTarget &i\_target, uint64\_t i\_address, uint32\_t i\_bytes, ecmdDataBuffer &o\_memoryData, ecmdDataBuffer &o\_memoryTags, ecmdDataBuffer &o\_memoryEcc, ecmdDataBuffer &o\_memoryEccError)**  
*Reads System Mainstore through the processor chip using a real address.*
- **uint32\_t cipPutMemProc (ecmdChipTarget &i\_target, uint64\_t i\_address, uint32\_t i\_bytes, ecmdDataBuffer &i\_memoryData, ecmdDataBuffer &i\_memoryTags, ecmdDataBuffer &i\_memoryErrorInject)**  
*Writes System Mainstore through the processor chip using a real address.*
- **uint32\_t cipGetMemMemCtrl (ecmdChipTarget &i\_target, uint64\_t i\_address, uint32\_t i\_bytes, ecmdDataBuffer &o\_memoryData, ecmdDataBuffer &o\_memoryTags, ecmdDataBuffer &o\_memoryEcc, ecmdDataBuffer &o\_memoryEccError, ecmdDataBuffer &o\_memorySpareBits)**  
*Reads System Mainstore through the memory controller using a real address.*



- `uint32_t cipPutMemMemCtrl (ecmdChipTarget &i_target, uint64_t i_address, uint32_t i_bytes, ecmdDataBuffer &i_memoryData, ecmdDataBuffer &i_memoryTags, ecmdDataBuffer &i_memoryEcc, ecmdDataBuffer &i_memorySpareBits, ecmdDataBuffer &i_memoryErrorInject)`

*Writes System Mainstore through the memory controller using a real address.*

### 6.1.1 Detailed Description

Cronus & IP eCMD Perlapi Extension.

Extension Owner : Chris Engel

### 6.1.2 Function Documentation

#### 6.1.2.1 `int cipInitExtension (const char * i_clientVersion)`

Initialize eCMD CIP Extension DLL.

**Parameters:**

*i\_clientVersion* Comma seperated list of eCMD Perl api major numbers this script supports, see details

**Return values:**

***ECMD\_SUCCESS*** if successful load

***ECMD\_INVALID\_DLL\_VERSION*** if Dll version loaded doesn't match client version

***nonzero*** if unsuccessful

**Postcondition:**

eCMD CIP Extension is initialized and version checked

VERSIONS : eCMD at times has to make changes to add/remove functionality and parameters to functions. This could cause incompatability in your script if you used functions that have changed. The *i\_clientVersion* string is used to tell eCMD which major releases you support such that your script will not continue execution if it encounters a version that is either not known about or not supported. This is similar to how the eCMD C-API works except in Perl you can support multiple versions with one script as long as the changes that were made between the versions do not affect your script.

USAGE : `if (cipInitExtension("ver3,ver4")) { die "Fatal errors initializing DLL"; }`

#### 6.1.2.2 `uint32_t cipStartInstructions (ecmdChipTarget & i_target)`

Start Instructions.

**Parameters:**

*i\_target* Struct that contains chip and cage/node/slot/position/core/thread information

**Return values:**

***ECMD\_RING\_CACHE\_ENABLED*** Ring Cache enabled function - must be disabled to use this function

***ECMD\_TARGET\_NOT\_CONFIGURED*** if target is not available in the system  
***ECMD\_SUCCESS*** if successful  
***nonzero*** if unsuccessful  
***ECMD\_CLOCKS\_IN\_INVALID\_STATE*** Chip Clocks were in an invalid state to perform the operation  
***ECMD\_INSTRUCTIONS\_IN\_INVALID\_STATE*** Current state of instructions is invalid to perform the operation

TARGET DEPTH : Thread

TARGET STATES : Unused

### 6.1.2.3 uint32\_t cipStartAllInstructions ()

Start Instructions on all configured processors.

#### Return values:

***ECMD\_RING\_CACHE\_ENABLED*** Ring Cache enabled function - must be disabled to use this function  
***ECMD\_SUCCESS*** if successful  
***nonzero*** if unsuccessful  
***ECMD\_CLOCKS\_IN\_INVALID\_STATE*** Chip Clocks were in an invalid state to perform the operation  
***ECMD\_INSTRUCTIONS\_IN\_INVALID\_STATE*** Current state of instructions is invalid to perform the operation

### 6.1.2.4 uint32\_t cipStartInstructionsSreset (ecmdChipTarget & i\_target)

Start Instructions using an S-Reset.

#### Parameters:

***i\_target*** Struct that contains chip and cage/node/slot/position/core/thread information

#### Return values:

***ECMD\_RING\_CACHE\_ENABLED*** Ring Cache enabled function - must be disabled to use this function  
***ECMD\_TARGET\_NOT\_CONFIGURED*** if target is not available in the system  
***ECMD\_SUCCESS*** if successful  
***nonzero*** if unsuccessful  
***ECMD\_CLOCKS\_IN\_INVALID\_STATE*** Chip Clocks were in an invalid state to perform the operation  
***ECMD\_INSTRUCTIONS\_IN\_INVALID\_STATE*** Current state of instructions is invalid to perform the operation

TARGET DEPTH : Thread

TARGET STATES : Unused

**6.1.2.5 uint32\_t cipStartAllInstructionsSreset ()**

Start Instructions on all configured processors using an S-Reset.

**Return values:**

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function

**ECMD\_SUCCESS** if successful

**nonzero** if unsuccessful

**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation

**ECMD\_INSTRUCTIONS\_IN\_INVALID\_STATE** Current state of instructions is invalid to perform the operation

**6.1.2.6 uint32\_t cipStopInstructions (ecmdChipTarget & i\_target)**

Stop Instructions.

**Parameters:**

**i\_target** Struct that contains chip and cage/node/slot/position/core/thread information

**Return values:**

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system

**ECMD\_SUCCESS** if successful

**nonzero** if unsuccessful

**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation

**ECMD\_INSTRUCTIONS\_IN\_INVALID\_STATE** Current state of instructions is invalid to perform the operation

TARGET DEPTH : Thread

TARGET STATES : Unused

**6.1.2.7 uint32\_t cipStopAllInstructions ()**

Stop All Instructions.

**Return values:**

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function

**ECMD\_SUCCESS** if successful

**nonzero** if unsuccessful

**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation

**ECMD\_INSTRUCTIONS\_IN\_INVALID\_STATE** Current state of instructions is invalid to perform the operation

### 6.1.2.8 uint32\_t cipStepInstructions (ecmdChipTarget & i\_target, uint32\_t i\_steps)

Step Instructions.

#### Parameters:

*i\_target* Struct that contains chip and cage/node/slot/position/core/thread information

*i\_steps* Number of steps to execute

#### Return values:

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system

**ECMD\_SUCCESS** if successful

**nonzero** if unsuccessful

**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation

**ECMD\_INSTRUCTIONS\_IN\_INVALID\_STATE** Current state of instructions is invalid to perform the operation

TARGET DEPTH : Thread

TARGET STATES : Unused

### 6.1.2.9 uint32\_t cipSetBreakpoint (ecmdChipTarget & i\_target, uint64\_t i\_address, ecmdBreakpointType\_t & i\_type)

Set a hardware breakpoint in Processor using a real address.

#### Parameters:

*i\_target* Struct that contains chip and cage/node/slot/position/core/thread information

*i\_address* Address to set breakpoint at

*i\_type* Type of breakpoint to set

#### Return values:

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function

**ECMD\_SUCCESS** if successful

**nonzero** if unsuccessful

**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation

TARGET DEPTH : Core

TARGET STATES : Unused

### 6.1.2.10 uint32\_t cipClearBreakpoint (ecmdChipTarget & *i\_target*, uint64\_t *i\_address*, ecmdBreakpointType\_t & *i\_type*)

Clear a hardware breakpoint from Processor using a real address.

#### Parameters:

- i\_target* Struct that contains chip and cage/node/slot/position/core/thread information
- i\_address* Address to clear breakpoint at
- i\_type* Type of breakpoint to set

#### Return values:

- ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system
- ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function
- ECMD\_SUCCESS** if successful
- nonzero** if unsuccessful
- ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation

TARGET DEPTH : Core

TARGET STATES : Unused

### 6.1.2.11 uint32\_t cipGetVr (ecmdChipTarget & *i\_target*, uint32\_t *i\_vrNum*, ecmdDataBuffer & *o\_data*)

Reads the selected Processor Architected VMX Register (VR) into the data buffer.

#### Return values:

- ECMD\_TARGET\_INVALID\_TYPE** if target is not a processor
- ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system
- ECMD\_INVALID\_ARGS** Vr number is invalid
- ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation
- ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function
- ECMD\_SUCCESS** if successful read
- nonzero** if unsuccessful

#### Parameters:

- i\_target* Struct that contains chip and cage/node/slot/position/core/thread information
- i\_vrNum* Number of vr to read from
- o\_data* DataBuffer object that holds data read from vr

TARGET DEPTH : Core

TARGET STATES : Unused

### 6.1.2.12 uint32\_t cipGetVrMultiple (ecmdChipTarget & i\_target, std::list<ecmdIndexEntry > & io\_entries)

Reads the selected Processor Architected VMX Register (VR) into the data buffers.

#### Return values:

**ECMD\_TARGET\_INVALID\_TYPE** if target is not a processor  
**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_INVALID\_ARGS** Vr number is invalid  
**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation  
**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function  
**ECMD\_SUCCESS** if successful read  
**nonzero** if unsuccessful

#### Parameters:

**i\_target** Struct that contains chip and cage/node/slot/position/core/thread information  
**io\_entries** List of entries to fetch **ecmdIndexEntry.index**(p. 71) field must be filled in

The return value of this function is set to the first non-zero return code found when retrieving multiple entries. The entry that caused the failure in the list will also be marked with the same return code. That data and all subsequent entries in the list will not be fetched and the data should be considered invalid.

TARGET DEPTH : Core

TARGET STATES : Unused

### 6.1.2.13 uint32\_t cipPutVr (ecmdChipTarget & i\_target, uint32\_t i\_vrNum, ecmdDataBuffer & i\_data)

Writes the data buffer into the selected Processor Architected VMX Register (VR).

#### Return values:

**ECMD\_TARGET\_INVALID\_TYPE** if target is not a processor  
**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_INVALID\_ARGS** Vr number is invalid  
**ECMD\_SUCCESS** if successful  
**ECMD\_DATA\_OVERFLOW** Too much data was provided for a write  
**ECMD\_DATA\_UNDERFLOW** Too little data was provided to a write function  
**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disaled to use this function  
**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation  
**nonzero** if unsuccessful

#### Parameters:

**i\_target** Struct that contains chip and cage/node/slot/position/core/thread information

*i\_vrNum* Number of vr to write to

*i\_data* DataBuffer object that holds data to write into vr

TARGET DEPTH : Core

TARGET STATES : Unused

#### 6.1.2.14 uint32\_t cipPutVrMultiple (ecmdChipTarget & i\_target, std::list< ecmdIndexEntry > & i\_entries)

Writes the data buffer into the selected Processor Architected VMX Register (VR).

##### Return values:

**ECMD\_TARGET\_INVALID\_TYPE** if target is not a processor

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system

**ECMD\_INVALID\_ARGS** Vr number is invalid

**ECMD\_SUCCESS** if successful

**ECMD\_DATA\_OVERFLOW** Too much data was provided for a write

**ECMD\_DATA\_UNDERFLOW** Too little data was provided to a write function

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function

**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation

**nonzero** if unsuccessful

##### Parameters:

*i\_target* Struct that contains chip and cage/node/slot/position/core/thread information

*i\_entries* List of entries to write all **ecmdIndexEntry**(p. 71) fields must be filled in

The return value of this function is set to the first non-zero return code found when writing multiple entries. The function will NOT continue through all subsequent entries.

TARGET DEPTH : Core

TARGET STATES : Unused

#### 6.1.2.15 uint32\_t cipGetMemProc (ecmdChipTarget & i\_target, uint64\_t i\_address, uint32\_t i\_bytes, ecmdDataBuffer & o\_memoryData, ecmdDataBuffer & o\_memoryTags, ecmdDataBuffer & o\_memoryEcc, ecmdDataBuffer & o\_memoryEccError)

Reads System Mainstore through the processor chip using a real address.

##### Return values:

**ECMD\_TARGET\_INVALID\_TYPE** if target is not a processor

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function

**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation

***ECMD\_INVALID\_MEMORY\_ADDRESS*** Memory Address was not on a 8-byte boundary

***ECMD\_SUCCESS*** if successful read

***nonzero*** if unsuccessful

**Parameters:**

***i\_target*** Struct that contains chip and cage/node/slot/position information

***i\_address*** Starting address to read from

***i\_bytes*** Number of bytes to write

***o\_memoryData*** DataBuffer object that holds data read from memory

***o\_memoryTags*** 1 Tag bit for every 64 bits of memory data

***o\_memoryEcc*** 8 ECC bits for every 64 bits of memory data

***o\_memoryEccError*** 1 ECC Error bit for every 64 bits of memory data

NOTE : This function requires that the address be aligned on a 64 bit boundary

TARGET DEPTH : Pos

TARGET STATES : Unused

**6.1.2.16** `uint32_t cipPutMemProc (ecmdChipTarget & i_target, uint64_t i_address, uint32_t i_bytes, ecmdDataBuffer & i_memoryData, ecmdDataBuffer & i_memoryTags, ecmdDataBuffer & i_memoryErrorInject)`

Writes System Mainstore through the processor chip using a real address.

**Return values:**

***ECMD\_TARGET\_INVALID\_TYPE*** if target is not a processor

***ECMD\_TARGET\_NOT\_CONFIGURED*** if target is not available in the system

***ECMD\_RING\_CACHE\_ENABLED*** Ring Cache enabled function - must be disabled to use this function

***ECMD\_CLOCKS\_IN\_INVALID\_STATE*** Chip Clocks were in an invalid state to perform the operation

***ECMD\_INVALID\_MEMORY\_ADDRESS*** Memory Address was not on a 8-byte boundary

***ECMD\_SUCCESS*** if successful

***nonzero*** if unsuccessful

**Parameters:**

***i\_target*** Struct that contains chip and cage/node/slot/position information

***i\_address*** Starting address to write to

***i\_bytes*** Number of bytes to write

***i\_memoryData*** DataBuffer object that holds data to write into memory

***i\_memoryTags*** 1 Tag bit for every 64 bits of memory data (If this has length of zero, the user wants the HW to generate this info; otherwise, use their values.)

***i\_memoryErrorInject*** 2 Error Inject bits for every 64 bits of memory data (If this has a length of zero, no error inject; otherwise 0b00, 0x11 no error inject, 0b01 single-bit error inject, 0b10 double-bit error inject.)



NOTE : This function requires that the address be aligned on a 64 bit boundary

TARGET DEPTH : Pos

TARGET STATES : Unused

**6.1.2.17** `uint32_t cipGetMemMemCtrl (ecmdChipTarget & i_target, uint64_t i_address, uint32_t i_bytes, ecmdDataBuffer & o_memoryData, ecmdDataBuffer & o_memoryTags, ecmdDataBuffer & o_memoryEcc, ecmdDataBuffer & o_memoryEccError, ecmdDataBuffer & o_memorySpareBits)`

Reads System Mainstore through the memory controller using a real address.

**Return values:**

**ECMD\_TARGET\_INVALID\_TYPE** if target is not a memory controller

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function

**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation

**ECMD\_INVALID\_MEMORY\_ADDRESS** Memory Address was not on a 8-byte boundary

**ECMD\_SUCCESS** if successful read

**nonzero** if unsuccessful

**Parameters:**

**i\_target** Struct that contains chip and cage/node/slot/position information

**i\_address** Starting address to read from

**i\_bytes** Number of bytes to write

**o\_memoryData** DataBuffer object that holds data read from memory

**o\_memoryTags** 2 Tag bits for every 32 bytes of memory data

**o\_memoryEcc** 24 ECC bits for every 32 bytes of memory data

**o\_memoryEccError** 1 ECC Error bit for every 32 bytes of memory data

**o\_memorySpareBits** 2 Spare bits for every 32 bytes of memory data

NOTE : This function requires that the address be aligned on a 32-byte boundary

TARGET DEPTH : Cage

TARGET STATES : Unused

**6.1.2.18** `uint32_t cipPutMemMemCtrl (ecmdChipTarget & i_target, uint64_t i_address, uint32_t i_bytes, ecmdDataBuffer & i_memoryData, ecmdDataBuffer & i_memoryTags, ecmdDataBuffer & i_memoryEcc, ecmdDataBuffer & i_memorySpareBits, ecmdDataBuffer & i_memoryErrorInject)`

Writes System Mainstore through the memory controller using a real address.

**Return values:**

***ECMD\_TARGET\_INVALID\_TYPE*** if target is not a memory controller  
***ECMD\_TARGET\_NOT\_CONFIGURED*** if target is not available in the system  
***ECMD\_RING\_CACHE\_ENABLED*** Ring Cache enabled function - must be disabled to use this function  
***ECMD\_CLOCKS\_IN\_INVALID\_STATE*** Chip Clocks were in an invalid state to perform the operation  
***ECMD\_INVALID\_MEMORY\_ADDRESS*** Memory Address was not on a 8-byte boundary  
***ECMD\_SUCCESS*** if successful  
***nonzero*** if unsuccessful

**Parameters:**

***i\_target*** Struct that contains chip and cage/node/slot/position information  
***i\_address*** Starting address to write to  
***i\_bytes*** Number of bytes to write  
***i\_memoryData*** DataBuffer object that holds data to write into memory  
***i\_memoryTags*** [Optional] 2 Tag bits for every 32 bytes of memory data  
***i\_memoryEcc*** 24 ECC bits for every 32 bytes of memory data  
***i\_memorySpareBits*** [Optional] 2 Spare bits for every 32 bytes of memory data  
***i\_memoryErrorInject*** 2 Error Inject bits for every 64 bits of memory data (If this has a length of zero, no error inject; otherwise 0b00, 0x11 no error inject, 0b01 single-bit error inject, 0b10 double-bit error inject.)

NOTE : This function requires that the address be aligned on a 32-byte boundary

NOTE : If *ecmdDataBuffers* for *i\_memoryTags* and *i\_memorySpareBits* have a length of zero, the user wants the HW to generate this info. If these *ecmdDataBuffers* have a length, the the user wants their values to be used.

TARGET DEPTH : Cage

TARGET STATES : Unused

## 6.2 cmdClientPerlapi.H File Reference

Command Line eCMD Perlapi Extension.

```
#include <ecmdReturnCodes.H>
#include <ecmdStructs.H>
#include <ecmdDataBuffer.H>
#include <cmdStructs.H>
```

### Load/Unload Functions

- **int cmdInitExtension** (const char \*i\_clientVersion)  
*Initialize eCMD CMD Extension.*

### Functions

- **uint32\_t cmdRunCommand** (std::string i\_command)  
*Run the command line command passed in , output goes to stdout and is not returned.*
- **uint32\_t cmdRunCommandCaptureOutput** (std::string i\_command, std::string &o\_output)  
*Run the command line command passed in , stdout is captured and returned.*

### 6.2.1 Detailed Description

Command Line eCMD Perlapi Extension.

Extension Owner : Chris Engel

### 6.2.2 Function Documentation

#### 6.2.2.1 int cmdInitExtension (const char \* i\_clientVersion)

Initialize eCMD CMD Extension.

##### Parameters:

**i\_clientVersion** Comma seperated list of eCMD Perl api major numbers this script supports, see details

##### Return values:

**ECMD\_SUCCESS** if successful load

**ECMD\_INVALID\_DLL\_VERSION** if Dll version loaded doesn't match client version

**nonzero** if unsuccessful

##### Postcondition:

eCMD CIP Extension is initialized and version checked

VERSIONS : eCMD at times has to make changes to add/remove functionality and parameters to functions. This could cause incompatibility in your script if you used functions that have changed. The `i_clientVersion` string is used to tell eCMD which major releases you support such that your script will not continue execution if it encounters a version that is either not known about or not supported. This is similar to how the eCMD C-API works except in Perl you can support multiple versions with one script as long as the changes that were made between the versions do not affect your script.

USAGE : `if (cmdInitExtension("ver3,ver4")) { die "Fatal errors initializing DLL"; }`

#### 6.2.2.2 `uint32_t cmdRunCommand (std::string i_command)`

Run the command line command passed in , output goes to stdout and is not returned.

##### Parameters:

*i\_command* Command to pass to interpreter, ie 'ecmdquery version'

##### Return values:

*ECMD\_SUCCESS* if successful load

*nonzero* if unsuccessful

#### 6.2.2.3 `uint32_t cmdRunCommandCaptureOutput (std::string i_command, std::string & o_output)`

Run the command line command passed in , stdout is captured and returned.

##### Parameters:

*i\_command* Command to pass to interpreter, ie 'ecmdquery version'

*o\_output* Standard out from running command

##### Return values:

*ECMD\_SUCCESS* if successful load

*nonzero* if unsuccessful

## 6.3 croClientPerlapi.H File Reference

Cronus eCMD Perlapi Extension.

```
#include <ecmdReturnCodes.H>
#include <ecmdStructs.H>
#include <ecmdDataBuffer.H>
#include <croStructs.H>
```

### Load/Unload Functions

- **int croInitExtension** (const char \*\_i\_clientVersion)  
*Initialize eCMD CRO Extension DLL.*

### Misc Functions

- **uint32\_t croReset** ()  
*Reset Cronus internal state variables.*
- **uint32\_t croDisplayVersion** ()  
*Display the Cronus version information to stdout.*
- **uint32\_t croSetDebug** (char i\_major, char i\_minor= '1')  
*Set a Cronus debug flag -debug.*
- **uint32\_t croClearDebug** (char i\_major, char i\_minor= '1')  
*Clear a Cronus debug flag -debug.*
- **bool croIsDebugOn** (char i\_major, char i\_minor= '1')  
*Checks whether Cronus debug flag is set.*

### JTAG Scan Functions

- **uint32\_t croJtagScanRead** (ecmdChipTarget &i\_target, int i\_bitlength, ecmdDataBuffer &o\_data, croJtagScanMode i\_mode=CRO\_JTAG\_SHIFTDR)  
*Perform a scan operation on the chip and sample TDO.*
- **uint32\_t croJtagScanWrite** (ecmdChipTarget &i\_target, int i\_bitlength, ecmdDataBuffer &i\_data, croJtagScanMode i\_mode=CRO\_JTAG\_SHIFTDR)  
*Perform a scan operation on the chip and drive TDI.*
- **uint32\_t croJtagScanReadWrite** (ecmdChipTarget &i\_target, int i\_bitlength, ecmdDataBuffer &i\_data, ecmdDataBuffer &o\_data, croJtagScanMode i\_mode=CRO\_JTAG\_SHIFTDR)  
*Perform a scan operation on the chip and drive TDI and sample TDO on same cycle.*

## L2 Functions

- `uint32_t croFastLoadL2 (ecmdChipTarget &i_target, std::list< ecmdMemoryEntry > &i_data, const char *o_ringFile=NULL)`  
*Load the provided data into L2 using the fast load mechanism.*
- `uint32_t croFastLoadL2RingImage (ecmdChipTarget &i_target, const char *i_ringFile)`  
*Load the provided data into L2 using the fast load mechanism with a prebuilt ring image file.*
- `uint32_t croRamInstruction (ecmdChipTarget &i_target, const char *i_instructionDecode)`  
*Ram a particular instruction decode in Echlipz P6.*
- `uint32_t croGetL2 (ecmdChipTarget &i_target, uint64_t i_address, croL2Fields &i_l2fields, ecmdDataBuffer &o_data)`  
*Displays cache lines from Level 2 processor cache.*
- `uint32_t croGetL2Data (ecmdChipTarget &i_target, croL2Fields &i_l2fields, ecmdDataBuffer &o_data)`  
*Displays cache lines from Level 2 processor cache data.*
- `uint32_t croGetL2Dir (ecmdChipTarget &i_target, croL2Fields &i_l2fields, ecmdDataBuffer &o_data)`  
*Displays Level 2 processor cache directory entry.*
- `uint32_t croGetL2Tag (ecmdChipTarget &i_target, uint64_t i_address, croL2Fields &i_l2fields, ecmdDataBuffer &o_data)`  
*Displays Level 2 processor cache tag bit per quadword basis.*
- `uint32_t croPutL2 (ecmdChipTarget &i_target, uint64_t i_address, croL2Fields &i_l2fields, ecmdDataBuffer &i_data)`  
*Replace Level 2 processor cache line.*
- `uint32_t croPutL2Data (ecmdChipTarget &i_target, croL2Fields &i_l2fields, ecmdDataBuffer &i_data)`  
*Replace a full Level 2 processor data cache line.*
- `uint32_t croPutL2Dir (ecmdChipTarget &i_target, croL2Fields &i_l2fields, ecmdDataBuffer &i_data)`  
*Replace a full Level 2 processor directory cache entry.*
- `uint32_t croPutL2Tag (ecmdChipTarget &i_target, uint64_t i_address, croL2Fields &i_l2fields)`  
*Put the L2 tag bit for the quadword beginning at the given address.*

## Functions

- `uint32_t croGetConfiguration (ecmdChipTarget &i_target, std::string i_name, ecmdConfigValid_t &o_validOutput, std::string &o_valueAlpha, uint32_t &o_valueNumeric)`

*Retrieve the value of a Configuration Setting - Cronus version.*

- `uint32_t croSetConfiguration (ecmdChipTarget &i_target, std::string i_name, ecmd-ConfigValid_t i_validInput, std::string i_valueAlpha, uint32_t i_valueNumeric)`

*Set the value of a Configuration Setting - Cronus version.*

### 6.3.1 Detailed Description

Cronus eCMD Perlapi Extension.

Extension Owner : Chris Engel

### 6.3.2 Function Documentation

#### 6.3.2.1 `int croInitExtension (const char * i_clientVersion)`

Initialize eCMD CRO Extension DLL.

**Parameters:**

*i\_clientVersion* Comma seperated list of eCMD Perl api major numbers this script supports, see details

**Return values:**

*ECMD\_SUCCESS* if successful load

*ECMD\_INVALID\_DLL\_VERSION* if Dll version loaded doesn't match client version

*nonzero* if unsuccessful

**Postcondition:**

eCMD CRO Extension is initialized and version checked

VERSIONS : eCMD at times has to make changes to add/remove functionality and parameters to functions. This could cause incompatibility in your script if you used functions that have changed. The *i\_clientVersion* string is used to tell eCMD which major releases you support such that your script will not continue execution if it encounters a version that is either not known about or not supported. This is similar to how the eCMD C-API works except in Perl you can support multiple versions with one script as long as the changes that were made between the versions do not affect your script.

USAGE : `if (croInitExtension("ver3,ver4")) { die "Fatal errors initializing DLL"; }`

#### 6.3.2.2 `uint32_t croReset ()`

Reset Cronus internal state variables.

**Return values:**

*ECMD\_SUCCESS* if successful

*nonzero* if unsuccessful

**Postcondition:**

All internal Cronus data is cleared, config file is reread and Cronus is reinitialized

### 6.3.2.3 uint32\_t croDisplayVersion ()

Display the Cronus version information to stdout.

**Return values:**

*ECMD\_SUCCESS* if successful

*nonzero* if unsuccessful

NOTE : This is equivalent to 'croquery version'

### 6.3.2.4 uint32\_t croSetDebug (char i\_major, char i\_minor = '1')

Set a Cronus debug flag -debug.

**Parameters:**

*i\_major* Major debug char

*i\_minor* Minor debug char

**Return values:**

*ECMD\_SUCCESS* if successful

*nonzero* if unsuccessful

NOTE : To set all minor's of a particular major, set i\_minor = '0'

NOTE : debug 5 == 5.1 (hence the default minor number if not specified is 1)

### 6.3.2.5 uint32\_t croClearDebug (char i\_major, char i\_minor = '1')

Clear a Cronus debug flag -debug.

**Parameters:**

*i\_major* Major debug char

*i\_minor* Minor debug char

**Return values:**

*ECMD\_SUCCESS* if successful

*nonzero* if unsuccessful

NOTE : To clear all minor's of a particular major, set i\_minor = '0'

NOTE : debug 5 == 5.1 (hence the default minor number if not specified is 1)

### 6.3.2.6 bool croIsDebugEnabled (char i\_major, char i\_minor = '1')

Checks whether Cronus debug flag is set.

**Parameters:**

*i\_major* Major debug char

*i\_minor* Minor debug char



**Return values:**

*true* if debug is on  
*false* if debug is off

NOTE : To check if any minor of a particular major is on, set i\_minor = '0'

NOTE : debug 5 == 5.1 (hence the default minor number if not specified is 1

**6.3.2.7** `uint32_t croJtagScanRead (ecmdChipTarget & i_target, int i_bitlength, ecmdDataBuffer & o_data, croJtagScanMode i_mode = CRO_JTAG_SHIFTDR)`

Perform a scan operation on the chip and sample TDO.

**Parameters:**

*i\_target* Struct that contains chip and cage/node/slot/position information  
*o\_data* Output from TDO  
*i\_bitlength* Bit Length to shift scan chain  
*i\_mode* Scan mode settings

**Return values:**

*ECMD\_SUCCESS* if successful  
*nonzero* if unsuccessful

NOTE : This function assumes the user has sent in the appropriate scan instruction

NOTE : The chain is shifted for the exact length of i\_bitlength

TARGET DEPTH : Pos

TARGET STATES : Unused

**6.3.2.8** `uint32_t croJtagScanWrite (ecmdChipTarget & i_target, int i_bitlength, ecmdDataBuffer & i_data, croJtagScanMode i_mode = CRO_JTAG_SHIFTDR)`

Perform a scan operation on the chip and drive TDI.

**Parameters:**

*i\_target* Struct that contains chip and cage/node/slot/position information  
*i\_data* Input to drive on TDI  
*i\_bitlength* Bit Length to shift scan chain  
*i\_mode* Scan mode settings

**Return values:**

*ECMD\_SUCCESS* if successful  
*nonzero* if unsuccessful

NOTE : This function assumes the user has sent in the appropriate scan instruction

NOTE : The chain is shifted for the exact length of i\_bitlength

TARGET DEPTH : Pos

TARGET STATES : Unused

**6.3.2.9** `uint32_t croJtagScanReadWrite (ecmdChipTarget & i_target, int i_bitlength, ecmdDataBuffer & i_data, ecmdDataBuffer & o_data, croJtagScanMode i_mode = CRO_JTAG_SHIFTDR)`

Perform a scan operation on the chip and drive TDI and sample TDO on same cycle.

**Parameters:**

*i\_target* Struct that contains chip and cage/node/slot/position information  
*i\_data* Input to drive on TDI  
*o\_data* Output from TDO  
*i\_bitlength* Bit Length to shift scan chain  
*i\_mode* Scan mode settings

**Return values:**

*ECMD\_SUCCESS* if successful  
*nonzero* if unsuccessful

NOTE : This function assumes the user has sent in the appropriate scan instruction

NOTE : The chain is shifted for the exact length of *i\_bitlength*

TARGET DEPTH : Pos

TARGET STATES : Unused

**6.3.2.10** `uint32_t croGetConfiguration (ecmdChipTarget & i_target, std::string i_name, ecmdConfigValid_t & o_validOutput, std::string & o_valueAlpha, uint32_t & o_valueNumeric)`

Retrieve the value of a Configuration Setting - Cronus version.

**Parameters:**

*i\_target* struct that contains chip and cage/node/slot/position/core information if necessary  
*i\_name* Name of setting as defined by eCMD Api  
*o\_validOutput* Indicator if *o\_valueAlpha*, *o\_valueNumeric* (or both) are valid.  
*o\_valueAlpha* Alpha value of setting (if appropriate)  
*o\_valueNumeric* Numeric value of setting (if appropriate)

**Return values:**

*ECMD\_INVALID\_CONFIG\_NAME* Name specified is not valid  
*ECMD\_TARGET\_NOT\_CONFIGURED* if target is not available in the system  
*ECMD\_SUCCESS* if successful

TARGET DEPTH : Thread

TARGET STATES : Unused

### 6.3.2.11 `uint32_t croSetConfiguration (ecmdChipTarget & i_target, std::string i_name, ecmdConfigValid_t i_validInput, std::string i_valueAlpha, uint32_t i_valueNumeric)`

Set the value of a Configuration Setting - Cronus version.

#### Parameters:

- i\_target* struct that contains chip and cage/node/slot/position/core information if necessary
- i\_name* Name of setting as defined by eCMD Api
- i\_validInput* Indicator if i\_valueAlpha, i\_valueNumeric (or both) are valid.
- i\_valueAlpha* Alpha value of setting (if appropriate)
- i\_valueNumeric* Numeric value of setting (if appropriate)

#### Return values:

- ECMD\_DBUF\_INVALID\_DATA\_FORMAT** Value is not in correct format for specified configuration setting
- ECMD\_INVALID\_CONFIG\_NAME** Name specified is not valid
- ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system
- ECMD\_SUCCESS** if successful
- nonzero** on failure

TARGET DEPTH : Thread

TARGET STATES : Unused

### 6.3.2.12 `uint32_t croFastLoadL2 (ecmdChipTarget & i_target, std::list<ecmdMemoryEntry > & i_data, const char * o_ringFile = NULL)`

Load the provided data into L2 using the fast load mechanism.

#### Parameters:

- i\_target* struct that contains chip and cage/node/slot/position information if necessary
- i\_data* List of DataBuffer objects that holds data to write into l2
- o\_ringFile* Optional : Output filename to store ring images for later use with croFastLoadL2RingImage

#### Return values:

- ECMD\_SUCCESS** if successful
- nonzero** if unsuccessful

TARGET DEPTH : Pos

TARGET STATES : Unused

### 6.3.2.13 `uint32_t croFastLoadL2RingImage (ecmdChipTarget & i_target, const char * i_ringFile)`

Load the provided data into L2 using the fast load mechanism with a prebuilt ring image file.

**Parameters:**

*i\_target* struct that contains chip and cage/node/slot/position information if necessary  
*i\_ringFile* Filename to read ring images from, previously built from croFastLoadL2

**Return values:**

*ECMD\_SUCCESS* if successful  
*nonzero* if unsuccessful

TARGET DEPTH : Pos

TARGET STATES : Unused

**6.3.2.14** `uint32_t croRamInstruction (ecmdChipTarget & i_target, const char * i_instructionDecode)`

Ram a particular instruction decode in Eclipz P6.

**Parameters:**

*i\_target* struct that contains chip and cage/node/slot/position information if necessary  
*i\_instructionDecode* Decode of instruction to run ie 'addi G7,G3,0x0000'

**Return values:**

*ECMD\_SUCCESS* if successful  
*nonzero* if unsuccessful

TARGET DEPTH : Core

TARGET STATES : Unused

**6.3.2.15** `uint32_t croGetL2 (ecmdChipTarget & i_target, uint64_t i_address, croL2Fields & i_l2fields, ecmdDataBuffer & o_data)`

Displays cache lines from Level 2 processor cache.

**Parameters:**

*i\_target* struct that contains chip and cage/node/slot/position information if necessary  
*i\_address* Real address(0:63) from which to get data  
*i\_l2fields* Struct that holds L2 cache fields  
*o\_data* DataBuffer object that holds cache line data

**Return values:**

*ECMD\_SUCCESS* if successful  
*nonzero* if unsuccessful

TARGET DEPTH : Pos

TARGET STATES : Unused

### 6.3.2.16 `uint32_t croGetL2Data (ecmdChipTarget & i_target, croL2Fields & i_l2fields, ecmdDataBuffer & o_data)`

Displays cache lines from Level 2 processor cache data.

**Parameters:**

*i\_target* struct that contains chip and cage/node/slot/position information if necessary

*i\_l2fields* Struct that holds L2 cache fields

*o\_data* DataBuffer object that holds cache line data

**Return values:**

*ECMD\_SUCCESS* if successful

*nonzero* if unsuccessful

TARGET DEPTH : Pos

TARGET STATES : Unused

### 6.3.2.17 `uint32_t croGetL2Dir (ecmdChipTarget & i_target, croL2Fields & i_l2fields, ecmdDataBuffer & o_data)`

Displays Level 2 processor cache directory entry.

**Parameters:**

*i\_target* struct that contains chip and cage/node/slot/position information if necessary

*i\_l2fields* Struct that holds L2 cache fields

*o\_data* DataBuffer object that holds cache directory data

**Return values:**

*ECMD\_SUCCESS* if successful

*nonzero* if unsuccessful

TARGET DEPTH : Pos

TARGET STATES : Unused

### 6.3.2.18 `uint32_t croGetL2Tag (ecmdChipTarget & i_target, uint64_t i_address, croL2Fields & i_l2fields, ecmdDataBuffer & o_data)`

Displays Level 2 processor cache tag bit per quadword basis.

**Parameters:**

*i\_target* struct that contains chip and cage/node/slot/position information if necessary

*i\_address* Starting real address(0:63) from which to get tag data

*i\_l2fields* Struct that holds L2 cache fields

*o\_data* DataBuffer object that holds tag bits

**Return values:**

*ECMD\_SUCCESS* if successful

*nonzero* if unsuccessful

TARGET DEPTH : Pos

TARGET STATES : Unused

### 6.3.2.19 `uint32_t croPutL2 (ecmdChipTarget & i_target, uint64_t i_address, croL2Fields & i_l2fields, ecmdDataBuffer & i_data)`

Replace Level 2 processor cache line.

#### Parameters:

*i\_target* struct that contains chip and cage/node/slot/position information if necessary  
*i\_address* Real address(0:63) to which to get write data  
*i\_l2fields* Struct that holds L2 cache fields  
*i\_data* DataBuffer object that holds cache data to be written

#### Return values:

*ECMD\_SUCCESS* if successful  
*nonzero* if unsuccessful

TARGET DEPTH : Pos

TARGET STATES : Unused

### 6.3.2.20 `uint32_t croPutL2Data (ecmdChipTarget & i_target, croL2Fields & i_l2fields, ecmdDataBuffer & i_data)`

Replace a full Level 2 processor data cache line.

#### Parameters:

*i\_target* struct that contains chip and cage/node/slot/position information if necessary  
*i\_l2fields* Struct that holds L2 cache fields  
*i\_data* DataBuffer object that holds cache data to be written

#### Return values:

*ECMD\_SUCCESS* if successful  
*nonzero* if unsuccessful

TARGET DEPTH : Pos

TARGET STATES : Unused

### 6.3.2.21 `uint32_t croPutL2Dir (ecmdChipTarget & i_target, croL2Fields & i_l2fields, ecmdDataBuffer & i_data)`

Replace a full Level 2 processor directory cache entry.

#### Parameters:

*i\_target* struct that contains chip and cage/node/slot/position information if necessary  
*i\_l2fields* Struct that holds L2 cache fields  
*i\_data* DataBuffer object that holds cache data to be written

#### Return values:

*ECMD\_SUCCESS* if successful  
*nonzero* if unsuccessful

TARGET DEPTH : Pos

TARGET STATES : Unused

### 6.3.2.22 uint32\_t croPutL2Tag (ecmdChipTarget & *i\_target*, uint64\_t *i\_address*, croL2Fields & *i\_l2fields*)

Put the L2 tag bit for the quadword beginning at the given address.

**Parameters:**

*i\_target* struct that contains chip and cage/node/slot/position information if necessary

*i\_address* Real address(0:63) (in hex) to put L2 tag data

*i\_l2fields* Struct that holds L2 cache fields

**Return values:**

*ECMD\_SUCCESS* if successful

*nonzero* if unsuccessful

TARGET DEPTH : Pos

TARGET STATES : Unused

## 6.4 ecmdClientPerlapi.H File Reference

eCMD Perl API Usage :

```
#include <string>
#include <ecmdStructs.H>
#include <ecmdDataBuffer.H>
#include <ecmdReturnCodes.H>
```

### Load/Unload Functions

- **int ecmdLoadDll** (const char \*i\_dllName, const char \*i\_clientVersion)  
*Initialize the eCMD DLL.*
- **void ecmdUnloadDll** ()  
*Clean up the Perl Module - MUST BE CALLED JUST BEFORE SCRIPT EXIT.*
- **int ecmdCommandArgs** (char \*\*io\_argv)  
*Pass any unknown command line paramaters to the DLL for processing (ex. -p#, Cronus - debug).*

### Error Handling Functions

- **void ecmdEnablePerlSafeMode** ()  
*Enable Perl Error Handling Safe Mode - Croak on any eCMD error (default is enabled).*
- **void ecmdDisablePerlSafeMode** ()  
*Disable Perl Error Handling Safe Mode - Return eCMD errors to client (default is enabled).*

### Command Line Parsing Functions

- **bool ecmdParseOption** (char \*\*io\_argv, const char \*i\_option)  
*Iterates over argv, looking for given option string, removes it if found.*
- **char \* ecmdParseOptionWithArgs** (char \*\*io\_argv, const char \*i\_option)  
*Iterates over argv, looking for given option string, removes it if found.*

### Query Functions

- **uint32\_t ecmdQueryDllInfo** (ecmdDllInfo &o\_dllInfo)  
*Query information about the Dll that is loaded.*
- **bool ecmdQueryVersionGreater** (const char \*version)  
*Query to see if plugin is greater or equal to release specified.*



- `uint32_t ecmdQueryConfig (ecmdChipTarget &i_target, ecmdQueryData &o_queryData, ecmdQueryDetail_t i_detail=ECMD_QUERY_DETAIL_HIGH)`  
*Query configuration information from the DLL.*
- `uint32_t ecmdQuerySelected (ecmdChipTarget &i_target, ecmdQueryData &o_queryData, ecmdConfigLoopType_t i_looptype=ECMD_SELECTED_TARGETS_LOOP)`  
*Query User Selected Targeting information from the DLL, i.e (-p#,-c#,-t#).*
- `uint32_t ecmdQueryRing (ecmdChipTarget &i_target, std::list< ecmdRingData > &o_queryData, const char *i_ringName=NULL, ecmdQueryDetail_t i_detail=ECMD_QUERY_DETAIL_HIGH)`  
*Query Ring information from the DLL.*
- `uint32_t ecmdQueryLatch (ecmdChipTarget &i_target, std::list< ecmdLatchData > &o_queryData, ecmdLatchMode_t i_mode, const char *i_latchName, const char *i_ringName=NULL, ecmdQueryDetail_t i_detail=ECMD_QUERY_DETAIL_HIGH)`  
*Query Latch information from the DLL.*
- `uint32_t ecmdQueryArray (ecmdChipTarget &i_target, std::list< ecmdArrayData > &o_queryData, const char *i_arrayName=NULL, ecmdQueryDetail_t i_detail=ECMD_QUERY_DETAIL_HIGH)`  
*Query Array information from the DLL.*
- `uint32_t ecmdQuerySpy (ecmdChipTarget &i_target, std::list< ecmdSpyData > &o_queryData, const char *i_spyName=NULL, ecmdQueryDetail_t i_detail=ECMD_QUERY_DETAIL_HIGH)`  
*Query Spy information from the DLL.*
- `uint32_t ecmdQueryScom (ecmdChipTarget &i_target, std::list< ecmdScomData > &o_queryData, uint32_t i_address=0xFFFFFFFF, ecmdQueryDetail_t i_detail=ECMD_QUERY_DETAIL_HIGH)`  
*Query Scom information from the DLL.*
- `uint32_t ecmdQueryTraceArray (ecmdChipTarget &i_target, std::list< ecmdTraceArrayData > &o_queryData, const char *i_traceArrayName=NULL, ecmdQueryDetail_t i_detail=ECMD_QUERY_DETAIL_HIGH)`  
*Query Trace Array information from the DLL.*
- `uint32_t ecmdQueryFileLocation (ecmdChipTarget &i_target, ecmdFileType_t i_fileType, std::string &o_fileLocation)`  
*Query the location of a specific file type for the selected target.*
- `bool ecmdQueryTargetConfigured (ecmdChipTarget i_target, ecmdQueryData *i_queryData=NULL)`  
*Query if a particular target is configured in the system.*

## Scan Functions

- `uint32_t getRing (ecmdChipTarget &i_target, const char *i_ringName, ecmdDataBuffer &o_data)`

*Scans the ring from the selected chip into the data buffer.*

- **uint32\_t putRing** (**ecmdChipTarget** &i\_target, const char \*i\_ringName, **ecmdDataBuffer** &i\_data)

*Scans ring from the data buffer into the selected chip in the selected ring.*

- **uint32\_t getLatch** (**ecmdChipTarget** &i\_target, const char \*i\_ringName, const char \*i\_latchName, std::list< **ecmdLatchEntry** > &o\_data, **ecmdLatchMode\_t** i\_mode)

*Reads the selected spy into the data buffer.*

- **uint32\_t putLatch** (**ecmdChipTarget** &i\_target, const char \*i\_ringName, const char \*i\_latchName, **ecmdDataBuffer** &i\_data, **uint32\_t** i\_startBit, **uint32\_t** i\_numBits, **uint32\_t** &o\_matches, **ecmdLatchMode\_t** i\_mode)

*Writes the data buffer into the all latches matching i\_latchName.*

- **uint32\_t getRingWithModifier** (**ecmdChipTarget** &i\_target, **uint32\_t** i\_address, **uint32\_t** i\_bitLength, **ecmdDataBuffer** &o\_data)

*Scans the specified number of bits from the selected chip and ring address into the data buffer.*

- **uint32\_t putRingWithModifier** (**ecmdChipTarget** &i\_target, **uint32\_t** i\_address, **uint32\_t** i\_bitLength, **ecmdDataBuffer** &i\_data)

*Scans the specified number of bits from the data buffer into the selected chip in the selected ring address.*

## Scom Functions

- **uint32\_t getScom** (**ecmdChipTarget** &i\_target, **uint32\_t** i\_address, **ecmdDataBuffer** &o\_data)

*Scoms bits from the selected address into the data buffer.*

- **uint32\_t putScom** (**ecmdChipTarget** &i\_target, **uint32\_t** i\_address, **ecmdDataBuffer** &i\_data)

*Scoms bits from the data buffer into the selected address.*

## Jtag Functions

- **uint32\_t sendCmd** (**ecmdChipTarget** &i\_target, **uint32\_t** i\_instruction, **uint32\_t** i\_modifier, **ecmdDataBuffer** &o\_status)

*Send a JTAG instruction and modifier to the specified chip.*

## FSI Functions

- **uint32\_t getCfamRegister** (**ecmdChipTarget** &i\_target, **uint32\_t** i\_address, **ecmdDataBuffer** &o\_data)

*Read data from the selected CFAM register address into the data buffer.*

- `uint32_t putCfamRegister (ecmdChipTarget &i_target, uint32_t i_address, ecmdDataBuffer &i_data)`

*Write data into the selected CFAM register address.*

## Spy Functions

- `uint32_t getSpy (ecmdChipTarget &i_target, const char *i_spyName, ecmdDataBuffer &o_data)`

*Reads the selected spy into the data buffer.*

- `uint32_t getSpyEnum (ecmdChipTarget &i_target, const char *i_spyName, std::string &o_enumValue)`

*Reads the selected spy and returns it's associated enum.*

- `uint32_t getSpyEpCheckers (ecmdChipTarget &i_target, const char *i_spyEpCheckersName, ecmdDataBuffer &o_inLatchData, ecmdDataBuffer &o_outLatchData, ecmdDataBuffer &o_eccErrorMask)`

*Read an ECC grouping and return the in and out bits as well as a error mask if any out bits are invalid.*

- `uint32_t getSpyGroups (ecmdChipTarget &i_target, const char *i_spyName, std::list< ecmdSpyGroupData > &o_groups)`

*Reads the selected spy and load all the spy groups into provided list.*

- `uint32_t putSpy (ecmdChipTarget &i_target, const char *i_spyName, ecmdDataBuffer &i_data)`

*Writes the data buffer into the selected spy.*

- `uint32_t putSpyEnum (ecmdChipTarget &i_target, const char *i_spyName, const std::string i_enumValue)`

*Writes the enum into the selected spy.*

## Ring Cache Functions

- `void ecmdEnableRingCache ()`

*Enables internal caching of read/writes of scan rings to the chip for functions like getring/getspy/getspr.*

- `uint32_t ecmdDisableRingCache ()`

*Disable internal caching of reads/writes of scan rings.*

- `uint32_t ecmdFlushRingCache ()`

*Flush all modified data from the internal cache to the hardware, then remove all rings from cache.*

- `bool ecmdIsRingCacheEnabled ()`

*Returns true/false to signify if caching is currently enabled.*

## Array Functions

- `uint32_t getArray (ecmdChipTarget &i_target, const char *i_arrayName, ecmdDataBuffer &i_address, ecmdDataBuffer &o_data)`  
*Reads bits from the selected array into the data buffer.*
- `uint32_t getArrayMultiple (ecmdChipTarget &i_target, const char *i_arrayName, std::list< ecmdArrayEntry > &io_entries)`  
*Reads bits from multiple array addresses/elements into the list of data buffers.*
- `uint32_t putArray (ecmdChipTarget &i_target, const char *i_arrayName, ecmdDataBuffer &i_address, ecmdDataBuffer &i_data)`  
*Writes bits from the data buffer into the selected array.*
- `uint32_t putArrayMultiple (ecmdChipTarget &i_target, const char *i_arrayName, std::list< ecmdArrayEntry > &i_entries)`  
*Writes bits from the list of entries into the selected array.*

## Clock Functions

- `uint32_t ecmdQueryClockState (ecmdChipTarget &i_target, const char *i_clockDomain, ecmdClockState_t &o_clockState)`  
*Query the state of the clocks for a domain.*
- `uint32_t startClocks (ecmdChipTarget &i_target, const char *i_clockDomain, bool i_forceState=false)`  
*Start the clocks in the domain specified.*
- `uint32_t stopClocks (ecmdChipTarget &i_target, const char *i_clockDomain, bool i_forceState=false)`  
*Stop the clocks in the domain specified.*
- `uint32_t ecmdSetClockSpeed (ecmdChipTarget &i_target, ecmdClockType_t i_type, uint32_t i_speed, ecmdClockSpeedType_t i_speedType, ecmdClockSetMode_t i_mode, ecmdClockRange_t i_range)`  
*Change a system clock speed without adjusting system initialization settings using speed value.*
- `uint32_t ecmdSetClockMultDiv (ecmdChipTarget &i_target, ecmdClockType_t i_type, uint32_t i_multiplier, uint32_t i_divider)`  
*Change a system clock speed without adjusting system initialization settings using speed value.*

## iSteps Functions

- `uint32_t iStepsByNumber (ecmdDataBuffer &i_steps)`  
*Run iSteps by number.*
- `uint32_t iStepsByName (std::string i_stepName)`  
*Run a single iStep by name.*

- `uint32_t iStepsByNameMultiple (std::list< std::string > i_stepNames)`  
*Run multiple iSteps by name.*
- `uint32_t iStepsByNameRange (std::string i_stepNameBegin, std::string i_stepNameEnd)`  
*Run all iSteps by name starting with i\_stepNameBegin and ending with i\_stepNameEnd.*

## Processor Functions

- `uint32_t ecmdQueryProcRegisterInfo (ecmdChipTarget &i_target, const char *i_name, ecmdProcRegisterInfo &o_data)`  
*Query Information about a Processor Register (SPR/GPR/FPR).*
- `uint32_t getSpr (ecmdChipTarget &i_target, const char *i_sprName, ecmdDataBuffer &o_data)`  
*Reads the selected Processor Architected Special Purpose Register (SPR) into the data buffer.*
- `uint32_t getSprMultiple (ecmdChipTarget &i_target, std::list< ecmdNameEntry > &i_entries)`  
*Reads the selected Processor Architected Special Purpose Register (SPR) into the data buffer.*
- `uint32_t putSpr (ecmdChipTarget &i_target, const char *i_sprName, ecmdDataBuffer &i_data)`  
*Writes the data buffer into the selected Processor Architected Special Purpose Register (SPR).*
- `uint32_t putSprMultiple (ecmdChipTarget &i_target, std::list< ecmdNameEntry > &i_entries)`  
*Writes the data buffer into the selected Processor Architected Special Purpose Register (SPR).*
- `uint32_t getGpr (ecmdChipTarget &i_target, uint32_t i_gprNum, ecmdDataBuffer &o_data)`  
*Reads the selected Processor Architected General Purpose Register (GPR) into the data buffer.*
- `uint32_t getGprMultiple (ecmdChipTarget &i_target, std::list< ecmdIndexEntry > &i_entries)`  
*Reads the selected Processor Architected General Purpose Register (GPR) into the data buffer.*
- `uint32_t putGpr (ecmdChipTarget &i_target, uint32_t i_gprNum, ecmdDataBuffer &i_data)`  
*Writes the data buffer into the selected Processor Architected General Purpose Register (GPR).*
- `uint32_t putGprMultiple (ecmdChipTarget &i_target, std::list< ecmdIndexEntry > &i_entries)`  
*Writes the data buffer into the selected Processor Architected General Purpose Register (GPR).*
- `uint32_t getFpr (ecmdChipTarget &i_target, uint32_t i_fprNum, ecmdDataBuffer &o_data)`  
*Reads the selected Processor Architected Floating Point Register (FPR) into the data buffer.*

- `uint32_t getFprMultiple (ecmdChipTarget &i_target, std::list< ecmdIndexEntry > &i_entries)`  
*Reads the selected Processor Architected Floating Point Register (FPR) into the data buffer.*
- `uint32_t putFpr (ecmdChipTarget &i_target, uint32_t i_fprNum, ecmdDataBuffer &i_data)`  
*Writes the data buffer into the selected Processor Architected Floating Point Register (FPR).*
- `uint32_t putFprMultiple (ecmdChipTarget &i_target, std::list< ecmdIndexEntry > &i_entries)`  
*Writes the data buffer into the selected Processor Architected Floating Point Register (FPR).*
- `uint32_t getSlb (ecmdChipTarget &i_target, uint32_t i_slbNum, ecmdDataBuffer &o_data)`  
*Reads the selected Processor SLB Entry into the data buffer.*
- `uint32_t getSlbMultiple (ecmdChipTarget &i_target, std::list< ecmdIndexEntry > &i_entries)`  
*Reads the selected Processor SLB Entry into the data buffer.*
- `uint32_t putSlb (ecmdChipTarget &i_target, uint32_t i_slbNum, ecmdDataBuffer &i_data)`  
*Writes the data buffer into the selected Processor SLB Entry.*
- `uint32_t putSlbMultiple (ecmdChipTarget &i_target, std::list< ecmdIndexEntry > &i_entries)`  
*Writes the data buffer into the selected Processor SLB Entry.*

## Trace Array Functions

- `uint32_t getTraceArray (ecmdChipTarget &i_target, const char *i_name, bool i_doTraceStopStart, std::vector< ecmdDataBuffer > &o_data)`  
*Dump all entries of specified trace array.*
- `uint32_t getTraceArrayMultiple (ecmdChipTarget &i_target, bool i_doTraceStopStart, std::list< ecmdNameVectorEntry > &o_data)`  
*Dump all entries of specified trace array.*

## Memory Functions

- `uint32_t getMemProc (ecmdChipTarget &i_target, uint64_t i_address, uint32_t i_bytes, ecmdDataBuffer &o_data)`  
*Reads System Mainstore through the processor chip using a real address.*
- `uint32_t putMemProc (ecmdChipTarget &i_target, uint64_t i_address, uint32_t i_bytes, ecmdDataBuffer &i_data)`  
*Writes System Mainstore through the processor chip using a real address.*

- `uint32_t getMemDma (ecmdChipTarget &i_target, uint64_t i_address, uint32_t i_bytes, ecmdDataBuffer &o_data)`  
*Reads System Mainstore through the PSI or DMA interface (whichever is available) using a real address.*
- `uint32_t putMemDma (ecmdChipTarget &i_target, uint64_t i_address, uint32_t i_bytes, ecmdDataBuffer &i_data)`  
*Writes System Mainstore through the PSI or DMA interface (whichever is available) using a real address.*
- `uint32_t getMemMemCtrl (ecmdChipTarget &i_target, uint64_t i_address, uint32_t i_bytes, ecmdDataBuffer &o_data)`  
*Reads System Mainstore through the memory controller using a real address.*
- `uint32_t putMemMemCtrl (ecmdChipTarget &i_target, uint64_t i_address, uint32_t i_bytes, ecmdDataBuffer &i_data)`  
*Writes System Mainstore through the memory controller using a real address.*
- `uint32_t ecmdCacheFlush (ecmdChipTarget &i_target, ecmdCacheType_t i_cacheType)`  
*Cache Flush.*

## Simulation Functions

- `uint32_t simaet (const char *i_function)`  
*Enable/Disable Simulation AET Logging.*
- `uint32_t simcheckpoint (const char *i_checkpoint)`  
*Store a checkpoint to specified file.*
- `uint32_t simclock (uint32_t i_cycles)`  
*Clock the model.*
- `uint32_t simecho (const char *i_message)`  
*Echo message to stdout and sim log.*
- `uint32_t simexit (uint32_t i_rc=0, const char *i_message=NULL)`  
*Close down the simulation model.*
- `uint32_t simEXPECTFAC (const char *i_facname, uint32_t i_bitlength, ecmdDataBuffer &i_expect, uint32_t i_row=0, uint32_t i_offset=0)`  
*Perform expect on facility using name.*
- `uint32_t simexpecttcfac (const char *i_tcfacname, uint32_t i_bitlength, ecmdDataBuffer &i_expect, uint32_t i_row=0)`  
*Perform expect on TCFAC facility.*
- `uint32_t simgetcurrentcycle (uint64_t &o_cyclecount)`

*Fetch current model cycle count.*

- `uint32_t simGETFAC` (`const char *i_facname`, `uint32_t i_bitlength`, `ecmdDataBuffer &o_data`, `uint32_t i_row=0`, `uint32_t i_offset=0`)

*Retrieve a Facility using a name.*

- `uint32_t simGETFACX` (`const char *i_facname`, `uint32_t i_bitlength`, `ecmdDataBuffer &o_data`, `uint32_t i_row=0`, `uint32_t i_offset=0`)

*Retrieve a Facility using a name - preserving Xstate.*

- `uint32_t simgettcfac` (`const char *i_tcfacname`, `ecmdDataBuffer &o_data`, `uint32_t i_row=0`, `uint32_t i_startbit=0`, `uint32_t i_bitlength=0`)

*Retrieve a TCFAC facility.*

- `uint32_t siminit` (`const char *i_checkpoint`)

*Initialize the simulation.*

- `uint32_t simPOLLFAC` (`const char *i_facname`, `uint32_t i_bitlength`, `ecmdDataBuffer &i_expect`, `uint32_t i_row=0`, `uint32_t i_offset=0`, `uint32_t i_maxcycles=1`, `uint32_t i_pollinterval=1`)

*Poll a facility waiting for expected value.*

- `uint32_t simpolltcfac` (`const char *i_tcfacname`, `ecmdDataBuffer &i_expect`, `uint32_t i_row=0`, `uint32_t i_startbit=0`, `uint32_t i_bitlength=0`, `uint32_t i_maxcycles=1`, `uint32_t i_pollinterval=1`)

*Poll a TCFAC facility waiting for expected value.*

- `uint32_t simPUTFAC` (`const char *i_facname`, `uint32_t i_bitlength`, `ecmdDataBuffer &i_data`, `uint32_t i_row=0`, `uint32_t i_offset=0`)

*Write a Facility using a name.*

- `uint32_t simPUTFACX` (`const char *i_facname`, `uint32_t i_bitlength`, `ecmdDataBuffer &i_data`, `uint32_t i_row=0`, `uint32_t i_offset=0`)

*Write a Facility using a name - preserving Xstate.*

- `uint32_t simputtcfac` (`const char *i_tcfacname`, `uint32_t i_bitlength`, `ecmdDataBuffer &i_data`, `uint32_t i_row=0`, `uint32_t i_numrows=0`)

*Write a TCFAC facility.*

- `uint32_t simrestart` (`const char *i_checkpoint`)

*Load a checkpoint into model.*

- `uint32_t simSTKFAC` (`const char *i_facname`, `uint32_t i_bitlength`, `ecmdDataBuffer &i_data`, `uint32_t i_row=0`, `uint32_t i_offset=0`)

*Stick a Facility using a name.*

- `uint32_t simstktcfac` (`const char *i_tcfacname`, `uint32_t i_bitlength`, `ecmdDataBuffer &i_data`, `uint32_t i_row=0`, `uint32_t i_numrows=0`)

*Stick a TCFAC facility.*

- `uint32_t simSUBCMD` (`const char *i_command`)



*Run RTX SUBCMD.*

- `uint32_t simtckinterval` (`uint32_t i_tckinterval`)  
*Set TCK Interval setting in the model for JTAG Master.*
- `uint32_t simUNSTICK` (`const char *i_facname`, `uint32_t i_bitlength`, `uint32_t i_row=0`, `uint32_t i_offset=0`)  
*Unstick a Facility using a name.*
- `uint32_t simunsticktcfac` (`const char *i_tcfacname`, `uint32_t i_bitlength`, `ecmdData-Buffer &i_data`, `uint32_t i_row=0`, `uint32_t i_numrows=0`)  
*Unstick a TCFAC facility.*
- `uint32_t simGetHierarchy` (`ecmdChipTarget &i_target`, `std::string &o_hierarchy`)  
*Fetch the hierarchy for the specified chip target relative to the latch names in the scandef.*
- `uint32_t ecmdQueryChipSimModelVersion` (`ecmdChipTarget &i_target`, `std::string &o_timestamp`)  
*Will retrieve the model timestamp from the simulation, in hardware mode "NA" is returned.*
- `uint32_t ecmdQueryChipScandefVersion` (`ecmdChipTarget &i_target`, `std::string &o_timestamp`)  
*Will retrieve the scandef timestamp from the scandef being used for the specified target.*
- `std::string simCallFusionCommand` (`const char *i_fusionObject`, `const char *i_replica-ID`, `const char *i_command`)  
*Run a command on another Fusion module.*
- `uint32_t simFusionRand32` (`uint32_t i_min=0`, `uint32_t i_max=~0UL`, `const char *i_fusionRandObject=NULL`)  
*Returns a random 32 bit number in the range [min,max] using the Fusion MasterSeed; by default each client will have an own instance of Fusion's Random32BitNumber object, but the user can specify the object's name and reuse the same object across multiple clients; if no range is specified 0 and MAXINT32 will be used.*
- `uint32_t simOutputFusionMessage` (`const char *i_header`, `const char *i_message`, `ecmdFusionSeverity_t i_severity`, `ecmdFusionMessageType_t i_type`, `const char *i_file=NULL`, `uint32_t i_line=0`)  
*Echo Messages to Fusion logs.*
- `void simSetFusionMessageFormat` (`const char *i_format`)  
*Set Fusion Message Format.*
- `uint32_t simPutDial` (`const char *i_dialName`, `const std::string i_enumValue`)  
*Write a simulation dial with specified value.*
- `uint32_t simGetDial` (`const char *i_dialName`, `std::string &o_enumValue`)  
*Read a simulation dial.*
- `uint32_t simGetOutFile` (`const char *i_filename`, `std::string &o_absFilename`)

*Obtain absolute filename of a file that will be placed in the SIMOUT directory of the server / Fusion process and add new file to the bom information in the SUM file.*

- `uint32_t simGetInFile (const char *_filename, std::string &o_absFilename)`  
*Resolve absolute filename of a file by searching the SIMIN paths and add new file to the bom information in the SUM file.*
- `uint32_t simGetEnvironment (const char *_envName, std::string &o_envValue)`  
*Retrieve value of an environment variable on the server side.*
- `uint32_t simGetModelInfo (ecmdSimModelInfo &o_modelInfo)`  
*Query information about the model from the server.*

## Error Handling Functions

- `std::string ecmdGetErrorMsg (uint32_t i_errorCode, bool i_parseReturnCode=true)`  
*Retrieve additional error information for errorcode.*
- `uint32_t ecmdRegisterErrorMsg (uint32_t i_errorCode, const char *_i_whom, const char *_i_message)`  
*Register an error message that has occurred.*
- `void ecmdFlushRegisteredErrorMsgs ()`  
*Flush all registered messages, they are no long retrievable.*

## Output Functions

- `void ecmdOutputError (const char *_i_message)`  
*Output a message related to an error.*
- `void ecmdOutputWarning (const char *_i_message)`  
*Output a message related to an warning.*
- `void ecmdOutput (const char *_i_message)`  
*Output a message to the screen or logs.*

## Misc Functions

- `uint32_t ecmdGetGlobalVar (ecmdGlobalVarType_t i_type)`  
*Retrieve the value of some ecmdGlobalVars.*
- `void ecmdSetTraceMode (ecmdTraceType_t i_type, bool i_enable)`  
*Enable/Disable a trace mode.*
- `bool ecmdQueryTraceMode (ecmdTraceType_t i_type)`  
*Query the state of a trace mode.*

- `uint32_t ecmdDelay (uint32_t i_simCycles, uint32_t i_msDelay)`  
*Function to delay a procedure either by running sim cycles or by doing a millisecond delay.*
- `uint32_t makeSPSystemCall (ecmdChipTarget &i_target, const std::string &i_command, std::string &o_stdout)`  
*Make a system call on the targetted Service Processor or Service Element.*

## Configuration Functions

- `uint32_t ecmdGetConfiguration (ecmdChipTarget &i_target, std::string i_name, ecmdConfigValid_t &o_validOutput, std::string &o_valueAlpha, uint32_t &o_valueNumeric)`  
*Retrieve the value of a Configuration Setting.*
- `uint32_t ecmdSetConfiguration (ecmdChipTarget &i_target, std::string i_name, ecmdConfigValid_t i_validInput, std::string i_valueAlpha, uint32_t i_valueNumeric)`  
*Set the value of a Configuration Setting.*
- `uint32_t ecmdDeconfigureTarget (ecmdChipTarget &i_target)`  
*Deconfigure a target in the system.*
- `uint32_t ecmdConfigureTarget (ecmdChipTarget &i_target)`  
*Configure a target in the system - must be previously known to the system.*
- `uint32_t ecmdTargetToUnitId (ecmdChipTarget &o_target)`  
*Converts an eCmd (physical) Target to a HOM Unit Id.*
- `uint32_t ecmdUnitIdStringToTarget (std::string i_unitId, std::list< ecmdChipTarget > &o_targetList)`  
*Converts a Unit Id String to an eCmd (physical) Target.*
- `uint32_t ecmdUnitIdToTarget (uint32_t i_unitId, std::list< ecmdChipTarget > &o_targetList)`  
*Converts a Unit Id to an eCmd (physical) Target.*
- `uint32_t ecmdUnitIdToString (uint32_t i_unitId, std::string &o_unitIdStr)`  
*Converts a Unit Id into its String representation.*
- `uint32_t ecmdSequenceIdToTarget (uint32_t i_core_seq_num, ecmdChipTarget &o_target, uint32_t i_thread_seq_num=0)`  
*Sequence ID of Cores and Threads converted to ecmdChipTarget(p. 20) struct.*

## Module VPD Functions

- `uint32_t getModuleVpdKeyword (ecmdChipTarget &i_target, const char *i_record_name, const char *i_keyword, uint32_t i_bytes, ecmdDataBuffer &o_data)`  
*Read Module VPD Keyword Interface.*

- `uint32_t putModuleVpdKeyword (ecmdChipTarget &i_target, const char *i_record_name, const char *i_keyword, ecmdDataBuffer &i_data)`

*Write Module VPD Keyword Interface.*

- `uint32_t getModuleVpdImage (ecmdChipTarget &i_target, uint32_t i_bytes, ecmdDataBuffer &o_data)`

*Read Module VPD Image Interface.*

- `uint32_t putModuleVpdImage (ecmdChipTarget &i_target, ecmdDataBuffer &i_data)`

*Write Module VPD Image Interface.*

## I2C Functions

- `uint32_t ecmdI2cReset (ecmdChipTarget &i_target, uint32_t i_engineId, uint32_t i_port)`

*Resets the specified engine port.*

- `uint32_t ecmdI2cRead (ecmdChipTarget &i_target, uint32_t i_engineId, uint32_t i_port, uint32_t i_slaveAddress, ecmdI2cBusSpeed_t i_busSpeed, uint32_t i_bytes, ecmdDataBuffer &o_data)`

*Read data from an I2C device.*

- `uint32_t ecmdI2cReadOffset (ecmdChipTarget &i_target, uint32_t i_engineId, uint32_t i_port, uint32_t i_slaveAddress, ecmdI2cBusSpeed_t i_busSpeed, uint32_t i_offset, uint32_t i_offsetFieldSize, uint32_t i_bytes, ecmdDataBuffer &o_data)`

*Read data from an I2C device at the given offset.*

- `uint32_t ecmdI2cWrite (ecmdChipTarget &i_target, uint32_t i_engineId, uint32_t i_port, uint32_t i_slaveAddress, ecmdI2cBusSpeed_t i_busSpeed, ecmdDataBuffer &i_data)`

*Write the provided data into the I2C device.*

- `uint32_t ecmdI2cWriteOffset (ecmdChipTarget &i_target, uint32_t i_engineId, uint32_t i_port, uint32_t i_slaveAddress, ecmdI2cBusSpeed_t i_busSpeed, uint32_t i_offset, uint32_t i_offsetFieldSize, ecmdDataBuffer &i_data)`

*Write the provided data into the I2C device at the given offset.*

## GPIO Functions

- `uint32_t ecmdGpioConfigPin (ecmdChipTarget &i_target, uint32_t i_engineId, uint32_t i_pin, ecmdDioMode_t i_mode)`

*Configures mode of pin.*

- `uint32_t ecmdGpioReadPin (ecmdChipTarget &i_target, uint32_t i_engineId, uint32_t i_pin, uint32_t &o_state)`

*Read the state of the specified pin (0/1).*

- `uint32_t ecmdGpioReadLatch (ecmdChipTarget &i_target, uint32_t i_engineId, uint32_t i_pin, ecmdDioMode_t i_mode, uint32_t &o_state)`  
*Read the state of the latch.*
- `uint32_t ecmdGpioWriteLatch (ecmdChipTarget &i_target, uint32_t i_engineId, uint32_t i_pin, ecmdDioMode_t i_mode, uint32_t i_state)`  
*Write value to the specified pin.*
- `uint32_t ecmdGpioReadPins (ecmdChipTarget &i_target, uint32_t i_engineId, uint32_t i_mask, uint32_t &o_value)`  
*Read the GPIO input register and AND with i\_mask.*
- `uint32_t ecmdGpioWriteLatches (ecmdChipTarget &i_target, uint32_t i_engineId, ecmdDioMode_t i_mode, uint32_t i_mask, uint32_t i_value)`  
*Write several pins specified by i\_mask.*

### 6.4.1 Detailed Description

eCMD Perl API Usage :

```
use ecmd;
```

### 6.4.2 Function Documentation

#### 6.4.2.1 `int ecmdLoadDll (const char * i_dllName, const char * i_clientVersion)`

Initialize the eCMD DLL.

**Return values:**

0 if successful load 1 if unsuccessful

**Parameters:**

***i\_dllName*** Full path and filename of the eCMD Dll to load

***i\_clientVersion*** Comma seperated list of eCMD Perl api major numbers this script supports, see details

**Precondition:**

ecmdClientPerlapi constructor must have been called

- initializes the eCMD Dll.

**VERSIONS :**

eCMD at times has to make changes to add/remove functionality and parameters to functions. This could cause incompatibility in your script if you used functions that have changed. The `i_clientVersion` string is used to tell eCMD which major releases you support such that your script will not continue execution if it encounters a version that is either not known about or not supported. This is similar to how the eCMD C-API works except in Perl you can support multiple

versions with one script as long as the changes that were made between the versions do not affect your script.

USAGE :

```
if (ecmdLoadDll("", "ver3,ver4")) { die "Fatal errors initializing DLL"; }
```

#### 6.4.2.2 void ecmdUnloadDll ()

Clean up the Perl Module - MUST BE CALLED JUST BEFORE SCRIPT EXIT.

#### 6.4.2.3 int ecmdCommandArgs (char \*\* *io\_argv*)

Pass any unknown command line paramaters to the DLL for processing (ex. -p#, Cronus -debug).

**Return values:**

*ECMD\_SUCCESS* if successful

*nonzero* if unsuccessful

**Parameters:**

*io\_argv* Passed from Command line Arguments

**Precondition:**

initDll must have been called

**Postcondition:**

Global options (ex. -p#, -c#) will be removed from arg list

**See also:**

initDll

- argv gets passed to the eCMD DLL.
- Global options such as -p#, -c# will be parsed out.
- Target flags can be queried later with functions like ecmdQuerySelected

NOTE : This function does not affect ring caching

USAGE :

```
ecmdCommandArgs(@ARGV);
```

#### 6.4.2.4 void ecmdEnablePerlSafeMode ()

Enable Perl Error Handling Safe Mode - Croak on any eCMD error (default is enabled).

#### 6.4.2.5 void ecmdDisablePerlSafeMode ()

Disable Perl Error Handling Safe Mode - Return eCMD errors to client (default is enabled).

**6.4.2.6 bool ecmdParseOption (char \*\* *io\_argv*, const char \* *i\_option*)**

Iterates over argv, looking for given option string, removes it if found.

**Return values:**

*1* if option found, 0 otherwise

**Parameters:**

*io\_argv* Array of strings passed in from command line

*i\_option* Option to look for

**See also:**

**ecmdParseOptionWithArgs**(p. 139)

**6.4.2.7 char\* ecmdParseOptionWithArgs (char \*\* *io\_argv*, const char \* *i\_option*)**

Iterates over argv, looking for given option string, removes it if found.

**Return values:**

*Value* of option arg if found, NULL otherwise

**Parameters:**

*io\_argv* Array of strings passed in from command line

*i\_option* Option to look for

**See also:**

**ecmdParseOptionWithArgs**(p. 139)

**6.4.2.8 uint32\_t ecmdQueryDllInfo (ecmdDllInfo & *o\_dllInfo*)**

Query information about the Dll that is loaded.

**Parameters:**

*o\_dllInfo* Return data with data from the current dll loaded

**Return values:**

*ECMD\_SUCCESS* if successful

*nonzero* on failure

This interface allows you to query what particular instance of the DLL is loaded (i.e Cronus/IP/Z), along with additional information.

NOTE : This function does not affect ring caching

**6.4.2.9 bool ecmdQueryVersionGreater (const char \* *version*)**

Query to see if plugin is greater or equal to release specified.

**Parameters:**

*version* eCMD Release (ex "5.1", "6.3")

**Return values:**

*true* If the plugin release is  $\geq$  version specified

*false* If the plugin release is  $<$  version specified

eCMD won't allow your code to run if the major numbers mismatch, but at times you may want to use a new function that was released in a minor release. This api let's you see if the plugin is at least or greater then the minor number where the new function was made available.

So if new function X was dropped in eCMD release v6.2 then if you include the following check in your code you can neatly handle if a user is trying to run a plugin that is 6.1 or less:

```
if (!ecmdQueryVersionGreater("6.2")) {
    ecmdOutputWarning("Plugin doesn't support function X , skipping the new stuff\n");
}
```

**6.4.2.10** `uint32_t ecmdQueryConfig (ecmdChipTarget & i_target, ecmdQueryData & o_queryData, ecmdQueryDetail_t i_detail = ECMD_QUERY_DETAIL_HIGH)`

Query configuration information from the DLL.

**Parameters:**

*i\_target* Struct that contains partial information to limit query results

*o\_queryData* Return data from query

*i\_detail* Specify the level of detail that should be returned with the query

**Return values:**

*ECMD\_SUCCESS* if successful

*nonzero* on failure

The Valid bits of the target are used to refine the query

The target paramater should be filled in with as much data as you know to limit the query, (including the chipType).

When a field state is set to ECMD\_TARGET\_FIELD\_WILDCARD the query function will iterate on all possible values for that entry and return the relevant data.

When a field state is set to ECMD\_TARGET\_FIELD\_UNUSED the query function will stop iterating at that level and below

Ex: to query what positions of the Nova chip are on cage 1, node 2:

cage = 1, node = 2, pos = 'wildcard', chipType = 'Nova', core = 'wildcard', thread = 'wildcard'

Ex: to query what positions of the Nova chip are in the entire system:

cage = 'wildcard', node = 'wildcard', pos = 'wildcard', chipType = 'Nova', core = 'wildcard', thread = 'wildcard'

Ex: to query all the chips on cage 3, node 0:

cage = 3, node = 0, pos = 'wildcard', chipType = 'wildcard', core = 'wildcard', thread = 'wildcard'



Ex: to query all the chips in the entire system:

```
cage = 'wildcard', node = 'wildcard', pos = 'wildcard', chipType = 'wildcard', core = 'wildcard',
thread = 'wildcard'
```

Ex: to query the total nodes in a system:

```
cage = 'wildcard', node = 'wildcard', pos = 'ignore', chipType = 'ignore', core = 'ignore', thread
= 'ignore'
```

NOTE : This function does not affect ring caching

TARGET DEPTH : Thread

TARGET STATES : Must be Initialized

**6.4.2.11** `uint32_t ecmdQuerySelected (ecmdChipTarget & io_target,  
ecmdQueryData & o_queryData, ecmdConfigLoopType_t i_looptype =  
ECMD_SELECTED_TARGETS_LOOP)`

Query User Selected Targeting information from the DLL, i.e (-p#,-c#,-t#).

**Parameters:**

*io\_target* Struct that contains partial information to limit query results - chipType is unused

*o\_queryData* Return data from query

*i\_looptype* (Optional) Used by config looper to specify different query modes

**Return values:**

*ECMD\_SUCCESS* if successful

*nonzero* on failure

This function acts just like `ecmdQueryConfig` except it operates on what targets were selected by the user args -n#, -p#, -c#, -t#

Use of this function is the same as `ecmdQueryConfig`

When -talive is specified all threads configured will be returned in `o_queryData` and `io_target.threadState` will be set to `ECMD_TARGET_THREAD_ALIVE`.

NOTE : This function does not affect ring caching

TARGET DEPTH : Thread

TARGET STATES : Must be Initialized

**6.4.2.12** `uint32_t ecmdQueryRing (ecmdChipTarget & i_target, std::list<  
ecmdRingData > & o_queryData, const char * i_ringName = NULL,  
ecmdQueryDetail_t i_detail = ECMD_QUERY_DETAIL_HIGH)`

Query Ring information from the DLL.

**Parameters:**

*i\_target* Struct that contains chip and cage/node/slot/position information of chip to use

*o\_queryData* Return list from query

*i\_ringName* if != NULL used to refine query to a single ring

*i\_detail* Specify the level of detail that should be returned with the query

**Return values:**

**ECMD\_INVALID\_RING** if *i\_ringName* is not valid for target  
**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_SUCCESS** if successful  
**nonzero** on failure

NOTE : This function does not affect ring caching

TARGET DEPTH : Pos

TARGET STATES : Unused

**6.4.2.13** `uint32_t ecmdQueryLatch (ecmdChipTarget & i_target, std::list<ecmdLatchData > & o_queryData, ecmdLatchMode_t i_mode, const char * i_latchName, const char * i_ringName = NULL, ecmdQueryDetail_t i_detail = ECMD_QUERY_DETAIL_HIGH)`

Query Latch information from the DLL.

**Parameters:**

*i\_target* Struct that contains chip and cage/node/slot/position information of chip to use  
*o\_queryData* Return list from query  
*i\_ringName* if != NULL used to refine query to a single ring  
*i\_latchName* if != NULL used to refine query to a single latch  
*i\_mode* LatchName search mode (full or partial names)  
*i\_detail* Specify the level of detail that should be returned with the query

**Return values:**

**ECMD\_INVALID\_RING** if *i\_ringName* is not valid for target  
**ECMD\_INVALID\_LATCHNAME** if latchname not found in scandef  
**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_SUCCESS** if successful  
**nonzero** on failure

NOTE : *i\_latchName* or *i\_ringName* MUST be used, they can't both be NULL

NOTE : This function does not affect ring caching

TARGET DEPTH : Pos

TARGET STATES : Unused

**6.4.2.14** `uint32_t ecmdQueryArray (ecmdChipTarget & i_target, std::list<ecmdArrayData > & o_queryData, const char * i_arrayName = NULL, ecmdQueryDetail_t i_detail = ECMD_QUERY_DETAIL_HIGH)`

Query Array information from the DLL.

**Parameters:**

*i\_target* Struct that contains chip and cage/node/slot/position/core/thread information of chip to use

*o\_queryData* Return list from query  
*i\_arrayName* if != NULL used to refine query to a single array  
*i\_detail* Specify the level of detail that should be returned with the query

**Return values:**

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_INVALID\_ARRAY** if *i\_arrayName* is not valid for target  
**ECMD\_SUCCESS** if successful  
**nonzero** on failure

NOTE : This function does not affect ring caching

TARGET DEPTH : Pos

TARGET STATES : Unused

**6.4.2.15** `uint32_t ecmdQuerySpy (ecmdChipTarget & i_target, std::list< ecmdSpyData > & o_queryData, const char * i_spyName = NULL, ecmdQueryDetail_t i_detail = ECMD_QUERY_DETAIL_HIGH)`

Query Spy information from the DLL.

**Parameters:**

*i\_target* Struct that contains chip and cage/node/slot/position/core/thread information of chip to use  
*o\_queryData* Return data from query  
*i\_spyName* if != NULL used to refine query to a single spy  
*i\_detail* Specify the level of detail that should be returned with the query

**Return values:**

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_SUCCESS** if successful  
**ECMD\_INVALID\_SPY** if spy name is not valid for target  
**nonzero** on failure

NOTE : This function does not affect ring caching

TARGET DEPTH : Pos

TARGET STATES : Unused

**6.4.2.16** `uint32_t ecmdQueryScom (ecmdChipTarget & i_target, std::list< ecmdScomData > & o_queryData, uint32_t i_address = 0xFFFFFFFF, ecmdQueryDetail_t i_detail = ECMD_QUERY_DETAIL_HIGH)`

Query Scom information from the DLL.

**Parameters:**

*i\_target* Struct that contains chip and cage/node/slot/position/core/thread information of chip to use

*o\_queryData* Return data from query  
*i\_address* if != 0xFFFFFFFF used to refine query to a single scom  
*i\_detail* Specify the level of detail that should be returned with the query

**Return values:**

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_SUCCESS** if successful  
**nonzero** on failure

NOTE : This function does not affect ring caching

TARGET DEPTH : Pos

TARGET STATES : Unused

**6.4.2.17** `uint32_t ecmdQueryTraceArray (ecmdChipTarget & i_target,  
std::list< ecmdTraceArrayData > & o_queryData, const char  
* i_traceArrayName = NULL, ecmdQueryDetail_t i_detail =  
ECMD_QUERY_DETAIL_HIGH)`

Query Trace Array information from the DLL.

**Parameters:**

*i\_target* Struct that contains chip and cage/node/slot/position/core/thread information of chip to use  
*o\_queryData* Return data from query  
*i\_traceArrayName* if != NULL used to refine query to a single trace array  
*i\_detail* Specify the level of detail that should be returned with the query

**Return values:**

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_SUCCESS** if successful  
**nonzero** on failure

NOTE : This function does not affect ring caching

TARGET DEPTH : Pos

TARGET STATES : Unused

**6.4.2.18** `uint32_t ecmdQueryFileLocation (ecmdChipTarget & i_target,  
ecmdFileType_t i_fileType, std::string & o_fileLocation)`

Query the location of a specific file type for the selected target.

**Parameters:**

*i\_target* Struct that contains chip and cage/node/slot/position/core/thread information  
*i\_fileType* Enum that specifies which type of file you are looking for scandef/spydef/arraydef  
*o\_fileLocation* Return string with full path and filename to location

**Return values:**

*ECMD\_SUCCESS* if successful  
*ECMD\_UNKNOWN\_FILE* if unable to find requested file  
*nonzero* if unsuccessful

NOTE : This function does not affect ring caching

TARGET DEPTH : Pos (where applicable based on i\_fileType)

TARGET STATES : Unused

#### 6.4.2.19 bool ecmdQueryTargetConfigured (ecmdChipTarget i\_target, ecmdQueryData \* i\_queryData = NULL)

Query if a particular target is configured in the system.

**Parameters:**

*i\_target* Target to query in system configuration  
*i\_queryData* If specified this data will be used, otherwise a call to ecmdQueryConfig will be made

**Return values:**

*true* if Target is configured in system  
*false* if Target is not configured in system

NOTE : This function calls ecmdQueryConfig and searches for the specified target

NOTE : The target State fields must be filled in as either VALID or UNUSED

TARGET DEPTH : Thread

TARGET STATES : Must be Initialized

#### 6.4.2.20 uint32\_t getRing (ecmdChipTarget & i\_target, const char \* i\_ringName, ecmdDataBuffer & o\_data)

Scans the ring from the selected chip into the data buffer.

**Return values:**

*ECMD\_INVALID\_RING* if ringname is not valid for target  
*ECMD\_TARGET\_NOT\_CONFIGURED* if target is not available in the system  
*ECMD\_CLOCKS\_IN\_INVALID\_STATE* Chip Clocks were in an invalid state to perform the operation  
*ECMD\_SUCCESS* if successful  
*nonzero* if unsuccessful  
*ECMD\_RING\_CACHE\_ENABLED* Ring Cache enabled function - must be disabled to use this function

**Parameters:**

*i\_target* Struct that contains chip and cage/node/slot/position/core information of ring to read  
*i\_ringName* Name of ring to read from

*o\_data* DataBuffer object that holds data read from ring

See also:

`putRing`(p. 146)

TARGET DEPTH : Core

TARGET STATES : Unused

**6.4.2.21** `uint32_t putRing (ecmdChipTarget & i_target, const char * i_ringName, ecmdDataBuffer & i_data)`

Scans ring from the data buffer into the selected chip in the selected ring.

Return values:

***ECMD\_SUCCESS*** if successful

***nonzero*** if unsuccessful

***ECMD\_DATA\_OVERFLOW*** Too much data was provided for a write

***ECMD\_DATA\_UNDERFLOW*** Too little data was provided to a write function

***ECMD\_TARGET\_NOT\_CONFIGURED*** if target is not available in the system

***ECMD\_INVALID\_RING*** if ringname is not valid for target

***ECMD\_CLOCKS\_IN\_INVALID\_STATE*** Chip Clocks were in an invalid state to perform the operation

***ECMD\_RING\_CACHE\_ENABLED*** Ring Cache enabled function - must be disabled to use this function

Parameters:

***i\_target*** Struct that contains chip and cage/node/slot/position/core information of ring to write

***i\_ringName*** Name of ring to write to

***i\_data*** DataBuffer object that holds data to write into ring

See also:

`getRing`(p. 145)

TARGET DEPTH : Core

TARGET STATES : Unused

**6.4.2.22** `uint32_t getLatch (ecmdChipTarget & i_target, const char * i_ringName, const char * i_latchName, std::list< ecmdLatchEntry > & o_data, ecmdLatchMode_t i_mode)`

Reads the selected spy into the data buffer.

Return values:

***ECMD\_TARGET\_NOT\_CONFIGURED*** if target is not available in the system

***ECMD\_CLOCKS\_IN\_INVALID\_STATE*** Chip Clocks were in an invalid state to perform the operation

**ECMD\_SUCCESS** if successful read  
**ECMD\_UNABLE\_TO\_OPEN\_SCANDEF** eCMD was unable to open the scandef  
**ECMD\_INVALID\_RING** if ringname is not valid for target  
**ECMD\_INVALID\_LATCHNAME** if latchname not found in scandef  
**nonzero** if unsuccessful

**Parameters:**

**i\_target** Struct that contains chip and cage/node/slot/position/core information  
**i\_latchName** Name of latch to read (can be a partial or full name based on i\_mode)  
**o\_data** list of Entries containing all latches found matching i\_latchName  
**i\_ringName** Name of ring to search for latch if == NULL, entire scandef is searched  
**i\_mode** LatchName search mode (full or partial names)

NOTE : This function is ring cache enabled

TARGET DEPTH : Core

TARGET STATES : Unused

**6.4.2.23** `uint32_t putLatch (ecmdChipTarget & i_target, const char *  
i_ringName, const char * i_latchName, ecmdDataBuffer & i_data,  
uint32_t i_startBit, uint32_t i_numBits, uint32_t & o_matches,  
ecmdLatchMode_t i_mode)`

Writes the data buffer into the all latches matching i\_latchName.

**Return values:**

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_SUCCESS** if successful  
**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to  
perform the operation  
**ECMD\_UNABLE\_TO\_OPEN\_SCANDEF** eCMD was unable to open the scandef  
**ECMD\_INVALID\_RING** if ringname is not valid for target  
**ECMD\_INVALID\_LATCHNAME** if latchname not found in scandef  
**ECMD\_DATA\_OVERFLOW** Too much data was provided for a write  
**ECMD\_DATA\_UNDERFLOW** Too little data was provided to a write function  
**nonzero** if unsuccessful

**Parameters:**

**i\_target** Struct that contains chip and cage/node/slot/position/core information  
**i\_latchName** Name of latch to write (can be a partial or full name based on i\_mode)  
**i\_data** DataBuffer object that holds data to write into latch  
**i\_ringName** Name of ring to search for latch if == NULL, entire scandef is searched  
**i\_mode** LatchName search mode  
**i\_startBit** Startbit in latchname to insert data  
**i\_numBits** Number of bits to insert from startbit  
**o\_matches** Number of latches found that matched your name and data was inserted

NOTE : This function is ring cache enabled

TARGET DEPTH : Core

TARGET STATES : Unused

#### 6.4.2.24 `uint32_t getRingWithModifier (ecmdChipTarget & i_target, uint32_t i_address, uint32_t i_bitLength, ecmdDataBuffer & o_data)`

Scans the specified number of bits from the selected chip and ring address into the data buffer.

##### Return values:

***ECMD\_TARGET\_NOT\_CONFIGURED*** if target is not available in the system  
***ECMD\_CLOCKS\_IN\_INVALID\_STATE*** Chip Clocks were in an invalid state to perform the operation  
***ECMD\_SUCCESS*** if successful  
***nonzero*** if unsuccessful  
***ECMD\_RING\_CACHE\_ENABLED*** Ring Cache enabled function - must be disabled to use this function

##### Parameters:

***i\_target*** Struct that contains chip and cage/node/slot/position information of ring to read  
***i\_address*** Address of ring to read from  
***i\_bitLength*** Bit Length to scan for  
***o\_data*** DataBuffer object that holds data read from ring

##### See also:

`putRingWithModifier`(p. 148)

NOTE : This is a debug interface and should not be used in normal situations

NOTE : This function does not handle processor cores for you, the *i\_address* will be taken and used with no modifications so you are responsible for specifying the correct core address

NOTE : This function will only scan for the length provided, if this length doesn't match the actual length of the ring corruption may occur

TARGET DEPTH : Pos

TARGET STATES : Unused

#### 6.4.2.25 `uint32_t putRingWithModifier (ecmdChipTarget & i_target, uint32_t i_address, uint32_t i_bitLength, ecmdDataBuffer & i_data)`

Scans the specified number of bits from the data buffer into the selected chip in the selected ring address.

##### Return values:

***ECMD\_SUCCESS*** if successful  
***nonzero*** if unsuccessful  
***ECMD\_DATA\_OVERFLOW*** Too much data was provided for a write  
***ECMD\_DATA\_UNDERFLOW*** Too little data was provided to a write function  
***ECMD\_TARGET\_NOT\_CONFIGURED*** if target is not available in the system  
***ECMD\_CLOCKS\_IN\_INVALID\_STATE*** Chip Clocks were in an invalid state to perform the operation  
***ECMD\_RING\_CACHE\_ENABLED*** Ring Cache enabled function - must be disabled to use this function



**Parameters:**

*i\_target* Struct that contains chip and cage/node/slot/position information of ring to write  
*i\_address* Address of ring to write to  
*i\_bitLength* Bit Length to scan for  
*i\_data* DataBuffer object that holds data to write into ring

**See also:**

**getRingWithModifier**(p. 148)

NOTE : This is a debug interface and should not be used in normal situations

NOTE : This function does not handle processor cores for you, the *i\_address* will be taken and used with no modifications so you are responsible for specifying the correct core address

NOTE : This function will only scan for the length provided, if this length doesn't match the actual length of the ring corruption may occur

TARGET DEPTH : Pos

TARGET STATES : Unused

**6.4.2.26** `uint32_t getScom (ecmdChipTarget & i_target, uint32_t i_address, ecmdDataBuffer & o_data)`

Scoms bits from the selected address into the data buffer.

**Return values:**

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation  
**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function  
**ECMD\_SUCCESS** if successful  
**nonzero** if unsuccessful

**Parameters:**

*i\_target* Struct that contains chip and cage/node/slot/position/core information of scom address to read  
*i\_address* Scom address to read from  
*o\_data* DataBuffer object that holds data read from address

**See also:**

**putScom**(p. 150)

NOTE : For processor cores, only "core0 only" addresses are supported, other core addresses cause a failure

TARGET DEPTH : Core

TARGET STATES : Unused

#### 6.4.2.27 uint32\_t putScom (ecmdChipTarget & *i\_target*, uint32\_t *i\_address*, ecmdDataBuffer & *i\_data*)

Scoms bits from the data buffer into the selected address.

##### Return values:

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation  
**ECMD\_DATA\_OVERFLOW** Too much data was provided for a write  
**ECMD\_DATA\_UNDERFLOW** Too little data was provided to a write function  
**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function  
**ECMD\_SUCCESS** if successful  
**nonzero** if unsuccessful

##### Parameters:

***i\_target*** Struct that contains chip and cage/node/slot/position/core information of scom address to write  
***i\_address*** Scom address to write to  
***i\_data*** DataBuffer object that holds data to write into address

##### See also:

**getScom**(p. 149)

NOTE : For processor cores, only "core0 only" addresses are supported, other core addresses cause a failure

TARGET DEPTH : Core

TARGET STATES : Unused

#### 6.4.2.28 uint32\_t sendCmd (ecmdChipTarget & *i\_target*, uint32\_t *i\_instruction*, uint32\_t *i\_modifier*, ecmdDataBuffer & *o\_status*)

Send a JTAG instruction and modifier to the specified chip.

##### Parameters:

***i\_target*** Struct that contains chip and cage/node/slot/position information of scom address to write  
***i\_instruction*** Right aligned instruction to send to chip  
***i\_modifier*** Right aligned instruction modifier to send  
***o\_status*** Instruction status register value retrieved

##### Return values:

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function  
**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_SUCCESS** if successful

***ECMD\_NON\_JTAG\_CHIP*** Chip Target is a non-jtag attached chip  
***nonzero*** if unsuccessful

NOTE : Proper parity will be generated on the command and modifier

TARGET DEPTH : Pos

TARGET STATES : Unused

#### 6.4.2.29 uint32\_t getCfamRegister (ecmdChipTarget & *i\_target*, uint32\_t *i\_address*, ecmdDataBuffer & *o\_data*)

Read data from the selected CFAM register address into the data buffer.

Return values:

***ECMD\_TARGET\_NOT\_CONFIGURED*** if target is not available in the system

***ECMD\_SUCCESS*** if successful

***nonzero*** if unsuccessful

***ECMD\_RING\_CACHE\_ENABLED*** Ring Cache enabled function - must be disabled to use this function

***ECMD\_NON\_FSI\_CHIP*** Targetted chip is not attached via FSI

Parameters:

***i\_target*** Struct that contains chip and cage/node/slot/position information

***i\_address*** CFAM address to read from

***o\_data*** DataBuffer object that holds data read from address

TARGET DEPTH : Pos

TARGET STATES : Unused

#### 6.4.2.30 uint32\_t putCfamRegister (ecmdChipTarget & *i\_target*, uint32\_t *i\_address*, ecmdDataBuffer & *i\_data*)

Write data into the selected CFAM register address.

Return values:

***ECMD\_TARGET\_NOT\_CONFIGURED*** if target is not available in the system

***ECMD\_DATA\_OVERFLOW*** Too much data was provided for a write

***ECMD\_DATA\_UNDERFLOW*** Too little data was provided to a write function

***ECMD\_RING\_CACHE\_ENABLED*** Ring Cache enabled function - must be disabled to use this function

***ECMD\_SUCCESS*** if successful

***ECMD\_NON\_FSI\_CHIP*** Targetted chip is not attached via FSI

***nonzero*** if unsuccessful

Parameters:

***i\_target*** Struct that contains chip and cage/node/slot/position information

***i\_address*** CFAM address to write to

*i\_data* DataBuffer object that holds data to write into address

TARGET DEPTH : Pos

TARGET STATES : Unused

**6.4.2.31** `uint32_t getSpy (ecmdChipTarget & i_target, const char * i_spyName, ecmdDataBuffer & o_data)`

Reads the selected spy into the data buffer.

**Return values:**

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system

**ECMD\_SPY\_FAILED\_ECC\_CHECK** if invalid ECC detected on Spy read

**ECMD\_INVALID\_SPY** Spy name is invalid or Spy is an ECC Grouping

**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation

**ECMD\_SPY\_IS\_EDIAL** Spy is an edial have to use getSpyEnum

**ECMD\_SPY\_GROUP\_MISMATCH** A mismatch was found reading a group spy not all groups set the same

**ECMD\_SUCCESS** if successful read

**nonzero** if unsuccessful

**Parameters:**

*i\_target* Struct that contains chip and cage/node/slot/position/core information of spy to read

*i\_spyName* Name of spy to read from

*o\_data* DataBuffer object that holds data read from spy

NOTE : This function is ring cache enabled

TARGET DEPTH : Core

TARGET STATES : Unused

**6.4.2.32** `uint32_t getSpyEnum (ecmdChipTarget & i_target, const char * i_spyName, std::string & o_enumValue)`

Reads the selected spy and returns it's associated enum.

**Return values:**

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system

**ECMD\_SPY\_FAILED\_ECC\_CHECK** if invalid ECC detected on Spy read - valid Spy Data still returned

**ECMD\_INVALID\_SPY** Spy name is invalid or Spy is an ECC Grouping

**ECMD\_INVALID\_SPY\_ENUM** if value in hardware doesn't map to a valid enum

**ECMD\_SPY\_NOT\_ENUMERATED** Spy is not enumerated must use getSpy

**ECMD\_SPY\_GROUP\_MISMATCH** A mismatch was found reading a group spy not all groups set the same

**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation

**ECMD\_SUCCESS** if successful read

**nonzero** if unsuccessful

**Parameters:**

**i\_target** Struct that contains chip and cage/node/slot/position/core information of spy to read

**i\_spyName** Name of spy to read from

**o\_enumValue** Enum value read from the spy

NOTE : This function is ring cache enabled

TARGET DEPTH : Core

TARGET STATES : Unused

**6.4.2.33** `uint32_t getSpyEpCheckers (ecmdChipTarget & i_target, const char * i_spyEpCheckersName, ecmdDataBuffer & o_inLatchData, ecmdDataBuffer & o_outLatchData, ecmdDataBuffer & o_eccErrorMask)`

Read an ECC grouping and return the in and out bits as well as a error mask if any out bits are invalid.

**Return values:**

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system

**ECMD\_SUCCESS** if successful

**ECMD\_INVALID\_SPY** Spy name is invalid or Spy is not an ECC Grouping

**ECMD\_SPY\_FAILED\_ECC\_CHECK** if invalid ECC detected on Spy read - valid Spy Data still returned

**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation

**nonzero** if unsuccessful

**Parameters:**

**i\_target** Struct that contains chip and cage/node/slot/position/core information of spy to read

**i\_spyEpCheckersName** Name of spy to read from

**o\_inLatchData** Return the data for the input to the eccGroup

**o\_outLatchData** Return the Ecc data associated with the outbits of the eccGroup

**o\_eccErrorMask** Return a mask for the Ecc data a 1 in the mask means the associated eccData was in error

**Return values:**

**nonzero** if unsuccessful

NOTE : This function is ring cache enabled

TARGET DEPTH : Core

TARGET STATES : Unused

#### 6.4.2.34 uint32\_t getSpyGroups (ecmdChipTarget & *i\_target*, const char \* *i\_spyName*, std::list< ecmdSpyGroupData > & *o\_groups*)

Reads the selected spy and load all the spy groups into provided list.

##### Return values:

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_SPY\_FAILED\_ECC\_CHECK** if invalid ECC detected on Spy read  
**ECMD\_INVALID\_SPY** Spy name is invalid or Spy is an ECC Grouping  
**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation  
**ECMD\_SPY\_IS\_EDIAL** Spy is an edial have to use getSpyEnum  
**ECMD\_SUCCESS** if successful read  
**nonzero** if unsuccessful

##### Parameters:

***i\_target*** Struct that contains chip and cage/node/slot/position/core information of spy to read  
***i\_spyName*** Name of spy to read from  
***o\_groups*** List of structures containing the group data and deadbits mask

NOTE : This function is ring cache enabled

TARGET DEPTH : Core

TARGET STATES : Unused

#### 6.4.2.35 uint32\_t putSpy (ecmdChipTarget & *i\_target*, const char \* *i\_spyName*, ecmdDataBuffer & *i\_data*)

Writes the data buffer into the selected spy.

##### Return values:

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_SUCCESS** if successful  
**ECMD\_INVALID\_SPY** Spy name is invalid or Spy is an ECC Grouping  
**ECMD\_DATA\_OVERFLOW** Too much data was provided for a write  
**ECMD\_DATA\_UNDERFLOW** Too little data was provided to a write function  
**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation  
**ECMD\_SPY\_IS\_EDIAL** Spy is an edial have to use putSpyEnum  
**nonzero** if unsuccessful

##### Parameters:

***i\_target*** Struct that contains chip and cage/node/slot/position/core information of spy to write  
***i\_spyName*** Name of spy to write to  
***i\_data*** DataBuffer object that holds data to write into spy

NOTE : This function is ring cache enabled

TARGET DEPTH : Core

TARGET STATES : Unused

### 6.4.2.36 uint32\_t putSpyEnum (ecmdChipTarget & i\_target, const char \* i\_spyName, const std::string i\_enumValue)

Writes the enum into the selected spy.

#### Return values:

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_SUCCESS** if successful  
**ECMD\_INVALID\_SPY** Spy name is invalid or Spy is an ECC Grouping 2retval  
**ECMD\_SPY\_NOT\_ENUMERATED** Spy is not enumerated must use putSpy  
**ECMD\_INVALID\_SPY\_ENUM** if enum value specified is not valid  
**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation  
**nonzero** if unsuccessful

#### Parameters:

**i\_target** Struct that contains chip and cage/node/slot/position/core information of spy to write  
**i\_spyName** Name of spy to write to  
**i\_enumValue** String enum value to load into the spy

NOTE : This function is ring cache enabled

TARGET DEPTH : Core

TARGET STATES : Unused

### 6.4.2.37 void ecmdEnableRingCache ()

Enables internal caching of read/writes of scan rings to the chip for functions like getring/getspy/getspr.

#### Postcondition:

Ring caching is enabled on cache enabled functions

- Functions that support caching are documented in the detailed description of the function
- Functions that do not affect the state of the cache are documented in the detailed description of the function
- Any non-cache enabled function will force a flush of the cache before performing the operation
- Some Dll's may not support ring caching, they will not fail on these functions but you will not see the performance gains

### 6.4.2.38 uint32\_t ecmdDisableRingCache ()

Disable internal caching of reads/writes of scan rings.

#### Return values:

**ECMD\_SUCCESS** if successful  
**nonzero** if unsuccessful

NOTE: A Flush of the cache is performed before disabling the cache

**6.4.2.39 uint32\_t ecmdFlushRingCache ()**

Flush all modified data from the internal cache to the hardware, then remove all rings from cache.

**Return values:**

*ECMD\_SUCCESS* if successful

*nonzero* if unsuccessful

**6.4.2.40 bool ecmdIsRingCacheEnabled ()**

Returns true/false to signify if caching is currently enabled.

**Return values:**

*true* if ring caching is enabled

*false* if ring caching is disabled

**6.4.2.41 uint32\_t getArray (ecmdChipTarget & i\_target, const char \* i\_arrayName, ecmdDataBuffer & i\_address, ecmdDataBuffer & o\_data)**

Reads bits from the selected array into the data buffer.

**Return values:**

*ECMD\_TARGET\_NOT\_CONFIGURED* if target is not available in the system

*ECMD\_INVALID\_ARRAY* if i\_arrayName is not valid for target

*ECMD\_CLOCKS\_IN\_INVALID\_STATE* Chip Clocks were in an invalid state to perform the operation

*ECMD\_RING\_CACHE\_ENABLED* Ring Cache enabled function - must be disabled to use this function

*ECMD\_SUCCESS* if successful

*nonzero* if unsuccessful

**Parameters:**

*i\_target* Struct that contains chip and cage/node/slot/position information of array to read

*i\_arrayName* Name of array to read from

*o\_data* DataBuffer object that holds data read from address

*i\_address* Array Address to read from - length of DataBuffer should be set to length of valid address data

**See also:**

**putArray**(p. 157)

**getArrayMultiple**(p. 157)

TARGET DEPTH : Pos

TARGET STATES : Unused



#### 6.4.2.42 uint32\_t getArrayMultiple (ecmdChipTarget & *i\_target*, const char \* *i\_arrayName*, std::list< ecmdArrayEntry > & *io\_entries*)

Reads bits from multiple array addresses/elements into the list of data buffers.

##### Return values:

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_INVALID\_ARRAY** if *i\_arrayName* is not valid for target  
**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation  
**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function  
**ECMD\_SUCCESS** if successful  
**nonzero** if unsuccessful

##### Parameters:

*i\_target* Struct that contains chip and cage/node/slot/position information of array to read  
*i\_arrayName* Name of array to read from  
*io\_entries* list of array entries to fetch

##### See also:

**putArray**(p. 157)  
**getArray**(p. 156)

NOTE : To use this function the *io\_entries* list should be pre-loaded with the addresses to fetch, the associated dataBuffers will be loaded upon return

The return value of this function is set to the first non-zero return code found when retrieving multiple entries. The entry that caused the failure in the list will also be marked with the same return code. That data and all subsequent entries in the list will not be fetched and the data should be considered invalid.

TARGET DEPTH : Pos

TARGET STATES : Unused

#### 6.4.2.43 uint32\_t putArray (ecmdChipTarget & *i\_target*, const char \* *i\_arrayName*, ecmdDataBuffer & *i\_address*, ecmdDataBuffer & *i\_data*)

Writes bits from the data buffer into the selected array.

##### Return values:

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_INVALID\_ARRAY** if *i\_arrayName* is not valid for target  
**ECMD\_DATA\_OVERFLOW** Too much data was provided for a write  
**ECMD\_DATA\_UNDERFLOW** Too little data was provided to a write function  
**ECMD\_SUCCESS** if successful  
**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function  
**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation

*nonzero* if unsuccessful

**ECMD\_DATA\_OVERFLOW** Too much data was provided for a write

**Parameters:**

*i\_target* Struct that contains chip and cage/node/slot/position information of array to write

*i\_arrayName* Name of array to write to

*i\_data* DataBuffer object that holds data to write into array

*i\_address* Array Address to write to - length of DataBuffer should be set to length of valid address data

**See also:**

`getArray`(p. 156)

TARGET DEPTH : Pos

TARGET STATES : Unused

**6.4.2.44** `uint32_t putArrayMultiple (ecmdChipTarget & i_target, const char * i_arrayName, std::list< ecmdArrayEntry > & i_entries)`

Writes bits from the list of entries into the selected array.

**Return values:**

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system

**ECMD\_INVALID\_ARRAY** if *i\_arrayName* is not valid for target

**ECMD\_DATA\_OVERFLOW** Too much data was provided for a write

**ECMD\_DATA\_UNDERFLOW** Too little data was provided to a write function

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function

**ECMD\_SUCCESS** if successful

**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation

*nonzero* if unsuccessful

**ECMD\_DATA\_OVERFLOW** Too much data was provided for a write

**Parameters:**

*i\_target* Struct that contains chip and cage/node/slot/position information of array to write

*i\_arrayName* Name of array to write to

*i\_entries* List of addresses and data to write to chip

**See also:**

`getArray`(p. 156)

NOTE : *i\_entries* should be pre-loaded with address and data

The return value of this function is set to the first non-zero return code found when writing multiple entries. The function will NOT continue through all subsequent entries.

TARGET DEPTH : Pos

TARGET STATES : Unused

**6.4.2.45** `uint32_t ecmdQueryClockState (ecmdChipTarget & i_target, const char * i_clockDomain, ecmdClockState_t & o_clockState)`

Query the state of the clocks for a domain.

**Return values:**

**ECMD\_SUCCESS** if successful

**nonzero** if unsuccessful

**ECMD\_INVALID\_CLOCK\_DOMAIN** An invalid clock domain name was specified

**Parameters:**

**i\_target** Struct that contains chip and cage/node/slot/position information

**i\_clockDomain** Clock domain to query - as defined in scandef - use "ALL" to check all domains

**o\_clockState** State of clocks for that domain

TARGET DEPTH : Core

TARGET STATES : Must be Initialized

**6.4.2.46** `uint32_t startClocks (ecmdChipTarget & i_target, const char * i_clockDomain, bool i_forceState = false)`

Start the clocks in the domain specified.

**Return values:**

**ECMD\_SUCCESS** if successful

**nonzero** if unsuccessful

**ECMD\_INVALID\_CLOCK\_DOMAIN** An invalid clock domain name was specified

**ECMD\_CLOCKS\_ALREADY\_ON** The clocks in the specified domain are already on

**ECMD\_CLOCKS\_IN\_INVALID\_STATE** The clock in the specified domain are in an unknown state (not all on/off)

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function

**Parameters:**

**i\_target** Struct that contains chip and cage/node/slot/position information

**i\_clockDomain** Clock domain to start - as defined in scandef - use "ALL" to start all domains

**i\_forceState** Force the clocks into the appropriate state - ignore if not in correct state to start

NOTE : If i\_target refers to a particular chip object the i\_clockDomain has to be "ALL" or a clock domain as defined in the scandef If i\_target refers to a Cage/node then i\_clockDomain has to be "ALL" or one of the predefined convenience clock domains as documented in the eCMD system spec for your particular product.

TARGET DEPTH : Core

TARGET STATES : Must be Initialized

**6.4.2.47** `uint32_t stopClocks (ecmdChipTarget & i_target, const char *  
i_clockDomain, bool i_forceState = false)`

Stop the clocks in the domain specified.

**Return values:**

**ECMD\_SUCCESS** if successful

**nonzero** if unsuccessful

**ECMD\_INVALID\_CLOCK\_DOMAIN** An invalid clock domain name was specified

**ECMD\_CLOCKS\_ALREADY\_OFF** The clocks in the specified domain are already off

**ECMD\_CLOCKS\_IN\_INVALID\_STATE** The clock in the specified domain are in an unknown state (not all on/off)

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function

**Parameters:**

**i\_target** Struct that contains chip and cage/node/slot/position information

**i\_clockDomain** Clock domain to stop - as defined in scandef - use "ALL" to stop all domains

**i\_forceState** Force the clocks into the appropriate state - ignore if not in correct state to start

NOTE : If i\_target refers to a particular chip object the i\_clockDomain has to be "ALL" or a clock domain as defined in the scandef If i\_target refers to a Cage/node then i\_clockDomain has to be "ALL" or one of the predefined convenience clock domains as documented in the eCMD system spec for your particular product.

TARGET DEPTH : Core

TARGET STATES : Must be Initialized

**6.4.2.48** `uint32_t ecmdSetClockSpeed (ecmdChipTarget & i_target,  
ecmdClockType_t i_type, uint32_t i_speed, ecmdClockSpeedType_t  
i_speedType, ecmdClockSetMode_t i_mode, ecmdClockRange_t  
i_range)`

Change a system clock speed without adjusting system initialization settings using speed value.

**Parameters:**

**i\_target** Struct that contains chip and cage information

**i\_type** Clock type to change in system

**i\_speed** New speed value, specified in Mhz or micro-seconds based on i\_speedType

**i\_speedType** Specifies if i\_speed is provided in frequency or cycle time

**i\_mode** Do adjustment in one step or steer the clock to the new value

**i\_range** Adjustments for the clock steer procedure

**Return values:**

**ECMD\_SUCCESS** if successful

**nonzero** if unsuccessful

TARGET DEPTH : Cage

TARGET STATES : Unused

**6.4.2.49** `uint32_t ecmdSetClockMultDiv (ecmdChipTarget & i_target,  
ecmdClockType_t i_type, uint32_t i_multiplier, uint32_t i_divider)`

Change a system clock speed without adjusting system initialization settings using speed value.

**Parameters:**

*i\_target* Struct that contains chip and cage information

*i\_type* Clock type to change in system

*i\_multiplier* Multiplier to use to program clock

*i\_divider* Divider value to use to program clock

**Return values:**

***ECMD\_SUCCESS*** if successful

***nonzero*** if unsuccessful

TARGET DEPTH : Cage

TARGET STATES : Unused

**6.4.2.50** `uint32_t iStepsByNumber (ecmdDataBuffer & i_steps)`

Run iSteps by number.

**Return values:**

***ECMD\_RING\_CACHE\_ENABLED*** Ring Cache enabled function - must be disabled to use this function

***ECMD\_ISTEPS\_INVALID\_STEP*** An invalid step number was provided

***ECMD\_SUCCESS*** if successful

***nonzero*** if unsuccessful

**Postcondition:**

iSteps specified are complete

**Parameters:**

*i\_steps* Bit mask defining which steps to run

NOTE - function returns on first failure and remaining steps are not run

**6.4.2.51** `uint32_t iStepsByName (std::string i_stepName)`

Run a single iStep by name.

**Return values:**

***ECMD\_RING\_CACHE\_ENABLED*** Ring Cache enabled function - must be disabled to use this function

***ECMD\_ISTEPS\_INVALID\_STEP*** An invalid step name was provided

***ECMD\_SUCCESS*** if successful

***nonzero*** if unsuccessful

**Postcondition:**

iStep specified is complete

**Parameters:**

*i\_stepName* List of iStep names to run

**6.4.2.52 uint32\_t iStepsByNameMultiple (std::list< std::string > i\_stepNames)**

Run multiple iSteps by name.

**Return values:**

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function

**ECMD\_ISTEPS\_INVALID\_STEP** An invalid step name was provided

**ECMD\_SUCCESS** if successful

**nonzero** if unsuccessful

**Postcondition:**

iSteps specified are complete

**Parameters:**

*i\_stepNames* List of iStep names to run

NOTE - Steps are run in order as is appropriate for proper system configuration, not by order provided in list

NOTE - function returns on first failure and remaining steps are not run

**6.4.2.53 uint32\_t iStepsByNameRange (std::string i\_stepNameBegin, std::string i\_stepNameEnd)**

Run all iSteps by name starting with i\_stepNameBegin and ending with i\_stepNameEnd.

**Return values:**

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function

**ECMD\_ISTEPS\_INVALID\_STEP** An invalid step name was provided

**ECMD\_SUCCESS** if successful

**nonzero** if unsuccessful

**Postcondition:**

iSteps specified are complete

**Parameters:**

*i\_stepNameBegin* Starting iStep to run

*i\_stepNameEnd* Ending iStep to run

NOTE - function returns on first failure and remaining steps are not run

**6.4.2.54** `uint32_t ecmdQueryProcRegisterInfo (ecmdChipTarget & i_target, const char * i_name, ecmdProcRegisterInfo & o_data)`

Query Information about a Processor Register (SPR/GPR/FPR).

**Parameters:**

*i\_target* Struct that contains chip and cage/node/slot/position/core/thread information  
*i\_name* Name of the Register to fetch data about (can be either a specific SPR or GPR/FPR)  
*o\_data* Data retrieved about the register

**Return values:**

*ECMD\_TARGET\_INVALID\_TYPE* if target is not a processor  
*ECMD\_TARGET\_NOT\_CONFIGURED* if target is not available in the system  
*ECMD\_INVALID\_SPR* Spr name is invalid  
*ECMD\_SUCCESS* if successful read  
*nonzero* if unsuccessful

TARGET DEPTH : Thread

TARGET STATES : Unused

**6.4.2.55** `uint32_t getSpr (ecmdChipTarget & i_target, const char * i_sprName, ecmdDataBuffer & o_data)`

Reads the selected Processor Architected Special Purpose Register (SPR) into the data buffer.

**Return values:**

*ECMD\_TARGET\_INVALID\_TYPE* if target is not a processor  
*ECMD\_TARGET\_NOT\_CONFIGURED* if target is not available in the system  
*ECMD\_INVALID\_SPR* Spr name is invalid  
*ECMD\_CLOCKS\_IN\_INVALID\_STATE* Chip Clocks were in an invalid state to perform the operation  
*ECMD\_RING\_CACHE\_ENABLED* Ring Cache enabled function - must be disabled to use this function  
*ECMD\_SUCCESS* if successful read  
*nonzero* if unsuccessful

**Parameters:**

*i\_target* Struct that contains chip and cage/node/slot/position/core/thread information  
*i\_sprName* Name of spr to read from  
*o\_data* DataBuffer object that holds data read from spr

TARGET DEPTH : Thread

TARGET STATES : Unused

#### 6.4.2.56 uint32\_t getSprMultiple (ecmdChipTarget & i\_target, std::list<ecmdNameEntry > & io\_entries)

Reads the selected Processor Architected Special Purpose Register (SPR) into the data buffer.

##### Return values:

**ECMD\_TARGET\_INVALID\_TYPE** if target is not a processor  
**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_INVALID\_SPR** Spr name is invalid  
**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation  
**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function  
**ECMD\_SUCCESS** if successful read  
**nonzero** if unsuccessful

##### Parameters:

**i\_target** Struct that contains chip and cage/node/slot/position/core/thread information  
**io\_entries** List of entries to fetch **ecmdNameEntry.name**(p.81) field must be filled in

- NOTE : There are special keywords that can be specified to fetch groups of entries, they are used by adding only an entry to **io\_entries** and setting **ecmdNameEntry.name**(p.81) = -keyword-
  - "ALLTHREADED" : To fetch all threaded (replicated) SPR's for particular target
  - "ALLSHARED" : To fetch all non-threaded SPR's for particular target

The return value of this function is set to the first non-zero return code found when retrieving multiple entries. The entry that caused the failure in the list will also be marked with the same return code. That data and all subsequent entries in the list will not be fetched and the data should be considered invalid.

TARGET DEPTH : Thread

TARGET STATES : Unused

#### 6.4.2.57 uint32\_t putSpr (ecmdChipTarget & i\_target, const char \* i\_sprName, ecmdDataBuffer & i\_data)

Writes the data buffer into the selected Processor Architected Special Purpose Register (SPR).

##### Return values:

**ECMD\_TARGET\_INVALID\_TYPE** if target is not a processor  
**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_SUCCESS** if successful  
**ECMD\_INVALID\_SPR** Spr name is invalid  
**ECMD\_DATA\_OVERFLOW** Too much data was provided for a write  
**ECMD\_DATA\_UNDERFLOW** Too little data was provided to a write function  
**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function



**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation

**nonzero** if unsuccessful

**Parameters:**

**i\_target** Struct that contains chip and cage/node/slot/position/core/thread information

**i\_sprName** Name of spr to write to

**i\_data** DataBuffer object that holds data to write into spr

TARGET DEPTH : Thread

TARGET STATES : Unused

#### 6.4.2.58 uint32\_t putSprMultiple (ecmdChipTarget & i\_target, std::list<ecmdNameEntry > & i\_entries)

Writes the data buffer into the selected Processor Architected Special Purpose Register (SPR).

**Return values:**

**ECMD\_TARGET\_INVALID\_TYPE** if target is not a processor

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system

**ECMD\_SUCCESS** if successful

**ECMD\_INVALID\_SPR** Spr name is invalid

**ECMD\_DATA\_OVERFLOW** Too much data was provided for a write

**ECMD\_DATA\_UNDERFLOW** Too little data was provided to a write function

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function

**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation

**nonzero** if unsuccessful

**Parameters:**

**i\_target** Struct that contains chip and cage/node/slot/position/core/thread information

**i\_entries** List of entries to write all **ecmdNameEntry**(p. 81) fields must be filled in

The return value of this function is set to the first non-zero return code found when writing multiple entries. The function will NOT continue through all subsequent entries.

TARGET DEPTH : Thread

TARGET STATES : Unused

#### 6.4.2.59 uint32\_t getGpr (ecmdChipTarget & i\_target, uint32\_t i\_gprNum, ecmdDataBuffer & o\_data)

Reads the selected Processor Architected General Purpose Register (GPR) into the data buffer.

**Return values:**

**ECMD\_TARGET\_INVALID\_TYPE** if target is not a processor

***ECMD\_TARGET\_NOT\_CONFIGURED*** if target is not available in the system  
***ECMD\_INVALID\_GPR*** Gpr number is invalid  
***ECMD\_CLOCKS\_IN\_INVALID\_STATE*** Chip Clocks were in an invalid state to perform the operation  
***ECMD\_RING\_CACHE\_ENABLED*** Ring Cache enabled function - must be disabled to use this function  
***ECMD\_SUCCESS*** if successful read  
***nonzero*** if unsuccessful

**Parameters:**

***i\_target*** Struct that contains chip and cage/node/slot/position/core/thread information  
***i\_gprNum*** Number of gpr to read from  
***o\_data*** DataBuffer object that holds data read from gpr

TARGET DEPTH : Thread

TARGET STATES : Unused

**6.4.2.60** `uint32_t getGprMultiple (ecmdChipTarget & i_target, std::list< ecmdIndexEntry > & io_entries)`

Reads the selected Processor Architected General Purpose Register (GPR) into the data buffer.

**Return values:**

***ECMD\_TARGET\_INVALID\_TYPE*** if target is not a processor  
***ECMD\_TARGET\_NOT\_CONFIGURED*** if target is not available in the system  
***ECMD\_INVALID\_GPR*** Gpr number is invalid  
***ECMD\_CLOCKS\_IN\_INVALID\_STATE*** Chip Clocks were in an invalid state to perform the operation  
***ECMD\_RING\_CACHE\_ENABLED*** Ring Cache enabled function - must be disabled to use this function  
***ECMD\_SUCCESS*** if successful read  
***nonzero*** if unsuccessful

**Parameters:**

***i\_target*** Struct that contains chip and cage/node/slot/position/core/thread information  
***io\_entries*** List of entries to fetch ***ecmdIndexEntry.index***(p. 71) field must be filled in

The return value of this function is set to the first non-zero return code found when retrieving multiple entries. The entry that caused the failure in the list will also be marked with the same return code. That data and all subsequent entries in the list will not be fetched and the data should be considered invalid.

TARGET DEPTH : Thread

TARGET STATES : Unused

#### 6.4.2.61 uint32\_t putGpr (ecmdChipTarget & *i\_target*, uint32\_t *i\_gprNum*, ecmdDataBuffer & *i\_data*)

Writes the data buffer into the selected Processor Architected General Purpose Register (GPR).

Return values:

**ECMD\_TARGET\_INVALID\_TYPE** if target is not a processor  
**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_INVALID\_GPR** Gpr number is invalid  
**ECMD\_SUCCESS** if successful  
**ECMD\_DATA\_OVERFLOW** Too much data was provided for a write  
**ECMD\_DATA\_UNDERFLOW** Too little data was provided to a write function  
**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function  
**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation  
**nonzero** if unsuccessful

Parameters:

***i\_target*** Struct that contains chip and cage/node/slot/position/core/thread information  
***i\_gprNum*** Number of gpr to write to  
***i\_data*** DataBuffer object that holds data to write into gpr

TARGET DEPTH : Thread

TARGET STATES : Unused

#### 6.4.2.62 uint32\_t putGprMultiple (ecmdChipTarget & *i\_target*, std::list<ecmdIndexEntry > & *i\_entries*)

Writes the data buffer into the selected Processor Architected General Purpose Register (GPR).

Return values:

**ECMD\_TARGET\_INVALID\_TYPE** if target is not a processor  
**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_INVALID\_GPR** Gpr number is invalid  
**ECMD\_SUCCESS** if successful  
**ECMD\_DATA\_OVERFLOW** Too much data was provided for a write  
**ECMD\_DATA\_UNDERFLOW** Too little data was provided to a write function  
**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function  
**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation  
**nonzero** if unsuccessful

Parameters:

***i\_target*** Struct that contains chip and cage/node/slot/position/core/thread information

*i\_entries* List of entries to write all **ecmdIndexEntry**(p. 71) fields must be filled in

The return value of this function is set to the first non-zero return code found when writing multiple entries. The function will NOT continue through all subsequent entries.

TARGET DEPTH : Thread

TARGET STATES : Unused

**6.4.2.63** `uint32_t getFpr (ecmdChipTarget & i_target, uint32_t i_fprNum, ecmdDataBuffer & o_data)`

Reads the selected Processor Architected Floating Point Register (FPR) into the data buffer.

**Return values:**

**ECMD\_TARGET\_INVALID\_TYPE** if target is not a processor

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system

**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation

**ECMD\_INVALID\_FPR** Fpr number is invalid

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function

**ECMD\_SUCCESS** if successful read

**nonzero** if unsuccessful

**Parameters:**

*i\_target* Struct that contains chip and cage/node/slot/position/core/thread information

*i\_fprNum* Number of fpr to read from

*o\_data* DataBuffer object that holds data read from fpr

TARGET DEPTH : Thread

TARGET STATES : Unused

**6.4.2.64** `uint32_t getFprMultiple (ecmdChipTarget & i_target, std::list< ecmdIndexEntry > & io_entries)`

Reads the selected Processor Architected Floating Point Register (FPR) into the data buffer.

**Return values:**

**ECMD\_TARGET\_INVALID\_TYPE** if target is not a processor

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system

**ECMD\_INVALID\_FPR** Fpr number is invalid

**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function

**ECMD\_SUCCESS** if successful read

**nonzero** if unsuccessful

**Parameters:**

- i\_target* Struct that contains chip and cage/node/slot/position/core/thread information  
*io\_entries* List of entries to fetch **ecmdIndexEntry.index**(p. 71) field must be filled in

The return value of this function is set to the first non-zero return code found when retrieving multiple entries. The entry that caused the failure in the list will also be marked with the same return code. That data and all subsequent entries in the list will not be fetched and the data should be considered invalid.

TARGET DEPTH : Thread

TARGET STATES : Unused

#### 6.4.2.65 uint32\_t putFpr (ecmdChipTarget & i\_target, uint32\_t i\_fprNum, ecmdDataBuffer & i\_data)

Writes the data buffer into the selected Processor Architected Floating Point Register (FPR).

**Return values:**

- ECMD\_TARGET\_INVALID\_TYPE** if target is not a processor  
**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_SUCCESS** if successful  
**ECMD\_INVALID\_FPR** Fpr number is invalid  
**ECMD\_DATA\_OVERFLOW** Too much data was provided for a write  
**ECMD\_DATA\_UNDERFLOW** Too little data was provided to a write function  
**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function  
**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation  
**nonzero** if unsuccessful

**Parameters:**

- i\_target* Struct that contains chip and cage/node/slot/position/core/thread information  
*i\_fprNum* Number of fpr to write to  
*i\_data* DataBuffer object that holds data to write into fpr

TARGET DEPTH : Thread

TARGET STATES : Unused

#### 6.4.2.66 uint32\_t putFprMultiple (ecmdChipTarget & i\_target, std::list< ecmdIndexEntry > & i\_entries)

Writes the data buffer into the selected Processor Architected Floating Point Register (FPR).

**Return values:**

- ECMD\_TARGET\_INVALID\_TYPE** if target is not a processor  
**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_INVALID\_FPR** Fpr number is invalid

**ECMD\_SUCCESS** if successful

**ECMD\_DATA\_OVERFLOW** Too much data was provided for a write

**ECMD\_DATA\_UNDERFLOW** Too little data was provided to a write function

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function

**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation

**nonzero** if unsuccessful

**Parameters:**

***i\_target*** Struct that contains chip and cage/node/slot/position/core/thread information

***i\_entries*** List of entries to write all **ecmdIndexEntry**(p. 71) fields must be filled in

The return value of this function is set to the first non-zero return code found when writing multiple entries. The function will NOT continue through all subsequent entries.

TARGET DEPTH : Thread

TARGET STATES : Unused

**6.4.2.67** `uint32_t getSlb (ecmdChipTarget & i_target, uint32_t i_slbNum, ecmdDataBuffer & o_data)`

Reads the selected Processor SLB Entry into the data buffer.

**Return values:**

**ECMD\_TARGET\_INVALID\_TYPE** if target is not a processor

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system

**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation

**ECMD\_INVALID\_ENTRY\_REQUESTED** Slb number is invalid

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function

**ECMD\_SUCCESS** if successful read

**nonzero** if unsuccessful

**Parameters:**

***i\_target*** Struct that contains chip and cage/node/slot/position/core/thread information

***i\_slbNum*** Number of fpr to read from

***o\_data*** DataBuffer object that holds data read from fpr

TARGET DEPTH : Thread

TARGET STATES : Unused

**6.4.2.68** `uint32_t getSlbMultiple (ecmdChipTarget & i_target, std::list< ecmdIndexEntry > & io_entries)`

Reads the selected Processor SLB Entry into the data buffer.

**Return values:**

**ECMD\_TARGET\_INVALID\_TYPE** if target is not a processor  
**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_INVALID\_ENTRY\_REQUESTED** Slb number is invalid  
**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation  
**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function  
**ECMD\_SUCCESS** if successful read  
**nonzero** if unsuccessful

**Parameters:**

**i\_target** Struct that contains chip and cage/node/slot/position/core/thread information  
**io\_entries** List of entries to fetch **ecmdIndexEntry.index**(p.71) field must be filled in with slb number

The return value of this function is set to the first non-zero return code found when retrieving multiple entries. The entry that caused the failure in the list will also be marked with the same return code. That data and all subsequent entries in the list will not be fetched and the data should be considered invalid.

TARGET DEPTH : Thread

TARGET STATES : Unused

#### 6.4.2.69 uint32\_t putSlb (ecmdChipTarget & i\_target, uint32\_t i\_slbNum, ecmdDataBuffer & i\_data)

Writes the data buffer into the selected Processor SLB Entry.

**Return values:**

**ECMD\_TARGET\_INVALID\_TYPE** if target is not a processor  
**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_SUCCESS** if successful  
**ECMD\_INVALID\_ENTRY\_REQUESTED** Slb number is invalid  
**ECMD\_DATA\_OVERFLOW** Too much data was provided for a write  
**ECMD\_DATA\_UNDERFLOW** Too little data was provided to a write function  
**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function  
**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation  
**nonzero** if unsuccessful

**Parameters:**

**i\_target** Struct that contains chip and cage/node/slot/position/core/thread information  
**i\_slbNum** Number of fpr to write to  
**i\_data** DataBuffer object that holds data to write into fpr

TARGET DEPTH : Thread

TARGET STATES : Unused

#### 6.4.2.70 uint32\_t putSlbMultiple (ecmdChipTarget & i\_target, std::list< ecmdIndexEntry > & i\_entries)

Writes the data buffer into the selected Processor SLB Entry.

##### Return values:

**ECMD\_TARGET\_INVALID\_TYPE** if target is not a processor  
**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_INVALID\_ENTRY\_REQUESTED** Slb number is invalid  
**ECMD\_SUCCESS** if successful  
**ECMD\_DATA\_OVERFLOW** Too much data was provided for a write  
**ECMD\_DATA\_UNDERFLOW** Too little data was provided to a write function  
**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function  
**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation  
**nonzero** if unsuccessful

##### Parameters:

**i\_target** Struct that contains chip and cage/node/slot/position/core/thread information  
**i\_entries** List of entries to write all **ecmdIndexEntry**(p.71) fields must be filled in with slb number

The return value of this function is set to the first non-zero return code found when writing multiple entries. The function will NOT continue through all subsequent entries.

TARGET DEPTH : Thread

TARGET STATES : Unused

#### 6.4.2.71 uint32\_t getTraceArray (ecmdChipTarget & i\_target, const char \* i\_name, bool i\_doTraceStopStart, std::vector< ecmdDataBuffer > & o\_data)

Dump all entries of specified trace array.

##### Parameters:

**i\_target** Target info to specify what to configure (target states must be set)  
**i\_name** Name of trace array - names may vary for each product/chip  
**i\_doTraceStopStart** If true disable trace arrays before logging and renewable after completion, if false client is in control  
**o\_data** Vector of trace array data retrieved

##### Return values:

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_INVALID\_ARRAY** Invalid trace array name specified  
**ECMD\_SUCCESS** if successful

TARGET DEPTH : Core

TARGET STATES : Unused



#### 6.4.2.72 uint32\_t getTraceArrayMultiple (ecmdChipTarget & i\_target, bool i\_doTraceStopStart, std::list< ecmdNameVectorEntry > & o\_data)

Dump all entries of specified trace array.

##### Parameters:

- i\_target* Target info to specify what to configure (target states must be set)
- i\_doTraceStopStart* If true disable trace arrays before logging and renewable after completion, if false client is in control
- o\_data* List of trace array data retrieved

##### Return values:

- ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system
- ECMD\_INVALID\_ARRAY** Invalid trace array name specified
- ECMD\_SUCCESS** if successful

The return value of this function is set to the first non-zero return code found when retrieving multiple entries. The entry that caused the failure in the list will also be marked with the same return code. That data and all subsequent entries in the list will not be fetched and the data should be considered invalid.

- NOTE : to fetch all Trace Arrays available add only one entry to io\_entries and set **ecmdNameVectorEntry.name**(p. 82) = "ALL"

TARGET DEPTH : Core

TARGET STATES : Unused

#### 6.4.2.73 uint32\_t getMemProc (ecmdChipTarget & i\_target, uint64\_t i\_address, uint32\_t i\_bytes, ecmdDataBuffer & o\_data)

Reads System Mainstore through the processor chip using a real address.

##### Return values:

- ECMD\_TARGET\_INVALID\_TYPE** if target is not a processor
- ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system
- ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function
- ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation
- ECMD\_SUCCESS** if successful read
- nonzero** if unsuccessful

##### Parameters:

- i\_target* Struct that contains chip and cage/node/slot/position information
- i\_address* Starting address to read from
- i\_bytes* Number of bytes to write
- o\_data* DataBuffer object that holds data read from memory

TARGET DEPTH : Pos

TARGET STATES : Unused

#### 6.4.2.74 uint32\_t putMemProc (ecmdChipTarget & i\_target, uint64\_t i\_address, uint32\_t i\_bytes, ecmdDataBuffer & i\_data)

Writes System Mainstore through the processor chip using a real address.

##### Return values:

**ECMD\_TARGET\_INVALID\_TYPE** if target is not a processor  
**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_SUCCESS** if successful  
**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function  
**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation  
**nonzero** if unsuccessful

##### Parameters:

**i\_target** Struct that contains chip and cage/node/slot/position information  
**i\_address** Starting address to write to  
**i\_bytes** Number of bytes to write  
**i\_data** DataBuffer object that holds data to write into memory

TARGET DEPTH : Pos

TARGET STATES : Unused

#### 6.4.2.75 uint32\_t getMemDma (ecmdChipTarget & i\_target, uint64\_t i\_address, uint32\_t i\_bytes, ecmdDataBuffer & o\_data)

Reads System Mainstore through the PSI or DMA interface (whichever is available) using a real address.

##### Return values:

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function  
**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation  
**ECMD\_SUCCESS** if successful read  
**nonzero** if unsuccessful

##### Parameters:

**i\_target** Struct that contains cage/node information  
**i\_address** Starting address to read from  
**i\_bytes** Number of bytes to write  
**o\_data** DataBuffer object that holds data read from memory

TARGET DEPTH : Pos

TARGET STATES : Unused

**6.4.2.76** `uint32_t putMemDma (ecmdChipTarget & i_target, uint64_t i_address, uint32_t i_bytes, ecmdDataBuffer & i_data)`

Writes System Mainstore through the PSI or DMA interface (whichever is available) using a real address.

**Return values:**

*ECMD\_TARGET\_NOT\_CONFIGURED* if target is not available in the system

*ECMD\_SUCCESS* if successful

*ECMD\_RING\_CACHE\_ENABLED* Ring Cache enabled function - must be disabled to use this function

*ECMD\_CLOCKS\_IN\_INVALID\_STATE* Chip Clocks were in an invalid state to perform the operation

*nonzero* if unsuccessful

**Parameters:**

*i\_target* Struct that contains cage/node information

*i\_address* Starting address to write to

*i\_bytes* Number of bytes to write

*i\_data* DataBuffer object that holds data to write into memory

TARGET DEPTH : Pos

TARGET STATES : Unused

**6.4.2.77** `uint32_t getMemMemCtrl (ecmdChipTarget & i_target, uint64_t i_address, uint32_t i_bytes, ecmdDataBuffer & o_data)`

Reads System Mainstore through the memory controller using a real address.

**Return values:**

*ECMD\_TARGET\_INVALID\_TYPE* if target is not a memory controller

*ECMD\_TARGET\_NOT\_CONFIGURED* if target is not available in the system

*ECMD\_RING\_CACHE\_ENABLED* Ring Cache enabled function - must be disabled to use this function

*ECMD\_CLOCKS\_IN\_INVALID\_STATE* Chip Clocks were in an invalid state to perform the operation

*ECMD\_SUCCESS* if successful read

*nonzero* if unsuccessful

**Parameters:**

*i\_target* Struct that contains chip and cage/node/slot/position information

*i\_address* Starting address to read from

*i\_bytes* Number of bytes to write

*o\_data* DataBuffer object that holds data read from memory

WARNING : This operation is typically not cache-coherent

TARGET DEPTH : Cage

TARGET STATES : Unused

**6.4.2.78** `uint32_t putMemMemCtrl (ecmdChipTarget & i_target, uint64_t i_address, uint32_t i_bytes, ecmdDataBuffer & i_data)`

Writes System Mainstore through the memory controller using a real address.

**Return values:**

***ECMD\_TARGET\_INVALID\_TYPE*** if target is not a memory controller  
***ECMD\_TARGET\_NOT\_CONFIGURED*** if target is not available in the system  
***ECMD\_SUCCESS*** if successful  
***ECMD\_RING\_CACHE\_ENABLED*** Ring Cache enabled function - must be disabled to use this function  
***ECMD\_CLOCKS\_IN\_INVALID\_STATE*** Chip Clocks were in an invalid state to perform the operation  
***nonzero*** if unsuccessful

**Parameters:**

***i\_target*** Struct that contains chip and cage/node/slot/position information  
***i\_address*** Starting address to write to  
***i\_bytes*** Number of bytes to write  
***i\_data*** DataBuffer object that holds data to write into memory

WARNING : This operation is typically not cache-coherent

TARGET DEPTH : Cage

TARGET STATES : Unused

**6.4.2.79** `uint32_t ecmdCacheFlush (ecmdChipTarget & i_target, ecmdCacheType_t i_cacheType)`

Cache Flush.

**Parameters:**

***i\_target*** ecmdChipTarget\_t struct defines what chip(s) to flush  
***i\_cacheType*** ecmdCacheType\_t struct defines what type of cache gets flushed

**Return values:**

***ECMD\_TARGET\_NOT\_CONFIGURED*** if target is not available in the system  
***ECMD\_SUCCESS*** if successful  
***non-zero*** if unsuccessful

TARGET DEPTH : Core

TARGET STATES : Unused

**6.4.2.80** `uint32_t simaet (const char * i_function)`

Enable/Disable Simulation AET Logging.

**Parameters:**

***i\_function*** Should be either 'on'/'off'/'flush'

**Return values:**

***ECMD\_SUCCESS*** if successful

***ECMD\_RING\_CACHE\_ENABLED*** Ring Cache enabled function - must be disabled to use this function

***nonzero*** on failure

**6.4.2.81 uint32\_t simcheckpoint (const char \* *i\_checkpoint*)**

Store a checkpoint to specified file.

**Parameters:**

***i\_checkpoint*** Name of checkpoint to write to

**Return values:**

***ECMD\_SUCCESS*** if successful

***ECMD\_RING\_CACHE\_ENABLED*** Ring Cache enabled function - must be disabled to use this function

***nonzero*** on failure

**6.4.2.82 uint32\_t simclock (uint32\_t *i\_cycles*)**

Clock the model.

**Parameters:**

***i\_cycles*** Number of cycles to clock model

**Return values:**

***ECMD\_SUCCESS*** if successful

***ECMD\_RING\_CACHE\_ENABLED*** Ring Cache enabled function - must be disabled to use this function

***nonzero*** on failure

**6.4.2.83 uint32\_t simecho (const char \* *i\_message*)**

Echo message to stdout and sim log.

**Parameters:**

***i\_message*** Message to echo

**Return values:**

***ECMD\_SUCCESS*** if successful

***ECMD\_RING\_CACHE\_ENABLED*** Ring Cache enabled function - must be disabled to use this function

***nonzero*** on failure

#### 6.4.2.84 `uint32_t simexit (uint32_t i_rc = 0, const char * i_message = NULL)`

Close down the simulation model.

##### Parameters:

*i\_rc* [Optional] Send a testcase failure return code to the simulation

*i\_message* [Optional] Send a testcase failure message to the simulation

##### Return values:

**ECMD\_SUCCESS** if successful

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function

**nonzero** on failure

#### 6.4.2.85 `uint32_t simEXPECTFAC (const char * i_facname, uint32_t i_bitlength, ecmdDataBuffer & i_expect, uint32_t i_row = 0, uint32_t i_offset = 0)`

Perform expect on facility using name.

##### Parameters:

*i\_facname* Facility name

*i\_expect* Value to expect on facility

*i\_bitlength* Length of data to expect

*i\_row* Optional: Array Facility row

*i\_offset* Optional: Facility offset

##### Return values:

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function

**ECMD\_SUCCESS** if successful

**nonzero** on failure

#### 6.4.2.86 `uint32_t simexpecttcfac (const char * i_tcfacname, uint32_t i_bitlength, ecmdDataBuffer & i_expect, uint32_t i_row = 0)`

Perform expect on TCFAC facility.

##### Parameters:

*i\_tcfacname* Facility name

*i\_expect* Value to expect on facility

*i\_bitlength* Length of data to expect

*i\_row* Optional: Array Facility row

##### Return values:

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function

**ECMD\_SUCCESS** if successful

**nonzero** on failure

**6.4.2.87 uint32\_t simgetcurrentcycle (uint64\_t & o\_cyclecount)**

Fetch current model cycle count.

**Parameters:**

*o\_cyclecount* Current model cycle count

**Return values:**

**ECMD\_SUCCESS** if successful

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function

**nonzero** on failure

**6.4.2.88 uint32\_t simGETFAC (const char \* i\_facname, uint32\_t i\_bitlength, ecmdDataBuffer & o\_data, uint32\_t i\_row = 0, uint32\_t i\_offset = 0)**

Retrieve a Facility using a name.

**Parameters:**

*i\_facname* Facility name

*i\_bitlength* Bit length to read from facility

*o\_data* Data read from facility

*i\_row* Optional: Array row

*i\_offset* Optional : Facility offset

**Return values:**

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function

**ECMD\_SUCCESS** if successful

**nonzero** on failure

**6.4.2.89 uint32\_t simGETFACX (const char \* i\_facname, uint32\_t i\_bitlength, ecmdDataBuffer & o\_data, uint32\_t i\_row = 0, uint32\_t i\_offset = 0)**

Retrieve a Facility using a name - preserving Xstate.

**Parameters:**

*i\_facname* Facility name

*i\_bitlength* Bit length to read from facility

*o\_data* Data read from facility

*i\_row* Optional: Array row

*i\_offset* Optional : Facility offset

**Return values:**

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function

**ECMD\_SUCCESS** if successful

**nonzero** on failure

**6.4.2.90** `uint32_t simgettcfac (const char * i_tcfacname, ecmdDataBuffer & o_data, uint32_t i_row = 0, uint32_t i_startbit = 0, uint32_t i_bitlength = 0)`

Retrieve a TCFAC facility.

**Parameters:**

*i\_tcfacname* TCFAC name  
*o\_data* Value read  
*i\_row* Optional: Array Facility row  
*i\_startbit* Optional: Startbit to read  
*i\_bitlength* Optional: Length of data to read

**Return values:**

***ECMD\_RING\_CACHE\_ENABLED*** Ring Cache enabled function - must be disabled to use this function  
***ECMD\_SUCCESS*** if successful  
***nonzero*** on failure

**6.4.2.91** `uint32_t siminit (const char * i_checkpoint)`

Initialize the simulation.

**Parameters:**

*i\_checkpoint* Checkpoint to load : 'none' to skip

**Return values:**

***ECMD\_RING\_CACHE\_ENABLED*** Ring Cache enabled function - must be disabled to use this function  
***ECMD\_SUCCESS*** if successful  
***nonzero*** on failure

**6.4.2.92** `uint32_t simPOLLFAC (const char * i_facname, uint32_t i_bitlength, ecmdDataBuffer & i_expect, uint32_t i_row = 0, uint32_t i_offset = 0, uint32_t i_maxcycles = 1, uint32_t i_pollinterval = 1)`

Poll a facility waiting for expected value.

**Parameters:**

*i\_facname* Facility name  
*i\_bitlength* Bit length to expect  
*i\_expect* Data to expect in facility  
*i\_row* Optional: Array row  
*i\_offset* Optional : Facility offset  
*i\_maxcycles* Optional : Maximum number of cycles to run  
*i\_pollinterval* Option : Number of clock cycles to run between each poll



**Return values:**

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function  
**ECMD\_POLLING\_FAILURE** Polling completed without reaching expected value  
**ECMD\_SUCCESS** if successful  
**nonzero** on failure

**6.4.2.93** `uint32_t simpolltcfac (const char * i_tcfacname, ecmdDataBuffer & i_expect, uint32_t i_row = 0, uint32_t i_startbit = 0, uint32_t i_bitlength = 0, uint32_t i_maxcycles = 1, uint32_t i_pollinterval = 1)`

Poll a TCFAC facility waiting for expected value.

**Parameters:**

*i\_tcfacname* Facility name  
*i\_bitlength* Bit length to expect  
*i\_expect* Data to expect in facility  
*i\_row* Optional: Array row  
*i\_startbit* Optional : Facility startbit  
*i\_maxcycles* Optional : Maximum number of cycles to run  
*i\_pollinterval* Option : Number of clock cycles to run between each poll

**Return values:**

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function  
**ECMD\_POLLING\_FAILURE** Polling completed without reaching expected value  
**ECMD\_SUCCESS** if successful  
**nonzero** on failure

**6.4.2.94** `uint32_t simPUTFAC (const char * i_facname, uint32_t i_bitlength, ecmdDataBuffer & i_data, uint32_t i_row = 0, uint32_t i_offset = 0)`

Write a Facility using a name.

**Parameters:**

*i\_facname* Facility name  
*i\_bitlength* Bit length to write to facility  
*i\_data* Data to write  
*i\_row* Optional: Array row  
*i\_offset* Optional : Facility offset

**Return values:**

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function  
**ECMD\_SUCCESS** if successful  
**nonzero** on failure

**6.4.2.95** `uint32_t simPUTFACX (const char * i_facname, uint32_t i_bitlength,  
ecmdDataBuffer & i_data, uint32_t i_row = 0, uint32_t i_offset = 0)`

Write a Facility using a name - preserving Xstate.

**Parameters:**

*i\_facname* Facility name  
*i\_bitlength* Bit length to write to facility  
*i\_data* Data to write  
*i\_row* Optional: Array row  
*i\_offset* Optional : Facility offset

**Return values:**

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled  
to use this function  
**ECMD\_SUCCESS** if successful  
*nonzero* on failure

**6.4.2.96** `uint32_t simputtcfac (const char * i_tcfacname, uint32_t i_bitlength,  
ecmdDataBuffer & i_data, uint32_t i_row = 0, uint32_t i_numrows =  
0)`

Write a TCFAC facility.

**Parameters:**

*i\_tcfacname* TCFAC name  
*i\_data* Value to write  
*i\_row* Optional: Array Facility row  
*i\_numrows* Optional: Number of rows to write  
*i\_bitlength* Bit length to write to facility

**Return values:**

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled  
to use this function  
**ECMD\_SUCCESS** if successful  
*nonzero* on failure

**6.4.2.97** `uint32_t simrestart (const char * i_checkpoint)`

Load a checkpoint into model.

**Parameters:**

*i\_checkpoint* Name of checkpoint

**Return values:**

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled  
to use this function  
**ECMD\_SUCCESS** if successful  
*nonzero* on failure

**6.4.2.98** `uint32_t simSTKFAC (const char * i_facname, uint32_t i_bitlength,  
ecmdDataBuffer & i_data, uint32_t i_row = 0, uint32_t i_offset = 0)`

Stick a Facility using a name.

**Parameters:**

*i\_facname* Facility name  
*i\_bitlength* Bit length to stick to facility  
*i\_data* Data to stick  
*i\_row* Optional: Array row  
*i\_offset* Optional : Facility offset

**Return values:**

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled  
to use this function  
**ECMD\_SUCCESS** if successful  
**nonzero** on failure

**6.4.2.99** `uint32_t simstktcfac (const char * i_tcfacname, uint32_t i_bitlength,  
ecmdDataBuffer & i_data, uint32_t i_row = 0, uint32_t i_numrows =  
0)`

Stick a TCFAC facility.

**Parameters:**

*i\_tcfacname* TCFAC name  
*i\_data* Value to stick  
*i\_row* Optional: Array Facility row  
*i\_numrows* Optional: Number of rows to stick  
*i\_bitlength* Bit length to write to facility

**Return values:**

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled  
to use this function  
**ECMD\_SUCCESS** if successful  
**nonzero** on failure

**6.4.2.100** `uint32_t simSUBCMD (const char * i_command)`

Run RTX SUBCMD.

**Parameters:**

*i\_command* Command

**Return values:**

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled  
to use this function  
**ECMD\_SUCCESS** if successful  
**nonzero** on failure

**6.4.2.101 uint32\_t simtckinterval (uint32\_t i\_tckinterval)**

Set TCK Interval setting in the model for JTAG Master.

**Parameters:**

*i\_tckinterval* new setting for tck interval when using JTAG

**Return values:**

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function

**ECMD\_SUCCESS** if successful

**nonzero** on failure

**6.4.2.102 uint32\_t simUNSTICK (const char \* i\_facname, uint32\_t i\_bitlength, uint32\_t i\_row = 0, uint32\_t i\_offset = 0)**

Unstick a Facility using a name.

**Parameters:**

*i\_facname* Facility name

*i\_bitlength* Bit length to unstick to facility

*i\_row* Optional: Array row

*i\_offset* Optional : Facility offset

**Return values:**

**ECMD\_SUCCESS** if successful

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function

**nonzero** on failure

**6.4.2.103 uint32\_t simunsticktcfac (const char \* i\_tcfacname, uint32\_t i\_bitlength, ecmdDataBuffer & i\_data, uint32\_t i\_row = 0, uint32\_t i\_numrows = 0)**

Unstick a TCFAC facility.

**Parameters:**

*i\_tcfacname* TCFAC name

*i\_data* Value to unstick to

*i\_row* Optional: Array Facility row

*i\_numrows* Optional: Number of rows to unstick

*i\_bitlength* Bit length to unstick to facility

**Return values:**

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function

**ECMD\_SUCCESS** if successful

**nonzero** on failure

#### 6.4.2.104 uint32\_t simGetHierarchy (ecmdChipTarget & i\_target, std::string & o\_hierarchy)

Fetch the hierarchy for the specified chip target relative to the latch names in the scandef.

**Return values:**

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system

**ECMD\_SUCCESS** if successful

**nonzero** if unsuccessful

**Parameters:**

**i\_target** Struct that contains chip and cage/node/slot/position/core information

**o\_hierarchy** Return the model hierarchy for this target

NOTE - To retrieve the hierarchy of a processor core the core field must be set and the state set to ECMD\_TARGET\_FIELD\_VALID

TARGET DEPTH : Core

TARGET STATES : Must be Initialized

#### 6.4.2.105 uint32\_t ecmdQueryChipSimModelVersion (ecmdChipTarget & i\_target, std::string & o\_timestamp)

Will retrieve the model timestamp from the simulation, in hardware mode "NA" is returned.

**Parameters:**

**i\_target** Target to query for information

**o\_timestamp** Timestamp value from simulation model

**Return values:**

**ECMD\_SUCCESS** on success

**non-zero** on failure

TARGET DEPTH : Pos

TARGET STATES : Unused

#### 6.4.2.106 uint32\_t ecmdQueryChipScandefVersion (ecmdChipTarget & i\_target, std::string & o\_timestamp)

Will retrieve the scandef timestamp from the scandef being used for the specified target.

**Parameters:**

**i\_target** Target to query for information

**o\_timestamp** Timestamp value from scandef

**Return values:**

**ECMD\_SUCCESS** on success

**non-zero** on failure

TARGET DEPTH : Pos

TARGET STATES : Unused

**6.4.2.107** `std::string simCallFusionCommand (const char * i_fusionObject, const char * i_replicaID, const char * i_command)`

Run a command on another Fusion module.

**Parameters:**

*i\_fusionObject* Name of Fusion module to run against  
*i\_replicaID* Id of Fusion module  
*i\_command* Command to run

**Return values:**

*Results* of command

NOTE - The fusion module has to provide the appropriate api for this call to be functional

**6.4.2.108** `uint32_t simFusionRand32 (uint32_t i_min = 0, uint32_t i_max = ~0UL, const char * i_fusionRandObject = NULL)`

Returns a random 32 bit number in the range [min,max] using the Fusion MasterSeed; by default each client will have an own instance of Fusion's Random32BitNumber object, but the user can specify the object's name and reuse the same object across multiple clients; if no range is specified 0 and MAXINT32 will be used.

**Parameters:**

*i\_min* lower bound for random number  
*i\_max* upper bound for random number  
*i\_fusionRandObject* name of Fusion random number object to use; if not specified, each this client will get a unique instance of the class

**Return values:**

*Random* number

**6.4.2.109** `uint32_t simOutputFusionMessage (const char * i_header, const char * i_message, ecmdFusionSeverity_t i_severity, ecmdFusionMessageType_t i_type, const char * i_file = NULL, uint32_t i_line = 0)`

Echo Messages to Fusion logs.

**Parameters:**

*i\_header* Message header  
*i\_message* Message text  
*i\_severity* Severity  
*i\_type* Message type  
*i\_file* File where message originated  
*i\_line* Line number where message originated

**Return values:**

*ECMD\_SUCCESS* on success  
*non-zero* on failure

**6.4.2.110 void simSetFusionMessageFormat (const char \* *i\_format*)**

Set Fusion Message Format.

**Parameters:**

*i\_format* New Format

**6.4.2.111 uint32\_t simPutDial (const char \* *i\_dialName*, const std::string *i\_enumValue*)**

Write a simulation dial with specified value.

**Parameters:**

*i\_dialName* Fully qualified dial name

*i\_enumValue* Value to set dial to either enum or numeric (ie 0b11 or 0xFE)

**Return values:**

*ECMD\_SUCCESS* on success

*non-zero* on failure

**6.4.2.112 uint32\_t simGetDial (const char \* *i\_dialName*, std::string & *o\_enumValue*)**

Read a simulation dial.

**Parameters:**

*i\_dialName* Fully qualified dial name

*o\_enumValue* Value read from model

**Return values:**

*ECMD\_SUCCESS* on success

*non-zero* on failure

**6.4.2.113 uint32\_t simGetOutFile (const char \* *i\_filename*, std::string & *o\_absFilename*)**

Obtain absolute filename of a file that will be placed in the SIMOUT directory of the server / Fusion process and add new file to the bom information in the SUM file.

**Parameters:**

*i\_filename* filename (w/o path information) of the file to create / lookup in the SIMOUT directory

*o\_absFilename* will contain the absolute filename upon successful return from the call

**Return values:**

*ECMD\_SUCCESS* on success

*non-zero* on failure

**6.4.2.114** `uint32_t simGetInFile (const char * i_filename, std::string & o_absFilename)`

Resolve absolute filename of a file by searching the SIMIN paths and add new file to the bom information in the SUM file.

**Parameters:**

*i\_filename* name (w/o path information) of the file to lookup in the SIMIN directories

*o\_absFilename* will contain the absolute filename upon successful return from the call

**Return values:**

*ECMD\_SUCCESS* on success

*non-zero* on failure

**6.4.2.115** `uint32_t simGetEnvironment (const char * i_envName, std::string & o_envValue)`

Retrieve value of an environment variable on the server side.

**Parameters:**

*i\_envName* name of environment variable to retrieve

*o\_envValue* will contain the envvar's value upon successful return from the call

**Return values:**

*ECMD\_SUCCESS* on success

*non-zero* on failure

**6.4.2.116** `uint32_t simGetModelInfo (ecmdSimModelInfo & o_modelInfo)`

Query information about the model from the server.

**Parameters:**

*o\_modelInfo* pointer to a user-provided `sd_model_info` struct; SDAPI will fill the members of this struct upon successful return from the call

**Return values:**

*ECMD\_SUCCESS* on success

*non-zero* on failure

**6.4.2.117** `std::string ecmdGetErrorMsg (uint32_t i_errorCode, bool i_parseReturnCode = true)`

Retrieve additional error information for errorcode.

**Parameters:**

*i\_errorCode* Error code to lookup up message for

*i\_parseReturnCode* If true will search through return codes definitions to return define name of error code

**Return values:**

*point* to NULL terminated string containing error data, NULL if error occurs



**6.4.2.118**    `uint32_t ecmdRegisterErrorMsg (uint32_t i_errorCode, const char *  
  i_whom, const char * i_message)`

Register an error message that has occurred.

**6.4.2.119**    `void ecmdFlushRegisteredErrorMsgs ()`

Flush all registered messages, they are no long retrievable.

**6.4.2.120**    `void ecmdOutputError (const char * i_message)`

Output a message related to an error.

**Parameters:**

*i\_message* String to output

**6.4.2.121**    `void ecmdOutputWarning (const char * i_message)`

Output a message related to an warning.

**Parameters:**

*i\_message* String to output

**6.4.2.122**    `void ecmdOutput (const char * i_message)`

Output a message to the screen or logs.

**Parameters:**

*i\_message* String to output

**6.4.2.123**    `uint32_t ecmdGetGlobalVar (ecmdGlobalVarType_t i_type)`

Retrieve the value of some ecmdGlobalVars.

**Parameters:**

*i\_type* Specifies which global var you are looking for

**Return values:**

*Value* of global var

**6.4.2.124**    `void ecmdSetTraceMode (ecmdTraceType_t i_type, bool i_enable)`

Enable/Disable a trace mode.

**Parameters:**

*i\_type* Specifies which trace mode to enable

*i\_enable* Enable or disable

**6.4.2.125 bool ecmdQueryTraceMode (ecmdTraceType\_t i\_type)**

Query the state of a trace mode.

**Parameters:**

*i\_type* Specifies which trace mode to query

**Return values:**

*Value* of trace mode enable

**6.4.2.126 uint32\_t ecmdDelay (uint32\_t i\_simCycles, uint32\_t i\_msDelay)**

Function to delay a procedure either by running sim cycles or by doing a millisecond delay.

**Parameters:**

*i\_simCycles* Number of sim cycles to run in simulation mode

*i\_msDelay* Number of milliseconds to delay in hardware mode

**Return values:**

*ECMD\_SUCCESS* on success

*non-zero* on failure

**6.4.2.127 uint32\_t makeSPSystemCall (ecmdChipTarget & i\_target, const std::string & i\_command, std::string & o\_stdout)**

Make a system call on the targetted Service Processor or Service Element.

**Parameters:**

*i\_target* SP to run command on

*i\_command* Command line call to make

*o\_stdout* Standard out captured by running command

TARGET DEPTH : Node TARGET STATES : Unused

**6.4.2.128 uint32\_t ecmdGetConfiguration (ecmdChipTarget & i\_target, std::string i\_name, ecmdConfigValid\_t & o\_validOutput, std::string & o\_valueAlpha, uint32\_t & o\_valueNumeric)**

Retrieve the value of a Configuration Setting.

**Parameters:**

*i\_target* struct that contains chip and cage/node/slot/position/core information if necessary

*i\_name* Name of setting as defined by eCMD Api

*o\_validOutput* Indicator if o\_valueAlpha, o\_valueNumeric (or both) are valid.

*o\_valueAlpha* Alpha value of setting (if appropriate)

*o\_valueNumeric* Numeric value of setting (if appropriate)

**Return values:**

***ECMD\_INVALID\_CONFIG\_NAME*** Name specified is not valid  
***ECMD\_TARGET\_NOT\_CONFIGURED*** if target is not available in the system  
***ECMD\_SUCCESS*** if successful

TARGET DEPTH : Thread (depending on value of *i\_name*)

TARGET STATES : Unused

**6.4.2.129** `uint32_t ecmdSetConfiguration (ecmdChipTarget & i_target, std::string i_name, ecmdConfigValid_t i_validInput, std::string i_valueAlpha, uint32_t i_valueNumeric)`

Set the value of a Configuration Setting.

**Parameters:**

***i\_target*** struct that contains chip and cage/node/slot/position/core information if necessary  
***i\_name*** Name of setting as defined by eCMD Api  
***i\_validInput*** Indicator if *i\_valueAlpha*, *i\_valueNumeric* (or both) are valid.  
***i\_valueAlpha*** Alpha value of setting (if appropriate)  
***i\_valueNumeric*** Numeric value of setting (if appropriate)

**Return values:**

***ECMD\_DBUF\_INVALID\_DATA\_FORMAT*** Value is not in correct format for specified configuration setting  
***ECMD\_INVALID\_CONFIG\_NAME*** Name specified is not valid  
***ECMD\_TARGET\_NOT\_CONFIGURED*** if target is not available in the system  
***ECMD\_SUCCESS*** if successful  
***nonzero*** on failure

TARGET DEPTH : Thread (depending on value of *i\_name*)

TARGET STATES : Unused

**6.4.2.130** `uint32_t ecmdDeconfigureTarget (ecmdChipTarget & i_target)`

Deconfigure a target in the system.

**Parameters:**

***i\_target*** Target info to specify what to deconfigure (target states must be set)

**Return values:**

***ECMD\_TARGET\_NOT\_CONFIGURED*** if target is not available in the system  
***ECMD\_SUCCESS*** if successful  
***nonzero*** on failure

NOTE - lowest state that is valid is level that is deconfigured.

ex - if coreState is VALID the core selected is deconfigured

ex - if coreState is UNUSED and posState is VALID then the pos is deconfigured

This interface allows you to deconfigure all levels cages, nodes, slots, pos's, cores

TARGET DEPTH : Core

TARGET STATES : Must be Initialized

#### 6.4.2.131 uint32\_t ecmdConfigureTarget (ecmdChipTarget & i\_target)

Configure a target in the system - must be previously known to the system.

##### Parameters:

*i\_target* Target info to specify what to configure (target states must be set)

##### Return values:

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system, or was not previously deconfigured

**ECMD\_SUCCESS** if successful

**nonzero** on failure

NOTE - lowest state that is valid is level that is configured.

ex - if coreState is VALID the core selected is configured

ex - if coreState is UNUSED and posState is VALID then the pos is configured

This interface allows you to configure all levels cages, nodes, slots, pos's, cores

TARGET DEPTH : Core

TARGET STATES : Must be Initialized

#### 6.4.2.132 uint32\_t ecmdTargetToUnitId (ecmdChipTarget & io\_target)

Converts an eCmd (physical) Target to a HOM Unit Id.

##### Parameters:

*io\_target* an **ecmdChipTarget**(p.20) struct representing a specific eCmd target

##### Return values:

**ECMD\_SUCCESS** if conversion successful

**ECMD\_INVALID\_ARGS** if unsuccessful in finding a matching Unit ID

##### Postcondition:

HOM Unit Ids in **ecmdChipTarget**(p.20) struct are set and valid

TARGET DEPTH : Thread

TARGET STATES : Must be Initialized

#### 6.4.2.133 uint32\_t ecmdUnitIdStringToTarget (std::string i\_unitId, std::list<ecmdChipTarget > & o\_targetList)

Converts a Unit Id String to an eCmd (physical) Target.

**Parameters:**

- i\_unitId* a string representing the name of a unitId  
*o\_targetList* a list of targets that match the input unitId string

**Return values:**

- ECMD\_SUCCESS* if conversion successful  
*ECMD\_INVALID\_ARGS* if unsuccessful in matching the string to a target

**Postcondition:**

There will be a list ecmdChipTargets that represent the passed in unitId string

**6.4.2.134** uint32\_t ecmdUnitIdToTarget (uint32\_t i\_unitId, std::list< ecmdChipTarget > & o\_targetList)

Converts a Unit Id to an eCmd (physical) Target.

**Parameters:**

- i\_unitId* a uint32\_t representing an unitID  
*o\_targetList* a list of targets that match the unitId input

**Return values:**

- ECMD\_SUCCESS* if conversion successful  
*ECMD\_INVALID\_ARGS* if unsuccessful in matching the string to a target

**Postcondition:**

ecmdChipTarget(p.20) Fields are set and represent the passed in unitId string

**6.4.2.135** uint32\_t ecmdUnitIdToString (uint32\_t i\_unitId, std::string & o\_unitIdStr)

Converts a Unit Id into its String representation.

**Parameters:**

- i\_unitId* a uint32\_t representing an unitID  
*o\_unitIdStr* a string to match the unitId input

**Return values:**

- ECMD\_SUCCESS* if conversion successful  
*ECMD\_INVALID\_ARGS* if unsuccessful in matching the unitID to a String

**Postcondition:**

HOM Unit Id String is set and represents the passed in uint32\_t unitId

**6.4.2.136** `uint32_t ecmdSequenceIdToTarget (uint32_t i_core_seq_num,  
ecmdChipTarget & io_target, uint32_t i_thread_seq_num = 0)`

Sequence ID of Cores and Threads converted to `ecmdChipTarget`(p.20) struct.

**Parameters:**

*i\_core\_seq\_num* Sequence ID number of the core  
*io\_target* `ecmdChipTarget`(p.20) struct set to the result of the conversion  
*i\_thread\_seq\_num* (OPTIONAL, default to 0) Sequence ID number of thread relative to the core parm

**Return values:**

*ECMD\_INVALID\_ARGS* the inputs could not be mapped to an `ecmdChipTarget`(p.20) struct  
*ECMD\_SUCCESS* if successful  
*non-zero* if unsuccessful

**Precondition:**

*io\_target* must have states defined to either core or thread level  
*io\_target* must have an acceptable processor chipType

**Postcondition:**

*io\_target* fields are set accordingly

TARGET DEPTH : Thread

TARGET STATES : Must be Initialized

**6.4.2.137** `uint32_t getModuleVpdKeyword (ecmdChipTarget & i_target, const  
char * i_record_name, const char * i_keyword, uint32_t i_bytes,  
ecmdDataBuffer & o_data)`

Read Module VPD Keyword Interface.

**Parameters:**

*i\_target* Struct that contains cage/node/slot/position of module vpd to access  
*i\_record\_name* Name of VPD Record for given keyword  
*i\_keyword* Name of VPD Keyword to Read  
*i\_bytes* Byte length to read  
*o\_data* Data buffer to copy data to

**Return values:**

*ECMD\_TARGET\_NOT\_CONFIGURED* if target is not available in the system  
*ECMD\_INVALID\_ARGS* the inputs could not be mapped to a keyword  
*ECMD\_SUCCESS* if successful  
*non-zero* if unsuccessful

TARGET DEPTH : Chip

TARGET STATES : Unused

**6.4.2.138** `uint32_t putModuleVpdKeyword (ecmdChipTarget & i_target, const char * i_record_name, const char * i_keyword, ecmdDataBuffer & i_data)`

Write Module VPD Keyword Interface.

**Parameters:**

*i\_target* Struct that contains cage/node/slot/position of module vpd to access  
*i\_record\_name* Name of VPD Record for given keyword  
*i\_keyword* Name of VPD Keyword to Write  
*i\_data* Data buffer of data to write

**Return values:**

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_INVALID\_ARGS** the inputs could not be mapped to a keyword  
**ECMD\_SUCCESS** if successful  
**non-zero** if unsuccessful

TARGET DEPTH : Chip

TARGET STATES : Unused

**6.4.2.139** `uint32_t getModuleVpdImage (ecmdChipTarget & i_target, uint32_t i_bytes, ecmdDataBuffer & o_data)`

Read Module VPD Image Interface.

**Parameters:**

*i\_target* Struct that contains cage/node/slot/position of module vpd to access  
*i\_bytes* Byte length to read  
*o\_data* Data buffer of data read from module

**Return values:**

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_INVALID\_ARGS** the inputs could not be mapped to a module  
**ECMD\_SUCCESS** if successful  
**non-zero** if unsuccessful

TARGET DEPTH : Chip

TARGET STATES : Unused

**6.4.2.140** `uint32_t putModuleVpdImage (ecmdChipTarget & i_target, ecmdDataBuffer & i_data)`

Write Module VPD Image Interface.

**Parameters:**

*i\_target* Struct that contains cage/node/slot/position of module vpd to access

*i\_data* Data buffer of data to write

**Return values:**

***ECMD\_TARGET\_NOT\_CONFIGURED*** if target is not available in the system

***ECMD\_INVALID\_ARGS*** the inputs could not be mapped to a module

***ECMD\_DATA\_OVERFLOW*** Too much data was provided for a write

***ECMD\_DATA\_UNDERFLOW*** Too little data was provided to a write function

***ECMD\_SUCCESS*** if successful

***non-zero*** if unsuccessful

TARGET DEPTH : Chip

TARGET STATES : Unused

**6.4.2.141** `uint32_t ecmdI2cReset (ecmdChipTarget & i_target, uint32_t i_engineId, uint32_t i_port)`

Resets the specified engine port.

**Parameters:**

*i\_target* Struct that contains cage/node/slot/position of device to access

*i\_engineId* I2c engine to use

*i\_port* I2C port to use

**Return values:**

***ECMD\_TARGET\_NOT\_CONFIGURED*** if target is not available in the system

***ECMD\_TARGET\_INVALID\_TYPE*** if target doesn't support I2c

***ECMD\_INVALID\_ARGS*** Invalid argument values found

***ECMD\_SUCCESS*** if successful

***non-zero*** if unsuccessful

TARGET DEPTH : Chip

TARGET STATES : Unused

**6.4.2.142** `uint32_t ecmdI2cRead (ecmdChipTarget & i_target, uint32_t i_engineId, uint32_t i_port, uint32_t i_slaveAddress, ecmdI2cBusSpeed_t i_busSpeed, uint32_t i_bytes, ecmdDataBuffer & o_data)`

Read data from an I2C device.

**Parameters:**

*i\_target* Struct that contains cage/node/slot/position of device to access

*i\_engineId* I2c engine to use

*i\_port* I2C port to use

*i\_slaveAddress* I2C slave device address to use

*i\_busSpeed* I2C Bus speed to use



*i\_bytes* Byte length to read  
*o\_data* Data read from device

**Return values:**

***ECMD\_TARGET\_NOT\_CONFIGURED*** if target is not available in the system  
***ECMD\_TARGET\_INVALID\_TYPE*** if target doesn't support I2c  
***ECMD\_INVALID\_ARGS*** Invalid argument values found  
***ECMD\_SUCCESS*** if successful  
***non-zero*** if unsuccessful

TARGET DEPTH : Chip

TARGET STATES : Unused

**6.4.2.143** `uint32_t ecmdI2cReadOffset (ecmdChipTarget & i_target,  
uint32_t i_engineId, uint32_t i_port, uint32_t i_slaveAddress,  
ecmdI2cBusSpeed_t i_busSpeed, uint32_t i_offset, uint32_t  
i_offsetFieldSize, uint32_t i_bytes, ecmdDataBuffer & o_data)`

Read data from an I2C device at the given offset.

**Parameters:**

*i\_target* Struct that contains cage/node/slot/position of device to access  
*i\_engineId* I2c engine to use  
*i\_port* I2C port to use  
*i\_slaveAddress* I2C slave device address to use  
*i\_busSpeed* I2C Bus speed to use  
*i\_offset* Byte offset in the device  
*i\_offsetFieldSize* Specifies the field size used in the I2C protocol of the slave device  
*i\_bytes* Byte length to read  
*o\_data* Data read from device

**Return values:**

***ECMD\_TARGET\_NOT\_CONFIGURED*** if target is not available in the system  
***ECMD\_TARGET\_INVALID\_TYPE*** if target doesn't support I2c  
***ECMD\_INVALID\_ARGS*** Invalid argument values found  
***ECMD\_SUCCESS*** if successful  
***non-zero*** if unsuccessful

TARGET DEPTH : Chip

TARGET STATES : Unused

**6.4.2.144** `uint32_t ecmdI2cWrite (ecmdChipTarget & i_target, uint32_t i_engineId, uint32_t i_port, uint32_t i_slaveAddress, ecmdI2cBusSpeed_t i_busSpeed, ecmdDataBuffer & i_data)`

Write the provided data into the I2C device.

**Parameters:**

*i\_target* Struct that contains cage/node/slot/position of device to access  
*i\_engineId* I2c engine to use  
*i\_port* I2C port to use  
*i\_slaveAddress* I2C slave device address to use  
*i\_busSpeed* I2C Bus speed to use  
*i\_data* Data to write to device

**Return values:**

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_TARGET\_INVALID\_TYPE** if target doesn't support I2c  
**ECMD\_INVALID\_ARGS** Invalid argument values found  
**ECMD\_SUCCESS** if successful  
**non-zero** if unsuccessful

TARGET DEPTH : Chip

TARGET STATES : Unused

**6.4.2.145** `uint32_t ecmdI2cWriteOffset (ecmdChipTarget & i_target, uint32_t i_engineId, uint32_t i_port, uint32_t i_slaveAddress, ecmdI2cBusSpeed_t i_busSpeed, uint32_t i_offset, uint32_t i_offsetFieldSize, ecmdDataBuffer & i_data)`

Write the provided data into the I2C device at the given offset.

**Parameters:**

*i\_target* Struct that contains cage/node/slot/position of device to access  
*i\_engineId* I2c engine to use  
*i\_port* I2C port to use  
*i\_slaveAddress* I2C slave device address to use  
*i\_busSpeed* I2C Bus speed to use  
*i\_offset* Byte offset in the device  
*i\_offsetFieldSize* Specifies the field size used in the I2C protocol of the slave device  
*i\_data* Data to write to device

**Return values:**

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_TARGET\_INVALID\_TYPE** if target doesn't support I2c  
**ECMD\_INVALID\_ARGS** Invalid argument values found  
**ECMD\_SUCCESS** if successful  
**non-zero** if unsuccessful

TARGET DEPTH : Chip

TARGET STATES : Unused

**6.4.2.146** `uint32_t ecmdGpioConfigPin (ecmdChipTarget & i_target, uint32_t i_engineId, uint32_t i_pin, ecmdDioMode_t i_mode)`

Configures mode of pin.

**Parameters:**

*i\_target* Struct that contains cage/node/slot/position of device to access

*i\_engineId* Gpio engine to use

*i\_pin* Pin to use

*i\_mode* Mode to configure pin

**Return values:**

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system

**ECMD\_TARGET\_INVALID\_TYPE** if target doesn't support Gpio

**ECMD\_INVALID\_ARGS** Invalid argument values found

**ECMD\_SUCCESS** if successful

**non-zero** if unsuccessful

NOTE : Configuring a pin explicitly as output is not necessary since the write latch commands implicitly perform the required settings.

TARGET DEPTH : Chip

TARGET STATES : Unused

**6.4.2.147** `uint32_t ecmdGpioReadPin (ecmdChipTarget & i_target, uint32_t i_engineId, uint32_t i_pin, uint32_t & o_state)`

Read the state of the specified pin (0/1).

**Parameters:**

*i\_target* Struct that contains cage/node/slot/position of device to access

*i\_engineId* Gpio engine to use

*i\_pin* Pin to use

*o\_state* State read on pin (0/1)

**Return values:**

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system

**ECMD\_TARGET\_INVALID\_TYPE** if target doesn't support Gpio

**ECMD\_INVALID\_ARGS** Invalid argument values found

**ECMD\_SUCCESS** if successful

**non-zero** if unsuccessful

TARGET DEPTH : Chip

TARGET STATES : Unused

**6.4.2.148** `uint32_t ecmdGpioReadLatch (ecmdChipTarget & i_target, uint32_t i_engineId, uint32_t i_pin, ecmdDioMode_t i_mode, uint32_t & o_state)`

Read the state of the latch.

**Parameters:**

*i\_target* Struct that contains cage/node/slot/position of device to access  
*i\_engineId* Gpio engine to use  
*i\_pin* Pin to use  
*i\_mode* Mode to configure pin  
*o\_state* State read on pin (0/1)

**Return values:**

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_TARGET\_INVALID\_TYPE** if target doesn't support Gpio  
**ECMD\_INVALID\_ARGS** Invalid argument values found  
**ECMD\_SUCCESS** if successful  
**non-zero** if unsuccessful

TARGET DEPTH : Chip

TARGET STATES : Unused

**6.4.2.149** `uint32_t ecmdGpioWriteLatch (ecmdChipTarget & i_target, uint32_t i_engineId, uint32_t i_pin, ecmdDioMode_t i_mode, uint32_t i_state)`

Write value to the specified pin.

**Parameters:**

*i\_target* Struct that contains cage/node/slot/position of device to access  
*i\_engineId* Gpio engine to use  
*i\_pin* Pin to use  
*i\_mode* Mode to configure pin  
*i\_state* State to write to pin

**Return values:**

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_TARGET\_INVALID\_TYPE** if target doesn't support Gpio  
**ECMD\_INVALID\_ARGS** Invalid argument values found  
**ECMD\_SUCCESS** if successful  
**non-zero** if unsuccessful

TARGET DEPTH : Chip

TARGET STATES : Unused

**6.4.2.150** `uint32_t ecmdGpioReadPins (ecmdChipTarget & i_target, uint32_t i_engineId, uint32_t i_mask, uint32_t & o_value)`

Read the GPIO input register and AND with i\_mask.

**Parameters:**

*i\_target* Struct that contains cage/node/slot/position of device to access  
*i\_engineId* Gpio engine to use  
*i\_mask* Mask to apply to pins  
*o\_value* Value read from pins with mask applied

**Return values:**

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_TARGET\_INVALID\_TYPE** if target doesn't support Gpio  
**ECMD\_INVALID\_ARGS** Invalid argument values found  
**ECMD\_SUCCESS** if successful  
**non-zero** if unsuccessful

TARGET DEPTH : Chip

TARGET STATES : Unused

**6.4.2.151** `uint32_t ecmdGpioWriteLatches (ecmdChipTarget & i_target, uint32_t i_engineId, ecmdDioMode_t i_mode, uint32_t i_mask, uint32_t i_value)`

Write several pins specified by i\_mask.

**Parameters:**

*i\_target* Struct that contains cage/node/slot/position of device to access  
*i\_engineId* Gpio engine to use  
*i\_mask* Mask to apply to pins  
*i\_mode* Mode to configure pin  
*i\_value* Value to write to pins with mask applied

**Return values:**

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_TARGET\_INVALID\_TYPE** if target doesn't support Gpio  
**ECMD\_INVALID\_ARGS** Invalid argument values found  
**ECMD\_SUCCESS** if successful  
**non-zero** if unsuccessful

TARGET DEPTH : Chip

TARGET STATES : Unused

## 6.5 ecmdDataBuffer.H File Reference

Provides a means to handle data from the eCMD C API.

```
#include <string>
#include <inttypes.h>
```

### Classes

- class **ecmdDataBufferImplementationHelper**  
*This is used to help low-level implementation of the **ecmdDataBuffer**(p.24), this CAN NOT be used by any eCMD client or data corruption will occur.*
- class **ecmdDataBuffer**  
*Provides a means to handle data from the eCMD C API.*
- class **ecmdOptimizableDataBuffer**

### Defines

- #define **ECMD\_DBUF\_SUCCESS** 0x0  
*DataBuffer returned successfully.*
- #define **ECMD\_DBUF\_INIT\_FAIL** (0x01000000 | 0x2000)  
*Initialization of the DataBuffer failed.*
- #define **ECMD\_DBUF\_BUFFER\_OVERFLOW** (0x01000000 | 0x2010)  
*Attempt to read/write data beyond the length of the DataBuffer.*
- #define **ECMD\_DBUF\_XSTATE\_ERROR** (0x01000000 | 0x2020)  
*An 'X' character occured where it was not expected.*
- #define **ECMD\_DBUF\_UNDEFINED\_FUNCTION** (0x01000000 | 0x2030)  
*Function not included in this version of DataBuffer.*
- #define **ECMD\_DBUF\_INVALID\_ARGS** (0x01000000 | 0x2040)  
*Args provided to dataBuffer were invalid.*
- #define **ECMD\_DBUF\_INVALID\_DATA\_FORMAT** (0x01000000 | 0x2041)  
*String data didn't match expected input format.*
- #define **ECMD\_DBUF\_FOPEN\_FAIL** (0x01000000 | 0x2050)  
*File open on file for reading or writing the data buffer failed.*
- #define **ECMD\_DBUF\_FILE\_FORMAT\_MISMATCH** (0x01000000 | 0x2051)  
*In readFile specified format not found in the data file.*
- #define **ECMD\_DBUF\_DATANUMBER\_NOT\_FOUND** (0x01000000 | 0x2052)

*In readFileMultiple specified data number not found in file.*

- **#define ECMD\_DBUF\_FILE\_OPERATION\_FAIL** (0x01000000 | 0x2053)  
*File operation failed.*
- **#define ECMD\_DBUF\_NOT\_OWNER** (0x01000000 | 0x2060)  
*Don't own this buffer so can't do this operation.*
- **#define ECMD\_DBUF\_XSTATE\_NOT\_ENABLED** (0x01000000 | 0x2062)  
*Xstate function called on a buffer that doesn't have xstates enabled.*
- **#define ETRAC0**(fmt) printf( "%s> ETRC: " fmt "\n", \_\_FUNCTION\_\_ );
- **#define ETRAC1**(fmt, arg1) printf( "%s> ETRC: " fmt "\n", \_\_FUNCTION\_\_, arg1 );
- **#define ETRAC2**(fmt, arg1, arg2) printf( "%s> ETRC: " fmt "\n", \_\_FUNCTION\_\_, arg1, arg2 );
- **#define ETRAC3**(fmt, arg1, arg2, arg3) printf( "%s> ETRC: " fmt "\n", \_\_FUNCTION\_\_, arg1, arg2, arg3 );
- **#define ETRAC4**(fmt, arg1, arg2, arg3, arg4) printf( "%s> ETRC: " fmt "\n", \_\_FUNCTION\_\_, arg1, arg2, arg3, arg4 );
- **#define ETRAC5**(fmt, arg1, arg2, arg3, arg4, arg5) printf( "%s> ETRC: " fmt "\n", \_\_FUNCTION\_\_, arg1, arg2, arg3, arg4, arg5 );
- **#define ETRAC6**(fmt, arg1, arg2, arg3, arg4, arg5, arg6) printf( "%s> ETRC: " fmt "\n", \_\_FUNCTION\_\_, arg1, arg2, arg3, arg4, arg5, arg6 );
- **#define ETRAC7**(fmt, arg1, arg2, arg3, arg4, arg5, arg6, arg7) printf( "%s> ETRC: " fmt "\n", \_\_FUNCTION\_\_, arg1, arg2, arg3, arg4, arg5, arg6, arg7 );
- **#define ETRAC8**(fmt, arg1, arg2, arg3, arg4, arg5, arg6, arg7, arg8) printf( "%s> ETRC: " fmt "\n", \_\_FUNCTION\_\_, arg1, arg2, arg3, arg4, arg5, arg6, arg7, arg8 );
- **#define ETRAC9**(fmt, arg1, arg2, arg3, arg4, arg5, arg6, arg7, arg8, arg9) printf( "%s> ETRC: " fmt "\n", \_\_FUNCTION\_\_, arg1, arg2, arg3, arg4, arg5, arg6, arg7, arg8, arg9 );

## Enumerations

- enum **ecmdFormatType\_t** { **ECMD\_SAVE\_FORMAT\_BINARY**, **ECMD\_SAVE\_FORMAT\_BINARY\_DATA**, **ECMD\_SAVE\_FORMAT\_ASCII**, **ECMD\_SAVE\_FORMAT\_XSTATE** }

*This is the different formats in which the output file will be written.*

- enum **ecmdWriteMode\_t** { **ECMD\_WRITE\_MODE**, **ECMD\_APPEND\_MODE** }

*This is the different write modes for writing databuffer into a file.*

### 6.5.1 Detailed Description

Provides a means to handle data from the eCMD C API.

DataBuffers handle and store data in a Big Endian fashion with Bit 0 being the MSB

## 6.5.2 Define Documentation

### 6.5.2.1 `#define ECMD_DBUF_SUCCESS 0x0`

DataBuffer returned successfully.

### 6.5.2.2 `#define ECMD_DBUF_INIT_FAIL (0x01000000 | 0x2000)`

Initialization of the DataBuffer failed.

### 6.5.2.3 `#define ECMD_DBUF_BUFFER_OVERFLOW (0x01000000 | 0x2010)`

Attempt to read/write data beyond the length of the DataBuffer.

### 6.5.2.4 `#define ECMD_DBUF_XSTATE_ERROR (0x01000000 | 0x2020)`

An 'X' character occurred where it was not expected.

### 6.5.2.5 `#define ECMD_DBUF_UNDEFINED_FUNCTION (0x01000000 | 0x2030)`

Function not included in this version of DataBuffer.

### 6.5.2.6 `#define ECMD_DBUF_INVALID_ARGS (0x01000000 | 0x2040)`

Args provided to dataBuffer were invalid.

### 6.5.2.7 `#define ECMD_DBUF_INVALID_DATA_FORMAT (0x01000000 | 0x2041)`

String data didn't match expected input format.

### 6.5.2.8 `#define ECMD_DBUF_FOPEN_FAIL (0x01000000 | 0x2050)`

File open on file for reading or writing the data buffer failed.

### 6.5.2.9 `#define ECMD_DBUF_FILE_FORMAT_MISMATCH (0x01000000 | 0x2051)`

In readFile specified format not found in the data file.

### 6.5.2.10 `#define ECMD_DBUF_DATANUMBER_NOT_FOUND (0x01000000 | 0x2052)`

In readFileMultiple specified data number not found in file.



**6.5.2.11** `#define ECMD_DBUF_FILE_OPERATION_FAIL (0x01000000 | 0x2053)`

File operation failed.

**6.5.2.12** `#define ECMD_DBUF_NOT_OWNER (0x01000000 | 0x2060)`

Don't own this buffer so can't do this operation.

**6.5.2.13** `#define ECMD_DBUF_XSTATE_NOT_ENABLED (0x01000000 | 0x2062)`

Xstate function called on a buffer that doesn't have xstates enabled.

- 6.5.2.14 `#define ETRAC0(fmt) printf( "%s> ETRC: " fmt "\n",  
__FUNCTION__);`
- 6.5.2.15 `#define ETRAC1(fmt, arg1) printf( "%s> ETRC: " fmt "\n",  
__FUNCTION__, arg1);`
- 6.5.2.16 `#define ETRAC2(fmt, arg1, arg2) printf( "%s> ETRC: " fmt "\n",  
__FUNCTION__, arg1, arg2);`
- 6.5.2.17 `#define ETRAC3(fmt, arg1, arg2, arg3) printf( "%s> ETRC: " fmt "\n",  
__FUNCTION__, arg1, arg2, arg3);`
- 6.5.2.18 `#define ETRAC4(fmt, arg1, arg2, arg3, arg4) printf( "%s> ETRC: " fmt  
"\n", __FUNCTION__, arg1, arg2, arg3, arg4);`
- 6.5.2.19 `#define ETRAC5(fmt, arg1, arg2, arg3, arg4, arg5) printf( "%s> ETRC:  
" fmt "\n", __FUNCTION__, arg1, arg2, arg3, arg4, arg5);`
- 6.5.2.20 `#define ETRAC6(fmt, arg1, arg2, arg3, arg4, arg5, arg6) printf( "%s>  
ETRC: " fmt "\n", __FUNCTION__, arg1, arg2, arg3, arg4, arg5,  
arg6);`
- 6.5.2.21 `#define ETRAC7(fmt, arg1, arg2, arg3, arg4, arg5, arg6, arg7) printf(  
"%s> ETRC: " fmt "\n", __FUNCTION__, arg1, arg2, arg3, arg4,  
arg5, arg6, arg7);`
- 6.5.2.22 `#define ETRAC8(fmt, arg1, arg2, arg3, arg4, arg5, arg6, arg7, arg8)  
printf( "%s> ETRC: " fmt "\n", __FUNCTION__, arg1, arg2, arg3,  
arg4, arg5, arg6, arg7, arg8);`
- 6.5.2.23 `#define ETRAC9(fmt, arg1, arg2, arg3, arg4, arg5, arg6, arg7, arg8, arg9)  
printf( "%s> ETRC: " fmt "\n", __FUNCTION__, arg1, arg2, arg3,  
arg4, arg5, arg6, arg7, arg8, arg9);`

### 6.5.3 Enumeration Type Documentation

#### 6.5.3.1 `enum ecmdFormatType_t`

This is the different formats in which the output file will be written.

Enumeration values:

***ECMD\_SAVE\_FORMAT\_BINARY*** binary file with header with info like bit length,  
format etc

***ECMD\_SAVE\_FORMAT\_BINARY\_DATA*** binary file with data only - will NOT  
work with scan ring data as length is rounded up to next byte

***ECMD\_SAVE\_FORMAT\_ASCII*** ascii text file with header having same info like bi-  
nary hdr

***ECMD\_SAVE\_FORMAT\_XSTATE*** xstate text file with header having same info like  
binary hdr

### 6.5.3.2 enum ecmdWriteMode\_t

This is the different write modes for writing databuffer into a file.

**Enumeration values:**

***ECMD\_WRITE\_MODE*** Overrrwrite the data if the file already exists.

***ECMD\_APPEND\_MODE*** Add databuffer to the end of the file.

## 6.6 ecmdSharedUtils.H File Reference

Useful functions for use throughout the ecmd C API and Plugin.

```
#include <string>
#include <vector>
#include <inttypes.h>
#include <ecmdDataBuffer.H>
#include <ecmdStructs.H>
```

### Gen Functions

- `std::string ecmdGenEbcdic (ecmdDataBuffer &i_data, int start, int bitLen)`  
*Turns the data in the buffer into ebcdic text.*
- `uint32_t ecmdGenB32FromHex (uint32_t *o_numPtr, const char *i_hexChars, int startPos)`  
*Default function for converting hex strings to unsigned int arrays.*
- `uint32_t ecmdGenB32FromHexLeft (uint32_t *o_numPtr, const char *i_hexChars)`  
*Convert a string of left-aligned Hex chars into a left-aligned unsigned int array.*
- `uint32_t ecmdGenB32FromHexRight (uint32_t *o_numPtr, const char *i_hexChars, int i_expectBits=0)`  
*Convert a string of right-aligned Hex chars into a left-aligned unsigned int array.*

### Enumerations

- `enum ecmdTargetDepth_t {`  
    `ECMD_DEPTH_CAGE = 0, ECMD_DEPTH_NODE, ECMD_DEPTH_SLOT,`  
    `ECMD_DEPTH_CHIP,`  
    `ECMD_DEPTH_CORE, ECMD_DEPTH_THREAD }`  
*Used by ecmdSetTargetDepth.*
- `enum ecmdTargetDisplayMode_t { ECMD_DISPLAY_TARGET_DEFAULT }`  
*Used by ecmdWriteTarget to specify displayMode.*

### Functions

- `void ecmdParseTokens (std::string line, const char *seperators, std::vector< std::string > &tokens)`  
*Breaks the string line into tokens based on all chars in seperators.*
- `uint32_t ecmdHexToUInt32 (const char *i_str)`  
*Converts strings to unsigned int values. The input format is 0xABCDEF.*

- `uint32_t ecmdHashString32 (const char *i_str, uint32_t i_c)`  
*Calculates a 32bit hash value for a given string.*
- `uint32_t ecmdSetTargetDepth (ecmdChipTarget &io_target, ecmdTargetDepth_t i_depth)`  
*Sets State Fields of Chip Target based on depth.*
- `uint32_t ecmdReadDcard (const char *i_filename, std::list< ecmdMemoryEntry > &o_data)`  
*Sets Fields of ecmdMemoryEntry\_t from the DCard data in the file.*
- `std::string ecmdWriteTarget (ecmdChipTarget &i_target, ecmdTargetDisplayMode_t i_displayMode=ECMD_DISPLAY_TARGET_DEFAULT)`  
*Returns a formatted string containing the data in the given ecmdChipTarget(p. 20).*

### 6.6.1 Detailed Description

Useful functions for use throughout the ecmd C API and Plugin.

### 6.6.2 Enumeration Type Documentation

#### 6.6.2.1 enum ecmdTargetDepth\_t

Used by `ecmdSetTargetDepth`.

Enumeration values:

*ECMD\_DEPTH\_CAGE*  
*ECMD\_DEPTH\_NODE*  
*ECMD\_DEPTH\_SLOT*  
*ECMD\_DEPTH\_CHIP*  
*ECMD\_DEPTH\_CORE*  
*ECMD\_DEPTH\_THREAD*

#### 6.6.2.2 enum ecmdTargetDisplayMode\_t

Used by `ecmdWriteTarget` to specify `displayMode`.

Enumeration values:

*ECMD\_DISPLAY\_TARGET\_DEFAULT* Default mode.

### 6.6.3 Function Documentation

#### 6.6.3.1 void ecmdParseTokens (std::string line, const char \* seperators, std::vector< std::string > & tokens)

Breaks the string line into tokens based on all chars in `seperators`.

**Parameters:**

*line* String to tokenize  
*seperators* String of characters to use as seperators  
*tokens* Vector of strings that contain all the tokens

### 6.6.3.2 `std::string ecmdGenEbcDic (ecmdDataBuffer & i_data, int start, int bitLen)`

Turns the data in the buffer into ebcDic text.

**Parameters:**

*i\_data* Data to convert  
*start* Bit to start at  
*bitLen* Number of bits

### 6.6.3.3 `uint32_t ecmdGenB32FromHex (uint32_t * o_numPtr, const char * i_hexChars, int startPos)`

Default function for converting hex strings to unsigned int arrays.

**Return values:**

*First* element of the parsed data, or 0xFFFFFFFF if error

**Parameters:**

*o\_numPtr* The array that stores the data parsed from the input string  
*i\_hexChars* input string of hex data- alignment stuff handled by Left and Right functions  
*startPos*

**See also:**

`ecmdGenB32FromHexRight`(p. 211)  
`ecmdGenB32FromHexLeft`(p. 210)

### 6.6.3.4 `uint32_t ecmdGenB32FromHexLeft (uint32_t * o_numPtr, const char * i_hexChars)`

Convert a string of left-aligned Hex chars into a left-aligned unsigned int array.

**Return values:**

*The* first element of the parsed string data, or 0xFFFFFFFF if error

**Parameters:**

*o\_numPtr* The array that stores the data parsed from the input string  
*i\_hexChars* A string of hex characters

**See also:**

`ecmdGenB32FromHexRight`(p. 211)  
`ecmdGenB32FromHex`(p. 210)

### 6.6.3.5 uint32\_t ecmdGenB32FromHexRight (uint32\_t \* o\_numPtr, const char \* i\_hexChars, int i\_expectBits = 0)

Convert a string of right-aligned Hex chars into a left-aligned unsigned int array.

#### Return values:

*The* first element of the parsed string data, or 0xFFFFFFFF if error

#### Parameters:

*o\_numPtr* The array that stores the data parsed from the input string

*i\_hexChars* A string of hex characters

*i\_expectBits* The number of defined bits in the o\_numPtr array returned

#### See also:

ecmdGenB32FromHex(p. 210)

ecmdGenB32FromHexLeft(p. 210)

### 6.6.3.6 uint32\_t ecmdHexToUInt32 (const char \* i\_str)

Converts strings to unsigned int values. The input format is 0xABCDEF.

#### Parameters:

*i\_str* String in hexadecimal notation

#### Date:

Tue Sep 21 13:22:33 2004

#### Return values:

*uint32\_t* value of converted input string

### 6.6.3.7 uint32\_t ecmdHashString32 (const char \* i\_str, uint32\_t i\_c)

Calculates a 32bit hash value for a given string.

LICENSE: By Bob Jenkins, 1996. bob\_jenkins@burtleburtle.net. You may use this code any way you wish, private, educational, or commercial. It's free. See <http://burtleburtle.net/bob/hash/doobs.html>

#### Parameters:

*i\_str* String to convert to hash

*i\_c* Start value for hash.

#### Return values:

*Hash* value

### 6.6.3.8 `uint32_t ecmdSetTargetDepth (ecmdChipTarget & io_target, ecmdTargetDepth_t i_depth)`

Sets State Fields of Chip Target based on depth.

#### Parameters:

*io\_target* an `ecmdChipTarget`(p.20) struct representing a specific eCmd target  
*i\_depth* an `ecmdTargetDepth_t` enum representing depth to be set valid

#### Return values:

*ECMD\_SUCCESS* if setting successful  
*ECMD\_INVALID\_ARGS* if unsuccessful in finding a matching depth

#### Postcondition:

State Fields of Chip Target are set to either `ECMD_TARGET_FIELD_VALID` or `ECMD_TARGET_FIELD_UNUSED`

TARGET DEPTH : Input To This Function TARGET STATES : Gets Set By This Function

### 6.6.3.9 `uint32_t ecmdReadDcard (const char * i_filename, std::list< ecmdMemoryEntry > & o_data)`

Sets Fields of `ecmdMemoryEntry_t` from the DCard data in the file.

#### Parameters:

*i\_filename* file to read the d-card data from  
*o\_data* list to be updated with the d-card data

#### Return values:

*ECMD\_SUCCESS* if setting successful  
*ECMD\_INVALID\_ARGS* if unsuccessful in finding a matching depth

### 6.6.3.10 `std::string ecmdWriteTarget (ecmdChipTarget & i_target, ecmdTargetDisplayMode_t i_displayMode = ECMD_DISPLAY_TARGET_DEFAULT)`

Returns a formatted string containing the data in the given `ecmdChipTarget`(p.20).

#### Returns:

String with formatted target data

#### Parameters:

*i\_target* `ecmdChipTarget`(p.20) containing data to format into string  
*i\_displayMode* Mode to format data

TARGET DEPTH : Thread TARGET STATES : Must be Initialized



## 6.7 ecmdStructs.H File Reference

All the Structures required for the eCMD Capi.

```
#include <inttypes.h>
#include <list>
#include <vector>
#include <string>
#include <ecmdDataBuffer.H>
```

### Classes

- **struct ecmdDllInfo**  
*This is used by ecmdQueryDllInfo to return info to the client about what Dll instance they are actually running with.*
- **struct ecmdChipTarget**  
*Structure used to designate which cec object/chip you would like the function to operate on.*
- **struct ecmdThreadData**  
*Used for the ecmdQueryConfig function to return thread data.*
- **struct ecmdCoreData**  
*Used for the ecmdQueryConfig function to return core data.*
- **struct ecmdChipData**  
*Used for the ecmdQueryConfig function to return chip data.*
- **struct ecmdSlotData**  
*Used for the ecmdQueryConfig function to return slot data.*
- **struct ecmdNodeData**  
*Used for the ecmdQueryConfig function to return node data.*
- **struct ecmdCageData**  
*Used for the ecmdQueryConfig function to return cage data.*
- **struct ecmdQueryData**  
*Used by the ecmdQueryConfig function to return data.*
- **struct ecmdRingData**  
*Used for the ecmdQueryRing function to return ring info.*
- **struct ecmdArrayData**  
*Used for the ecmdQueryArray function to return array info.*
- **struct ecmdTraceArrayData**  
*Used for the ecmdQueryTraceArray function to return trace array info.*

- **struct ecmdScomData**  
*Used for the ecmdQueryScom function to return scom info.*
- **struct ecmdLatchData**  
*Used for the ecmdQueryLatch function to return latch info.*
- **struct ecmdArrayEntry**  
*Used by the getArrayMultiple function to pass data.*
- **struct ecmdSpyGroupData**  
*Used by get/putspr function to create the return data from a group.*
- **struct ecmdNameEntry**  
*Used by get/putSprMultiple function to pass data.*
- **struct ecmdNameVectorEntry**  
*Used by getTraceArrayMultiple function to pass data.*
- **struct ecmdIndexVectorEntry**  
*Used by ??? function to pass data.*
- **struct ecmdIndexEntry**  
*Used by get/put Gpr/Fpr Multiple function to pass data.*
- **struct ecmdLatchEntry**  
*Used by getlatch function to return data.*
- **struct ecmdProcRegisterInfo**  
*Used by ecmdQueryProcRegisterInfo function to return data about a Architected register.*
- **struct ecmdSpyData**  
*Used for the ecmdQuerySpy function to return spy info.*
- **struct ecmdMemoryEntry**  
*Used by ecmdReadDcard.*
- **struct ecmdSimModelInfo**  
*Used by simGetModelInfo.*

## Defines

- **#define ECMD\_CAPI\_VERSION "6.0"**  
*eCMD API Version*
- **#define QD\_HDR\_MAGIC 0xFFFFFFFF1**
- **#define CAGE\_HDR\_MAGIC 0xFFFFFFFF2F**
- **#define NODE\_HDR\_MAGIC 0xFFFFFFFF3FF**
- **#define SLOT\_HDR\_MAGIC 0xFFFFF4FFF**
- **#define CHIP\_HDR\_MAGIC 0xFFFF5FFFF**

- #define CORE\_HDR\_MAGIC 0xFF6FFFFFFF
- #define THREAD\_HDR\_MAGIC 0xF7FFFFFFF
- #define ECMD\_CHIPT\_PROCESSOR "pu"
- #define ECMD\_CHIPT\_MEM\_BUF "memb"
- #define ECMD\_CHIPT\_MEM\_CNTRL "memc"
- #define ECMD\_CHIPT\_MEM\_L2CACHE "l2cache"
- #define ECMD\_CHIPT\_MEM\_L3CACHE "l3cache"
- #define ECMD\_CHIPT\_IOBDG "iobdg"
- #define ECMD\_CHIPT\_IOHUB "iohub"
- #define ECMD\_CHIPT\_MUX "mux"
- #define ECMD\_CHIPT\_SERVICE\_PROCESSOR "sp"
- #define ECMD\_CHIPFLAG\_BUSMASK 0xC0000000
- #define ECMD\_CHIPFLAG\_RSVDBUS1 0x00000000

*This is reserved for later expansion (should not be used).*

- #define ECMD\_CHIPFLAG\_JTAG 0x40000000
- #define ECMD\_CHIPFLAG\_FSI 0x80000000
- #define ECMD\_CHIPFLAG\_RSVDBUS2 0xC0000000

*This is reserved for later expansion (should not be used).*

## Enumerations

- enum ecmdCacheType\_t {  
ECMD\_CACHE\_UNKNOWN = 0, ECMD\_CACHE\_LEVEL1D, ECMD\_CACHE\_LEVEL1I, ECMD\_CACHE\_LEVEL2,  
ECMD\_CACHE\_LEVEL3, ECMD\_CACHE\_LEVEL4 }  
*Used by ecmdCacheFlush to specify which level of cache to flush.*
- enum ecmdChipInterfaceType\_t { ECMD\_INTERFACE\_ACCESS, ECMD\_INTERFACE\_CFAM, ECMD\_INTERFACE\_UNKNOWN }  
*Used in ecmdChipData(p. 17) to describe the interface macro used by the chip.*
- enum ecmdChipTargetState\_t {  
ECMD\_TARGET\_UNKNOWN\_STATE, ECMD\_TARGET\_FIELD\_VALID,  
ECMD\_TARGET\_FIELD\_UNUSED, ECMD\_TARGET\_FIELD\_WILDCARD,  
ECMD\_TARGET\_THREAD\_ALIVE }  
*Used by ecmdChipTarget(p. 20) to describe the value in the state fields.*
- enum ecmdClockRange\_t {  
ECMD\_CLOCK\_RANGE\_DEFAULT, ECMD\_CLOCK\_RANGE\_LOWEST,  
ECMD\_CLOCK\_RANGE\_LOW, ECMD\_CLOCK\_RANGE\_MIDDLE,  
ECMD\_CLOCK\_RANGE\_HIGH, ECMD\_CLOCK\_RANGE\_HIGHEST }  
*Used by SetClockSpeed interfaces to adjust clock steering procedure.*
- enum ecmdClockSetMode\_t { ECMD\_CLOCK\_ONE\_STEP, ECMD\_CLOCK\_STEER }

*Used by SetClockSpeed interfaces to specify to do adjustment in one operation or to steer to new value.*

- enum `ecmdClockSpeedType_t` { `ECMD_CLOCK_FREQUENCY_SPEC`, `ECMD_CLOCK_CYCLETIME_SPEC` }

*Used by SetClockSpeed interfaces to specify what notation the speed is provided in.*

- enum `ecmdClockState_t` { `ECMD_CLOCKSTATE_UNKNOWN`, `ECMD_CLOCKSTATE_ON`, `ECMD_CLOCKSTATE_OFF`, `ECMD_CLOCKSTATE_NA` }

*Used by Ring/Array/Spy Query functions to return a required clock state.*

- enum `ecmdClockType_t` { `ECMD_PROC_REFCLOCK`, `ECMD_MEMCTRL_REFCLOCK` }

*Used by SetClockSpeed interfaces to specify the clock to control.*

- enum `ecmdConfigLoopMode_t` { `ECMD_STATIC_DEPTH_LOOP` }

*Used by ecmdConfigLooperInit to enable/disable variable depth looping.*

- enum `ecmdConfigLoopType_t` { `ECMD_SELECTED_TARGETS_LOOP`, `ECMD_SELECTED_TARGETS_LOOP_DEFALL`, `ECMD_SELECTED_TARGETS_LOOP_VD`, `ECMD_SELECTED_TARGETS_LOOP_VD_DEFALL`, `ECMD_ALL_TARGETS_LOOP` }

*Used by ecmdConfigLooperInit function to specify what type of data to loop on.*

- enum `ecmdConfigValid_t` { `ECMD_CONFIG_VALID_FIELD_NONE`, `ECMD_CONFIG_VALID_FIELD_ALPHA`, `ECMD_CONFIG_VALID_FIELD_NUMERIC`, `ECMD_CONFIG_VALID_FIELD_BOTH` }

*Used by the get/set configuration functions to specify what data is good.*

- enum `ecmdDioMode_t` { `ECMD_DIO_INPUT`, `ECMD_DIO_OPEN_DRAIN`, `ECMD_DIO_OPEN_SOURCE`, `ECMD_DIO_PUSH_PULL` }

*Used by the GPIO functions to specify the different modes for the GPIO pin.*

- enum `ecmdDllEnv_t` { `ECMD_DLL_ENV_HW`, `ECMD_DLL_ENV_SIM` }

*This is used by ecmdQueryDllInfo to return what environment the dll is designed to run in (i.e Simulation vs Hardware).*

- enum `ecmdDllProduct_t` { `ECMD_DLL_PRODUCT_UNKNOWN`, `ECMD_DLL_PRODUCT_ECLIPZ` }

*This is used by ecmdQueryDllInfo to return what product the dll supports.*

- enum `ecmdDllType_t` { `ECMD_DLL_UNKNOWN`, `ECMD_DLL_STUB`, `ECMD_DLL_CRONUS`, `ECMD_DLL_IPSERIES`, `ECMD_DLL_ZSERIES`, `ECMD_DLL_SCAND` }

*This is used by ecmdQueryDllInfo to return who's dll you are actually running against.*

- enum `ecmdFileType_t` {  
`ECMD_FILE_SCANDEF`, `ECMD_FILE_SPYDEF`, `ECMD_FILE_ARRAYDEF`, `ECMD_FILE_HELPTEXT`,  
`ECMD_FILE_SCOMDATA`, `ECMD_FILE_SPYDEFHASH`, `ECMD_FILE_SCANDEFHASH` }

*Used for the `ecmdQueryFileLocation` function to specify the file type you are looking for.*

- enum `ecmdFusionMessageType_t` {  
`ECMD_SIM_MSG_EXCEPTION` = 1, `ECMD_SIM_MSG_TESTCASE` = 2,  
`ECMD_SIM_MSG_CMD_RS` = 4, `ECMD_SIM_MSG_CMD_EXE` = 8,  
`ECMD_SIM_MSG_DEBUG` = 16, `ECMD_SIM_MSG_BROADSIDE` = 32,  
`ECMD_SIM_MSG_END_SD_MSGS` = 0x000000ff, `ECMD_SIM_MSG_ALWAYS` = 0xff }

*Used by `simOutputFusionMessage` function to specify message type Values copied from `globals.h` of `SimDispatcher` delivery.*

- enum `ecmdFusionSeverity_t` { `ECMD_SIM_ERROR` = 0x1, `ECMD_SIM_WARNING` = 0x2, `ECMD_SIM_INFO` = 0x3, `ECMD_SIM_PLAIN` = ~0 }

*Used by `simOutputFusionMessage` function to specify message severity Values copied from `globals.h` of `SimDispatcher` delivery.*

- enum `ecmdGlobalVarType_t` { `ECMD_GLOBALVAR_DEBUG`, `ECMD_GLOBALVAR_QUIETMODE` }

*Used by `ecmdGetGlobalVar` to specify what variable you are looking for.*

- enum `ecmdI2cBusSpeed_t` { `ECMD_I2C_BUSSPEED_50KHZ`, `ECMD_I2C_BUSSPEED_100KHZ`, `ECMD_I2C_BUSSPEED_400KHZ` }

*Used by I2C functions to specify bus speed.*

- enum `ecmdLatchMode_t` { `ECMD_LATCHMODE_FULL`, `ECMD_LATCHMODE_PARTIAL` }

*Used by `get/putLatch` functions to specify what mode should be used to find latches in the `scandef`.*

- enum `ecmdQueryDetail_t` { `ECMD_QUERY_DETAIL_LOW`, `ECMD_QUERY_DETAIL_HIGH` }

*Used by `ecmdQueryConfig` to specify detail level of query.*

- enum `ecmdSpyType_t` { `ECMD_SPYTYPE_ALIAS`, `ECMD_SPYTYPE_IDIAL`, `ECMD_SPYTYPE_EDIAL`, `ECMD_SPYTYPE_ECCGROUP` }

*Used for the `ecmdQuerySpy` function to specify which type of spy we have.*

- enum `ecmdTraceType_t` { `ECMD_TRACE_SCAN`, `ECMD_TRACE_PROCEDURE` }

*Used by `ecmdSetTraceMode` to specify which trace to control.*

### 6.7.1 Detailed Description

All the Structures required for the eCMD Capi.

## 6.7.2 Define Documentation

### 6.7.2.1 `#define ECMD_CAPI_VERSION "6.0"`

eCMD API Version

### 6.7.2.2 `#define QD_HDR_MAGIC 0xFFFFFFFF1`

### 6.7.2.3 `#define CAGE_HDR_MAGIC 0xFFFFFFFF2F`

### 6.7.2.4 `#define NODE_HDR_MAGIC 0xFFFFFFFF3FF`

### 6.7.2.5 `#define SLOT_HDR_MAGIC 0xFFFF4FFF`

### 6.7.2.6 `#define CHIP_HDR_MAGIC 0xFFF5FFFF`

### 6.7.2.7 `#define CORE_HDR_MAGIC 0xFF6FFFFF`

### 6.7.2.8 `#define THREAD_HDR_MAGIC 0xF7FFFFFF`

### 6.7.2.9 `#define ECMD_CHIPT_PROCESSOR "pu"`

Predefined common chip names for `ecmdChipData.chipCommonType`(p. 18)

### 6.7.2.10 `#define ECMD_CHIPT_MEM_BUF "memb"`

### 6.7.2.11 `#define ECMD_CHIPT_MEM_CNTRL "memc"`

### 6.7.2.12 `#define ECMD_CHIPT_MEM_L2CACHE "l2cache"`

### 6.7.2.13 `#define ECMD_CHIPT_MEM_L3CACHE "l3cache"`

### 6.7.2.14 `#define ECMD_CHIPT_IOBDG "iobdg"`

### 6.7.2.15 `#define ECMD_CHIPT_IOHUB "iohub"`

### 6.7.2.16 `#define ECMD_CHIPT_MUX "mux"`

### 6.7.2.17 `#define ECMD_CHIPT_SERVICE_PROCESSOR "sp"`

### 6.7.2.18 `#define ECMD_CHIPFLAG_BUSMASK 0xC0000000`

Defines for the `ecmdChipData`(p. 17) `chipFlags` field

### 6.7.2.19 `#define ECMD_CHIPFLAG_RSVD BUS1 0x00000000`

This is reserved for later expansion (should not be used).

**6.7.2.20** `#define ECMD_CHIPFLAG_JTAG 0x40000000`

**6.7.2.21** `#define ECMD_CHIPFLAG_FSI 0x80000000`

**6.7.2.22** `#define ECMD_CHIPFLAG_RSVDBUS2 0xC0000000`

This is reserved for later expansion (should not be used).

### 6.7.3 Enumeration Type Documentation

#### 6.7.3.1 `enum ecmdCacheType_t`

Used by `ecmdCacheFlush` to specify which level of cache to flush.

Enumeration values:

***ECMD\_CACHE\_UNKNOWN*** Unknown Cache Type.

***ECMD\_CACHE\_LEVEL1D*** L1 Data Cache.

***ECMD\_CACHE\_LEVEL1I*** L1 Instruction Cache.

***ECMD\_CACHE\_LEVEL2*** L2 Cache.

***ECMD\_CACHE\_LEVEL3*** L3 Cache.

***ECMD\_CACHE\_LEVEL4*** L4 Cache.

#### 6.7.3.2 `enum ecmdChipInterfaceType_t`

Used in `ecmdChipData`(p. 17) to describe the interface macro used by the chip.

Enumeration values:

***ECMD\_INTERFACE\_ACCESS*** Standard Jtag Access Macro.

***ECMD\_INTERFACE\_CFAM*** CommonFirmwareAccessMacro.

***ECMD\_INTERFACE\_UNKNOWN*** Unknown Interface.

#### 6.7.3.3 `enum ecmdChipTargetState_t`

Used by `ecmdChipTarget`(p. 20) to describe the value in the state fields.

Enumeration values:

***ECMD\_TARGET\_UNKNOWN\_STATE*** State field has not been initialized.

***ECMD\_TARGET\_FIELD\_VALID*** Associated State Field is set to a valid value.

***ECMD\_TARGET\_FIELD\_UNUSED*** Associated State Field is unused and should be ignored.

***ECMD\_TARGET\_FIELD\_WILDCARD*** Associated State Field is a wildcard and should be iterated on in query functions.

***ECMD\_TARGET\_THREAD\_ALIVE*** Used when calling thread dependent functions tell the function to check for the thread to be alive before running.

**6.7.3.4 enum ecmdClockRange\_t**

Used by SetClockSpeed interfaces to adjust clock steering procedure.

Enumeration values:

*ECMD\_CLOCK\_RANGE\_DEFAULT*  
*ECMD\_CLOCK\_RANGE\_LOWEST*  
*ECMD\_CLOCK\_RANGE\_LOW*  
*ECMD\_CLOCK\_RANGE\_MIDDLE*  
*ECMD\_CLOCK\_RANGE\_HIGH*  
*ECMD\_CLOCK\_RANGE\_HIGHEST*

**6.7.3.5 enum ecmdClockSetMode\_t**

Used by SetClockSpeed interfaces to specify to do adjustment in one operation or to steer to new value.

Enumeration values:

*ECMD\_CLOCK\_ONE\_STEP* Change to new frequency in one operation.  
*ECMD\_CLOCK\_STEER* Steer to new frequency.

**6.7.3.6 enum ecmdClockSpeedType\_t**

Used by SetClockSpeed interfaces to specify what notation the speed is provided in.

Enumeration values:

*ECMD\_CLOCK\_FREQUENCY\_SPEC* Clock speed is specified in Mhz.  
*ECMD\_CLOCK\_CYCLETIME\_SPEC* Clock speed is specified in cycle time.

**6.7.3.7 enum ecmdClockState\_t**

Used by Ring/Array/Spy Query functions to return a required clock state.

Enumeration values:

*ECMD\_CLOCKSTATE\_UNKNOWN* Unable to determine a required clock state.  
*ECMD\_CLOCKSTATE\_ON* Chip clocks must be on to access.  
*ECMD\_CLOCKSTATE\_OFF* Chip clocks must be off to access.  
*ECMD\_CLOCKSTATE\_NA* Chip clocks can be in any state to access.

**6.7.3.8 enum ecmdClockType\_t**

Used by SetClockSpeed interfaces to specify the clock to control.

Enumeration values:

*ECMD\_PROC\_REFCLOCK* Processor reference clock.  
*ECMD\_MEMCTRL\_REFCLOCK* Memory Controller reference clock.



**6.7.3.9 enum ecmdConfigLoopMode\_t**

Used by ecmdConfigLooperInit to enable/disable variable depth looping.

**Enumeration values:**

**ECMD\_STATIC\_DEPTH\_LOOP** Use the state specified on init, don't allow plugin to change.

**6.7.3.10 enum ecmdConfigLoopType\_t**

Used by ecmdConfigLooperInit function to specify what type of data to loop on.

**Enumeration values:**

**ECMD\_SELECTED\_TARGETS\_LOOP** Loop on only targets in the system the user specified with -p# -c# -n#, etc. if not specified default to 0.

**ECMD\_SELECTED\_TARGETS\_LOOP\_DEFALL** Loop on only targets in the system the user specified with -p# -c# -n#, etc. if not specified default to all.

**ECMD\_SELECTED\_TARGETS\_LOOP\_VD** Loop only on targets in the system to the depth user specified on command line (ie if user said only '-n0' then -s and below are unused) if not specified default to 0.

**ECMD\_SELECTED\_TARGETS\_LOOP\_VD\_DEFALL** Loop only on targets in the system to the depth user specified on command line (ie if user said only '-n0' then -s and below are unused) if not specified default to all.

**ECMD\_ALL\_TARGETS\_LOOP** Loop on all valid targets in the system.

**6.7.3.11 enum ecmdConfigValid\_t**

Used by the get/set configuration functions to specify what data is good.

**Enumeration values:**

**ECMD\_CONFIG\_VALID\_FIELD\_NONE** No field is valid, must have been an error.

**ECMD\_CONFIG\_VALID\_FIELD\_ALPHA** The string field contains valid data.

**ECMD\_CONFIG\_VALID\_FIELD\_NUMERIC** The numeric field contains valid data.

**ECMD\_CONFIG\_VALID\_FIELD\_BOTH** Both the string and numeric fields contain valid data.

**6.7.3.12 enum ecmdDioMode\_t**

Used by the GPIO functions to specify the different modes for the GPIO pin.

High (1)	Low (0)	Output Enable	Output Register	Output Enable	Output Register
Push Pull	true   1	true   0	Open Drain	false   0	true   0
			Open Source	true   1	false   1

**Enumeration values:**

**ECMD\_DIO\_INPUT** Input pin.

***ECMD\_DIO\_OPEN\_DRAIN*** See detailed table.  
***ECMD\_DIO\_OPEN\_SOURCE*** See detailed table.  
***ECMD\_DIO\_PUSH\_PULL*** See detailed table.

#### 6.7.3.13 enum ecmdDllEnv\_t

This is used by ecmdQueryDllInfo to return what environment the dll is designed to run in (i.e Simulation vs Hardware).

##### Enumeration values:

***ECMD\_DLL\_ENV\_HW*** Hardware Environment.  
***ECMD\_DLL\_ENV\_SIM*** Simulation Environment.

#### 6.7.3.14 enum ecmdDllProduct\_t

This is used by ecmdQueryDllInfo to return what product the dll supports.

##### Enumeration values:

***ECMD\_DLL\_PRODUCT\_UNKNOWN*** Unknown product.  
***ECMD\_DLL\_PRODUCT\_ECLIPZ*** Eclipz.

#### 6.7.3.15 enum ecmdDllType\_t

This is used by ecmdQueryDllInfo to return who's dll you are actually running against.

##### Enumeration values:

***ECMD\_DLL\_UNKNOWN*** This should never be encountered.  
***ECMD\_DLL\_STUB*** This is a stub version of the dll for client testing.  
***ECMD\_DLL\_CRONUS*** Running against the Cronus Dll.  
***ECMD\_DLL\_IPSERIES*** Running against I/P Series HOM.  
***ECMD\_DLL\_ZSERIES*** Running against Z Series HOM.  
***ECMD\_DLL\_SCAND*** Running against the ScanD dll owned by Meghna Paruthi.

#### 6.7.3.16 enum ecmdFileType\_t

Used for the ecmdQueryFileLocation function to specify the file type you are looking for.

##### Enumeration values:

***ECMD\_FILE\_SCANDEF*** Scandef file type.  
***ECMD\_FILE\_SPYDEF*** Spy Definition file.  
***ECMD\_FILE\_ARRAYDEF*** Array Definition file.  
***ECMD\_FILE\_HELPTEXT*** eCMD Help Text file - target field of ecmdQueryFileLocation is not used for this and just a path is returned  
***ECMD\_FILE\_SCOMDATA*** eCMD ScanComm Parse data files, used by getscom - target field of ecmdQueryFileLocation is not used for this and just a path is returned  
***ECMD\_FILE\_SPYDEFHASH*** Hash file for spy definition.  
***ECMD\_FILE\_SCANDEFHASH*** Hash file for the scandef.

**6.7.3.17 enum ecmdFusionMessageType\_t**

Used by simOutputFusionMessage function to specify message type Values copied from globals.h of SimDispatcher delivery.

Enumeration values:

*ECMD\_SIM\_MSG\_EXCEPTION*  
*ECMD\_SIM\_MSG\_TESTCASE*  
*ECMD\_SIM\_MSG\_CMD\_RS*  
*ECMD\_SIM\_MSG\_CMD\_EXE*  
*ECMD\_SIM\_MSG\_DEBUG*  
*ECMD\_SIM\_MSG\_BROADSIDE*  
*ECMD\_SIM\_MSG\_END\_SD\_MSGS*  
*ECMD\_SIM\_MSG\_ALWAYS*

**6.7.3.18 enum ecmdFusionSeverity\_t**

Used by simOutputFusionMessage function to specify message severity Values copied from globals.h of SimDispatcher delivery.

Enumeration values:

*ECMD\_SIM\_ERROR*  
*ECMD\_SIM\_WARNING*  
*ECMD\_SIM\_INFO*  
*ECMD\_SIM\_PLAIN*

**6.7.3.19 enum ecmdGlobalVarType\_t**

Used by ecmdGetGlobalVar to specify what variable you are looking for.

Enumeration values:

*ECMD\_GLOBALVAR\_DEBUG* Retrieve the value of the ecmd debug flag set by ECMD\_DEBUG env var.  
*ECMD\_GLOBALVAR\_QUIETMODE* Retrieve the value of the quiet mode debug flag = set by -quiet default = 0.

**6.7.3.20 enum ecmdI2cBusSpeed\_t**

Used by I2C functions to specify bus speed.

Enumeration values:

*ECMD\_I2C\_BUSSPEED\_50KHZ* Run I2c bus at 50Khz.  
*ECMD\_I2C\_BUSSPEED\_100KHZ* Run I2c bus at 100Khz.  
*ECMD\_I2C\_BUSSPEED\_400KHZ* Run I2c bus at 400Khz.

**6.7.3.21 enum ecmdLatchMode\_t**

Used by get/putLatch functions to specify what mode should be used to find latches in the scandef.

**Enumeration values:**

*ECMD\_LATCHMODE\_FULL* Latch must match exactly.

*ECMD\_LATCHMODE\_PARTIAL* Latch can be a partial match.

**6.7.3.22 enum ecmdQueryDetail\_t**

Used by ecmdQueryConfig to specify detail level of query.

**Enumeration values:**

*ECMD\_QUERY\_DETAIL\_LOW* Only config info is returned.

*ECMD\_QUERY\_DETAIL\_HIGH* All info is returned.

**6.7.3.23 enum ecmdSpyType\_t**

Used for the ecmdQuerySpy function to specify which type of spy we have.

**See also:**

ecmdSpyData(p.92)

**Enumeration values:**

*ECMD\_SPYTYPE\_ALIAS* Spy is an alias.

*ECMD\_SPYTYPE\_IDIAL* Spy is an iDial.

*ECMD\_SPYTYPE\_EDIAL* Spy is an eDial.

*ECMD\_SPYTYPE\_ECCGROUP* Spy is an eccGrouping.

**6.7.3.24 enum ecmdTraceType\_t**

Used by ecmdSetTraceMode to specify which trace to control.

**Enumeration values:**

*ECMD\_TRACE\_SCAN* Scan Trace.

*ECMD\_TRACE\_PROCEDURE* Procedure Trace.

**6.7.4 Function Documentation****6.7.4.1 std::string ecmdGetSharedLibVersion ()**

Returns the version of the shared lib so it can be compared with the other versions.

## 6.8 ecmdUtils.H File Reference

Useful functions for use throughout the ecmd C API.

```
#include <inttypes.h>
#include <string>
#include <vector>
#include <ecmdClientCapi.H>
```

### Classes

- struct **ecmdLooperData**

*Used internally by ecmdConfigLooper to store looping state information.*

### eCMD Utility Functions

- uint32\_t **ecmdConfigLooperInit** (ecmdChipTarget &io\_target, ecmdConfigLoopType\_t i\_looptype, ecmdLooperData &io\_state, ecmdConfigLoopMode\_t i\_mode=ECMD\_STATIC\_DEPTH\_LOOP)

*Initializes data structures and code to loop over configured and selected elements of the system.*

- uint32\_t **ecmdConfigLooperNext** (ecmdChipTarget &io\_target, ecmdLooperData &io\_state)

*Loops over configured and selected elements of the system, updating target to point to them.*

- uint32\_t **ecmdReadDataFormatted** (ecmdDataBuffer &o\_data, const char \*i\_dataStr, std::string i\_format, int i\_expectedLength=0)

*Reads data from data string into data buffer based on a format type.*

- uint32\_t **decToUInt32** (const char \*i\_decstr)

*Converts decimal string to uint32\_t.*

- std::string **ecmdWriteDataFormatted** (ecmdDataBuffer &i\_data, std::string i\_format, uint64\_t i\_address=0)

*Formats data from data buffer into a string according to format flag and returns the string.*

- std::string **ecmdBitsHeader** (int i\_initCharOffset, int i\_blockSize, int i\_numCols, int i\_maxBitWidth)

*Print the bits header used in the output formats.*

- uint32\_t **ecmdGetChipData** (ecmdChipTarget &i\_target, ecmdChipData &o\_data)

*Fetch the detailed chip data structure for the selected target.*

- uint32\_t **ecmdDisplayDllInfo** ()

*Function calls ecmdQueryDllInfo and displays the output to stdout.*

- `uint32_t ecmdDisplayScomData (ecmdChipTarget &i_target, uint32_t i_address, ecmdDataBuffer &i_data, const char *i_format)`  
*Display the Scom data with the bit descriptions.*

### 6.8.1 Detailed Description

Useful functions for use throughout the ecmd C API.

### 6.8.2 Function Documentation

- 6.8.2.1** `uint32_t ecmdConfigLooperInit (ecmdChipTarget & io_target, ecmdConfigLoopType_t i_looptype, ecmdLooperData & io_state, ecmdConfigLoopMode_t i_mode = ECMD_STATIC_DEPTH_LOOP)`

Initializes data structures and code to loop over configured and selected elements of the system.

**Parameters:**

- io\_target* Initial `ecmdChipTarget`(p.20) that may contain information used in building the struct to loop over
- i\_looptype* Specify type of all, all chips in system or all chips selected by user
- i\_mode* Specify if you want to allow the plugin to change the depth of your loop or not
- io\_state* Used internally by ConfigLooper to keep track of state, unique instance must be passed into each loop and must be passed to `ecmdConfigLooperNext`

**Return values:**

- ECMD\_SUCCESS* if initialization succeeded, error code if otherwise

**See also:**

- `ecmdConfigLooperNext`(p.226)

TARGET DEPTH : Thread TARGET STATES : Must Be Initialized

- 6.8.2.2** `uint32_t ecmdConfigLooperNext (ecmdChipTarget & io_target, ecmdLooperData & io_state)`

Loops over configured and selected elements of the system, updating target to point to them.

**Parameters:**

- io\_target* `ecmdChipTarget`(p.20) that contains info about next target to process
- io\_state* Used internally to keep track of state, must be passed from output of `ecmdConfigLooperInit`

**Return values:**

- 1* if *io\_target* is valid, 0 if it is not

**See also:**

- `ecmdConfigLooperInit`(p.226)

TARGET DEPTH : Thread TARGET STATES : Must be Initialized (from `ecmdConfigLooperInit`)

**6.8.2.3** `uint32_t ecmdReadDataFormatted (ecmdDataBuffer & o_data, const char * i_dataStr, std::string i_format, int i_expectedLength = 0)`

Reads data from data string into data buffer based on a format type.

**Return values:**

*ECMD\_SUCCESS* if data is well-formatted, non-zero otherwise

**Parameters:**

*o\_data* `ecmdDataBuffer`(p.24) where data from data string is placed.

*i\_dataStr* string of characters containing data

*i\_format* Flag that tells how to parse the data string, e.g., "b" = binary, "x" = hex left

*i\_expectedLength* If length of data is known before hand , should be passed is necessary for right aligned data that is not byte aligned lengths

**6.8.2.4** `uint32_t decToUInt32 (const char * i_decstr)`

Converts decimal string to uint32\_t.

**Return values:**

*uint32\_t* value of converted input string

**Parameters:**

*i\_decstr* string of characters containing data

**6.8.2.5** `std::string ecmdWriteDataFormatted (ecmdDataBuffer & i_data, std::string i_format, uint64_t i_address = 0)`

Formats data from data buffer into a string according to format flag and returns the string.

**Returns:**

String of formatted data

**Parameters:**

*i\_data* `ecmdDataBuffer`(p.24) where data to format is stored

*i\_format* Flag that tells how to parse the data into a string, e.g., "b" = binary, "x" = hex left

*i\_address* A base address value that can be used in forming certain data- i.e., data from memory

**6.8.2.6** `std::string ecmdBitsHeader (int i_initCharOffset, int i_blockSize, int i_numCols, int i_maxBitWidth)`

Print the bits header used in the output formats.

**Parameters:**

*i\_initCharOffset* char offset on screen to start printing

*i\_blockSize* Binary block size (ie. column char size)  
*i\_numCols* Number of columns to display  
*i\_maxBit Width* Maximum number of bits to display - this is actual data valid so we don't display more columns then we need

**Returns:**

String of formatted data

### 6.8.2.7 `uint32_t ecmdGetChipData (ecmdChipTarget & i_target, ecmdChipData & o_data)`

Fetch the detailed chip data structure for the selected target.

**Return values:**

*ECMD\_SUCCESS* if chip data for target is found, non-zero otherwise

**Parameters:**

*i\_target* `ecmdChipTarget`(p. 20) that information is requested for  
*o\_data* `ecmdChipData`(p. 17) struct that contains detailed info on chip ec level, etc.

TARGET DEPTH : Pos TARGET STATES : Unused

### 6.8.2.8 `uint32_t ecmdDisplayDllInfo ()`

Function calls `ecmdQueryDllInfo` and displays the output to stdout.

**Return values:**

*ECMD\_SUCCESS* if successful  
*nonzero* on failure

### 6.8.2.9 `uint32_t ecmdDisplayScomData (ecmdChipTarget & i_target, uint32_t i_address, ecmdDataBuffer & i_data, const char * i_format)`

Display the Scom data with the bit descriptions.

**Return values:**

*ECMD\_SUCCESS* if scom lookup and display was successful, non-zero otherwise

**Parameters:**

*i\_target* target for which scom data needs to be displayed.  
*i\_address* Scom Address for which the details are required  
*i\_data* buffer that holds the scom data  
*i\_format* possible values -v, -vs0, -vs1 for the information that needs to be displayed



## 6.9 gipClientPerlapi.H File Reference

IP eCMD Perlapi Extension.

```
#include <ecmdReturnCodes.H>
#include <ecmdStructs.H>
#include <ecmdDataBuffer.H>
#include <gipStructs.H>
```

### Load/Unload Functions

- **int gipInitExtension** (const char \*i\_clientVersion)

*Initialize eCMD GIP Extension DLL.*

### Chic Control Functions

- **uint32\_t gipReserve** (chicReserveId i\_reserveId, uint32\_t i\_waitTime)

*Requests that the cecserver's serial thread only run commands that are sent with the specified reserve id. (From chicclientlib.H/C).*

- **uint32\_t gipRelease** (chicReserveId i\_reserveId)

*Release an active reserve. (From chicclientlib.H/C).*

- **uint32\_t gipAbort** (chicReserveId i\_reserveId)

*Abort the currently executing serial command and any pending serial commands. (From chic-clientlib.H/C).*

- **uint32\_t gipSetServAddr** (const char \*i\_servAddr, uint32\_t nets\_port)

*Set the the Client's IP Address and the port # for the server its connecting to.*

### Memory Functions

- **uint32\_t gipGetMemProcVariousAddrType** (ecmdChipTarget &i\_target, ecmdDataBuffer i\_address, uint32\_t i\_bytes, gipXlateVariables i\_xlateVars, ecmdDataBuffer &o\_memoryData, ecmdDataBuffer &o\_memoryTags, ecmdDataBuffer &o\_memoryEcc, ecmdDataBuffer &o\_memoryEccError, ecmdDataBuffer &o\_realAddress)

*Reads System Mainstore through the processor chip using an effective address.*

- **uint32\_t gipPutMemProcVariousAddrType** (ecmdChipTarget &i\_target, ecmdDataBuffer i\_address, uint32\_t i\_bytes, gipXlateVariables i\_xlateVars, ecmdDataBuffer &i\_memoryData, ecmdDataBuffer &io\_memoryTags, ecmdDataBuffer &o\_realAddress)

*Writes System Mainstore through the processor chip using an effective address.*

## Breakpoint Functions

- `uint32_t gipSetSoftwareBreakpoint (ecmdChipTarget &i_target, ecmdDataBuffer i_address, gipXlateVariables i_xlateVars, ecmdDataBuffer &o_breakpointTable, ecmdDataBuffer &o_virtualAddress)`

*Set a software breakpoint in Processor.*

- `uint32_t gipClearSoftwareBreakpoint (ecmdChipTarget &i_target, ecmdDataBuffer i_address, gipXlateVariables i_xlateVars, ecmdDataBuffer &o_breakpointTable, ecmdDataBuffer &o_virtualAddress)`

*Clear a software breakpoint in Processor.*

- `uint32_t gipGetSoftwareBreakpoint (ecmdChipTarget &i_target, ecmdDataBuffer i_address, gipXlateVariables i_xlateVars, ecmdDataBuffer &o_breakpointTable, ecmdDataBuffer &o_virtualAddress)`

*Get software breakpoint table.*

## System Info Function

- `uint32_t gipGetSystemInfo (cpcfSysInfo_t &o_systemInfo)`

*Get the System Info structure.*

## Misc/Test Functions

- `uint32_t gipConnectionTest (uint32_t i_options)`

*Used to interface with connection test function.*

### 6.9.1 Detailed Description

IP eCMD Perlapi Extension.

Extension Owner : Chris Engel

### 6.9.2 Function Documentation

#### 6.9.2.1 `int gipInitExtension (const char * i_clientVersion)`

Initialize eCMD GIP Extension DLL.

##### Parameters:

***i\_clientVersion*** Comma seperated list of eCMD Perl api major numbers this script supports, see details

##### Return values:

***ECMD\_SUCCESS*** if successful load

***ECMD\_INVALID\_DLL\_VERSION*** if Dll version loaded doesn't match client version

***nonzero*** if unsuccessful

**Postcondition:**

eCMD GIP Extension is initialized and version checked

VERSIONS : eCMD at times has to make changes to add/remove functionality and parameters to functions. This could cause incompatibility in your script if you used functions that have changed. The `i_clientVersion` string is used to tell eCMD which major releases you support such that your script will not continue execution if it encounters a version that is either not known about or not supported. This is similar to how the eCMD C-API works except in Perl you can support multiple versions with one script as long as the changes that were made between the versions do not affect your script.

```
USAGE : if (gipInitExtension("ver3,ver4")) { die "Fatal errors initializing DLL"; }
```

**6.9.2.2 uint32\_t gipReserve (chicReserveId i\_reserveId, uint32\_t i\_waitTime)**

Requests that the cecserver's serial thread only run commands that are sent with the specified reserve id. (From `chicclientlib.H/C`).

**Parameters:**

*i\_reserveId* The id that should be associated with the reserve if it is granted.

*i\_waitTime* The number of milliseconds to wait for the reserve to be granted. If this is set to zero, it will wait without timing out.

**Return values:**

*ECMD\_SUCCESS* if successful read

*nonzero* if unsuccessful

NOTE : See `chicclientlib.C` for more details

**6.9.2.3 uint32\_t gipRelease (chicReserveId i\_reserveId)**

Release an active reserve. (From `chicclientlib.H/C`).

**Parameters:**

*i\_reserveId* The id of an active reserve which is to be released. Possible values can be found in `chiccommon.H`.

**Returns:**

Upon success, a NULL pointer will be returned. Otherwise, a pointer to an `ErrlEntry` with the return code field set to one of the values below will be returned.

**Return values:**

*ECMD\_SUCCESS* if successful read

*nonzero* if unsuccessful

NOTE : See `chicclientlib.C` for more details

**6.9.2.4 uint32\_t gipAbort (chicReserveId i\_reserveId)**

Abort the currently executing serial command and any pending serial commands. (From `chicclientlib.H/C`).

**Parameters:**

*i\_reserveId* The reserve Id that will be made active just before chicAbort completes.

**Return values:**

**ECMD\_SUCCESS** if successful read

**nonzero** if unsuccessful NOTE : See chicclientlib.C for more details

### 6.9.2.5 uint32\_t gipSetServAddr (const char \* i\_servAddr, uint32\_t nets\_port)

Set the the Client's IP Address and the port # for the server its connecting to.

**Parameters:**

*i\_servAddr* constant string for the IP Address to be used

*nets\_port* [optional] port number to be used on the server

**Return values:**

**ECMD\_SUCCESS** if successful read

**nonzero** if unsuccessful NOTE : See chicclientlib.C for more details

### 6.9.2.6 uint32\_t gipGetMemProcVariousAddrType (ecmdChipTarget & i\_target, ecmdDataBuffer i\_address, uint32\_t i\_bytes, gipXlateVariables i\_xlateVars, ecmdDataBuffer & o\_memoryData, ecmdDataBuffer & o\_memoryTags, ecmdDataBuffer & o\_memoryEcc, ecmdDataBuffer & o\_memoryEccError, ecmdDataBuffer & o\_realAddress)

Reads System Mainstore through the processor chip using an effective address.

**Return values:**

**ECMD\_TARGET\_INVALID\_TYPE** if target is not a processor

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system

**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function

**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation

**ECMD\_INVALID\_MEMORY\_ADDRESS** Memory Address was not on a 8-byte boundary

**ECMD\_SUCCESS** if successful read

**nonzero** if unsuccessful

**Parameters:**

*i\_target* Struct that contains chip and cage/node/slot/position information

*i\_address* Starting address to read from

*i\_bytes* Number of bytes to write

*i\_xlateVars* Struct with numerous translation variables

*o\_memoryData* DataBuffer object that holds data read from memory

*o\_memoryTags* 1 Tag bit for every 64 bits of memory data

*o\_memoryEcc* 8 ECC bits for every 64 bits of memory data  
*o\_memoryEccError* 1 ECC Error bit for every 64 bits of memory data  
*o\_realAddress* Calculated Real Address

NOTE : This function requires that the address be aligned on an 8-byte boundary

TARGET DEPTH : Thread

TARGET STATES : Unused

**6.9.2.7** `uint32_t gipPutMemProcVariousAddrType (ecmdChipTarget & i_target,  
ecmdDataBuffer i_address, uint32_t i_bytes, gipXlateVariables  
i_xlateVars, ecmdDataBuffer & i_memoryData, ecmdDataBuffer &  
io_memoryTags, ecmdDataBuffer & o_realAddress)`

Writes System Mainstore through the processor chip using an effective address.

Return values:

**ECMD\_TARGET\_INVALID\_TYPE** if target is not a processor  
**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled  
to use this function  
**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to  
perform the operation  
**ECMD\_INVALID\_MEMORY\_ADDRESS** Memory Address was not on a 8-byte  
boundary  
**ECMD\_SUCCESS** if successful read  
**nonzero** if unsuccessful

Parameters:

*i\_target* Struct that contains chip and cage/node/slot/position information  
*i\_address* Starting address to read from  
*i\_bytes* Number of bytes to write  
*i\_xlateVars* Struct with numerous translation variables  
*i\_memoryData* DataBuffer object that holds data read from memory  
*io\_memoryTags* 1 Tag bit for every 64 bits of memory data (If this has length of zero, the  
user wants the HW to generate this info; otherwise, use their values.)  
*o\_realAddress* Calculated Real Address

NOTE : This function requires that the address be aligned on an 8-byte boundary

TARGET DEPTH : Thread

TARGET STATES : Unused

**6.9.2.8** `uint32_t gipSetSoftwareBreakpoint (ecmdChipTarget & i_target,  
ecmdDataBuffer i_address, gipXlateVariables i_xlateVars,  
ecmdDataBuffer & o_breakpointTable, ecmdDataBuffer &  
o_virtualAddress)`

Set a software breakpoint in Processor.

**Parameters:**

*i\_target* Struct that contains chip and cage/node/slot/position/core/thread information  
*i\_address* Address to set breakpoint at  
*i\_xlateVars* Struct with numerous translation variables  
*o\_breakpointTable* DataBuffer object that holds breakpoint table  
*o\_virtualAddress* Calculated Virtual Address

**Return values:**

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function  
**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation  
**ECMD\_RETRY\_WITH\_VIRTUAL\_ADDR** Requests that the user retries operation with returned Virtual Address  
**ECMD\_SUCCESS** if successful  
**nonzero** if unsuccessful

TARGET DEPTH : Thread

TARGET STATES : Unused

**6.9.2.9** `uint32_t gipClearSoftwareBreakpoint (ecmdChipTarget & i_target, ecmdDataBuffer i_address, gipXlateVariables i_xlateVars, ecmdDataBuffer & o_breakpointTable, ecmdDataBuffer & o_virtualAddress)`

Clear a software breakpoint in Processor.

**Parameters:**

*i\_target* Struct that contains chip and cage/node/slot/position/core/thread information  
*i\_address* Address to clear breakpoint at  
*i\_xlateVars* Struct with numerous translation variables  
*o\_breakpointTable* DataBuffer object that holds breakpoint table  
*o\_virtualAddress* Calculated Virtual Address

**Return values:**

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function  
**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation  
**ECMD\_RETRY\_WITH\_VIRTUAL\_ADDR** Requests that the user retries operation with returned Virtual Address  
**ECMD\_SUCCESS** if successful  
**nonzero** if unsuccessful

TARGET DEPTH : Thread

TARGET STATES : Unused

**6.9.2.10** `uint32_t gipGetSoftwareBreakpoint (ecmdChipTarget & i_target,  
ecmdDataBuffer i_address, gipXlateVariables i_xlateVars,  
ecmdDataBuffer & o_breakpointTable, ecmdDataBuffer &  
o_virtualAddress)`

Get software breakpoint table.

**Parameters:**

*i\_target* Struct that contains chip and cage/node/slot/position/core/thread information  
*i\_address* Address to get breakpoint at  
*i\_xlateVars* Struct with numerous translation variables  
*o\_breakpointTable* DataBuffer object that holds breakpoint table  
*o\_virtualAddress* Calculated Virtual Address

**Return values:**

**ECMD\_TARGET\_NOT\_CONFIGURED** if target is not available in the system  
**ECMD\_RING\_CACHE\_ENABLED** Ring Cache enabled function - must be disabled to use this function  
**ECMD\_CLOCKS\_IN\_INVALID\_STATE** Chip Clocks were in an invalid state to perform the operation  
**ECMD\_RETRY\_WITH\_VIRTUAL\_ADDR** Requests that the user retries operation with returned Virtual Address  
**ECMD\_SUCCESS** if successful  
**nonzero** if unsuccessful

TARGET DEPTH : Thread

TARGET STATES : Unused

**6.9.2.11** `uint32_t gipGetSystemInfo (cpcfSysInfo_t & o_systemInfo)`

Get the System Info structure.

**Parameters:**

*o\_systemInfo* Buffer containing the SystemInfo struct

**Return values:**

**ECMD\_SUCCESS** if successful  
**nonzero** if unsuccessful

**6.9.2.12** `uint32_t gipConnectionTest (uint32_t i_options)`

Used to interface with connection test function.

**Parameters:**

*i\_options* Options for the call

**Return values:**

**ECMD\_SUCCESS** if successful read  
**nonzero** if unsuccessful NOTE : See chicclientlib.C for more details

## 6.10 zseClientPerlapi.H File Reference

Z Series Perlapi Extension.

```
#include <ecmdReturnCodes.H>
#include <ecmdStructs.H>
#include <ecmdDataBuffer.H>
#include <zseStructs.H>
```

### Load/Unload Functions

- **int zseInitExtension** (const char \*i\_clientVersion)  
*Initialize eCMD GIP Extension DLL.*

#### 6.10.1 Detailed Description

Z Series Perlapi Extension.

Extension Owner : Han-Joachim Hartmann

#### 6.10.2 Function Documentation

##### 6.10.2.1 int zseInitExtension (const char \* i\_clientVersion)

Initialize eCMD GIP Extension DLL.

##### Parameters:

**i\_clientVersion** Comma seperated list of eCMD Perl api major numbers this script supports, see details

##### Return values:

**ECMD\_SUCCESS** if successful load

**ECMD\_INVALID\_DLL\_VERSION** if Dll version loaded doesn't match client version

**nonzero** if unsuccessful

##### Postcondition:

eCMD GIP Extension is initialized and version checked

VERSIONS : eCMD at times has to make changes to add/remove functionality and parameters to functions. This could cause incompatability in your script if you used functions that have changed. The i\_clientVersion string is used to tell eCMD which major releases you support such that your script will not continue execution if it encounters a version that is either not known about or not supported. This is similar to how the eCMD C-API works except in Perl you can support multiple versions with one script as long as the changes that were made between the versions do not affect your script.

USAGE : if (zseInitExtension("ver3,ver4")) { die "Fatal errors initializing DLL"; }



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