Question 1:

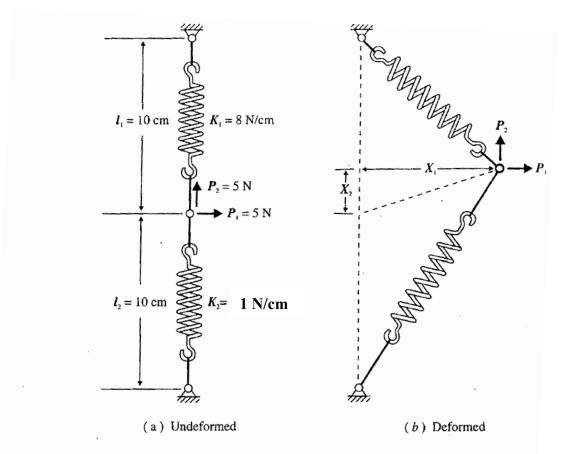
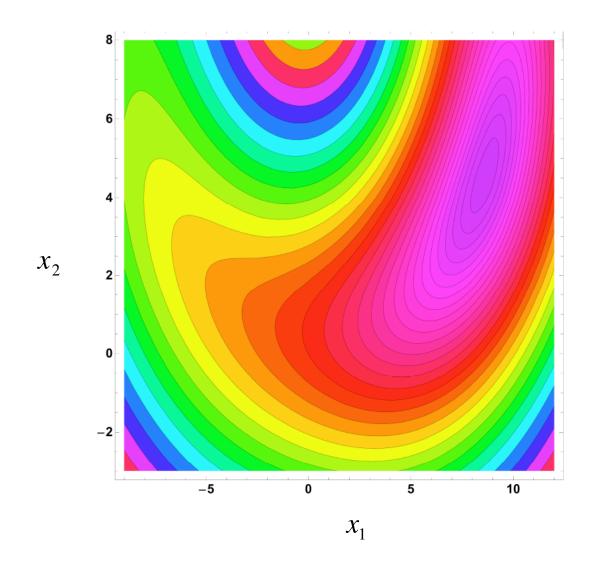


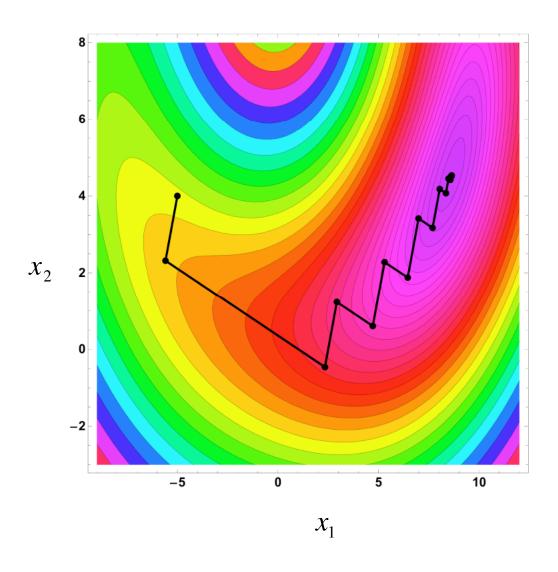
Figure 3-1 Equilibrium of a spring-force system.

$$F(x_1, x_2) = \frac{1}{2}K_1 \left\{ \sqrt{x_1^2 + (l_1 - x_2)^2} - l_1^2 \right\}^2 + \frac{1}{2}K_2 \left\{ \sqrt{x_1^2 + (l_2 + x_2)^2} - l_2^2 \right\}^2 - P_1 x_1 - P_2 x_2$$

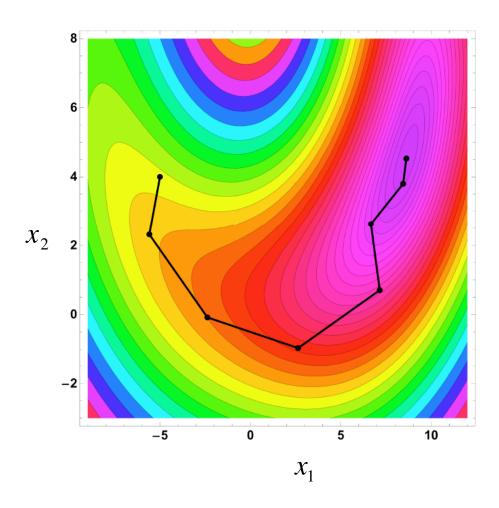


At the optimum $x_1 = 8.631 \text{ cm } x_2 = 4.533 \text{ cm}$ $F(x_1, x_2) = -41.81 \text{ N-cm}$

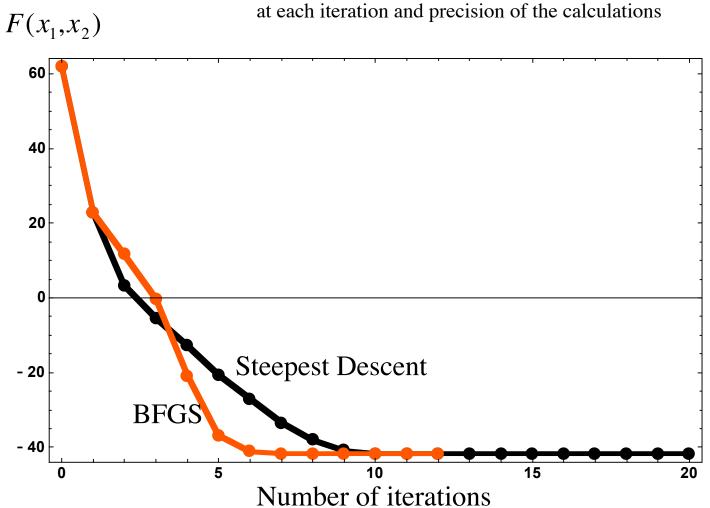
Steepest Descent (number of iterations = 20)



Quasi - Newton (BFGS) (number of iterations = 12)



Note that the number of itereations to converge may slightly change depending on the 1-D minimization results at each iteration and precision of the calculations



Question 2:

Define:

$$f_1(x) = 4x_1 - x_2 + x_3 - x_1x_4$$

$$f_2(x) = -x_1 + 3x_2 - 2x_3 - x_2x_4$$

$$f_3(x) = x_1 - 2x_2 + 3x_3 - x_3x_4$$

$$f_4(x) = x_1^2 + x_2^2 + x_3^2 - 1.0$$
where $x = \{x_1, x_2, x_3, x_4\}$

Minimize $f(x) = f_1^2 + f_2^2 + f_3^2 + f_4^2$ by Steepest Descent and BFGS methods

As can be seen from next slide, for both starting vectors BFGC method exhibits a superior convergence rate over the steepest descent method.

