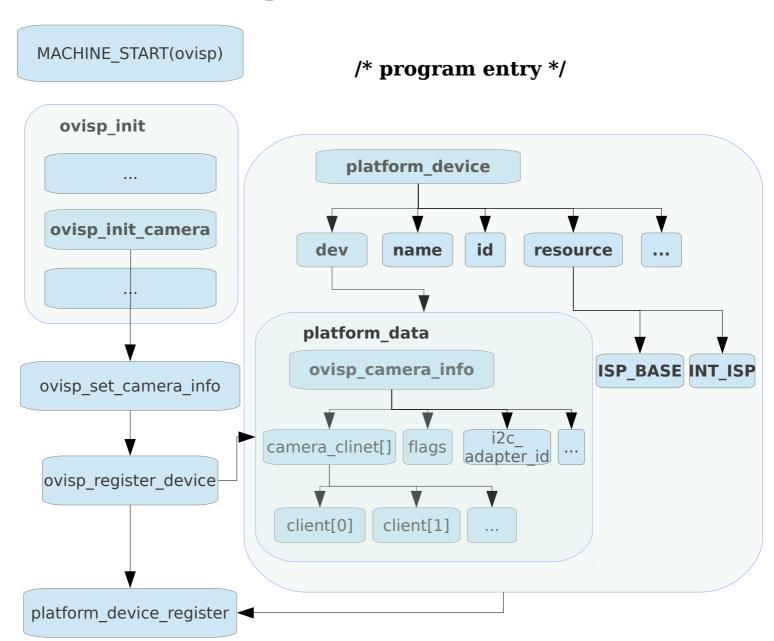
Ovisp_Driver_Spec

(1) register platform_device

arch/arm/mach-xxx/board xxx.c



add ovisp_camera_info to platform_device->dev.platform_data, add resource ISP_BASE and INT_ISP to platform_device->resource, then register platform_device

```
/*in arch/arm/mach-xxx/device.c */
/*ovisp device camera defined here*/
struct platform device ovisp device camera = {
  .name = "ovisp-camera",
  .id = -1,
  .dev = {
    .dma mask = &ovisp camera dma mask, /*\sim(u64)0*/
    .coherent dma mask = 0xfffffffff,
  },
  .num resources = ARRAY SIZE(ovisp resource camera),
  .resource = ovisp resource camera,
};
/* resource camera defined here */
static struct resource ovisp resource camera[] = {
  [0] = \{
    .start = ISP BASE,
    .end = ISP BASE + 0x80000,
    .flags = IORESOURCE MEM,
  },
  [1] = {
    .start = INT ISP
    .end = INT ISP
    .flags = IORESOURCE IRQ,
  },
};
/*camera clients for v4l2 subdev defined here*/
static struct ovisp camera client ovisp camera clients[] = {
#if defined(CONFIG VIDEO OV5647) {
    .board info = \&ov5647 board info,
    .flags = CAMERA CLIENT IF MIPI,
    .mclk rate = 26000000, /* can be set when isp open */
    .max video width = 1280,
    .max video height = 960,
    .power = ov5647 power,
    .reset = ov5647 reset
  },
#endif
#if defined(CONFIG VIDEO Front camera) {
    .board info = ,
    .flags = CAMERA CLIENT IF DVP
        | CAMERA CLIENT CLK EXT
        | CAMERA CLIENT ISP BYPASS,
```

(2)register ovisp_camera_ driver

```
drivers/media/video/ovisp/ovisp video.c
```

init:

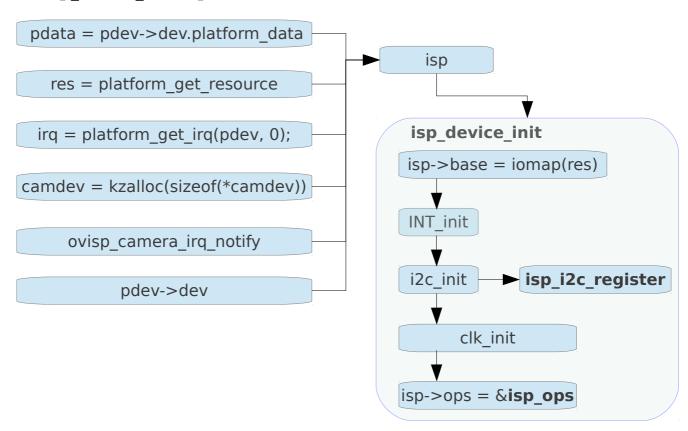
platform_driver_register(&ovisp_camera_driver);

probe:

ovisp_camera_probe(platform_device * pdev)

/* platform_device registered in step (1), got platform_data from pdev */

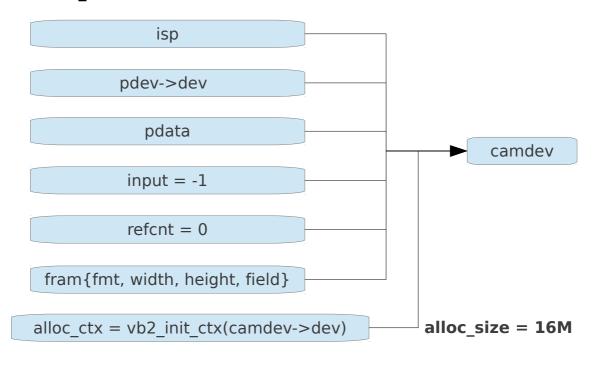
isp_device_init(isp);



```
v4l2_device_register(NULL, &camdev->v4l_dev);

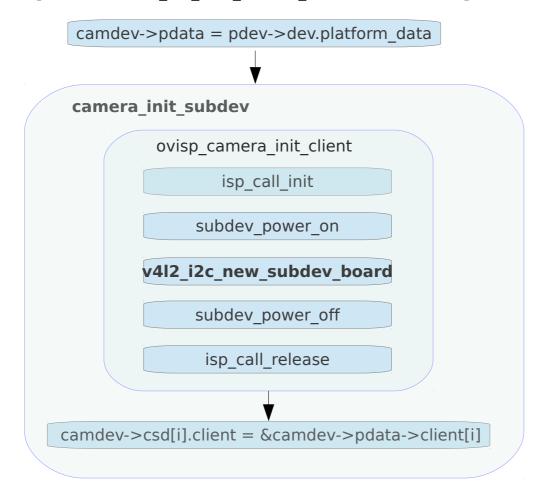
/* init camdev->v4l_dev , dev = NULL ,return 0, */
```

camdev init



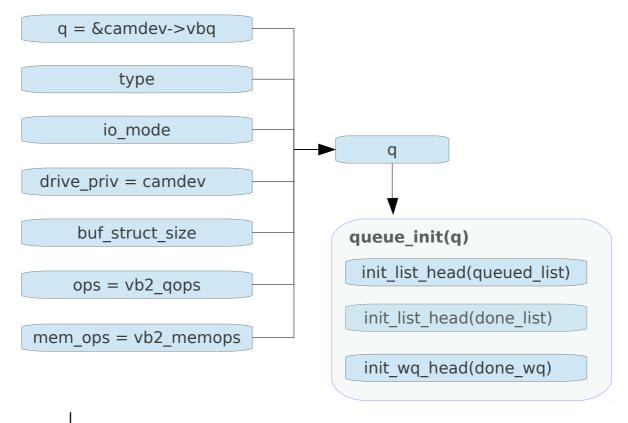
camera_init_subdev(&camdev);

/*ovisp_camera_init_client(camdev, &pdata->client[0/1], 0/1);*/
/*v4l2_subdev csd->sd = v4l2_i2c_new_subdev_board() */
/* the process of v4l2 i2c new subdev board described in part (5) */



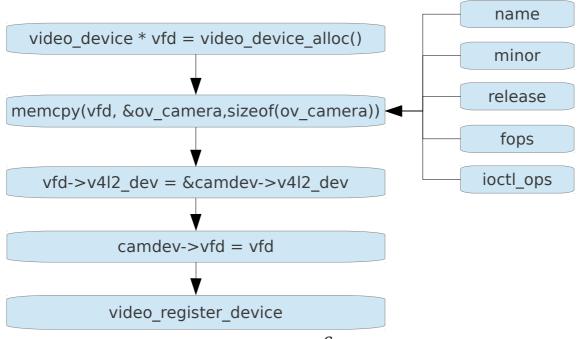
queue_init

/* initialized queue info, alloc queue will be finished in reqbufs */

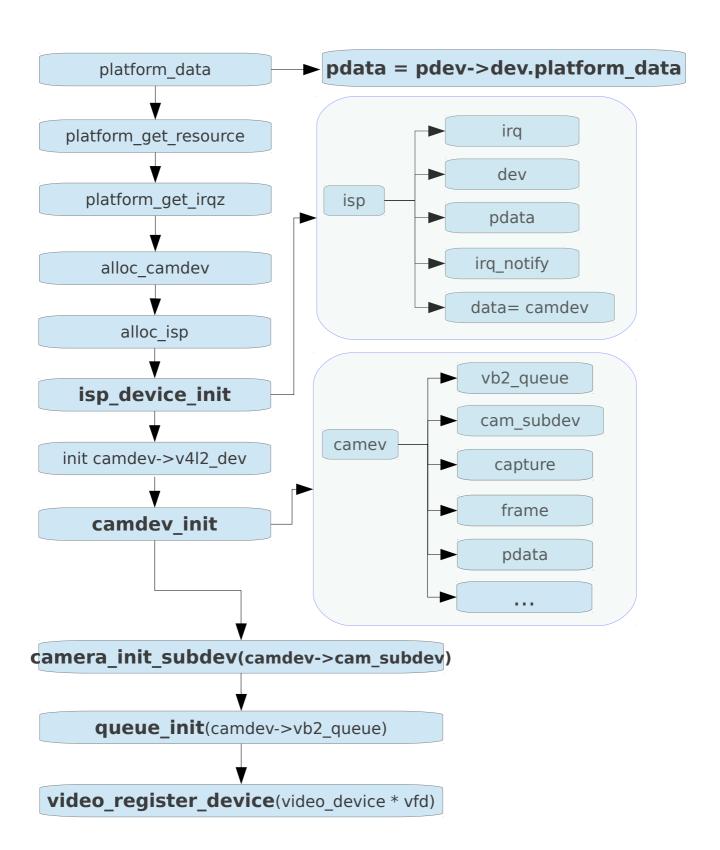


video_register_device(vfd, VFL_TYPE_GRABBER, -1);

/* register video device vfd */

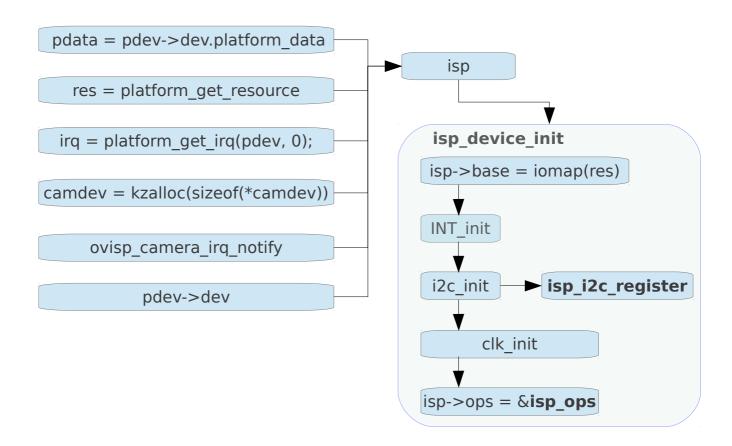


```
/* video device */
static struct video device ovisp camera = {
   .name = "ovisp-camera",
   .minor = -1,
  .release = video device release,
  .\text{fops} = \&\text{ovisp v4l2 fops},
  .ioctl ops = &ovisp \sqrt{412} ioctl ops,
};
/*struct platform driver*/
static struct platform driver ovisp camera driver = {
   .probe = ovisp camera probe,
   .remove = exit p(ovisp camera remove),
   .driver = {
     .name = "ovisp-camera",
     .owner = THIS MODULE,
#ifdef CONFIG_PM
     .pm = \&ovisp\_camera\_pm\_ops,
#endif
   },
};
```



(3)register and ioctl for ISP

/* init_isp in camera_probe*/



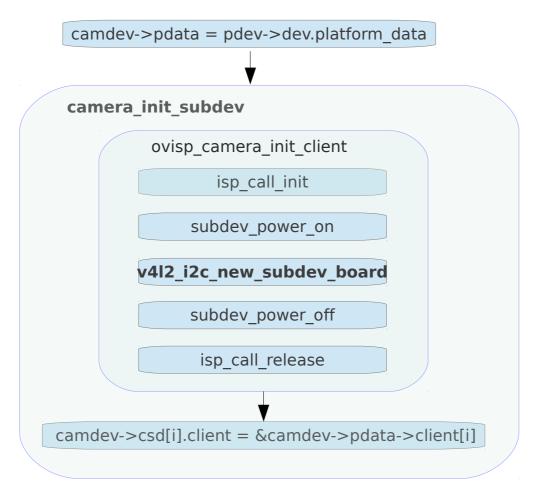
```
static struct resource ovisp resource camera[] = {
  [0] = [0]
    .start = ISP BASE,
    .end = ISP_BASE + 0x80000,
    .flags = IORESOURCE MEM,
  },
  [1] = {
    .start = INT ISP
    .end = INT ISP
    .flags = IORESOURCE IRQ,
  },
};
static struct isp_clk_info isp_clks[ISP_CLK_NUM] = {
   {"isp cphy cfg clk", 26000000, ISP CLK CSI},
   {"isp_axi_clk",
                   156000000, ISP_CLK_CSI},
                   156000000, ISP CLK MAIN | ISP CLK DEV},
   {"isp p sclk",
   {"isp sclk2",
                  156000000, ISP CLK MAIN},
                  200000000, ISP CLK MAIN},
   {"isp hclk",
};
```

```
isp->res get ovisp resource camera[0]
isp->irg get ovisp resource camera[1]
isp->base get isp base addr by iomap
isp irg registered in INT init, irg notify will be called in isp irg
isp i2c register in i2c init
clk init config 5 isp clk to choose
/* isp ops used to ctrl isp by app ioctl */
/* struct isp ops */
static struct isp ops isp ops = \{
   .init = isp init,
   .release = isp release,
   .open = isp open,
   .close = isp close,
   .config = isp config,
   .suspend = isp suspend,
   .resume = isp resume,
   .mclk on = isp mclk on,
   .mclk off = isp mclk off,
   .start capture = isp start capture,
   .stop capture = isp stop capture,
   .enable capture = isp enable capture,
   .disable capture = isp disable capture,
   .update buffer = isp update buffer,
   .check fmt = isp check fmt,
   .try fmt = isp try fmt,
   .pre fmt = isp pre fmt,
   .s fmt = isp s fmt,
   .s ctrl = isp s ctrl,
   .g ctrl = isp g ctrl,
   .s parm = isp s parm,
   .g parm = isp g parm,
};
```

(4)register and ioctl ov5647

drivers/media/video/ov5647.c

/* init_subdev process in camera_probe() */



```
csd = &camdev->csd[index];
csd->sd = v4l2 i2c new subdev board(&camdev->v4l2 dev,
    csd->i2c adap,
    client->board info,
    NULL);
                                 i2c adapter id =
                                                           client =
                           camdev->pdata->i2c_adapter_id
                                                           camdev->pdata->client[i]
   v4l2 device register
                           csd->i2c adap =
                                                            client->board info
(NULL , camdev->v4l dev)
                           i2c_get_adapter(i2c_adapter_id)
   camdev->v4l2 dev
                              i2c adapter * adapter
                                                            i2c board info * info
                  struct v4l2 subdev *
                  v4l2 i2c new subdev board()
              client = i2c_new_device(adapter, info)
                                    flag
                                                     client
                                    addr
              platform_data
                                     irq
                 parent
                                                     device_register
                                    name
                                                      (&client->dev)
                  bus
                                   adapter
                  type
                                     dev
                of node
                         sd = i2c get clientdata(client)
                  sd = v4l2 device register subdev(v4l2 dev, sd)
                            return sd; /*v4l2_subdev*/
```

#endif

};

i2c add driver(&ov5647 driver) ov5647 probe info = kzalloc(sizeof(struct ov5647 info), GFP KERNEL); v4l2 i2c subdev init(sd, client, &ov5647 ops); ov5647 detect kfree(info) /* i2c driver for ov5647 */ static struct i2c driver ov5647 driver = { $.driver = {$.owner = THIS MODULE,.name = "ov5647", }, .probe = ov5647 probe, remove = ov5647 remove,.id table = ov5647 id, **}**; /*ov5647 ops */ static const struct v4l2 subdev core ops ov5647 core ops = { .g chip ident = ov5647 g chip ident,.g ctrl = ov5647 g ctrl,.s ctrl = ov5647 s ctrl,.queryctrl = ov5647 queryctrl, .reset = ov5647 reset,.init = ov5647 init,#ifdef CONFIG VIDEO ADV DEBUG .g register = ov5647_g_register, .s register = ov5647 s register,

```
static const struct v4l2 subdev video ops ov5647 video ops = {
  .enum mbus fmt = \overline{\text{ov}}5647 enum mbus fmt,
  .try mbus fmt = ov5647 try mbus fmt,
  .s \overline{m}bus \overline{f}mt = ov5647 s \overline{m}bus fmt,
  .s stream = ov5647_s_stream,
  .cropcap = ov5647\_cropcap,
  .g crop = ov5647 g crop,
  .s_parm = ov5647_s_parm,
  .g parm = ov5647 g parm,
  .enum_frameintervals = ov5647_enum_frameintervals,
  .enum framesizes = ov5647 enum framesizes,
};
static const struct v4l2 subdev ops ov5647 ops = {
  .core = \&ov5647 core ops,
  .video = \&ov5647 video ops,
};
```

(5)Buffer Management

ovisp_vidioc_s_input((struct file *file, void *priv, unsigned int
index))

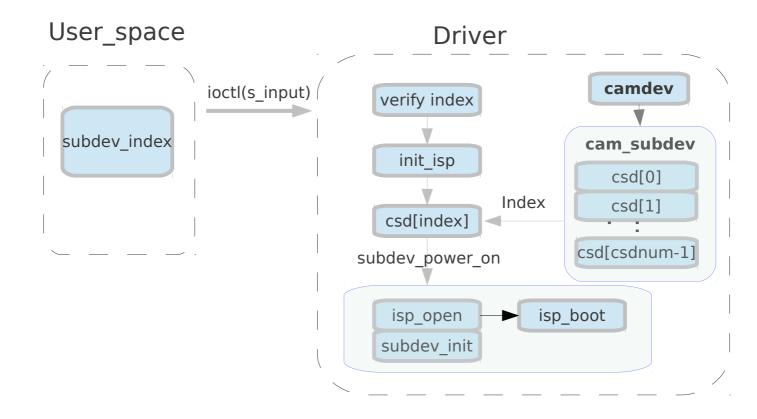
para:

file: file handle to get video_device;

priv: have not used;

index: client index for subdev;

process:



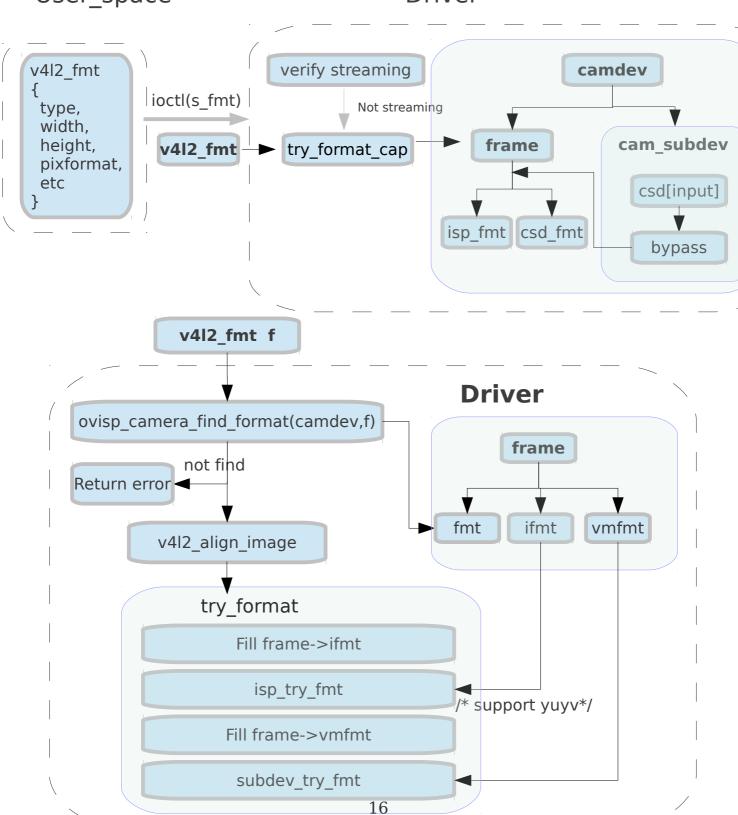
ovisp_vidioc_s_fmt_vid_cap(struct file *file, void *priv, struct
v4l2 format *f)

para:

f: v4l2_format set by app, include v4l2_type, video image format

process:

User_space Driver



```
/* isp format */
static struct ovisp_camera_format formats[] = {
  {
            = "YUV 4:2:2 packed, YCbYCr",
     .name
            = V4L2 MBUS FMT SBGGR8 1X8,
     .code
     .fourcc = V4L2 PIX FMT YUYV,
     .depth
             = 16.
  },
            = "YUV 4:2:0 semi planar, Y/CbCr",
     .name
            = V4L2 MBUS FMT SBGGR8 1X8,
     .code
     .fourcc = V4L2 PIX FMT NV12,
            = 12.
     .depth
  },
};
static struct ovisp camera format bypass formats[] = {
  {
            = "YUV 4:2:2 packed, YCbYCr",
     .name
            = V4L2 MBUS FMT YUYV8 2X8,
     .code
     .fourcc = V4L2 PIX FMT YUYV
     .depth
             = 16,
  },
};
/* ov5647 format */
static struct ov5647 format struct {
  enum v4l2 mbus pixelcode mbus code;
  enum v4l2 colorspace colorspace;
  struct regval list *regs;
} ov5647 formats[] = {
  {
     .mbus code = V4L2 MBUS FMT SBGGR8 1X8,
     .colorspace = V4L2 COLORSPACE SRGB,
     .reas
             = NULL
  },
};
```

ovisp_vidioc_reqbufs(struct file *file, void *priv, struct,
v4l2_requestbuffers *p)

para:

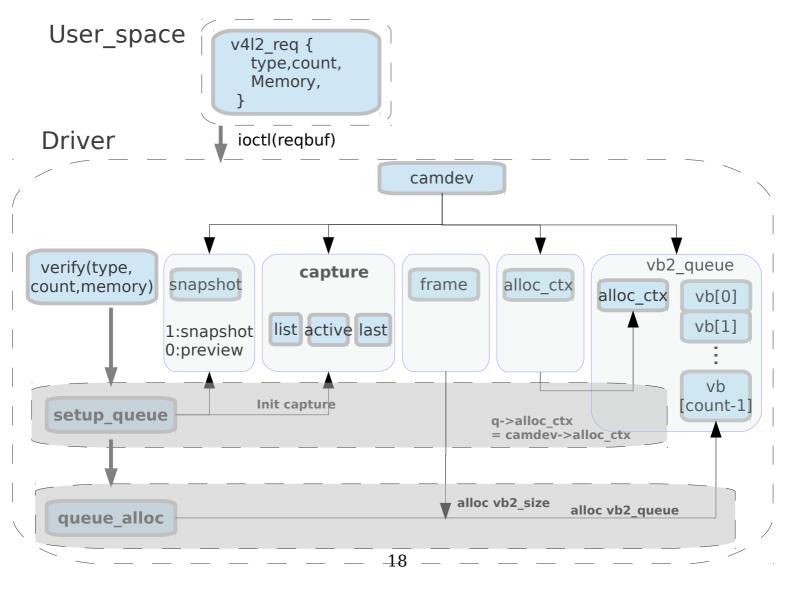
p: struct passed from userspace

functions:

- 1) verifies streaming parameters passed from the userspace,
- 2) sets up the queue,
- 3) negotiates number of buffers and planes per buffer with the driver to be used during streaming,
- 4) allocates internal buffer structures (struct vb2_buffer), according to the agreed parameters,
- 5) for MMAP memory type, allocates actual video memory, using the memory handling/allocation routines provispided during queue initialization

process:

vb2_reqbufs(struct vb2_queue *q, struct v4l2_requestbuffers *req)



ovisp_vidioc_querybuf(struct file *file, void *priv, struct v4l2 buffer *p)

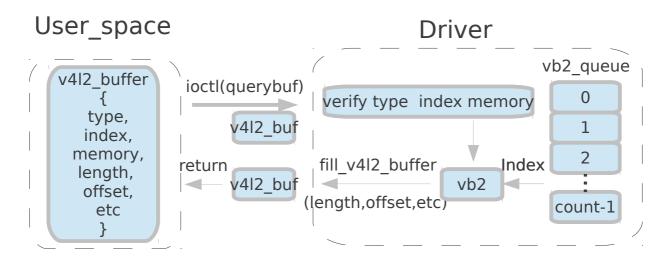
para:

function:

verify the passed v4l2_buffer structure and fill the relevant information for the userspace.

process:

vb2_qbuf(struct vb2_queue *q, struct v4l2_buffer *b)
struct vb2_queue q = camdev->vbq



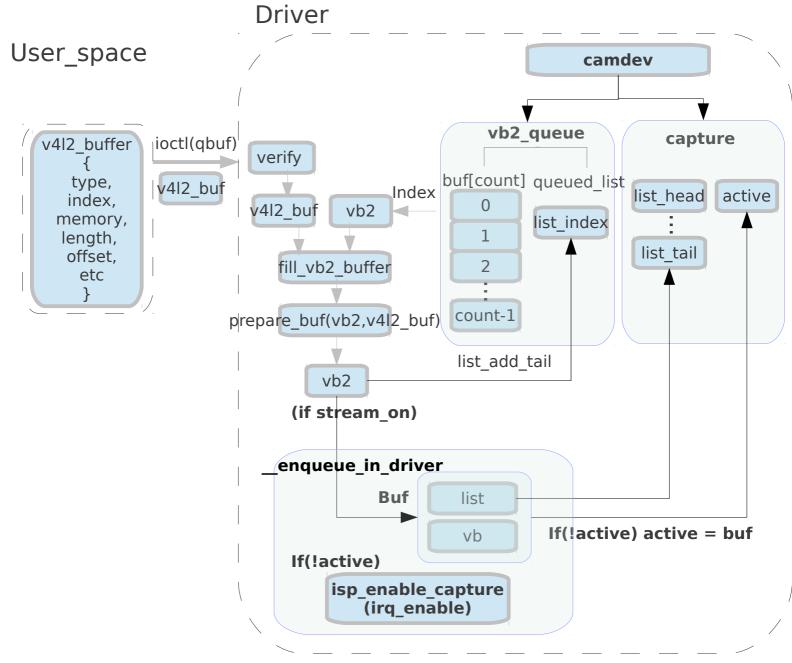
ovisp_vidioc_qbuf(struct file *file, void *priv, struct v4l2_buffer
*p)

para: function:

- 1) verifies the passed buffer,
- 2) calls buf_prepare callback in the driver (if provispided), in which driver-specific buffer initialization can be performed,
- 3) if streaming is on, queues the buffer in driver by the means of buf_queue callback for processing.

Progress:

vb2_qbuf(struct vb2_queue *q, struct v4l2_buffer *b)



ovisp_vidioc_streamon(struct file *file,void *priv, enum v4l2_buf_type i)

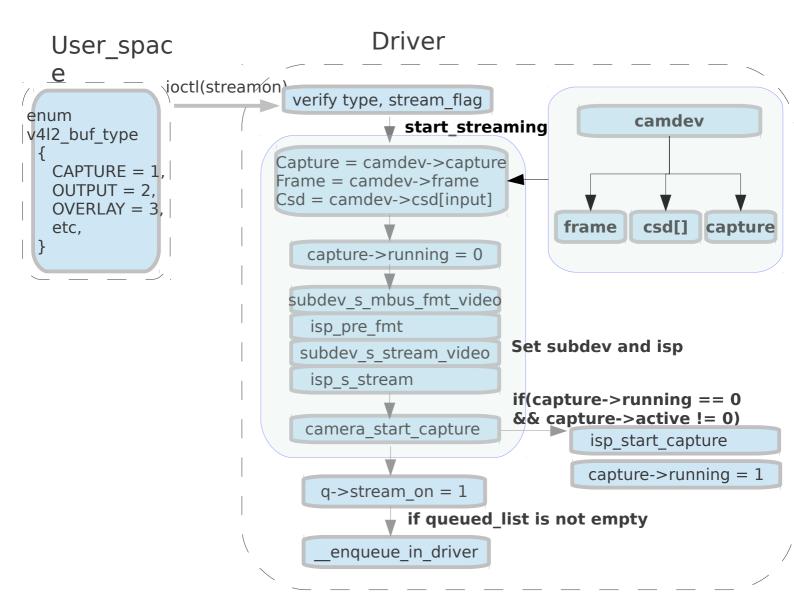
para:

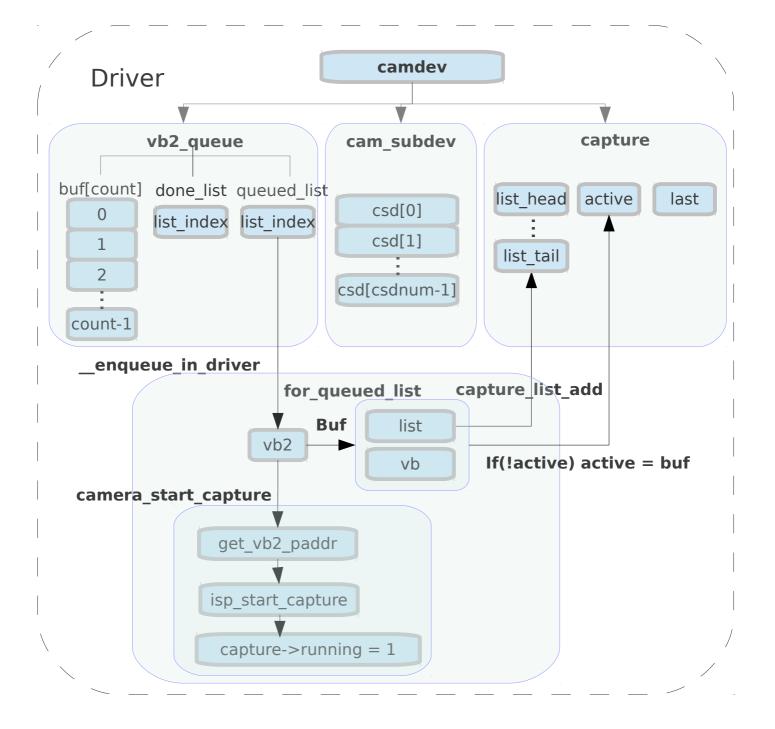
function:

- 1) verifies current state
- 2) starts streaming and passes any previously queued buffers to the driver

process:

ovisp camera start streaming(struct ovisp camera dev *camdev)





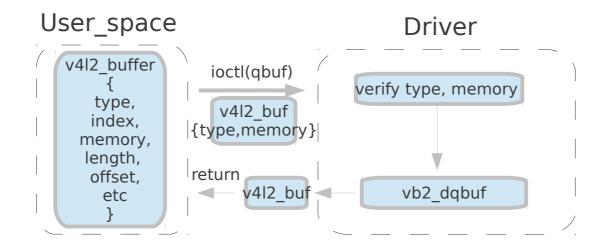
ovisp_vidioc_dqbuf(struct file *file, void *priv, struct v4l2_buffer
*p)

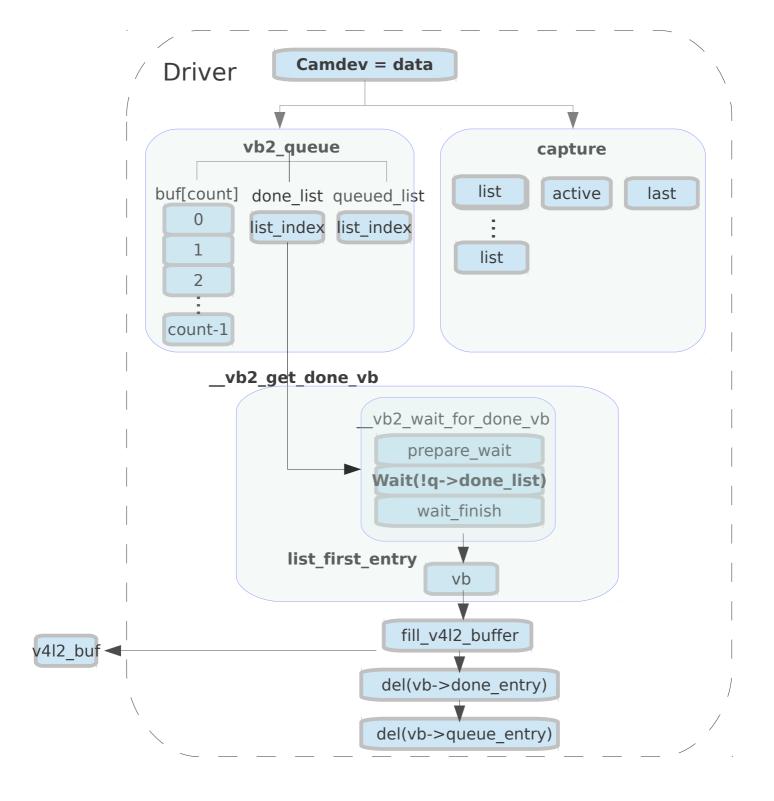
para:

Function:

- 1) verifies the passed buffer,
- 2) calls buf_finish callback in the driver (if provided), in which driver can perform any additional operations that may be required before returning the buffer to userspace, such as cache sync,
- 3) the buffer struct members are filled with relevant information for the userspace.

Process:





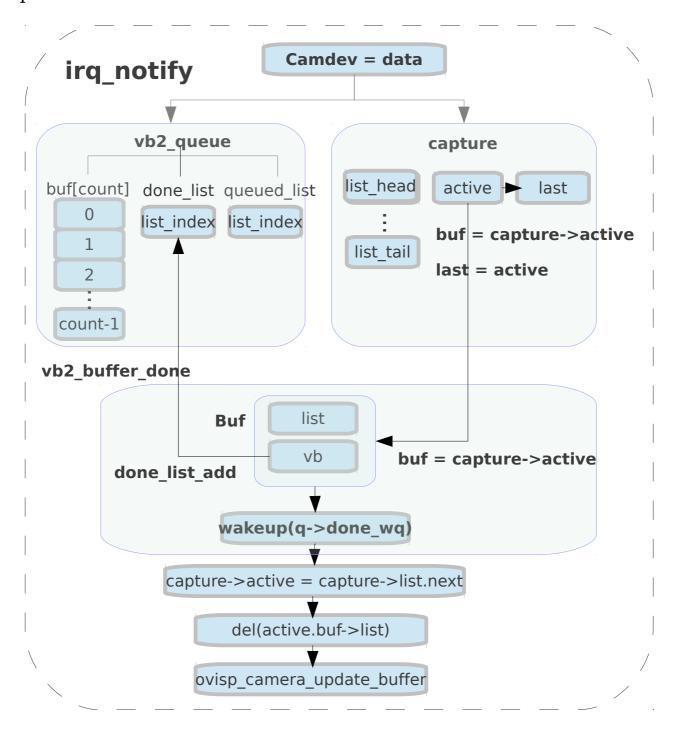
ovisp_camera_irq_notify(unsigned int status, void *data)

para:

function:

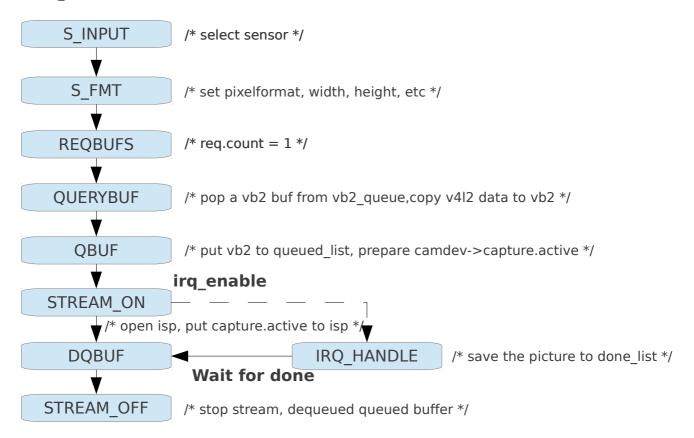
irq function called after hardware operation, capture frame and update the $vb2_queue\ list$

process:



(6) Main Operations

Capture

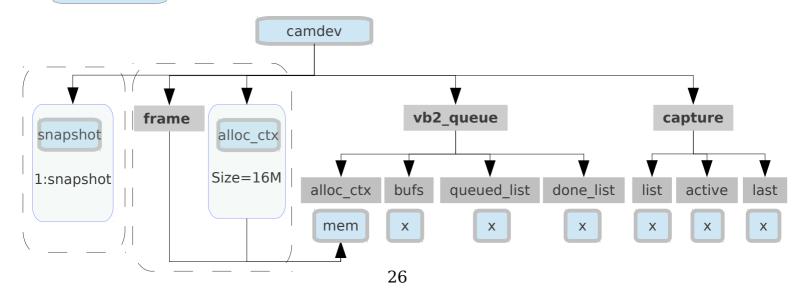


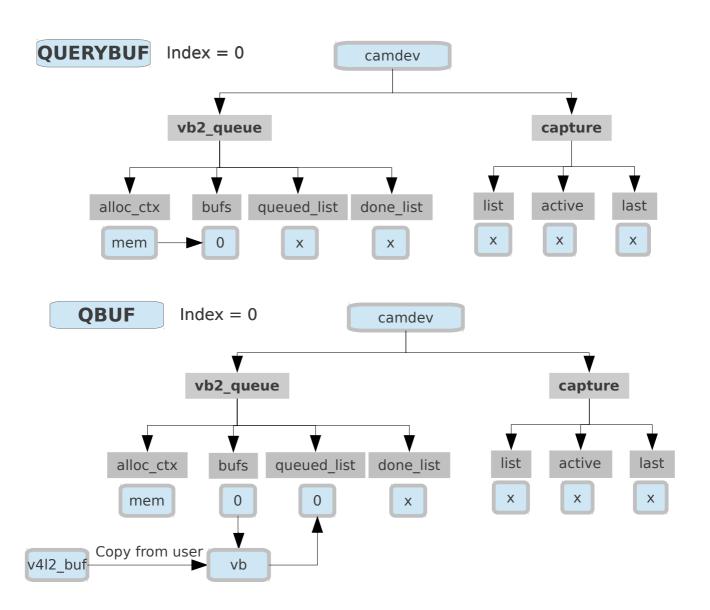
/* camdev in capture process */

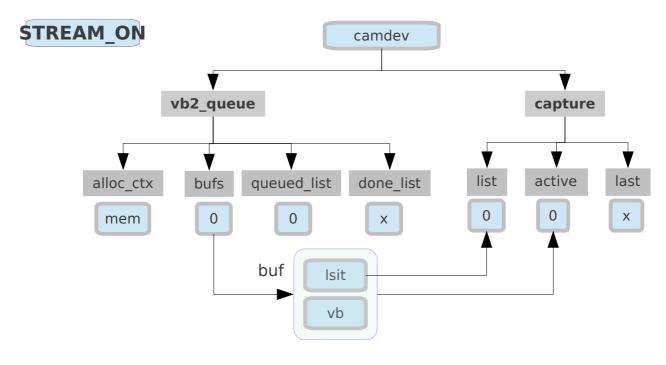
S_INPUT

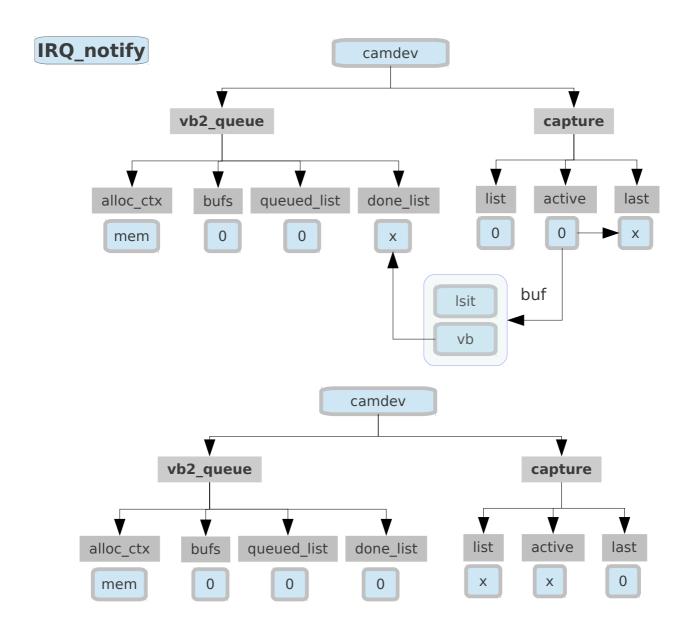
S_FMT

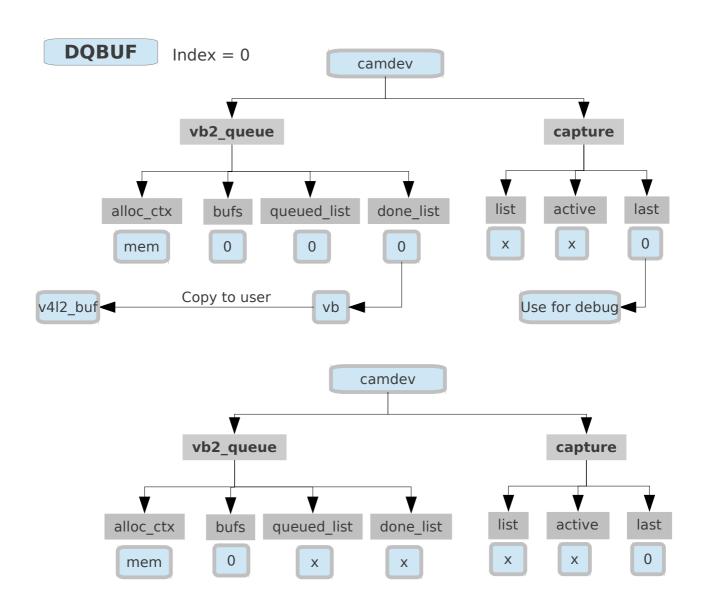
REQBUFS req.count = 1

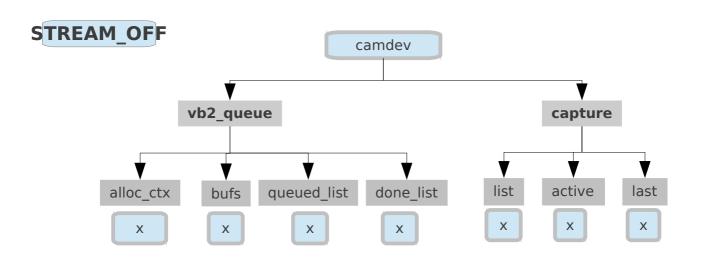




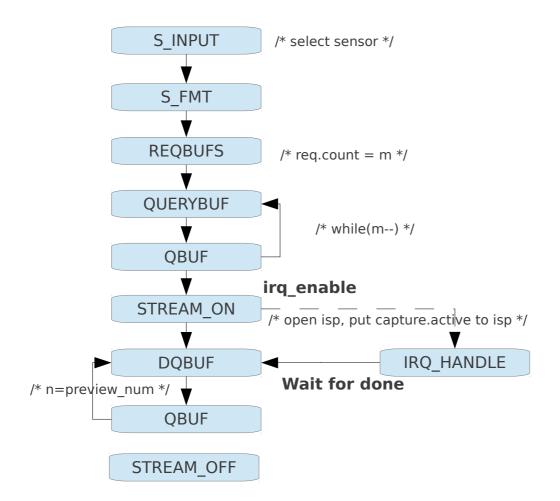








Preview

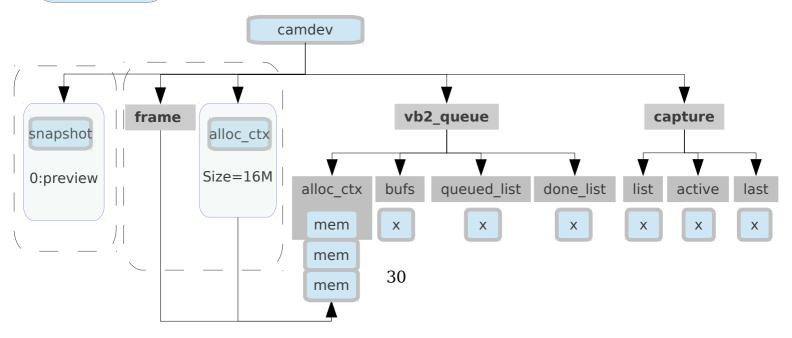


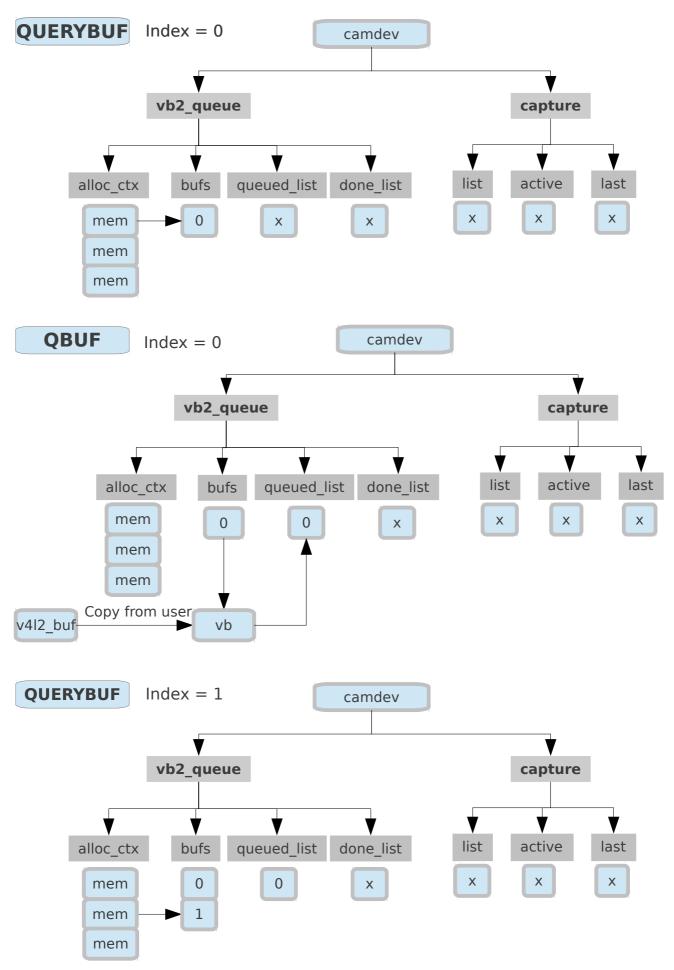
/* camdev in capture process */

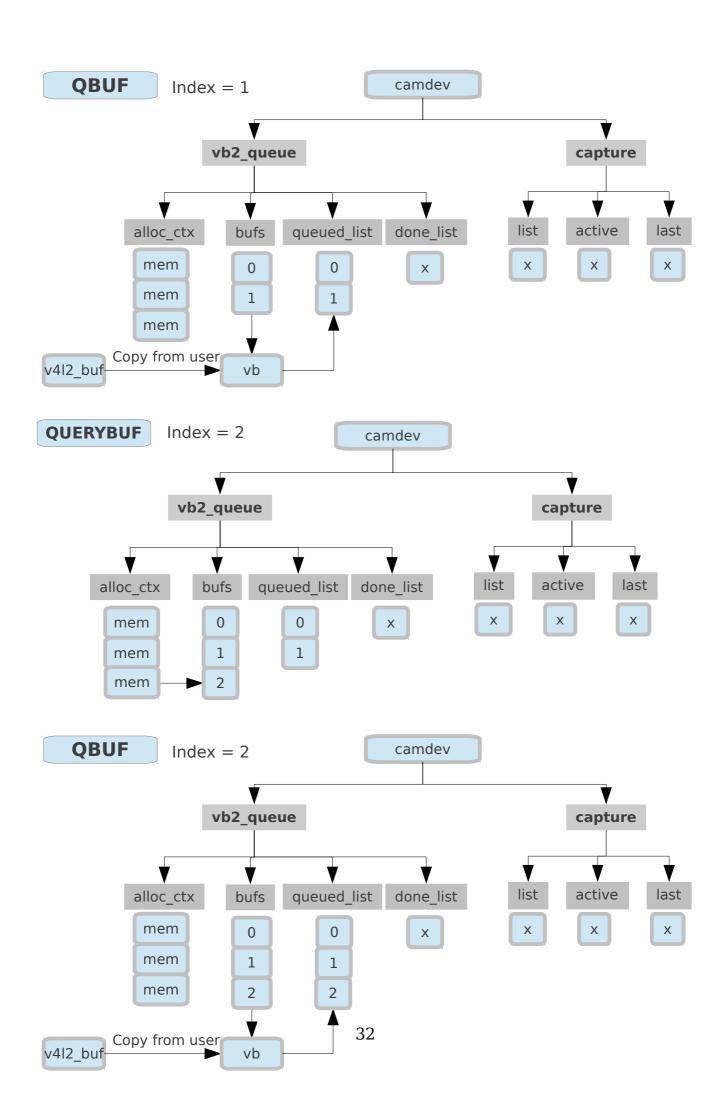
S INPUT

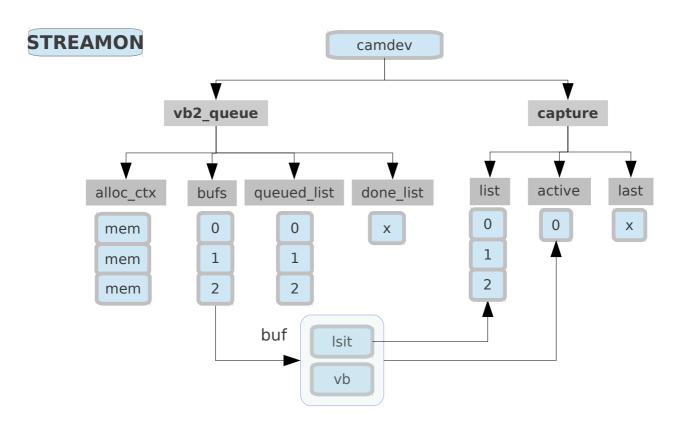
S_FMT

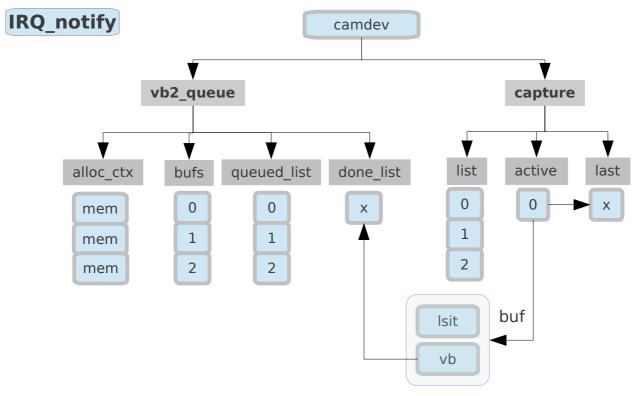
REQBUFS req.count = 3

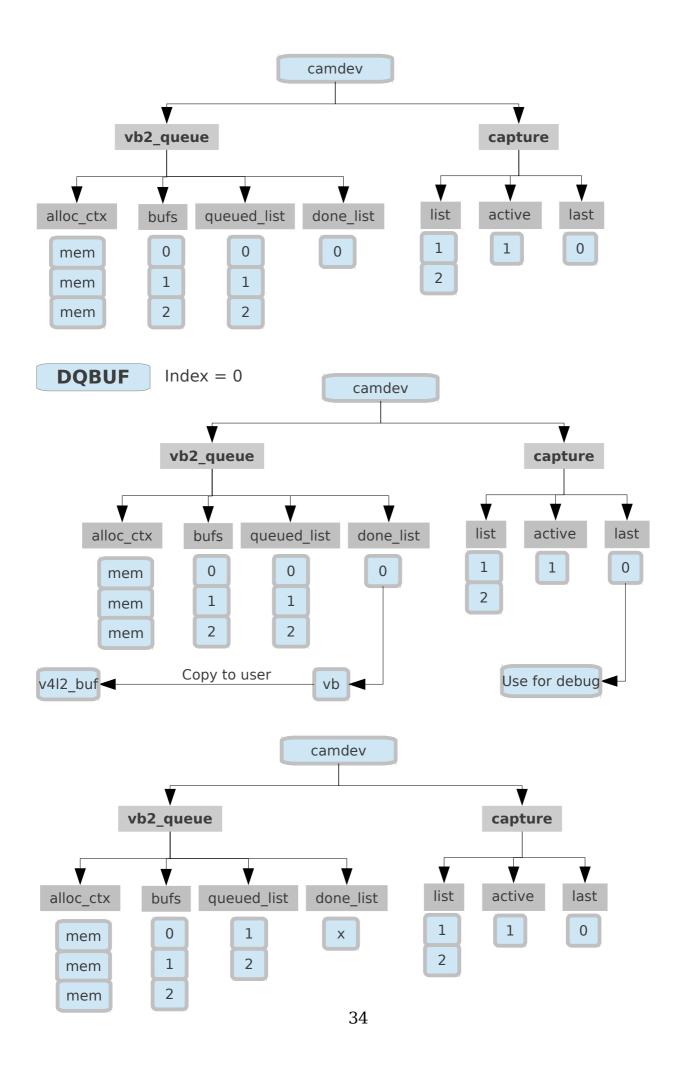


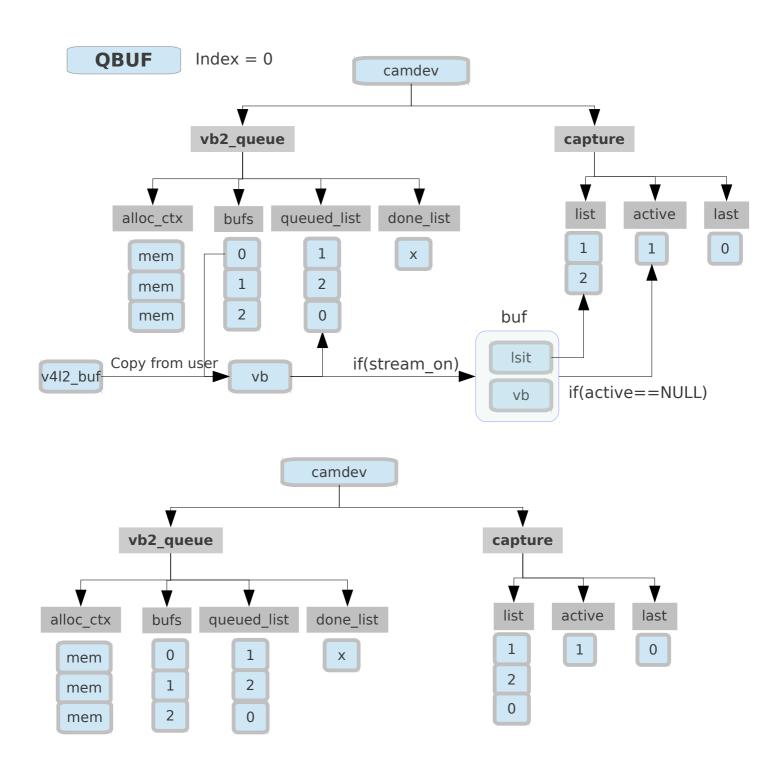






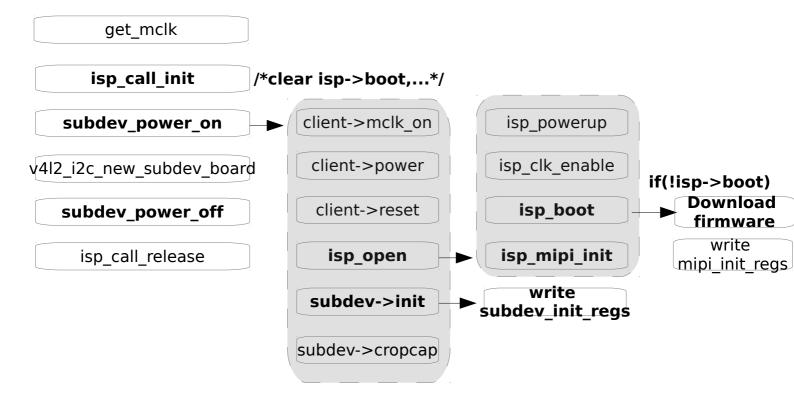




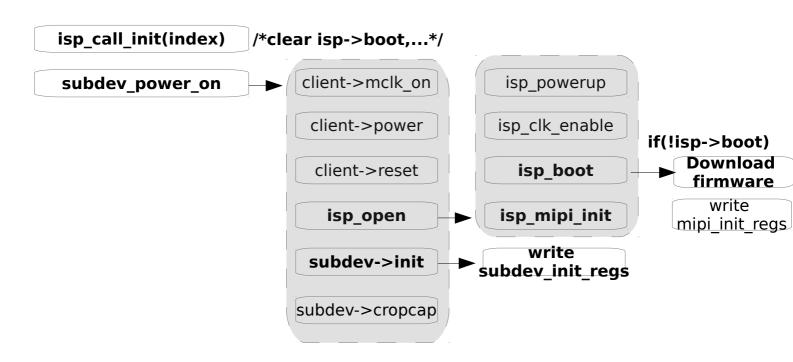


(7) ISP CONFIG

camera_init_client

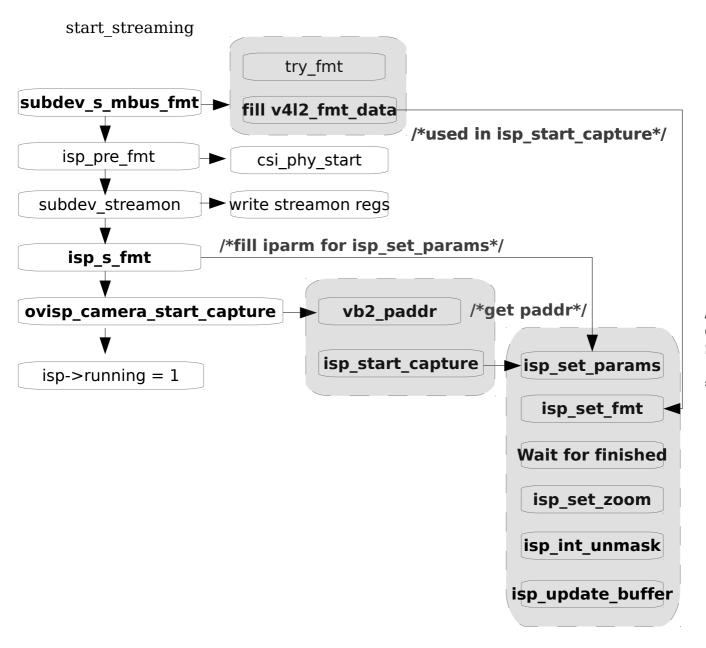


s_input



s_fmt

stream_on



/* change Sensor Fmt */