Topics for Final Exam Math 212 Fall Semester 2017

The final exam will contain *four* sections: (I) **Definitions**, (II) **T/F**, (III) **Multiple Choice**, and (IV) **Problems**. The following topics might appear on the final exam.

• Definitions:

- 1. linear equation
- 2. particular solution to a linear equation
- 3. general solution to a linear equation
- 4. $m \times n$ linear system of equations
- 5. particular solution a linear system of equations
- 6. general solution to a linear system of equations
- 7. consistent linear system of equations
- 8. augmented matrix of a linear system of equations
- 9. three types of row operations
- 10. row echelon form
- 11. pivot entry
- 12. pivot positions
- $13.\ pivot\ columns$
- 14. Fundamental Theorem of Linear Systems
- $15.\ reduced\ row\ echelon\ form$
- 16. free variable
- 17. matrix equality
- $18.\ matrix\ addition/subtraction$
- 19. matrix-scalar multiplication
- 20. matrix-matrix multiplication
- 21. indentity matrix I_n
- 22. matrix transpose
- $23.\ matrix\ trace$
- 24. matrix inverse
- $25.\ nonsigular\ matrix$
- 26. singular matrix
- 27. $matrix power A^n$
- 28. a linear transformation $T: \mathbb{R}^n \to \mathbb{R}^m$
- 29. the two linearity properties of a linear transformation
- 30. linear combination of vectors $u_1, u_2, ..., u_k$ in \mathbb{R}^n
- 31. null space of a linear transformation $T: \mathbb{R}^n \to \mathbb{R}^m$
- 32. unit vector e_i in \mathbb{R}^n
- 33. standard matrix A of a linear transformation $T: \mathbb{R}^n \to \mathbb{R}^m$
- 34. determinant of a square matrix A in terms of ref and factors
- 35. minor of an entry a_{ij} in a matrix A
- 36. cofactor of an entry a_{ij} in a matrix A
- 37. adjoint of a matrix A

- 38. closure of \oplus and \odot in a vector space
- 39. commutativity of \oplus
- 40. associativity of \oplus
- 41. distributivity of \odot across \oplus
- 42. the vector spaces \mathbb{R}^n , \mathcal{M}_{mxn} , \mathbb{P} , \mathbb{P}_n , \mathbb{R}^+ (with $x \oplus y = xy$ and $\alpha \oplus x = x^{\alpha}$), \mathbb{R} (with $x \oplus y = x y b$ and $\alpha \oplus x = \alpha(x b) + b$)
- 43. a *subspace* of an abstract vector space
- 44. the $span\{v_1, v_2, ..., v_k\}$
- 45. a nontrivial linear combination of the vectors $\{v_1, v_2, ..., v_k\}$
- 46. linearly dependent vectors $\{v_1, v_2, ..., v_k\}$
- 47. linearly independent vectors $\{v_1, v_2, ..., v_k\}$
- 48. basis of a vector space V
- 49. finite-dimensional vector space V
- 50. dim(V)
- 51. standard basis for \mathbb{R}^n
- 52. coordinates of a vector $(v)_B$ with respect to a basis B
- 53. transition matrix $P_{B\to B'}$ where B and B' are bases of the same vector space
- 54. eigenvalue λ of a linear transformation $T: \mathbb{R}^n \to \mathbb{R}^n$
- 55. eigenvector v of an eigenvalue λ
- 56. characteristic polynomial $p(\lambda) = \det(\lambda I A)$
- 57. eigenspace of an eigenvalue λ
- 58. Row(A), Col(A), Null(A)
- 59. nullity of A
- $60. \ rank \ of A$
- 61. one-to-one function
- 62. onto function
- 63. injection, surjection, and bijection
- 64. identity linear transformation
- **Problems:** Be able to do the following types of problems.
 - 1. Form the augmented matrix of a linear system of equation, put it into row echelon form, and find the general solution of the system.
 - 2. Put a matrix in row echelon form into reduced row echelon form.
 - 3. Perform varied types of computations with matrices: add, subtract, scalar-multiply, multiply, find transposes, find traces, and find powers of matrices.
 - 4. Prove simple facts about matrices, their inverses, transposes, powers, traces, etc.
 - 5. Find the inverse of a matrix by solving a system of equations.
 - 6. Know the seven equivalent statements (so far) that can be made about a matrix A: A is invertible $\Leftrightarrow Ax = 0$ has only the trivial solution \Leftrightarrow the reduced row echelon form of A is the identity $I_n \Leftrightarrow A$ is the product of elementary matrices $\Leftrightarrow Ax = b$ is consistent for any choice of rhs $b \Leftrightarrow Ax = b$ has a unique solution for every choice of rhs $b \Leftrightarrow \det(A) \neq 0$.
 - 7. Know how to prove that a function $T: \mathbb{R}^n \to \mathbb{R}^m$ is a linear transformation from the definition of a linear transformation.
 - 8. Know the two commuting diagrams presented in class for a linear transformation.

- 9. Know how to disprove that a function $T: \mathbb{R}^n \to \mathbb{R}^m$ is a linear transformation.
- 10. Know that $T(0_n) = 0_m$ where 0_n and 0_m are the zero column vectors in \mathbb{R}^n and \mathbb{R}^m respectively.
- 11. Know that $T(\alpha u + \beta v) = \alpha T(u) + \beta T(v)$ where $u, v \in \mathbb{R}^n$ and $\alpha, \beta \in \mathbb{R}$. In general, a linear transformation of a linear combination of vectors in \mathbb{R}^n is a linear combination of the functional values of those vectors in \mathbb{R}^m .
- 12. Know how to obtain the standard matrix of a linear transformation.
- 13. Know that the standard matrix of a linear transformation is unique.
- 14. Know how to prove that a vector is in the *range* of a linear transformation by setting up a linear system and proving that it is consistent.
- 15. Know how to find the *null space* of a linear transformation as the general solution to a linear system of the form Ax = 0 where A is the standard matrix of the linear transformation.
- 16. Know how to show that a linear transformation is *one-to-one*, *onto*, or *both* using its standard matrix.
- 17. Know what the factors are for each type of row operation.
- 18. Know how to find the determinant of a matrix A by using only row operations.
- 19. Know how to compute a 2×2 determinant.
- 20. Know how to compute a 3×3 determinant using Sarrus's Rule.
- 21. Know what the determinants of the elementary matrices are.
- 22. Know that a matrix A is invertible $\Leftrightarrow \det(A) \neq 0$.
- 23. Know that det(AB) = det(A) det(B).
- 24. Know that $\det(A^{-1}) = 1/\det(A)$.
- 25. Know that $det(A^T) = det(A)$.
- 26. Know how to compute the determinant of a matrix by expansion by cofactors.
- 27. Know how to compute the adjoint, Adj(A), of a matrix A.
- 28. Know that if A is invertible, then $A^{-1} = 1/\det(A) \cdot Adj(A)$.
- 29. Know how verify that a given set V equipped with operations \oplus and \odot satisfies the vector space axioms.
- 30. Know how to do computations in and generally be able to work with the vector spaces given in class: \mathbb{R}^n , $\mathcal{M}_{m\times n}$, \mathbb{P} , \mathbb{P}_n , \mathbb{R}^+ (with $x\oplus y=xy$ and $\alpha\oplus x=x^{\alpha}$), \mathbb{R} (with $x\oplus y=x-y-b$ and $\alpha\oplus x=\alpha(x-b)+b$).
- 31. Know how do a simple proof using only the vector space axioms.
- 32. Know how to show that a given subset S of V is a subspace (or not) of a vector space V by checking closure of addition and scalar multiplication.
- 33. Know how to show that a given vector is in the span of vectors $\{v_1, v_2, ..., v_k\}$.
- 34. Know how to show that a set of vectors $\{v_1, v_2, ..., v_k\}$ is linearly independent.
- 35. Know how to show that a set of vectors $\{v_1, v_2, ..., v_k\}$ is linearly dependent.
- 36. Know an example of an infinite-dimensional vector space.
- 37. Know examples of bases for $\mathcal{M}_{m\times n}$, \mathbb{P}_n , and \mathbb{P} .
- 38. Know how to find the coordinates of a vector with respect to a given basis in \mathbb{R}^n , $\mathcal{M}_{m \times n}$, \mathbb{P}_n , and \mathbb{P} .
- 39. Know how to change the coordinates of a vector from one basis to another by solving equations.
- 40. Know how to change the coordinates of a vector from one basis to another by using transition matrices.
- 41. Know how to find the transition matrix $P_{B\to B'}$, and find the transition matrix $P_{B'\to B}$ by the inverse method.

- 42. Know how to find all the eigenvalues of a linear transformation $T = T_A$ where A is the standard matrix of T.
- 43. Know how to find a basis for the eigenspace E_{λ} of an eigenvalue λ .
- 44. Know how to diagonalize a matrix A by finding matrices P and P^{-1} such that $P^{-1}AP = D$ where D is a diagonal matrix.
- 45. Know how to solve a system of first-order, linear differential equations by diagonalization.
- 46. Know how to find bases for Row(A), Col(A), and Null(A), and $Null(A^T)$.
- 47. Know what the Dimension Theorem is.
- 48. Know how to find the standard matrix of the inverse of a one-to-one linear transformation.