Project Status Report Template

Project Name: Pick and Place

Team Name: JFL

Project Manager: Robin Pottathuparambil

Team Members: Jailine Contreras Marquez, Fernando Zavala-Ortiz, Lap Nguyen

Report Date: 09/14/2023

Reporting Period: 8/21/2023 to 9/14/2023

Management Summary

Defined milestones completed: 1 of 7 (14%)

Defined tasks completed: 0 of 14 (0%) of child tasks in work breakdown structure

Total estimated project hours used:
Ahead of (or Behind) schedule by:

Known defects:

Staff members on project

Contingency hours remaining:

30 of 960 (.03%)

10 labor-hours, 0 days

0 open of 0 found

0 of 0 planned

100% of 30 hours

Schedule

Initial estimated completion date: May 10th 2024
Previous estimated completion date: May 10th 2024
Current estimated completion date: May 10th 2024

Key Milestones Table

| ID | Title | Planned Completion Date | Previous Forecast Completion Date | Current Forecast Completion Date | Actual Completion Date |
|----|--------------------------|-------------------------------|--|---|------------------------------|
| 1 | requirements draft | 9/12/23 | 9/14/23 | 9/14/23 | 9/14/23 |
| | due/status report | | | | |
| 2 | specification draft due/ | 9/20/23 | 9/22/23 | 9/22/23 | 9/22/23 |
| | requirements due | | | | |
| 3 | specifications due | 9/27/23 | 9/29/23 | 9/29/23 | 9/29/23 |
| 4 | preliminary design due | 10/04/23 | 10/06/23 | 10/06/23 | 10/06/23 |
| 5 | parts order due | 10/11/23 | 10/13/23 | 10/13/23 | 10/13/23 |
| 6 | detailed design due | 10/18/23 | 10/20/23 | 10/20/23 | 10/20/23 |
| 7 | status report | 11/8/23 | 11/10/23 | 11/10/3 | 11/10/23 |

Product Size

Not applicable

Effort

One of the discrepancies is having access to the previous team documents.

| Life Cyale Activity | This Reporting Per | riod (labor-hours) | Project to Date (labor-hours) | | |
|--------------------------|--------------------|--------------------|-------------------------------|----------------------|--|
| Life Cycle Activity | Planned Effort | Actual Effort | Planned Effort | Actual Effort | |
| researching/requirements | 40 | 24 | 40 | 24 | |
| | | | | | |

Cost

Cost will be calculated as parts are picked.

| Life Coole Astinita | This Report | ting Period | Project to Date | | |
|---------------------|--------------|--------------------|---------------------|--------------------|--|
| Life Cycle Activity | Planned Cost | Actual Cost | Planned Cost | Actual Cost | |
| mini PC | N/A | N/A | N/A | N/A | |
| Camera | N/A | N/A | N/A | N/A | |
| Air Compressor | N/A | N/A | N/A | N/A | |

Requirements Status

| ID | Functional Requirements | Team Member Responsible | Effo rt (%) | Verification | Completed (%) |
|-----|---|---------------------------------|-------------------|-------------------|---------------|
| FR1 | A software model will use camera to identify PCB fiducial | Fernando Zavala | 45% | Test | 0 |
| FR2 | A fiducial will be created and used to identify location of PCB | Fernando Zavala | 30% | Demonstrati on | 0 |
| FR3 | Training images will be created for PCB fiducial | Fernando Zavala | 20% | Inspection | 0 |
| FR4 | Web framework use to communicate with the device | Jailine Contreras Marquez | 30 | demonstrati on | 0 |
| FR5 | Software should send a signal from the mini-PC when it keep or drop the PCB | Jailine Contreras Marquez | 30 | demonstrati on | 0 |
| FR6 | The bessel camera connect with the system by Ethernet | Jailine Contreras Marquez | 10 | demonstrati on | 0 |
| FR7 | Software should control the arm to move stability | Lap Nguyen | 40 | demonstrati on | 0 |

| FR8 | Software should control the system to pick up the PCB in location | Lap Nguyen | 20 | inspection | 0 |
|-----|---|------------|----|------------|---|
| FR9 | Software should control the system to drop the PCB in designated location for test tray | Lap Nguyen | 20 | inspection | 0 |

| ID | Non-Functional Requirements | Team Member Responsible | Effort (%) | Verificatio n | Completed (%) |
|------|---|------------------------------|------------|-------------------|---------------|
| NFR1 | The system speed for moving the PCB should be 10mm/s | Lap Nguyen | 20 | test | 0 |
| NFR2 | The system have the front end for user to remotely control | Jailine Contreras Marquez | 20 | demonstra tion | 0 |
| NFR3 | The system must accommodate PCBs 300 mm wide by 500 mm long. | none | 0 | inspection | 0 |
| NFR4 | The PCB lifting mechanism should be capable of lifting up to 2 kg | Fernando Zavala | 5% | Inspection | 0 |
| NFR5 | Replace FPGA with mini-PC | Jailine Contreras Maruqez | 10 | test | 0 |

Top Five Risks

- 1. System might have an error from last time it was used
- 2. Getting a defective mini PC
- 3. Software could work in surplus PC but might have to be changed on mini PC

Open Issues

- Having access to the previous team to demonstrate how the system works
- Time constraints on team members

Action Items

Not applicable

Defects

Not applicable