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Year: 1980

Name: The Solution of Linear Difference Models under Rational Expectations

Journal: Econometrica , Jul., 1980, Vol. 48, No. 5 (Jul., 1980), pp. 1305-1311

Fernández-Villaverde, Rubio-Ramírez, Schorfheide (2016) Handbook of Macroeconomics



The Model

The model is given by

The structural model.

$$\begin{bmatrix} X_{t+1} \\ P_{t+1}^{(t)} \end{bmatrix} = A \begin{bmatrix} X_t \\ P_t \end{bmatrix} + \gamma Z_t \quad (1.a)$$

- X_t : is an $n \times 1$ vector of variables predetermined at t
- P_t : is an $m \times 1$ vector of variables non-predetermined at t
- Z_t : is an $m \times 1$ vector of exogenous variables at t

Linear Rational Expectation

$$P_{t+1}^{(t)} = \mathbb{E}_t P_{t+1} | \Omega_t \quad (1.b)$$

- Ω_t : the information set at time t

$$\forall t, \exists \bar{Z}_t \in \mathbb{R}^k, \theta \in \mathbb{R}$$

such that

$$-(1+i)^{\theta_t} \bar{Z}_t \leq E(Z_{t+1} | \Omega_t) \leq (1+i)^{\theta_t} \bar{Z}_t \quad (1.c)$$

➤ Predetermined or backward looking variables

- Functions only of variables known at time t , that is of variables in Ω_t . i.e.,

$$X_{t+1} = \mathbb{E}_t X_{t+1} | \Omega_t \quad \text{or} \quad X_{t+1} = f(X_t) + \epsilon$$

- Forward iteration:

$$X_{t+1} = f^{(t)} \circ X_0 + \sum_{i=1}^t f^{(i)} \circ \epsilon_{t-i}$$

➤ Forward looking variables | Non-predetermined variables

- Variables following such formula

$$\mathbb{E}_t P_{t+1} = g(P_t) + \epsilon_t$$

- Forward iteration:

$$P_t = (g^{-1})^{(n)} \circ \mathbb{E}_t P_{t+n} - \sum_{i=0}^{n-1} (g^{-1})^{(i+1)} \circ \mathbb{E}_t \epsilon_{t+i}$$

Solution

BK Condition

Perspective of Jordan Canonical Form

🔥 Simplify the notations:

$$Y_{t+1} = AY_t + \gamma Z_t$$

⇓

🔥 The **Jordan Decomposition**:

$$A = C^{-1}JC$$

⇓

🔥 Ordering by magnitudes of eigenvalues

$$J = \begin{bmatrix} J_{1(\tilde{n} \times \tilde{n})} & 0 \\ 0 & J_{2(\tilde{m} \times \tilde{m})} \end{bmatrix} \quad C = \begin{bmatrix} C_{11(\tilde{n} \times n)} & C_{12(\tilde{n} \times m)} \\ C_{21(\tilde{m} \times n)} & C_{22(\tilde{m} \times m)} \end{bmatrix}$$

$$C^{-1} = \begin{bmatrix} B_{11(n \times \tilde{n})} & B_{12(m \times \tilde{m})} \\ B_{21(n \times \tilde{m})} & B_{22(m \times \tilde{m})} \end{bmatrix} \quad \gamma = \begin{bmatrix} \gamma_{1(\tilde{n} \times k)} \\ \gamma_{2(\tilde{m} \times k)} \end{bmatrix}$$

J_1 : all eigenvalues are on or inside the unit circle

J_2 : all eigenvalues are outside the unit circle



Blanchard-Kahn Condition:

- 📍 if the number of eigenvalues of A outside the unit circle is equal to the number of non-predetermined variables $\tilde{m} = m$, then there exists a **unique solution**

$$\begin{bmatrix} X_{t+1} \\ P_{t+1}^{(t)} \end{bmatrix} = \begin{bmatrix} B_{11}(n \times \tilde{n}) & B_{12}(m \times \tilde{m}) \\ B_{21}(n \times \tilde{m}) & B_{22}(m \times \tilde{m}) \end{bmatrix} \begin{bmatrix} J_1(\tilde{n} \times \tilde{n}) & 0 \\ 0 & J_2(\tilde{m} \times \tilde{m}) \end{bmatrix} \begin{bmatrix} C_{11}(\tilde{n} \times n) & C_{12}(\tilde{n} \times m) \\ C_{21}(\tilde{m} \times n) & C_{22}(\tilde{m} \times m) \end{bmatrix} \begin{bmatrix} X_t \\ P_t \end{bmatrix} + \begin{bmatrix} \gamma_1(\tilde{n} \times k) \\ \gamma_2(\tilde{m} \times k) \end{bmatrix} Z_t$$

\Downarrow

$$C \begin{bmatrix} X_{t+1} \\ P_{t+1}^{(t)} \end{bmatrix} = \begin{bmatrix} J_1(\tilde{n} \times \tilde{n}) & 0 \\ 0 & J_2(\tilde{m} \times \tilde{m}) \end{bmatrix} C \begin{bmatrix} X_t \\ P_t \end{bmatrix} + \begin{bmatrix} \gamma_1(\tilde{n} \times k) \\ \gamma_2(\tilde{m} \times k) \end{bmatrix} Z_t$$

\Downarrow

$$\begin{cases} \tilde{X}_{t+1} = J_1 \tilde{X}_t + \gamma_1 Z_t \\ \tilde{P}_{t+1} = J_2 \tilde{P}_t + \gamma_2 Z_t \end{cases}$$

- if the number of eigenvalues outside the unit circle exceeds the number of non-predetermined variables $\tilde{m} > m$, then there exists a **no solution**
- if the number of eigenvalues outside the unit circle is lower than the number of non-predetermined variables $\tilde{m} < m$, then there exists a **infinite solution**

Perspective of Schur Decomposition

See [Klein \(2000\)](#)