# Ai-Sensor project



#### **AGENDA**

Background

Proof of Concept (POC)

Prototype Model

Next Step

#### **Background: RVP**

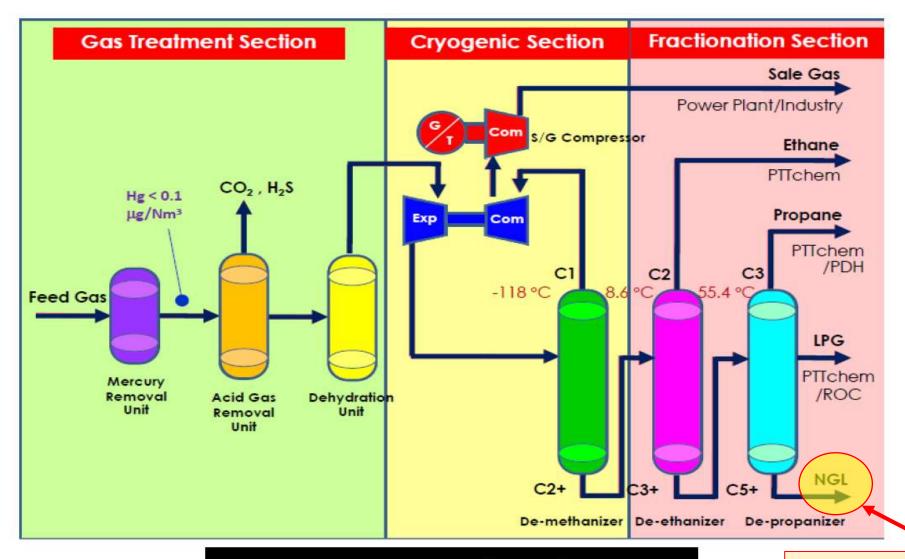


Fig. 1 ภาพรวม Process ของโรงแยกก๊าซธรรมชาติ

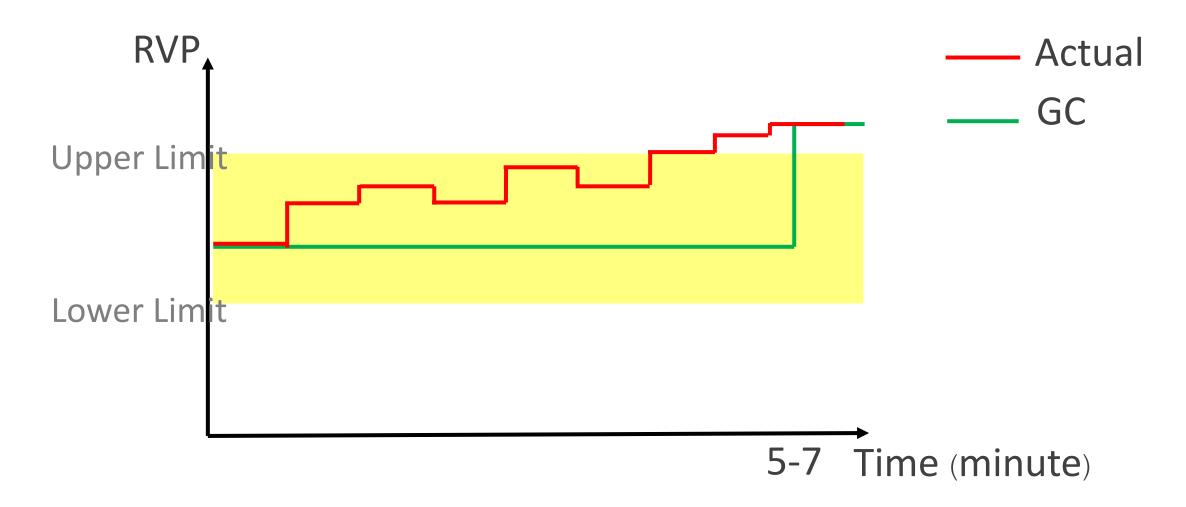
The spec. of NGL is control by RVP (Reid Vapor Pressure) spec.

#### **Background: On-Line RVP Analyzer**



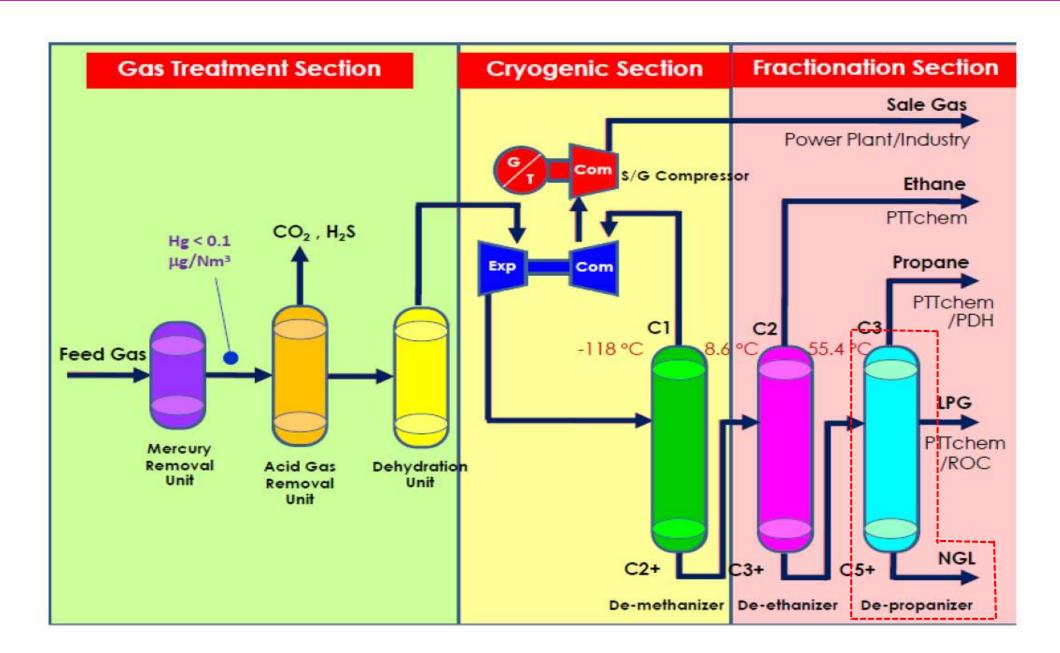
This device is used in the plant to online measure the RVP value for NGL. The interval of measurement is 5-7 minute/time.

#### **Background: Pain Point**

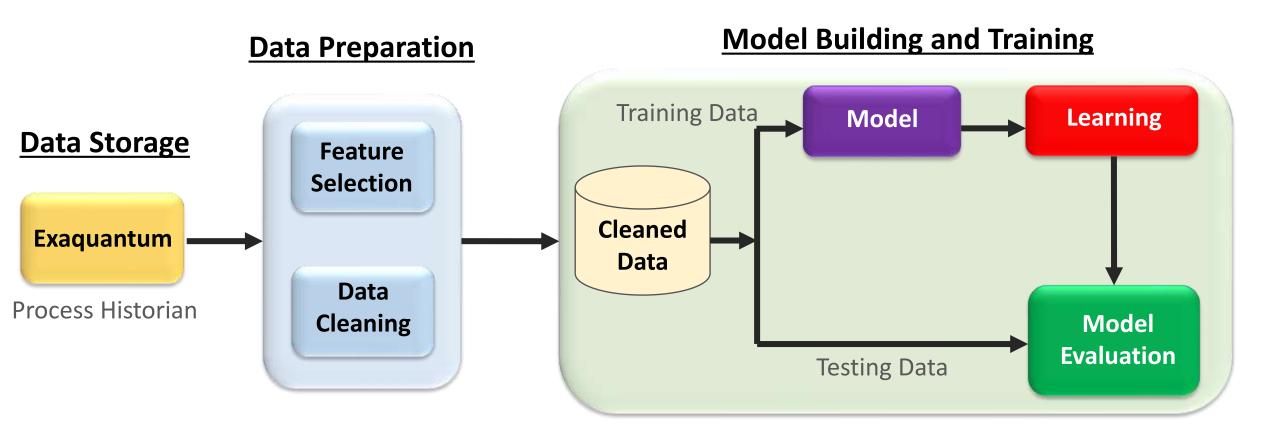


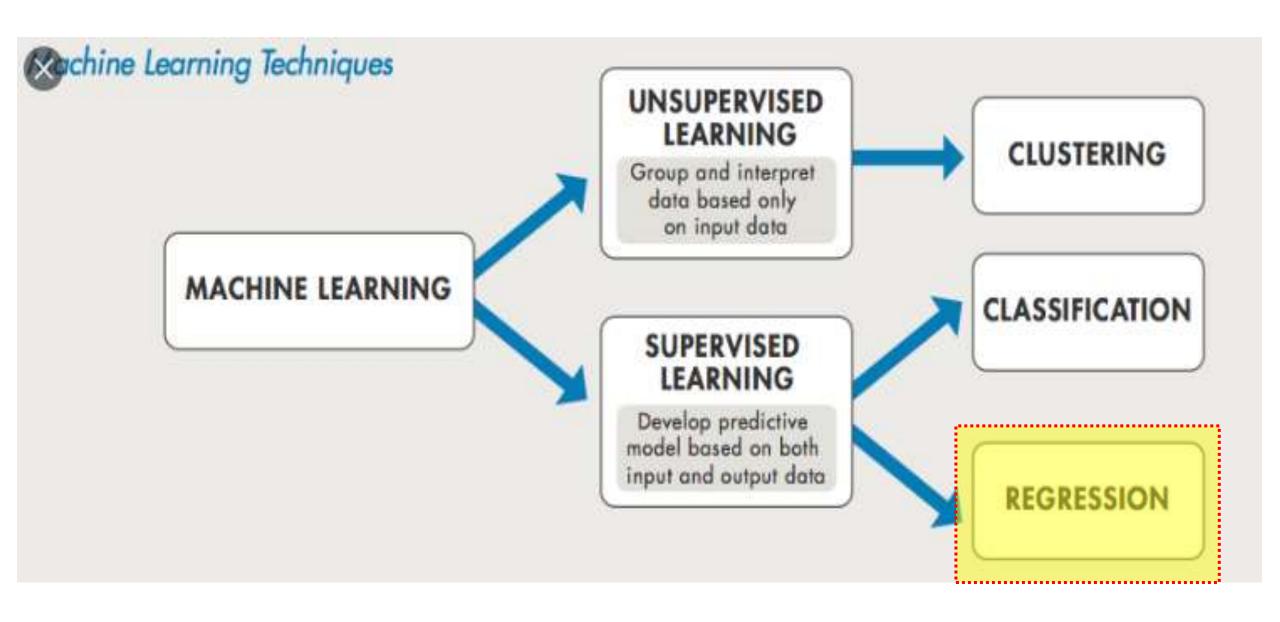
The wide interval time of measurement can lead to mis-operation issue.

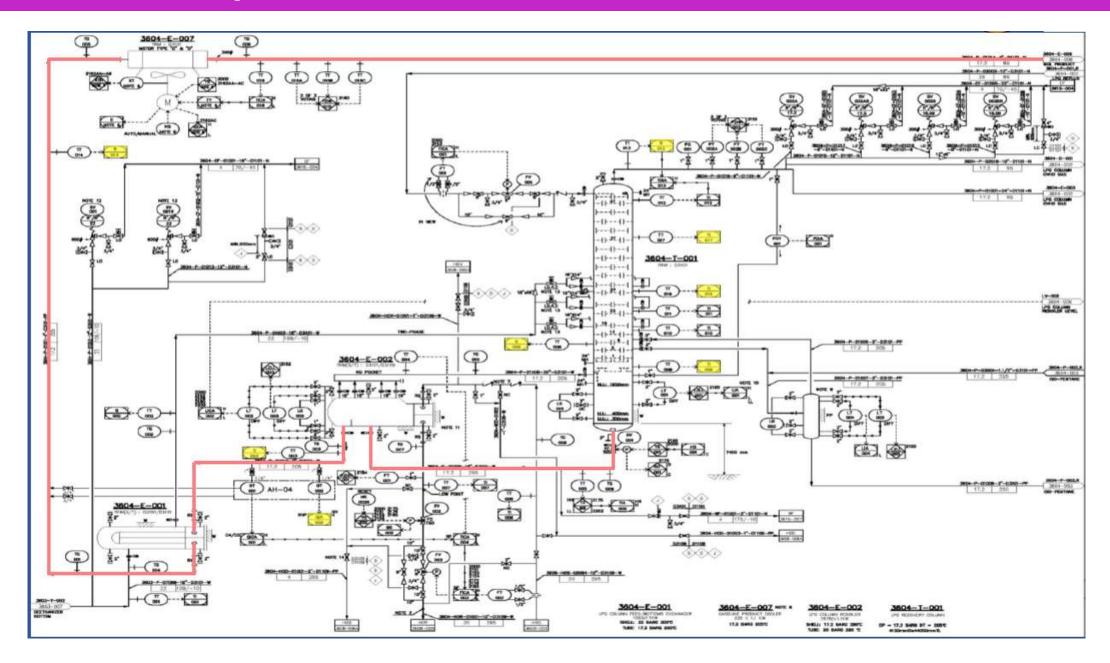
### Scope of Work

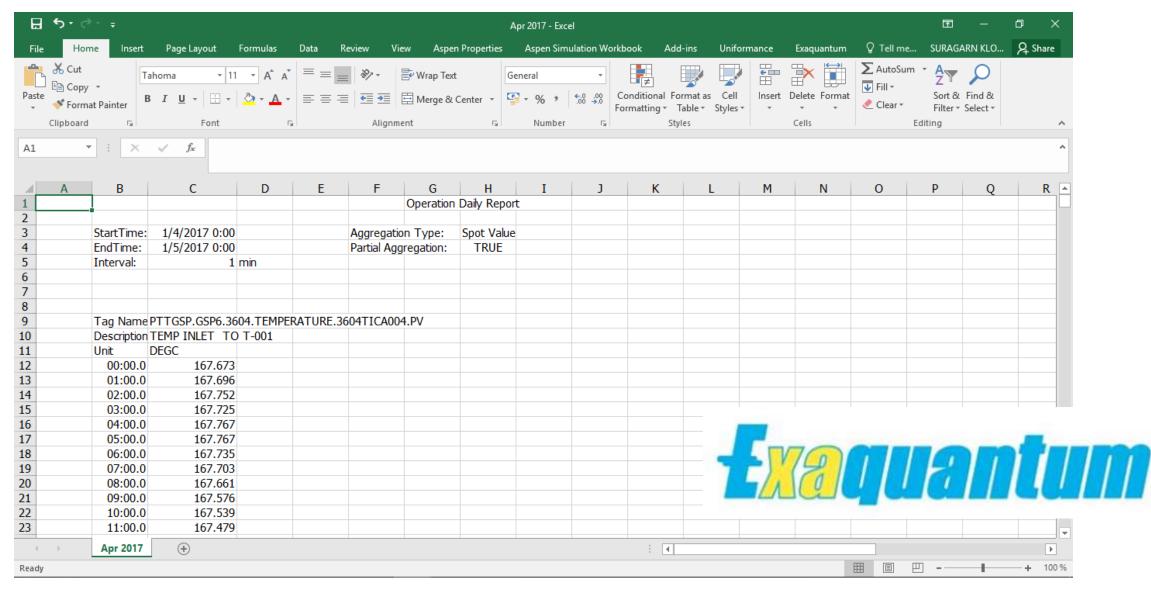


#### Concept

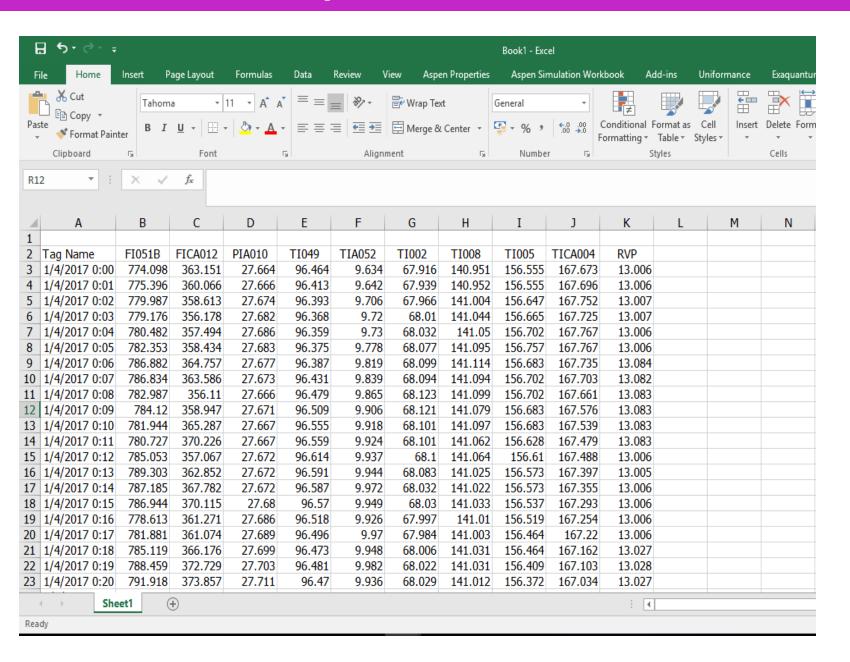






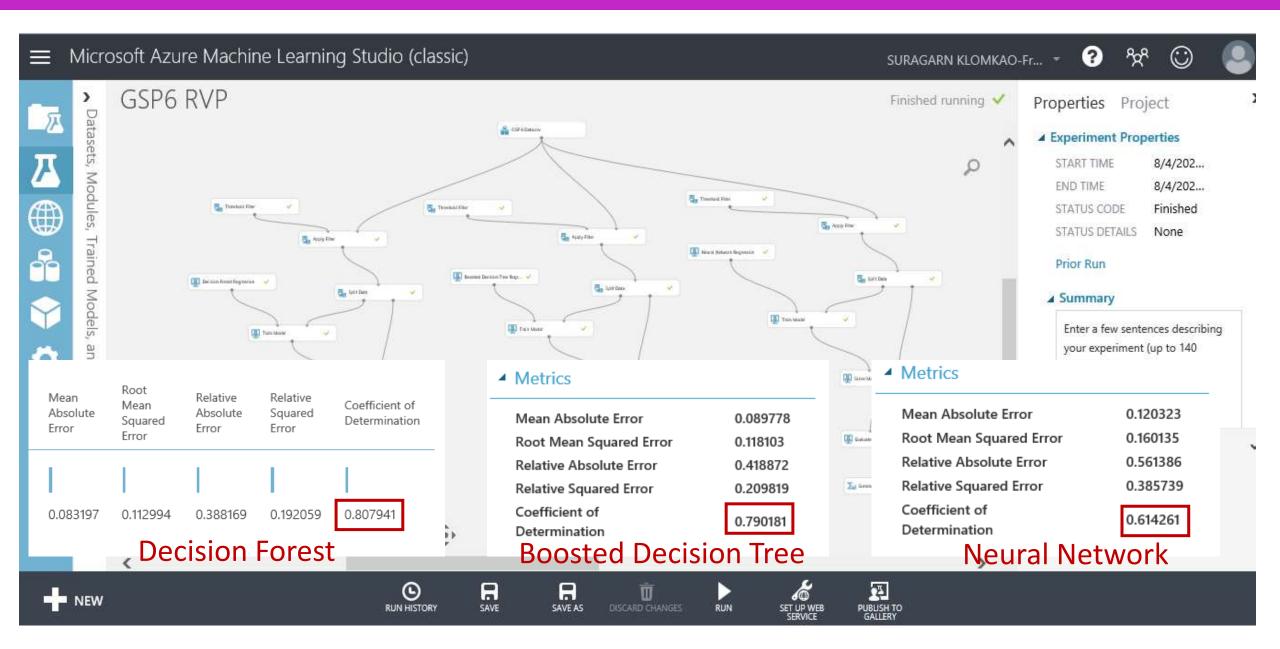


Data Extraction via Exaquantum: Each Tag per file &1 min Interval for 1 month as CSV

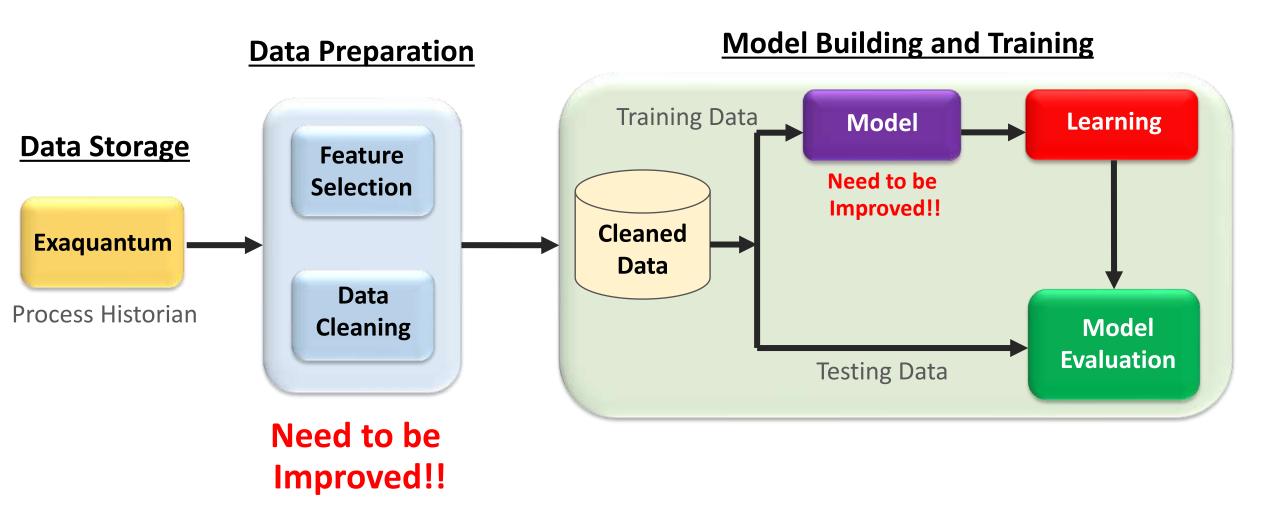


- **>9** Feature
- **▶1** Target
- >30 Days Period
- **→** 430,000 Cells of Data

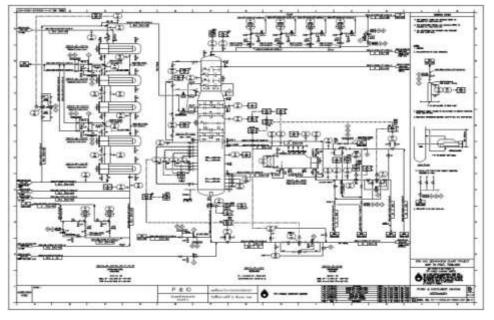


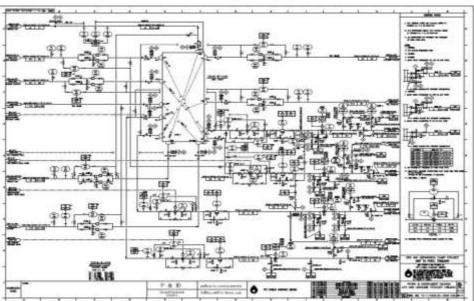


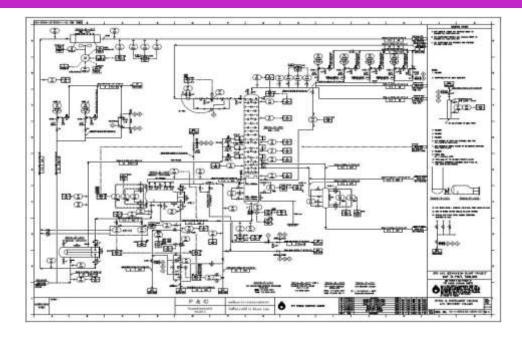
#### Concept



#### **Data Preparation: Feature Selection**

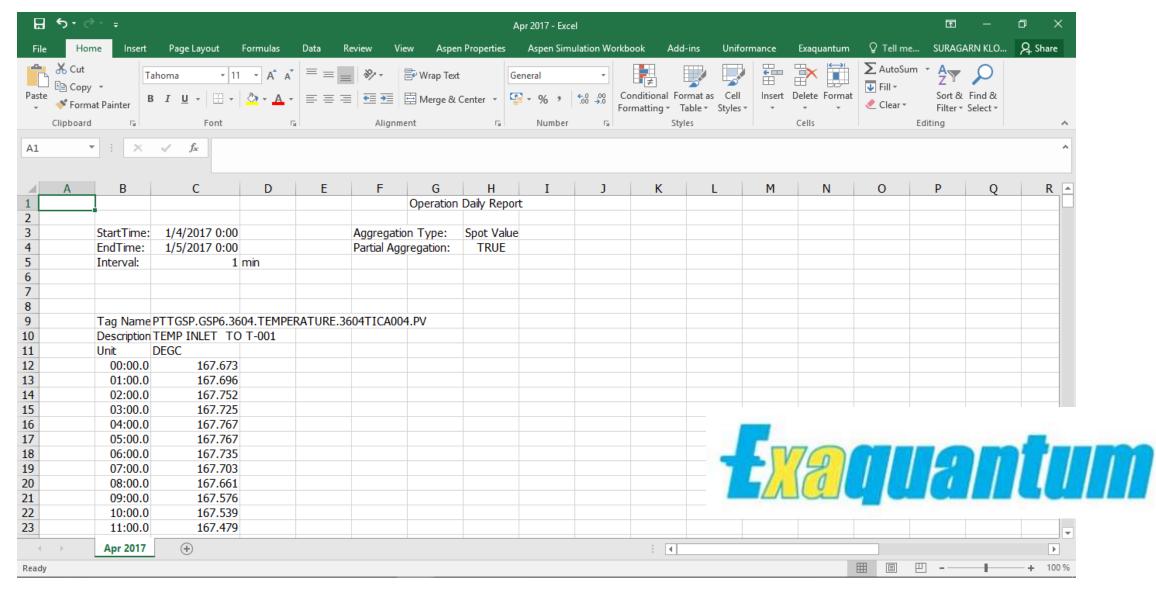






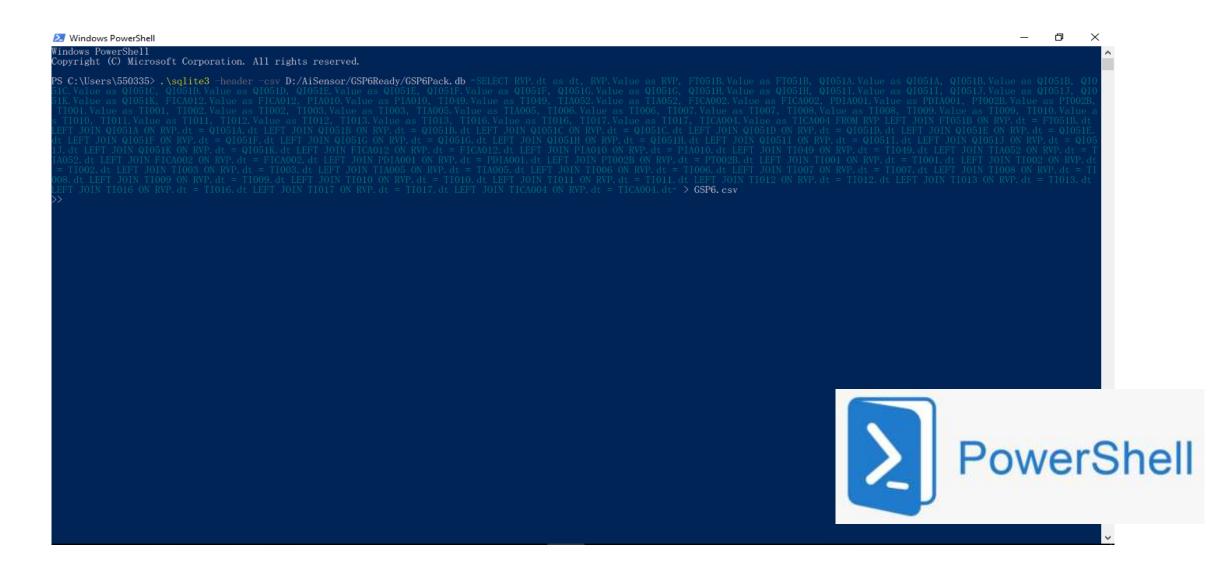
- Feed Inlet
- DeEthanizer Column
- LPG Recovery Column
- NGL Product to Storage

#### **Data Preparation: Pack Data**



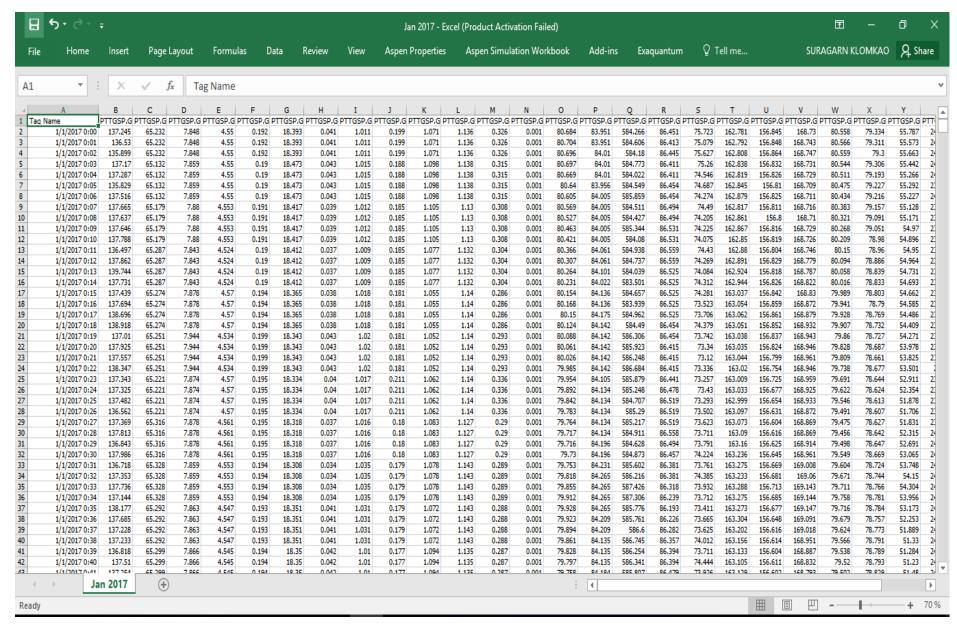
Data Extraction via Exaquantum: Each Tag per file &1 min Interval for 2.5 Years as CSV

#### **Data Preparation: Pack Data**



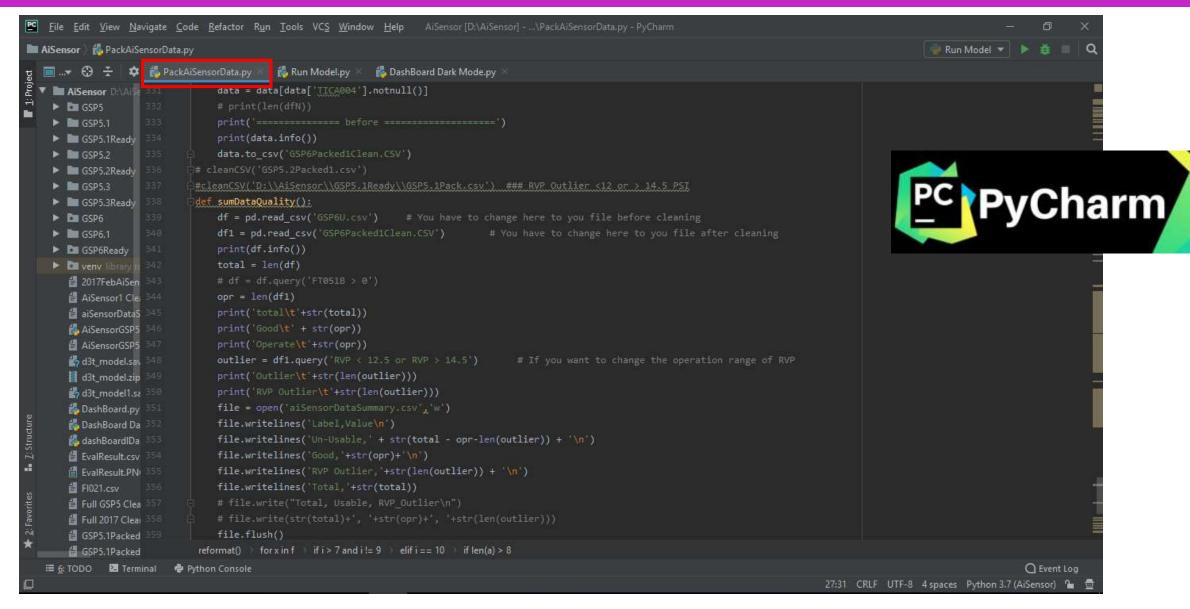
Pack Data to only 1 file and via PowerShell

#### **Data Preparation: Pack Data**



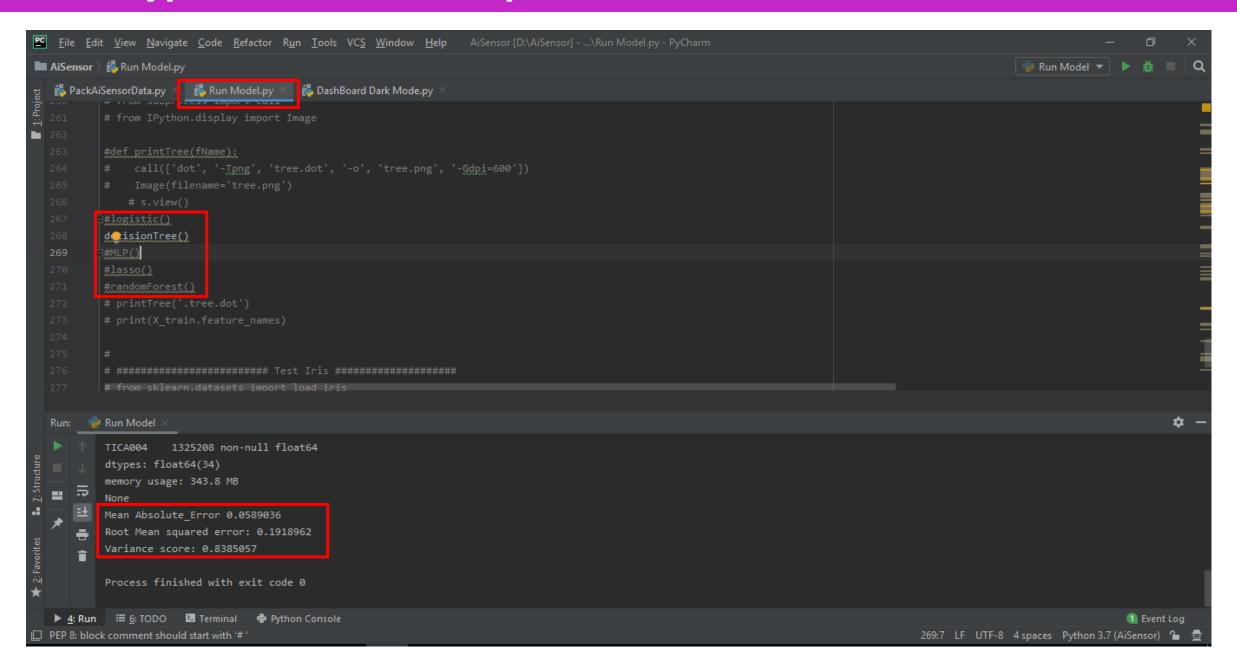
- > 36 Feature
- **▶** 1 Target
- > 30 Months Period
- > 50M Cells of Data

#### **Data Preparation: Data Cleaning**

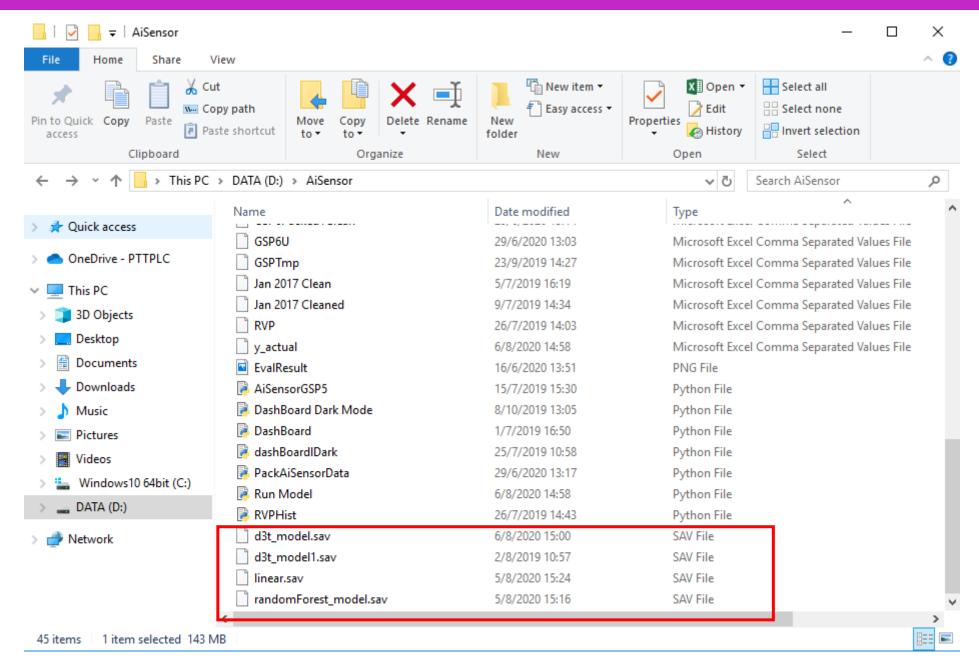


NULL & Zero Value & Outlier (RVP <12.5 or RVP >14.5 psi)

#### **Prototype Model Development**



#### **Prototype Model Development**



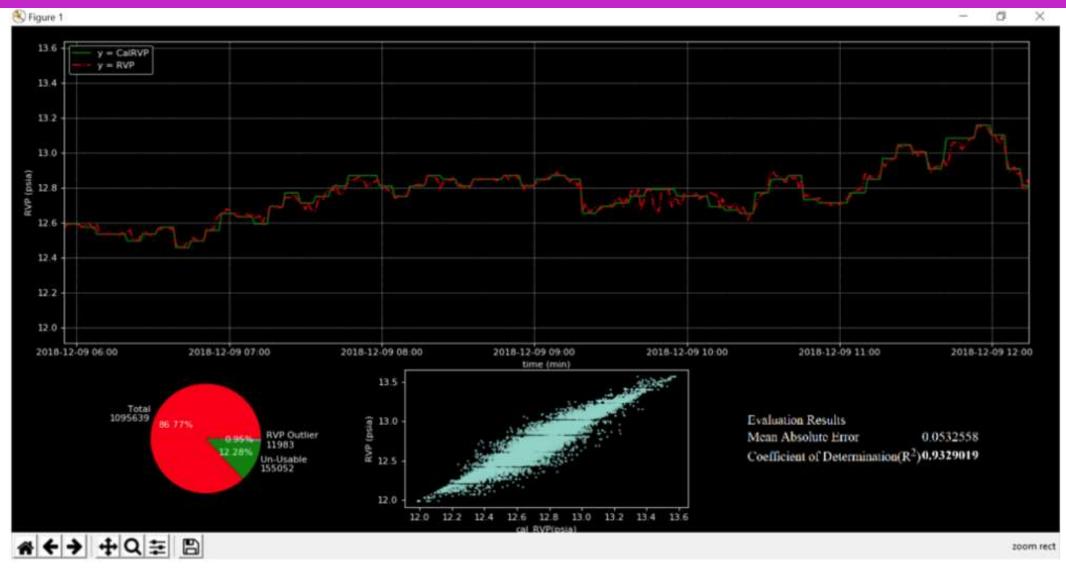
# **Prototype Model Results**

	Mean Absolute Error	Root Mean Square Error	R-Square
LASSO	0.244	0.445	0.13
<b>DECISION TREE</b>	0.058	0.191	0.84
RANDOM FOREST	0.058	0.137	0.92
MLP	_	-	<del>-</del>

#### **Prototype Model Visualization**

```
<u>File Edit View Navigate Code Refactor Run Tools VCS Window Help</u>
■ AiSensor 〉 🐍 DashBoard Dark Mode.py
                                                                                                                                                                      🧓 Run Model 🔻 🕨 🇯 🗏
                                            🐍 DashBoard Dark Mode.py
   PackAiSensorData.py X Run Model.py
            import pandas as pd
            import pickle5 as pickle
            import matplotlib.pyplot as plt
            from datetime import datetime
            import matplotlib.dates as mdates
            import matplotlib.image as mpimg
            import imgkit
            from sklearn.metrics import r2 score,mean absolute error
            fName = 'D:\\AiSensor\\2017FebAiSensorGSP5 1.csv'
           all_data = pd.read_csv(fName)
           X = all_data[cols]
           Y = all data['RVP']
           dt = all_data['dt']
           print(X.info())
            dates = [datetime.strptime(d, "%Y-%m-%d %H:%M:%S.000") for d in all data['dt']]
            load = pickle.load(file)
   🕨 4: Run 🔠 6: TODO 🔼 Terminal ಿ Python Console
                                                                                                                                                                                        Event Log
☐ IDE and Plugin Updates: PyCharm is ready to update. (27 minutes ago)
                                                                                                                                                   16:30 CRLF UTF-8 4 spaces Python 3.7 (AiSensor) 🦜
```

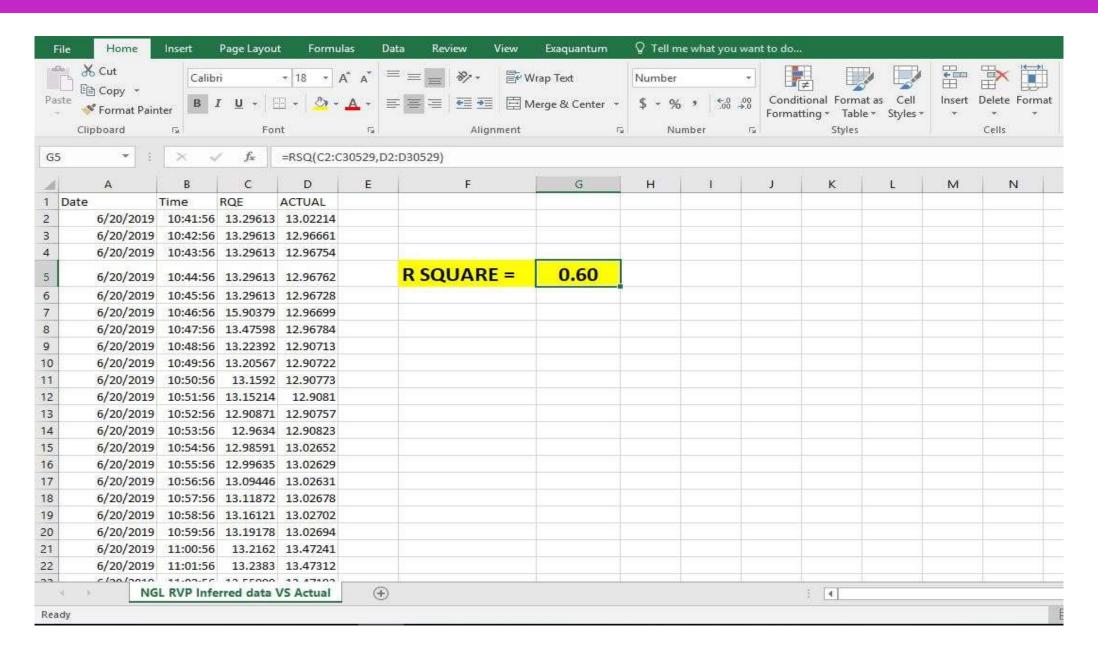
#### **Prototype Model Visualization**



**GSP#6 RVP Prediction Model: R2 = 0.92, Error = 0.05 psi** 

\*GSP#5 RVP Prediction Model: R2 = 0.93, Error = 0.05 psi

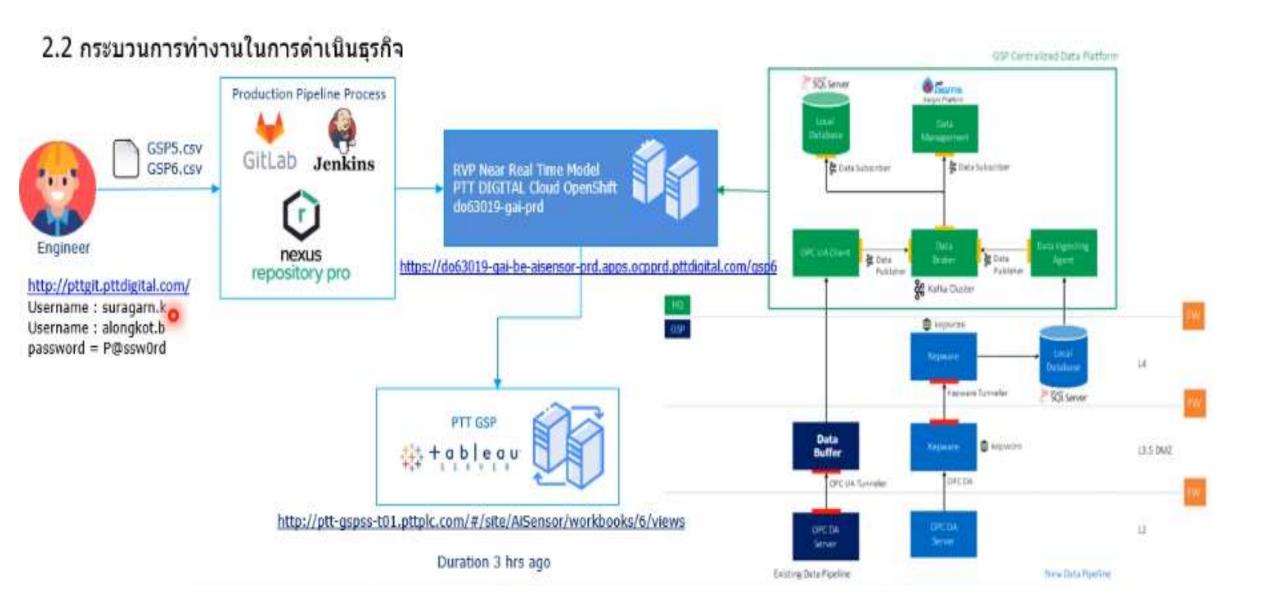
#### **RQE** Results



# Benchmarking

Method	<u>Interval</u>	<u>R-Square</u>
RVP On-Line	5-7 min	1
RQE	1 min	0.6++
Al Sensor <b>b</b>	1 min	0.9++

#### Next Step (Currently on work)



#### **Next Step**

> Energy Index Prediction

>WI prediction

>Other Prediction Model

#### What I have Learned

Data Preparation is the Key "Garbage-In Garbage Out"

> Simple is the Best

> Al is not everything

# Q&A