

**Lecture 2:**

# **A Modern Multi-Core Processor**

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**Parallel Computing  
Stanford CS149, Fall 2023**

# **Review from class 1:**

# **What is a computer program?**

# A program is a list of processor instructions!

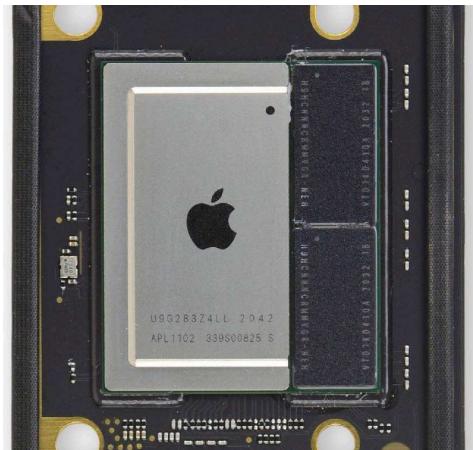
```
int main(int argc, char** argv) {  
  
    int x = 1;  
  
    for (int i=0; i<10; i++) {  
        x = x + x;  
    }  
  
    printf("%d\n", x);  
  
    return 0;  
}
```



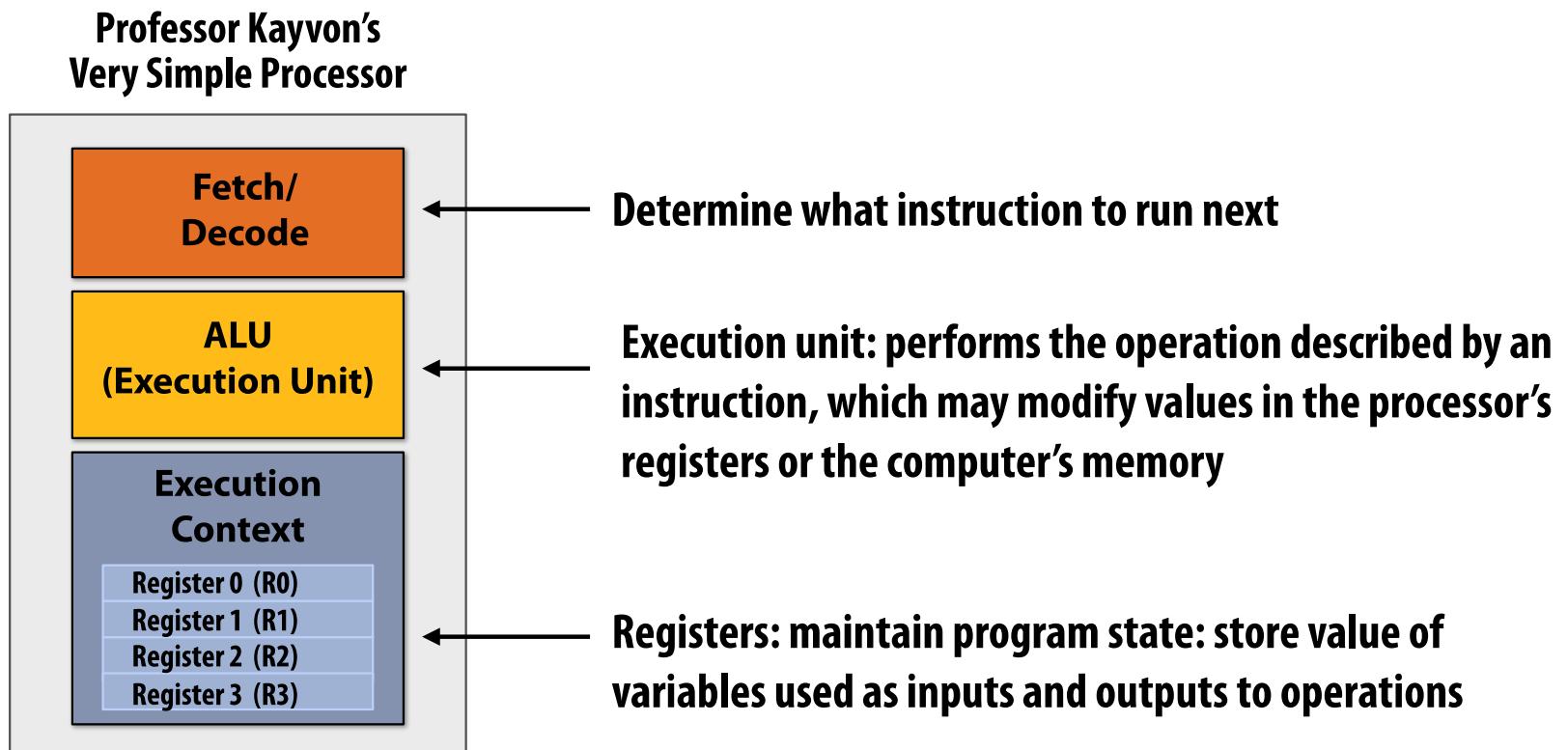
```
_main:  
100000f10: pushq   %rbp  
100000f11: movq %rsp, %rbp  
100000f14: subq $32, %rsp  
100000f18: movl $0, -4(%rbp)  
100000f1f: movl %edi, -8(%rbp)  
100000f22: movq %rsi, -16(%rbp)  
100000f26: movl $1, -20(%rbp)  
100000f2d: movl $0, -24(%rbp)  
100000f34: cmpl $10, -24(%rbp)  
100000f38: jge 23 <_main+0x45>  
100000f3e: movl -20(%rbp), %eax  
100000f41: addl -20(%rbp), %eax  
100000f44: movl %eax, -20(%rbp)  
100000f47: movl -24(%rbp), %eax  
100000f4a: addl $1, %eax  
100000f4d: movl %eax, -24(%rbp)  
100000f50: jmp -33 <_main+0x24>  
100000f55: leaq 58(%rip), %rdi  
100000f5c: movl -20(%rbp), %esi  
100000f5f: movb $0, %al  
100000f61: callq 14  
100000f66: xorl %esi, %esi  
100000f68: movl %eax, -28(%rbp)  
100000f6b: movl %esi, %eax  
100000f6d: addq $32, %rsp  
100000f71: popq %rbp  
100000f72: rets
```

# Review from class 1:

# What does a processor do?

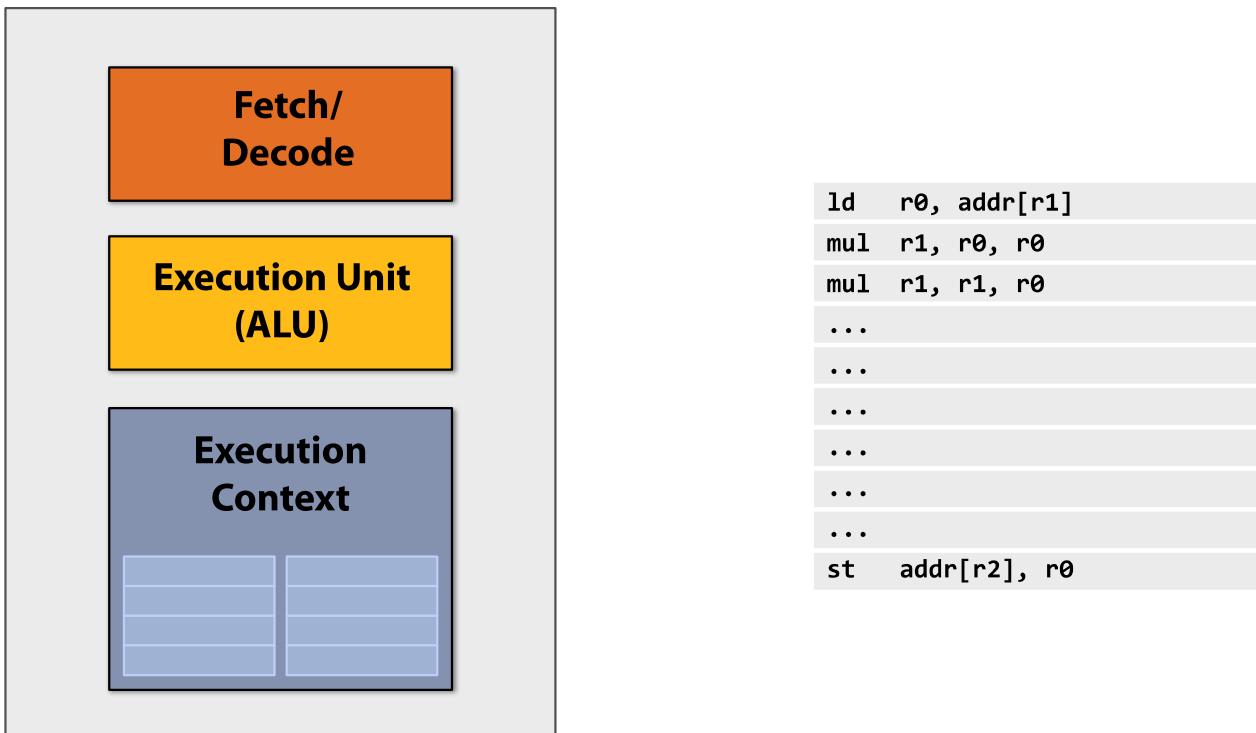


# A processor executes instructions



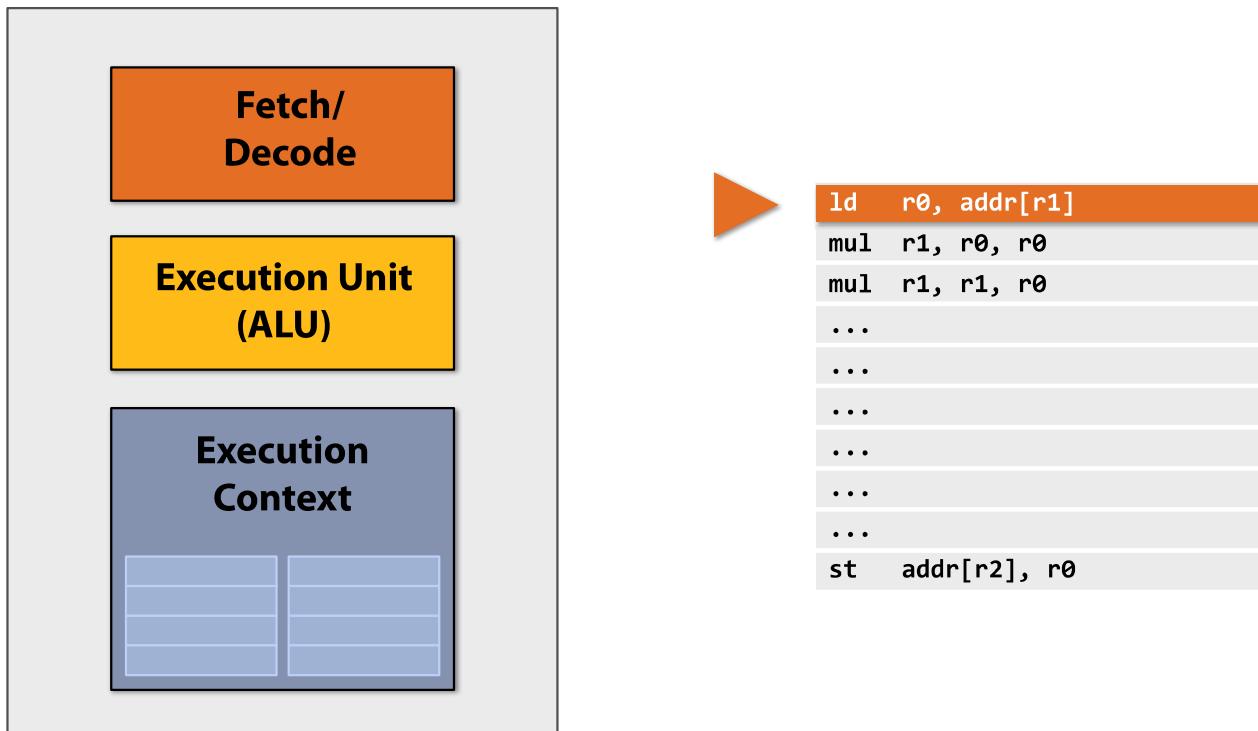
# Execute program

My very simple processor: executes one instruction per clock



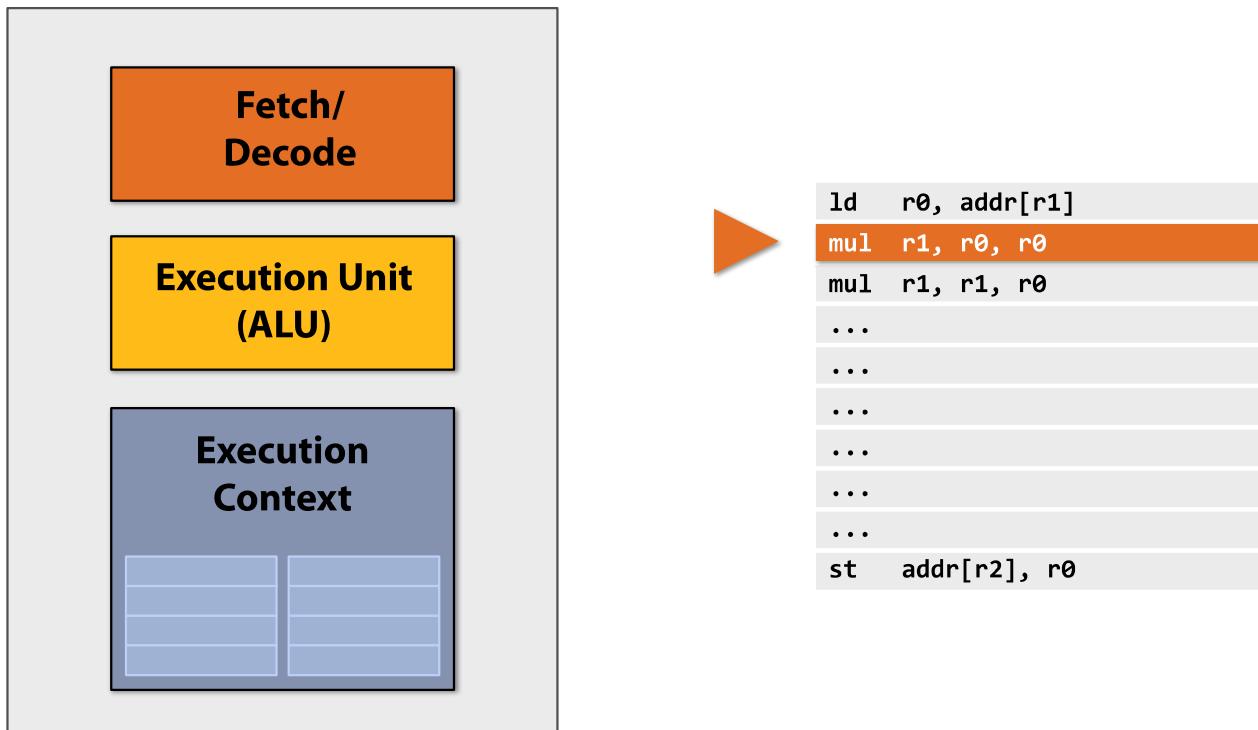
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My very simple processor: executes one instruction per clock



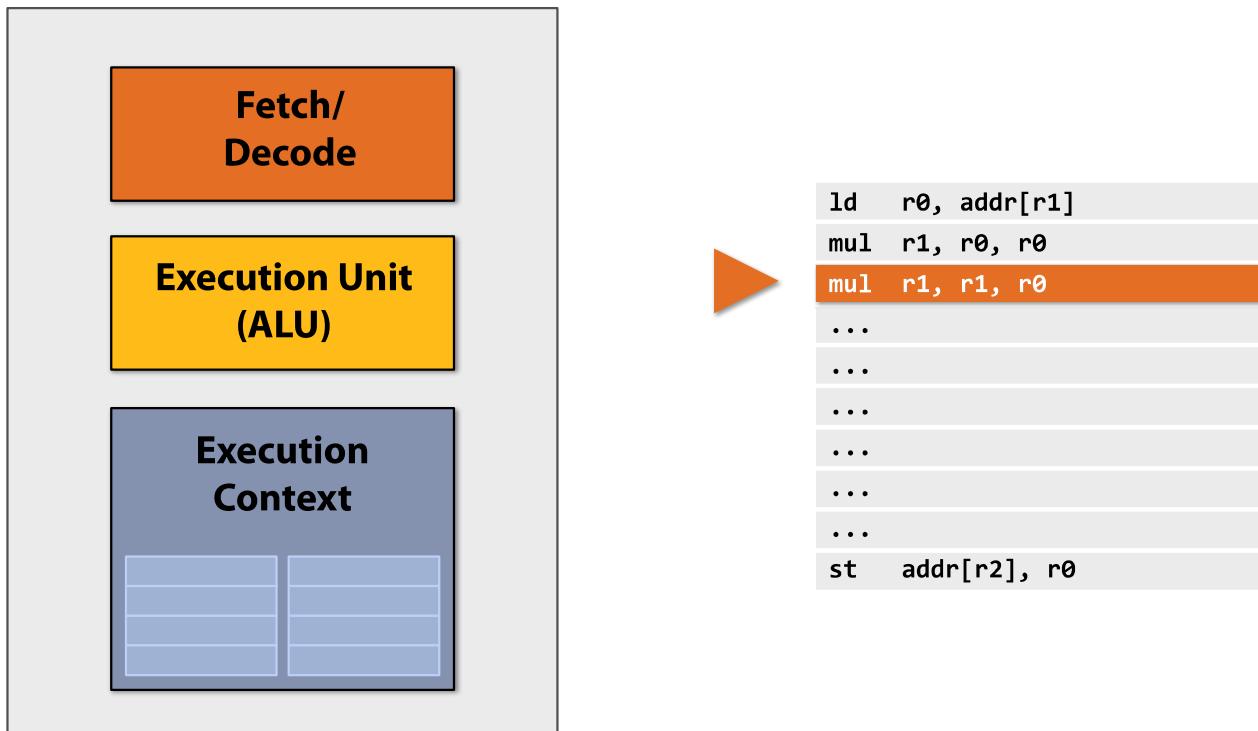
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My very simple processor: executes one instruction per clock



# Execute program

My very simple processor: executes one instruction per clock



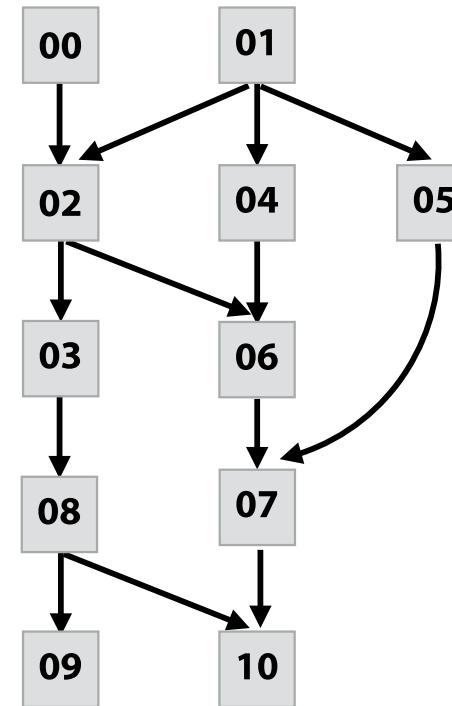
# A program with instruction level parallelism

Program (sequence of instructions)

PC	Instruction	
00	a = 2	
01	b = 4	
02	tmp2 = a + b // 6	
03	tmp3 = tmp2 + a // 8	
04	tmp4 = b + b // 8	
05	tmp5 = b * b // 16	
06	tmp6 = tmp2 + tmp4 // 14	
07	tmp7 = tmp5 + tmp6 // 30	
08	if (tmp3 > 7)	
09	print tmp3	
10	else	
	print tmp7	

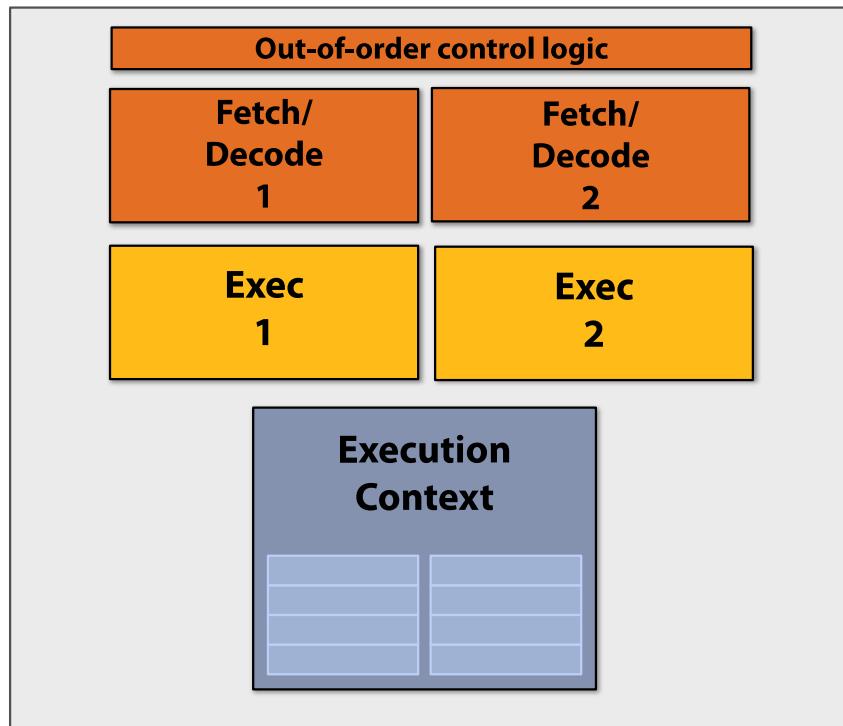
*value during  
execution*

Instruction dependency graph



# Superscalar processor

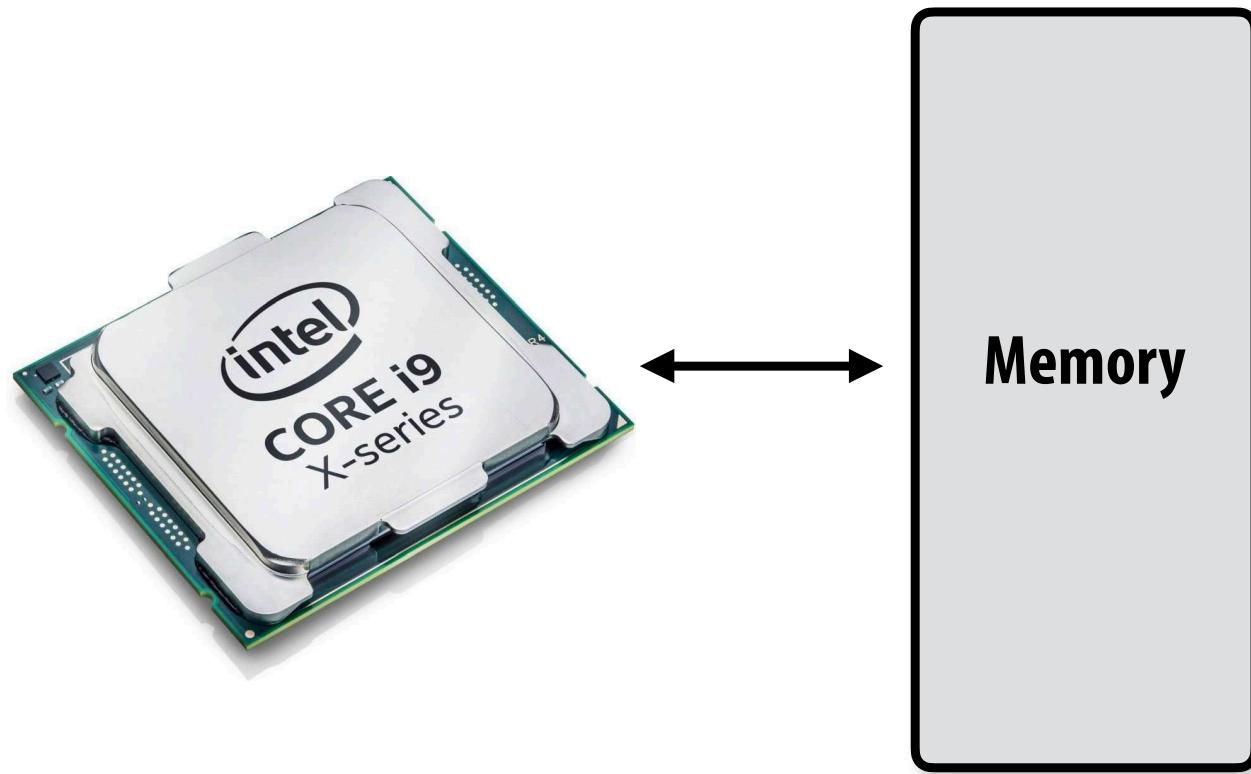
This processor can decode and execute up to two instructions per clock



**Superscalar execution:** processor automatically finds independent instructions in an instruction sequence and can execute them in parallel on multiple execution units.

What does it mean for a superscalar processor to “respect program order”?

# Review from class 1: What is memory?



# A program's memory address space

- A computer's memory is organized as an array of bytes
- Each byte is identified by its "address" in memory  
(its position in this array)  
(We'll assume memory is byte-addressable)

*"The byte stored at address 0x8 has the value 32."*

*"The byte stored at address 0x10 (16) has the value 128."*

In the illustration on the right, the program's  
memory address space is 32 bytes in size  
(so valid addresses range from 0x0 to 0x1F)

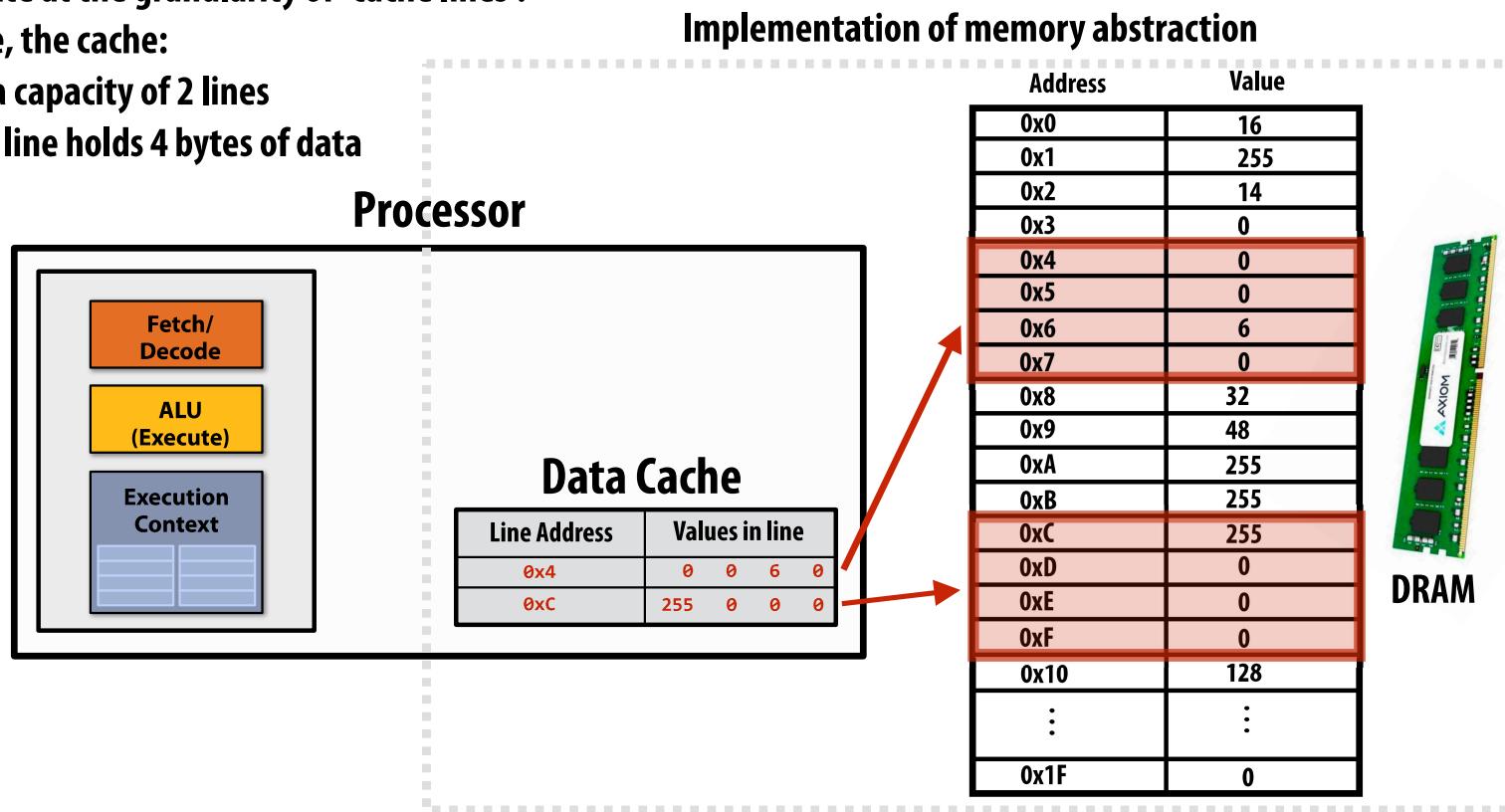
Address	Value
0x0	16
0x1	255
0x2	14
0x3	0
0x4	0
0x5	0
0x6	6
0x7	0
0x8	32
0x9	48
0xA	255
0xB	255
0xC	255
0xD	0
0xE	0
0xF	0
0x10	128
⋮	⋮
0x1F	0

# What are caches?

- A cache is a hardware implementation detail that does not impact the output of a program, only its performance
- Cache is on-chip storage that maintains a copy of a subset of the values in memory
- If an address is stored “in the cache” the processor can load/store to this address more quickly than if the data resides only in DRAM
- Caches operate at the granularity of “cache lines”.

In the figure, the cache:

- Has a capacity of 2 lines
- Each line holds 4 bytes of data



# Cache example 1

Array of 16 bytes in memory

Address	Value
0x0	16
0x1	255
0x2	14
0x3	0
Line 0x0	0x4
	0
	0
	6
Line 0x4	0x7
	0
	32
	48
Line 0x8	0xA
	255
	255
	255
Line 0xC	0xC
	0
	0
	0

Assume:

Total cache capacity of 8 bytes

Cache with 4-byte cache lines  
(So 2 lines fit in cache)

Least recently used (LRU)  
replacement policy

time

Address accessed	Cache action	Cache state (after load is complete)
0x0	"cold miss", load 0x0	0x0 . . . .
0x1	hit	0x0 . . . .
0x2	hit	0x0 . . . .
0x3	hit	0x0 . . . .
0x2	hit	0x0 . . . .
0x1	hit	0x0 . . . .
0x4	"cold miss", load 0x4	0x0 . . . . 0x4 . . . .
0x1	hit	0x0 . . . . 0x4 . . . .

There are two forms of "data locality" in this sequence:

Spatial locality: loading data in a cache line "preloads" the data needed for subsequent accesses to different addresses in the same line, leading to cache hits

Temporal locality: repeated accesses to the same address result in hits.

# Cache example 2

Array of 16 bytes in memory

Address	Value
0x0	16
0x1	255
0x2	14
0x3	0
Line 0x0	0x4
	0
	0
	6
Line 0x4	0x7
	0
	32
	48
Line 0x8	0xA
	255
	255
	0xC
Line 0xC	255
	0
	0
	0

Assume:

Total cache capacity of 8 bytes

Cache with 4-byte cache lines  
(So 2 lines fit in cache)

Least recently used (LRU)  
replacement policy

time

Address accessed	Cache action	Cache state (after load is complete)
0x0	"cold miss", load 0x0	0x0 . . . .
0x1	hit	0x0 . . . .
0x2	hit	0x0 . . . .
0x3	hit	0x0 . . . .
0x4	"cold miss", load 0x4	0x0 . . . . 0x4 . . . .
0x5	hit	0x0 . . . . 0x4 . . . .
0x6	hit	0x0 . . . . 0x4 . . . .
0x7	hit	0x0 . . . . 0x4 . . . .
0x8	"cold miss", load 0x8 (evict 0x0)	0x8 . . . . 0x4 . . . .
0x9	hit	0x8 . . . . 0x4 . . . .
0xA	hit	0x8 . . . . 0x4 . . . .
0xB	hit	0x8 . . . . 0x4 . . . .
0xC	"cold miss", load 0xC (evict 0x4)	0x8 . . . . 0xC . . . .
0xD	hit	0x8 . . . . 0xC . . . .
0xE	hit	0x8 . . . . 0xC . . . .
0xF	hit	0x8 . . . . 0xC . . . .
0x0	"capacity miss", load 0x0 (evict 0x8)	0x0 . . . . 0xC . . . .

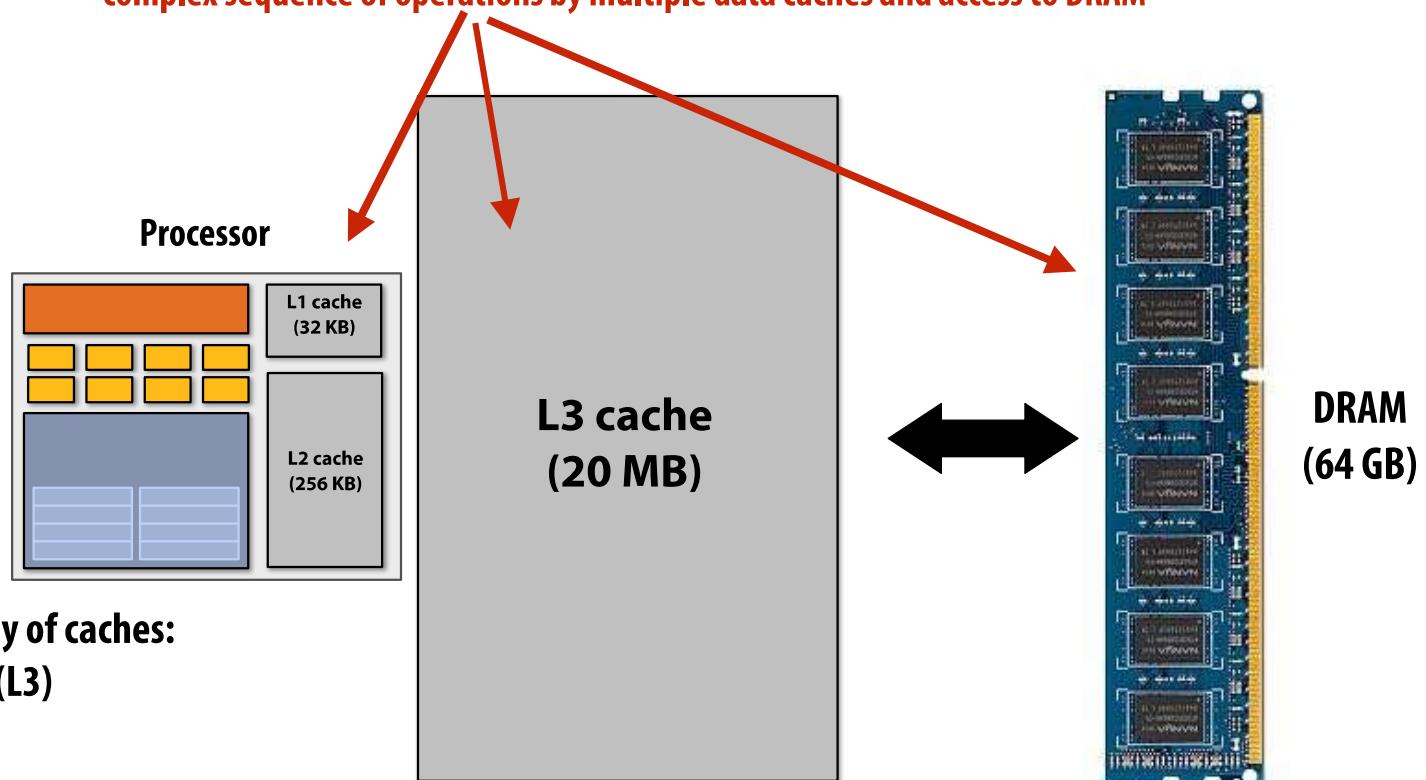
# Caches reduce length of stalls (reduce memory access latency)

- Processors run efficiently when they access data that is resident in caches
- Caches reduce memory access latency when processors accesses data that they have recently accessed! \*

\* Caches also provide high bandwidth data transfer

# The implementation of the linear memory address space abstraction on a modern computer is complex

The instruction “load the value stored at address X into register R0” might involve a complex sequence of operations by multiple data caches and access to DRAM

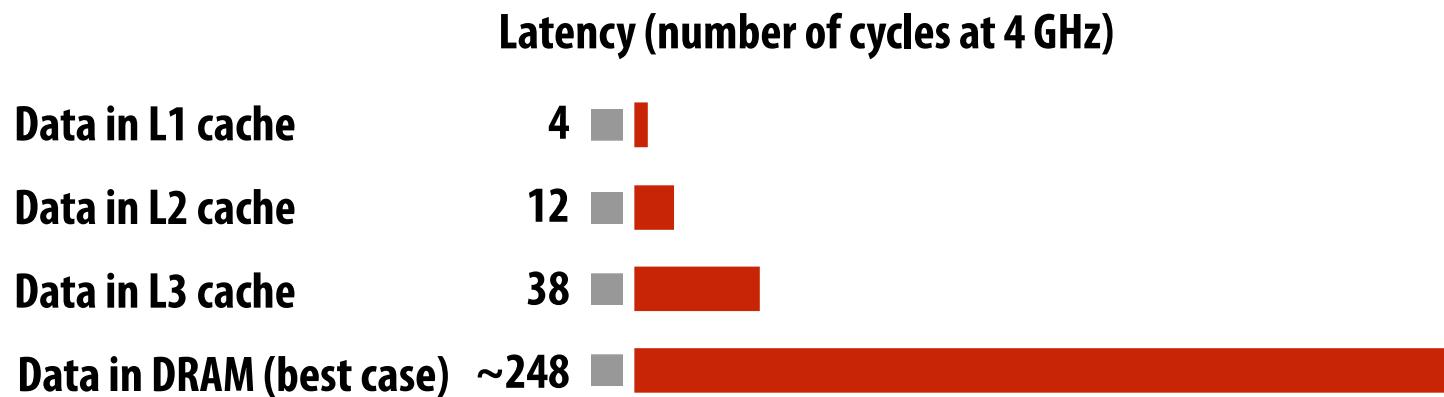


Common organization: hierarchy of caches:  
Level 1 (L1), level 2 (L2), level 3 (L3)

Smaller capacity caches near processor → lower latency  
Larger capacity caches farther away → larger latency

# Data access times

(Kaby Lake CPU)



# Today

- Today we're talking computer architecture... from a software engineer's perspective
- Key concepts about how modern parallel processors achieve high throughput
  - Two concern parallel execution (multi-core, SIMD parallel execution)
  - One addresses the challenges of memory latency (multi-threading)
- Understanding these basics will help you
  - Understand and optimize the performance of your parallel programs
  - Gain intuition about what workloads might benefit from fast parallel machines

# Today's example program

```
void sinx(int N, int terms, float* x, float* y)
{
    for (int i=0; i<N; i++)
    {
        float value = x[i];
        float numer = x[i] * x[i] * x[i];
        int denom = 6; // 3!
        int sign = -1;

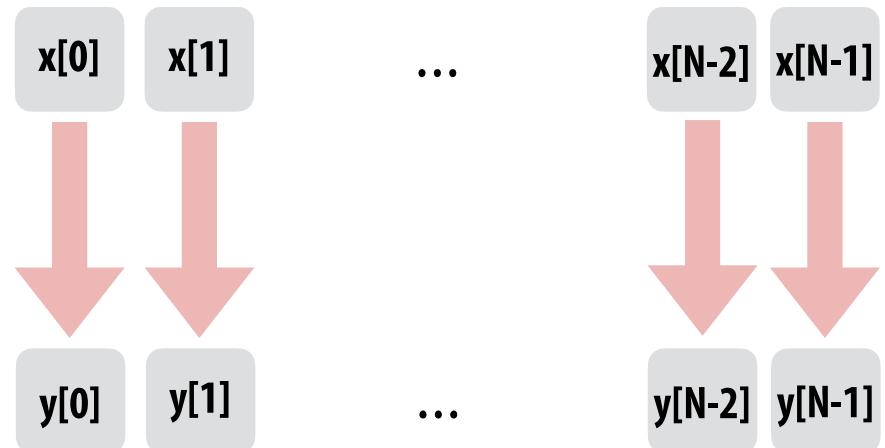
        for (int j=1; j<=terms; j++)
        {
            value += sign * numer / denom;
            numer *= x[i] * x[i];
            denom *= (2*j+2) * (2*j+3);
            sign *= -1;
        }

        y[i] = value;
    }
}
```

**Compute  $\sin(x)$  using Taylor expansion:**

$$\sin(x) = x - x^3/3! + x^5/5! - x^7/7! + \dots$$

**for each element of an array of  $N$  floating-point numbers**



# Compile program

```
void sinx(int N, int terms, float* x, float* y)
{
    for (int i=0; i<N; i++)
    {
        float value = x[i];
        float numer = x[i] * x[i] * x[i];
        int denom = 6; // 3!
        int sign = -1;

        for (int j=1; j<=terms; j++)
        {
            value += sign * numer / denom;
            numer *= x[i] * x[i];
            denom *= (2*j+2) * (2*j+3);
            sign *= -1;
        }

        y[i] = value;
    }
}
```

compiler

Compiled instruction stream  
(scalar instructions)

x[i]



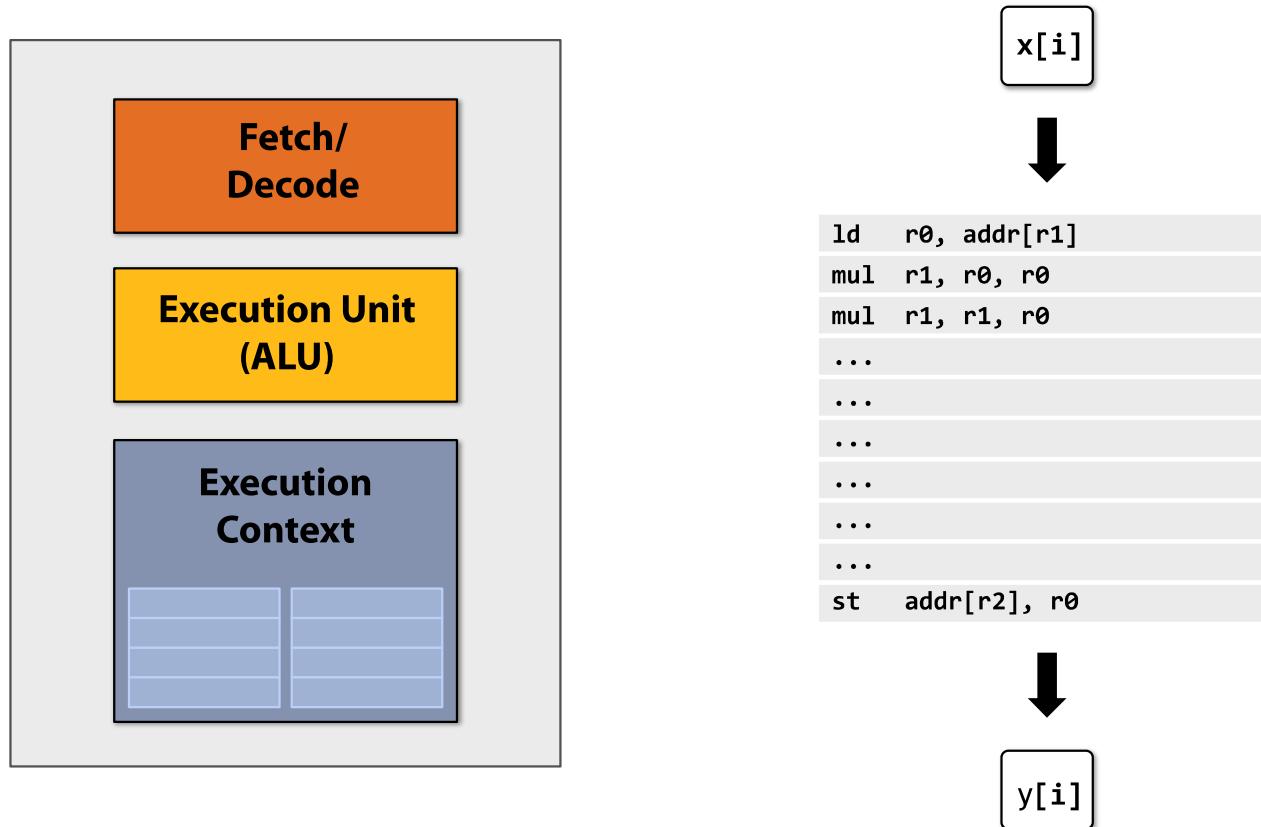
```
ld  r0, addr[r1]
mul r1, r0, r0
mul r1, r1, r0
...
...
...
...
...
...
...
st  addr[r2], r0
```

y[i]



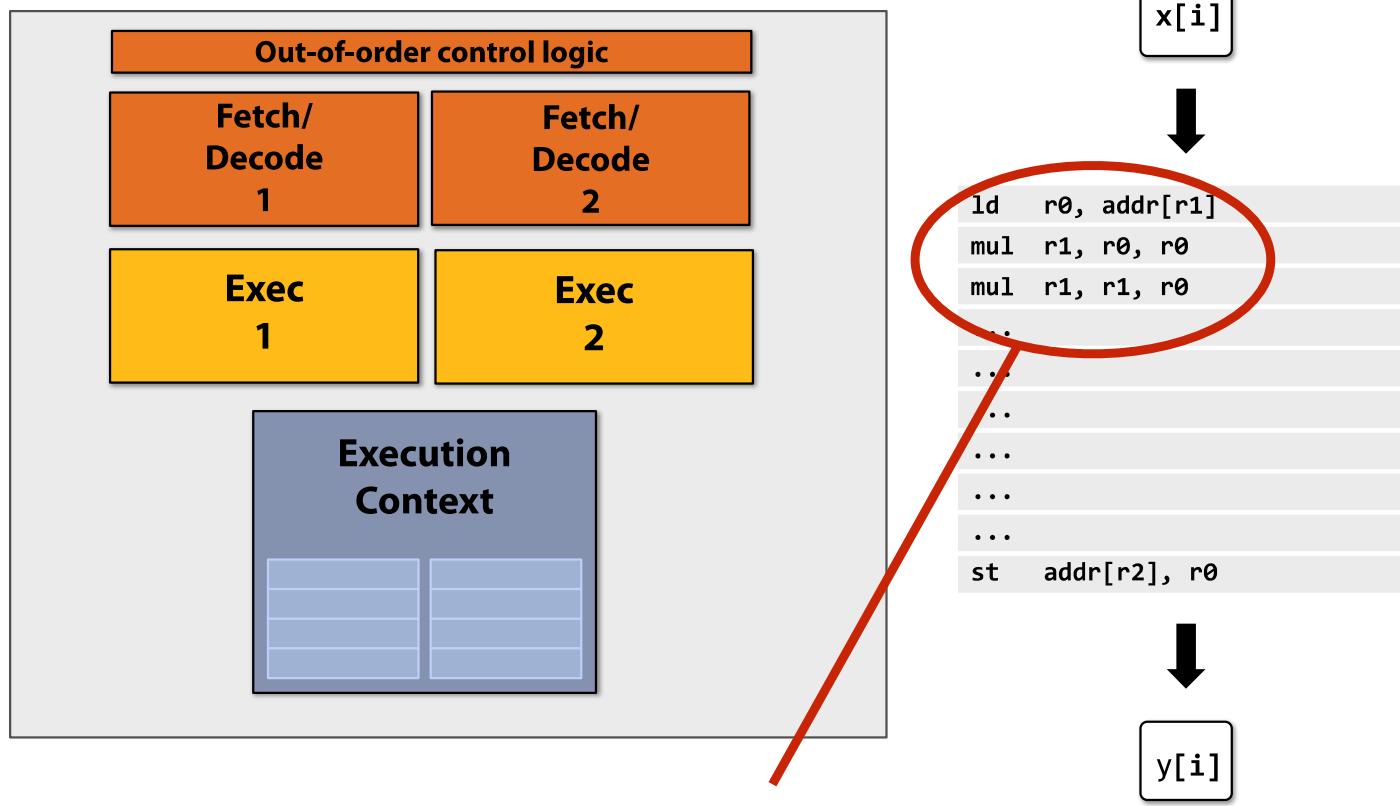
# Execute program

My very simple processor: executes one instruction per clock



# Superscalar processor

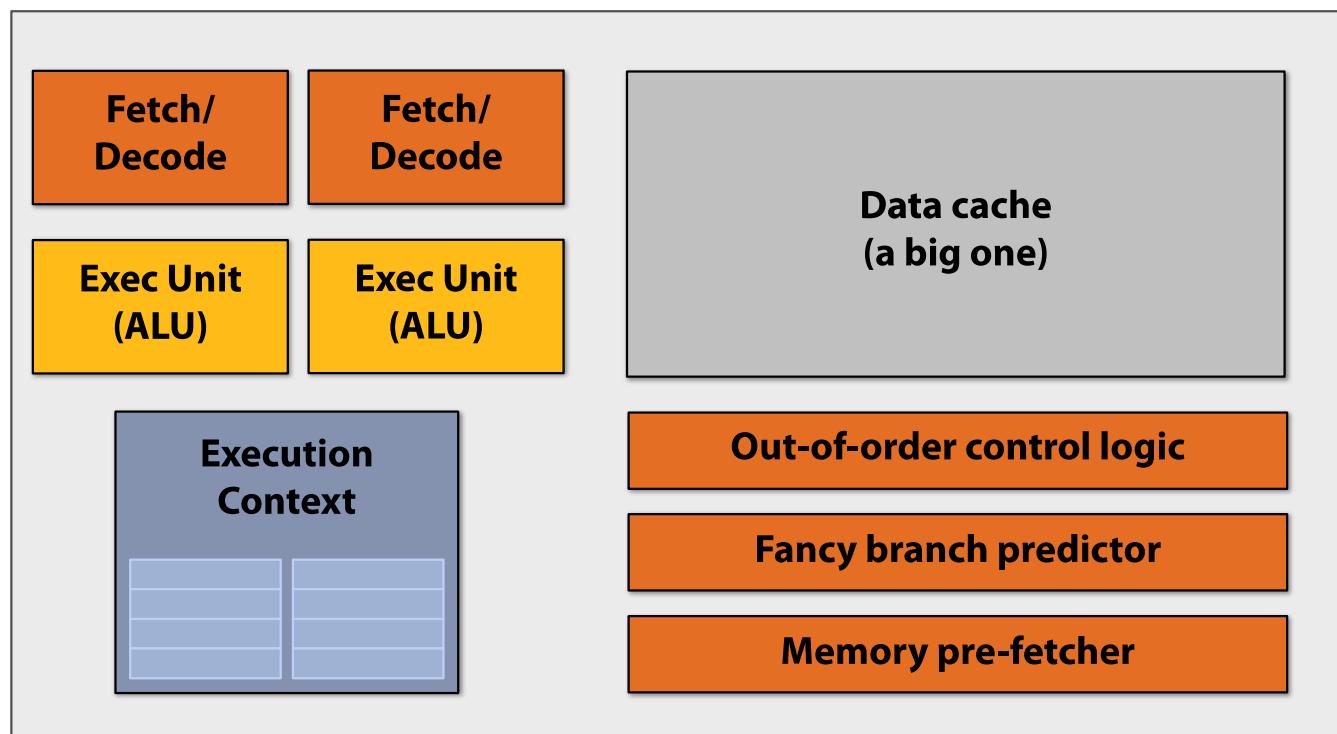
The processor shown here can decode and execute two instructions per clock  
(if independent instructions exist in an instruction stream)



Note: No ILP exists in this region of the program

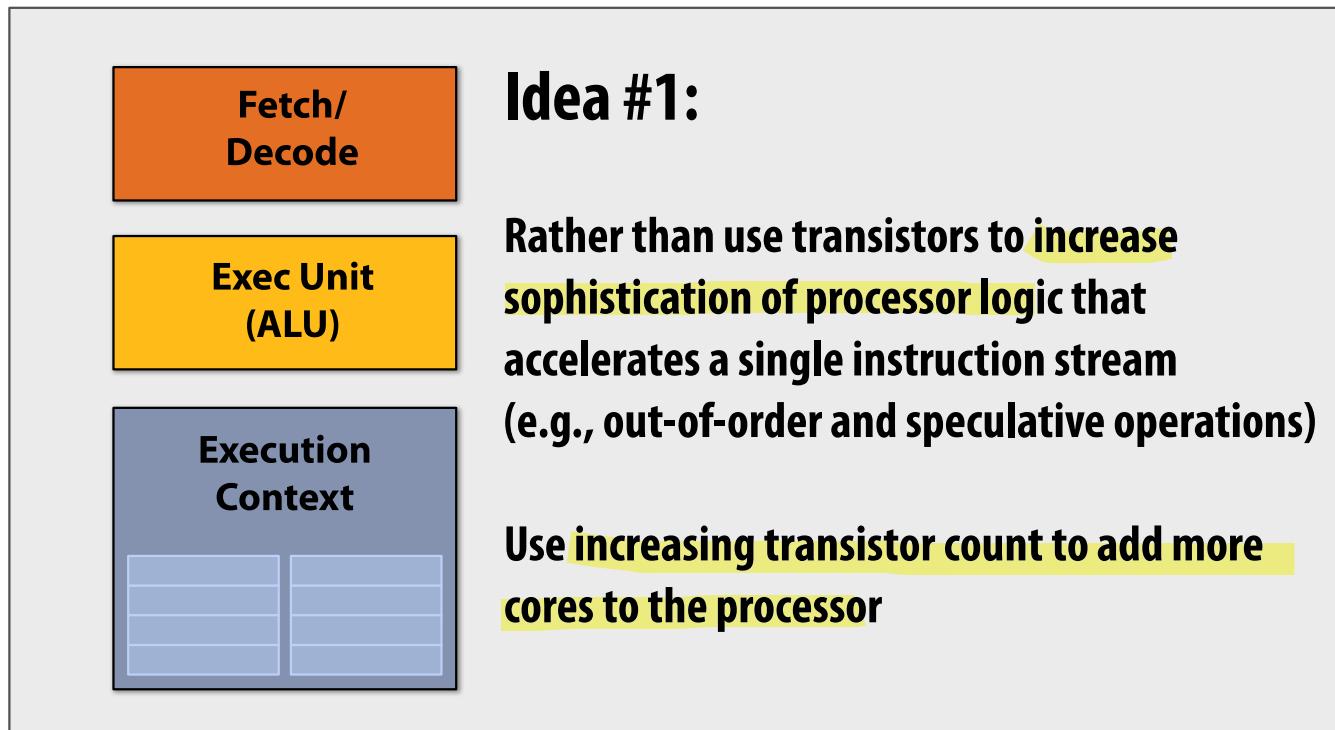
# Pre multi-core era processor

Majority of chip transistors used to perform operations that help make a single instruction stream run fast

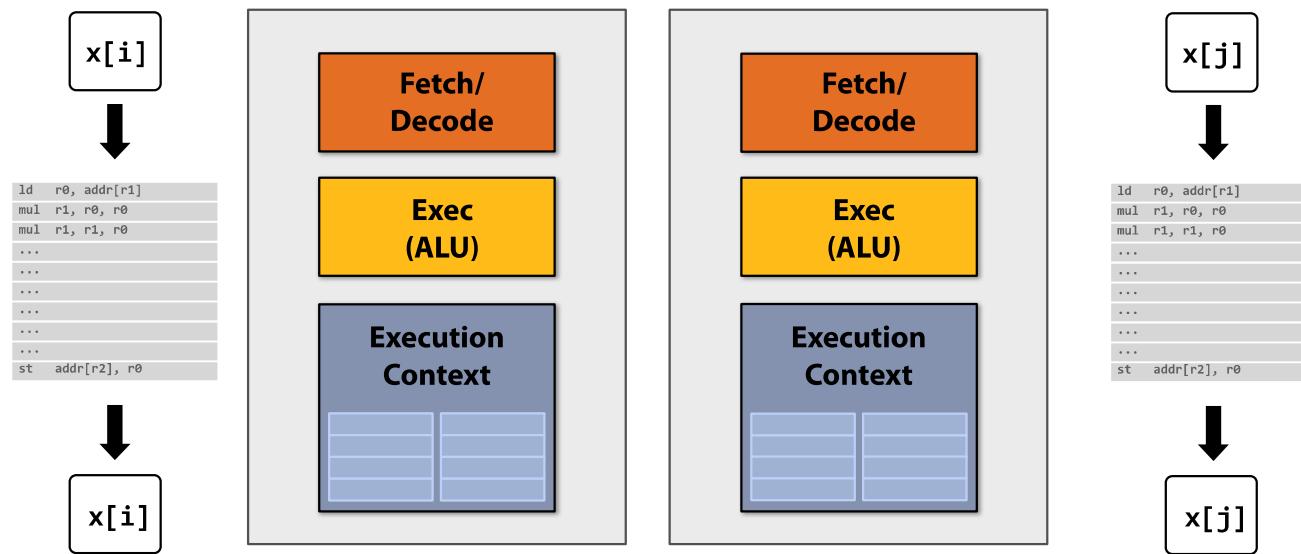


More transistors = larger cache, smarter out-of-order logic, smarter branch predictor, etc.

# Multi-core era processor



# Two cores: compute two elements in parallel



**Simpler cores: each core may be slower at running a single instruction stream than our original “fancy” core (e.g., 25% slower)**

**But there are now two cores:  $2 \times 0.75 = 1.5$  (potential for speedup!)**

# But our program expresses no parallelism

```
void sinx(int N, int terms, float* x, float* y)
{
    for (int i=0; i<N; i++)
    {
        float value = x[i];
        float numer = x[i] * x[i] * x[i];
        int denom = 6; // 3!
        int sign = -1;

        for (int j=1; j<=terms; j++)
        {
            value += sign * numer / denom;
            numer *= x[i] * x[i];
            denom *= (2*j+2) * (2*j+3);
            sign *= -1;
        }

        y[i] = value;
    }
}
```

This C program will compile to an instruction stream that runs as one thread on one processor core.

If each of the simpler processor cores was 25% slower than the original single complicated one, our program now runs 25% slower than before.



# Example: expressing parallelism using C++ threads

```
typedef struct {
    int N;
    int terms;
    float* x;
    float* y;
} my_args;

void my_thread_func(my_args* args)
{
    sinx(args->N, args->terms, args->x, args->y); // do work
}

void parallel_sinx(int N, int terms, float* x, float* y)
{
    std::thread my_thread;
    my_args args;

    args.N = N/2;
    args.terms = terms;
    args.x = x;
    args.y = y;

    my_thread = std::thread(my_thread_func, &args); // launch thread
    sinx(N - args.N, terms, x + args.N, y + args.N); // do work on main thread
    my_thread.join(); // wait for thread to complete
}
```

```
void sinx(int N, int terms, float* x, float* y)
{
    for (int i=0; i<N; i++)
    {
        float value = x[i];
        float numer = x[i] * x[i] * x[i];
        int denom = 6; // 3!
        int sign = -1;

        for (int j=1; j<=terms; j++)
        {
            value += sign * numer / denom;
            numer *= x[i] * x[i];
            denom *= (2*j+2) * (2*j+3);
            sign *= -1;
        }

        y[i] = value;
    }
}
```

# Data-parallel expression

(in Kayvon's fictitious programming language with a "forall" construct)

```
void sinx(int N, int terms, float* x, float* y)
{
    // declares that loop iterations are independent
    forall (int i from 0 to N)

    {
        float value = x[i];
        float numer = x[i] * x[i] * x[i];
        int denom = 6; // 3!
        int sign = -1;

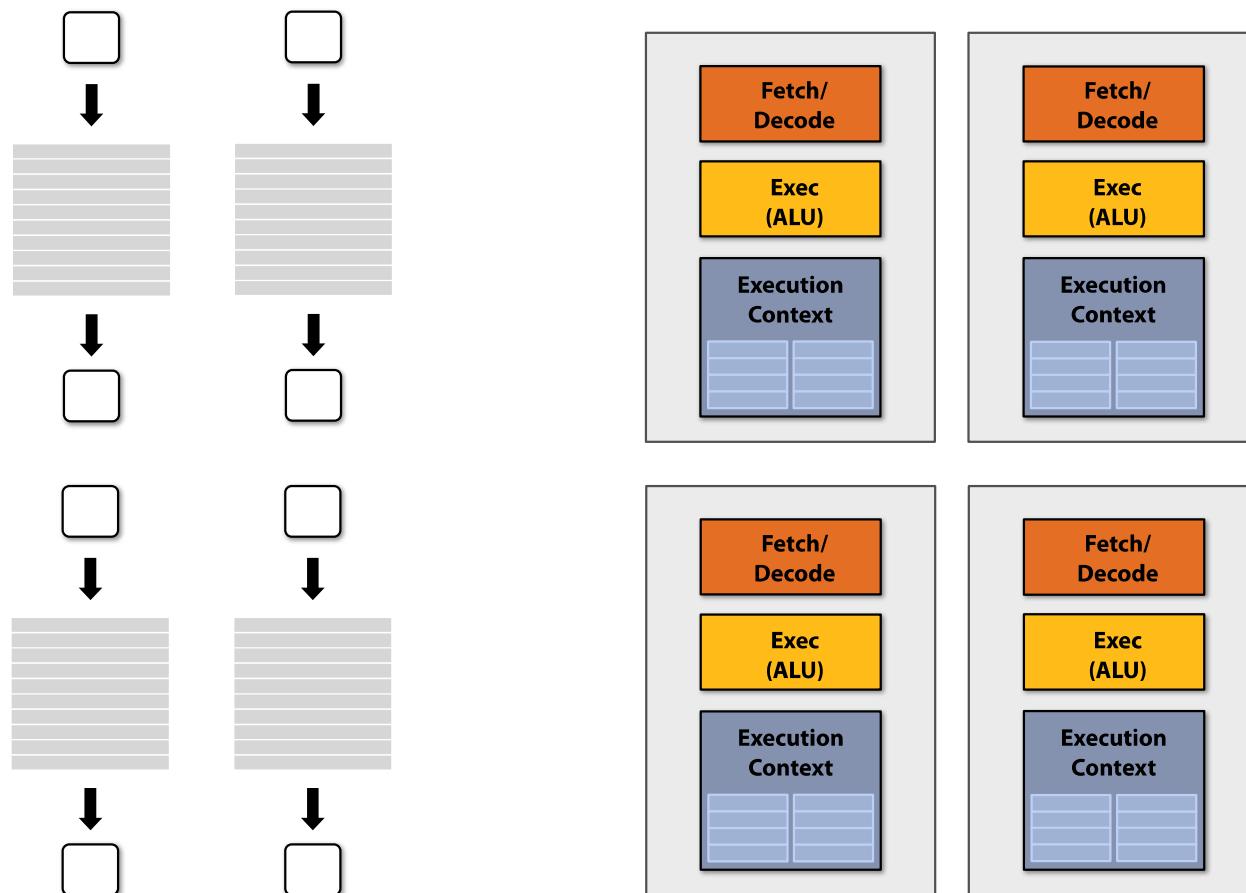
        for (int j=1; j<=terms; j++)
        {
            value += sign * numer / denom;
            numer *= x[i] * x[i];
            denom *= (2*j+2) * (2*j+3);
            sign *= -1;
        }

        y[i] = value;
    }
}
```

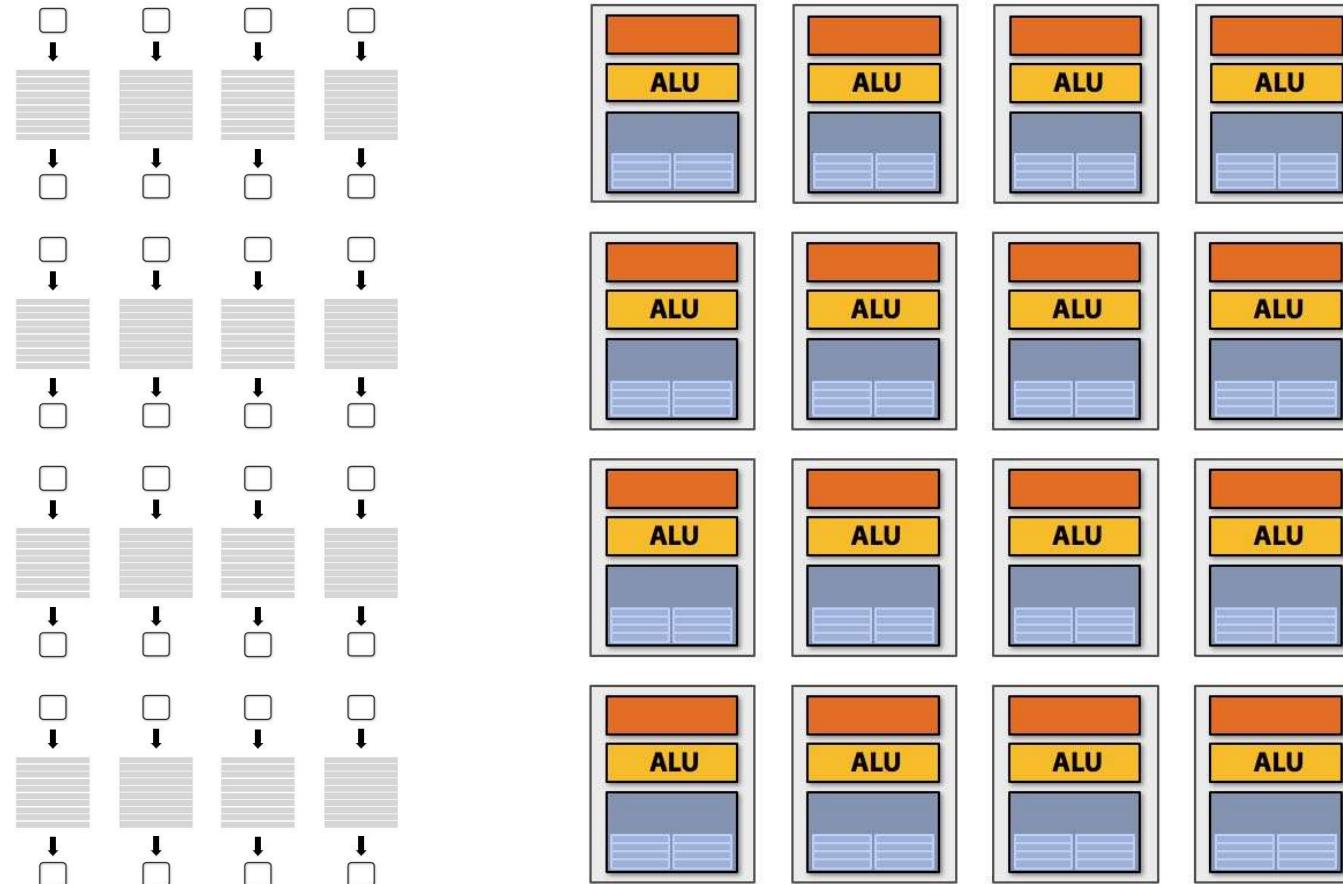
In this code, **loop iterations are declared by the programmer to be independent (see the 'forall')**

With this information, you could imagine how a compiler might automatically generate threaded code for you.

# Four cores: compute four elements in parallel



# Sixteen cores: compute sixteen elements in parallel



Sixteen cores, sixteen simultaneous instruction streams

# Example: multi-core CPU

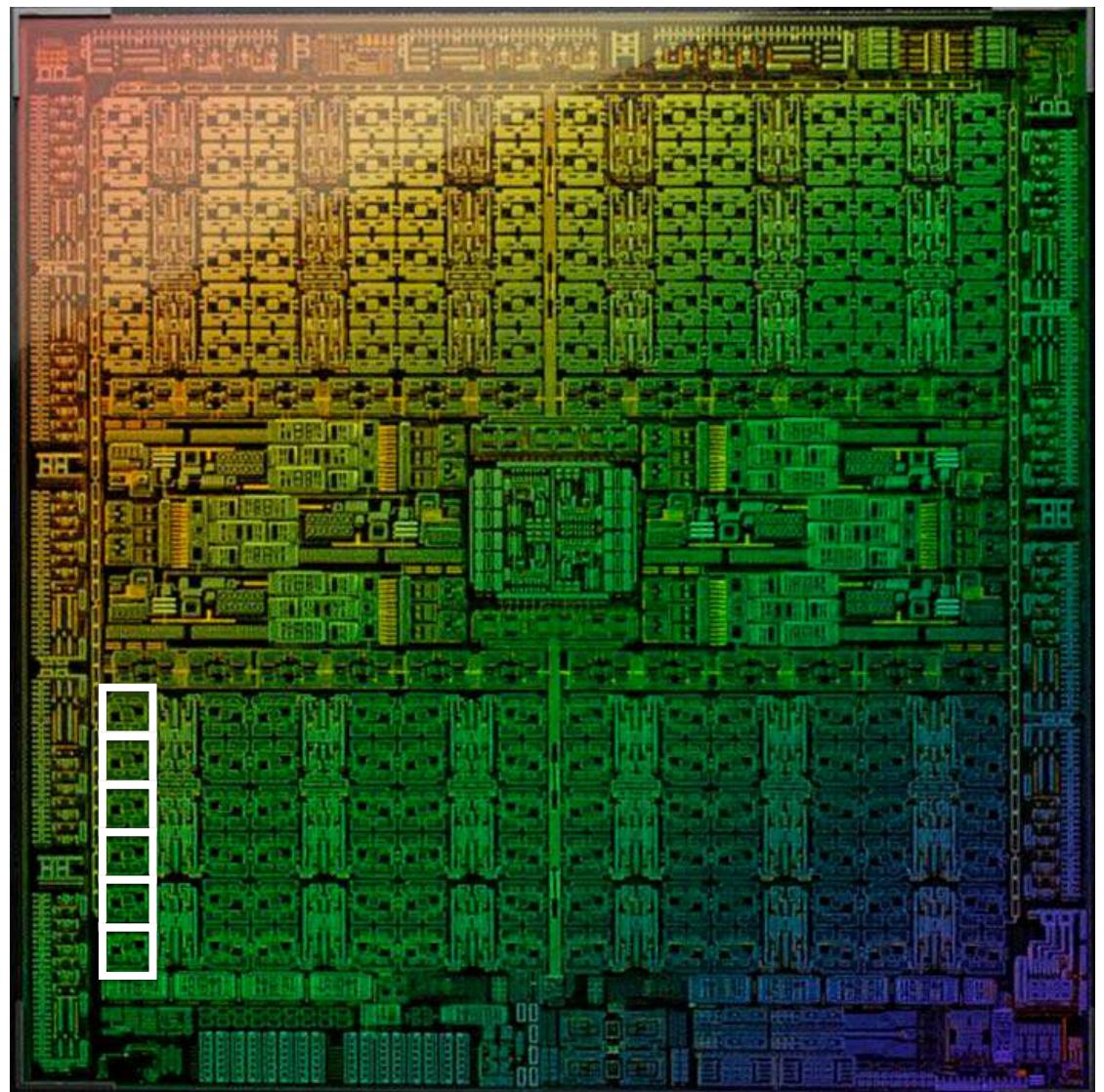
Intel “Comet Lake” 10th Generation Core i9 10-core CPU (2020)



# Multi-core GPU

GeForce RTX 4090 (2022)

144 processing blocks (called SMs)



# Apple A15 Bionic

Two “big cores” + four “small” cores

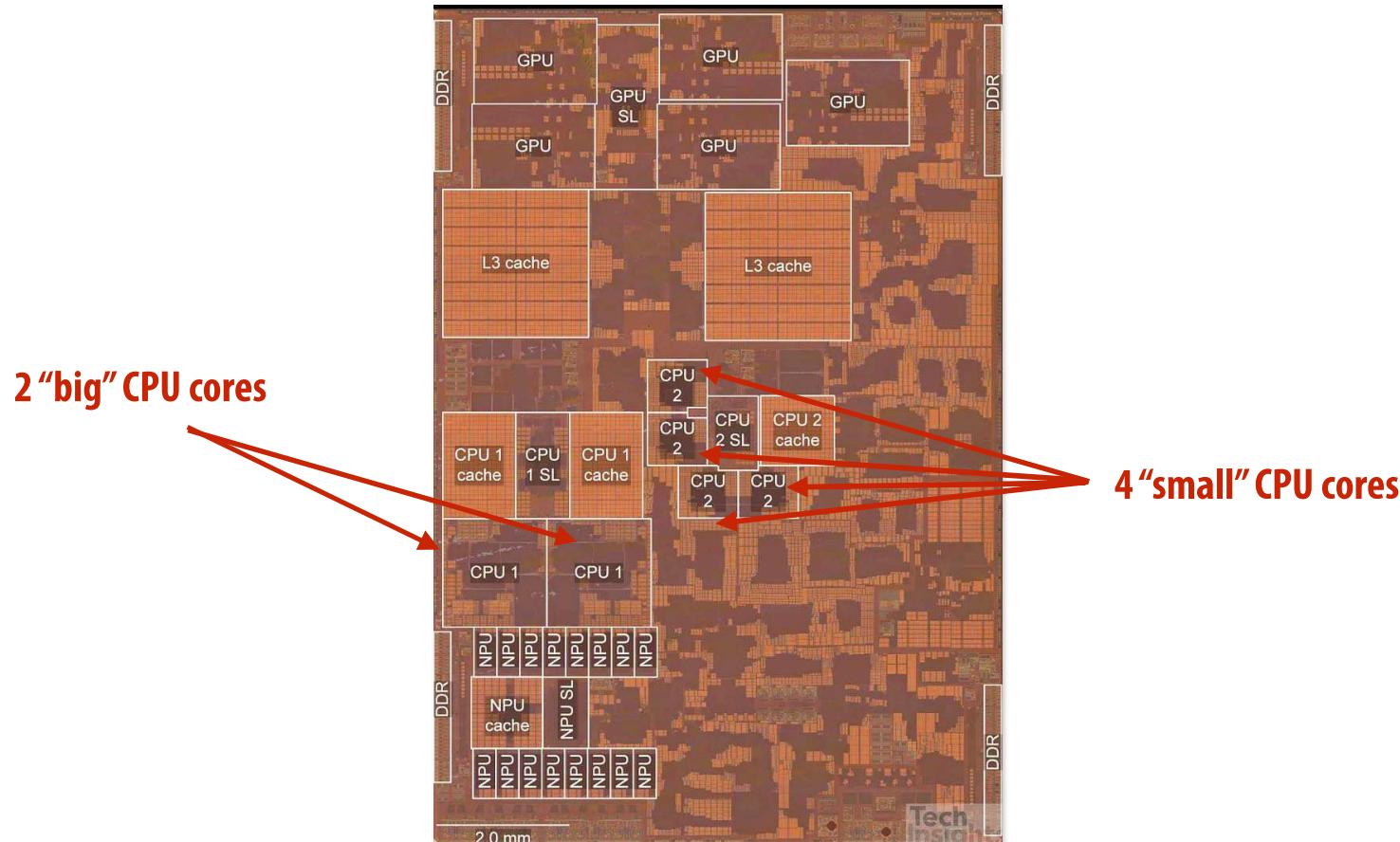


Image Credit: TechInsights Inc.

Stanford CS149, Fall 2023

# Data-parallel expression

(in Kayvon's fictitious programming language with a "forall" construct)

```
void sinx(int N, int terms, float* x, float* result)
{
    // declares that loop iterations are independent
    forall (int i from 0 to N)
    {
        float value = x[i];
        float numer = x[i] * x[i] * x[i];
        int denom = 6; // 3!
        int sign = -1;

        for (int j=1; j<=terms; j++)
        {
            value += sign * numer / denom;
            numer *= x[i] * x[i];
            denom *= (2*j+2) * (2*j+3);
            sign *= -1;
        }

        result[i] = value;
    }
}
```

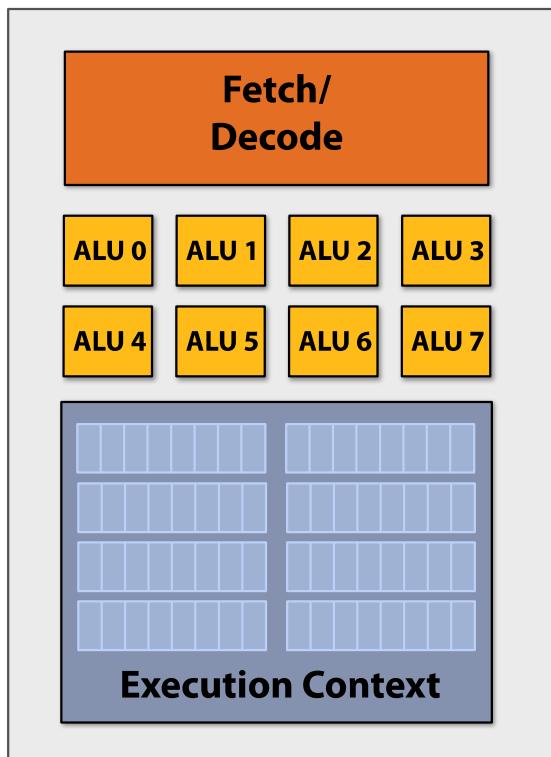
**Another interesting property of this code:**

**Parallelism is across iterations of the loop.**

**All the iterations of the loop carry out the exact same sequence of instructions (defined by the loop body), but on different input data given by  $x[i]$**

**(the loop body computes  $\sin(x[i])$ )**

# Add execution units (ALUs) to increase compute capability



**Idea #2:**  
Amortize cost/complexity of managing an  
instruction stream across many ALUs

## SIMD processing

Single instruction, multiple data

Same instruction broadcast to all ALUs  
This operation is executed in parallel on all ALUs

# Recall our original scalar program

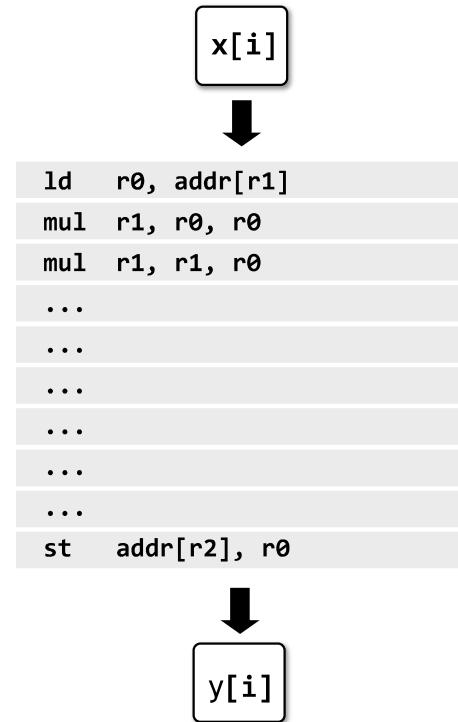
```
void sinx(int N, int terms, float* x, float* y)
{
    for (int i=0; i<N; i++)
    {
        float value = x[i];
        float numer = x[i] * x[i] * x[i];
        int denom = 6; // 3!
        int sign = -1;

        for (int j=1; j<=terms; j++)
        {
            value += sign * numer / denom;
            numer *= x[i] * x[i];
            denom *= (2*j+2) * (2*j+3);
            sign *= -1;
        }

        y[i] = value;
    }
}
```

**Original compiled program:**

**Processes one array element using scalar instructions  
on scalar registers (e.g., 32-bit floats)**



# Vector program (using AVX intrinsics)

```
#include <immintrin.h>

void sinx(int N, int terms, float* x, float* y)
{
    float three_fact = 6; // 3!
    for (int i=0; i<N; i+=8)
    {
        __m256 origx = _mm256_load_ps(&x[i]);
        __m256 value = origx;
        __m256 numer = _mm256_mul_ps(origx, _mm256_mul_ps(origx, origx));
        __m256 denom = _mm256_broadcast_ss(&three_fact);
        int sign = -1;

        for (int j=1; j<=terms; j++)
        {
            // value += sign * numer / denom
            __m256 tmp = _mm256_div_ps(_mm256_mul_ps(_mm256_set1ps(sign), numer), denom);
            value = _mm256_add_ps(value, tmp);

            numer = _mm256_mul_ps(numer, _mm256_mul_ps(origx, origx));
            denom = _mm256_mul_ps(denom, _mm256_broadcast_ss((2*j+2) * (2*j+3)));
            sign *= -1;
        }
        _mm256_store_ps(&y[i], value);
    }
}
```

**Intrinsic datatypes and functions available to C programmers**

**Intrinsic functions operate on vectors of eight 32-bit values (e.g., vector of 8 floats)**

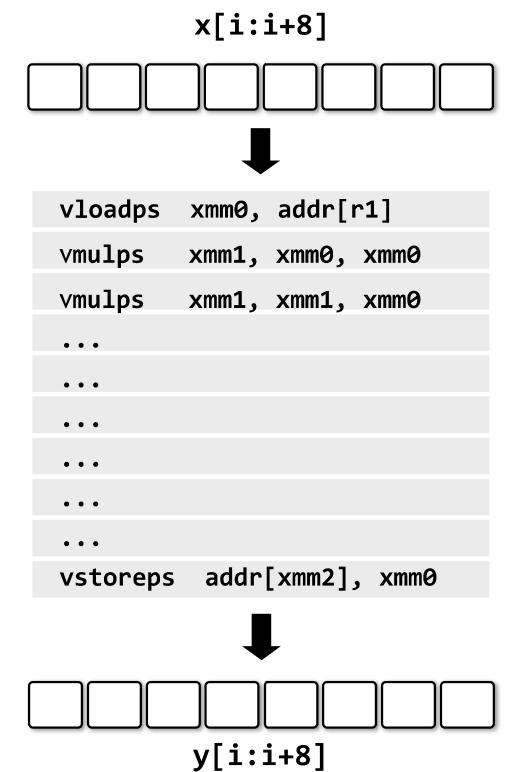
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```
#include <immintrin.h>

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{
    float three_fact = 6; // 3!
    for (int i=0; i<N; i+=8)
    {
        __m256 origx = _mm256_load_ps(&x[i]);
        __m256 value = origx;
        __m256 numer = _mm256_mul_ps(origx, _mm256_mul_ps(origx, origx));
        __m256 denom = _mm256_broadcast_ss(&three_fact);
        int sign = -1;

        for (int j=1; j<=terms; j++)
        {
            // value += sign * numer / denom
            __m256 tmp = _mm256_div_ps(_mm256_mul_ps(_mm256_set1_ps(sign), numer), denom);
            value = _mm256_add_ps(value, tmp);

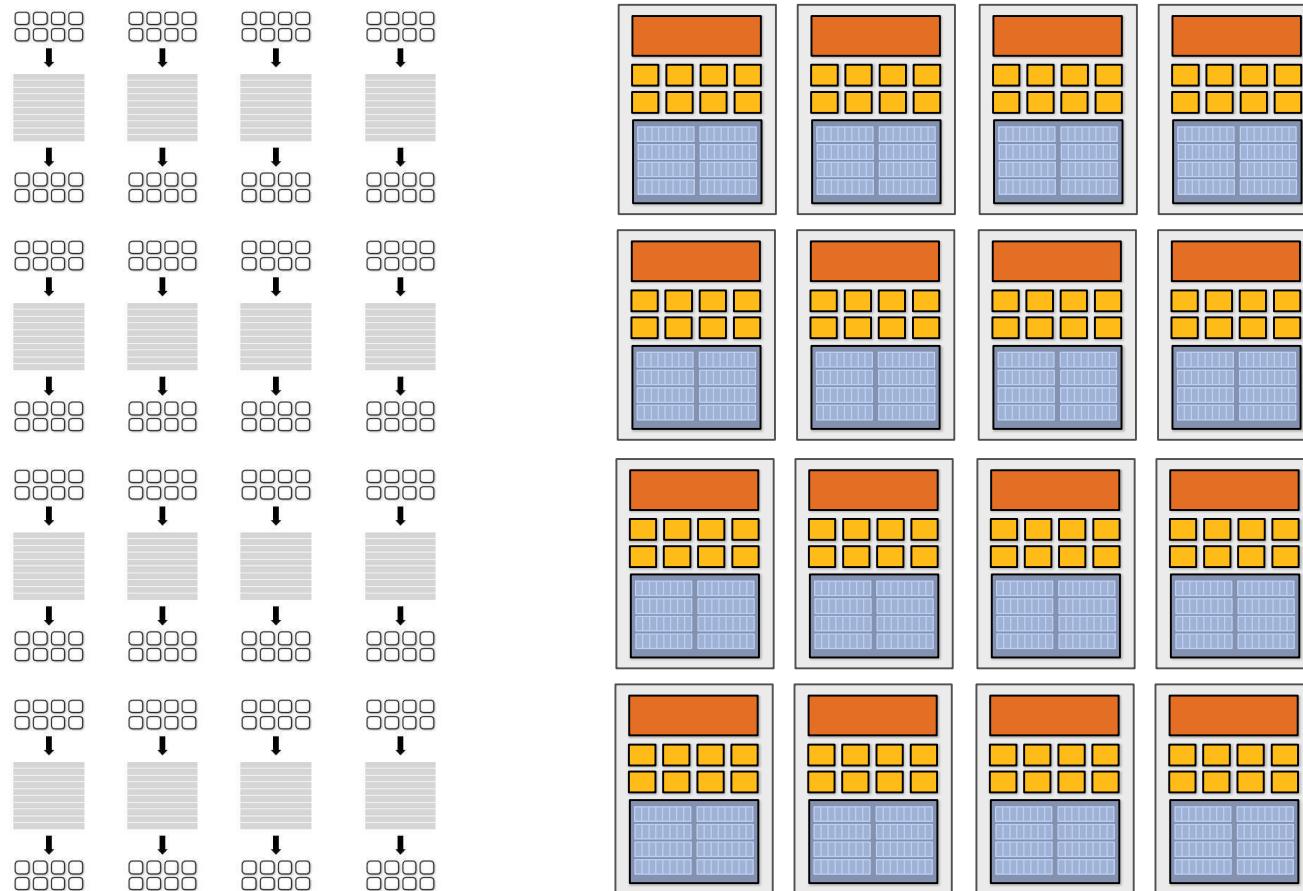
            numer = _mm256_mul_ps(numer, _mm256_mul_ps(origx, origx));
            denom = _mm256_mul_ps(denom, _mm256_broadcast_ss((2*j+2) * (2*j+3)));
            sign *= -1;
        }
        _mm256_store_ps(&y[i], value);
    }
}
```



**Compiled program:**

**Processes eight array elements simultaneously using vector instructions on 256-bit vector registers**

# 16 SIMD cores: 128 elements in parallel



**16 cores, 128 ALUs, 16 simultaneous instruction streams**

# Data-parallel expression

(in Kayvon's fictitious programming language with a "forall" construct)

```
void sinx(int N, int terms, float* x, float* result)
{
    // declares that loop iterations are independent
    forall (int i from 0 to N)
    {
        float value = x[i];
        float numer = x[i] * x[i] * x[i];
        int denom = 6; // 3!
        int sign = -1;

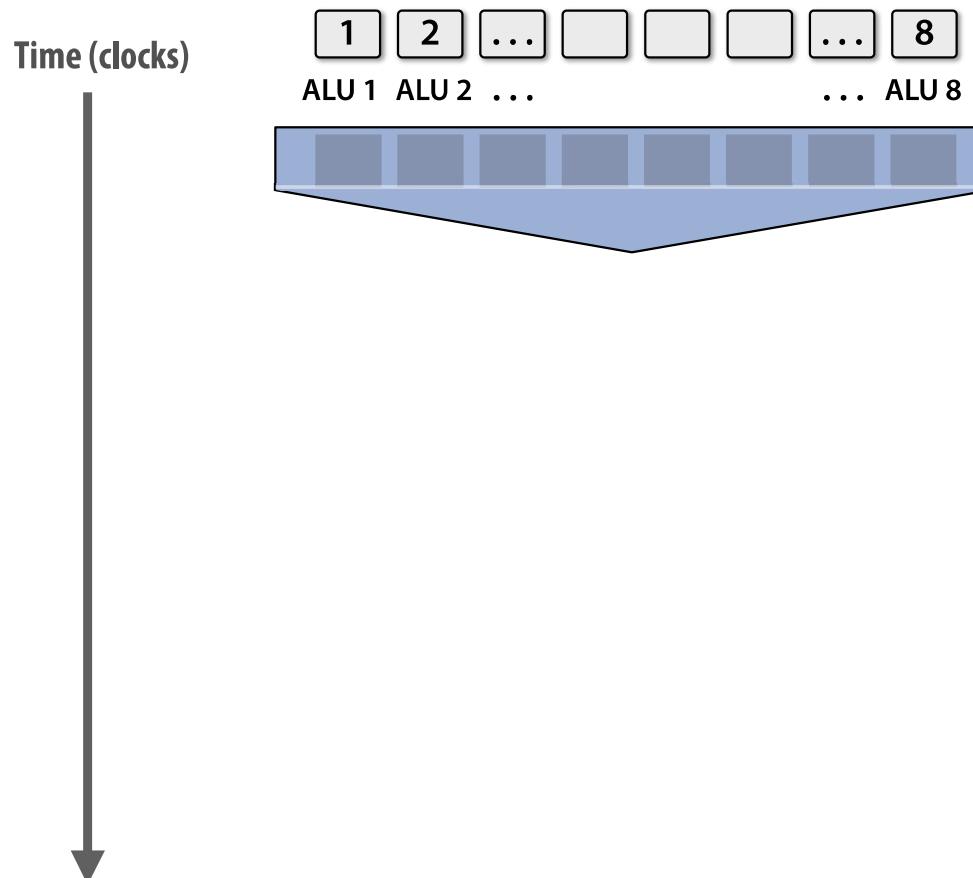
        for (int j=1; j<=terms; j++)
        {
            value += sign * numer / denom;
            numer *= x[i] * x[i];
            denom *= (2*j+2) * (2*j+3);
            sign *= -1;
        }

        result[i] = value;
    }
}
```

The program's use of "forall" declares to the compiler that loop iterations are independent, and that same loop body will be executed on a large number of data elements.

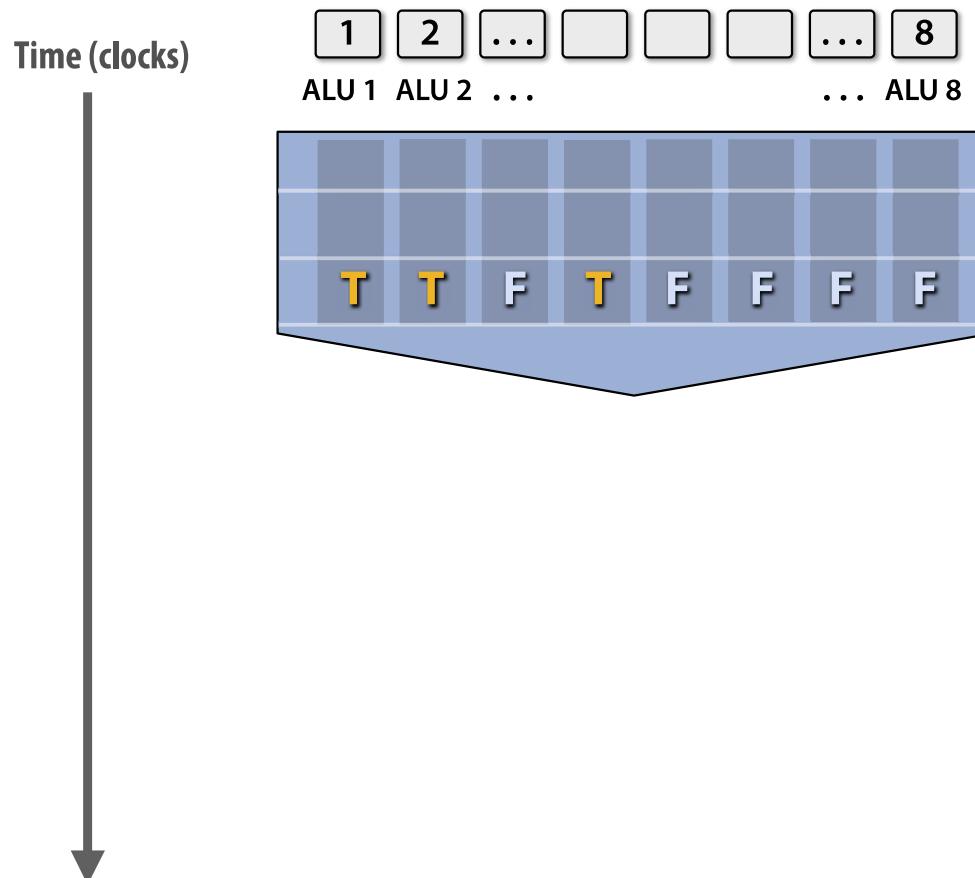
This abstraction can facilitate automatic generation of both multi-core parallel code, and vector instructions to make use of SIMD processing capabilities within a core.

# What about conditional execution?



```
forall (int i from 0 to N) {  
    float t = x[i];  
    <unconditional code>  
  
    if (t > 0.0) {  
        t = t * t;  
        t = t * 50.0;  
        t = t + 100.0;  
    } else {  
        t = t + 30.0;  
        t = t / 10.0;  
    }  
  
<resume unconditional code>  
    y[i] = t;  
}
```

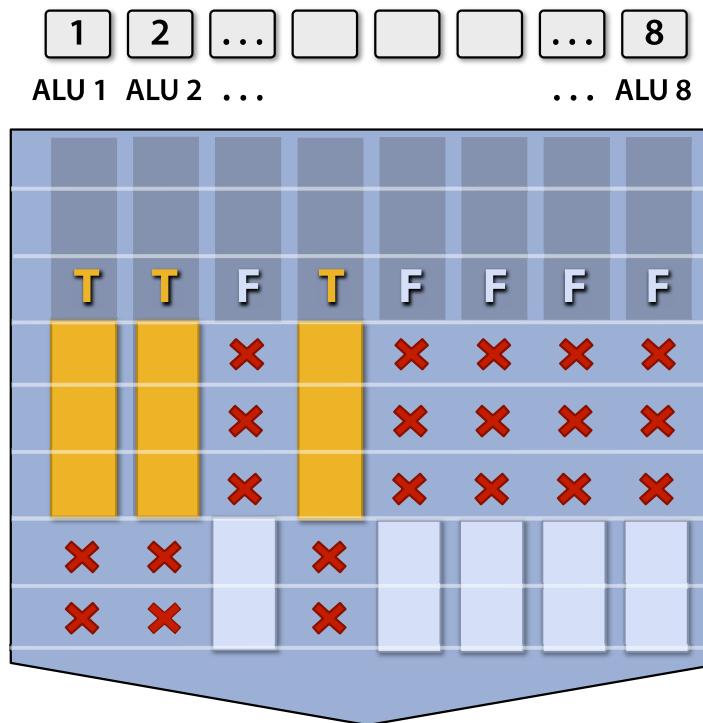
# What about conditional execution?



```
forall (int i from 0 to N) {  
    float t = x[i];  
    <unconditional code>  
  
    if (t > 0.0) {  
        t = t * t;  
        t = t * 50.0;  
        t = t + 100.0;  
    } else {  
        t = t + 30.0;  
        t = t / 10.0;  
    }  
  
<resume unconditional code>  
    y[i] = t;  
}
```

# Mask (discard) output of ALU

Time (clocks)



Not all ALUs do useful work!

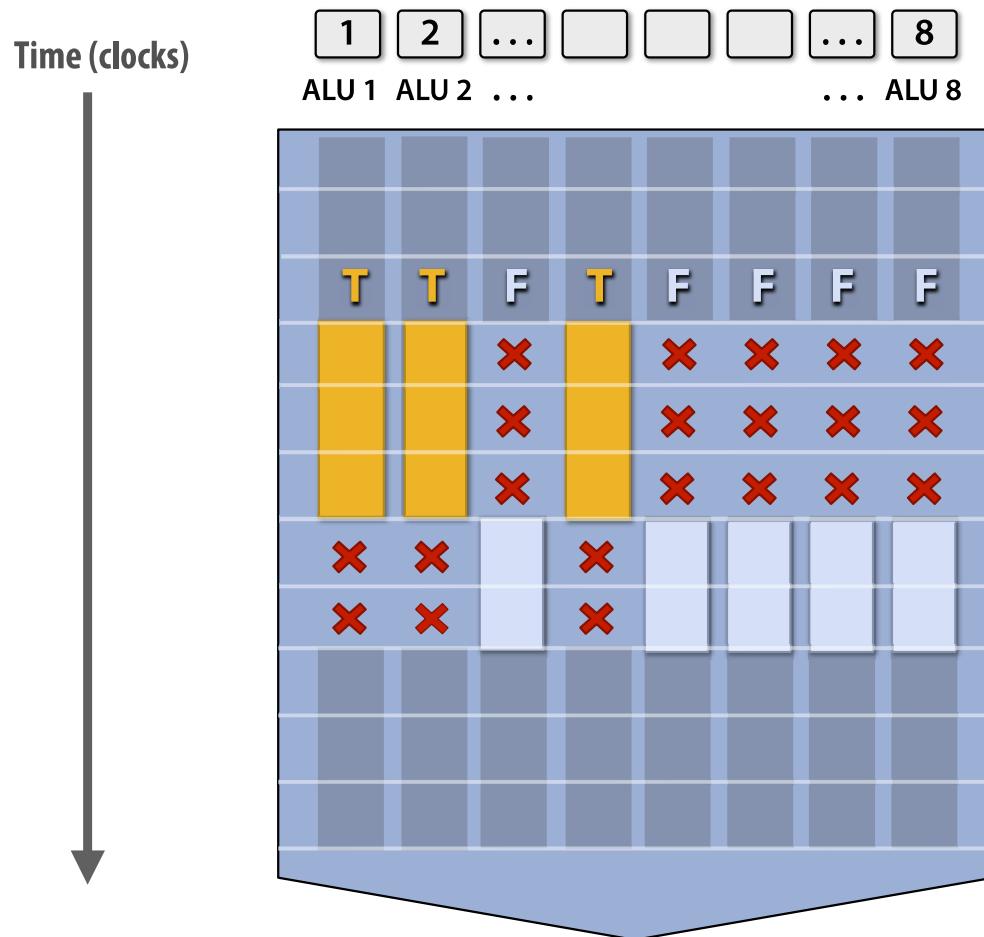
Worst case: 1/8 peak performance

```
forall (int i from 0 to N) {
    float t = x[i];
    <unconditional code>

    if (t > 0.0) {
        t = t * t;
        t = t * 50.0;
        t = t + 100.0;
    } else {
        t = t + 30.0;
        t = t / 10.0;
    }

    <resume unconditional code>
    y[i] = t;
}
```

# After branch: continue at full performance

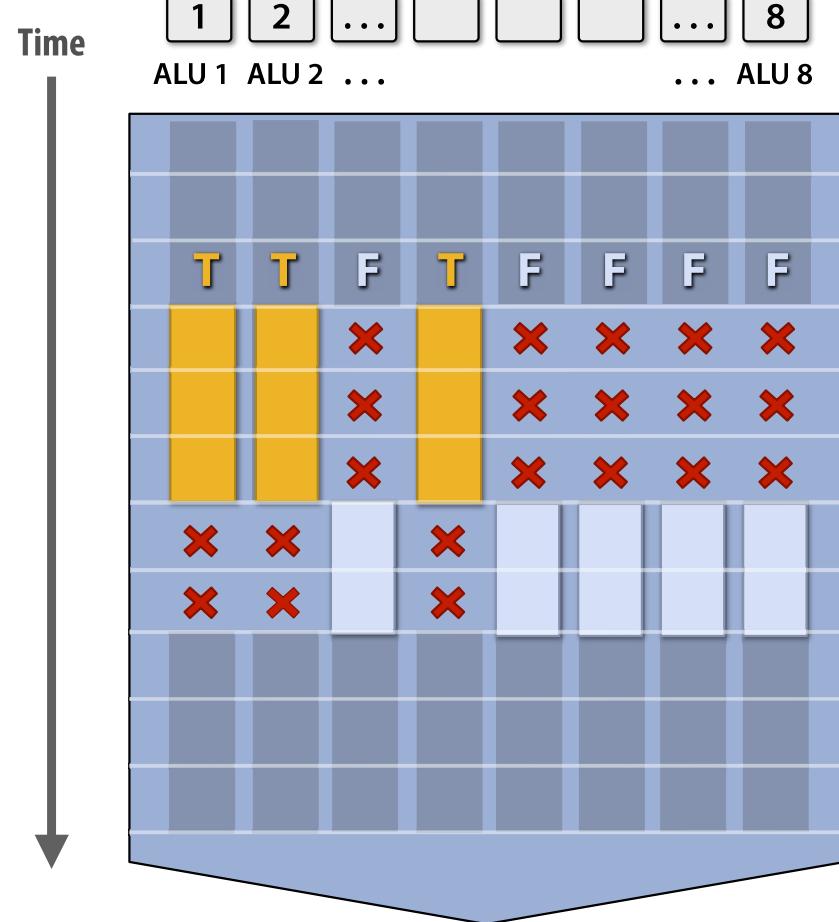


```
forall (int i from 0 to N) {  
    float t = x[i];  
    <unconditional code>  
  
    if (t > 0.0) {  
        t = t * t;  
        t = t * 50.0;  
        t = t + 100.0;  
    } else {  
        t = t + 30.0;  
    }  
  
<resume unconditional code>  
    y[i] = t;  
}
```

# Breakout question

Can you think of piece of code that yields the worst case performance on a processor with 8-wide SIMD execution?

*Hint: can you create it using only a single "if" statement?*



```
forall (int i from 0 to N) {  
    float t = x[i];  
    <unconditional code>  
  
    if (t > 0.0) {  
        ???  
    } else {  
        ???  
    }  
    <resume unconditional code>  
    y[i] = t;  
}
```

# Some common jargon

- **Instruction stream coherence (“coherent execution”)**
  - Property of a program where the same instruction sequence applies to many data elements
  - Coherent execution IS NECESSARY for SIMD processing resources to be used efficiently
  - Coherent execution IS NOT NECESSARY for efficient parallelization across different cores, since each core has the capability to fetch/decode a different instructions from their thread’s instruction stream
- **“Divergent” execution**
  - A lack of instruction stream coherence in a program

# SIMD execution: modern CPU examples

- Intel AVX2 instructions: 256 bit operations: 8x32 bits or 4x64 bits (8-wide float vectors)
- Intel AVX512 instruction: 512 bit operations: 16x32 bits...
- ARM Neon instructions: 128 bit operations: 4x32 bits...
- Instructions are generated by the compiler
  - Parallelism explicitly requested by programmer using intrinsics
  - Parallelism conveyed using parallel language semantics (e.g., `forall` example)
  - Parallelism inferred by dependency analysis of loops by “auto-vectorizing” compiler
- Terminology: “explicit SIMD”: SIMD parallelization is performed at compile time
  - Can inspect program binary and see SIMD instructions (`vstoreps`, `vmulps`, etc.)

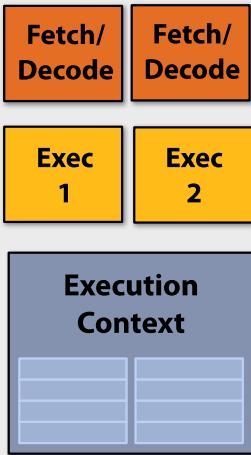
# SIMD execution on many modern GPUs

TL;DR — see “going farther” video

- “Implicit SIMD”
  - Compiler generates a binary with scalar instructions
  - But N instances of the program are always run together on the processor
  - Hardware (not compiler) is responsible for simultaneously executing the same instruction from multiple program instances on different data on SIMD ALUs
- SIMD width of most modern GPUs ranges from 8 to 32
  - Divergent execution can be a big issue  
(poorly written code might execute at 1/32 the peak capability of the machine!)

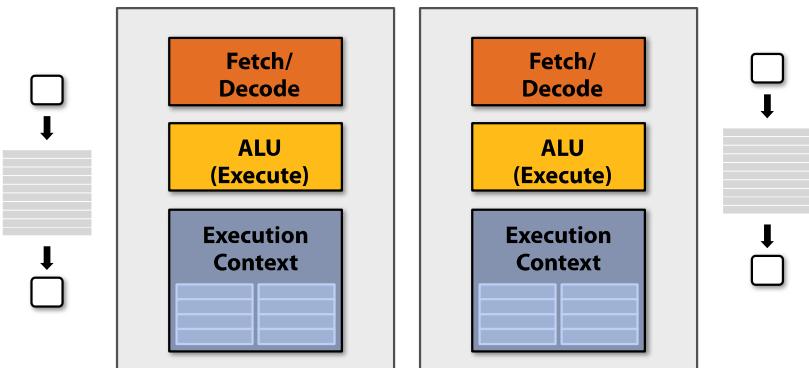
# Summary: three different forms of parallel execution

- **Superscalar:** exploit ILP within an instruction stream. Process different instructions from the same instruction stream in parallel (within a core)
  - Parallelism automatically discovered by the hardware during execution
- **SIMD:** multiple ALUs controlled by same instruction (within a core)
  - Efficient for data-parallel workloads: amortize control costs over many ALUs
  - Vectorization done by compiler (explicit SIMD) or at runtime by hardware (implicit SIMD)
- **Multi-core:** use multiple processing cores
  - Provides thread-level parallelism: simultaneously execute a completely different instruction stream on each core
  - Software creates threads to expose parallelism to hardware (e.g., via threading API)

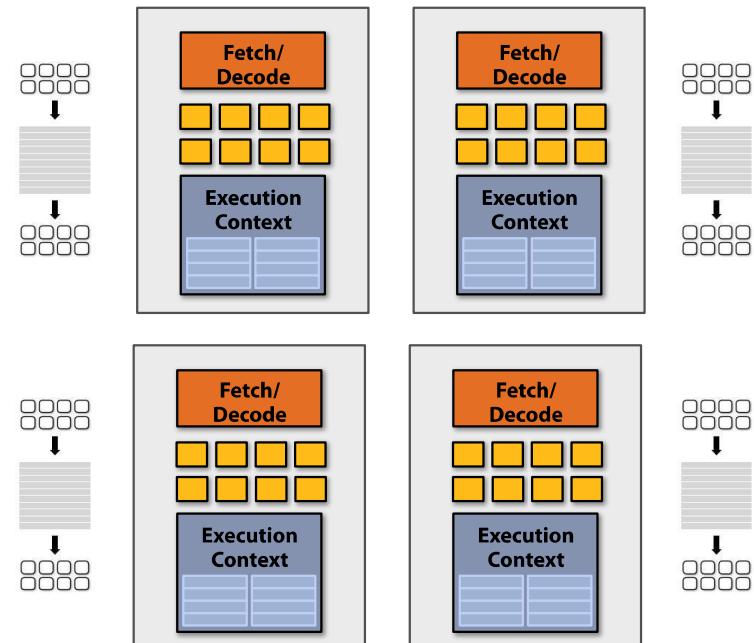


**My single core, superscalar processor:**  
**executes up to two instructions per clock**  
**from a single instruction stream (if the**  
**instructions are independent)**

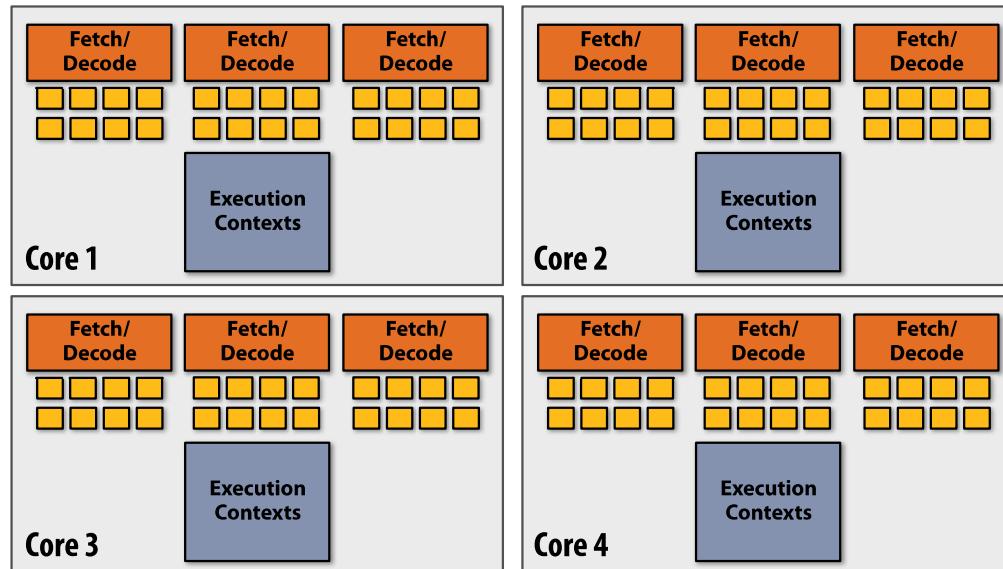
**My dual-core processor:**  
**executes one instruction per clock**  
**from one instruction stream on each core.**



**My SIMD quad-core processor:**  
**executes one 8-wide SIMD instruction per clock**  
**from one instruction stream on each core.**



# Example: four-core Intel i7-7700K CPU (Kaby Lake)

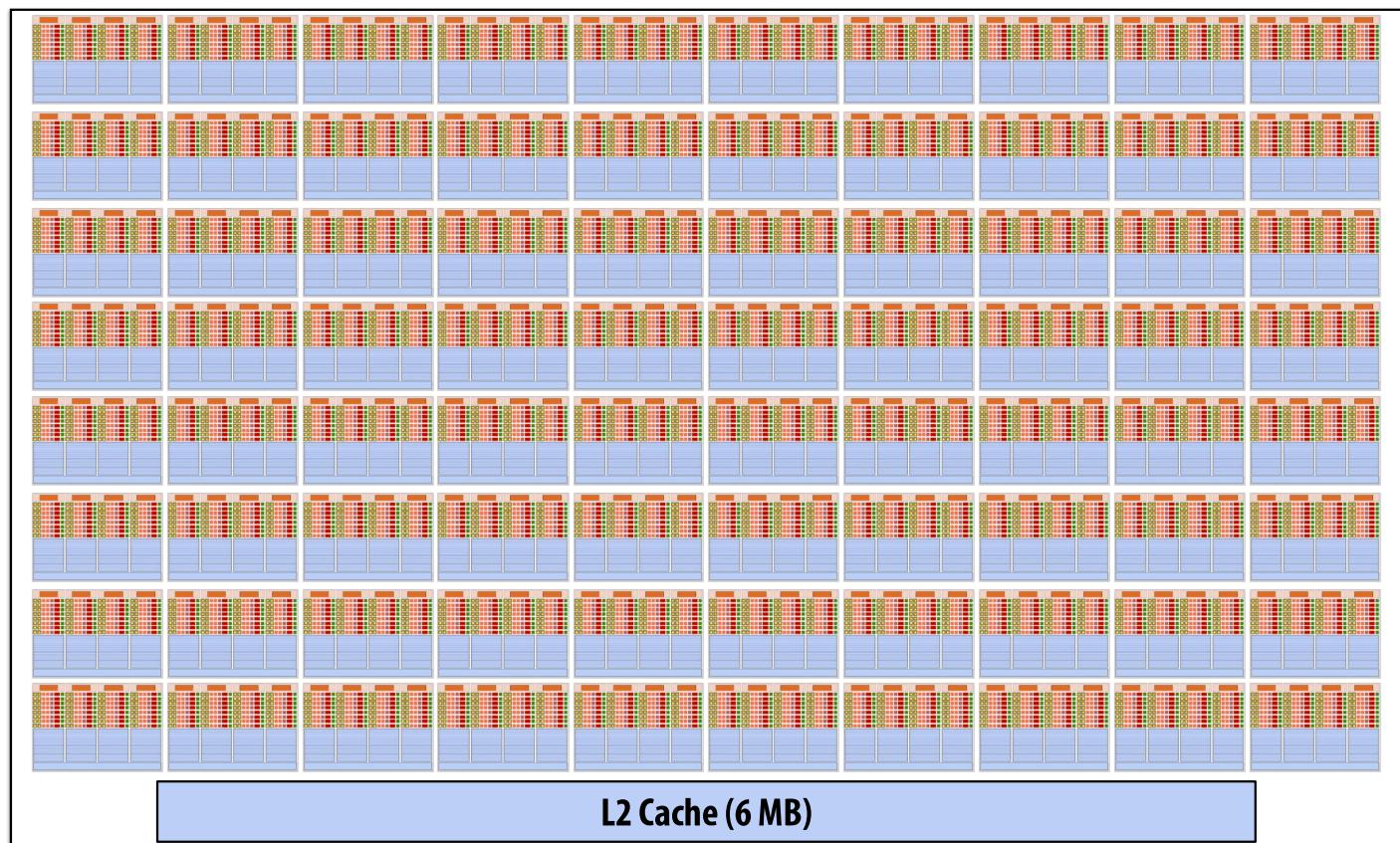


4 core processor  
Three 8-wide SIMD ALUs per core  
(AVX2 instructions)

4 cores x 8-wide SIMD x 3 x 4.2 GHz = 400 GFLOPs

\* Showing only AVX math units, and fetch/decode unit for AVX (additional capability for integer math)

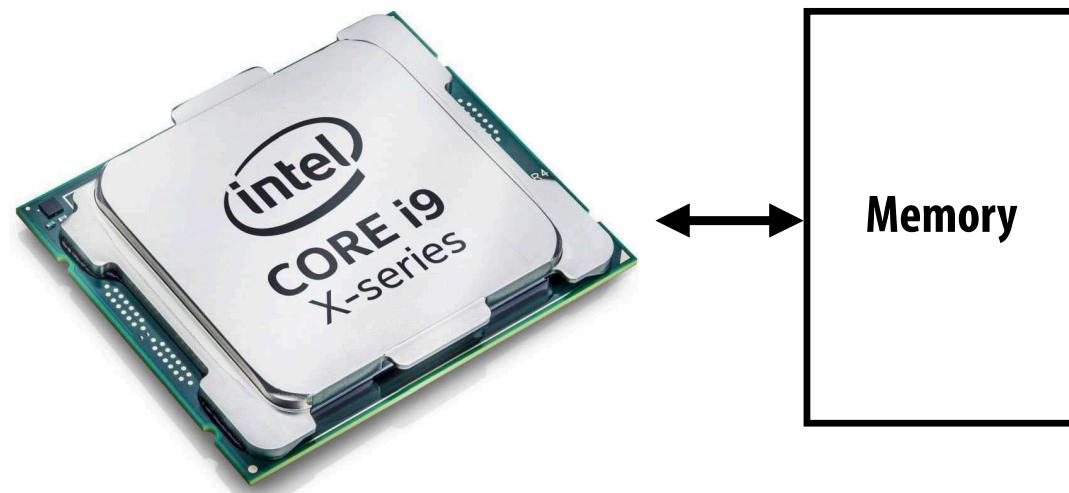
# Example: NVIDIA V100 GPU



80 "SM" cores

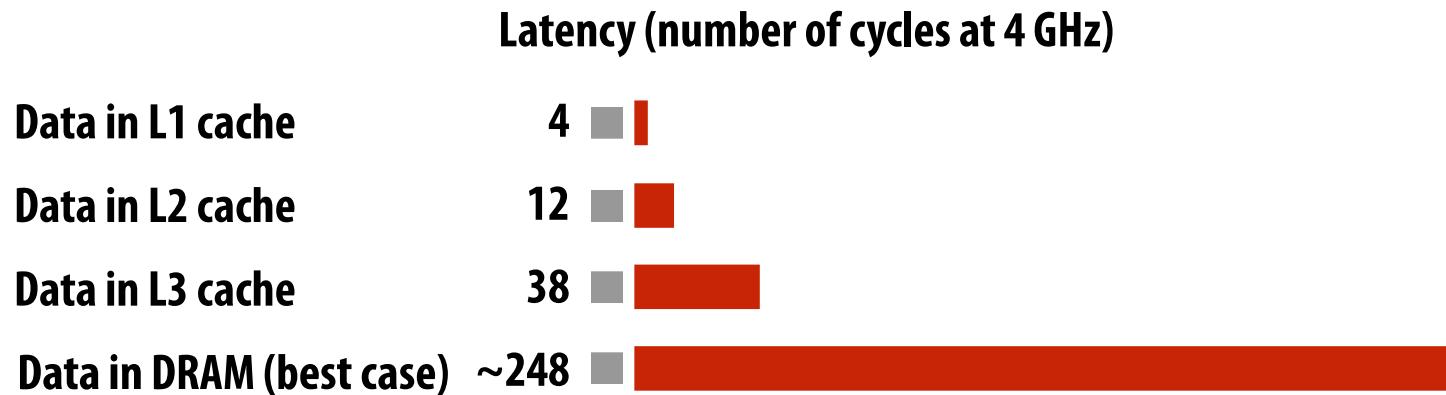
128 SIMD ALUs per "SM" (@1.6 GHz) = 16 TFLOPs (~250 Watts)

# Part 2: accessing memory



# Recall: [very] long latency of data access

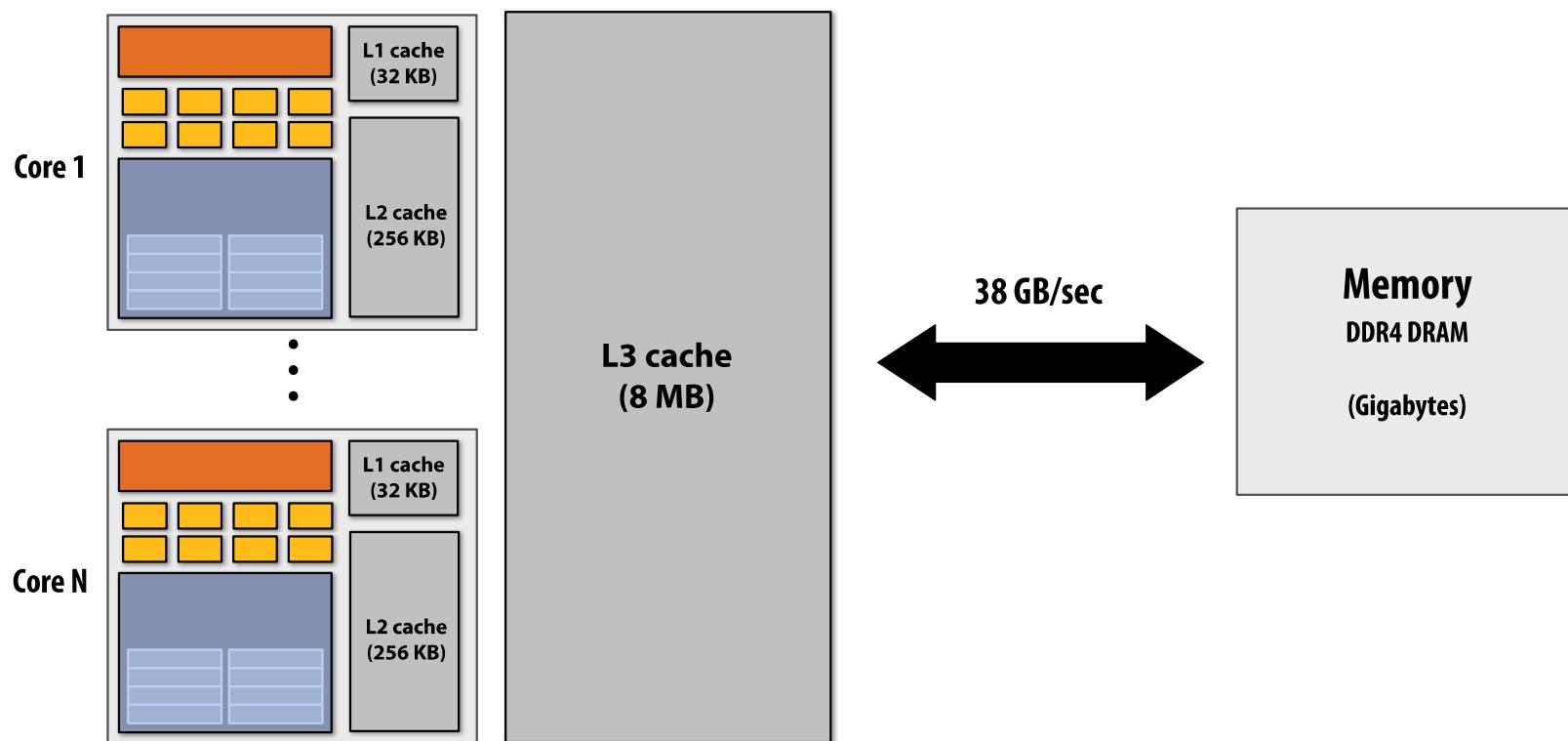
(Kaby Lake CPU)



# Caches reduce length of stalls (reduce memory access latency)

Processors run efficiently when they access data resident in caches

Caches reduce memory access latency **when accessing data that they have recently accessed!\***



\* Caches also provide high bandwidth data transfer

# Recall this access pattern

Program reads entire array of 16 bytes, then reads entire array again in the future.

Assume:

Total cache capacity = 8 bytes

Cache has 4-byte cache lines  
(So 2 lines fit in cache)

Least recently used (LRU)  
replacement policy

## Discussion Questions:

Why is there no “hit” on second read of address 0x0?

What about second read of address 0x4?

Would your answer change if the cache had a capacity of 4 lines?

Address accessed	Cache action
0x0	“cold miss”, load 0x0
0x1	hit
0x2	hit
0x3	hit
0x4	“cold miss”, load 0x4
0x5	hit
0x6	hit
0x7	hit
0x8	“cold miss”, load 0x8 (evict 0x0)
0x9	hit
0xA	hit
0xB	hit
0xC	“cold miss”, load 0xC (evict 0x4)
0xD	hit
0xE	hit
0xF	hit
0x0	“capacity miss”, load 0x0 (evict 0x8)

# Data prefetching reduces stalls (hides latency)

- Many modern CPUs have logic for guessing what data will be accessed in the future and “pre-fetching” this data into caches
  - Dynamically analyze program’s memory access patterns to make predictions
- Prefetching reduces stalls since data is resident in cache when accessed

```
predict value of r2, initiate load  
predict value of r3, initiate load
```

...

...

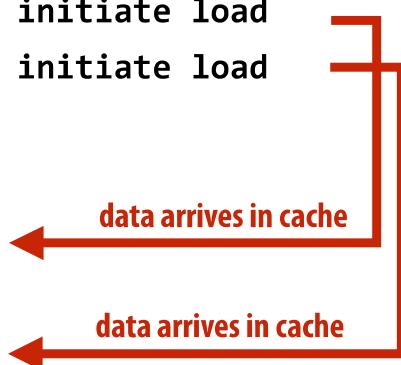
...

...

...

...

```
ld r0 mem[r2]  
ld r1 mem[r3]  
add r0, r0, r1
```



Note: Prefetching can also reduce performance if the guess is wrong (consumes bandwidth, pollutes caches)

**But what if data hasn't been read recently,  
so does not reside in cache?**

**And the next piece of data to  
read is not easily predictable?**

```
int x = some_function();  
int y = A[x];
```

**Consider doing your laundry...**



**Or cooking a meal...**



Credit: <https://www.theodysseyonline.com/the-dos-and-donts-of-dorm-laundry>

Image credit: <https://www.escoffier.edu/blog/food-entrepreneurship/culinary-side-hustles/>

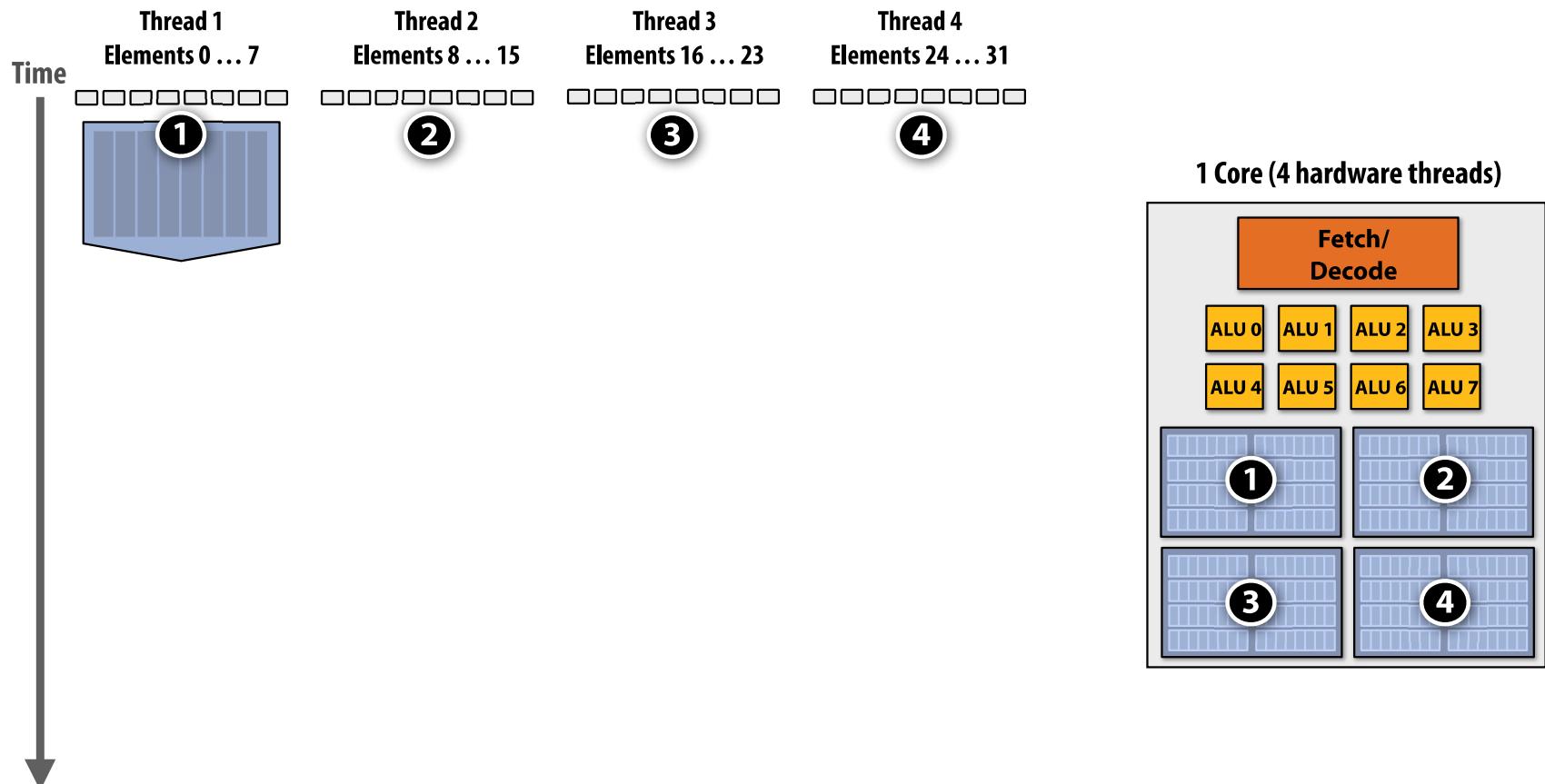
# Multi-threading reduces stalls

- Idea #3: interleave processing of multiple threads on the same core to hide stalls
  - If you can't make progress on the current thread... work on another one

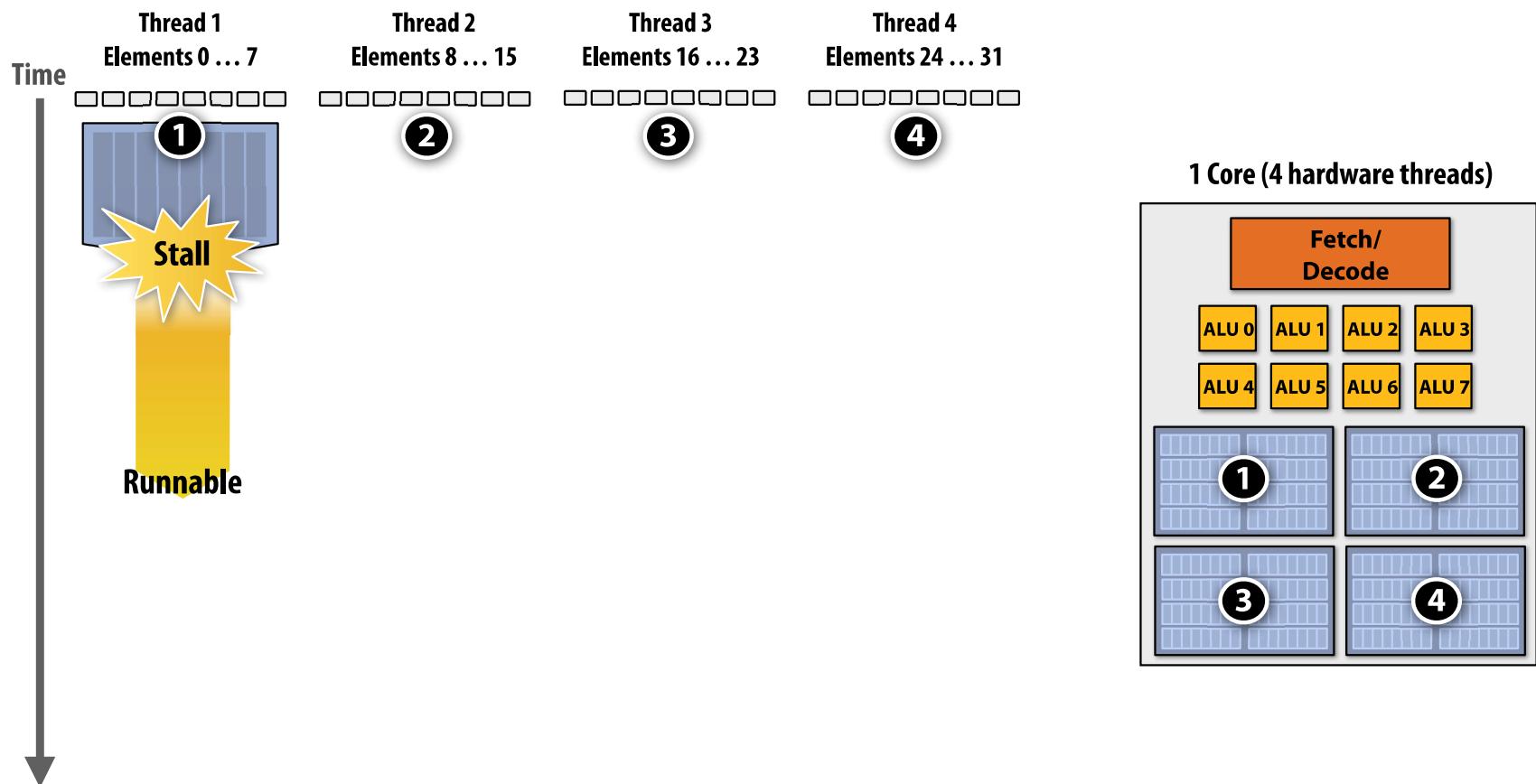
# Hiding stalls with multi-threading



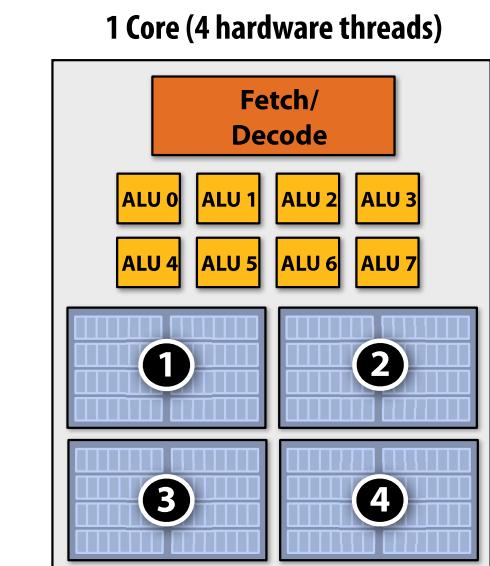
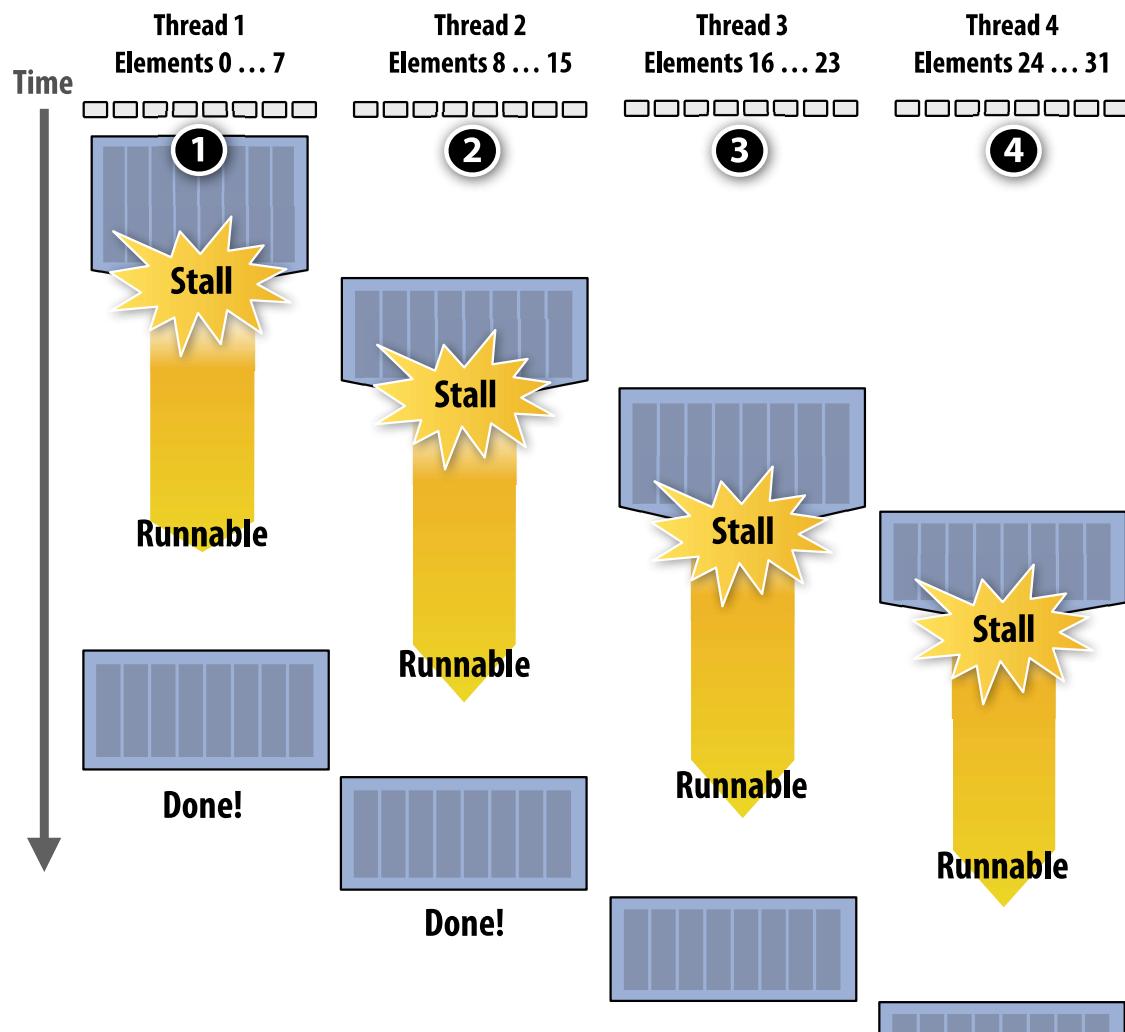
# Hiding stalls with multi-threading



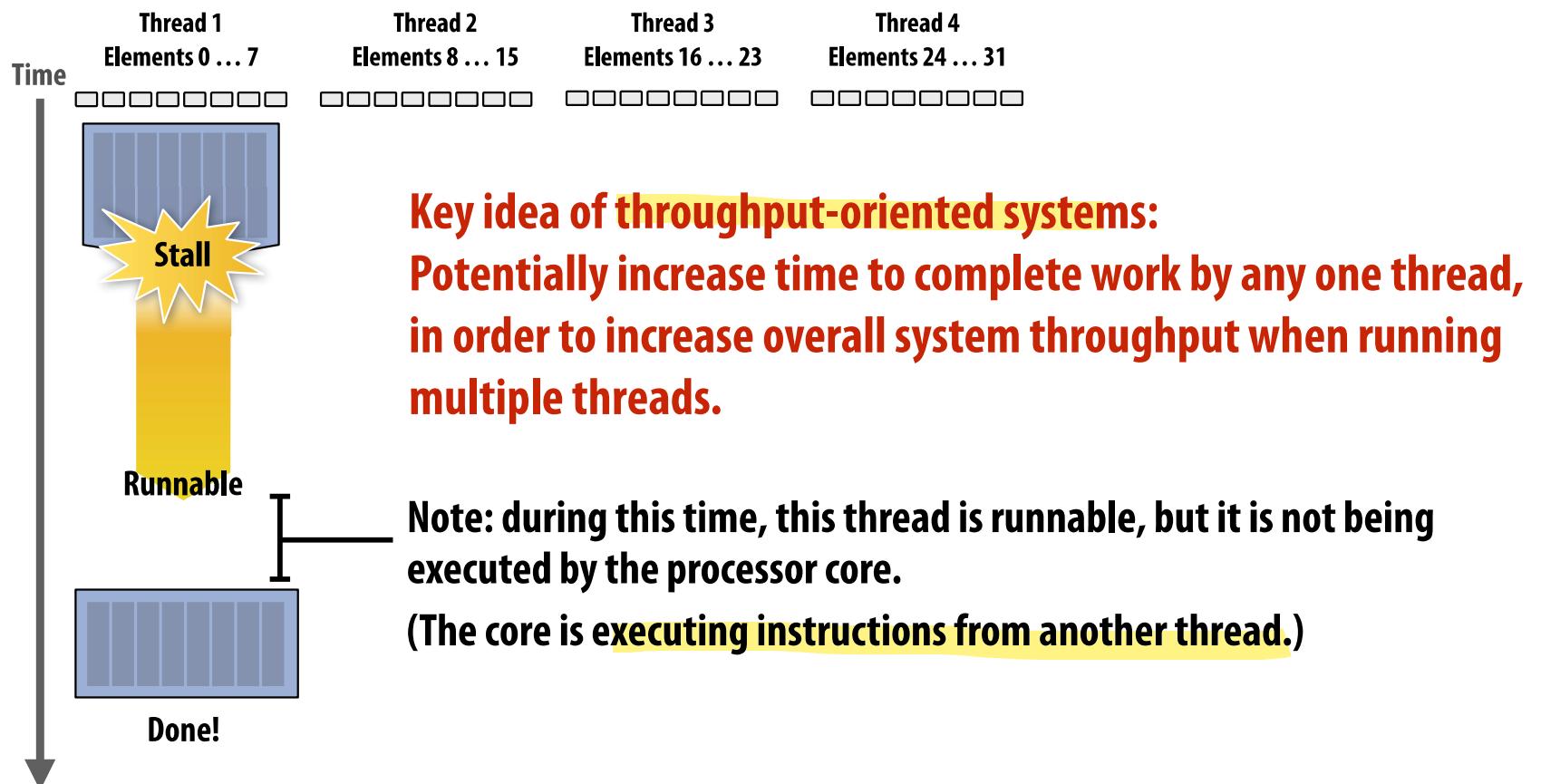
# Hiding stalls with multi-threading



# Hiding stalls with multi-threading

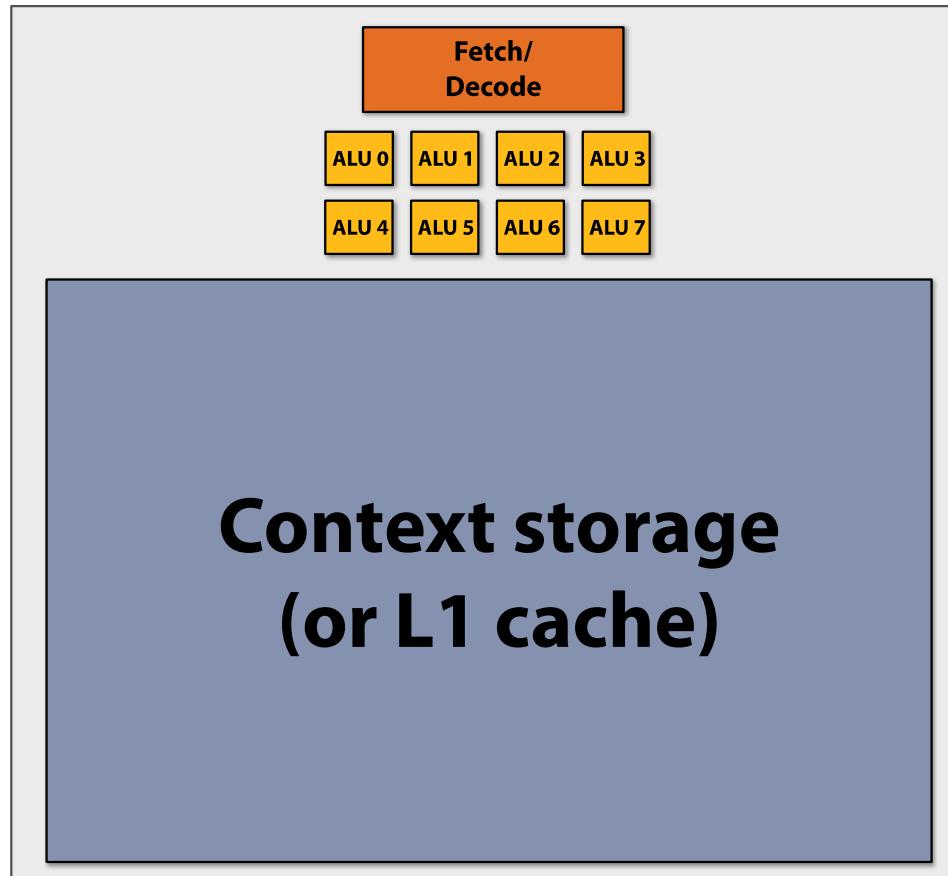


# Throughput computing: a trade-off



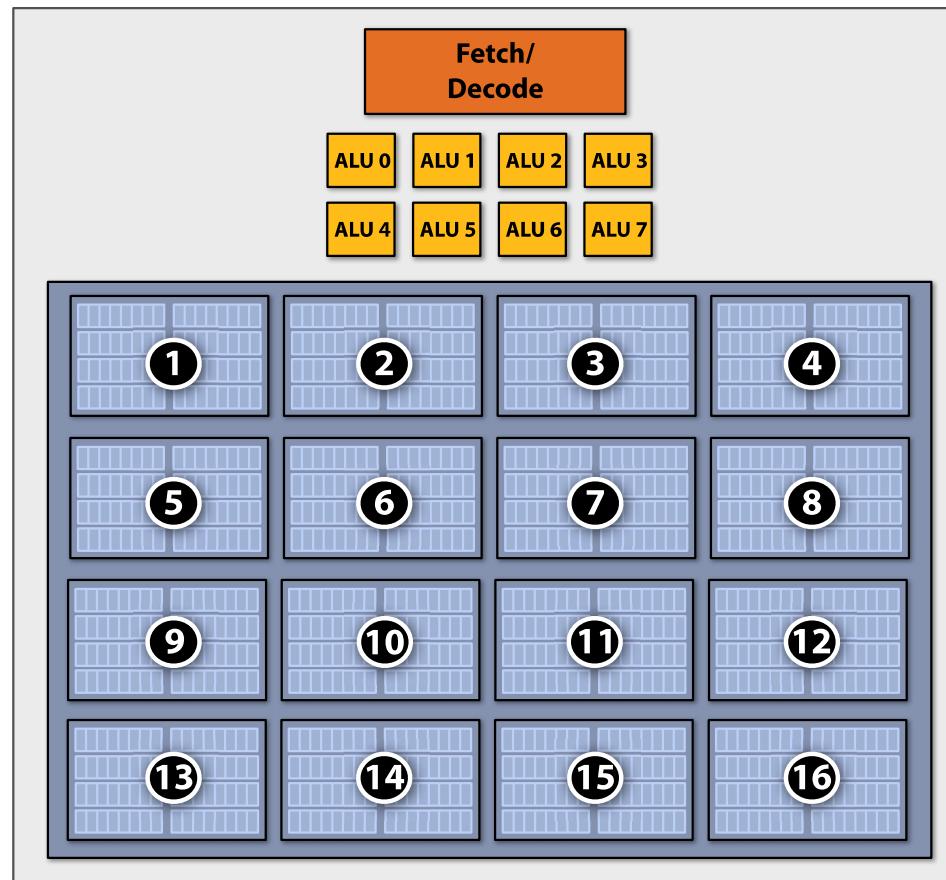
# No free lunch: storing execution contexts

Consider on-chip storage of execution contexts as a finite resource



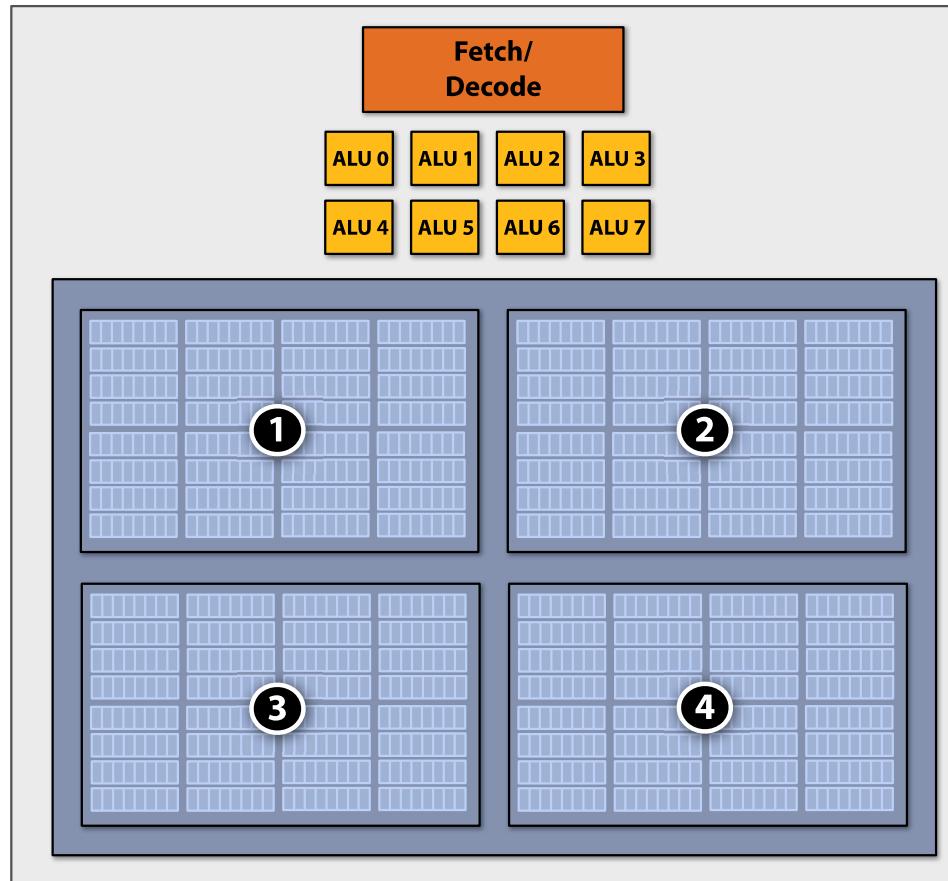
# Many small contexts (high latency hiding ability)

16 hardware threads: storage for small working set per thread

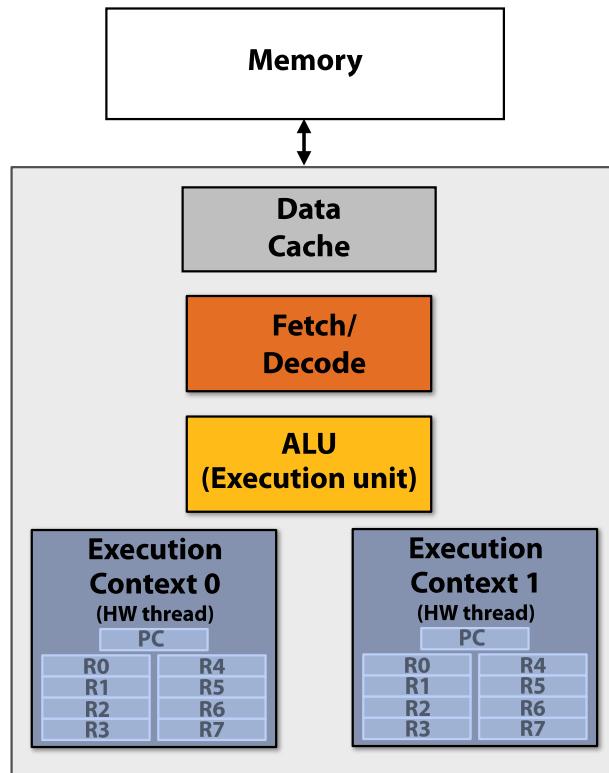


# Four large contexts (low latency hiding ability)

4 hardware threads: storage for large working set per thread

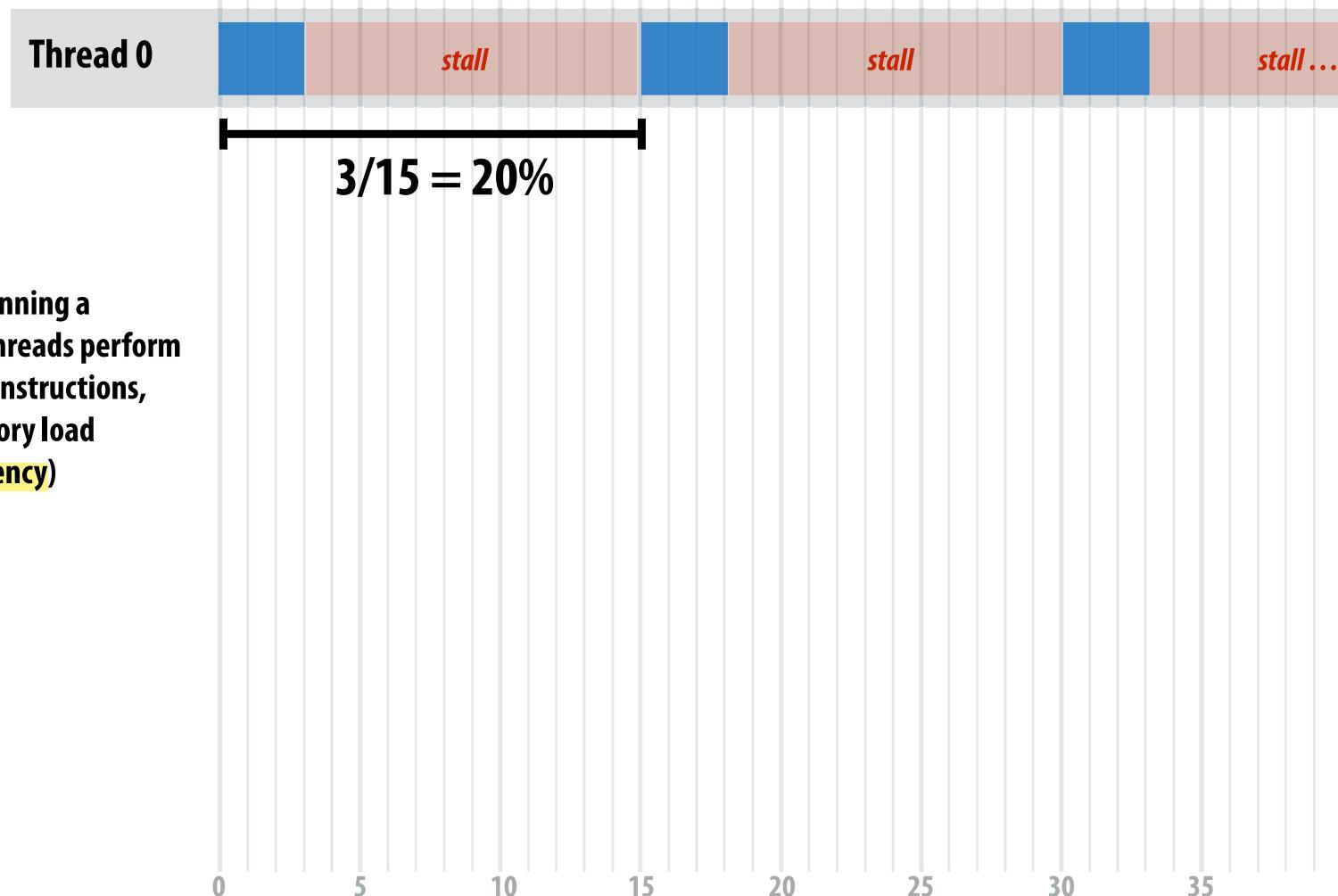


# Exercise: consider a simple two-threaded core



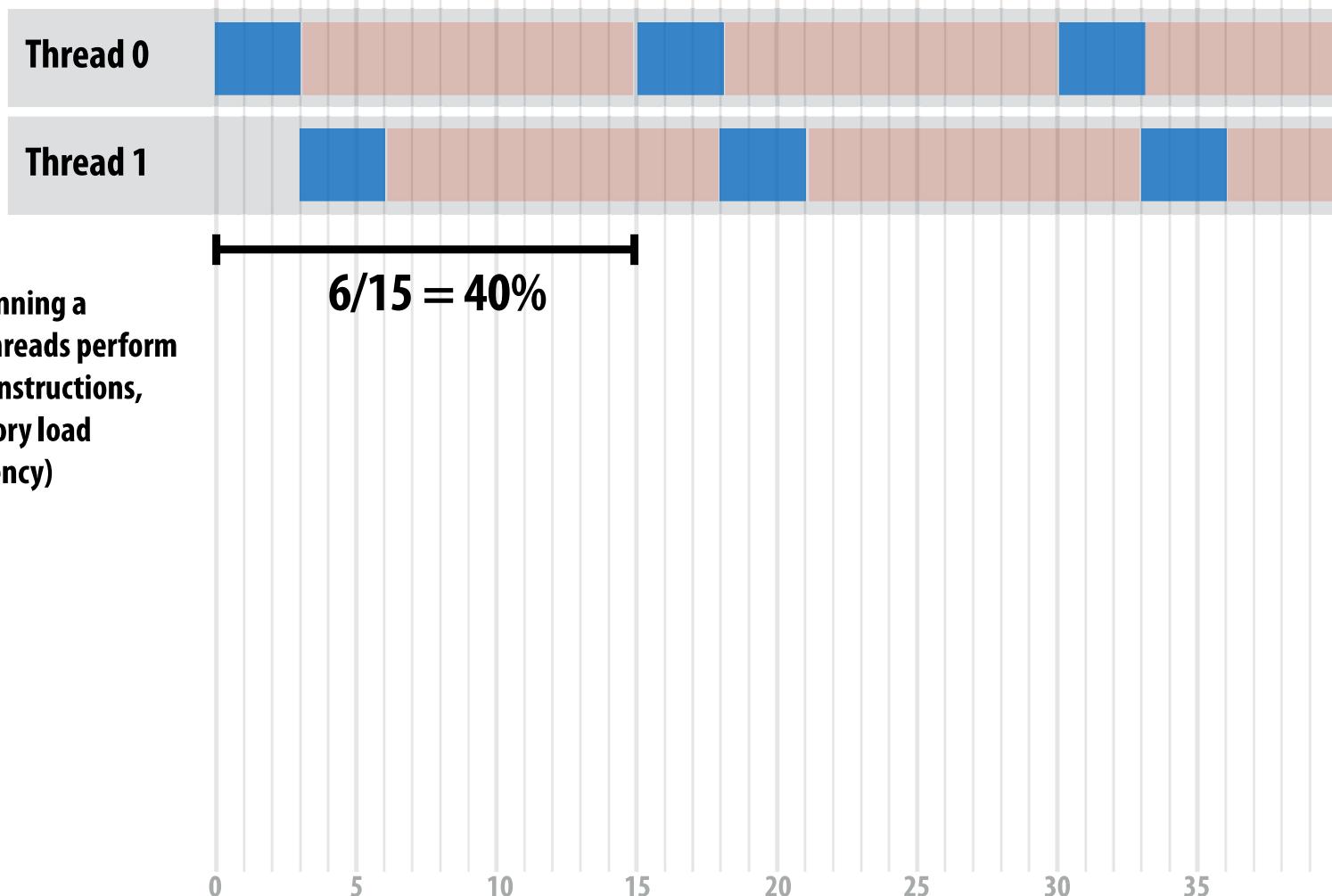
**Single core processor, multi-threaded core (2 threads).**  
**Can run one scalar instruction per clock from  
one of the hardware threads**

# What is the utilization of the core? (one thread)



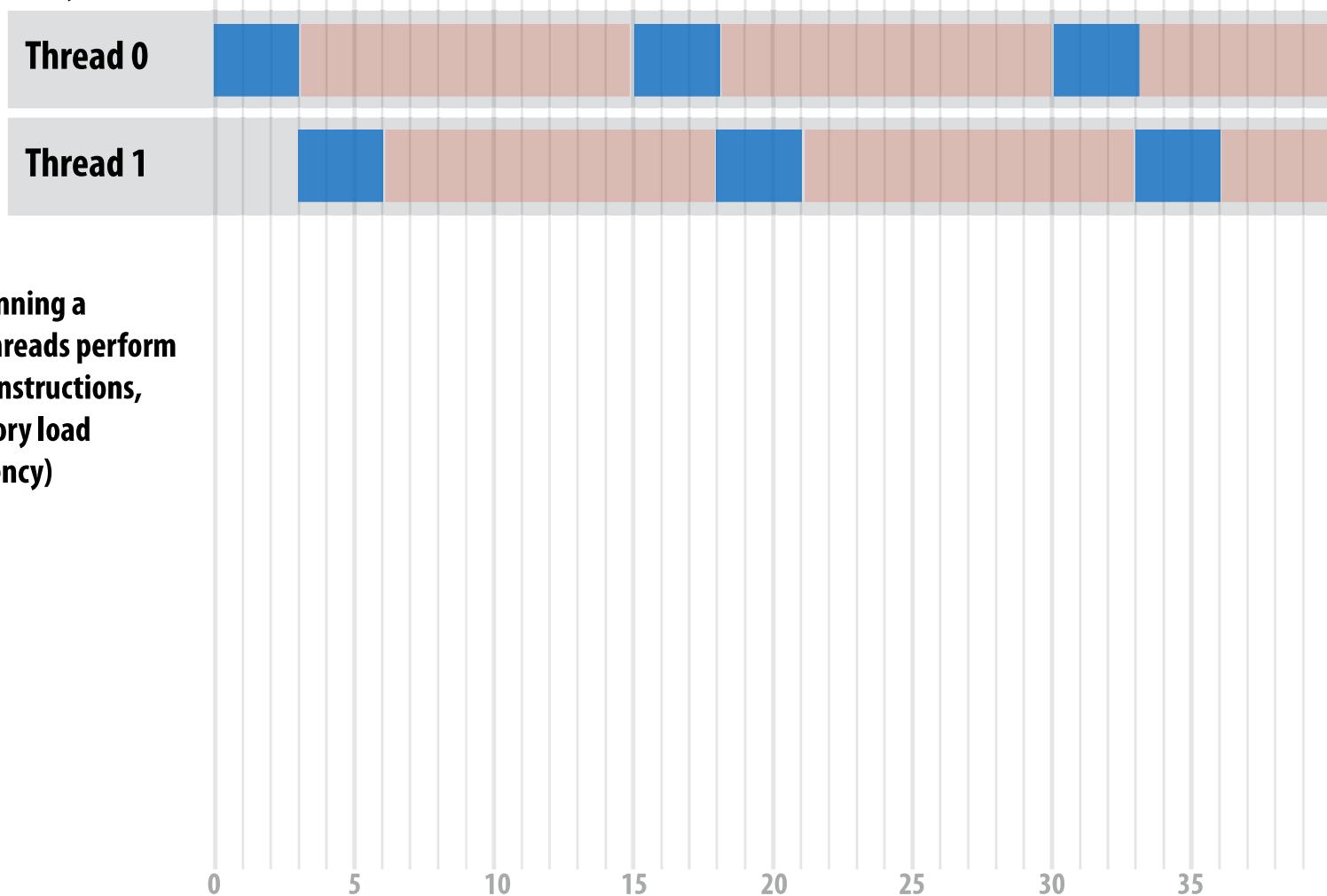
Assume we are running a program where threads perform three arithmetic instructions, followed by memory load (with **12 cycle latency**)

# What is the utilization of the core? (two threads)



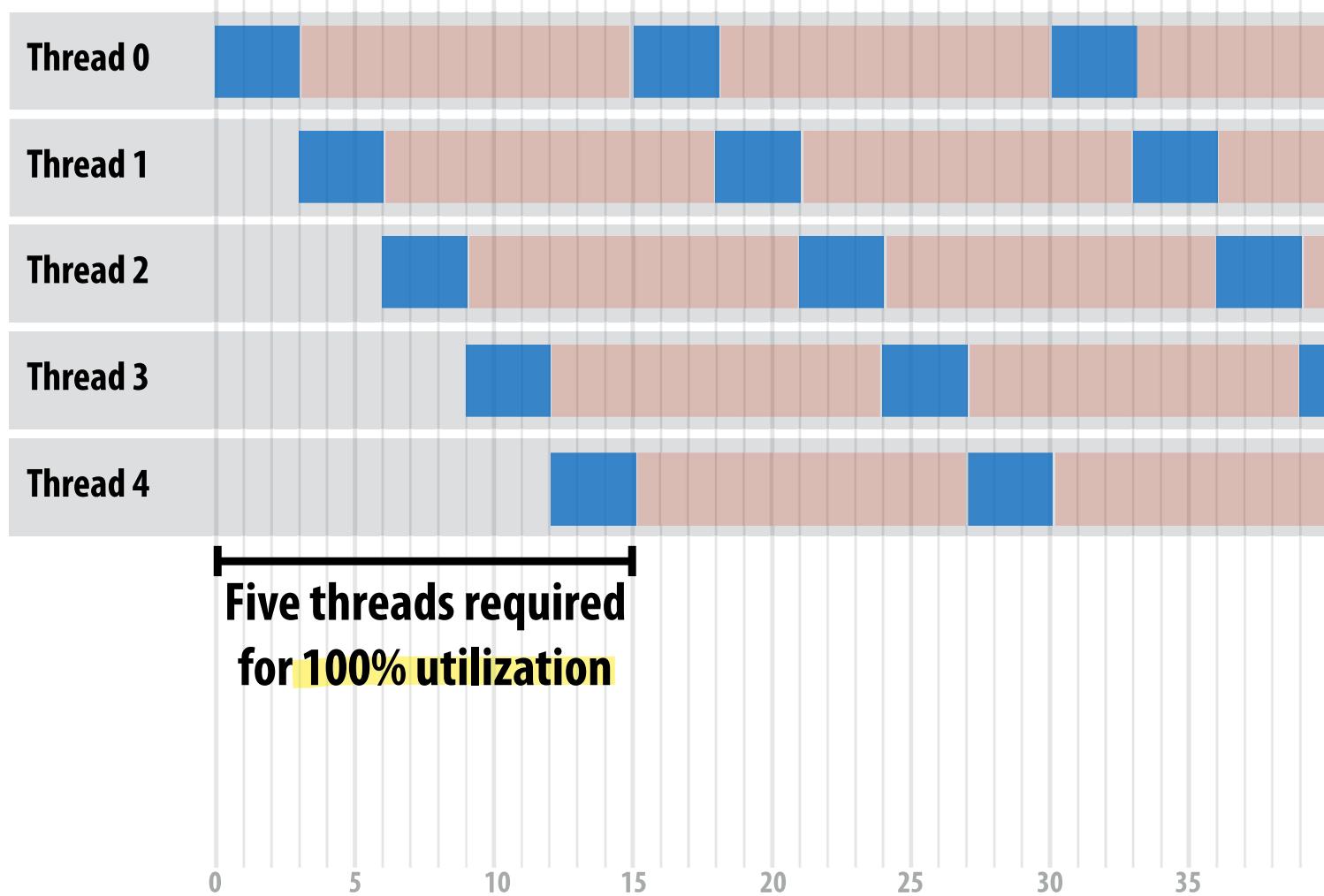
Assume we are running a program where threads perform three arithmetic instructions, followed by memory load (with 12 cycle latency)

# How many threads are needed to achieve 100% utilization?

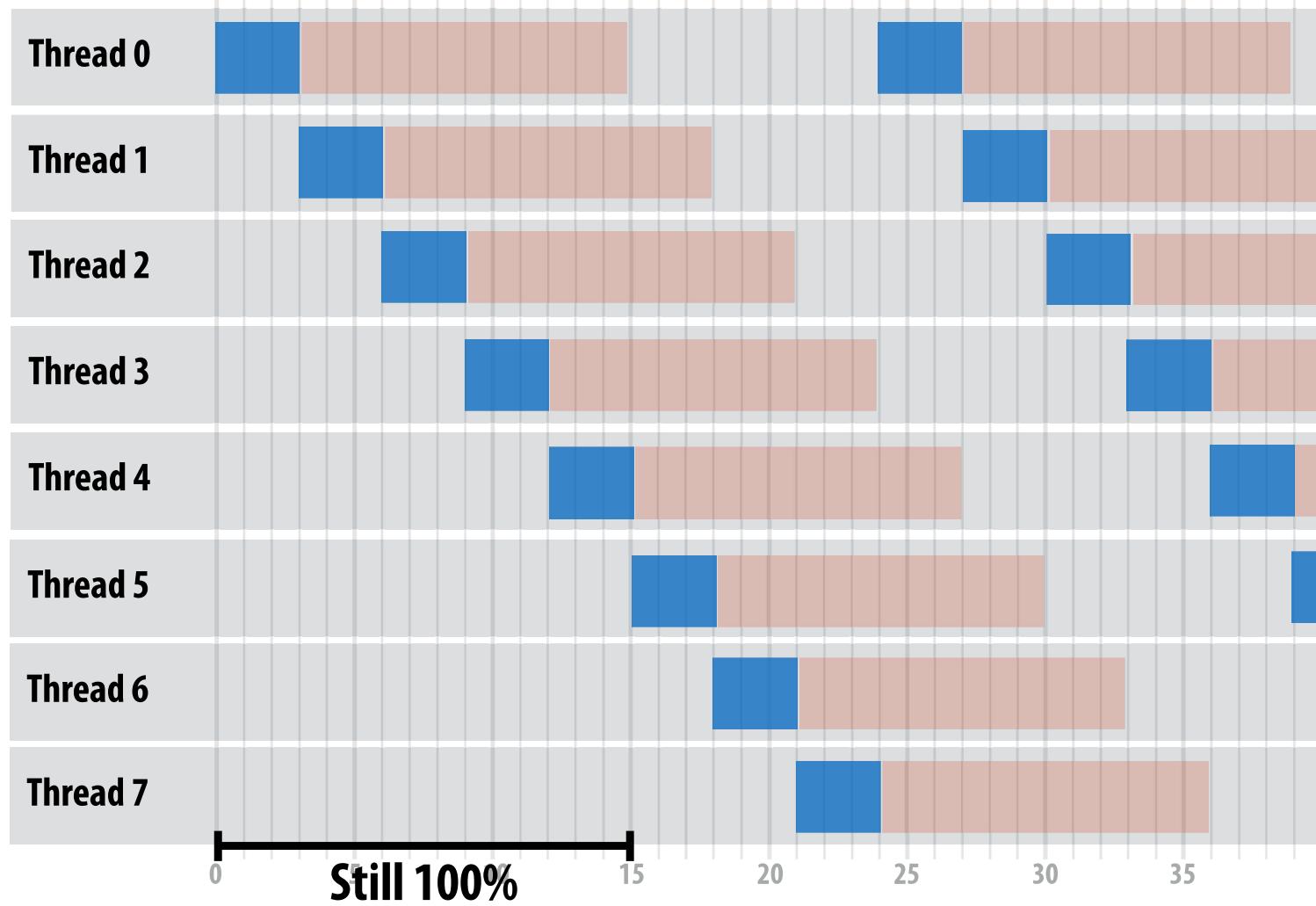


Assume we are running a program where threads perform three arithmetic instructions, followed by memory load (with 12 cycle latency)

# Five threads needed to obtain 100% utilization

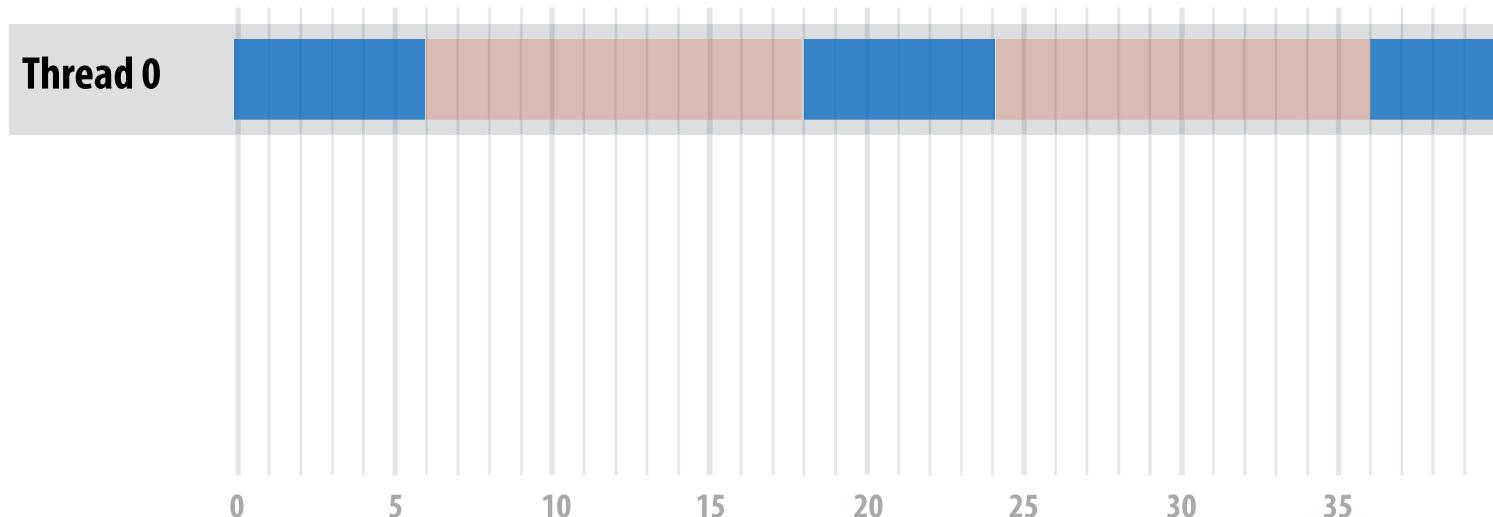


# Additional threads yield no benefit (already 100% utilization)



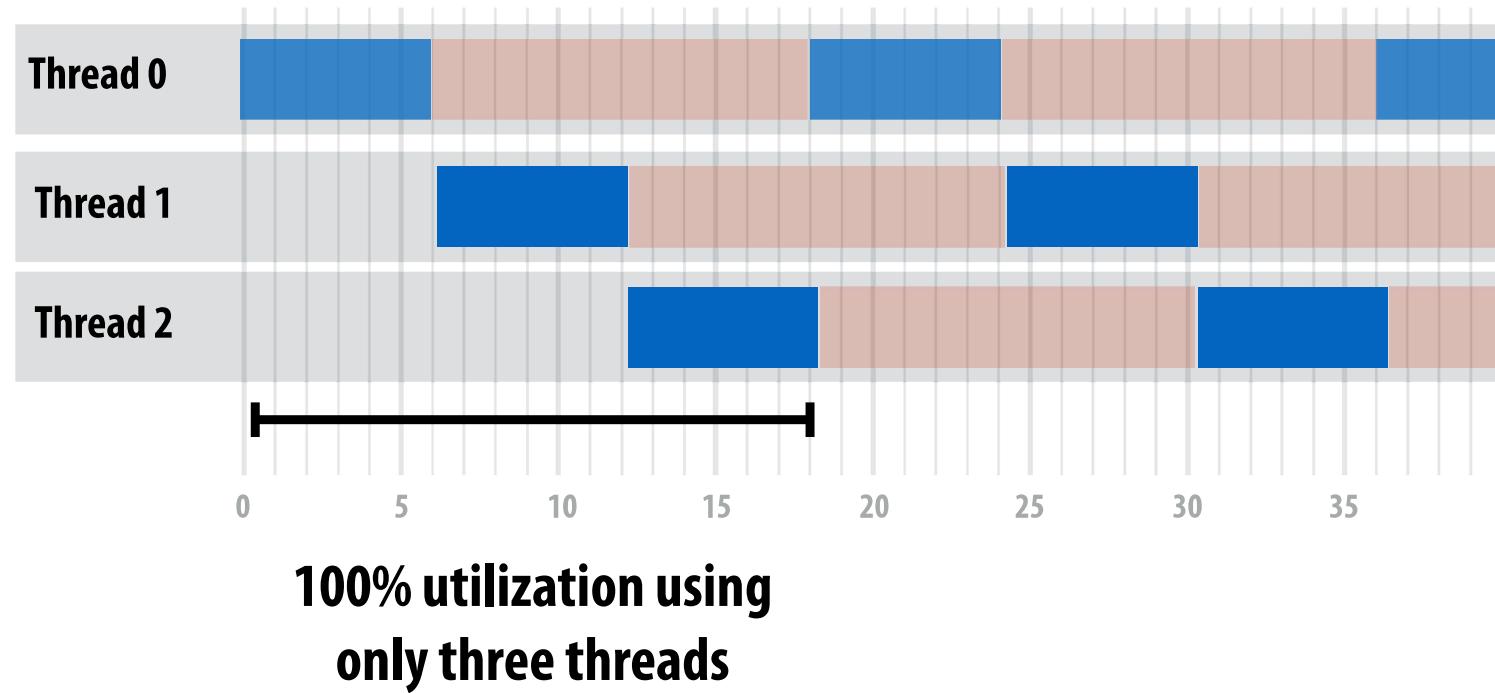
# How many threads are needed to achieve 100% utilization?

Threads now perform *six arithmetic instructions*, followed by memory load (with 12 cycle latency)



# Now only three threads needed for 100% utilization?

Threads now perform *six arithmetic instructions*, followed by memory load (with 12 cycle latency)



How does a **higher ratio of math instructions to memory latency** affect the number of threads needed for latency hiding?

# Takeaway (point 1):

A processor with multiple hardware threads has the ability to *avoid stalls* by performing instructions from other threads when one thread must wait for a long latency operation to complete.

Note: the latency of the memory operation is not changed by multi-threading, it just no longer causes reduced processor utilization.

# Takeaway (point 2):

A multi-threaded processor **hides memory latency by performing arithmetic from other threads.**

**Programs that feature more arithmetic per memory access need fewer threads to hide memory stalls.**

# Hardware-supported multi-threading

- Core manages execution contexts for multiple threads
  - Core still has the same number of ALU resources: multi-threading only helps use them more efficiently in the face of high-latency operations like memory access
  - Processor makes decision about which thread to run each clock
- Interleaved multi-threading (a.k.a. temporal multi-threading)
  - What I described on the previous slides: each clock, the core chooses a thread, and runs an instruction from the thread on the core's ALUs
- Simultaneous multi-threading (SMT)
  - Each clock, core chooses instructions from multiple threads to run on ALUs
  - Example: Intel Hyper-threading (2 threads per core)
  - See "going further videos" provided online

# Kayvon's fictitious multi-core chip

**16 cores**

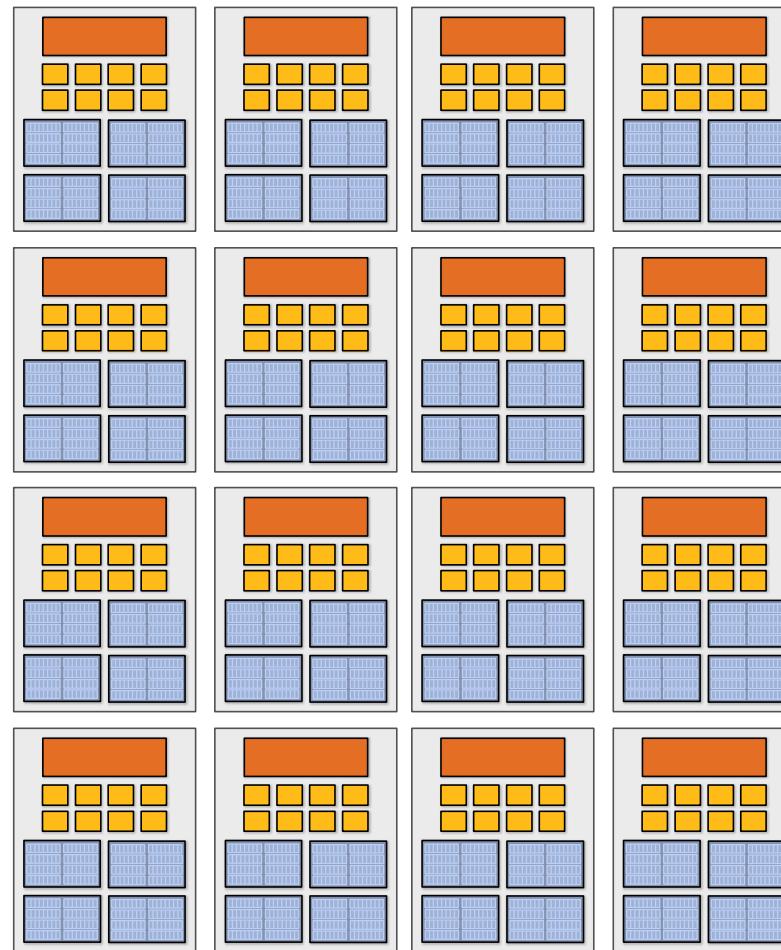
**8 SIMD ALUs per core  
(128 total)**

**4 threads per core**

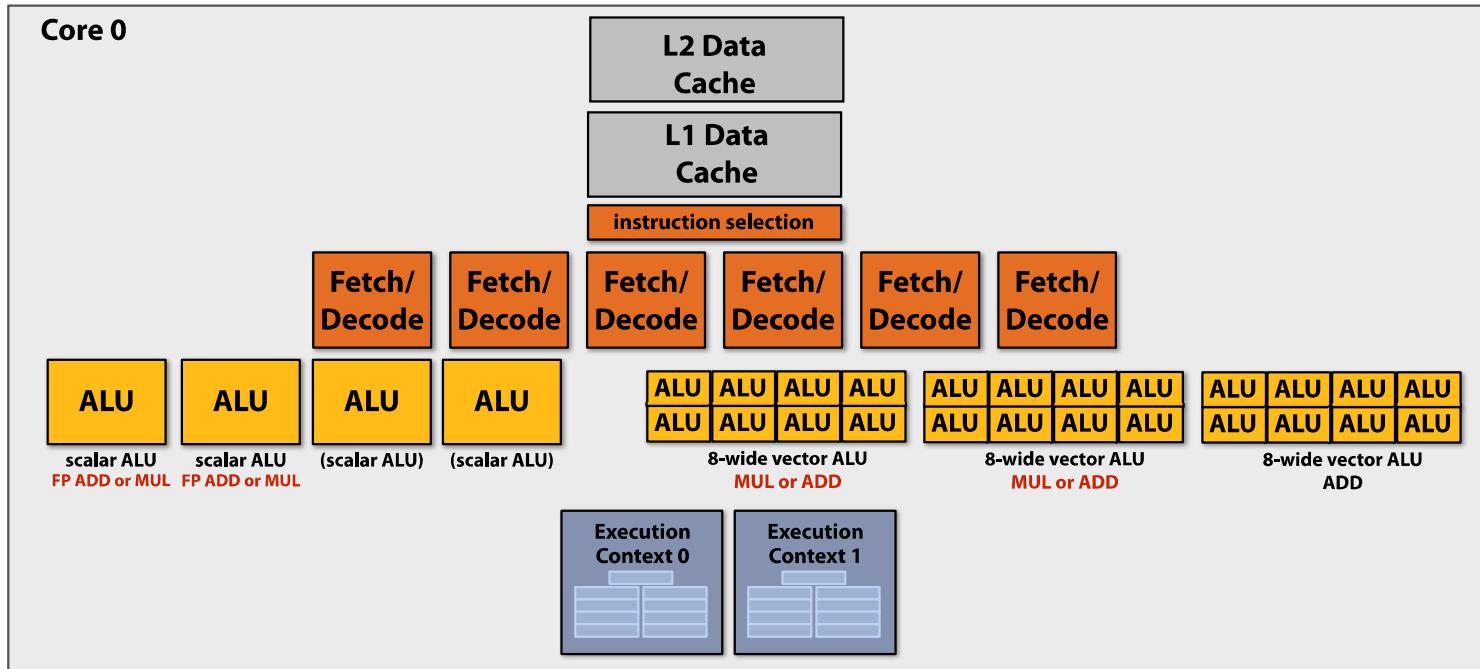
**16 simultaneous  
instruction streams**

**64 total concurrent  
instruction streams**

**512 independent pieces of  
work are needed to run chip  
with maximal latency  
hiding ability**



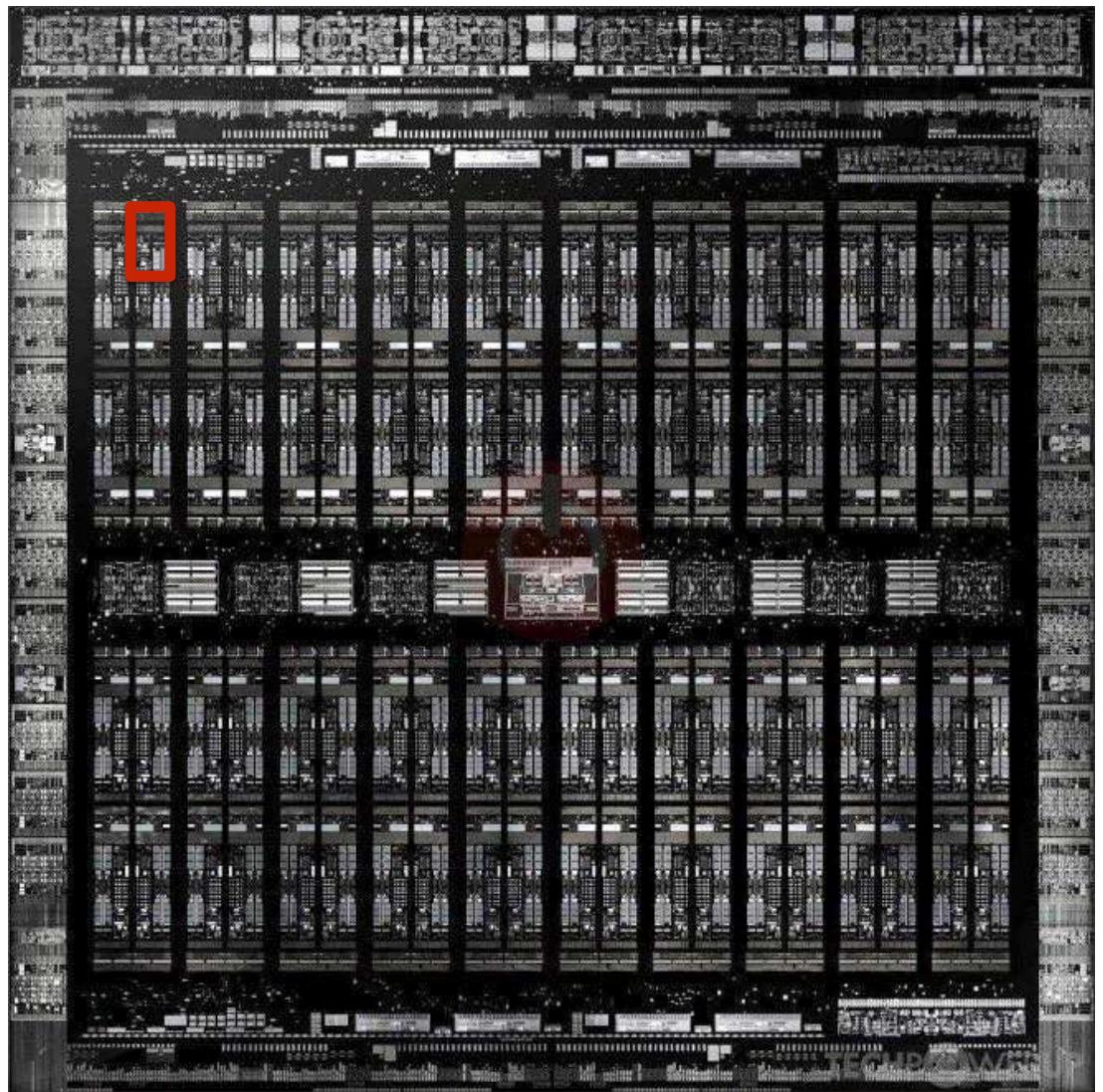
# Example: Intel Skylake/Kaby Lake core



**Two-way multi-threaded cores (2 threads).**  
**Each core can run up to four independent scalar instructions**  
**and up to three 8-wide vector instructions**  
**(up to 2 vector mul or 3 vector add)**

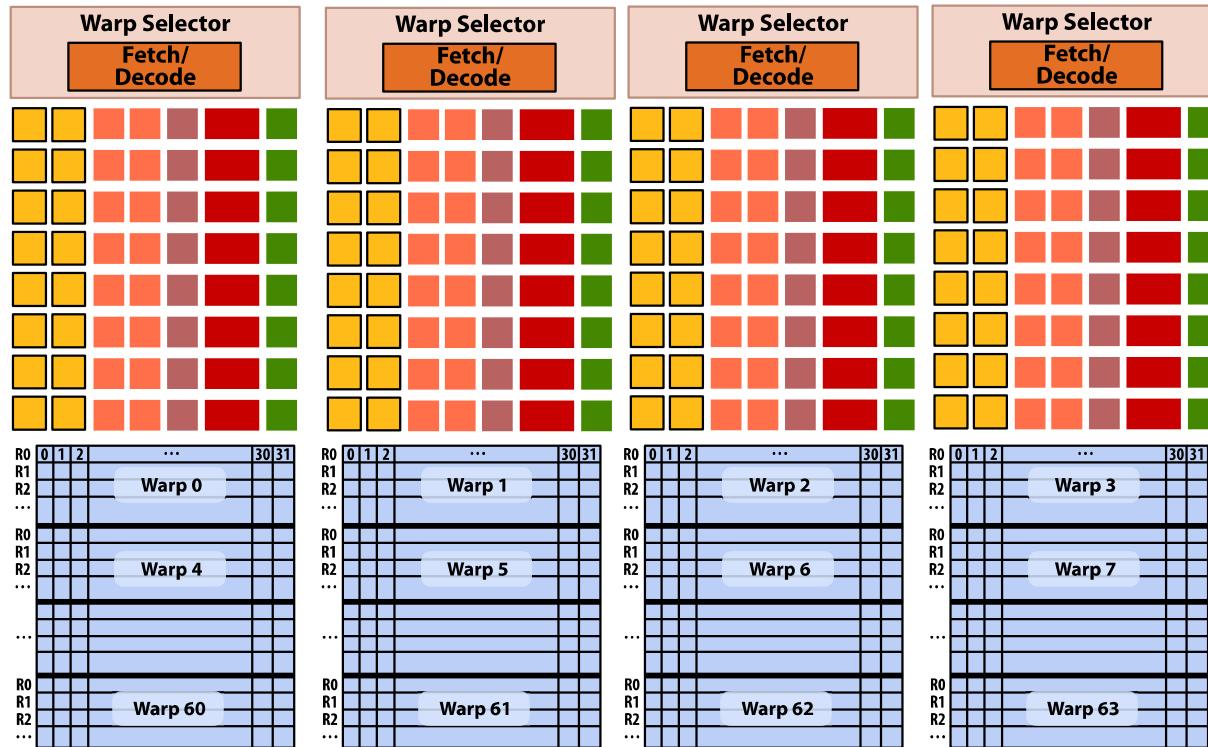
# NVIDIA V100

- SM = “Streaming Multi-processor”



# GPUs: extreme throughput-oriented processors

This is one NVIDIA V100 streaming multi-processor (SM) unit



64 “warp” execution contexts per SM

Wide SIMD: 16-wide SIMD ALUs (carry out 32-wide SIMD execute over 2 clocks)

64 x 32 = up to 2048 data items processed concurrently per “SM” core

64 KB registers per sub-core

256 KB registers in total per SM

Registers divided among (up to) 64 “warps” per SM

- = SIMD fp32 functional unit, control shared across 16 units (16 x MUL-ADD per clock \*)
- = SIMD int functional unit, control shared across 16 units (16 x MUL/ADD per clock \*)
- = SIMD fp64 functional unit, control shared across 8 units (8 x MUL/ADD per clock \*\*)
- = Tensor core unit
- = Load/store unit

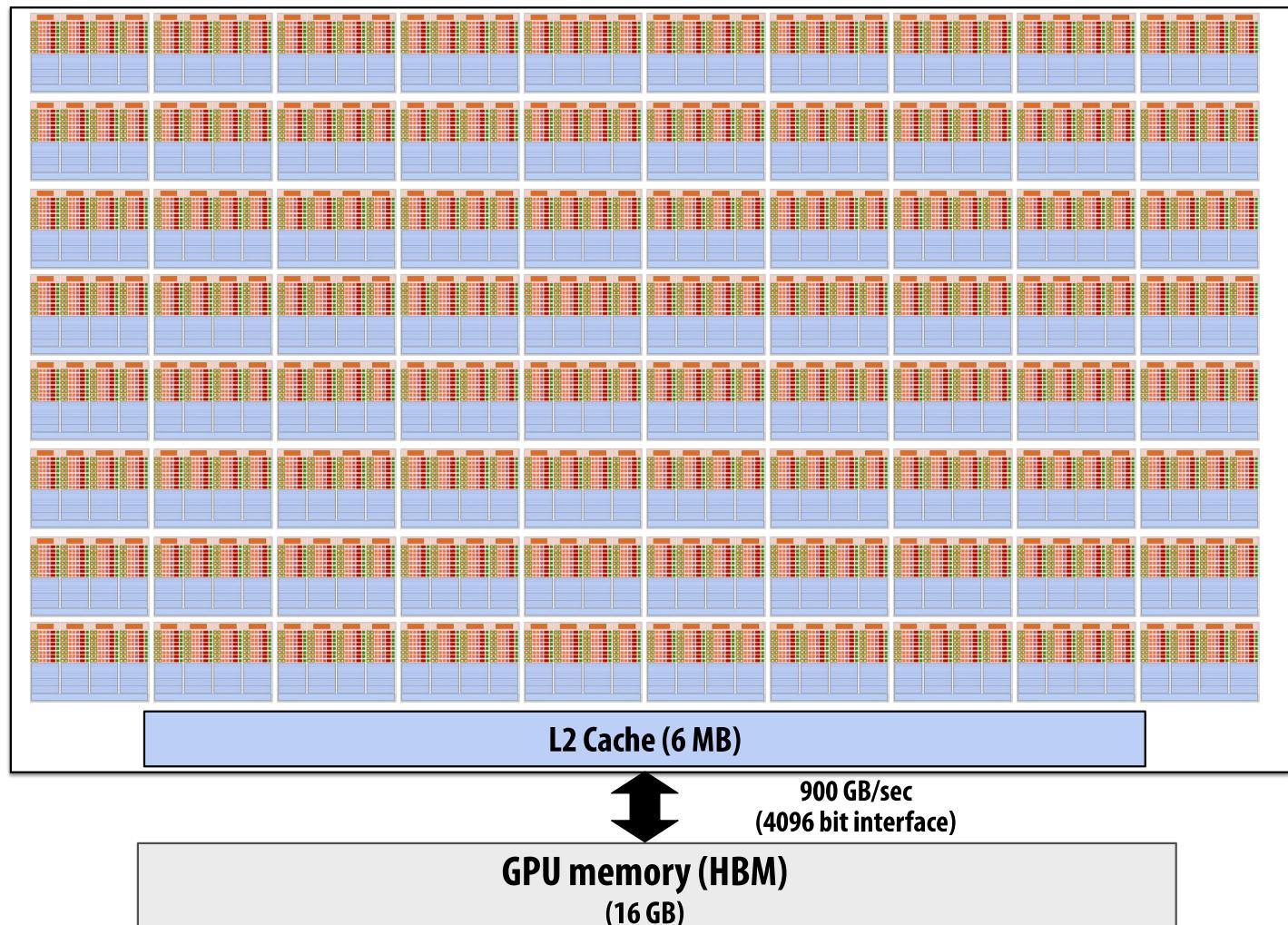
\* one 32-wide SIMD operation every 2 clocks

\*\* one 32-wide SIMD operation every 4 clocks

# NVIDIA V100

There are **80 SM cores** on the V100:

That's **163,840 pieces of data** being processed concurrently to get maximal latency hiding!



# The story so far...

To utilize modern parallel processors efficiently, an application must:

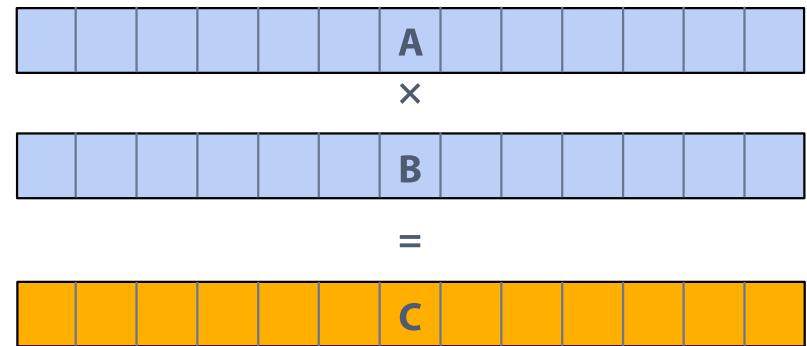
1. Have sufficient parallel work to utilize all available execution units (across many cores and many execution units per core)
2. Groups of parallel work items must require the same sequences of instructions (to utilize SIMD execution)
3. Expose more parallel work than processor ALUs to enable interleaving of work to hide memory stalls

# Thought experiment

**Task: element-wise multiplication of two vectors A and B**

**Assume vectors contain millions of elements**

- Load input  $A[i]$
- Load input  $B[i]$
- Compute  $A[i] \times B[i]$
- Store result into  $C[i]$



**Is this a good application to run on a modern throughput-oriented parallel processor?**



**To answer this question, we first have to  
understand the difference between  
latency and bandwidth**

**(We'll start there next time)**

# Suggestion to students: know these terms

- **Instruction stream**
- **Multi-core processor**
- **SIMD execution**
- **Coherent control flow**
- **Hardware multi-threading**
  - **Interleaved multi-threading**
  - **Simultaneous multi-threading**

Bonus slides:

# REVIEW

## HOW IT ALL FITS TOGETHER:

**superscalar execution,**  
**SIMD execution,**  
**multi-core execution,**  
and **hardware multi-threading**

(If you understand this sequence you understand lecture 2)

# Running code on a simple processor

## C program source

```
void sinx(int N, int terms, float* x, float* y)
{
    for (int i=0; i<N; i++)
    {
        float value = x[i];
        float numer = x[i] * x[i] * x[i];
        int denom = 6; // 3!
        int sign = -1;

        for (int j=1; j<=terms; j++)
        {
            value += sign * numer / denom;
            numer *= x[i] * x[i];
            denom *= (2*j+2) * (2*j+3);
            sign *= -1;
        }

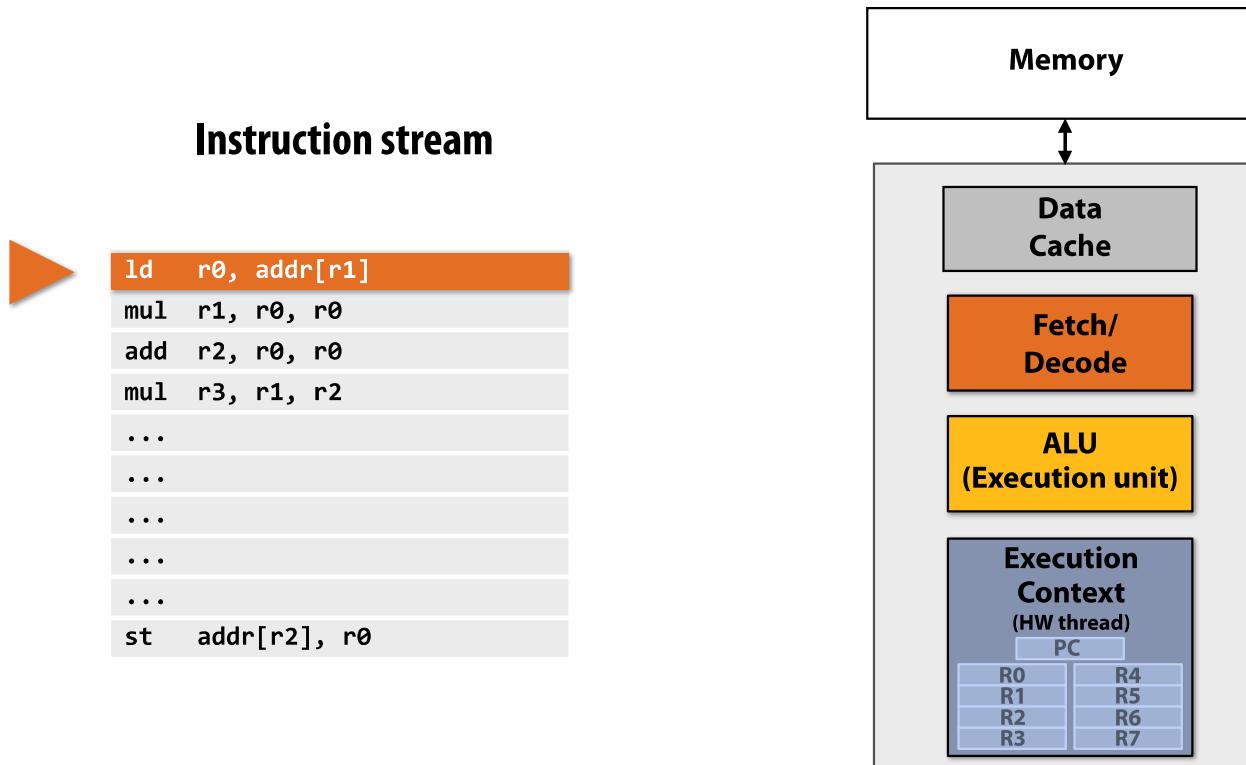
        y[i] = value;
    }
}
```

compiler

## Compiled instruction stream (scalar instructions)

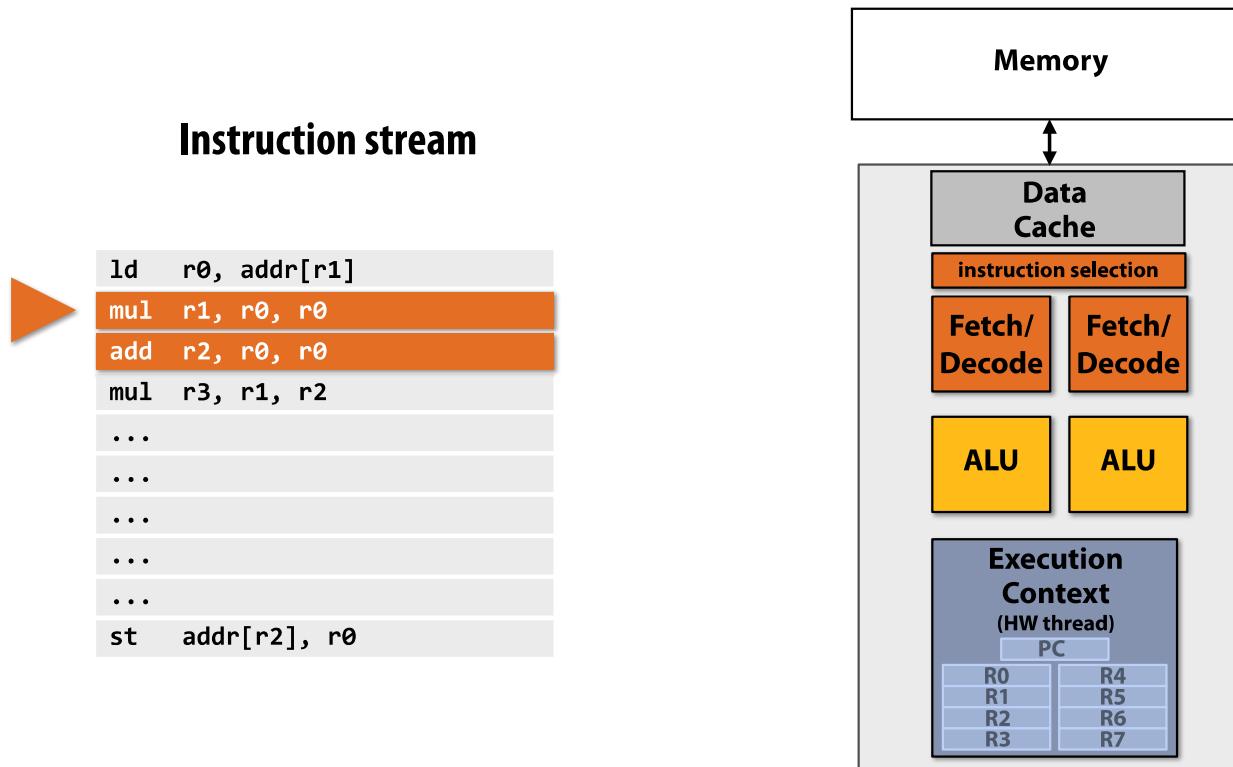
ld r0, addr[r1]
mul r1, r0, r0
add r2, r0, r0
mul r3, r1, r2
...
...
...
...
...
st addr[r2], r0

# Running code on a simple processor



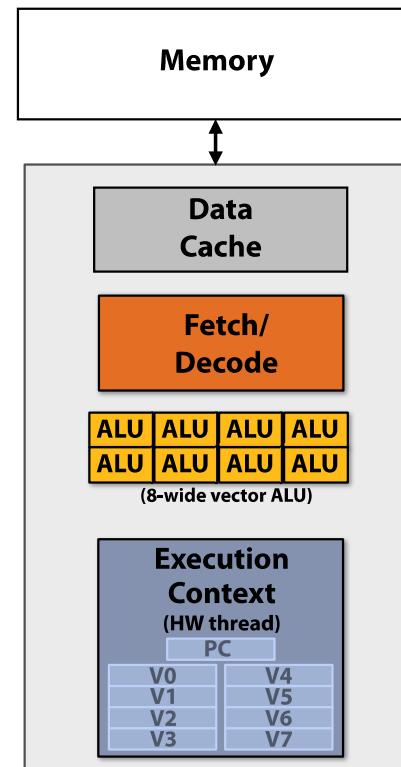
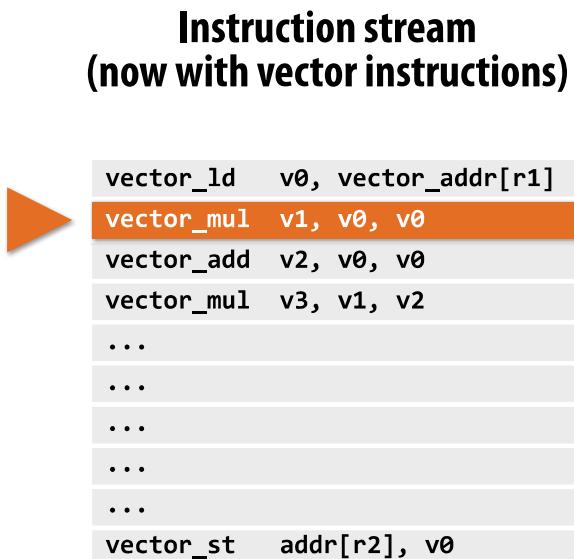
Single core processor, single-threaded core.  
Can run one scalar instruction per clock

# Superscalar core



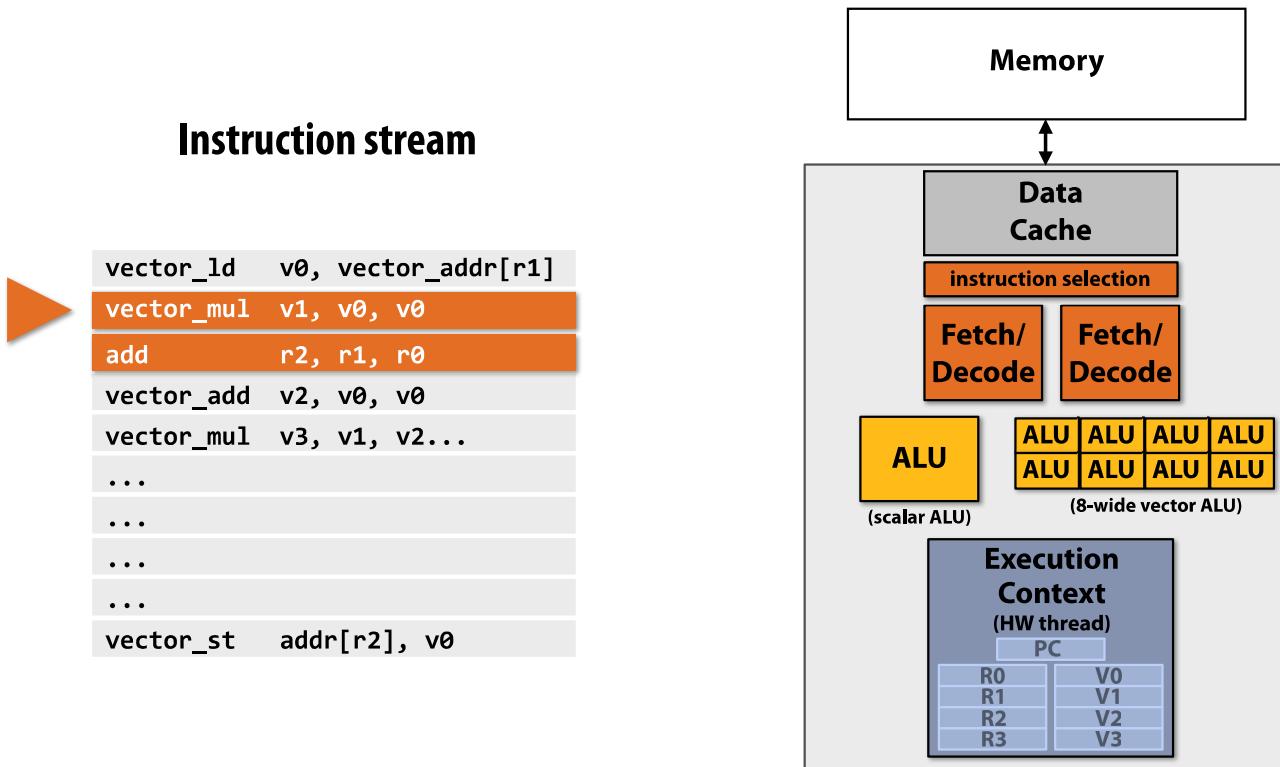
Single core processor, single-threaded core.  
Two-way superscalar core:  
can run up to two independent scalar instructions  
per clock from one instruction stream (one hardware thread)

# SIMD execution capability



Single core processor, single-threaded core.  
can run one **8-wide SIMD vector instruction** from  
one instruction stream

# Heterogeneous superscalar (scalar + SIMD)



Single core processor, single-threaded core.

Two-way superscalar core:

can run up to two independent instructions per clock from one instruction stream, provided one is scalar and the other is vector

# Multi-threaded core

Instruction stream 0

```
ld r0, addr[r1]  
mul r1, r0, r0  
add r2, r0, r0  
mul r3, r1, r2  
...  
...  
...  
...  
...  
st addr[r2], r0
```

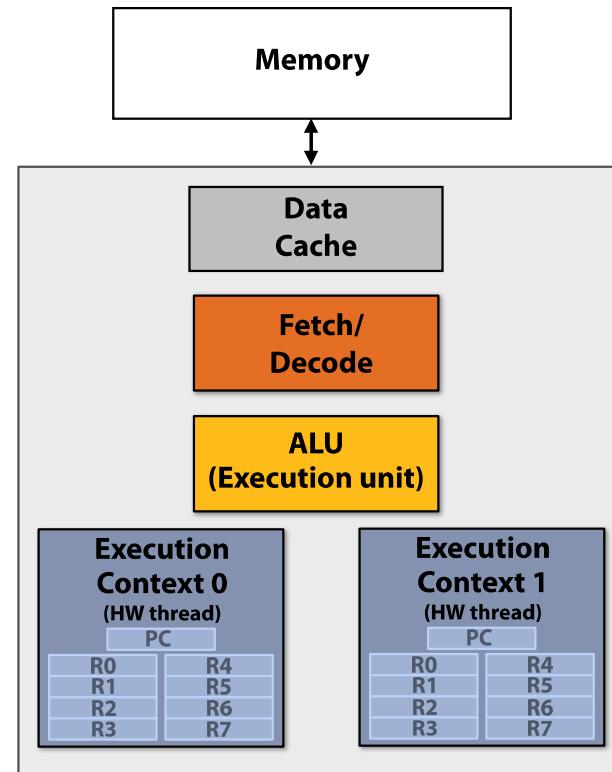
Instruction stream 1

```
ld r0, addr[r1]  
sub r1, r0, r0  
add r2, r1, r0  
mul r5, r1, r0  
...  
...  
...  
...  
...  
st addr[r2], r0
```



Note: threads can be running completely different instruction streams (and be at different points in these streams)

Execution of hardware threads is interleaved in time.



Single core processor, multi-threaded core (2 threads).  
Can run one scalar instruction per clock from  
one of the instruction streams (hardware threads)

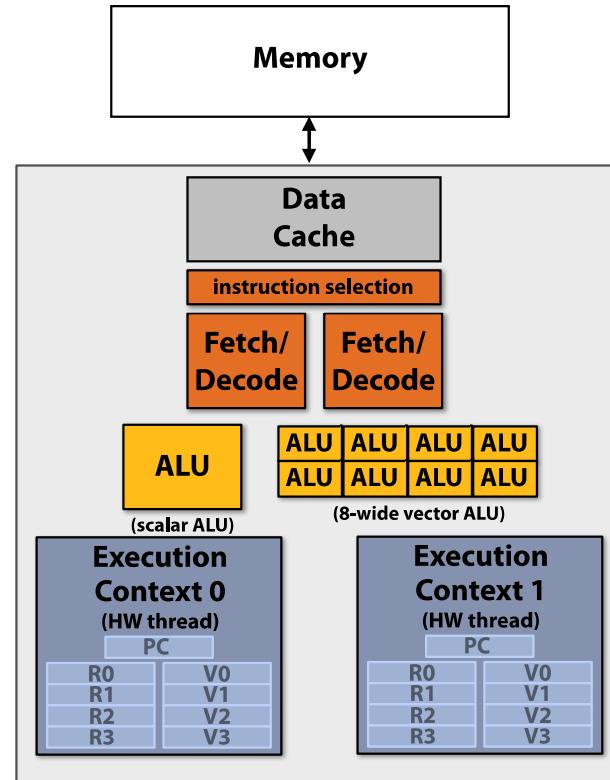
# Multi-threaded, superscalar core

Instruction stream 0

```
vector_ld  v0, addr[r1]
vector_mul v1, v0, v0
vector_add v2, v1, v1
mul      r2, r1, r1
...
...
...
...
...
vector_st  addr[r2], v0
```

Instruction stream 1

```
vector_ld  v0, addr[r1]
sub      r1, r0, r0
vector_add v2, v0, v0
mul      r5, r1, r0
...
...
...
...
rect     addr[r2], v0
```



Note: threads can be running completely different instruction streams (and be at different points in these streams)

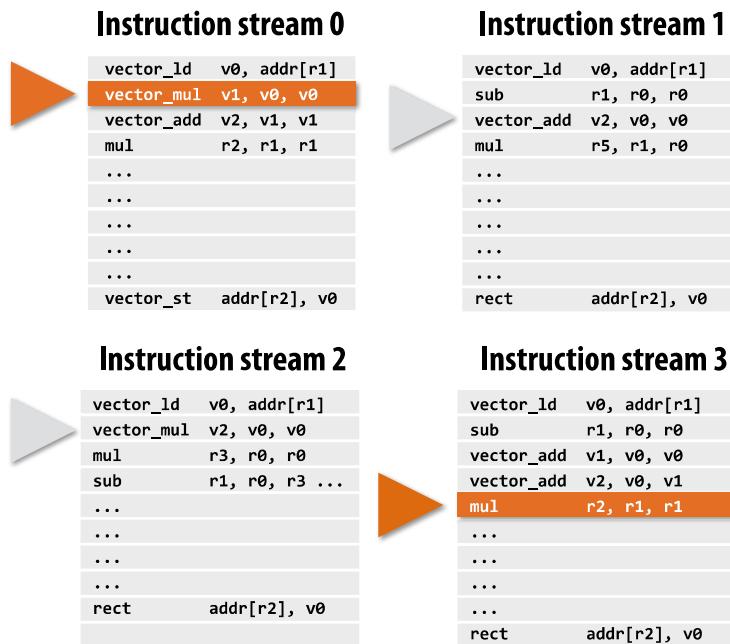
Execution of hardware threads is interleaved in time.

\* This detail was an arbitrary decision on this slide:  
a different implementation of "instruction selection" might run two  
instructions where one is drawn from each thread, see next slide.

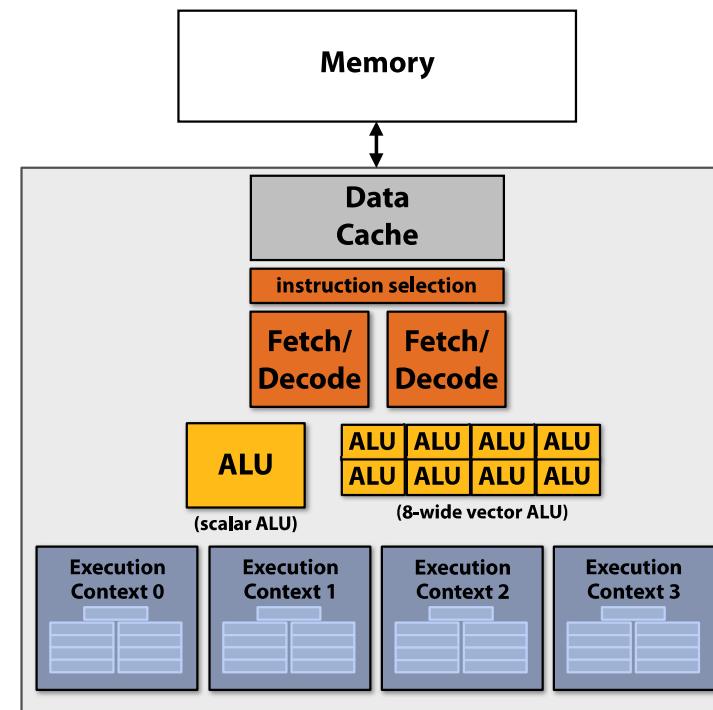
Single core processor, multi-threaded core (2 threads).  
Two-way superscalar core: in this example I defined my core  
as being capable of running up to two independent instructions  
per clock from a single instruction stream\*, provided one is scalar  
and the other is vector

# Multi-threaded, superscalar core

(that combines interleaved and simultaneous execution of multiple hardware threads)



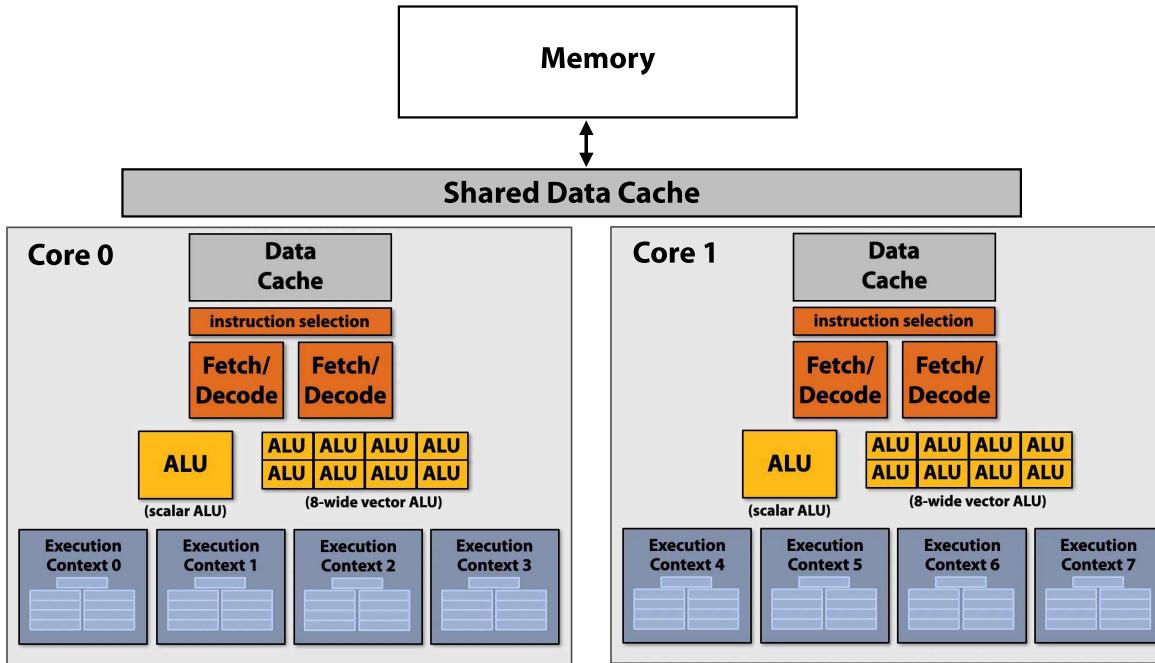
Execution of hardware threads may or may not be interleaved in time  
(instructions from different threads may be running simultaneously)



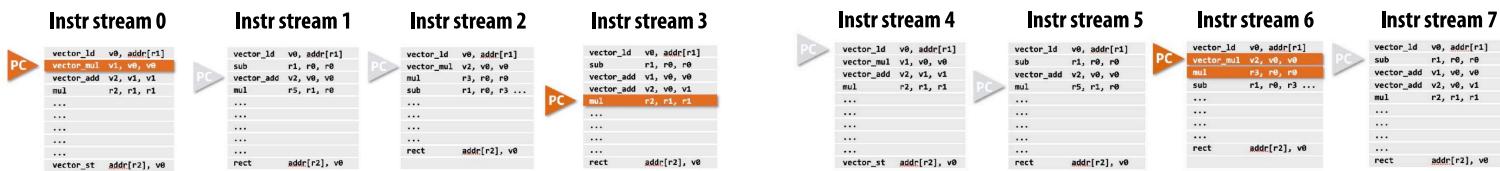
Single core processor, multi-threaded core (4 threads).

Two-way superscalar core:  
can run up to two independent instructions per clock from any of the threads,  
provided one is scalar and the other is vector

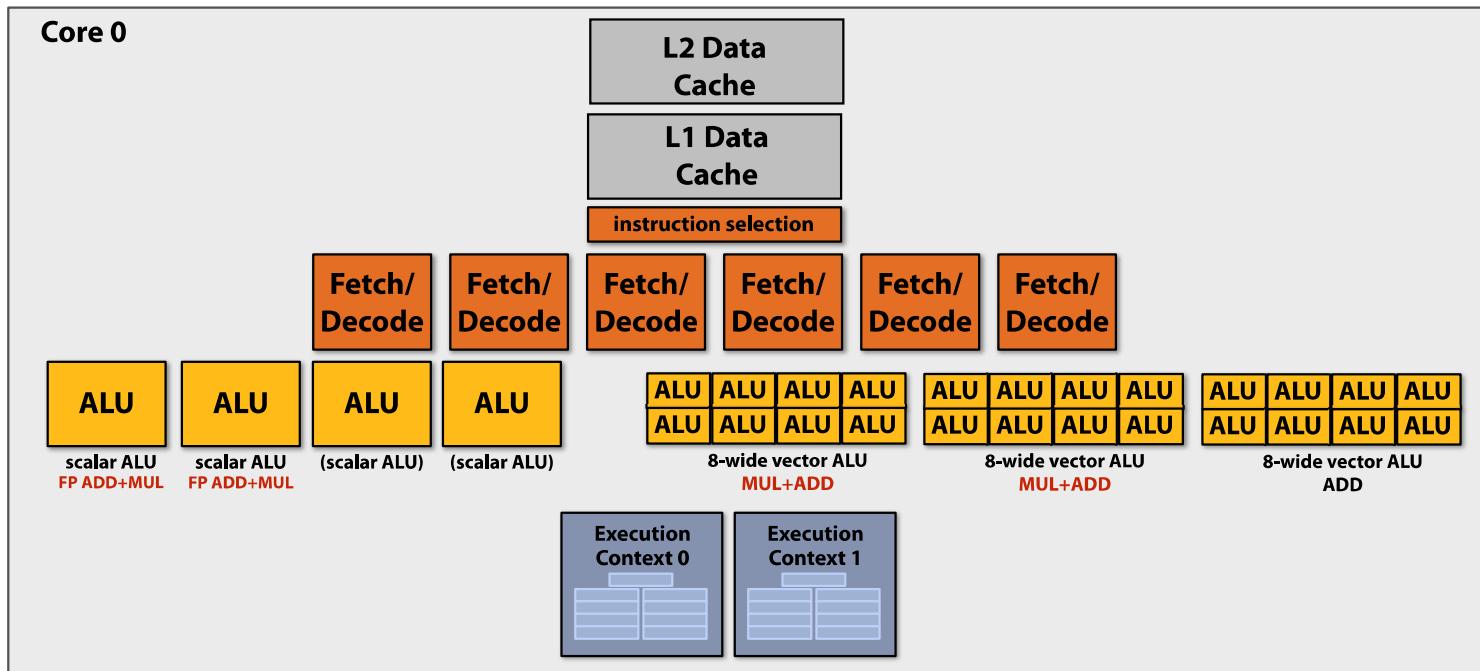
# Multi-core, with multi-threaded, superscalar cores



**Dual-core processor, multi-threaded cores (4 threads/core).**  
**Two-way superscalar cores: each core can run up to two independent instructions per clock from any of its threads, provided one is scalar and the other is vector**

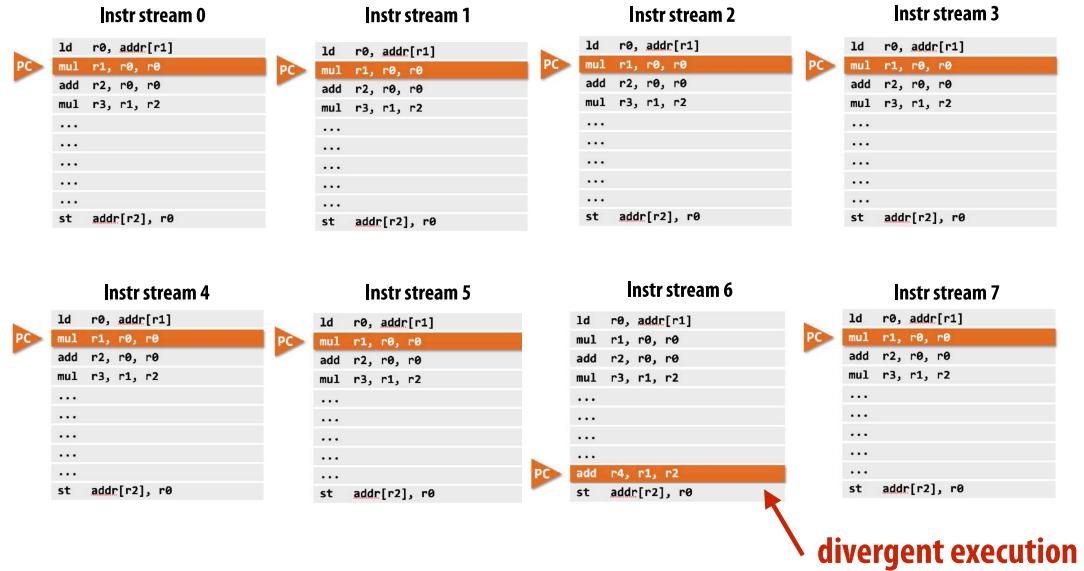


# Example: Intel Skylake/Kaby Lake core



**Two-way multi-threaded cores (2 threads).**  
**Each core can run up to four independent scalar instructions and up to three 8-wide vector instructions (up to 2 vector mul or 3 vector add)**

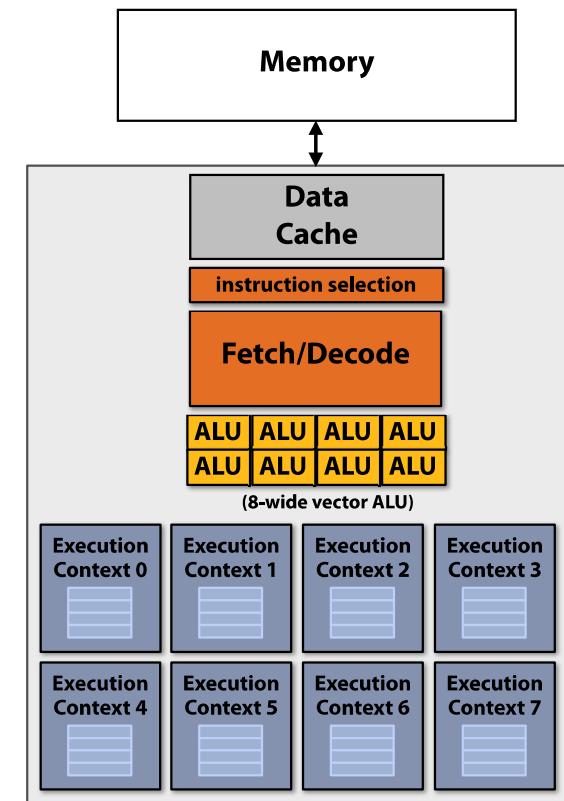
# GPU “SIMT” (single instruction multiple thread)



Many modern GPUs execute hardware threads that run instruction streams with only scalar instructions.

GPU cores detect when different hardware threads are executing the same instruction, and implement simultaneous execution of up to SIMD-width threads using SIMD ALUs.

Here ALU 6 would be “masked off” since thread 6 is not executing the same instruction as the other hardware threads.



# Thought experiment

- You write a C application that spawns two threads
- The application runs on the processor shown below
  - Two cores, two-execution contexts per core, up to instructions per clock, one instruction is an 8-wide SIMD instruction
- Question: “who” is responsible for mapping the application’s threads to the processor’s thread execution contexts?  
**Answer: the operating system**
- Question: If you were implementing the OS, how would to assign the two threads to the four execution contexts?
- Another question: How would you assign threads to execution contexts if your C program spawned five threads?

