

Mark Scheme (Results) January 2010

GCE

Mechanics M3 (6679)



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Question Number	Scheme	Marks
Q1.	$0.5a = 4 + \cos\left(\pi t\right)$	B1
	Integrating $0.5v = 4t + \frac{\sin(\pi t)}{\pi} (+C)$	M1 A1
	Using boundary values $3 = 4 + C \Rightarrow C = -1$	M1 A1
	When $t = 1.5$ $0.5v = 6 - \frac{1}{\pi} - 1$ $v \approx 9.36 \text{ (m s}^{-1}\text{)}$ cao	M1
	$v \approx 9.36 \text{ (m s}^{-1}\text{)}$ cao	A1 (7) [7]

Question Number	Scheme	Marks	
Q2.	(a) $\frac{2\pi}{\omega} = 2.4 \implies \omega = \frac{5\pi}{6} (\approx 2.62)$ $x = 0, t = 0 \implies x = a \sin \omega t$	M1 A1	
	when $t = 0.4$, $x = a \sin\left(\frac{5\pi}{6} \times 0.4\right)$ $\left(=\frac{\sqrt{3}}{2}a\right)$	M1	
	$v^2 = \omega^2 (a^2 - x^2) \implies 16 = \frac{25\pi^2}{36} \left(a^2 - \frac{3a^2}{4} \right) \implies a = \frac{48}{5\pi} (\approx 3.06)$	M1 A1	
	$v_{\text{max}} = a\omega = 8$ (or awrt 8.0 if decimals used earlier) cao	M1 A1 (7	7)
	(b) $\ddot{x}_{\text{max}} = a\omega^2 = \frac{20\pi}{3}$ awrt 21	M1 A1 (2	2) 9]
	Alternative in (a) (a) $ \frac{2\pi}{\omega} = 2.4 \Rightarrow \omega = \frac{5\pi}{6} $ $ x = 0, t = 0 \Rightarrow x = a \sin \omega t $ $ \dot{x} = a\omega \cos \omega t $ $ 4 = a\omega \cos \left(\frac{5\pi}{6} \times 0.4\right) $ $ a = \frac{48}{5\pi} (\approx 3.06) \text{ or } a\omega = 8 $ $ v_{\text{max}} = a\omega = 8 $	M1 A1 M1 A1 M1 A1 (7	7)

Question Number	Scheme	Marks
Q3.	(a) $\begin{array}{cccccccccccccccccccccccccccccccccccc$	B1 B1
	$8 \times \frac{1}{4}r + 19\overline{x} = 27 \times \frac{3}{8}r$ $\overline{x} = \frac{65}{152}r \qquad *$	M1 A1ft A1 (5)
	(b) $Mg \qquad kMg$ $Mg \times \overline{x} \sin \theta = kMg \times r \cos \theta$ leading to $k = \frac{13}{38}$	- M1 A1=A1 - M1 A1 (5) [10]

Question Number	Scheme	Marks
Q4.	O θ T $A0 N$ $A0 N$	
	$ \uparrow T \cos \theta = 40 \qquad \text{M1 attempt at both equations} \rightarrow T \sin \theta = 30 \text{leading to} T = 50 $	M1 A1 A1 M1 A1
	$E = \frac{\lambda x^2}{2a} = 10$ HL $T = \frac{\lambda x}{a} = 50$	B1 - M1
	leading to $x = 0.4$	- M1 A1
	OP = 0.5 + 0.4 = 0.9 (m)	A1ft (10) [10]

Question Number	Scheme	Marks
Q5.	(a) $\frac{1}{2}m \times 2ag - \frac{1}{2}mv^2 = mg(2a - 3a\sin\theta)$ leading to $v^2 = 2ga(3\sin\theta - 1) + 2ga(3\sin\theta)$ (b) minimum value of T is when $v = 0 \implies \sin\theta = \frac{1}{3}$ $T = mg\sin\theta = \frac{mg}{3}$ maximum value of T is when $\theta = \frac{\pi}{2}$ $\left(v^2 = 4ag\right)$ $\uparrow T = \frac{mv^2}{3a} + mg$ $= \frac{7mg}{3}$ $\left(\frac{mg}{3} \le T \le \frac{7mg}{3}\right)$	M1 A1=A1 -M1 A1 (5) B1 M1 A1 M1 A1 (6)

Question Number	Scheme	e Marks	
Q6.	(a) μR mg $\uparrow R = mg$ Use of limiting friction, $F_r = \mu R$ $\leftarrow \mu R = \frac{m28^2}{120}$ $\mu = \frac{28^2}{120 \times 9.8} = \frac{2}{3} *$ cao (b)	B1 B1 M1 A1 M1 A1 (6)	
	$ \uparrow R\cos\alpha - \mu R\sin\alpha = mg $ $ \leftarrow \mu R\cos\alpha + R\sin\alpha = \frac{mv^2}{r} $ $ \frac{\mu\cos\alpha + \sin\alpha}{\cos\alpha - \mu\sin\alpha} = \frac{v^2}{rg} $ Eliminating R $ \frac{2\cos\alpha + 3\sin\alpha}{3\cos\alpha - 2\sin\alpha} = \frac{25}{24} $ Substituting values $ \text{leading to} \tan\alpha = \frac{27}{122} $ awrt 0.22	M1 A1 M1 A1 M1 A1 M1 M1 M1 M1 M1 M1 M1 M1 (8) [14]	

Question Number	Scheme	Marks
Q7.	(a) $\frac{1}{2}mv^2 + \frac{3mgx^2}{4a} = mg(a+x)$ leading to $v^2 = 2g(a+x) - \frac{3gx^2}{2a}$ * cso	M1 A2 (1, 0) A1 (4)
	(b) Greatest speed is when the acceleration is zero $T = \frac{\lambda x}{a} = \frac{3mgx}{2a} = mg \implies x = \frac{2a}{3}$ $v^2 = 2g\left(a + \frac{2a}{3}\right) - \frac{3g}{2a} \times \left(\frac{2a}{3}\right)^2 \left(=\frac{8ag}{3}\right)$ $v = \frac{2}{3}\sqrt{6ag} \qquad \text{accept exact equivalents}$	- M1 A1 - M1 A1 (4)
	(c) $v = 0 \implies 2g(a+x) - \frac{3gx^2}{2a} = 0$ $3x^2 - 4ax - 4a^2 = (x-2a)(3x+2a) = 0$ x = 2a	M1 M1 A1
	At D , $m\ddot{x} = mg - \frac{\lambda \times 2a}{a}$ ft their $2a$ $ \ddot{x} = 2g$	M1 A1ft A1 (6) [14]
	Alternative to (b) $v^{2} = 2g(a+x) - \frac{3gx^{2}}{2a}$ Differentiating with respect to x $2v\frac{dv}{dx} = 2g - \frac{3gx}{a}$ $\frac{dv}{dx} = 0 \Rightarrow x = \frac{2a}{3}$ $v^{2} = 2g\left(a + \frac{2a}{3}\right) - \frac{3g}{2a} \times \left(\frac{2a}{3}\right)^{2} \left(=\frac{8ag}{3}\right)$ $v = \frac{2}{3}\sqrt{6ag}$ accept exact equivalents	- M1 A1 - M1 A1 (4)

Question Number	Scheme	Marks		
Q7.	Alternative approach using SHM for (b) and (c) If SHM is used mark (b) and (c) together placing the marks in the gird as shown.			
	Establishment of equilibrium position $T = \frac{\lambda x}{a} = \frac{3mge}{2a} = mg \implies e = \frac{2a}{3}$ N2L using y for displacement from equilibrium position	bM1 bA1		
	N2L, using y for displacement from equilibrium position $m\ddot{y} = mg - \frac{\frac{3}{2}mg(y+e)}{a} = -\frac{3g}{2a}y$ $\omega^2 = \frac{3g}{2a}$			
	Speed at end of free fall $u^2 = 2ga$	cM1		
	Using A for amplitude and $v^2 = \omega^2 (a^2 - x^2)$			
	$u^2 = 2ga \text{ when } y = -\frac{2}{3}a \implies 2ga = \frac{3g}{2a}\left(A^2 - \frac{4a^2}{9}\right)$	cM1		
	$A = \frac{4a}{3}$	cA1		
	Maximum speed $A\omega = \frac{4a}{3} \times \sqrt{\left(\frac{3g}{2a}\right)} = \frac{2}{3}\sqrt{(6ag)}$	cM1 cA1		
	Maximum acceleration $A\omega^2 = \frac{4a}{3} \times \frac{3g}{2a} = 2g$	cA1		

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