

Chapter 2: Message Passing

(中文版)

Message Passing Paradigm

Let $x_v \in \mathbb{R}^{d_1}$ be the feature for node v , and $w_e \in \mathbb{R}^{d_2}$ be the feature for edge (u, v) . The **message passing paradigm** defines the following node-wise and edge-wise computation at step $t + 1$:

$$\text{Edge-wise: } m_e^{(t+1)} = \phi \left(x_v^{(t)}, x_u^{(t)}, w_e^{(t)} \right), (u, v, e) \in \mathcal{E}.$$

$$\text{Node-wise: } x_v^{(t+1)} = \psi \left(x_v^{(t)}, \rho \left(\left\{ m_e^{(t+1)} : (u, v, e) \in \mathcal{E} \right\} \right) \right).$$

In the above equations, ϕ is a **message function** defined on each edge to generate a message by combining the edge feature with the features of its incident nodes; ψ is an **update function** defined on each node to update the node feature by aggregating its incoming messages using the **reduce function** ρ .

Roadmap

This chapter introduces DGL's message passing APIs, and how to efficiently use them on both nodes and edges. The last section of it explains how to implement message passing on heterogeneous graphs.

- [2.1 Built-in Functions and Message Passing APIs](#)
- [2.2 Writing Efficient Message Passing Code](#)
- [2.3 Apply Message Passing On Part Of The Graph](#)
- [2.5 Message Passing on Heterogeneous Graph](#)