

Lista Modelagem

(Q1) $F(s) = \frac{2s+12}{s^2+2s+5}$

Utilizando Polysym e ilaplace chegamos no seguinte Resultado:

$$f(t) = 2e^{-t} \left(\cos(2t) + \frac{5\sin(2t)}{2} \right)$$

(Q2) $F(s) = \frac{s^2+2s+3}{(s+1)^3} = \frac{A}{(s+1)^3} + \frac{B}{(s+1)^2} + \frac{C}{(s+1)}$

$$A = s^2+2s+3 \Big|_{s=-1} = 1-2+3 = 2$$

$$B = \frac{d}{ds} [s^2+2s+3] \Big|_{s=-1} = 2s+2 \Big|_{s=-1} = 0$$

$$C = \frac{1}{2!} \frac{d^2}{ds^2} [s^2+2s+3] = \frac{1}{2!} \cdot 2 = 1$$

$$F(s) = \frac{2}{(s+1)^3} + \frac{1}{(s+1)} \Rightarrow f(t) = 2 \cdot \frac{1}{(3-1)!} \cdot t^{3-1-1} e^{-(+1)t} + e^{-t} = 2e^{-t} + e^{-t}$$

$$f(t) = e^{-t}(t^2+1)$$

(Q3) $F(s) = \frac{A(s)}{B(s)} = \frac{s^4+2s^3+3s^2+4s+5}{s(s+1)} = (G(s), \underbrace{(-1,288 \pm 0,8579j)(0,2878 \pm 1,1416j)}_{s(s+1)})$

$$f(t) = 2\delta(t) - 3e^{-t} + \delta(t-1) + \delta(t-2) + 5$$

(Q4) $F(s) = \frac{3}{s^3+2s^2+5s} \rightsquigarrow f(t) = \frac{3}{5} - \frac{3e^{-t}}{5} \left(\cos(2t) + \frac{\sin(2t)}{2} \right)$

(Q5) $2\ddot{x} + 7\dot{x} + 3x = 0 \quad x(0) = 3 \quad \dot{x}(0) = 0$

$$2s^2X(s) - 2sX(0) - 2\dot{X}(0) + 7sX(s) - 7X(0) + 3X(s) = 0$$

$$X(s)(2s^2+7s+3) - 6s - 21 = 0$$

$$X(s) = \frac{6s+21}{2s^2+7s+3} \rightarrow x(t) = \frac{18}{5} e^{-\frac{t}{2}} - \frac{3}{5} e^{-3t}$$

Q6) $\ddot{x} + 2\dot{x} = \delta(t)$; $x(0) = 0$

$$sX(s) - x(0) + 2X(s) = 1 \rightarrow X(s) = \frac{1}{s+2} \rightarrow x(t) = e^{-2t}$$

Q7) $\ddot{x} + 2\xi\omega_n\dot{x} + \omega_n^2 x = 0$ $x(0) = a$ $\dot{x}(0) = b$

$$s^2 X(s) - s x(0) - \dot{x}(0) + 2\xi\omega_n s X(s) - 2\xi\omega_n x(0) + \omega_n^2 \frac{1}{s} = 0$$

$$X(s)(s^2 + 2\xi\omega_n s) + x(0)(s + 2\xi\omega_n) - \dot{x}(0) + \frac{\omega_n^2}{s} = 0$$

$$X(s)(s^2 + 2\xi\omega_n s) - a(s + 2\xi\omega_n) - b + \frac{\omega_n^2}{s} = 0$$

$$X(s)(s^3 + 2\xi\omega_n s^2) = a(s^2 + 2\xi\omega_n s) + b s - \omega_n^2$$

$$X(s) = \frac{a s^2 + s(2\xi\omega_n a + b) - \omega_n^2}{s^3 + 2\xi\omega_n s^2}$$

$$\rightarrow x(t) = \frac{4a\omega_n\xi^2 - 2b\xi + \omega_n}{4\omega_n\xi^2} - \frac{t\omega_n}{2\xi} - \frac{e^{-2\xi\omega_n t}}{4\omega_n\xi^2} (\omega_n - 2b\xi)$$

$$x(t) = a + \frac{\omega_n - 2b\xi}{4\omega_n\xi^2} - \frac{\omega_n t}{2\xi} - \frac{e^{-2\xi\omega_n t}}{4\xi^2} + \frac{e^{-2\xi\omega_n t}}{2\omega_n\xi} b$$

Q8) $\dot{x} + ax = A \sin(\omega t)$, $x(0) = b$

$$sX(s) - x(0) + aX(s) = \frac{A\omega}{s^2 + \omega^2} \rightarrow X(s)(s+a) - b = \frac{A\omega}{s^2 + \omega^2}$$

$$X(s) = \frac{A\omega}{(s+a)(s^2 + \omega^2)} + \frac{b}{(s+a)}$$

$$X(s) = \frac{A\omega}{s^3 + \omega^2 s + a s^2 + a \omega^2} + \frac{b}{s+a} = \frac{A\omega}{s^3 + a s^2 + \omega^2 s + a \omega^2} + \frac{b}{s+a}$$

$$x(t) = \frac{A \cdot a \cdot \sin(\omega t) - A \cdot \omega \cdot \cos(\omega t)}{a^2 + \omega^2} + \frac{A \omega e^{-at}}{a^2 + \omega^2} + b e^{-at}$$

Q9) $\ddot{x} + 3\dot{x} + 6x = 0$, $x(0) = 0$ $\dot{x}(0) = 3$

$$s^2 X(s) - s x(0) - \dot{x}(0) + 3s X(s) - 3x(0) + 6X(s) = 0$$

$$X(s)(s^2 + 3s + 6) - 3 = 0 \rightarrow X(s) = \frac{3}{s^2 + 3s + 6}$$

$$x(t) = 3t - 2.7916 \sin(0.9306t) \cosh(0.9306t) - 2.7918 \cos(0.9306t) \sinh(0.9306t)$$