

Analyse a set of outputs of ARWV with machine learning:

Can Deep Learning help us see order in chaos?

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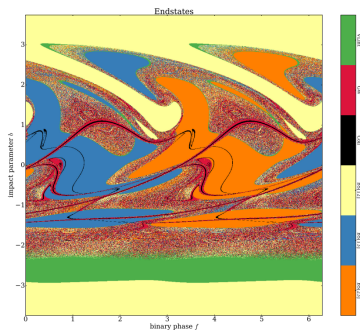
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- 1 Introduction
- 2 Data analysis and manipulation
- 3 Neural Network and training
- 4 Output analysis

Introduction: The general problem

- The 3 body problem has puzzled physicists and mathematicians for centuries.
- Differential equations that describe gravity have no general analytical solutions.
- Numerical integration is required to solve the equations
- **High dependence on initial condition** leads to chaotic behaviours.

- Computational Complexity rises fast.



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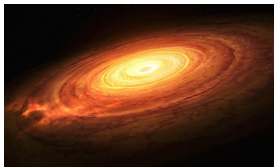
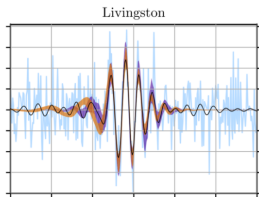


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Introduction : Modern Challenges in science

Gravitational Waves astronomy

- The LIGO-VIRGO collaboration has observed many Binary Black Holes (BBH) mergers for years
- The formation of these massive BBH system (like GW190521) is theorized to occur mainly in the densest parts of Star Clusters (SC)
- **Many close gravitational and chaotic interactions** occur in SCs
- Single-binary BHs scattering can lead to formations of tightly bounded high mass systems.
- But are **Hard to integrate**



Introduction : When does ML comes in

The aim of this project is to build a **Fully connected Deep NN** that can **predict the topology** (general outcome) of an encounter.

- By taking the output of a large set of 3-body interactions (BBH-BH) computed by ARWV (a highly accurate nbody relativistic integrator) we can **train a neural network on it**
- once trained(and if it works) it computes the outcome in a fraction of the time required by ARWV, skipping the numerical integration altogether

This network can be used:

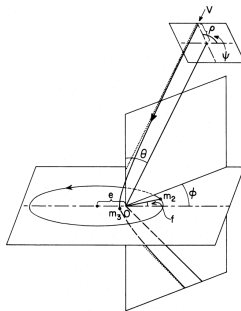
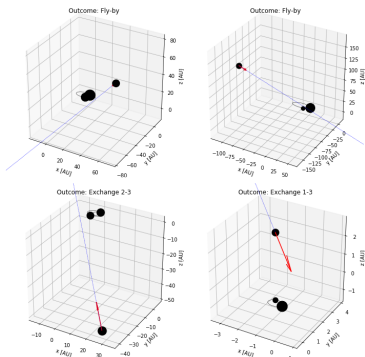
- to study the probability distribution of the outcomes in general
- To predict the outcome of just close encounters in larger SCs simulations, by trading precision with less computational requirements.



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Dataset

Main focus on a dataset of $1e5$ simulations performed with ARWV , with 18 columns that describe initial conditions of each simulations and 4 columns that describe the output.

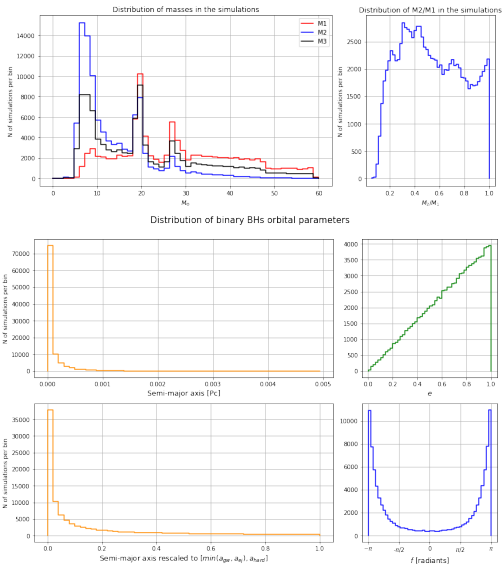


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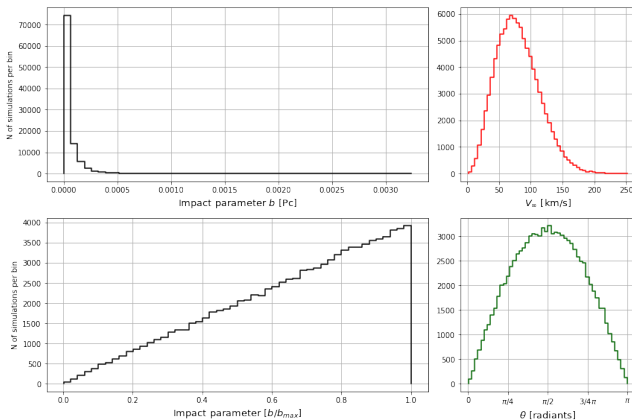
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Dataset: Masses and BBH orbital parameters



Dataset: Single BH parameters

Distribution of parameter of the single BH



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Dataset manipulation

Problem: Neural networks work best when data is roughly in the range $[-1, 1]$:

- Solution for $\{m_1, m_3, a, e, v_\infty, \theta\}$:

$$x_{\text{NN}} = \frac{x_0 - \overline{x_0}}{\text{std}(x_0)}$$

- Solution for $\{\psi, \phi, f\}$

$$x_{\text{NN}} = \{\sin(x_0), \cos(x_0)\}$$

(To impose periodicity of the output function)

- Solution for b :

$$b_{\text{NN}} = \frac{b_0}{b_{\text{max}}} - \overline{\left(\frac{b_0}{b_{\text{max}}}\right)}$$

- Solution for a :

$$a_{NN} = \frac{a - \min(a_{gw}, a_{ej})}{a_{hard} - \min(a_{gw}, a_{ej})},$$

- Solution for m_2 :

$$M_{2NN} = \frac{M_2}{M_1}$$

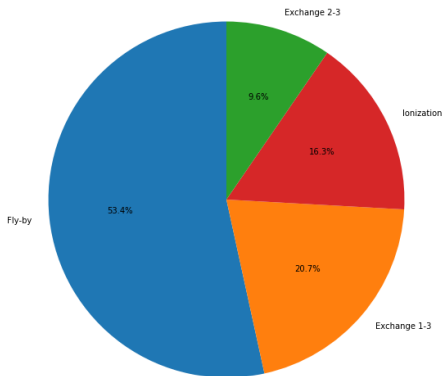
- Additional parameter: v_{crit} indicator is 1 if

$$v_{\infty} > v_{crit} = \sqrt{\frac{m_1 m_2 (m_1 + m_2 + m_3)}{m_3 a (m_1 + m_2)}}$$

Dataset: Outcomes

| Index | Outcome | Description |
|-------|--------------|--|
| 0 | Fly-by | The binary BHs remain as a binary at the end of the simulation |
| 1 | Exchange 1-3 | The smaller BH in the binary is replaced by the single BH |
| 2 | Exchange 2-3 | The bigger BH in the binary is replaced by the single BH |
| 3 | Ionization | No binaries remain at the end of the simulation |

Distribution of total outcomes

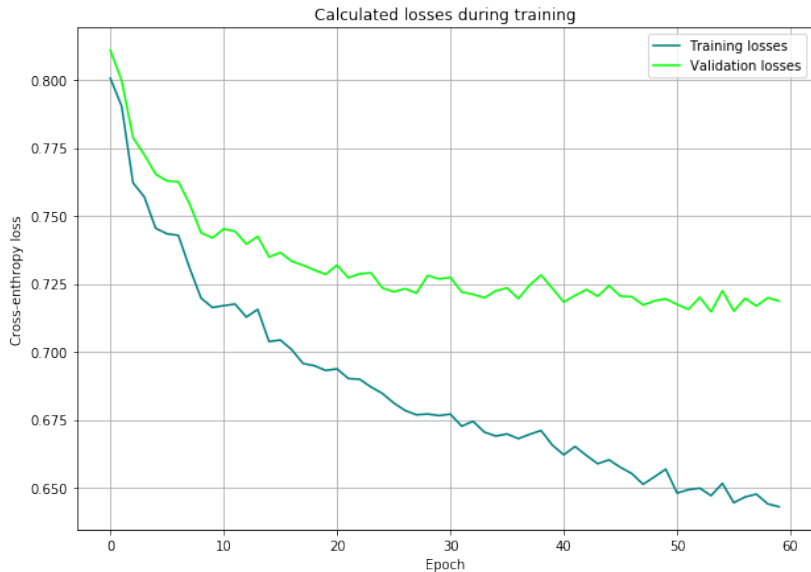


Neural network

Neural network constructed with pytorch

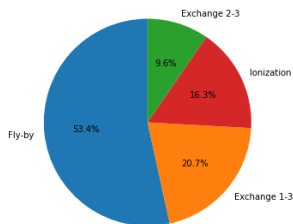
- 4 hidden layers, with 256 nodes each.
- 15 nodes as inputs (8 "normal" parameters + 3 sines + 3 cosines + v_{crit}), 4 nodes as outputs (4 classes)
- ReLU as activation function
- Optimizer: Adamax with $lr = 2e-3$
- minibatch learning with sample shuffle and 256 as batch size
- Dropout 0.3 and L2 regularization used to avoid overfitting (weight decay = $2e-5$)
- loss function: Cross entropy (weighted classes: [0.21 , 0.21 , 0.31 , 0.27])

Neural Network: Training for 60 epochs

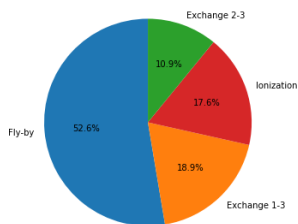


Network Output Distribution

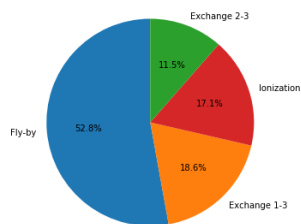
Distribution of real outcomes



Distribution of predicted outcomes (Validation)



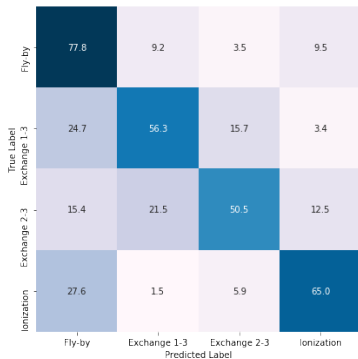
Distribution of predicted outcomes (Test)



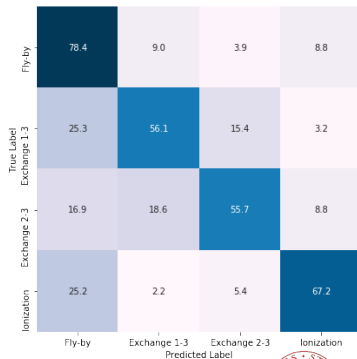
Network output: Confusion matrices

Confusion matrices

Validation Dataset
Overall accuracy: 68.64 %



Test Dataset
Overall accuracy: 69.8 %



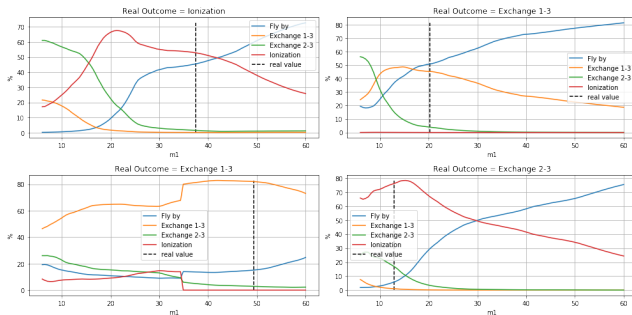
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Network output: 1D analysis of M_1

Here we analyze the network output in more specific detail, choosing a random simulation and looking at how the output function changes by varying just one parameter



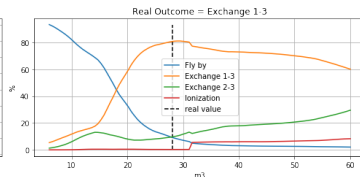
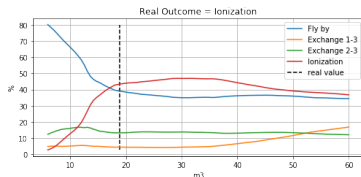
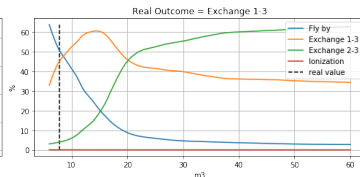
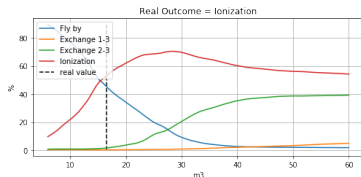
- High $M_1 \rightarrow$ high fly-by
- Interesting behaviour with ionization in some cases

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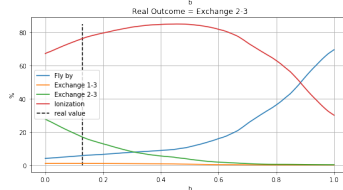
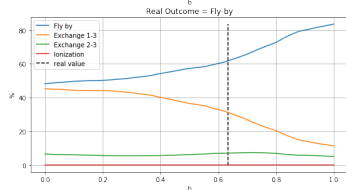
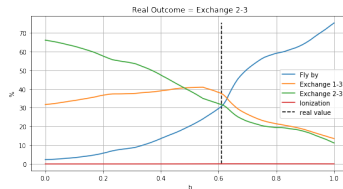
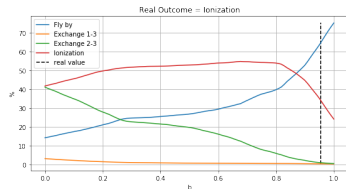
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Network output: 1D analysis of M_3



- High $M_3 \rightarrow$ Low fly-by
- some "trading" exists between exchange probabilities

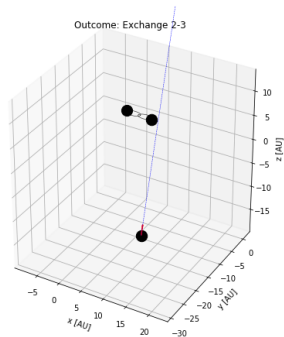
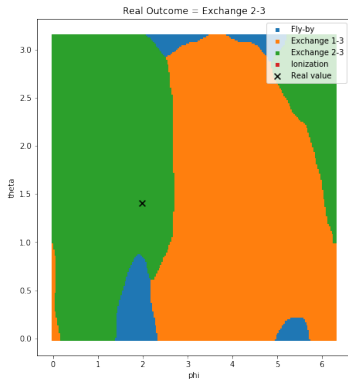
Network output: 1D analysis of b/b_{max}



- High b/b_{max} \rightarrow high fly-by
- Exchanges follow similar patterns

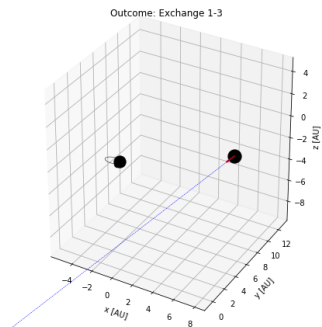
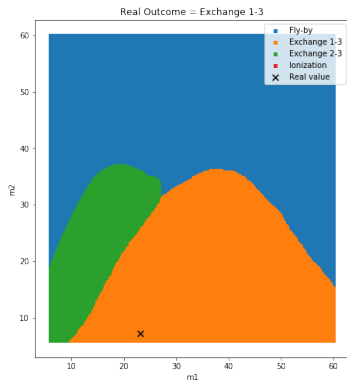
Network output: 2D analysis of ϕ and θ

Same concept as before applies, but now 2 parameters are changed at the same time.



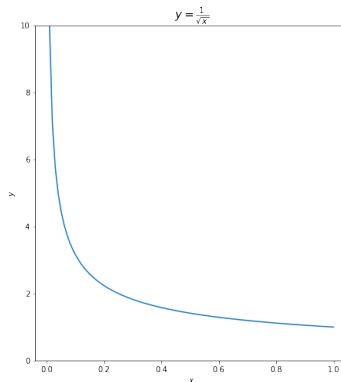
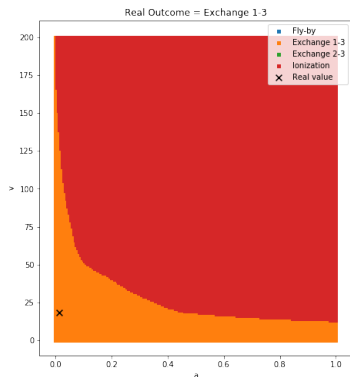
- Highly simmetrical system leads to highly simmetrical output
- fly-by probabilities: net artifacts? Actual property?

Network output: 2D analysis of M_1 and M_2



- Expected Symmetry in $M_1 - M_2$ is weakly present, even if the network was not trained on recognising it
- moving far away from actual training data distr makes the accuracy go down

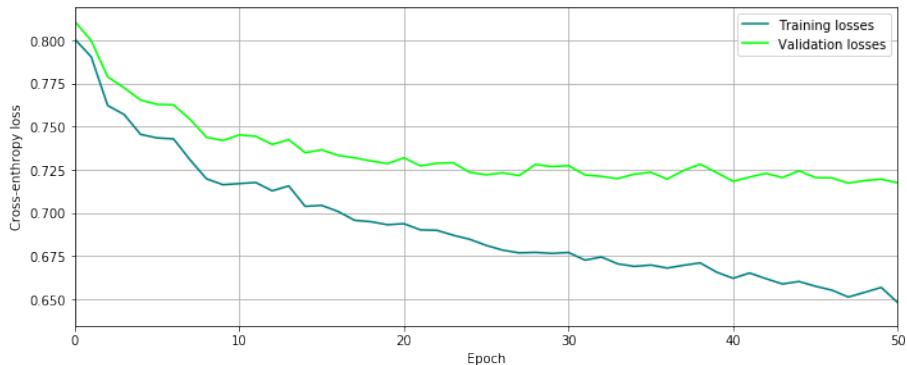
Network output: 2D analysis of v_∞ and Semi-major axis



- Expected behaviour from v_{crit} formula

Network output: Complexity as a function of training

Topology plot of phi vs theta as the training advances



Epochs = 10



Epochs = 20



Epochs = 30

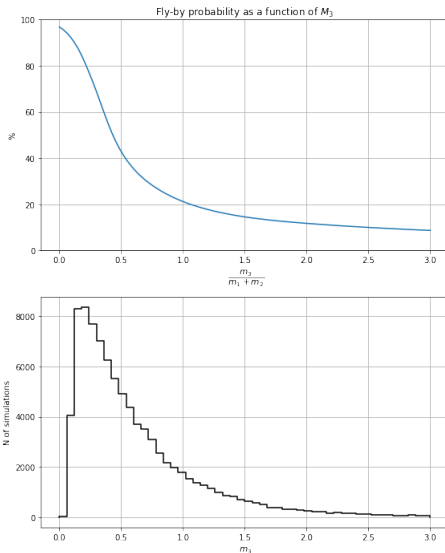


Epochs = 40



Epochs = 50

Network output: Probability of fly-by as the ratio $\frac{m_3}{m_1+m_2}$



- We know that this relation should hold up in theory, since fly-by should go down as this ratio increases and probability of interaction become more common
- Prediction breaks down when the data lacks (around 0), where we expect 100 % fly by

Conclusions

- A Deep Neural Network can approximate the outcome of 3-body encounters with $\sim 70\%$ accuracy.
- really good for a chaotic system
- if it can be proven that it does not introduce any bias, it could be possibly implemented in large cluster simulations to cut down time.
- It could be used to study outcome probability distribution in more details, to help us understand chaos of 3-body interactions

Can we improve it?

- More simulations -> possible to expand the network
- Experiment with data augmentation
- More accurate Gridsearch or bayesian search of hyperparameters
- Experiment with letting the network overfit
- Weighting loss function over chaoticness of interaction.

Thanks for your attention!

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