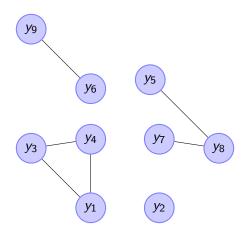
Estimating bayesian mutliple graphical models with EM

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Undirected bayesian graph



Setting and assumptions

We observe p parameters across n samples. That is we have n observations $y^1, \ldots, y^n \in \mathbb{R}^p$ of a p dimensional vector. We assume that $y^1, \ldots, y^n \overset{i.i.d.}{\sim} \mathcal{N}_p(0, \Sigma)$ have a multivariate normal distribution.

- ► To estimate the graph we would like to know whether $y_i \stackrel{\text{\tiny M}}{=} y_j | y_{-i,-j}$.
- ▶ Idea: We know that in the *precision matrix*, $\Omega = \Sigma^{-1}$ the (i,j)-th entry is zero only if $y_i \perp \!\!\! \perp y_j | y_{-i,-j}$
- ▶ How do we find the zero entries of Ω ?

Why should we use the Bayesian method?

- ► Flexible hierarchical modeling
- ► Ease of interpretation of results
- Use prior knowledge

If we consider Ω as being drawn from a prior distribution $p(\Omega)$ we can obtain a posterior distribution $p(\Omega|X)$ of which the maximum is the maximum à-posteriori estimate Ω .

Spike and slab prior

The spike and slab prior for Ω helps us differentiate between zero and non-zero entries of Ω

$$egin{aligned} y | \Omega &\sim \textit{N}_{\textit{p}}(0,\Omega^{-1}), \ \omega_{ij} | \delta_{ij} &\sim \delta_{ij} \textit{N}(0,\textit{v}_1^2) + (1-\delta_{ij}) \textit{N}(0,\textit{v}_0^2), i
eq j, \ \omega_{ii} &\sim \textit{Exp}(\lambda/2), \ \delta_{ij} | \pi &\sim \textit{Bern}(\pi), \ \pi &\sim \textit{Beta}(a,b). \end{aligned}$$

Posterior joint distribution

After a few manipulations we find that

$$p(\Omega, \delta, \pi | y) \propto p(y|\Omega)p(\Omega|\delta)p(\delta|\pi)p(\pi)$$

$$\begin{split} &\log(p(\Omega,\delta,\pi|Y)) = \\ &\sum_{j < k} -\log(v_0^2(1-\delta_{jk}) + v_1^2\delta_{jk}) - \frac{\omega_{jk}^2}{2} \frac{1}{v_0^2(1-\delta_{jk}) + v_1^2\delta_{jk}} - \sum_j \frac{\lambda}{2}\omega_{jj} \\ &+ \sum_{j < k} \delta_{jk} \log\left(\frac{\pi}{1-\pi}\right) + \log(1-\pi) \\ &+ (a-1)\log(\pi) + (b-1)\log(1-\pi) \\ &+ \frac{n}{2}\log\det(\Omega) - \frac{1}{2}\operatorname{tr}(Y^tY\Omega) + \operatorname{constants}. \end{split}$$

Taking expectations

$$\begin{split} &Q(\Omega,\pi|\Omega^{(I)},\pi^{(I)}) = E_{\delta|Y,\Omega^{(I)},\pi^{(I)}}(\log(p(\Omega,\delta,\pi|Y)|Y,\Omega^{(I)},\pi^{(I)}) = \\ &-\sum_{j< k} \frac{\omega_{jk}^2}{2} E_{\delta_{jk}|\cdot} \left(\frac{1}{v_0^2(1-\delta_{jk})+v_1^2\delta_{jk}}\right) - \sum_j \frac{\lambda}{2} \omega_{jj} \\ &+\sum_{j< k} E_{\delta_{jk}|\cdot}(\delta_{jk}) \log\left(\frac{\pi}{1-\pi}\right) + \log(1-\pi) \\ &+ (a-1)\log(\pi) + (b-1)\log(1-\pi) \\ &+ \frac{n}{2}\log\det(\Omega) - \frac{1}{2}\operatorname{tr}(Y^tY\Omega) + \operatorname{constants}. \end{split}$$

Computing expectation terms

$$q_{jk} := \mathsf{E}_{\delta_{jk}|\cdot}(\delta_{jk}) = rac{\pi p(\omega_{jk}|\delta=1)}{\pi p(\omega_{jk}|\delta=1) + (1-\pi)p(\omega_{jk}|\delta=0)}.$$

And

$$d_{jk} := extstyle E_{\delta_{jk}|.} \left(rac{1}{v_0^2 (1 - \delta_{jk}) + v_1^2 \delta_{jk}}
ight) = rac{1 - q_{jk}}{v_0^2} + rac{q_{jk}}{v_1^2}$$

Maximising π

Taking the derivative and setting to zero we find that

$$\pi^{(l+1)} = \frac{a - 1 + \sum_{j < k} q_{jk}}{a + b - 2 + \frac{p(p-1)}{2}}$$

Maximising Ω

If we partition

$$\Omega = \begin{pmatrix} \Omega_{11} & \omega_{12} \\ \omega_{12}^t & \omega_{22} \end{pmatrix} \quad X^t X = \begin{pmatrix} S_{11} & s_{12} \\ s_{12}^t & s_{22} \end{pmatrix}$$

we find that

$$\omega_{12} \sim \textit{N}(-\textit{C}^{-1}\textit{s}_{12},\textit{C}) \quad \textit{C} = (\textit{s}_{22} + \lambda)\Omega_{11}^{-1} + \text{diag}(\textit{v}_{12}^{-1})$$

and that

$$\omega_{22} \sim \textit{Gamma}\left(rac{n}{2}+1,rac{ extsf{s}_{22}+\lambda}{2}
ight) + \omega_{12}^t\Omega_{11}^{-1}\omega_{12}.$$

Taking the modes we find the update steps

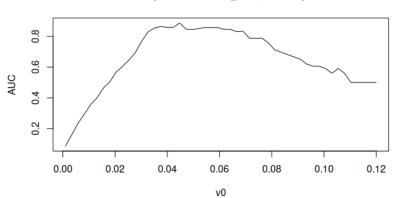
$$\omega_{12}^{(l+1)} = -((s_{22} + \lambda)\Omega_{11}^{-1} + \text{diag}(d_{12}))^{-1}s_{12}$$

$$\omega_{22}^{(l+1)} = \frac{n}{s_{22} + \lambda} + (\omega_{12}^{(l+1)})^t\Omega_{11}^{-1}\omega_{12}^{(l+1)}$$

Choosing hyperparameters

Big influence on performance

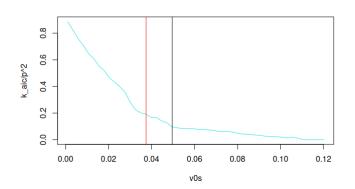
Fit performance (p=25, n=100)



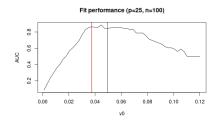
Try: fixing sparsity

Say I know I want about s = 10% sparsity.

- ▶ Then fix a, b so that a/(a+b) = s
- ▶ Try many v_0 , pick fit with closest sparsity.



Effect on performance



Fit performance (F1), (p=25, n=100)								
F1 score	0.70 0.80 0.90	0,02	0.04	0.06	0,08	0.10	0.12	
	0.00	0.02	0.04		0.00	0.10	0.12	
				v0				

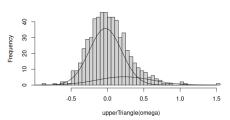
EMGS	MB	
0.86	0.45	
0.78	0.54	
0.72	0.52	
	0.86	

Table: AUC values for n = 100, p=25, 35, 50

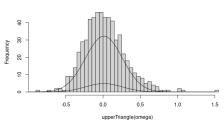
How to choose sparsity?

Fitting gaussian mixture model, not very convincing.



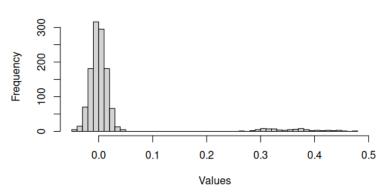


Histogram of upperTriangle(omega)



It will depend on generation method

Histogram of upper triangle of Omega, n=10000



Future work

The original aim of the project: multiple graphs. We now have a hierarchical model

$$egin{aligned} y|\Omega_k &\sim N_p(0,\Omega_k^{-1}), \ \omega_{ijk}|\delta_{ijk} &\sim \delta_{ijk}N(0,v_1^2) + (1-\delta_{ijk})N(0,v_0^2) ext{for } i
eq j, \ \omega_{iik} &\sim Exp(\lambda_k/2), \ \delta_{ijk}|\theta_{ijk} &\sim Bern(\Phi(\theta_{ijk})), \ \theta_{ij} &\sim N_K(0,\Sigma). \end{aligned}$$

The parameter Σ is a shared parameter across graphs.